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RESEARCH ARTICLE

MVItem: A Benchmark for Multi-View Cross-Modal Item Retrieval

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ABSTRACT The existing text-image pre-training models have demonstrated strong generalization capabilities, however, their performance of item retrieval in real-world scenarios still falls short of expectations. In order to optimize the performance of text-image pre-training model to retrieve items in real scenarios, we present a benchmark called MVItem for exploring multi-view item retrieval based on the open-source dataset MVImgNet. Firstly, we evenly sample items in MVImgNet to obtain 5 images from different views, and automatically annotate this images based on MiniGPT-4. Subsequently, through manual cleaning and comparison, we present a high-quality textual description for each sample. Then, in order to investigate the spatial misalignment problem of item retrieval in real-world scenarios and mitigate the impact of spatial misalignment on retrieval, we devise a multi-view feature fusion strategy and propose a cosine distance balancing method based on Sequential Least Squares Programming (SLSQP) to achieve the fusion of multiple view vectors, namely balancing cosine distance(BCD). On this basis, we select the representative state-of-the-art text-image pre-training retrieval models as baselines, and establish multiple test groups to explore the effectiveness of multi-view information on item retrieval to easing potential spatial misalignment. The experimental results show that the retrieval of fusing multi-view features is generally better than that of the baseline, indicating that multi-view feature fusion is helpful to alleviate the impact of spatial misalignment on item retrieval. Moreover, the proposed feature fusion, balancing cosine distance(BCD), is generally better than that of feature averaging, denoted as balancing euclidean distance(BED) in this work. At the results, we find that the fusion of multiple images with different views is more helpful for text-toimage (T2I) retrieval, and the fusion of a small number of images with large differences in views is more helpful for image-to-image (I2I) retrieval.

INDEX TERMS Cross-model retrieval, deep learning, item retrieval, contrastive text-image pre-training model, multi-view.

I. INTRODUCTION

Item retrieval has extensive potential applications in fields such as lost item search and product search [\[1\],](#page-11-0) [\[2\],](#page-11-1) [\[3\]. Th](#page-11-2)e objective of item retrieval is to find the item in a gallery that satisfy a given query, where the contents of the gallery are images and the query can be either an image or a textual

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description containing specific features. the current product datasets $[2]$, $[4]$, $[5]$, $[6]$ mainly consist of image-modal datasets with simple categorical labels, lacking effective textual description, which makes it difficult to apply method based this datasets to cross-modal retrieval task.

The contrastive text-image pre-trained cross-modal model, such as CLIP $[7]$ [and](#page-11-6) its derivatives $[8]$, $[9]$, $[10]$, $[11]$, due to its strong generalization capability, can serve as an offthe-shelf cross-modal item retrieval solution for achieving rapid application deployment and saving development costs. However, applying these models to cross-modal item retrieval still faces challenges.

On the one hand, the prevailing image-text datasets, such as Flickr30k [\[12\], M](#page-11-11)S COCO [\[13\]](#page-11-12) and Laion-400m [\[14\],](#page-11-13) contain a lot of content unrelated to item retrieval, such as scenery, people, and buildings. The test result of models on these datasets cannot be used to represent the performance of models on item retrieval.

On the other hand, in real-world scenarios, an image is a specific view sample of an item, while a query is typically a subjective and freely chosen description of the item from a specific view, provided by the user. We speculate

A yellow sofa with a rectangular pillow

FIGURE 1. Misalignment between the query and the positive images in the gallery.

that if there is a spatial misalignment between the query descriptive information and the positive images in the gallery, as shown in Figure [1,](#page-1-0) the retrieval performance is inevitably affected. Therefore, we are concerned about the item retrieval capability of contrastive text-image pre-trained models in multi-view environment.

To address the aforementioned issue, we propose a test benchmark named MVItem to explore the item retrieval capability of contrastive text-image pre-trained retrieval models in multi-view setting. Specifically, we select 158 categories of items from the open-source multi-view item image dataset MVImgNet [\[15\]](#page-11-14) and use MiniGPT-4 [\[16\]](#page-12-0) for auxiliary image annotation, and finally get a high-quality text description for each item sample by manual cleaning and comparison. The content of these texts pertains to the color, shape, texture of items, as well as the relationship between items and background.

On basis of MVItem, we select the representative state-ofthe-art text-image pre-training retrieval models to investigate the performance and explore rule of this models on item retrieval. Additionally, in order to solve the problem of spatial misalignment, we propose an item retrieval strategy based on multi-view feature fusion. Balancing euclidean distance is a common and effective feature fusion approach. However,

we argue that uniformly integrating multi-view information is more beneficial for responding the subjectively random nature of real-world query scenarios. Therefore, we attempt to balance cosine distance, such that the fused feature vector is equiangular with each view feature vector. We obtain the image features of single-view by random sampling, and use cross-validation to simulate the retrieval performance of traditional retrieval methods as the baseline.

All in all, the contribution and key observations of our work can be summarized as follows.

- We propose a test benchmark for multi-view text-image item retrieval named MVItem, which is annotated by MiniGPT-4 based on open-source multi-view image dataset MVImgNet. Through manual cleaning and comparison, MVItem has 2376 high-quality text description for 11880 multi-view item images of 158 major categories.
- We test multiple representative the state-of-the-art text-image pre-training retrieval models, evaluate the performance of these models on item retrieval, analyze deficiency the impact of the design strategies of the models on item retrieval based on the experimental results.
- We devise a multi-view feature fusion strategy, design experimental baselines, and establish multiple test groups to explore the influence of multi-view information introduction on item retrieval which has potential spatial misalignment.
- We find balancing cosine distance (BCD) is generally better than that of balancing euclidean distance (BED) in multi-view image feature fusion. Meanwhile, the fusion of multiple images with different views is more helpful for text-to-image retrieval, and the fusion of a small number of images with large differences in views is more helpful for image-to-image retrieval.

II. RELATED WORK

A. ITEM SEARCH BASED ON IMAGE RETRIEVAL

Item search has a wide range of applications in the field of commodity retail, and its development relies on widely appearing commodity datasets, such as RPC [\[4\], G](#page-11-3)rocery Products Dataset [\[17\],](#page-12-1) RP2k [\[18\],](#page-12-2) Supermarket Produce Dataset [\[19\]. I](#page-12-3)mage retrieval, as a primary technique for item search, usually involves encoding retrieval images into vectors using a pre-trained model of a categorization task [\[20\].](#page-12-4) The retrieval is accomplished by computing the similarity between vectors. Therefore, constructing discriminative feature vectors for image instances is crucial for image retrieval techniques, making contrastive learning the primary methodology for enhancing image retrieval performance, such as Siamese Loss [\[21\], T](#page-12-5)riplet Loss [\[22\]](#page-12-6) and InfoNCE [\[23\].](#page-12-7)

B. CROSS-MODAL RETRIEVAL

Cross-modal retrieval refers to the process of matching and searching between different modalities, aimed at eliminating

the heterogeneity differences among various modalities. This paper focus on investigating text-to-image retrieval. The primary approach for implementing text-to-image retrieval is to seek a method that maps text and image into a shared subspace $[24]$, $[25]$, $[26]$, $[27]$. The emergence of visiontext pre-training model makes the model can be trained once and applied many times, which reduces the threshold of cross-modal retrieval application. CLIP [\[7\]](#page-11-6) is a classic and representative cross-modal pre-training model. BLIP [\[28\],](#page-12-12) [\[29\]](#page-12-13) uses bootstrapping multitasking framework, and achieve the state-of-the-art results on text-to-image retrieval. The key advantage of pre-trained models lies in their zeroshot capability. Zero-shot capability is a highly sought-after performance in open category tasks [\[30\],](#page-12-14) [\[31\],](#page-12-15) [\[32\], s](#page-12-16)uch as the item retrieval discussed in this paper.

C. TEXT-TO-IMAGE RETRIEVAL BENCHMARK

Benchmark is a standard dataset that evaluates the performance of algorithms or models on a particular problem or task. Cola [\[33\]](#page-12-17) is a benchmark for compositional textto-image retrieval, which is used to explore empirical modeling designs to adapt pre-trained vision-text models to reason compositionally. T2I-VeRi [\[34\]](#page-12-18) provides an evaluation platform for text-to-image vehicle re-identification. UFineBench [\[35\]](#page-12-19) introduces a new benchmark for text-based person retrieval with ultra-fine granularity. HRS-Bench [\[36\]](#page-12-20) provides a holistic and objective evaluation scheme for textto-image synthesis tasks. PosterLayout [\[37\]](#page-12-21) provides data and evaluation for content-aware visual-textual presentation layouts. According to the above research, The work of benchmark involves not only collecting and processing data relevant to specific problems, but also establishing reasonable evaluation metrics and designing appropriate experimental methodologies to explore the underlying issues and discover patterns.

III. DESIGN PRINCIPLES OF MVItem BENCHMARK

A. EMPHASIS ON ITEM RETRIEVAL TASK

Item retrieval is a special kind of open-category retrieval task. In contrast to general image retrieval, item retrieval does not include non-item samples such as animals, landscapes and buildings. Additionally, unlike specific image retrieval tasks like vehicle re-identification [\[34\]](#page-12-18) and person retrieval [\[35\],](#page-12-19) item retrieval tasks encompass a diverse range of categories that are not limited to a single major class. Therefore, the generalization advantage and zero-shot learning capability of contrastive text-image pre-training model make it more competent in the task of item retrieval. It is essential to establish a testing scenario that focuses on items in order to examine the performance of the model in item retrieval tasks.

B. EXPLORING THE IMPACT OF SPATIAL MISALIGNMENT ON ITEM RETRIEVAL IN A MULTI-VIEW ENVIRONMENT

The current retrieval task usually ignores the multi-view factor. In real scenarios, user subjectively use image or description of an item from a certain view as the query:

$$
Query = \{Img_{view_x}, Text_{view_x}\}\tag{1}
$$

where *Imgview^x* represents a query image for a certain view *x*, and *Textview^x* represents the corresponding query description for that view.

Gallery can be described as:

$$
Gallery = \{ \{N_1, \ldots, N_M\}, \{P_{view_y}\} \}
$$
 (2)

where N_1 to N_M means there are M negative samples, and *Pview^y* means the positive sample a certain view *y*.

We are concerned about the presence of spatial misalignment between the view *x* in query and view *y* in gallery, which may affect the retrieval performance of the model.

Therefore, we need to devise a method to explore the influence of spatial misalignment on item retrieval in multiview environment, heuristically find a strategy to alleviate spatial misalignment.

IV. DATASET CONSTRUCTION

A. SOURCE OF IMAGE DATA

Our work is based on MVImgNet [\[15\], w](#page-11-14)hich is a large-scale dataset comprising multi-view images, which is originally a dataset for 3D reconstruction [\[38\]](#page-12-22) and encompasses 6.5 million frames extracted from 219,188 videos encompassing objects belonging to 238 classes. The content of MVImgNet focuses on objects commonly encountered in daily-life, excluding scenery, animals, buildings, and other non-item entities, thus satisfying the requirement of image content in item retrieval.

MVImgNet provides labels for every major categories, but simple category labels cannot meet the needs of cross-modal item retrieval. Therefore, further descriptive text annotation work is needed.

B. ANNOTATION AND CLEANING

1) AUTOMATIC ANNOTATION BY MiniGPT-4

Relying solely on manual methods for descriptive annotation is highly subjective and inefficient. Therefore, we employ a lightweight large-scale vision-language generation model, MiniGPT-4 [\[16\], t](#page-12-0)o generate descriptive annotation information. MiniGPT-4 consists of a pretrained image encoder, a large language model (LLM), and a linear layer for aligning visual information to the LLM. The pretrained image encoder employed is a Vit transformer [8] [com](#page-11-7)bined with a Q-Former in BLIP-2 [\[29\]](#page-12-13) and the LLM is Vicuna [\[39\].](#page-12-23)

The annotation process is shown in Fig. [2.](#page-3-0) Each sample in MVImgNet consists of approximately 30 consecutive multiview images, which exhibit minimal noticeable differences between adjacent images. Computing all of them would result in unnecessary computational overhead. Thus, we adopt an evenly sampling approach, capturing images from 5 distinct viewpoints. Next, we encode 5 images with different views respectively, and average the 5 image feature tensors to obtain the final <ImageHere> containing multi-view information.

FIGURE 2. Annotation and cleaning workflow based on MiniGPT-4.

This blue water pump is made of plastic and has a small handle on the side.
This blue water pump has a hose and sprayer that can be adjusted to different angles

The small green wicker basket is sitting on the brown paper. The basket has a
white handle and is made of woven straw. The basket is symmetrical, with a
wreced sim and straight sides curved rim and straight sides

The steel blade of the screwdriver is long and thin, designed to fit into tight
spaces. This is a screw driver lying on a black surface.

This metal pot is dented and has a rusty appearance. The empty pot floor, with no objects or food inside. A stainless steel pot with black handle is on the ground

This toy figure is made of plastic and has a molded design of a character from the SuperMario Bros video game series. The toy is laying down on a patterned sheet with its arms and legs extended outward.

In a green outer layer and warmer has a watermelon pattern, with a green outer layer and a pink inner layer. The hand warmer has a soft and cushioned surface.

The bottle has a white cap and a blue label. The bottle is about half full of a clear liquid that looks like water. It is placed on a gray table.

The lipstick is black and sleek with a silver trim. The lipstick has a slender, elegant design that fits comfortably in the hand. Its bullet shape makes it easy to apply. The matte finish provides a smooth, even coverage.

The black and white hammer is made of metal and plastic. The hammer has a long, thick handle that is sturdy and easy to hold onto. The head of the hammer is flat. The handle has a textured grip.

The pink and red calendar is sitting on a gray blanket. The calendar has 2023 marked with a pink sticker. The calendar is made of a small white paper box and pink content

The T-shirt is design with a brown teddy bear on a black background. It is a black T-shirt on a hanger.

The shoes have a light beige color. The shoes is made of synthetic leather, the soles
have a rough texture. The shoes tongue is also light beige in color and appears to be glued on

The toy duck is made of yellow rubber. There no visible markings or imperfections on the surface of the toy duck. The toy duck has a red mouth and is primarily yellow.

The toy train is blue with a white stripe down the side. The toy train has two pairs of black wheels. There are two black windows on each side of train's caboose. This toy has a smiling face on the front of it, probably na

This little electric razor has a curved, rubberized body that fits comfortably in the hand. The buttons on the front of the razor are large and easy to press. The back of the razor has a glossy, black finish.

This telescope is blue and has black accents. The telescope has a long, slender tube with black cap on one end and a large lens on the other. The telescope has a focus to turn and provides clear images.

FIGURE 3. Image-text data in MVItem.

We have designed a prompt for annotation, incorporating the <ImageHere> and the sample label [Label], which is fed into Vicuna to generate 8 descriptive semantic annotations for manual selection:

Prompt: ###Human:Here's a **[Label]** **<ImageHere>**, add some adjectives to describe what it looks from different views and return eight concise sentences without outputting irrelevant information.### Assistant:**[descriptive annotation]**

We are conducting data annotation on a server equipped with four Tesla V100-DGXS-32GB GPUs running Ubuntu 20.04. The file management format follows MVImgNet,

which ensures consistent major category numbers and sample IDs with MVImgNet.

2) MANUAL CLEANING AND COMPARISON

MVImgNet exists a significant amount of duplicate samples, necessitating manual de-duplication efforts in order to mitigate the issue of redundancy. In addition, MVImgNet includes some categories that are not suitable for item retrieval, such as scattered snacks, root of plant, etc. Therefore, we separate abnormal item categories and select the categories of artifact that are suitable for normal item retrieval need.

bag	bottle	washer	toy vessel	tov train	telephone	table	stove	sofa	skatebord	rifle	pistol	remote control
printer	flowerpot	pillow	piano	mug	motorcycle	microwave	microphone	mailbox	loudspeaker	laptop	lamp	knife
pot	helmet	guitar	bookshelf	faucet	earphone	display	dishwasher	computer keyboard	clock	chair	car	cap
can	camera	cabinet	bus	bowl	bicycle	bench	bed	bathtub	basket	ashcan	airplane	umbrella
plush toy	toy figure	towel	toothbrush	toy bear	toy cat	toy bird	toy insect	toy cow	toy dog	toy monkey	toy elephant	toy fish
toy horse	toy sheep	toy mouse	toy tiger	toy rabbit	toy dragon	toy snake	toy chook	toy pig	rice cooker	pressure cooker	toaster	dryer
battery	curtain	blackboard eraser	bucket	calculator	candle	cassette	cup sleeve	computer mouse	easel	fan	coat rack	guitar stand
can opener	flashlight	hammer	scissors	screw driver	spanner	hanger	jug	fork	chopsticks	spoon	ladder	ceiling lamp
wall lamp	lamp post	light switch	mirror	paper box	wheelchair	walking stick	picture frame	shower	toliet	sink	power socket	bagged snacks
tripod	selfie stick	hair drver	lipstick	glasses	sanitary napkin	tissue paper	rockery	book	projector	percussion	wind instruments	scarf
shoe	skirt	pants	clothing	box	soccer	power strip	toy turtle	bath sponge	glove	badminton	accessory	cigarette
stapler	lighter	key	watch	lock	hairbush	adhensive hook	bell	water pipe adapter	calendar	insecticide	electric saw	inflator
ironmongery	bulb	\sim	$\overline{}$	$\overline{}$	۰			$\overline{}$	$\overline{}$	\sim		

TABLE 1. Major categories selected from MVImgNet.

FIGURE 4. Instance distinction.

Moreover, It is worth noting that annotations based on MiniGPT-4 still show obvious hallucination. Therefore, we generated eight annotations using the model and then manually selected and cleaned 2-4 correct annotations, in order to eliminate the misrepresentation. Finally, these annotations are concatenated to form a complete description of the sample.

During the process of manual selection, it is crucial to ensure the completeness of the semantic information in the chosen annotations and avoid the occurrence of digressive and useless descriptions. Furthermore, efforts should be made to ensure that different annotations depict distinct content, thereby enriching the descriptive information from diverse perspectives and highlighting the features of each viewpoint.

Additionally, we allow the model to replace the label with synonyms, such as replacing "vessel" with "boat" or "soccer" with "ball" in order to preserve diversity in the descriptions.

The partial final results are shown in Fig. [3,](#page-3-1) which contains 5 images of a sample from different viewpoints and a complete sentence of description text.

It is worth noting that, in order to assess the reasonableness of evaluation, we need to ensure that each description corresponds to a single sample instance, avoiding situations where one description corresponds to multiple samples. Therefore, in the process of data cleansing, it is necessary to make further distinctions between approximate semantic annotations, as shown in the Fig. [4.](#page-4-0)

3) DATA STATISTICS

We obtain 2376 non-duplicate item samples from 158 major categories of artifact sampled from MVImgNet, as shown in

VOLUME 12, 2024 119567

Tab[.1,](#page-4-1) with a total of 11,880 images and 2376 text descriptions. Major category consists of multiple subcategories, in order to ensure the variety of samples. For instance, the bag category encompasses various types of bags such as backpacks, ladies shoulder bags, wallets, and briefcases.

V. MULTI-VIEW FEATURE FUSION

A. OVERVIEW

The spatial misalignment between query and the gallery can potentially affect the performance of retrieval. To address this issue, we propose a novel item retrieval strategy based on multi-view feature fusion to explore the influence of spatial misalignment on item retrieval in multi-view environment, as illustrated in Fig. [5.](#page-5-0)

Unlike traditional retrieval methods that use item image as the basic retrieval unit, we use a fused multi-view image feature of a sample as the fundamental retrieval unit in the gallery.

$$
I_{\text{gallery}} = \text{Fusion}\left(I_{v_1}, I_{v_2}, \dots, I_{v_n}\right) \tag{3}
$$

where *Igallery* represents the multi-view image fusion feature of a sample in gallery, and $I_{v_1}, I_{v_2}, \ldots, I_{v_n}$ represent the image features of each sample view.

We aim to investigate the item retrieval performance of the state-of-the-art contrasting text-image pre-training models and design a baseline representing traditional retrieval way to verify the effectiveness of the multi-view feature fusion approach in alleviating spatial misalignment.

B. FUSION STRATEGY

The essence of multi-view image feature fusion is to balance the distance between the query feature vector and the feature vectors of multi-view images of a sample, in order to introduce information from multiple views. Image multi-view features are fused before the actual query, and the query is unknowable at fusion operation. In the face of this situation, we have two approaches. One is to collect a large amount of query history information and design a feature fusion module to learn a fusion feature approach that conforms to the historical query preferences. Alternatively, in the absence of query participation, we can directly fuse the current multi-view image feature information.

FIGURE 5. Item retrieval strategy based on multi-view feature fusion.

In this paper, as an exploratory approach, we directly fuse multi-view image feature information, and observe the performance of balancing euclidean distance and balancing cosine distance in item retrieval.

1) BALANCING EUCLIDEAN DISTANCE(BED)

We can achieve balance in the euclidean distance by summing and averaging multi-view image feature vectors.

$$
Fusion_{BED} (I_{v_1}, I_{v_2}, \dots, I_{v_n}) = \frac{I_{v_1} + I_{v_2} + \dots + I_{v_N}}{N}
$$
 (4)

where *N* represents the number of views.

2) BALANCING COSINE DISTANCE(BCD)

The vector fusion method of BED tends to bias the final fused vector towards some specific given vectors. However, it is desirable to obtain a fusion result that is not skewed towards any given vector. Balanced cosine distance means to find a vector such that the angle between the vector and the given multi-view image feature vector is equal. In the above problems, there are generally multiple vectors satisfying the conditions, and we need to obtain the vector with the smallest angle with the multi-view image feature vector as the fusion feature.

In cases where the dimensionality of vectors is high, obtaining exact solutions using linear algebra methods can be challenging. Therefore, we resort to optimization algorithms, Sequential Least Squares Programming (SLSQP), to obtain the optimal solution.

a: OBJECTIVE FUNCTION

We choose the sum of the squared differences in angles between the target vector and the multi-view image feature vectors as the objective function.

$$
f(I_x) = \sum_{i=1}^{N} \left(\frac{I_x I_{v_i}}{||I_x||_2 ||I_{v_i}||_2} - \sum_{j=1}^{N} \frac{I_x I_{v_j}}{||I_x||_2 ||I_{v_j}||_2} / N \right)^2
$$
(5)

where I_x represents the target vector for the iterative calculation, and $|| \cdot ||_2$ represents the magnitude of the vector.

b: CONSTRAINT CONDITION

The image features of N views of a sample are similar, and we want to obtain an average vector that is approximately consistent with the feature vectors of these N views. Therefore, the angle between the target vector and the image feature vectors of N views should be smaller than the maximum angle among these N viewpoint vectors.

$$
\forall n \in N, g(I_x) = cosine(I_x, I_{v_n})
$$
 (6)

$$
g(I_x) \leq \max_{k,w \in N} \text{ cosine}(I_{v_k}, I_{v_w}) \tag{7}
$$

c: LAGRANGE FUNCTION FOR ITERATIVE OPTIMIZATION

The Lagrangian function for iterative training is constructed based on $f(I_x)$ and $g(I_x)$.

$$
L(I_x, \lambda) = f(I_x) + \lambda * g(I_x)
$$
 (8)

TABLE 2. Multi-view image feature cosine distance balancing algorithm based on Sequential Least Squares Programming (SLSQP).

where λ represents Lagrange coefficient. We choose error tolerance as the stopping criterion for iteration, and the overall algorithmic workflow is illustrated in Tab. [2.](#page-6-0)

VI. BENCHMARK SETTING

A. SETTING

1) BASELINE DESIGN

We assume that adopting the fusion feature of multi-view images in gallery can alleviate the impact of spatial misalignment on item retrieval. In this case, the retrieval unit in the gallery is a fusion feature of the sample multi-view image, and there is only one positive sample in the gallery.

Correspondingly, our baseline group uses single-view images in gallery as the retrieval unit, and there is also only one positive sample. We adopt cross-validation to ensure the randomness of positive sample in the gallery. Each validation group randomly selects one view image from each sample as a retrieval unit in the gallery. We severally set 50 cross-verification groups for Image-to-image(I2I) and Text-to-image(T2I) retrieval tests, and took the average results as the baseline for I2I and T2I.

2) THE INFLUENCE OF MULTI-VIEW FEATURE FUSION

By controlling the fused multi-view image number of item sample, we explore the influence of multi-view information introduction on item retrieval which has potential spatial misalignment. Specifically, we set up the fusion of 2-5 images with the biggest view difference of a sample to observe the T2I performance effect between them and the baseline respectively, as shown Fig. [6.](#page-6-1)

Similarly, we also have established multi-view fusion test group for I2I as well. For each MVItem sample, one image from the set of five images is selected as the query, and the remaining 2-4 images are fused based on maximizing the difference in viewpoints, resulting in the creation of four test groups.

B. MODELS SELECTED FOR EVALUATION

We are not only concerned with the performance of current CLIP-related the state-of-the-art pre-trained text-image

FIGURE 6. Multi-view feature fusion test groups.

models on item retrieval tasks, but also aim to further elucidate the impact of the underlying design strategies of these models on item retrieval. Therefore, we summarize the technical characteristics of the selected model:

1) CLIP [\[7\]](#page-11-6)

The fundamental idea of CLIP is to create an $N \times N$ matrix of image-text pairs, while simultaneously training an image encoder and a text encoder, with the aim of maximizing the cosine similarity of *N* positive image-text pairs and minimizing the cosine similarity of $N^2 - N$ negative text pairs. CLIP uses cross-entropy loss function (InfoNCE-like) to achieve contrastive representation learning for multi-class N-pair.

2) LONG-CLIP [\[40\]](#page-12-24)

Vanilla CLIP integrates absolute positional encoding with a suggested text input length limit of 77 tokens, which makes it challenging to apply in scenarios that require detailed descriptions. Therefore, Long-CLIP extends the text input length to 248 characters and performs fine-tuning on longtext image-text pairs to enhance the model's fine-grained retrieval capabilities.

3) ALBEF [\[41\]](#page-12-25)

The distinctive feature of ALBEF lies in aligning the image-text features before the fusion and incorporating momentum distillation. Feature alignment also adopts Image-Text contrastive Learning similar to CLIP to achieve semantic alignment between images and text at the overall level. Image-Text Matching and Masked text Modeling are used to complete the training of feature fusion. ALBEF introduces Momentum Distillation, where Momentum model is the exponential moving average of ALBEF that is constantly trained. Momentum Distillation makes each training of the

model take into account the prediction distribution of the previous version.

4) CoCa [\[9\]](#page-11-8)

The distinctive feature of CoCa is to pre-train the encoder by adding generative pre-trained task branches of captioning. CoCa can be approximated as adding an Encoder-Decoder Captioning to CLIP. Contrastive learning still employs the cross-entropy loss function and utilizes the maximum likelihood function to quantify the self-regressive captioning loss.

5) SLIP [\[10\]](#page-11-9)

The distinctive feature of SLIP is to combine the visual representation contrast learning of SimCLR [\[42\]](#page-12-26) with the image-text contrast learning of CLIP. SLIP simultaneously emphasizes the role of image information in the model while aligning modalities.

6) BLIP-2 [\[29\]](#page-12-13)

BLIP-2 leverages a frozen image encoder to bootstrap text-image representation learning and achieves multimodal semantic alignment through Image-Text contrastive learning similar to CLIP. The bootstrapping process involves a image-grounded text generation task and multiple trainable queries(Usually 32). Q-former is the main content of BLIP-2. We mainly pay attention to the performance of image encoder and text encoder of Q-former on item retrieval.

C. RETRIEVAL PERFORMANCE METRIC

1) RANK@1

Accuracy is a crucial metric for evaluating retrieval models. In the context of multi-view feature fusion, where the gallery contains only one feature vector representing the positive sample, it is essential to assess the model's ability to retrieve this positive sample in one query. We use *Rank*@1 to represent the accuracy of a single retrieval of the model.

$$
Rank@1 = \frac{P}{N} \times 100\% \tag{9}
$$

where *N* indicates the total number of queries, and *P* indicates the correct number of queries.

2) MEAN SIMILARITY DISTRIBUTION (mSD)

In addition to accuracy, we also need to quantitatively evaluate the model's feature extraction and alignment effect. Mean similarity distribution (mSD) [\[35\]](#page-12-19) deems continuous similarity values more realistically reflect the model's retrieval ability, thus overcoming the challenge faced by mean Average Precision (mAP) in accurately quantifying a model's retrieval performance from the same ranking results.

Item retrieval requires the ability to quantitatively assess the model with precision, rather than simply evaluating its performance based on continuous similarity pattern. Therefore, we choose mSD as the metric to evaluate the performance level of item retrieval.

$$
Top_n = \{S_1, S_2, \dots, S_n\} \tag{10}
$$

mSD requires computing the positive samples and negative samples ratio (PNR) in Top_n as well as the average similarity precision (ASP).

PNR calculate the normalized average similarity ratio between positive and negative:

$$
PNR = 1 - e^{-kx} \tag{11}
$$

where x is the average similarity ratio between positive and negative samples, and *k* is set to 1 as default.

ASP can be calculated as:

$$
ASP = \frac{1}{n^+} \sum_{k=1}^{n^+} \frac{\sum_{i=1}^{j_k} s_i^+}{\sum_{i=1}^{j_k} s_i}
$$
(12)

where $\{j_1, j_2, \ldots, j_{n^+}\}\$ represents the rankings of positive samples.

The similarity distribution (SD) of *Topⁿ* can be calculated by the product of PNR and ASP. Finally, mSD can be obtained by averaging SDs of all rank lists.

VII. EXPERIMENTS

A. IMPLEMENTATION DETAILS

We conduct experiments based on MVItem to investigate the performance of different pre-trained models on item retrieval. Specifically, we explore the impact of multi-view feature fusion on addressing potential spatial misalignment in item retrieval from both text-to-image and image-to-image perspectives.

The pre-trained models actually come in multiple versions. In order to fairly explore the performance of different models on item retrieval and analyze the impact of model design strategies on item retrieval. We uniformly select the model version under the Vit-L/14 image encoder. Specifically, CoCo [\[43\]](#page-12-27) and Flickr30k [\[12\]](#page-11-11) are currently the two most frequently used types of multimodal generalpurpose datasets. To compare the performance of these two datasets on the item retrieval task, we select the open-source models ALBEF_CoCo and ALBEF_Flickr30k. In the process of evolution, we utilize a plug-and-play text encoder based on Long-CLIP to achieve text feature encoding for texts exceeding 77 tokens of CLIP. We calculate mean similarity distribution(mSD) using top-5 returned results. The experiments are performed on 1 GeForce RTX 4090.

B. EXPERIMENTAL RESULT

1) TEXT-TO-IMAGE RETRIEVAL (T2I)

The results of the text-to-image item retrieval are shown in Tab. [3](#page-8-0) and Tab. [4.](#page-8-1)

a: ITEM RETRIEVAL PERFORMANCE OF PRE-TRAINED MODELS

The baseline reflects the fundamental capabilities of the model, with performance rankings on the T2I task as follows:

TABLE 3. Rank@1 of text-to-image item retrieval in MVItem.

TABLE 4. Top-5 mSD of text-to-image item retrieval in MVItem.

Model			BED			Baseline				
	2-view	3 -view	4-view	5-view	2-view	3 -view	4-view	5-view		
CLIP [7]	29.8718	30.5987	30.9306	31.0374	29.9013	30.662	30.9781	31.0781	28.7812	
$Long-CLIP$ [40]	33.8084	34.2275	34.3954	34.4064	33.9304	34.2332	34.4081	34.3498	31.4896	
ALBEF_CoCo [41]	23.6539	23.9102	23.9556	23.8382	23.7106	23.9371	24.0113	23.8721	21.6893	
ALBEF Flickr30k [41]	23.6412	23.7286	24.0838	23.8524	23.6891	23.8235	24.1036	23.8729	21.7038	
$CoCa$ [9]	44.7037	45.4201	45.1279	45.2534	44.7929	45.4189	45.1254	45.2591	42.8573	
$SLIP$ _Large $[10]$	14.4595	14.4565	14.6376	14.6591	14.4602	14.4592	14.6569	14.6631	12.7255	
BLIP2 CoCo [29]	40.0116	39.8231	39.9742	40.0813	40.0921	39.9802	40.0213	40.1293	37.8517	

CoCa > BLIP2 > LongCLIP > CLIP > ALBEF_Flickr30k > ALBEF $CoCo > SLIP$ Large.

The commonality between CoCa and BLIP2 lies in the presence of a cross attention module in their model structures, distinguishing them from subsequent models lacking this particular architecture. This suggests that cross attention plays a significant role in cross-modal alignment.

The superior performance of Long-CLIP over CLIP suggests that models trained with fine-grained text descriptions exhibit improved cross-modal alignment. Therefore, for item retrieval task, it is advisable to collect a more extensive set of detailed item description texts in order to enhance the model's capability to adapt to nuanced descriptions.

For ALBEF, compared with CoCo, Flickr30k has a more detailed text description, which makes the model trained based on Flickr30k better than the model trained based on CoCo on T2I when the model structure is the same. At the same time, even ALBEF also has cross-attention modules, the difference in the dimensions of training data scale and diversity between datasets, like Flickr30k and CoCo, and the large-scale training data collected from the Internet, like CLIP, has led to significant disparities between ALBEF and CLIP in the performance of item retrieval tasks based on MVItem.

It is worth noting that SLIP performs poorly on T2I, indicating that the direct introduction of image self-supervised learning on the basis of cross-modal contrast learning may significantly weaken the effect of cross-modal alignment.

b: ANALYSIS OF PERFORMANCE CHARACTERISTICS ON ITEM RETRIEVAL

Tab. [3](#page-8-0) illustrates that the current state-of-the-art textimage pre-training models still struggle to achieve perfect performance in multi-view item retrieval. To summarize and analyze the performance characteristics of models in item retrieval, we conduct tests specifically focusing on the bag category and present retrieval negative examples for each model in a single query, as shown in Fig. [7.](#page-9-0)

We can find that as the performance of the retrieval model improves, the characteristics of negative examples undergo change. In our experiment, SLIP performs the worst in T2I, with the negative example having only vague correspondences between certain words and the query. For example, in Fig. [7,](#page-9-0) it might have wrongly retrieved Mickey Mouse's bag for ''cartoon,'' even though in the positive case, "cartoon" refers to a chick.

With the improvement in performance, some accurate correspondence between negative examples and queries can be achieved. Such as in the first retrieval example of ALBEF_Flickr30k, the negative case accurately corresponds to the word ''golden''. However, due to the neglect of descriptions like ''chain straps'', it incorrectly retrieves a handbag decorated with a golden sheen.

In terms of characteristics, CLIP appears to be a performance boundary, with negative examples being globally matched with the queries. The added descriptions have some impact on retrieval, however, there still exists a significant difference between negative examples and positive examples.

FIGURE 7. Partial retrieval negative examples in bag category.

Models with better performance compared to CLIP exhibit a high degree of similarity between the negative and positive examples regarding their types and characteristics, with errors typically arising from more detailed and specific descriptive attributes. For instance, in the first retrieval example of BLIP-2, the negative example is also an envelope-shaped bag, differing from the positive example in terms of color depth and the absence of a fringe pendant. As seen in CoCa, the negative and positive examples are nearly identical in characteristics, with errors often stemming from the query itself being insufficiently detailed or ambiguous.

c: INFLUENCE OF SPATIAL MISALIGNMENT ON T2I

The superior retrieval performance of the multi-view feature fusion over the baseline indicates the non-negligible impact of spatial misalignment on T2I in real-world scenarios. Tab. [4](#page-8-1) provides a more detailed reflection of the performance difference between post-feature fusion and pre-feature fusion, as shown by the mSD values. From Tab. [4,](#page-8-1) it can be observed that the overall performance of BCD is superior to that of BED, even though there a instance where the performance of BED rarely exceeds that of BCD, such as with CoCa where

FIGURE 8. The relationship between the number of views and mean similarity distribution (mSD) variation in text-to-image item retrieval.

the BCD value is 45.4189 for the 3-view case, very closed to 45.4201 for BED.

The introduction of noise in multi-view images is inevitable, as it may include images with the greatest

TABLE 5. Rank@1 of image-to-image item retrieval in MVItem.

TABLE 6. Top-5 mSD of image-to-image item retrieval in MVItem.

Model		BED			Baseline			
	2-view	3 -view	4-view	2-view	3 -view	4-view		
CLIP [7]	63.3857	63.3378	63.3143	63.3902	63.3373	63.3139	57.7569	
Long–CLIP [40]	64.3104	64.0589	64.0566	64.3096	64.0859	64.1608	60.8277	
ALBEF CoCo ^[41]	61.8078	61.8176	61.7943	61.8101	61.8237	61.8004	59.9821	
ALBEF_Flickr30k [41]	62.0873	61.9582	61.9511	62.0881	62.1021	61.9875	59.1411	
$CoCa$ [9]	63.9029	63.7902	63.6432	63.9125	63.7562	63.6481	60.5324	
$SLIP$ _Large $[10]$	64.5468	64.4893	64.4257	64.5301	64.4691	64.4986	62.1412	
BLIP2_CoCo [29]	63.2641	63.0896	63.0041	63.3781	63.1075	63.0618	60.5997	

FIGURE 9. The relationship between the number of views and mean similarity distribution (mSD) variation in image-to-image item retrieval.

differences in viewing angles compared to the query. This noise can potentially lead to slightly lower performance in experimental groups that integrate a greater number of views compared to those with fewer views. However, this does not detract from the advantages that multi-view image fusion brings to T2I applications.

We have summarized the variation in mSD over the baseline on T2I after multi-view feature fusion, as shown in the Fig. [8.](#page-9-1) With the increase in the number of views, the mSD shows an increasing trend, indicating that the fusion of multiple images of one item with different views is beneficial for improving their T2I performance.

2) IMAGE-TO-IMAGE RETRIEVAL (I2I)

In addition, we also explore image-to-image retrieval of textimage pre-training models. The results of the image-to-image item retrieval are shown in Tab. [5](#page-10-0) and Tab. [6.](#page-10-1)

a: PERFORMANCE OF PRE-TRAINED MODELS

The performance of the model in the I2I task is significantly better than that in the T2I task, with the performance ranking under baseline as follows: SLIP_Large > LongCLIP > BLIP2 > CoCa > ALBEF_CoCo > ALBEF_Flickr30k > CLIP.

SLIP demonstrates outstanding performance on I2I tasks, indicating that incorporating self-supervised image learning on the basis of cross-modal contrast learning can significantly enhance the discriminative power of the model for image features.

LongCLIP demonstrates superior performance indicating that fine-grained textual descriptions are advantageous for enhancing the understanding and discriminative capabilities of models for image. Conversely, CLIP exhibits a comparatively inferior performance on the baseline, suggesting that short texts and ambiguous descriptions may have an impact on the image feature construction for item.

b: INFLUENCE OF SPATIAL MISALIGNMENT ON I2I

The superior retrieval performance of the multi-view feature fusion over the baseline also indicates the non-negligible impact of spatial misalignment on I2I in real-world scenarios. It is worth noting that, unlike T2I, the fusion of multi-view features leads to significant changes in the ranking

of the model's I2I capability compared to the baseline. Specifically, from the perspective of mSD, SLIP_Large > $LongCLIP > CoCa > CLIP > BLIP2 > ALBEF$ Flickr30k > ALBEF_CoCo.

We consider the fusion performance of BCD on I2I to be generally superior to that of BED. Even though rare results of BCD exhibits slightly lower scores compared to that of BED on Long-CLIP (64.3096 for BCD vs. 64.3104 for BED) and CoCa (64.5301 for BCD vs. 64.5468 for BED). We guess that the subtle differences in performance may be attributed to variances between optimization and precision calculations.

We have also summarized the variation in mSD over the baseline on I2I after multi-view feature fusion, as shown in the Fig. [9.](#page-10-2) We find that CLIP exhibits the most significant improvement in I2I tasks after multi-view fusion. With the increase in the number of views, the variation in mSD is relatively flat but shows a subtle downward trend, indicating that the fusion of a small number of images with significant view disparities plays a more beneficial role in I2I.

VIII. CONCLUSION AND DISCUSSION

In this paper, we have constructed a multi-view text-image item dataset to explore the performance of state-of-theart text-image pre-training retrieval models in simulated real-world item retrieval scenarios. We collect multiple views of item samples from the open-source multi-view item dataset MVImgNet, and design an annotation process for multi-view images based on MiniGPT-4. Through manual cleaning and comparison, we obtain a test set for multi-view item retrieval, which consists of 2376 samples belonging to 158 major categories, each accompanied by a high-quality description and images from five different views.

To investigate the potential impact of spatial misalignment in item retrieval under real-world scenarios, we propose an item retrieval strategy based on multi-view feature fusion. Building upon this approach, we select the current stateof-the-art text-image pre-training retrieval models, design experimental baselines, establish performance evaluation metrics, create multiple test groups, and conduct experiments to explore the performance. Our main findings are as follows:

- Potential spatial misalignment phenomenon in real world scenarios has a significant impact on item retrieval, but this effect can be effectively alleviated through multi-view image feature fusion. In the context of text-to-image retrieval, the fusion of multiple images with different views may be more effective. However, for image-to-image retrieval, a small number of images with large differences in views may be more effective.
- In the multi-view image feature fusion process, balancing cosine distance (BCD) is more effective than balancing euclidean distance (BED).
- The model incorporating cross attention modules, when provided with a sufficiently large training data set size comparable to that of CLIP, exhibits strong performance in text-to-image item retrieval tasks.

• On the basis of contrastive learning like CLIP, directly incorporating image self-supervised learning significantly decreases the performance of text-to-image retrieval, while significantly boosting the performance of image-to-image retrieval.

In summary, based on MVItem, we explore the performance of text-image pre-trained cross-modal models on item retrieval in real-world scenarios and design effective methods and strategies to mitigate the spatial misalignment issue. In the future, it is necessary to build a large-scale multi-view text-image training dataset, which could help to promote the development of item retrieval.

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