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COMMENTS AND CORRECTIONS

Corrections to “An Autonomous Underwater Vehicle Navigation Technique for Inspection and Data Acquisition in UWSNs”

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In the above article [1], reference 67 was retracted. As the work in this reference is no longer reliable, we are removing it from the reference list and replacing it with [2].

REFERENCES

- [1] A. Wibisono, M. J. Piran, H.-K. Song, and B. M. Lee, “An autonomous underwater vehicle navigation technique for inspection and data acquisition in UWSNs,” *IEEE Access*, vol. 12, pp. 8641–8654, 2024, doi: 10.1109/ACCESS.2024.3353382.
- [2] R. Zhu, A. Boukerche, L. Long, and Q. Yang, “Design guidelines on trust management for underwater wireless sensor networks,” *IEEE Commun. Surveys Tuts.*, early access, Apr. 16, 2024, doi: 10.1109/COMST.2024.3389728.

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