



Research Article

Frequency-Self-Adaptive Radio Frequency Power Harvester Enabled by Shape-Reconfigurable Liquid Metal

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Abstract — Radio frequency (RF) energy harvester as an efficient tool for capturing and converting the flourishing ambient RF energy provides a promising solution for long-term powering the wireless sensor networks and the Internet of things (IoTs). However, the actual distribution of the environmental RF signals is dynamically frequency-dependent due to the diverse wireless terminals only interacting with specified frequencies. To take full advantage of the RF energy carrying this characteristic, an intelligent RF energy harvester is in demand to automatically sense the frequency information of an incident signal and conduct the corresponding RF-to-direct current transformation process. Here, to the best of my knowledge, a frequency-self-adaptive RF harvester is first presented with the help of the shape-reconfigurable liquid metal, which can precisely identify and efficiently convert an arbitrary signal from the frequency span of 1.8 to 2.6 GHz. Companion with a microcontroller unit and a tensile system, the dynamic functionality of the entire system is comprehensively demonstrated, showing promising potential to significantly advance various fields, including sustainable IoT applications, green wearable technologies, and self-powered devices.

Keywords — Liquid metal, Radio frequency power harvesting, Frequency-self-adaptive, Broadband rectification.

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I. Introduction

Amid the landscape of burgeoning wireless terminals and a looming energy crisis, radio frequency (RF) energy stands as a promising man-made renewable resource that has garnered substantial attention [1]–[3]. Unlike time-dependent

renewable sources like solar [4]–[6] and tide [7], ambient RF power is perpetually accessible in densely populated areas [8]–[10], presenting a convenient avenue for harvesting and utilization. However, its inherent frequency characteristics, which have originally contributed to enhancing wireless communication speed and capability [11]–[12], paradoxi-

cally pose a challenge for RF energy harvesting. This challenge stems from the discrete signal channels of various technologies such as Bluetooth (2.4 GHz) [13], Wi-Fi (2.4 GHz and 5.8 GHz) [14], and the diverse bands of cellular networks like 5G (700 MHz, 1.9–2.6 GHz, 3.5 GHz, and 4.9 GHz) [15], each dynamically balanced and often regionally distributed [16]–[18]. In essence, while the continuous nature of ambient RF power is conducive to harvesting, the need to rectify this power into direct current (DC) introduces the requirement of recognizing the frequency information embedded in blind-source signals. Accomplishing this recognition and optimizing the capture performance of the harvester become a prerequisite. Thus, a compelling solution emerges: the imperative development of a novel frequency-self-adaptive RF energy harvester. This innovation would intelligently accommodate the ambient electromagnetic spectrum's variations and achieve efficient RF-to-DC conversion. Surprisingly, despite its significance, such research remains conspicuously absent thus far.

A classical RF energy harvester is traditionally comprised of two integral components: a receiving unit (typically an antenna [19]–[21] or metamaterial/metasurface [22]–[24]) responsible for capturing incoming RF signals, and a corresponding RF-to-DC conversion segment (usually a rectifier) [25]–[27]. Within this established design framework, achieving a frequency-self-adaptive RF energy harvester necessitates the incorporation of two intertwined elements: a frequency-reconfigurable receiver and a converter optimized to match the operational bandwidth. While extensive research has been conducted on broadband converters [28]–[30], the dynamic receiver component still faces certain limitations, including challenges related to modulation bandwidth and depth [31]–[33]. Consequently, a compelling avenue for scientific investigation lies in the advancement of receiver technologies. Recent developments have introduced the concept of employing p-type-intrinsic-n-type (PIN)-diode-embedded antennas, which offer the ability to discretely control their operational frequencies through the manipulation of integrated PIN diode states, toggling between the “ON” and “OFF” states to achieve this control [34]–[36]. For instance, a receiving antenna containing six PIN diodes was designed in [35], which can support 36 frequency states in a broad frequency range from 2.35 to 3.43 GHz. Nevertheless, the extent of tunable frequencies achievable through this approach remains constrained by the number of PIN diodes employed – specifically, utilizing n PIN diodes allows for a maximum realization of $2n$ coherent states, lacking the capacity for the requisite degree of arbitrary control. In response to these limitations, the integration of varactor diodes has been explored to establish tunable receiving antennas [37]. These antennas enable continuous adjustment of their operational frequency within a confined frequency range, achieved by smooth variations in the capacitance of the embedded varactor diodes. However, the potential of this method is inherently curtailed by the fixed receiver pattern and the constrained range of varactor

diode modulation. Consequently, the dynamic modulation range for operational frequency remains challenging to significantly expand using this technique, limiting its practical applicability.

Interestingly, both aforementioned strategies rely on the manipulation of the antenna's equivalent capacitance, guided by classical LC resonance principles [37]. However, in order to make substantial strides in enhancing dynamic performance, it becomes imperative to introduce novel design paradigms that offer greater flexibility for constructing highly efficient RF power receivers. An important consideration is that the receiver's equivalent capacitance and inductance, which play a pivotal role in determining its operational frequency, are directly influenced by its pattern structure [38]. Thus, a breakthrough can be achieved by reconfiguring the pattern to suit specific requirements. In this regard, numerous efforts have been made to address these urgent needs, resulting in a plethora of new technologies such as origami [39], “magic angle” [40], and shape memory materials [41]. However, due to the limitations of complex 3D or 2D configurations and performance stability, these strategies still lack practical applications in electromagnetic-feature-reconfigurable antennas. In fact, to fulfill the above-mentioned needs, highly conductive materials with deformation properties are necessary, of which the electrical conductivity can maintain stable despite deformation. Based on these considerations, liquid metal (LM) boasts outstanding electrical conductivity and fluidity, making it an ideal candidate for achieving the desired functionalities [42], [43]. Nowadays, taking advantage of these unique merits, LM has been widely adopted to implement flexible pressure sensors [44], [45], temperature sensors [44], current limiter [46], and phase shifters [47]. Besides, lots of dynamic RF devices also have been achieved with the help of LM, such as frequency-reconfigurable antennas [48]–[57], radiation pattern-reconfigurable antennas [58], [59], bandwidth-reconfigurable antennas [60], and stretchable filter [61], reflecting the sufficient possibilities of using LM to realize the desired object.

Herein, leveraging the capabilities of LM, we introduce an innovative frequency-tunable RF energy harvester, as illustrated in Figures 1(a) and (c). The architecture encompasses an LM-based mechanically frequency-reconfigurable receiving antenna and a high-efficiency broadband rectifier network, facilitating exceptional RF-to-DC conversion efficiency across the spectrum from 1.8 to 2.6 GHz. Crucially, our design features a dual “∞”-shaped receiver deliberately engineered to ensure continuous frequency tuning within the band of 1.46 to 2.7 GHz. This tuning aligns seamlessly with the converter's frequency range, and it can be achieved by applying external strain up to 100%, following the interrelationship depicted in Figure 1(b). Expanding upon this foundation, we progress to the realization of a frequency-self-adaptive RF energy harvester, depicted in Figure 2(a). This advanced system integrates a microcontroller unit (MCU) and a comprehensive tensile system, en-

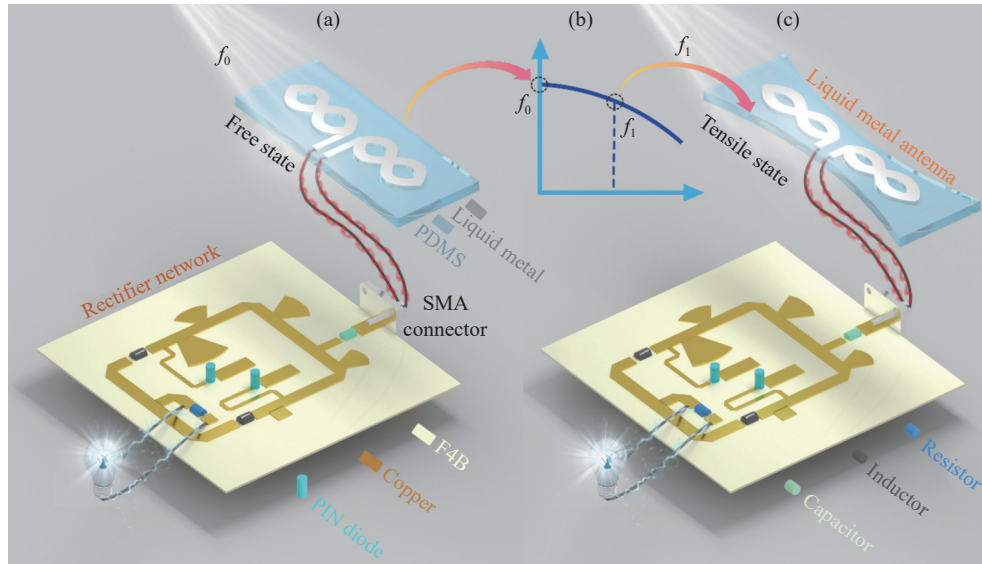


Figure 1 (a) Free state of the mechanically frequency-tunable RF energy harvester; (b) Relationship between operational frequency and tensile ratio of the LM-based antenna; (c) Tensile state of the frequency-tunable RF energy harvester. (F4B denotes the type of the dielectric plate; f_0 means the initial frequency; f_1 indicates another frequency different from f_0 ; PDMS: polydimethylsiloxane).

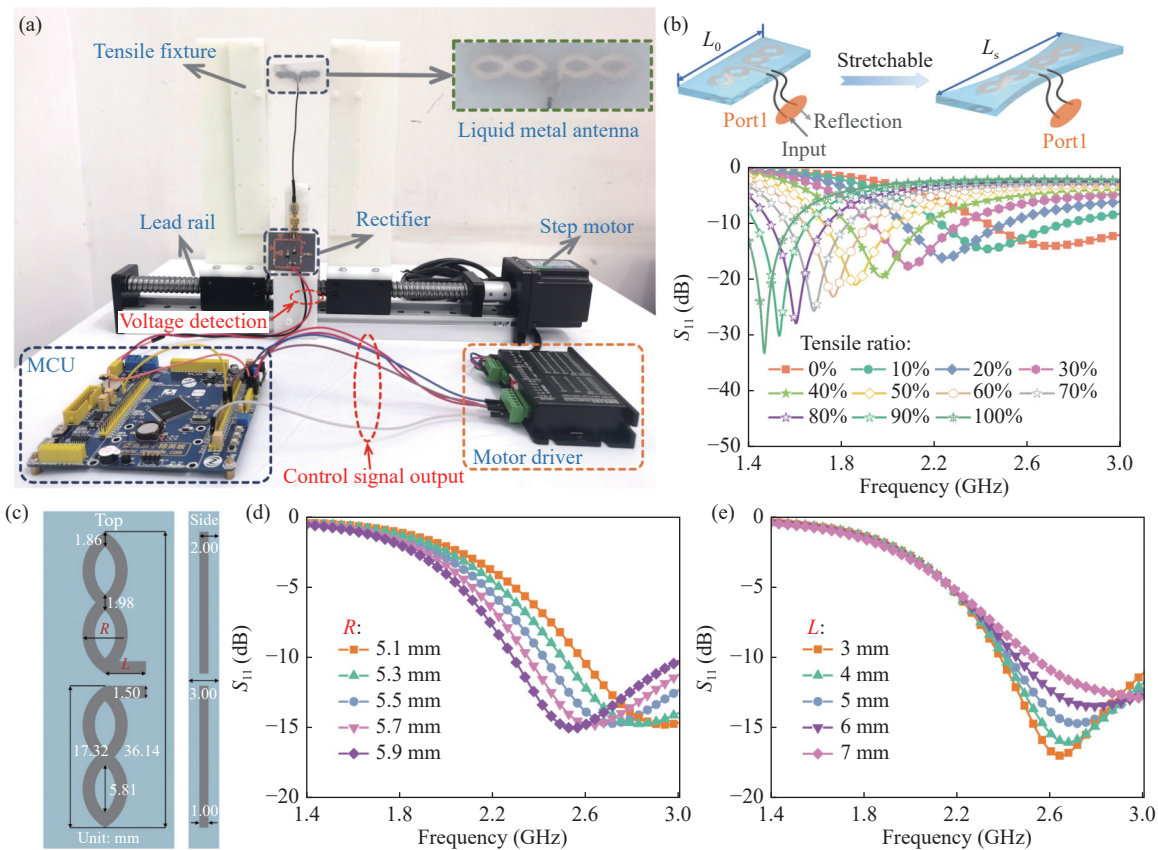


Figure 2 (a) Illustration of the proposed frequency-self-adaptive RF energy harvester. (b) Simulated port reflection coefficient S_{11} curves of the stretchable LM-based antenna under a tensile ratio varying from 0% to 100%. (c) Detailed structural parameters of the LM-based frequency reconfigurable antenna; Simulated S_{11} of the proposed antenna as a function of frequency with different values of (d) R and (e) L .

comprising a tensile fixture, lead rail, step motor, and its driver. The MCU, equipped with voltage detection capabilities, monitors the evolving DC voltage output from the rectifier network. Concurrently, it generates displacement signals to govern the step motor, orchestrating adjustments in

strain applied to the LM-based antenna. Employing an intricately devised detection and feedback circuit, the LM-enhanced system adeptly discerns the frequency characteristics of the input signal. Subsequently, it fine-tunes the applied strain on the flexible antenna to align with an optimal

value based on their correlated relationship, akin to the depiction in Figure 1(b). This perpetual real-time adaptation ensures the maintenance of peak RF power reception, consequently yielding a corresponding optimal DC power output. In summary, through ingenious integration of LM technology, our research yields a frequency-tunable RF energy harvester, progressing into a self-adaptive configuration. This transformative technology boasts potential implications in the realm of energy harvesting, perpetuating optimal power capture through continuous frequency tracking and dynamic strain modulation.

II. Theory and Design

Before assembling the total system, an LM-based antenna for dynamically capturing the frequency-varying RF signal via changing the externally applied strain should be obtained first to determine the working frequency bandwidth. To achieve the frequency-reconfigurable functionality, as shown in Figure 2(b), a dual “∞”-shaped antenna is designed based on the LM and embedded into a flexible polydimethylsiloxane (PDMS) substrate with the relative permittivity of 4.2. Our design resembles a spring structure that can maintain shape stability when stretched even at great tensile ratios, favoring consistent radiation patterns.

We subjected the designed antenna configuration to a broadband RF signal spanning from 1.4 to 3.0 GHz, which was introduced through Port1 for unveiling its RF energy capture capabilities, as illustrated in Figure 2(b). Notably, with an incremental increase in the tensile ratio, a discernible trend emerges: the peak of the port reflection coefficient (S_{11}) progressively shifts towards lower frequencies (Figure 2(b)). This shift mirrors a coherent and monotonous relationship (shown by the orange solid line in Figure 3(a)), aligning harmoniously with the previously established requirement. Simultaneously, the corresponding RF energy capture capability is vividly depicted by the solid green line in Figure 3(a). Employing the reciprocity theorem [62], we deduce that the power ratio reflected and detected at Port1 (Figure 3(a)) provides a direct window into the receiving performance of our proposed antenna. Remarkably, even amid deformation, our design continues to exhibit robust RF energy capture prowess, attributed to the pronounced ultra-low reflection phenomenon at Port1. This alignment with the prerequisites for efficient energy harvesting showcases the design's adeptness. Furthermore, the actual characteristics of the fabricated sample (depicted in Figure 2(a)) were meticulously measured to validate their impact on the ultimate integrated system's performance. As depicted in Figure 3(a), the measured outcomes (indicated by star icons) closely reflect the simulated results, attesting to a high degree of consistency. Any disparities between the simulated and measured operational frequencies can be ascribed to the precision of RF cable positioning concerning the LM-based antenna pattern. The detailed procedure for the fabrication of the LM-based antenna and its tensile property are described in Supplementary Note S1 and Fig-

ure S1 of the **Supporting Information**. Note that the strong agreement endows the proposed antenna with working frequency selectivity as appropriate strain is applied, which can be regarded as the foundation of the final RF energy harvester. Here, it needs to be emphasized that when design this antenna, the effect of the curvature radius (R) of the “∞”-shaped structure (Figure 2(d)) and the length (L) of the feeding line (Figure 2(e)) on the S_{11} of the proposed LM-based antenna (Figure 2(c)) has been comprehensively analyzed to determine its structural parameters. As shown in Figure 2(d), with the increase of R , the corresponding resonance frequency of the antenna gradually moves to lower frequencies, which can be attributed to the growth of its electrical length. Therefore, to ensure the initial resonance frequency stay at 2.69 GHz (namely 5G band), 5.5 mm was selected as the optimal value of R . Additionally, the S_{11} of the antenna can be improved when the feeding line is shortened as shown in Figure 2(e). Finally, comprehensively considering the concomitant redshift, 5 mm was chosen as the value of L . The other detailed structural parameters of the reconfigurable antenna can be obtained in Figure 2(c).

Alongside its tunable working frequency and impressive RF power reception efficiency, another noteworthy aspect emerges when observing the surface currents along the dual “∞”-shaped patterns, as exemplified in Figure 3(b). These surface current distributions consistently exhibit the characteristic traits of a half-wavelength dipole, featuring maximal current densities at the center while gradually diminishing to zero along the antenna's arms [63]. This behavior resembles a sine function with half period, a pattern that endures even when considering variations in stretching ratios. This unique surface current pattern aligns harmoniously with classical electromagnetic theory, giving rise to the potential for omnidirectional radiation patterns. The inherent nature of the current distribution underscores the capability of our LM-based antenna to facilitate omnidirectional reception, even in the face of diverse incident angles. In essence, this further accentuates the advantageous position of our antenna design, proficiently capturing input RF power from a variety of angles. Subsequently, to verify the excellent radiation performance of the antenna under original and stretched states, the corresponding simulated three-dimensional (3D) (first row), simulated and measured two-dimensional (2D) (second row) radiation patterns are supplied in Figure 3(c). It is obvious the H-plane scattering pattern is evenly distributed in all directions while a “∞”-shaped pattern is in the orthogonal plane (namely E-plane), which is consistent with the radiation behaviors of a half-wavelength dipole antenna as predicted. Furthermore, the measured results consistently align with the simulated ones, even when the sample is subjected to different external strains, verifying the correctness of our design.

Then to further showcase the impact of stretching on the antenna performance, the realized gain, radiation efficiency and polarization feature of the stretchable LM-based

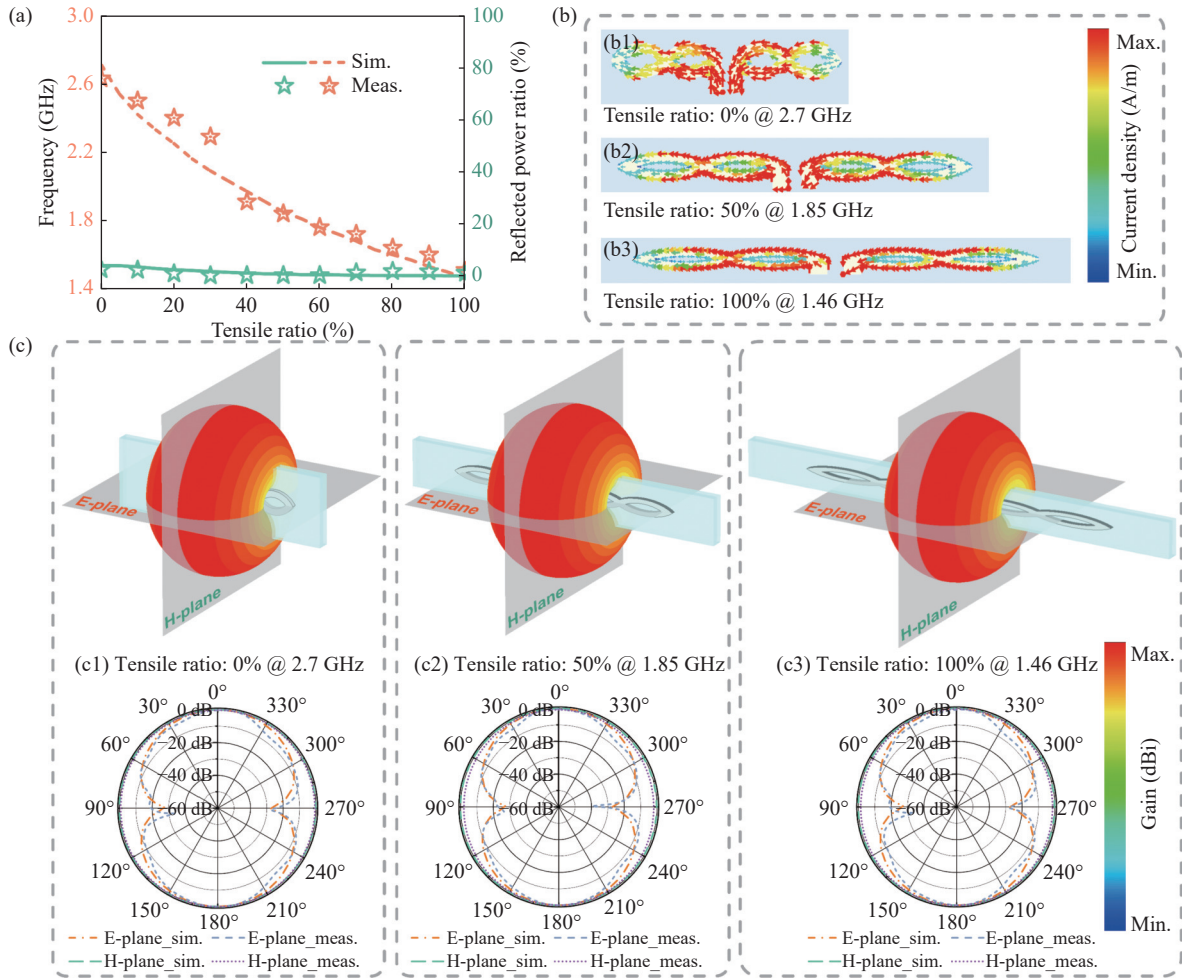


Figure 3 (a) Simulated and measured operation frequency and corresponding reflected power ratio of the stretchable antenna as a function of tensile ratio. (b) Surface currents and (c) 3D/2D radiation patterns of the stretchable antenna applied with different strains (corresponding different operation frequencies): (b1) and (c1) Free state @ 2.7 GHz; (b2) and (c2) Tensile ratio of 50% @ 1.85 GHz; (b3) and (c3) Tensile ratio of 100% @ 1.46 GHz. (Max. stands for maximum, Min. for minimum, sim. for simulation, meas. for measurement).

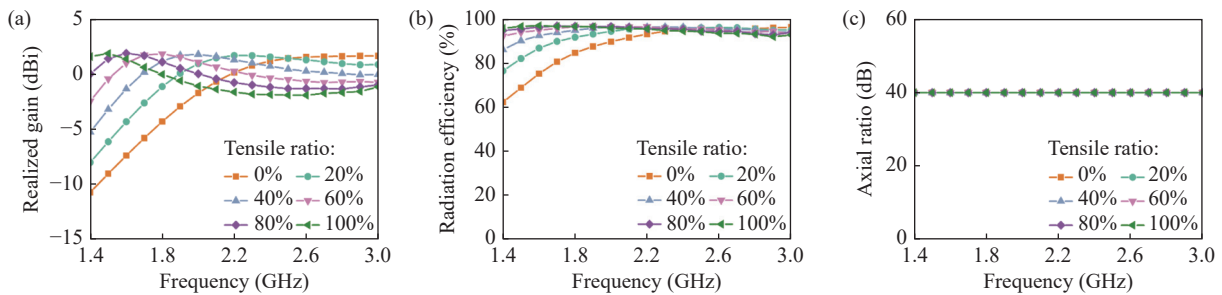


Figure 4 (a) Simulated realized gain, (b) radiation efficiency, and (c) axial ratio of the stretchable LM-based antenna as the tensile ratio varies from 0% to 100%.

antenna were simulated and presented in Figure 4. As shown in Figure 4(a), with the increase of the tensile ratio, the maximum realized gain of our design gradually shifts toward lower frequencies, conforming to the change regular of the resonance frequencies (shown in Figure 2(b) and Figure 3(a)). Additionally, the corresponding radiation efficiency at these frequencies can be significantly improved as the tensile ratio increases (Figure 4(b)), favoring the efficient capture of ambient RF power. Finally, the ultra-high

axial ratio (about 40 dB, Figure 4(c)) proves that the polarization state of our design is independent of tensile degree. Considering the transmit-receive reciprocity property, our design is no doubt a promising choice for harvesting the ambient RF energy. In addition, the resonance frequency and the corresponding amplitude (shown in Figure 5) of the fabricated antenna are always stable after 1000 tensile cycles, proving the excellent durability and strong stability.

Analyzing the existing LM-based frequency reconfig-

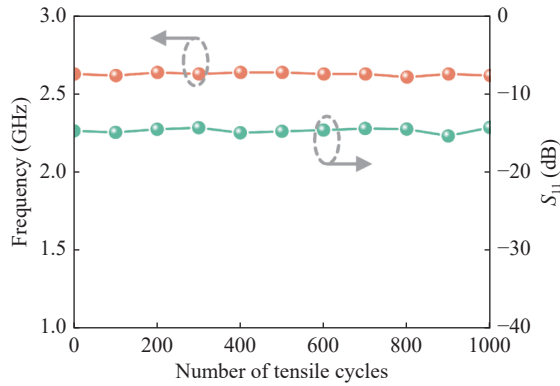


Figure 5 Working frequency and the corresponding S_{11} of the LM-based antenna after 100, 200, 300, 400, 500, 600, 700, 800, 900, and 1000 cycles of stretching (the applied strain repeatedly varies from 0% to ~100%).

urable antennas shown in Table 1 reveals that it is highly challenging to design an LM-based antenna with a large relative bandwidth where the radiation patterns remain stable during mechanical deformations. In contrast, thanks to the innovative design, our proposed antenna, to the best of our knowledge, exhibits maximum relative bandwidth (73%) while maintaining frequency continuity and stability of the radiation patterns as the operation frequency is tuned, making our design versatile for various application scenarios, including integration with other devices.

At this juncture, the realization of a frequency-tunable ambient RF power receiver has been successfully accomplished through the dynamic application of strain. The next pivotal step involves the integration of a broadband RF-DC converter, denoted as the rectifier network in Figure 6(a), designed to efficiently transform received RF power into DC energy. The converter's operational bandwidth is strategically selected to comprehensively encompass the tunable frequency range of the receiver. Given the typically modest power levels of ambient RF signals, the rectifier network must exhibit both exceptional RF-DC conversion efficiency at these power levels and a notable power handling ca-

capacity. To meet these dual criteria, we have developed an innovative rectifier network at the input power level of -10 dBm, as illustrated in Figure 6(a). This network encompasses a range of essential components, including a two-branch impedance matching circuit (highlighted in green) for transferring the input impedance of the rectifying network to the standard 50Ω , a rectifying network (colored orange), a pair of PIN diodes (the detailed information of the adopted diode is provided in Figure 7) for RF-DC conversion, a DC-pass filter to enhance output smoothness, and a load resistor. The detailed structural parameters of the rectifier network can be found in Figure 6(c).

In pursuit of an enhanced operational bandwidth, our design adopts a two-branch structure, delineated as Branch1 and Branch2 within Figure 6(a). Branch1 caters to the frequency range of 1.8 to 2.0 GHz, while Branch2 corresponds to the span of 2.2 to 2.6 GHz (as shown in Figure 6(a)). Examining Figure 6(d), we consider the case of a broadband RF signal spanning from 1.5 to 3.0 GHz, carrying a power of $100 \mu\text{W}$, directed into the rectifier network. Notably, power probe 1 (P_1), positioned ahead of the first PIN diode (D_1), effectively captures the majority of input power within the range of 1.8 to 2.0 GHz. Conversely, the power attributed to the range of 2.2 to 2.6 GHz predominantly flows through Branch2, leading to rectification by the second PIN diode (D_2). Significantly, both Branch1 and Branch2 collaboratively facilitate RF-DC conversion within the intermediate frequency band spanning 2.0 to 2.2 GHz, thereby endowing our design with a remarkable bandwidth spanning from 1.8 to 2.6 GHz. Beyond the expanded operational bandwidth, the corresponding RF-DC conversion efficiency, another pivotal metric, is unveiled in Figure 6(b). This parameter can be derived through the following equation:

$$\text{Efficiency} = V_{\text{out}}^2 / (R_{\text{load}} \times P_{\text{in}}) \quad (1)$$

where R_{load} is the optimal load resistance of the rectifier

Table 1 Comparison of our LM-based antenna with other related works

Ref.	Frequency range (GHz)	Relative bandwidth	Frequency continuity	Radiation pattern stability	Maximum tensile ratio	Methodology
[48]	1.7–3.5	69%	Yes	NR	NA	Injection
[49]	1.8–3.1 3.2–5.4	53% 51%	No	No	NA	Injection
[50]	2.4 and 3.87	NA	No	Yes	NA	Injection
[51]	5.8–6.4	10%	No	No	NA	Injection
[52]	0.6–13.5	183%	Yes	No	NA	Injection
[53]	1.9–2.35 3.2–3.5	21% 9%	Yes	Yes	NA	Injection
[54]	2.78–2.93	5%	Yes	Yes	15%	Stretching
[55]	2.42–3.45	35%	Yes	NR	60%	Stretching
[56]	0.738–1.53	70%	Yes	NR	120%	Stretching
[57]	1.37–1.7	21%	Yes	Yes	30%	Stretching
This work	1.4–3.0	73%	Yes	Yes	100%	Stretching

Note: NR, not reported; NA, not acquired.

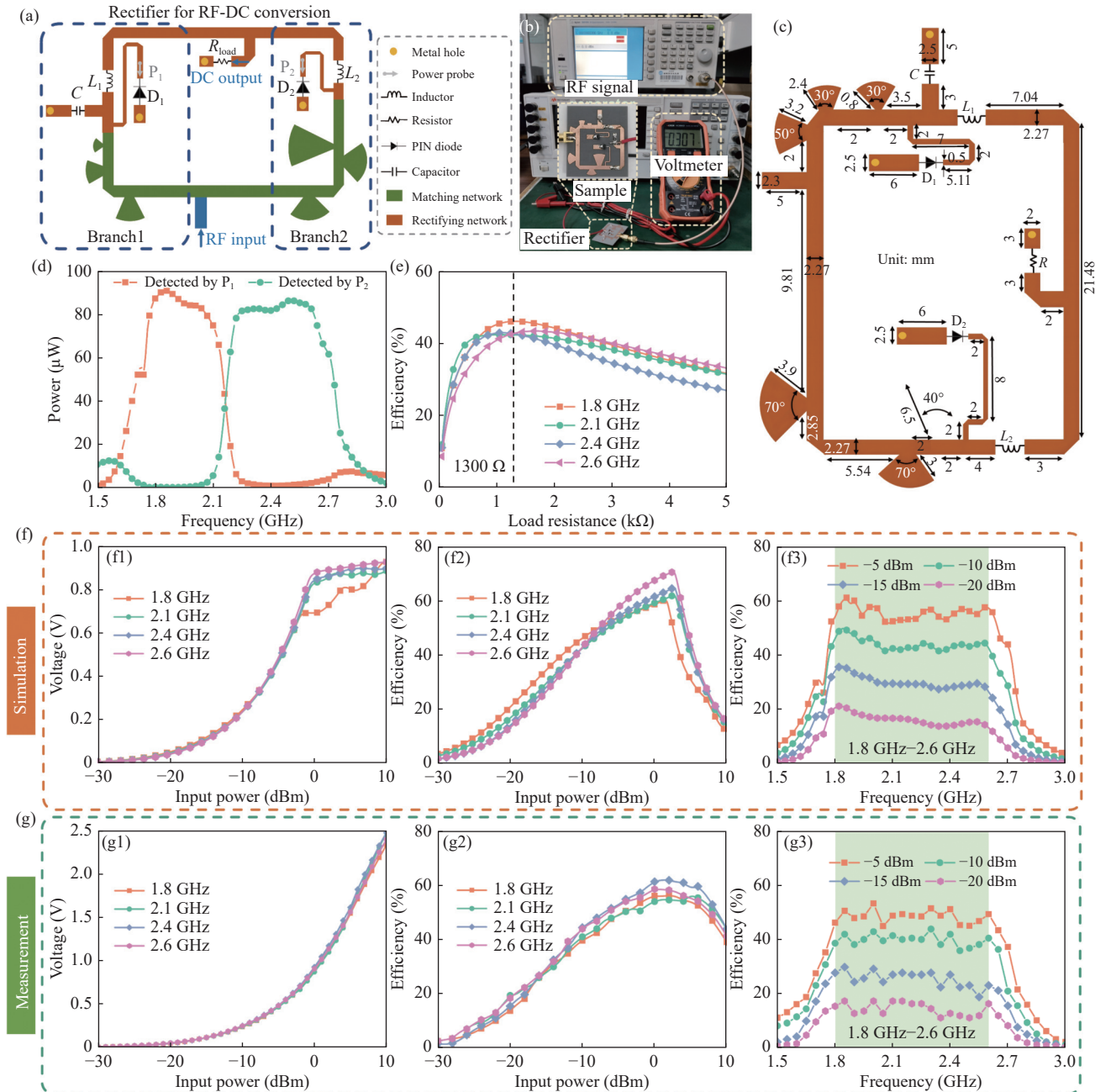


Figure 6 (a) Topology of the proposed broadband rectifier network for transforming the captured RF power (L_1, L_2 : 22 nH; C : 10 pF); (b) Photograph of the RF-DC conversion efficiency measurement setup. (c) Detailed structural parameters of the rectifier network. (d) Detected power distribution by two power probes (P_1 and P_2) as the input power is set to 100 μ W. (e) Simulated RF-DC conversion efficiency of the rectifier network as a function of load resistance at different frequencies. (f) and (g) Simulated and measured RF-DC conversion performance of the proposed rectifier network: (f1) and (g1) Output voltage vs. input power; (f2) and (g2) RF-DC conversion efficiency vs. input power; (f3) and (g3) RF-DC conversion efficiency vs. frequency.

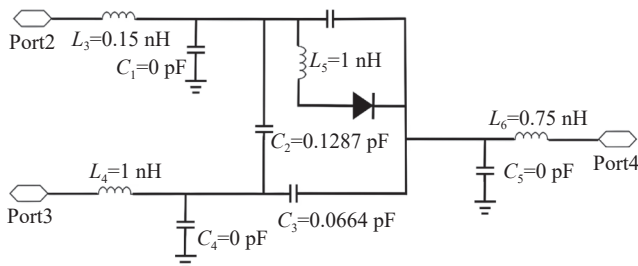


Figure 7 Equivalent circuit model and package parameters of the Schottky diode (SMS7630).

(1300 Ω which can support the optimal RF-DC conversion efficiency in the working bandwidth as shown in Figure 6(e)), P_{in} is the input power to the rectifier network illustrated in Figure 6(a), and V_{out} is the output voltage across the load resistance. By substituting the simulated input-power-dependent voltage output at different frequencies (Figure 6(f1)) into (1), then the theoretical efficiency can be calculated and presented in Figure 6(f2). Due to the linear characteristic of the PIN diode, the output voltage and conversion efficiency increase as the input power gradually en-

hances. However, once the PIN diodes are penetrated, the output voltage experiences saturation and stabilizes (as seen in Figure 6(f1)), while a diminishing efficiency becomes evident in Figure 6(f2) due to the heightened input power. Furthermore, the broadband nature of our design's capabilities is demonstrated in Figure 6(f3). When the input power is maintained at -10 dBm (equivalent to $100 \mu\text{W}$), the simulated RF-DC conversion efficiency spans the working bandwidth, surpassing the 40% threshold. This efficacy ensures the optimal utilization of the RF power captured at the frontend. It is noteworthy that the nonlinear phenomena previously demonstrated in Figures 6(f2) are also evident in Figure 6(f3) as input power variations are considered. Subsequently, to validate the rectification performance of our proposed rectifier network, the rectifier was built on a Duroid 5880 substrate with the relative permittivity of 2.2, and a comprehensive measurement was conducted using the setup delineated in Figure 6(b). In this experimental arrangement, a signal generator (Agilent N9310A) and a voltmeter were employed to generate the required RF signal and measure the resulting DC voltage output, respectively. Comparing the measured DC voltage (Figure 6(g1)) to the simulated results in Figure 6(f1), a congruent trend is observed in relation to input power variations. Notably, the saturation of voltage is not as evident in the measured data due to the nonlinear current-voltage characteristics of the rectifying diode. Consequently, this leads to a slightly more gradual decline in measured efficiency, as illustrated in Figure 6(g2), compared to Figure 6(f2). Meanwhile, the broadband RF-DC conversion efficiency of the fabricated rectifier network (Figure 6(g3)) closely aligns with the simulated outcome presented in Figure 6(f3). Any minor deviations can be attributed to manufacturing precision and potential testing errors.

Ultimately, the core component of the mechanically frequency-self-adaptive RF energy harvester illustrated in Figure 2(a) can be built by jointing the LM-based RF power receiver (Figure 2(b)) with the performance-matched RF-DC converter (Figure 6(a)), and the total system (Figure 2(a)) will be evaluated in the following part.

III. System Performance Evaluation

Before delving into the dynamic performance measurement of the frequency-self-adaptive total system, a comprehensive understanding of the MCU's control logic is paramount. The MCU is equipped with the capability to detect the generated voltage and manage the step motor's actions in tuning the strain applied to the LM-based antenna. When presented with a specified frequency signal, the RF receiver undergoes continuous stretching, transitioning from its original state to a state with a tensile ratio of 100%. This extension is accomplished through the involvement of the step motor, where each step length is defined as 1 mm. Concurrently, utilizing the temporal intervals between successive steps, the MCU persistently gauges the dynamic voltage values and records corresponding tensile lengths. Follow-

ing the completion of this intricate process, the maximum voltage can be readily identified through a comparison of the detected outcomes. Moreover, the optimal deformation ratio of the flexible antenna can be discerned. Subsequently, the MCU expeditiously configures the antenna to the determined tensile state through manipulating the step motor. Notably, the frequency-selective nature of the receiver bestows a unique feature: when the input signal is transformed to a frequency divergent from its initial state, the detected voltage experiences a notable decay, as anticipated by the trend in Figure 3(a). Consequently, this prompts the initiation of the previously described process, serving the purpose of sensing the newly set frequency and optimizing the DC output. Ultimately, by amalgamating the elaborately designed control circuit into the aforementioned control logic, the total system depicted in Figure 2(a) undergoes measurement within a microwave anechoic chamber (as illustrated in Figure 8(a)). In this setup, a horn antenna, linked to an RF signal generator, functioned as the transmitting source responsible for supplying the LM receiver.

Throughout the testing procedure, the receiving power of the total system was standardized at -10 dBm, attained by finely adjusting the output power of the signal generator. Subsequently, by systematically varying the frequency information of the input RF signal within the range of 1.5 to 2.6 GHz, automatic measurement of the tensile ratio and antenna length transpires. These measurements exhibit a linear correlation with the incident frequency (as exemplified in Figure 8(b)), consistently mirroring the simulated trends detailed in Figure 3(a). In addition, three demos for 2.6, 2.2, and 1.8 GHz have been provided in Figures 8(c)–(e), and their dynamic frequency adaptation process can be found in Supplementary Video S1 of the **Supporting Information** for showcasing the powerful capability of the novel system. Subsequently, in Figures 8(f)–(g), we present the simultaneously generated DC voltage from the total system alongside the corresponding achieved RF-DC efficiency. Evidently, the measured outcomes exhibit a strong alignment with the simulated results across an expansive frequency range. This span encompasses the Wi-Fi/WLAN band (2.4 GHz), traditional communication bands (1.8, 2.1, and 2.3 GHz), as well as the 5G band (2.6 GHz), effectively showcasing the excellent practical viability of our design.

It is worth noting that the primary aim of our work is to demonstrate the feasibility of using such a mechanically shifted adaptive system to sense and capture RF energy. Although the current system requires high power to drive all sub-system elements, including the motor and MCU, when the input energy is low, alternative low-power MCUs and motors could be employed to reduce the overall power consumption. To aid readers in understanding the roles and limitations of the MCU and motor, we have searched and compared several state-of-the-art components with those selected for this study, as detailed in Table S1 and Table S2 of the **Supporting Information**. Our findings show that by

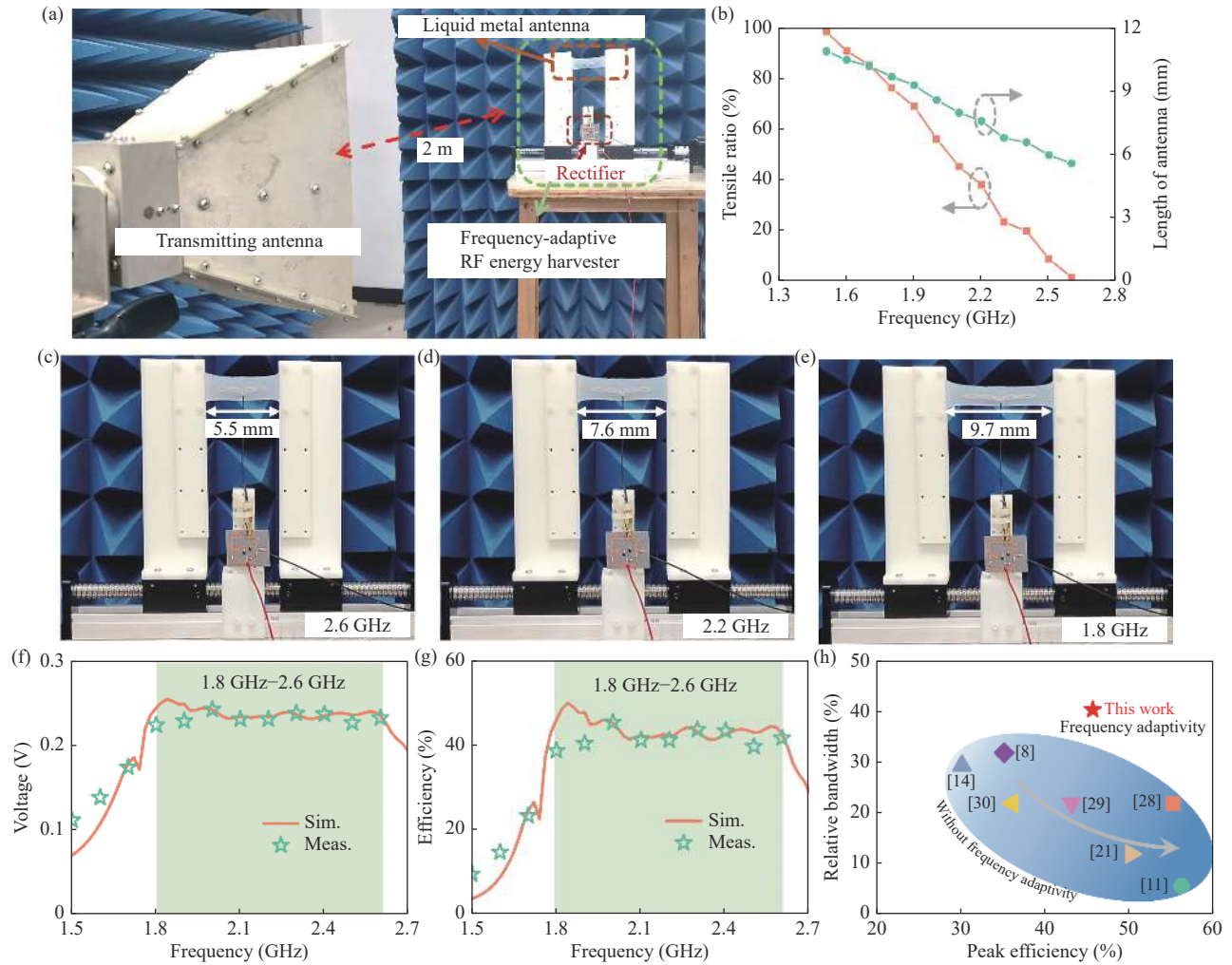


Figure 8 (a) Measurement photograph for the proposed frequency-self-adaptive RF energy harvester. (b) Measured tensile ratio and length of the antenna as a function of operation frequency. (c)–(e) Measured stretched state and length of the LM-based antenna corresponding to each frequency. Measured and simulated (f) Output DC voltage and (g) RF-DC efficiency of the proposed RF energy harvester as a function of frequency. (h) A comparison between our design with related designs.

carefully selecting components, the power consumption of the step motor can be reduced to as low as 0.05 W, while the MCU can operate on as little as 47.14 μ W. This significantly lowers the power demands, making the system suitable for low-power IoT infrastructures. Moreover, the potential applications of our design extend beyond frequency-adaptive RF energy harvesting; it could also be used for wireless ambient frequency and power sensing in future applications.

Finally, a comparison between our rectenna design and some recent rectenna and rectifier designs is given in Table 2. Comprehensively considering the radiation pattern stability, RF-DC conversion efficiency, and relative bandwidth, our design exhibits significant superiority over all others listed in Table 2. Although the peak RF-DC efficiency of the proposed rectenna is slightly lower than those reported in [11], [21], [28], our design still successfully breaks the traditional trade-off between peak efficiency and relative bandwidth, as demonstrated in Figure 8(h). In addition, our design appears to be the only one with frequency adaptivity, making

it an excellent candidate for RF energy harvesting in numerous practical applications.

IV. Conclusion

In this study, we have introduced a pioneering solution for RF energy harvesting – mechanical frequency-self-adaptive RF power harvester empowered by a dual “ ∞ ”-shaped antenna and reconfigurable LM. This innovation allows for continuous tuning of the system’s working frequency within the range of 1.8 to 2.6 GHz by applying external mechanical strain to the LM antenna. The integration of a tailored control logic into MCU enables automatic frequency adjustment and identification when exposed to specific signals. Simultaneously, the proposed system exhibits impressive rectification efficiency, yielding a rapid generation of DC power exceeding 0.25 V at an input power level of -10 dBm. This harvested DC power is readily accessible for direct utilization. Experimental validation serves as a testament to the system’s adaptability and robust performance across diverse operational conditions. These results

Table 2 Comparison of our design with other related works

Ref.	Radiation direction of antenna at all working bands	Radiation pattern stability	PCE at -10 dBm (%)	Operation band (GHz) ($\geq 80\% \times$ PCE)	Relative bandwidth (%)	Technique	Frequency adaptivity
[8]	NR	NR	35	0.84–1.16	32	Series	No
[11]	Non-omnidirectional	NR	56	2.38–2.52	5.7	Series	No
[14]	NR	NR	30	1.1–1.48	29.5	Double voltage	No
[21]	NR	NR	50	0.86–0.97	12	Conjugate matching	No
[28]	Non-omnidirectional	No	55	1.79–2.27	23.6	Double voltage	No
[29]	NR	NR	43	0.73–0.92	23	Double voltage	No
[30]	NR	NR	36	1.11–1.39	22.4	Double voltage	No
This work	Omnidirectional	Yes	45.5	1.75–2.65	40.9	Shunt	Yes

Note: NR, not reported; PCE, peak conversion efficiency.

hold significant promise in effectively harnessing RF energy from spatiotemporal-varying environments. In summary, our work presents a dynamic and self-adapting approach to RF energy harvesting. The synergy between frequency tuning and efficient rectification addresses the challenge of effectively capturing RF energy within an ever-changing spectrum. The successful experimental validation attests to the system's efficacy, showcasing its potential to address the intricate demands of RF energy harvesting in dynamic environments. This innovation marks a significant stride towards sustainable energy solutions. These results hold significant promise in effectively harnessing RF energy from spatiotemporal-varying environments. In summary, our work presents a dynamic and self-adapting approach to RF energy harvesting. The synergy between frequency tuning and efficient rectification addresses the challenge of effectively capturing RF energy within an ever-changing spectrum. The successful experimental validation attests to the system's efficacy, showcasing its potential to address the intricate demands of RF energy harvesting in dynamic environments. This innovation marks a significant stride towards sustainable energy solutions.

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Supporting Information

Supplementary Note S1, Fig. S1, Tables S1 to S2 and Video S1. The supporting information is available online at www.emscience.org. The supporting materials are published as submitted, without typesetting or editing. The responsibility for scientific accuracy and content remains entirely with the authors.

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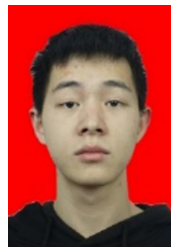
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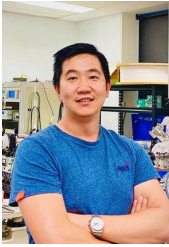
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