








Low-Coherence Brillouin Optical Correlation-Domain Reflectometry Based on Periodic Pseudo-Random Modulation

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Abstract—Brillouin optical correlation-domain reflectometry (BOCDR) is a technique for measuring the distribution of strain and temperature along an optical fiber, offering advantages such as operation with light injection from one end of the sensing fiber, relatively high spatial resolution, and random-access capability to sensing points. However, it faces a trade-off between spatial resolution and measurement range. In response, low-coherence BOCDR using a randomly modulated light source has been proposed, but this method requires a variable delay line for scanning the measurement position, limiting the measurement range. This paper proposes low-coherence BOCDR based on periodic pseudo-random modulation to address this issue and demonstrates its proof-of-concept operation. First, the dependence of the light source output spectrum on modulation parameters is investigated using a delayed self-homodyne method, showing the potential to resolve the trade-off between spatial resolution and measurement range. Subsequently, we demonstrate the capability of measuring strain distribution along optical fibers without a variable delay line under multiple conditions. Further, we show through simulation that this method can perform more accurate distributed strain measurements than standard BOCDR.

Index Terms—Brillouin optical correlation-domain reflectometry, distributed sensing, low coherence, pseudo-random modulation, strain sensing, temperature sensing.

I. INTRODUCTION

DISTRIBUTED optical fiber sensors using Brillouin scattering have been extensively studied as key technologies

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in smart structures and materials [1], [2]. These sensors utilize Brillouin frequency shift (BFS) changes dependent on strain and temperature to interpret distributed strain and temperature information. Among various spatial resolution principles—time-domain [3], [4], [5], [6], frequency-domain [7], [8], and correlation-domain [9], [10], [11], [12], [13], [14], [15], [16], [17]—the focus in this context is on correlation-domain methods, which are known for their relatively high spatial resolution and unique random-access capability.

Brillouin-based correlation-domain methods can be divided into two: Brillouin optical correlation-domain analysis (BOCDA) [9], [10], [11], [12] and Brillouin optical correlation-domain reflectometry (BOCDR) [9], [13], [14], [15], [16], [17], [18], [19]. BOCDA, utilizing stimulated Brillouin scattering (SBS) in a two-end injection system, achieves a high signal-to-noise ratio (SNR) and rapid operation due to the strong signal power of SBS and lock-in detection. However, its reliance on electro-optic modulators, including a single-sideband modulator and an intensity modulator, and a lock-in amplifier leads to higher cost and system complexity. In contrast, BOCDR, employing spontaneous Brillouin scattering, operates with a lower SNR than that of BOCDA but can continue measurements up to a breakage point in the fiber under test (FUT) owing to its one-end light injection configuration.

In a standard configuration of BOCDR [13], [14], a sinusoidal-modulated laser is used as the light source. Due to the periodic nature of the sinusoidal wave, multiple correlation peaks (measurement points) are formed periodically along the FUT. Typically, the measurement range is limited to include just one correlation peak within the FUT. By controlling the modulation frequency, the correlation peak is swept along the FUT to facilitate distributed measurements. However, a significant challenge is the trade-off between measurement range and spatial resolution. Although special schemes such as temporal gating [17], double modulation [18], and chirp modulation [19] have been proposed to mitigate this issue, they have not completely eliminated the fundamental trade-off.

To address the trade-off issue in standard BOCDR, low-coherence BOCDR (LC-BOCDR) [20], [21], [22] was proposed, utilizing a low-coherence light source. A randomly modulated laser has been used in LC-BOCDR systems, but note that in LC-BOCDA, in addition to randomly modulated lasers [23],

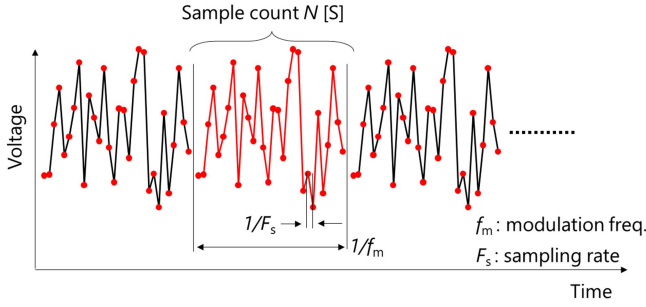


Fig. 1. Voltage waveform used for periodic pseudo-random modulation.

sources including amplified spontaneous emission (ASE) [24], [25] and chaotic lasers [26], [27] have also been employed. These light sources enable high spatial resolution determined by their coherence length, effectively addressing the direct trade-off between spatial resolution and measurement range. However, a correlation peak occurs only at the isochronous point, necessitating a variable delay line for sweeping the correlation peak along the FUT, which limits the measurement range. Pseudo-random binary sequence (PRBS) modulation in LC-BOCDA has been reported to overcome measurement range limitations [28], [29], but it still requires two-end light injection into the FUT.

In this work, we propose and demonstrate the basic operation of an LC-BOCDR system with periodic pseudo-random modulation, which operates without a variable delay line and uses single-end light injection. First, we investigate the dependence of the light source's output spectrum on modulation parameters using a delayed self-homodyne method, showcasing its potential to mitigate the trade-off between spatial resolution and measurement range. Subsequently, we demonstrate the ability to measure strain distribution along FUTs under various conditions without the need for a variable delay line. Finally, simulations indicate that this method can achieve more accurate strain distribution measurements than the standard configuration.

II. PRINCIPLE

In our proposed LC-BOCDR configuration, periodic pseudo-random modulation created by an arbitrary waveform generator (AWG) is directly applied to the driving current of the light source, leading to the modulation of its output frequency. Unlike conventional LC-BOCDR based on non-periodic random modulation, this method generates multiple correlation peaks (measurement points) along the FUT, allowing sweeping of correlation peaks other than the zeroth order along the FUT without the need for a variable delay line.

The waveform used in the periodic pseudo-random modulation is shown in Fig. 1. The operation starts by generating a sequence of random voltages following a Gaussian distribution. We set a voltage range and a sample count N [S], representing the number of samples in the sequence; the unit "S" stands for "samples". This sequence is then repeatedly output at a specified sampling rate F_S [S/s] (see Fig. 1). The modulation frequency f_m , defined as the repetition rate of the single-period sequence,

is given by:

$$f_m = \frac{F_S}{N}. \quad (1)$$

Similar to sinusoidal modulation, the beat signal of the light modulated with periodic signals creates correlation peaks at equal intervals centered around the isochronous point. The interval between peaks, d_m , is given by:

$$d_m = \frac{c}{2n f_m} = \frac{c N}{2n F_S}, \quad (2)$$

where c is the speed of light in vacuum, and n is the group index of the FUT core. By controlling F_S , the interval of correlation peaks is sequentially varied, sweeping a specific single peak along the FUT.

The spatial resolution of LC-BOCDR based on periodic pseudo-random modulation is expected to follow the same formulation as conventional non-periodically modulated LC-BOCDR. Existing LC-BOCDR systems use a laser modulated with a random sequence. As the modulation amplitude increases, the spectrum broadens and approaches a Gaussian shape, reducing the coherence of the output light. The spectra of both the reference light and Stokes light also approach Gaussian forms. The Stokes light returning from the isochronous point in the FUT interferes with the reference light, generating a zeroth-order correlation peak. While ideally, the cross-correlation of these two lights should be calculated, with sufficient modulation amplitude, their coherence lengths converge. Hence, we use the self-correlation-represented coherence function instead. When the spectral density of the light source is given by:

$$S(\nu) = \frac{2\sqrt{\frac{\ln 2}{\pi}}}{\Delta\nu} \exp\left[-4 \ln 2 \left(\frac{\nu - \nu_0}{\Delta\nu}\right)^2\right], \quad (3)$$

the normalized coherence function $r(\tau)$ can be determined from the Wiener-Khinchin theorem as:

$$r(\tau) = \exp\left[-\frac{\pi^2}{4 \ln 2} \cdot (\Delta\nu\tau)^2\right] \exp(-j2\pi\nu_0\tau), \quad (4)$$

where ν_0 and $\Delta\nu$ are the central frequency and occupied bandwidth of the modulated light source. The coherence time τ_c , defined as the time when $r(\tau)$ decays to 1/2, is given by [30], [31]:

$$\tau_c = \frac{2 \ln 2}{\pi} \cdot \frac{1}{\Delta\nu}. \quad (5)$$

This means that only Stokes light within $\pm\tau_c$ time difference interferes with the reference light. Converting this to a distance on the FUT gives the spatial resolution. The distance Δz between two points on the FUT and the time difference τ for Stokes light to reach from these points are related by:

$$\Delta z = \frac{c\tau}{2n}. \quad (6)$$

Thus, from (5) and (6), the spatial resolution is given by:

$$\Delta z = \frac{c 2 \ln 2}{\pi n \Delta\nu}. \quad (7)$$

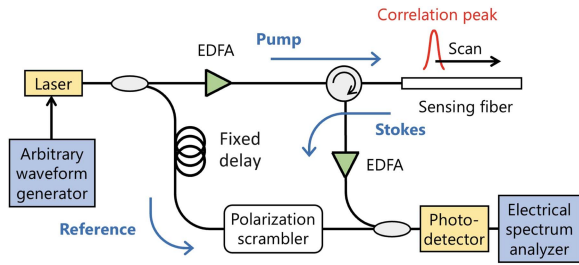


Fig. 2. Experimental setup of LC-BOCDR based on periodic pseudo-random modulation. EDFA: erbium-doped fiber amplifier.

III. EXPERIMENTS

A. Experimental Setup

The experimental setup for the LC-BOCDR based on periodic pseudo-random modulation is shown in Fig. 2. Its basic configuration mirrors that of a standard BOCDR setup. A distributed-feedback laser at 1550 nm was directly modulated using an AWG (SG-4222, IWATSU). The output light at 10 dBm was split into signal and reference paths via a coupler. The signal light was amplified to about 25 dBm using an erbium-doped fiber amplifier (EDFA, LXI2000, Luxpert), then injected into the FUT and the returning Stokes light was further amplified to approximately 3 dBm with another EDFA (ErFA1215, FITELE). The reference light, its polarization state averaged by a polarization scrambler (PCD104, General Photonics), was then combined with the Stokes light through a coupler. A fixed delay line with a length of 500 m was inserted in the reference path to utilize a non-zeroth-order correlation peak (the 1st-order peak was used in the demonstrations below). The heterodyne signal was converted into an electrical signal by a photodetector (PD, PR-12-B-M, Optilab) and observed with an electrical spectrum analyzer (R3273, Advantest) as the BGS. Averaging was performed 30 times on the ESA, and the sampling rate of the BFS of each sensing position was approximately 1.0 Hz, currently restricted by the switching speed of the AWG controlled using a general-purpose interface bus (GPIB).

B. Spectral Measurement

We investigated the dependence of the light source spectrum modulated by periodic pseudo-random modulation on the sampling rate. Changes in the spectral shape when varying the sampling rate were observed using a delayed self-homodyne method [32]. The modulation conditions were set to an offset of 7.0 V, a peak-to-peak amplitude of 6.0 V_{p-p}, and a sample count of 1000 S, with a sampling rate varied from 10 to 60 MS/s in 5 MS/s increments. The output light from the source was injected into a Mach-Zehnder interferometer, with one path including a 10 km delay fiber to provide significant time delay. The frequency resolution was about 10 kHz. The combined signals were detected with a PD and observed with an ESA (resolution bandwidth = 1 MHz, video bandwidth = 3 kHz). Gaussian fitting was performed on the obtained spectra to determine the frequency bandwidth. A portion of the observed homodyne spectrum is shown in Fig. 3(a). The spectrum overall increased

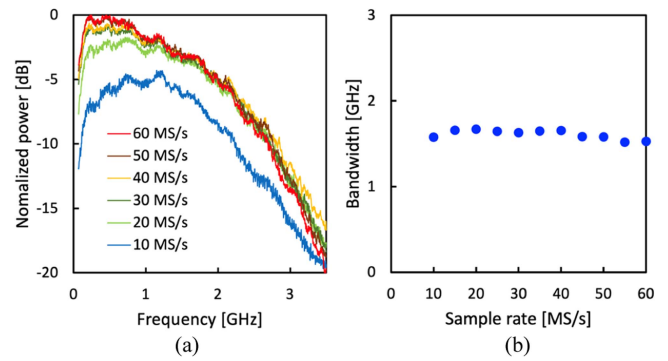


Fig. 3. Sampling rate dependencies on (a) power spectrum and (b) frequency bandwidth.

up to 20 MS/s but beyond that, only the central components were strengthened. This is probably due to the laser's response not keeping up with the abrupt voltage changes in parts of the pseudo-random sequence, resulting in a reduced frequency dispersion. The bandwidth, shown in Fig. 3(b), remained relatively constant despite changes in the spectrum with the sampling rate, with a standard deviation of approximately 50 MHz. This result indicates that the sampling rate, a variable that determines the measurement range, does not affect the spatial resolution, thus not leading to the trade-off issue typically encountered in standard sinusoidal-modulation-based BOCDR.

C. Distributed Strain Measurements

To demonstrate the proof-of-concept operation of our system, we performed distributed strain measurements on FUTs under different conditions. The $\Delta\nu$ value was set to 1.65 GHz, resulting in the theoretical spatial resolution of 5.5 cm according to (7). Initially, we performed a relatively short-range measurement using a dispersion-shifted fiber (DSF) with a BFS of approximately 10.5 GHz. The structure of the FUT is shown in Fig. 4, consisting of a 140 cm DSF sandwiched between 16 m and 2 m standard silica single-mode fibers (SMFs) through fusion splicing. The 16 m silica SMF segment was a combination of 15 m and 1 m SMFs, connected using an angled-physical-contact (APC) connector, with slightly different BFS values. In addition, the 2 m SMF section was constructed from two 1 m SMFs, also connected using an APC connector, with slightly varied BFS values. Near the distal open end, a bending loss was strategically applied. The different BFS of each fiber section allowed us to treat the DSF segment as a pseudo-strain region. We varied the sampling rate from 57.20 to 58.62 MS/s with a sample count of 290 S, sweeping the 1st-order correlation peaks over 12 m around the strain region to acquire the BFS distribution. The theoretical measurement range was approximately 493 m. The results are shown in Fig. 5(a) and (b). Fig. 5(a) shows the BFS distribution along the entire measurement length, while Fig. 5(b) focuses on the 2.8 m surrounding the strain region. A steep BFS decrease of about 360 MHz was observed over approximately 140 cm, corresponding to the DSF length, which indicates successful detection of the pseudo-strain. Note that, in Fig. 5(a), abrupt BFS changes of about 40 MHz were observed around 15.0 and

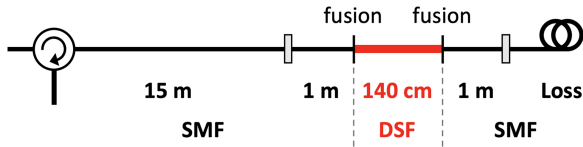


Fig. 4. Structure of the FUT used in the measurement with a shorter range. DSF: dispersion-shifted fiber, SMF: single-mode fiber.

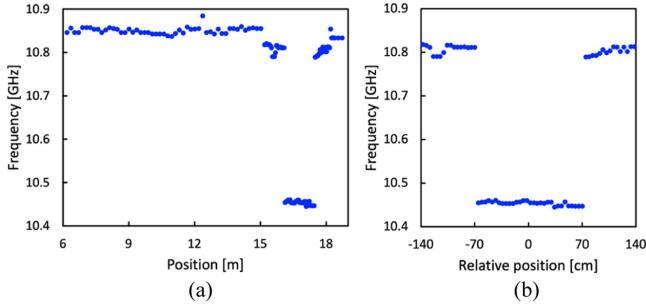


Fig. 5. Measured BFS distributions (a) along a ~ 12 m fiber section and (b) around a 140 cm DSF section.

18.4 m, which are attributed to the use of different types of SMFs.

Subsequently, we extended the measurement range and conducted distributed strain measurement on an FUT exceeding 100 m in length. The structure of the FUT is illustrated in Fig. 6, where approximately 0.5% strain was applied to a 120 cm section near the SMF tip. With a sample count of 320 S and a sampling rate varying from 57.0 to 60.0 MS/s, a correlation peak was swept over 72 m around the strain region to acquire the BFS distribution. The theoretical measurement range was approximately 544 m. The results are displayed in Fig. 7(a) and (b). Fig. 7(a) shows the BFS distribution for the entire measurement length, and Fig. 7(b) focuses on the 160 cm surrounding the strain region. The measured BFS change at the strained section, calculated from the averaged BFS values in the strained and non-strained sections, was approximately 220 MHz, corresponding to the BFS dependence on strain of 440 MHz/%, which closely aligns with a typical value. The high symmetry in the BFS distribution around the strained section suggests minimal systematic measurement error caused by the phase delay between amplitude modulation (AM) and frequency modulation (FM) in the laser [33], [34], [35].

As a final demonstration, we conducted a 100-m-range distributed strain measurement with a much shorter strained section. In this experiment, the delay line length was set to 10 km, utilizing the 4th-order correlation peak. The structure of the FUT is shown in Fig. 8, where approximately 0.4% strain was applied to a 10 cm section near the SMF tip. The FUT included two segments of 47 m SMFs tightly wound on mandrels, which exhibited higher BFSs compared to the loose sections. The $\Delta\nu$ value was set to 1.85 GHz, resulting in a theoretical spatial resolution of 4.8 cm. With a sample count of 290 S and a sampling rate varying from 89.3 to 91.1 MS/s, a correlation peak was swept over 100 m range, including the strained section, to acquire the BFS distribution. The theoretical measurement range was approximately 325

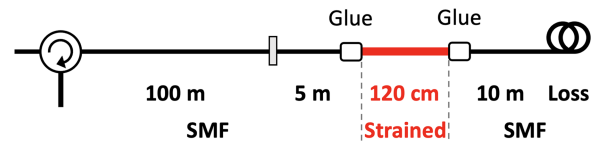


Fig. 6. Structure of the FUT used in the measurement with a longer range.

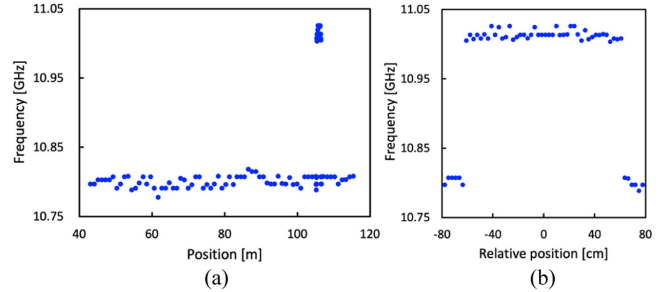


Fig. 7. Measured BFS distributions (a) along a ~ 72 m fiber section and (b) around a 120 cm strained section.

m. Fig. 9(a) shows the measured BFS distribution over the 100 m range. The SMF sections tightly wound on mandrels were clearly detected, exhibiting a BFS of approximately 10.96 GHz. The fluctuation in BFS is relatively large, which is expected due to the nonuniform strain applied to the SMFs wound on mandrels. At a relative position of approximately 98.5 m, the BFS change at the 10 cm strained section was also distinctly observed. The magnified view around the 10 cm strain is shown in Fig. 9(b). The BFS change amounted to approximately 180 MHz, which moderately agrees with the applied strain of 0.4%. The ratio of the measured range (~ 100 m) to the detected strain length (10 cm) is approximately 1000, surpassing the theoretical maximal value for the standard configuration (~ 540), which is the ratio of the theoretical measurement range to the theoretical spatial resolution. This clearly demonstrates the advantage of the periodic pseudo-random modulation configuration. It is noteworthy that the ratio of the theoretical measurement range (~ 325 m) to the theoretical spatial resolution (~ 4.8 cm) in this demonstration exceeds 6700.

IV. SIMULATION

Conventional randomly modulated LC-BOCDR is known not to produce measurement errors due to AM-FM phase delay [20]. However, whether periodic pseudo-random modulation is affected by AM-FM phase delay was a question we aimed to investigate. Following the method described in Ref. [35], we simulated the strain distribution measurements of our system. We distinguish between “intrinsic BGS,” representing the BGS at each position along the FUT, and “measured BGS,” the BGS as observed by BOCDR. These two BGS distributions fundamentally differ, with the measured BGS distribution derived from the square of the two-dimensional convolution of the beat spectrum and intrinsic BGS distribution. The beat spectrum is defined as the power spectrum obtained from the Fourier transform of the cross-correlation between reference and signal lights.

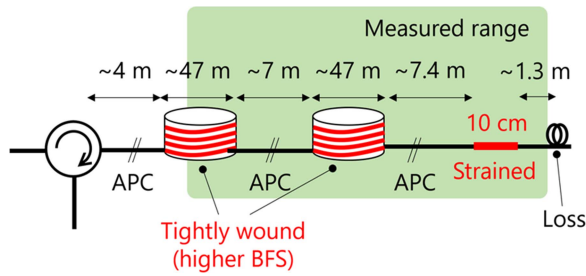


Fig. 8. Structure of the FUT used in the measurement with a longer range and a shorter strain.

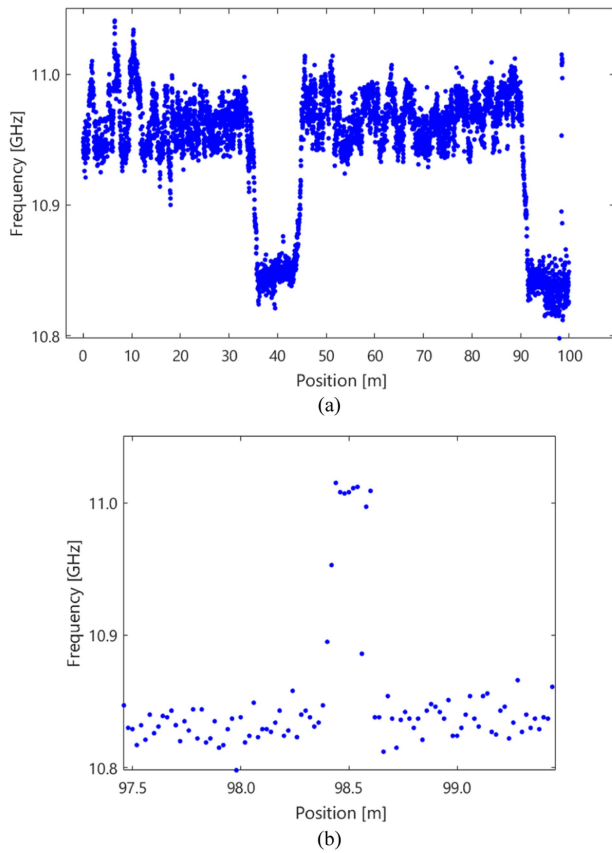


Fig. 9. Measured BFS distributions (a) along a ~ 100 m fiber section and (b) around a 10 cm strained section.

For standard sinusoidal-modulation-based BOCDR, the typical beat spectrum is shown in Fig. 10(a). The modulation conditions were: frequency modulation amplitude = 4 GHz, modulation frequency = ~ 1 MHz, intensity modulation power ratio = 3 dB, AM-FM phase delay = $\pi/4$, spatial resolution = ~ 0.24 m. The measurement conditions were: measurement range = ~ 100 m, FUT length = 5 m. The beat spectrum showed a sharp peak at relative position = 0 m, with an inverse sine distribution at other positions. The presence of AM-FM phase delay causes asymmetry in the beat spectrum. In contrast, for periodic pseudo-random-modulation-based LC-BOCDR, a typical beat spectrum is illustrated in Fig. 10(b). The measurement conditions were: sample count = 300 S, sampling rate = 60 MS/s, measurement range = ~ 500 m, assuming a Gaussian random sequence with a bandwidth of 1.65 GHz. The beat

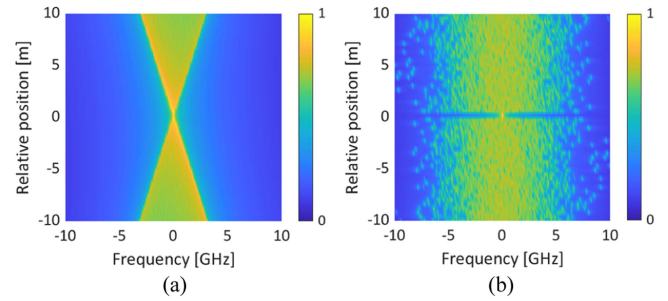


Fig. 10. Comparative beat spectra for (a) standard BOCDR with sinusoidal modulation and (b) LC-BOCDR with periodic pseudo-random modulation. The color bars show the normalized powers.

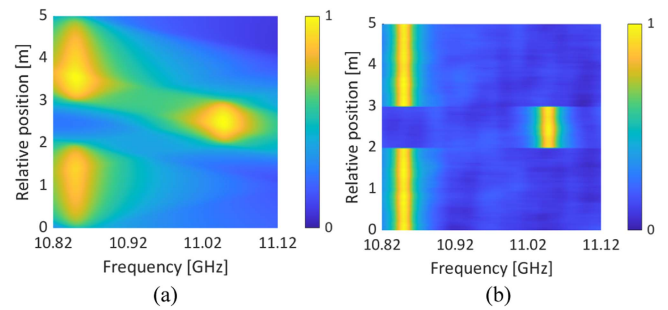


Fig. 11. Comparative “measured BGS” distributions for (a) standard BOCDR with sinusoidal modulation and (b) LC-BOCDR with periodic pseudo-random modulation. The color bars show the normalized powers.

spectrum showed a sharp peak at relative position = 0 m, with a Gaussian-like distribution at other positions. Even with AM-FM phase delay, the beat spectrum remained symmetric.

Finally, by calculating the two-dimensional convolutions of the beat spectra and intrinsic BGS distributions for both methods, we obtained the measured BGS and BFS distributions. The conditions for the intrinsic BGS distributions were: strain region = 1 m, strain magnitude = 0.4%. The comparisons of measured BGS distributions and BFS distributions for both methods are shown in Figs. 11(a), (b) and 12, respectively. The BFS distribution measured by LC-BOCDR closely resembled the actual strain distribution, indicating accurate results. These findings suggest that periodic pseudo-random-modulation-based LC-BOCDR can also reduce systematic measurement errors caused by AM-FM phase delay.

V. CONCLUSION

This study introduced a new approach in LC-BOCDR by employing periodic pseudo-random modulation, overcoming the conventional trade-off between spatial resolution and measurement range. Through experiments, we showed the feasibility of this method for distributed strain measurements along FUTs, with the advantage of not requiring a variable delay line. The delayed self-homodyne method revealed the modulation parameters’ impact on the output spectrum of the light source, validating the potential to maintain the spatial resolution while extending the measurement range. The simulation results confirmed that this approach yields more accurate strain measurements compared to standard BOCDR, free from systematic errors

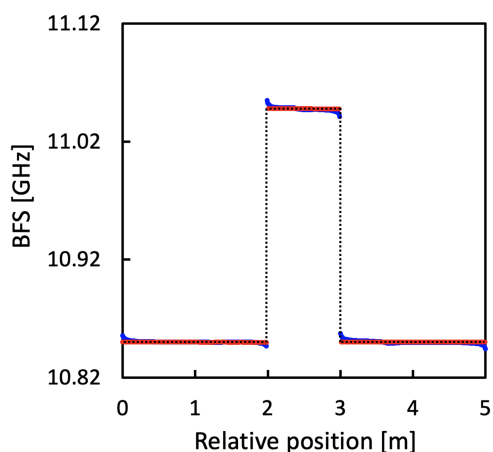


Fig. 12. BFS distributions for standard BOCADR (represented in blue) and periodic pseudo-random-modulation-based LC-BOCADR (represented in red). The black dotted lines indicate the intrinsic strain distribution, which closely aligns with the red plots.

associated with the AM-FM phase delay. This proof-of-concept sets the stage for future explorations into system optimization and in-depth performance analysis, such as enhanced spatial resolution, extended measurement range, increased measurement speed, and improved accuracy, vital areas for subsequent investigation.

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