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## RESEARCH ARTICLE

# Design of a 0.1–16GHz Reconfigurable Ultra-Wideband MMIC Power Amplifier

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**ABSTRACT** This paper proposes a reconfigurable ultra-wideband power amplifier based on reconfigurable technology. The power amplifier consists of a gain module and reconfigurable bias circuits. The gain module is based on the structure of distributed amplifiers and innovates with peaking inductance and cascode structure to increase the output power and gain of the power amplifier. In addition, unlike the off-chip bias used in most distributed amplifiers, we have designed on-chip bias circuits through reconfigurable technology, which effectively improves the efficiency of the power amplifier and reduces the size of the chip. The power amplifier is designed to operate in the 0.1 to 16GHz, and it is capable of providing over 30dBm of output power in the operating band, with a stable gain of around 16dB and Power-Added-Efficiency (PAE) of 21%~32%.

**INDEX TERMS** Reconfigurable, ultra-wideband, cascode, bias, MMIC.

## I. INTRODUCTION

With the development of system generalization and multi-system integration of composite communication systems, the ultra-wideband (UWB) power amplifier (PA) has become an inevitable trend of development [1]. With the development of Monolithic Microwave Integrated Circuit (MMIC), GaAs HEMT, which has the advantages of high electron mobility, and high cut-off frequency [2], [3], [4], has become an effective way to research UWB PAs [5].

The techniques to realize UWB PA usually include negative feedback, continuous impedance matching, balanced structure and distributed amplifier (DA). DA is a special type of PA. In reference [6], negative feedback technology is used to expand the bandwidth of the power amplifier at the expense of low-frequency gain. Due to the frequency roll-off characteristics of the gain, this method is not suitable for the millimeter wave frequency range. The design process for continuous impedance matching is shown in reference [7] which achieves a bandwidth of 4 octaves. As the bandwidth requirement increases, the difficulty of this method will increase dramatically, and the circuit volume will

become larger. The bandwidth of a balanced power amplifier is limited by both the amplifier and the coupler, as described in reference [8]. The reference [9] has cascaded the classical distributed structure with 3-stage, which achieves a bandwidth of 2.3~21GHz, but the efficiency is low (PAE<20%). Utilizing a three-stack FET structure as a power-controllable gain unit, and employing a dual-gate bias control scheme on the bottom and middle FETs to reconfigure the output power, is the approach mentioned in reference [10], which does not yield high output power. In reference [11], optimizing the cutoff frequency of the drain line to reduce its losses for increased gain is discussed. However, this method is not suitable for wider bandwidth applications.

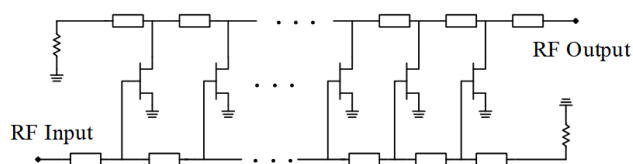


FIGURE 1. The topology of classic DA.

Fig.1 shows the topology of classic DA [12]. Because the parasitic capacitance and inductance of the transistors are

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absorbed by artificial transmission lines (ATL), DA can get rid of the gain-bandwidth-product limitation of traditional PAs and achieve a large bandwidth easily [13], [14], [15]. The output power and efficiency of the DA are low due to a large number of signal components absorbed by the terminal resistors [15], [16], [17]. Meanwhile, the bias of DA is usually off-chip, which increases its size and limits the development of DA [18].

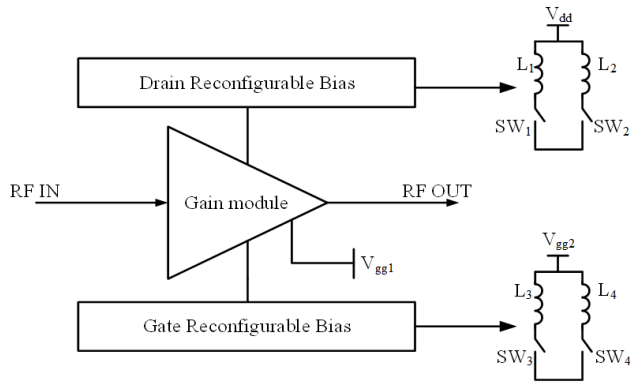


FIGURE 2. Structure of reconfigurable UWB PA.

Fig.2 shows the proposed reconfigurable UWB PA in this paper consists of a gain module based on DA structure and bias circuits based on reconfigurable technology.

In summary, this design has made a breakthrough in the efficiency, output power, gain, integration and other aspects of PA, which has a strong practical value.

## II. THEORY AND DESIGN OF THE GAIN MODULE

In the classic DA topology shown in Fig.1, the common-source transistor output capability is weak. If the size of a single transistor is increased, although the output capacity is improved, the parasitic capacitance and resistance of the transistor will be increased at the same time, so that the bandwidth of PA will get narrower [19], [20]. In contrast, the advantages of stack technology are more obvious.

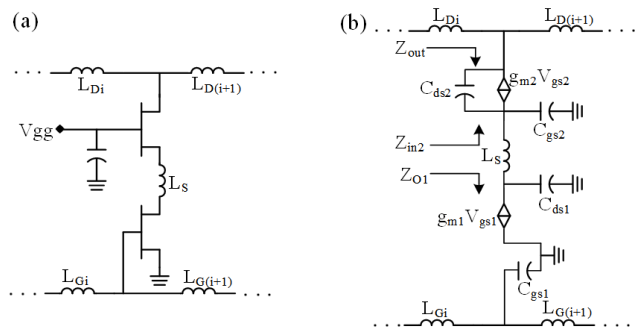


FIGURE 3. Cascode cell structure. (a) cascode cell circuits. (b) Equivalent model of the cascode cell.

As shown in Fig.3(a), the cascode cell is a typical structure of the stack technology. For one thing, it can connect two

transistors in series to increase the output power by increasing the drain voltage; for another, the common-gate transistor can shield the influence of the voltage change of the output point on the performance of the cascode cell, which is conducive to the construction of the drain ATL. Moreover, to improve the high-frequency gain, a peaking inductance  $L_S$  is added to the cascode cell [21].

Fig.3(b) shows the equivalent model of cascode cell.  $Z_{O1}$ ,  $Z_{in2}$ , and  $Z_{out}$  represent the equivalent intrinsic impedance of the common-source transistor, the input equivalent impedance of the common-gate transistor, and the equivalent intrinsic impedance of the cascode cell, respectively [22] and [23]. The analysis of the model shows that:

$$Z_{o1} = \frac{1}{j\omega C_{ds1}} \quad (1)$$

$$Z_{in2} = \frac{1}{j\omega C_{gs2} + g_{m2}} \quad (2)$$

$$Z_{out} = g_{m2} \frac{1 - \omega^2 L_S C_{ds1}}{\omega^2 [\omega^2 L_S C_{ds1} C_{gs2} C_{ds2} - (C_{ds1} + C_{gs2}) C_{ds2}]} \quad (3)$$

The voltage gain  $A_V$  of the cascode cell can be expressed as:

$$A_V = g_{m1} g_{m2} \frac{Z_{o1} Z_{out}}{Z_{o1} + Z_{in2} + j\omega L_S} \quad (4)$$

It follows from Eq. (4) that  $A_V$  is a function of  $Z_{O1}$ ,  $Z_{in2}$ , and  $Z_{out}$ , while  $Z_{O1}$  and  $Z_{in2}$  present capacitive impedances. Therefore,  $A_V$  is a frequency-sensitive variable that has an impact on the bandwidth and gain. In the structure proposed in Fig. 3, the inductive impedance of the peaked inductance  $L_S$  cancels out the capacitive impedance, thus improving the high-frequency gain of the cascode cell.

This design is based on a 0.15um GaAs process. The size of the two transistors in the cascode cell are  $6*45\mu\text{m}$  and  $4*45\mu\text{m}$  respectively. According to the above, the proposed gain module requires very high accuracy of the intrinsic parameters of the cascode cell, so the intrinsic parameters need to be extracted in the ADS with the help of Y-parameters. The intrinsic parameters can be extracted by the following equations:

$$C_{gd} = -\frac{im(Y_{12})}{\omega} \quad (5)$$

$$C_{gs} = \frac{im(Y_{11}) - \omega C_{gd}}{\omega} \left[ 1 + \frac{(re(Y_{11}))^2}{im(Y_{11}) - \omega C_{gd}} \right] \quad (6)$$

$$R_{gs} = \frac{re(Y_{11})}{[im(Y_{11}) - \omega C_{gd}]^2 + [re(Y_{11})]^2} \quad (7)$$

$$C_{ds} = \frac{im(Y_{22}) - \omega C_{gd}}{\omega} \quad (8)$$

$$R_{ds} = \frac{1}{re(Y_{22})} \quad (9)$$

When building two ATLs with a characteristic impedance of  $50\Omega$ , the intrinsic parameters of the cascode cell are

first characterised using the ideal capacitance model. The relationship between the characteristic impedance and cut-off frequency, of the ATL is shown in Eq. (10) and Eq. (11):

$$Z_0 = \sqrt{\frac{L}{C}} \quad (10)$$

$$f_c = \frac{1}{\pi\sqrt{LC}} \quad (11)$$

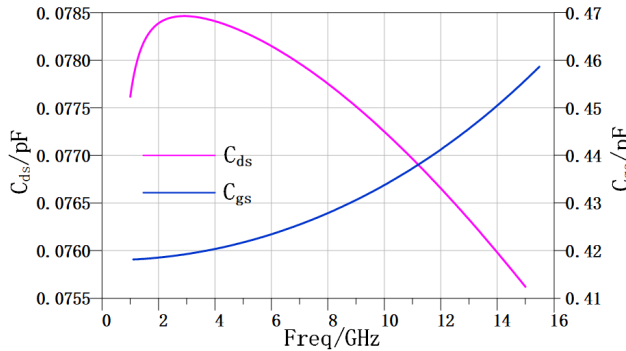


FIGURE 4. Results of intrinsic parameters extraction.

Fig. 4 shows that  $C_{gs}$  is much larger than  $C_{ds}$ , so the cut-off frequency of the gate ATL is much lower than that of the drain ATL, making the gate ATL become the main factor limiting the bandwidth of the PA. Therefore, ATLs should be modified. We make  $C_{gx}$  in series with  $C_{gs}$  to reduce the equivalent drain capacitance and  $C_{dx}$  in parallel with  $C_{ds}$  to increase the equivalent gate capacitance, thus achieving the same cut-off frequency for both ATLs [24]. The relationship between the two is shown in Eq. (12) and Eq. (13):

$$f_c = \frac{1}{\pi\sqrt{L_g C_{ge}}} = \frac{1}{\pi\sqrt{L_d C_{de}}} \quad (12)$$

$$Z_0 = \sqrt{\frac{L_g}{C_{ge}}} = \sqrt{\frac{L_d}{C_{de}}} \quad (13)$$

In the above equations,  $L_d$  and  $L_g$  denote the drain inductance and gate inductance respectively;  $C_{de}$  and  $C_{ge}$  denote the modified drain equivalent capacitance and gate equivalent capacitance respectively.  $C_{dx}$  and  $C_{gx}$  can be solved, according to Eq. (14) and Eq. (15).

$$C_{ge} = \frac{C_{gs}C_{gx}}{C_{gs}+C_{gx}} \quad (14)$$

$$C_{de} = C_{ds} + C_{dx} \quad (15)$$

The modified ATLs (at 6-stage, for example) are shown in Fig.5.

A comparison of the S-parameter simulation results for the modified ATLs and the typical ATLs is shown in Fig.6.

The simulation results show that the typical drain ATL cut-off frequency is much higher than 30GHz, while the typical gate ATL cut-off frequency only reaches 13GHz. If typical ATLs are used for the design of the proposed gain module, the bandwidth of it will drop below 13GHz.

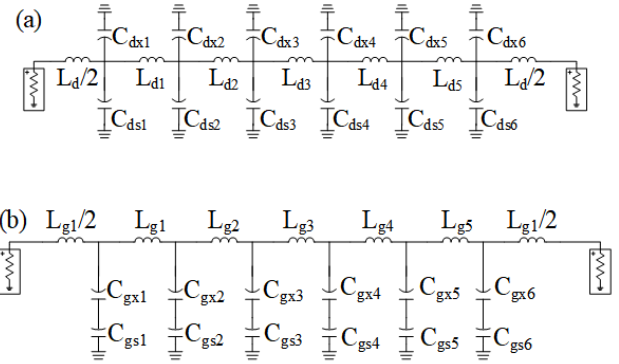


FIGURE 5. The circuit of ATLs. (a) Gate ATL. (b) Drain ATL.

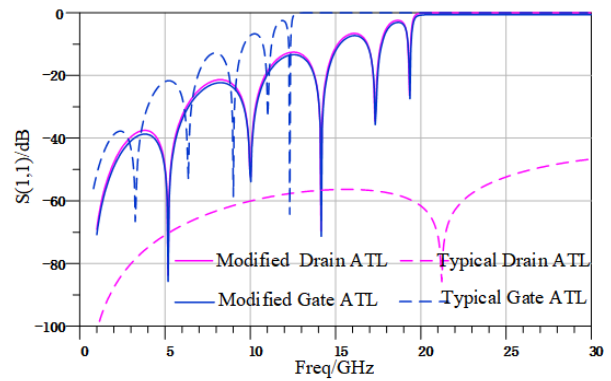


FIGURE 6. ATLs performance comparison.

The ATLs have been modified to have the same cut-off frequency and keep the signals in the same phase, giving full play to the gain module's output capability.

The design of the gain module part is completed by replacing  $C_{ds}$  and  $C_{gs}$  with cascode cells [25]. The circuit of the gain module is obtained by combining and adjusting the individual cells.

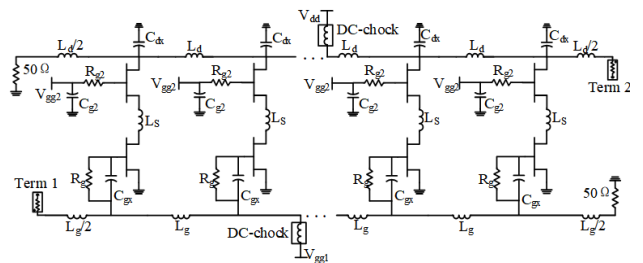


FIGURE 7. The circuit of gain module.

The gain module proposed in this paper is implemented using 6-stage cascode cells, with the duplicate cascode cells omitted in fig.7.  $R_g$  provides a DC path to the gate and together with  $C_{gx}$  forms a stable network; the  $C_{g2}$  provides the AC ground and in conjunction with the  $R_{g2}$ , the two ensure the absolute stability of transistors. Here, an ideal

DC-chock is used in the bias circuit. The handbook shows that the maximum withstand drain voltage for a single transistor is +6 V, so in this design  $V_{dd}$  is set to +10 V,  $V_{gg1}$  is set to -0.8 V and  $V_{gg2}$  is set to +3.7 V.

In fig8, small-signal simulation shows that  $S_{11}$  is less than -10 dB in the DC ~ 16GHz, proving that the gain module is well matched and can achieve broadband; the gain flatness is only  $\pm 0.8$  dB and the gain is stable in this frequency range;  $S_{22}$  is less than 14 dB in this frequency range and the gain module is in an absolutely stable state.

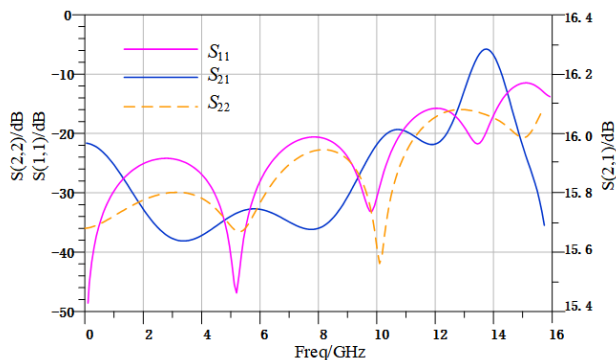


FIGURE 8. Small-signal simulation of gain module.

### III. REALIZATION AND ANALYSIS OF RECONFIGURABLE BIAS

The ideal DC-chock used for powering the gain module cannot be applied in practice. At present, there is no better solution to the volume problem of off-chip bias and the performance problem of on-chip bias. In this section, the impact of bias on the performance of UWB PA will be analyzed and an effective solution will be proposed.

#### A. THE RECONFIGURABLE SCHEME OF BIAS

In the narration above, the gain module is not reconfigurable, gate and drain bias circuits are reconfigurable and can power the gain module. Under ideal conditions, looking outwards from the gain module, the impedance of the bias is infinite [26], but in fact, this condition is impossible to achieve. And the upper limit  $f_h$  and lower limit  $f_l$  of the operating bandwidth are influenced by the ratio of bias impedance  $Z_B$  to the load impedance  $Z_l$ , as follows:

$$\frac{f_h}{f_l} = \frac{\pi - \tan^{-1}(Z_B/Z_l)}{\tan^{-1}(Z_B/Z_l)} \quad (16)$$

From Eq. (16), it can be seen that to achieve a relatively large  $f_h/f_l$  when the load impedance is  $50\Omega$ , the bias requires a larger impedance. However, a fixed inductance cannot provide sufficient impedance for bias at UWB conditions. This is why the bias limits the bandwidth of the gain module.

Fig. 9 shows the equivalent model of an on-chip spiral inductance, then  $C_p$  and  $R_p$  represent the parasitic capacitance and parasitic resistance, respectively.  $L$  affects low-frequency performance and  $C_p$  affects high-frequency performance.

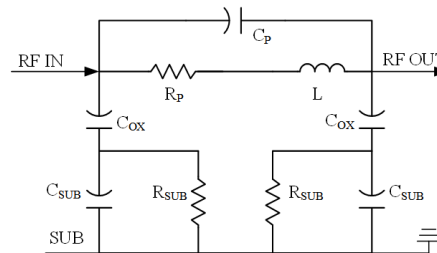


FIGURE 9. The spiral inductance equivalence model.

When using a spiral inductance as a choke, it is necessary to keep  $L$  as large as possible and  $C_p$  as small as possible. However,  $L$  and  $C_p$  are mutually restricted and cannot be achieved simultaneously. This is why the industry generally uses off-chip bias circuits, resulting in particularly large sizes.

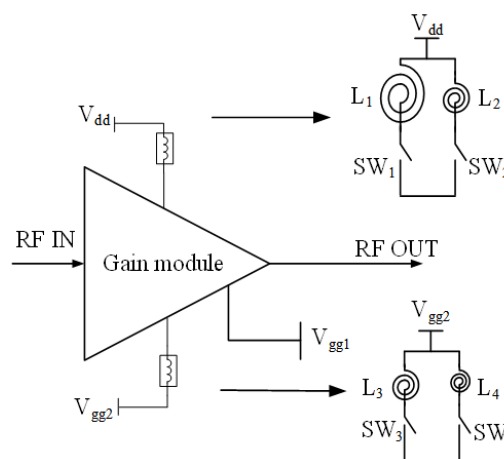


FIGURE 10. Reconfigurable scheme structure diagram.

The proposed reconfigurable scheme can perfectly break through these limitations and achieve on-chip bias. As shown in Fig.10, the design of switches 1-4 employs highly reliable MOSFET switches and utilizes a voltage-controlled switch device to connect the switches to L1-L4 respectively. Finally, protective circuits are designed to ensure that no damage to the power amplifier chip or signal distortion occurs during the switching process. By closing  $SW_1$  and  $SW_3$ , large inductances are connected to the circuit to ensure the low-frequency performance of the gain module; by closing  $SW_2$  and  $SW_4$ , small inductances are connected to the circuit to ensure the high-frequency performance of the gain module and overcome the influence of parasitic parameters.

#### B. SIMULATION OF RECONFIGURABLE BIAS

The lower the impedance of the bias, the better it is for UWB realization, but it can also cause signal leakage and reduce the efficiency of the DA. In order to achieve the best performance, the gate low-frequency mode requires higher maximum bias impedance at certain frequencies. The circuit was optimized according to the requirements

TABLE 1. PA operating mode control methods.

Mode	SW <sub>1</sub>	SW <sub>2</sub>	SW <sub>3</sub>	SW <sub>4</sub>	Band
Low	ON	OFF	ON	OFF	0.1 ~ 6.5GHz
High	OFF	ON	OFF	ON	6.5 ~ 16GHz

at different frequency ranges, and ultimately different bias impedances for the gate low-frequency mode were found to achieve optimal performance at different frequencies. The reconfigurable bias described in 3.1 was simulated and the results are shown in Fig.11.

The drain bias and gate bias provide high impedance to inhibit signal leakage from 0.1 to 20GHz. Two inductances for the low-frequency mode have self-resonance points greater than 10GHz, while two inductances for the high-frequency mode have the self-resonance points greater than 20GHz, avoiding the negative effects of self-resonant points on performance of gain module.

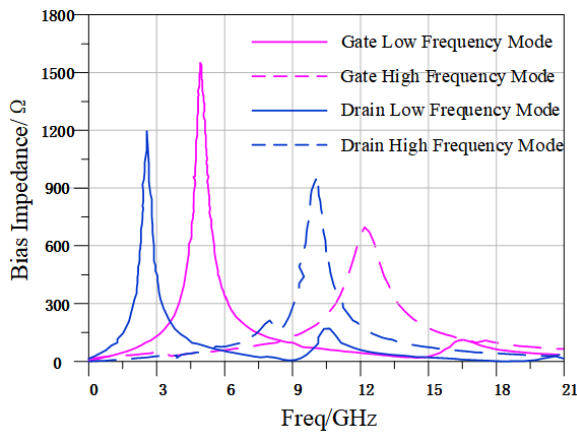


FIGURE 11. Simulation results of reconfigurable bias impedance.

IV. MEASUREMENT OF RECONFIGURABLE UWB PA

The inductances on the ATLs are replaced by microstrip lines, thus reducing the size of the chip. The overall circuit layout of reconfigurable UWB PA is shown in Fig.12.

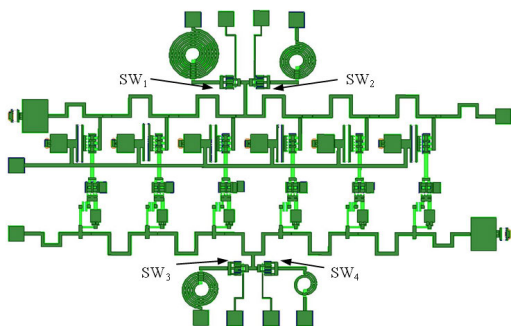


FIGURE 12. The overall circuit layout.

Fig 13 shows the chip photograph of the fabricated UWB power amplifier. After tape-out, the size of the chip is 5.88 mm<sup>2</sup> (3.03 × 1.94 mm). Fig 14 presents the

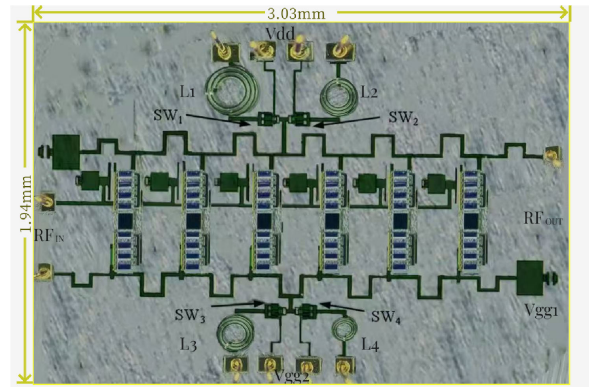


FIGURE 13. Chip photo of the fabricated UWB PA.

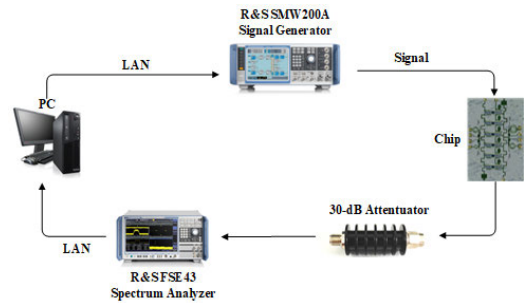


FIGURE 14. Large-signal measurement results.

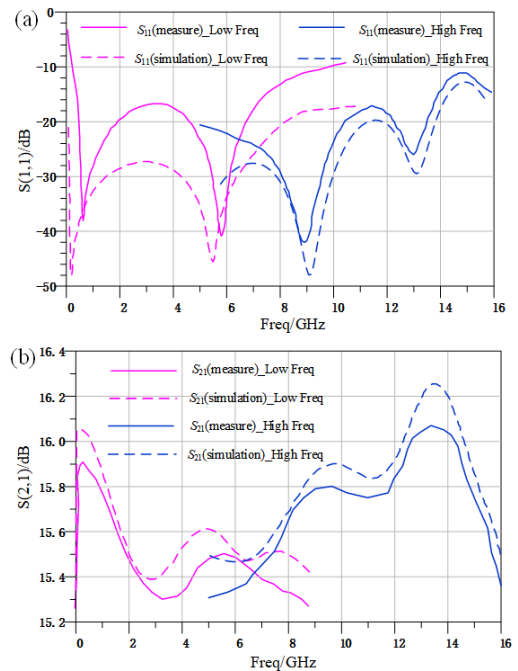


FIGURE 15. Comparison diagram of small signal test and simulation. (a) S<sub>11</sub> curves. (b) S<sub>21</sub> curves.

measurement setup for both large-signal and modulated signals, along with the flowchart of the entire testing procedure. We have divided the PA into two operating modes, high frequency and low-frequency, and the control method is shown in Tab.1.

Firstly, small-signal measurement and analysis of the PA show that it has typical frequency reconfiguration characteristics. PA can perform frequency-reconfiguration at 6.5GHz. As shown in Fig 15,  $S_{11}$  is less than  $-10$  dB for two operating modes;  $S_{21}$  stays near 16 dB, and the gain flatness is maintained at  $\pm 0.4$  dB.

Next, we performed a large-signal measurement on this PA using continuous waves. The results are shown in Fig. 16. The results show that the gain flatness is less than  $\pm 1$  dB and the gain is maintained at a stable level. The PAE reaches around 21% ~ 32%, significantly higher than classic PA.

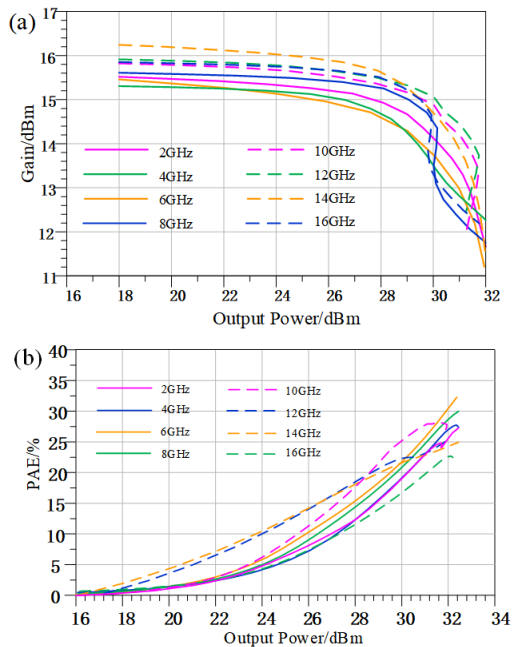


FIGURE 16. Large-signal measurement results.

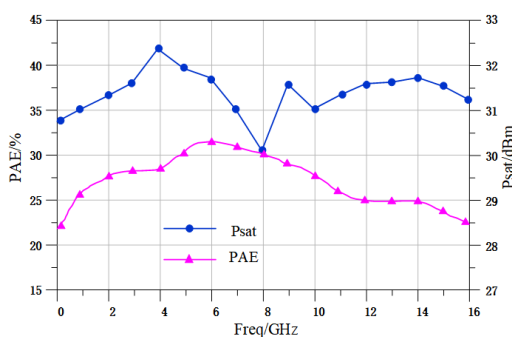


FIGURE 17. Frequency-domain measurement results.

Finally, the measurement results of PA in the frequency domain are shown in Fig. 17. The proposed PA is capable of maintaining a saturation output power of more than 30dB at 0.1 to 16GHz. Compared to traditional DAs (PAE is generally less than 20%), the PA proposed in this paper always maintains the adaptation of the bias and gain module, reducing the leakage of RF signals and increasing the PAE to 21%~32%.

The analysis above shows that there is a degree of deterioration in PA performance at  $f_h$  and  $f_l$ . This is due to the fact that in this paper the analysis is mainly carried out with 2 -stage of reconfigurable inductance, with relatively low fitness at  $f_h$  and  $f_l$ . In practice, more inductances can be used to achieve finer band divisions and increase the fitness of the bias for the entire operating band. The scheme in this paper is therefore high expansibility.

TABLE 2. Performances compared with PA proposed in other articles.

Ref	Bandwidth h/GHz	Gain/dB	Psat/dBm	PAE/%	Size/mm <sup>2</sup>	Bias
[27]	7	23.2	> 40	> 28.8	11.55	Off-chip
[28]	6.5	14	30	18 ~ 24	7.5	Off-chip
[29]	12	15.3	40.3	16 ~ 27	13.8	Off-chip
This work	15.9	16	> 30	21 ~ 32	5.88	On-chip

## V. CONCLUSION

In this paper, a reconfigurable UWB PA is proposed based on reconfigurable technology. We have increased the output power of the PA through cascode cells and modified ATLS. In addition, by using reconfigurable technology, this paper breaks through the limitations of off-chip bias and on-chip spiral inductances on the UWB PA and achieves integration. Based on the above scheme, we have designed a reconfigurable UWB PA operating from 0.1 to 16 GHz using a 0.15um GaAs process. It is capable of providing over 30dBm of output power in the operating band, with a stable gain of around 16dB and PAE of 21%~32%. This paper provides a new scheme for UWB PA research by achieving a breakthrough in gain, bandwidth, and efficiency through an innovative structure.

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