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Log-Domain Decoding of Quantum LDPC Codes Over Binary Finite Fields

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ABSTRACT A quantum stabilizer code over GF(q) corresponds to a classical additive code over $GF(q^2)$ that is self-orthogonal with respect to a symplectic inner product. We study the decoding of quantum low-density parity-check (LDPC) codes over binary finite fields $GF(q = 2^l)$ by the sum-product algorithm, also known as belief propagation (BP). Conventionally, a message in a nonbinary BP for quantum codes over $GF(2^l)$ represents a probability vector over $GF(2^{2l})$, inducing high decoding complexity. In this article, we explore the property of the symplectic inner product and show that scalar messages suffice for BP decoding of nonbinary quantum codes, rather than vector messages necessary for the conventional BP. Consequently, we propose a BP decoding algorithm for quantum codes over $GF(2^l)$ by passing scalar messages so that it has low computation complexity. The algorithm is specified in log domain by using log-likelihood ratios of the channel statistics to have a low implementation cost. Moreover, techniques such as message normalization or offset can be naturally applied in this algorithm to mitigate the effects of short cycles to improve the BP performance. This is important for nonbinary quantum codes since they may have more short cycles compared to binary quantum codes. Several computer simulations are provided to demonstrate these advantages. The scalar-based strategy can also be used to improve the BP decoding of classical linear codes over $GF(2^l)$ with many short cycles.

INDEX TERMS Belief propagation (BP), log-likelihood ratio (LLR), low-density parity-check (LDPC) codes, quantum stabilizer codes, short cycles, message normalization and offset, sparse-graph codes.

I. INTRODUCTION

Quantum stabilizer codes can be used to protect quantum information with efficient encoding and decoding procedures similar to classical error-correcting codes [1]–[6]. Since quantum coherence decays quickly, an efficient decoding procedure is particularly important. For this purpose, sparse-graph quantum codes, similar to classical low-density parity-check codes [7]–[9], are preferred since they can be efficiently decoded by the sum-product algorithm [10]–[18], which is usually understood as a realization of belief propagation (BP) [19]. BP is appealing because of its good decoding performance for sparse-graph codes and efficient computation complexity that is nearly linear in the code length [7]–[9]. BP decoding is done by iteratively passing messages on a Tanner graph [20] corresponding to the parity-check matrix of a code [21]–[25].

The concept of stabilizer codes has been extended from the binary case (qubits) to nonbinary case (q-ary qudits) [26]–[31]. We assume that a q-ary qudit suffers errors from an error

basis of q^2 elements. A quantum stabilizer code over GF(q) can be considered as a classical additive code over $GF(q^2)$. Although binary quantum codes are most widely studied, a nonbinary quantum code has its advantages over binary ones. For example, binary stabilizer codes do not perform as well as nonbinary codes in spatially correlated noise [32], [33]. To improve, we can group every *l* qubits that are strongly correlated together as a qudit and use quantum codes over $GF(2^l)$ at a cost of higher decoding complexity.

In BP decoding of a classical code over GF(q), a message is a probability vector of length q for a q-ary variable [34]. The complexity of BP is dominant by the *check-node complexity* per edge for the convolution of messages, which is $O(q \log q)$ per edge for classical codes over GF(q) [35], [36].

For quantum codes over GF(q), the check-node complexity is even higher proportional to $q^2 \log q^2$. To decode a length-*N* quantum code over GF(q) with *M* parity checks, one can represent its check matrix $H \in GF(q^2)^{M \times N}$ by a matrix in $GF(q)^{M \times 2N}$ and decode the code using *q*-ary BP (BP_q), so that the check-node complexity reduces to $O(q \log q)$ per edge. If $q = 2^l$, one can further represent H by a binary matrix \in GF(2)^{$M \times 2lN$} to use BP₂ and the check-node complexity reduces to O(1) per edge. However, these methods ignore some error correlations (such as the correlations between Pauli X and Z errors), causing performance degradation [13]–[16], [37]. Therefore, we would like to study the BP decoding problem for nonbinary quantum codes, and we will show that it can be simplified to O(1) for binary fields GF(2^l) without ignoring the error correlations. This is done by exploring the property of the symplectic inner product of quantum codes, so that scalar messages suffice for BP decoding of nonbinary quantum codes, rather than vector messages necessary for the conventional BP.¹

In classical coding theory, BP is usually implemented in log domain to require only additions and lookup tables for computation [7], [38]–[41] (see Remark 1 for our case). Moreover, the required bit-width for each scalar variable is fewer in log domain compared to linear domain (Remark 7). These greatly simplify the implementation of BP. We would like to have a quantum version of efficient log-domain BP.

Previously we proposed a refined BP₄ for binary quantum codes [16], which uses scalar messages with check-node complexity O(1) per edge and completes a decoding equivalent to the conventional BP₄. In this article, we extend this approach to quantum codes over GF(2^l) so that an efficient 2^{2l} -ary BP decoding with check-node complexity O(1) per edge is possible. The central idea is that a message of this BP concerns whether a qudit error commutes or anticommutes with a parity-check Pauli operator. Consequently, we are able to define a scalar message in log domain for quantum codes (Definition 6) and propose a log-likelihood ratio (LLR) BP (LLR-BP) decoding algorithm (Algorithm 1). This algorithm is applicable to any quantum codes over GF(2^l).

The proposed algorithm could be extended to quantum codes over $GF(p^l)$ for a prime *p*. In this case, the check-node complexity would reduce from $O(p^{2l} \log p^{2l})$ to $O(p \log p)$ per edge (see the discussion in Section V).

Another issue of BP decoding for quantum codes is that the Tanner graph of a stabilizer code contains many short cycles.² This may lead to ineffective message passing [10]– [18] since short cycles introduce unwanted dependency between messages to affect the convergence of BP [7, Sec. 4.2]. The problem can be mitigated during code construction [10], [15], [42]–[44], but this would restrict the code candidates in applications. Another direction is to improve the BP decoding algorithm. BP can be improved by postprocessing [11]–[15], [17], but this increases the computation complexity and, hence, increases the decoding time. Another approach is to use a neural BP (NBP) decoder [18]; however, NBP may not apply to large codes due to the complicated offline training process and more importantly, there is

¹In Appendix B, we clarify the complexities of our approach and the conventional approach, both maintaining the correlations between q^2 errors. ²This is caused by the overlaps of the rows in the check matrix, which

cannot be prevented due to the commutation relations of the stabilizers.

less guarantee of low error-floor from training (see Figs. 2 and 3).

As our LLR-BP uses scalar messages, it is straightforward to apply the techniques of message normalization or offset [45]–[47] without incurring much additional cost. These techniques can suppress overestimated messages caused by short cycles [47]. Applying these techniques significantly improves the BP performance on binary quantum codes [16]. For nonbinary quantum codes, the number of rows in a check matrix becomes more [e.g., see (11) and (12)], which may cause much more short cycles compared to the case of binary quantum codes. However, applying message normalization or offset on the scalar-based nonbinary BP again significantly improves the performance, and this improvement does not need a large number of iterations to achieve. Computer simulations will be conducted to show these advantages.

Since quantum codes are like classical codes with short cycles, our approach can also be used to improve the BP decoding of classical codes over $GF(2^l)$ with short cycles. (This will be discussed in Remark 8.)

This article is organized as follows. In Section II, we provide some basics for binary fields $GF(2^l)$ and define stabilizer codes over $GF(2^l)$. In Section III, we give a scalar-based LLR-BP for stabilizer codes over $GF(2^l)$. In Section IV, simulation results for several stabilizer codes are provided. We conclude and give some discussions in Section V.

II. STABILIZER CODES OVER BINARY FINITE FIELDS

The theory of binary and *q*-ary quantum stabilizer codes can be understood as certain classical codes over finite fields $GF(2^2)$ and $GF(q^2)$, respectively [1]–[6], [26]–[31]. We refer to [48] for the basics of finite fields.

Definition 1: For a finite field GF(p) and its extension field $GF(q' = p^m)$, the trace from GF(q') to GF(p) is defined as

$$\operatorname{Tr}_{p}^{q'}(\eta) = \eta + \eta^{p} + \dots + \eta^{p^{m-1}} \in \operatorname{GF}(p)$$

for any $\eta \in GF(q')$.

Assume $q = 2^{l}$ in the following if not otherwise specified.

A. SYMPLECTIC INNER PRODUCT VECTOR SPACE

Let $tr(\cdot)$ be the trace from GF(q) to the ground field $GF(2) = \{0, 1\}$, i.e., for $\eta \in GF(q)$,

$$\mathbf{r}(\eta) \triangleq \mathrm{Tr}_2^q(\eta) = \eta + \eta^2 + \dots + \eta^{2^{l-1}} \in \{0, 1\}.$$

For two vectors $u = (u_1, ..., u_N), v = (v_1, ..., v_N) \in$ GF(q)^N, their Euclidean inner product is

$$u \cdot v = \sum_j u_j v_j.$$

Let ω be a primitive element of GF(q^2). Then, { ω, ω^q } is a basis for GF(q^2) over GF(q) [29]–[31], [48]. Consequently, a vector u in the vector space GF(q^2)^N can be written as

$$u = \omega u' + \omega^q u''$$

where $u', u'' \in GF(q)^N$. That is, $GF(q^2)^N$ is isomorphic to $GF(q)^{2N}$, and a $u \in GF(q^2)^N$ is uniquely represented by a

 $(u'|u'') \in GF(q)^{2N}$ given $\{\omega, \omega^q\}$. To better align with the notation in Section II-B, we denote u' by u^X and u'' by u^Z . Equivalently, $u \in GF(q^2)^N$ may be denoted by

$$u = \omega u^X + \omega^q u^Z \equiv (u^X | u^Z) \in \mathrm{GF}(q)^{2N}.$$
(1)

Definition 2: For $u, v \in GF(q^2)^N$, where $q = 2^l$, the (binary) symplectic inner product of u and v is defined as

$$\langle u, v \rangle = \operatorname{tr}(u^X \cdot v^Z + u^Z \cdot v^X) \in \{0, 1\}.$$
(2)

Equation (2) is a symplectic {0, 1}-bilinear form, or a symplectic inner product. This form is important in the study of quantum codes, to link a quantum code over GF(q) as a classical code *C* over $GF(q^2)$ that is symplectic self-orthogonal (i.e., $\langle u, v \rangle = 0$ for any two codewords $u, v \in C$).

The Hermitian inner product of $u, v \in GF(q^2)^N$ is

$$u \cdot \bar{v} = \sum_{j} u_{j} v_{j}^{q}$$

where $\bar{v} \triangleq (v_1^q, v_2^q, \dots, v_N^q)$.

Theorem 1 (See [29], [31]): For $u, v \in GF(q^2)^N$, where $q = 2^l$, their symplectic inner product (2) can be computed by

$$\langle u, v \rangle = \operatorname{tr}\left(\frac{u \cdot \bar{v} + v \cdot \bar{u}}{\omega^2 + \omega^{2q}}\right).$$
 (3)

Proof: Write $u = \omega u^X + \omega^q u^Z$ and $v = \omega v^X + \omega^q v^Z$. Then

$$u \cdot \bar{v} + v \cdot \bar{u} = u \cdot \bar{v} + \overline{u \cdot \bar{v}}$$
$$= (\omega^2 + \omega^{2q})(u^X \cdot v^Z + u^Z \cdot v^X) \qquad (4)$$

which directly leads to (3).

A consequence of Definition 2 and Theorem 1 is in the following.

Corollary 1: For $q = 2^l$, two vectors $u, v \in GF(q^2)^N$ satisfy $\langle u, v \rangle = 0$ if one of the following conditions holds.

1) They are Hermitian orthogonal, i.e.,

$$u \cdot \bar{v} = 0. \tag{5}$$

 They satisfy the Calderbank–Shor–Steane (CSS) conditions [2], [3]

$$u \equiv (u^{X} | \mathbf{0}), v \equiv (v^{X} | \mathbf{0})$$

or $u \equiv (\mathbf{0} | u^{Z}), v \equiv (\mathbf{0} | v^{Z})$
or $u \equiv (u^{X} | \mathbf{0}), v \equiv (\mathbf{0} | v^{Z})$ with $u^{X} \cdot v^{Z} = 0$. (6)

Example 1: If q = 2, we have $\omega^2 + \omega^{2q} = 1$ in GF(4) and tr(·) = Tr₂²(·) is the identity map. For $u, v \in \text{GF}(4)^N$

$$\langle u, v \rangle = u^X \cdot v^Z + u^Z \cdot v^X.$$

It is well known that $\langle u, v \rangle = \text{Tr}_2^4(u \cdot \bar{v})$ [5]. Here, $\text{Tr}_2^4(0) = \text{Tr}_2^4(1) = 0$ and $\text{Tr}_2^4(\omega) = \text{Tr}_2^4(\omega^2) = 1$ by Definition 1. Given $\eta \in \text{GF}(q^2)$, define

$$[\eta] = \{ \xi \in \operatorname{GF}(q^2) : \langle \eta, \xi \rangle = 0 \}$$

$$[\eta]^{c} = \{ \xi \in \operatorname{GF}(q^2) : \langle \eta, \xi \rangle = 1 \}.$$

Then, $[\eta]$ and $[\eta]^c$ are two sets with elements that commute and anticommute with a certain element η , respectively, and $\{[\eta], [\eta]^c\}$ is a partition of GF(q^2).

Example 2: For the special case of q = 2, GF(4) = $\{0, 1, \omega, \omega^2\}$ with $1 = \omega + \omega^2$. Then, $\langle 1, \omega \rangle = \langle \omega, \omega^2 \rangle = \langle 1, \omega^2 \rangle = 1$. Thus, $[\omega] = \{0, \omega\}$ and $[\omega]^c = \{1, \omega^2\}$.

For two sets A and B, define $A \setminus B = \{a \in A : a \notin B\}$. If $B = \{b\}$, we may write $A \setminus \{b\}$ as $A \setminus b$ for simplicity.

Theorem 2: For $q = 2^l$, there exists an additive subgroup $S \subset GF(q)$ of size q/2 such that for $\eta \in S$, $tr(\eta) = 0$ and for $\eta' \in GF(q) \setminus S$, $tr(\eta') = 1$.

Proof: All the elements in GF(q) are the roots of $x^{2^l} + x$, which has a factorization

$$x^{2^{l}} + x = \prod_{b \in \{0,1\}} (x + x^{2} + \dots + x^{2^{l-1}} + b)$$

where the each factor $(x + x^2 + \dots + x^{2^{l-1}} + b)$ contains $2^{l-1} = q/2$ distinct roots in GF(q) for b = 0 or 1. If η is a root of $(x + x^2 + \dots + x^{2^{l-1}} + b)$, then it can be shown that $\operatorname{tr}(\eta) = b$. Thus, we have the statement.

Note that Theorem 2 easily extends for $GF(p^l)$ by a similar factorization equality in [48, Th. 8.1(e)].

Corollary 2: Given $\eta \neq 0$ in GF(q^2), where $q = 2^l$, we have

$$|[\eta]| = |[\eta]^{c}| = q^{2}/2.$$

Proof: Let $\eta = (\eta^X | \eta^Z) \in GF(q^2)$ for $\eta^X, \eta^Z \in GF(q)$. Since $\eta \neq 0$, at least $\eta^X \neq 0$ or $\eta^Z \neq 0$. Suppose that $\eta^Z \neq 0$ without loss of generality. For $\xi = (\xi^X | \xi^Z) \in GF(q^2)$ with $\xi^X, \xi^Z \in GF(q)$, we have $\langle \eta, \xi \rangle = tr(\eta^X \xi^Z + \eta^Z \xi^X) =$ $tr(\eta^X \xi^Z) + tr(\eta^Z \xi^X)$. Then, $\{\eta^Z \xi^X : \xi^X \in GF(q)\}$ is a permutation of $\{\xi^X \in GF(q)\}$. By Theorem 2, there exists $S \subset$ $\{\eta^Z \xi^X : \xi^X \in GF(q)\}$ with |S| = q/2 such that for all $\mu \in S$, $tr(\mu) = 0$ and for $\mu' \in GF(q) \setminus S$, $tr(\mu') = 1$. If $\eta^X = 0$, then we are done. Consider $\eta^X \neq 0$. Note that a fixed $\nu \in \{\eta^X \xi^Z : \xi^Z \in GF(q)\}$ such that

$$\operatorname{tr}(\nu) + \operatorname{tr}(\chi) = \begin{cases} \operatorname{tr}(\nu), & \text{if } \chi \in S \\ \operatorname{tr}(\nu) + 1, & \text{if } \chi \in \operatorname{GF}(q) \setminus S. \end{cases}$$

For a fixed ν , a half of the pairs $\{(\nu, \chi)\}$ have $tr(\nu)+tr(\chi)=0$, while the other half have $tr(\nu) + tr(\chi) = 1$. This holds for any ν . Thus, $|[\eta]| = |[\eta]^c| = q^2/2$.

The property that $|[\eta]| = |[\eta]^c|$ has its merit in implementation (for an important operator in Definition 6).

B. STABILIZER CODES OVER GF(2¹)

We review some basics of nonbinary quantum codes [26]– [31] and then define the decoding problem.

Let \mathbb{R} be the field of real numbers, \mathbb{Z}_+ be the set of positive integers, and \mathbb{C} be the field of complex numbers.

Consider a *q*-ary quantum system with $q = 2^l$, for some integer $l \ge 1$. A *qudit* is a unit vector in \mathbb{C}^q . Without loss of generality, let $\{|\eta\rangle : \eta \in GF(q)\}$ be a set of orthonormal basis for \mathbb{C}^q such that there is a set of (generalized) Pauli operators

 $\{X(\xi), Z(\xi') : \xi, \xi' \in GF(q)\}$ on \mathbb{C}^q , where

$$X(\xi)|\eta\rangle = |\eta + \xi\rangle, \quad Z(\xi)|\eta\rangle = (-1)^{\operatorname{tr}(\eta\xi)}|\eta\rangle.$$
(7)

Note that X(0) = Z(0) = I, the identity.

An *N*-qudit state is a unit vector in $(\mathbb{C}^q)^{\otimes N} = \mathbb{C}^{q^N}$. For $u = (u_1, \ldots, u_N) \in GF(q)^N$, we define the (generalized) *N*-fold Pauli operators

$$X(u) = X(u_1) \otimes \cdots \otimes X(u_N),$$

$$Z(u) = Z(u_1) \otimes \cdots \otimes Z(u_N).$$

The set $\{X(u^X)Z(u^Z) : u^X, u^Z \in GF(q)^N\}$ forms a basis for the linear operators on \mathbb{C}^{q^N} . It suffices to consider these discrete errors for error correction according to the error discretization theorem [6]. To form a group of operators with closure, we include phases ± 1 (due to $(-1)^{\operatorname{tr}(\eta\xi)} \in \{\pm 1\}$ in (7) for $q = 2^l$) and consider the group

$$\mathcal{G}_N \triangleq \{\pm X(u^X)Z(u^Z) : u^X, u^Z \in \mathrm{GF}(q)^N\}.$$

Elements of \mathcal{G}_N are connected to the elements of the vector space $GF(q^2)^N$ by a homomorphism $\varphi : \mathcal{G}_N \to GF(q^2)^N$ defined as follows. For $E = (-1)^c \bigotimes_{n=1}^N (X(u_n^X)Z(u_n^Z)) \in \mathcal{G}_N$, where $c \in \{0, 1\}$ and $u^X, u^Z \in GF(q)^N$, we have

$$\varphi(E) \triangleq \omega u^X + \omega^q u^Z \equiv (u^X | u^Z) \tag{8}$$

where ω is a primitive element of $GF(q^2)$ as discussed in Section II-A. Note that the kernel of φ is $\{\pm I^{\otimes N}\}$, i.e., the phase $(-1)^c$ of *E* does not appear in $\varphi(E)$.

Two operators $E, F \in \mathcal{G}_N$ either *commute* (EF = FE) or *anticommute* (EF = -FE) with each other. Suppose that $\varphi(E) = (u^X | u^Z)$ and $\varphi(F) = (v^X | v^Z)$. Then

$$EF = (-1)^{\operatorname{tr}(u^X \cdot v^Z + u^Z \cdot v^X)} FE$$
$$= (-1)^{\langle \varphi(E), \varphi(F) \rangle} FE.$$

Definition 3 (See[30], [31]): A stabilizer group S is an Abelian subgroup of \mathcal{G}_N such that $-I^{\otimes N} \notin S$. The stabilizer code $\mathcal{C}(S)$ defined by S is a subspace of \mathbb{C}^{q^N} that is the joint (+1)-eigenspace of all the operators in S, i.e.,

$$\mathcal{C}(\mathcal{S}) = \{ |\psi\rangle \in \mathbb{C}^{q^N} : F |\psi\rangle = |\psi\rangle \quad \forall F \in \mathcal{S} \}.$$

Every element in S is called a *stabilizer*.

If an occurred error $E \in \mathcal{G}_N$ anticommutes with certain stabilizers, it can be detected by measuring the eigenvalues of an independent generating set of S. If any of the eigenvalues is -1, we know that there is an error. Let $S^{\perp} = \{E' \in \mathcal{G}_N :$ $E'F = FE' \quad \forall F \in S\}$. Apparently, if $E \in S^{\perp} \setminus \{\pm S\}$ then it cannot be detected and will lead to a logical error.

For $u \in GF(q^2)^N$, let |u| be *Hamming weight* of u. For $E \in \mathcal{G}_N$, define the *weight* of E as wt $(E) \triangleq |\varphi(E)|$. The *minimum distance* of $\mathcal{C}(S)$ is defined as

$$D \triangleq \min\{\operatorname{wt}(F) : F \in \mathcal{S}^{\perp} \setminus \{\pm \mathcal{S}\}\}.$$

C(S) can correct an arbitrary error $E \in \mathcal{G}_N$ with weight wt $(E) \leq \lfloor \frac{D-1}{2} \rfloor$. If S has l(N - K) independent generators,

$$c_1 = \langle e, H_1 \rangle = \langle e_1, H_{11} \rangle + \langle e_2, H_{12} \rangle$$

$$c_2 = \langle e, H_2 \rangle = \langle e_1, H_{21} \rangle + \langle e_2, H_{22} \rangle + \langle e_3, H_{23} \rangle$$

$$c_3 = \langle e_3 \rangle$$

FIGURE 1. Tanner graph of $H = \begin{bmatrix} H_{11} & H_{12} & 0 \\ H_{21} & H_{22} & H_{23} \end{bmatrix}$.

then $\mathcal{C}(\mathcal{S})$ has dimension q^K . In this case, $\mathcal{C}(\mathcal{S})$ is called an $[[N, K, D]]_q$ stabilizer code.

Equivalently we may study quantum stabilizer codes using the language of finite fields. Let $C \triangleq \varphi(S) \subset GF(q^2)^N$. Since S is an Abelian group, C is an additive code over $GF(q^2)$ that is self-orthogonal with respect to $\langle \cdot, \cdot \rangle$ in (2), i.e, C is contained in the symplectic dual C^{\perp} of C

$$C \subseteq C^{\perp} \triangleq \{ u \in \operatorname{GF}(q^2)^N : \langle u, v \rangle = 0 \quad \forall v \in C \}.$$

Thus, $\varphi(\mathcal{S}^{\perp}) = C^{\perp}$ and $D = \min\{|v| : v \in C^{\perp} \setminus C\}$.

The encoding and decoding procedures of C(S) are strongly related to *C* and C^{\perp} . The encoding procedure, as well as the measurement circuit, can be referred to [6], [49]. We discuss the decoding procedure in the following, which is similar to the classical syndrome-based decoding of C^{\perp} .

The phase of a Pauli operator can be ignored when discussing the decoding, so, without loss of generality, in the following, we consider errors or stabilizers with phase +1.

Suppose that a codeword (state) in $\mathcal{C}(S)$ is disturbed by an unknown error $E = E_1 \otimes \cdots \otimes E_N \in \mathcal{G}_N$. We would like to infer $e = \varphi(E) \in \mathrm{GF}(q^2)^N$ by measuring a sequence of M stabilizers $\{S_m\}_{m=1}^M$, where $M \ge l(N - K)$ since S has l(N - K) independent generators. Write

$$S_m = S_{m1} \otimes \cdots \otimes S_{mN}, \qquad (9)$$

where $S_{mn} \in \mathcal{G}_1$. Since the error either commutes or anticommutes with a stabilizer, measuring a stabilizer returns outcome +1 or -1, which gives us a bit of error information. Let $H \in GF(q^2)^{M \times N}$ with (m, n)-entry $H_{mn} = \varphi(S_{mn})$. Then, H is called a *check matrix* of the stabilizer code $\mathcal{C}(S)$, and Cis the row space of H, denoted by $C = \operatorname{row}(H)$. After the measurements defined by $\{S_m\}_{m=1}^M$, we will obtain a *binary error syndrome* $z = (z_1, \ldots, z_M) \in \{0, 1\}^M$, where

$$z_m = \langle \varphi(E), \varphi(S_m) \rangle = \langle e, H_m \rangle \tag{10}$$

where $H_m \in GF(q^2)^N$ is the *m*th row of *H*, called a *check*. The decoding problem is as follows.

Decoding a stabilizer code over $GF(q = 2^l)$: Given a check matrix $H \in GF(q^2)^{M \times N}$, a binary syndrome $z \in \{0, 1\}^M$ of some (unknown) $e \in GF(q^2)^N$, and certain characteristics of the error model, the decoder has to infer an $\hat{e} \in GF(q^2)^N$ such that $\langle \hat{e}, H_m \rangle = z_m$ for m = 1, 2, ..., M and $\hat{e} - e \in row(H)$ with probability as high as possible.

Decoding by BP needs a Tanner graph defined by the check matrix *H* of the code C(S). The Tanner graph is a bipartite graph consisting of *N* variable nodes (representing $\{e_n\}_{n=1}^N$) and *M* check nodes (representing $\{z_m\}_{m=1}^M$), and

there is an edge, with type H_{mn} , connecting variable node n and check node m if $H_{mn} \neq 0$. An example is shown in Fig. 1. Let

$$\mathcal{N}(m) = \{n : H_{mn} \neq 0\}$$
$$\mathcal{M}(n) = \{m : H_{mn} \neq 0\}$$

which are the neighboring sets of the check node *m* and the variable node *n*, respectively. BP infers $\{e_n\}_{n=1}^N$ by passing messages between neighboring nodes in the Tanner graph.

C. STABILIZER CODE CONSTRUCTIONS

We finish this section with some stabilizer code constructions that will be used in our discussions and simulations.

A check matrix $H \in GF(2^{2l})^{M \times N}$ of a 2^{l} -ary quantum code may be constructed from an $\frac{M}{2l} \times N$ parity-check matrix \tilde{H} of a classical linear code over $GF(2^{2l})$ such that \tilde{H} is Hermitian self-orthogonal (cf. Corollary 1). Given such an \tilde{H} , we have a check matrix H by the CSS extension

$$H = \begin{bmatrix} \tilde{H} \\ \omega \tilde{H} \\ \vdots \\ \omega^{2l-1} \tilde{H} \end{bmatrix}$$
(11)

where ω is a primitive element of GF(2²¹). A simple construction of (11) is to find a binary \tilde{H} such that $\tilde{H}\tilde{H}^T = O$, where *O* is a zero matrix of appropriate dimension.³

If \tilde{H} in (11) is replaced by a set of Euclidean orthogonal binary matrices $\{H^{(i)}\}_{i=0}^{2l-1}$, where $H^{(i)}(H^{(j)})^T = O$ for $i \neq j$, then we have the generalized CSS extension⁴

$$H = \begin{bmatrix} H^{(0)} \\ \omega H^{(1)} \\ \vdots \\ \omega^{2l-1} H^{(2l-1)} \end{bmatrix}.$$
 (12)

Note that although (11) and (12) are called (generalized) CSS extension, the rows of *H* may not necessarily have the form defined in the CSS conditions (6).

III. BP DECODING OF STABILIZER CODES

In the following discussion, we assume that

GF
$$(q^2) = \{0, 1, \zeta, \zeta^2, \dots, \zeta^{q^2 - 2}\}$$

where ζ is a primitive root of $GF(q^2)$ and $q = 2^l$.

Consider that we want to solve the quantum decoding problem mentioned after (10). First, express (10) as

$$z_m = \langle e, H_m \rangle = \sum_{n=1}^N \langle e_n, H_{mn} \rangle \pmod{2}. \tag{13}$$

³If \tilde{H} is binary and $\tilde{H}\tilde{H}^T = O$, the supports of any two rows u, v of \tilde{H} have an overlap of even size; consequently, any two rows $\omega^i u$, $\omega^j v$ of H in (11) satisfy $(\omega^i u) \cdot \overline{(\omega^j v)} = 0$ (i.e., they satisfy (5), as required).

⁴We do not need $H^{(i)}(H^{(i)})^T = O$, since two rows u, v of $H^{(i)}$ become two rows $\omega^i u, \omega^i v$ of $\omega^i H^{(i)}$ in (12), with $\langle \omega^i u, \omega^i v \rangle = 0$ by Theorem 1.

The addition for syndrome generation will always be mod 2 without further specification. We may use $z = \langle e, H \rangle$ to mean that $z_m = \langle e, H_m \rangle \forall m$.

Consider a memoryless error model that each qudit suffers an independent error, i.e., the probability that the error vector is $u \in GF(q^2)^N$ is $P(e = u) = \prod_{n=1}^N P(e_n = u_n)$ for some distribution $P(e_n = \eta) = p_\eta$ over $\{\eta \in GF(q^2)\}$, where $\sum_{\eta} p_{\eta} = 1$. In BP, the goal is to find the most probable value of each $e_n \in GF(q^2)$ given *z*. Initially each e_n has value in $GF(q^2)$ according to the initial channel characteristics $\{P(e_n = \eta) = p_\eta\}_{\eta \in GF(q^2)}$. The likelihood of each value of e_n is recorded and continuously updated according to (13) and the initial channel characteristics.

A. LLR-BP FOR STABILIZER CODES OVER GF(2¹)

Definition 4: Suppose that we have an (unknown) error vector $e = (e_1, \ldots, e_N) \in GF(q^2)^N$. For $n = 1, \ldots, N$, the initial belief of e_n being 0 rather than $\zeta^i \neq 0 \in GF(q^2)$ for $i \in \{0, 1, \ldots, q^2 - 2\}$ is the LLR

$$\Lambda_n^{(i)} = \ln \frac{P(e_n = 0)}{P(e_n = \zeta^i)} \in \mathbb{R}.$$

The initial belief distribution of e_n is the LLR vector

$$\Lambda_n = (\Lambda_n^{(0)}, \Lambda_n^{(1)}, \dots, \Lambda_n^{(q^2-2)}) \in \mathbb{R}^{q^2-1}.$$

Definition 5: A generalized depolarizing channel with error rate ϵ is a memoryless q^2 -ary symmetric channel that takes each nonzero error $\zeta^i \in GF(q^2), i \in \{0, 1, \dots, q^2 - 2\}$, with probability $\frac{\epsilon}{q^2-1}$ and no error with probability $1 - \epsilon$, i.e.,

$$\Lambda_n^{(i)} = \ln\left((1-\epsilon)(q^2-1)/\epsilon\right) \quad \forall i = 0, 1, \dots, q^2 - 2.$$

The initial beliefs $\{\Lambda_n\}_{n=1}^N$ are the information about the channel statistics and will be kept constant during decoding.

Given $\{\Lambda_n\}_{n=1}^N$, $z \in \{0, 1\}^M$, and $H \in GF(q^2)^{M \times N}$, BP intends to find the most probable value of e_n for each *n* by computing a set of running beliefs $\{\Gamma_n = (\Gamma_n^{(0)}, \dots, \Gamma_n^{(q^2-2)}) \in \mathbb{R}^{q^2-1}\}_{n=1}^N$, where $\Gamma_n^{(i)}$ is to estimate

$$\ln \frac{P(e_n = 0 \mid \text{syndrome } z)}{P(e_n = \zeta^i \mid \text{syndrome } z)} = \ln \frac{P(e_n = 0, \text{ syndrome } z)}{P(e_n = \zeta^i, \text{ syndrome } z)}$$
$$= \ln \frac{\sum_{u \in GF(q^2)^N: u_n = 0} \mathbb{1}_{\{\langle u, H \rangle = z\}} P(e = u)}{\sum_{u \in GF(q^2)^N: u_n = \zeta^i} \mathbb{1}_{\{\langle u, H \rangle = z\}} P(e = u)}$$
(14)

where $\mathbb{1}_{(\langle u,H\rangle=z)} = 1$, if $\langle u,H\rangle = z$, and $\mathbb{1}_{(\langle u,H\rangle=z)} = 0$, otherwise. For $u \in GF(q^2)^N$, let $u|_{\mathcal{N}(m)}$ be the restriction of u to $\mathcal{N}(m)$. Note that $H_m|_{\mathcal{N}(m)}$ is the vector consisting of the nonzero entries of H_m . Then, (13) can be written as

$$z_m = \langle e|_{\mathcal{N}(m)}, H_m|_{\mathcal{N}(m)} \rangle \tag{15}$$

or

$$\langle e_n, H_{mn} \rangle + z_m = \langle e|_{\mathcal{N}(m) \setminus n}, H_m|_{\mathcal{N}(m) \setminus n} \rangle.$$
 (16)

By (15) and (16), terms in (14) can be approximated by the distributive law [23], if the check matrix is sparse, as follows:

$$P(e_{n} = \zeta^{i}, \text{ syndrome } z)$$

$$= \sum_{\substack{u \in GF(q^{2})^{N}:u_{n} = \zeta^{i}, \\ (u,M_{m})=z_{m} \forall m}} P(e = u)$$

$$= \sum_{\substack{u \in GF(q^{2})^{N}:u_{n} = \zeta^{i}, \\ (u|_{\mathcal{N}(m)},H_{m}|_{\mathcal{N}(m)})=z_{m} \forall m}} \left(\prod_{j=1}^{N} P(e_{j} = u_{j}) \right)$$

$$\propto \prod_{\substack{u \in GF(q^{2})^{N}:u_{n} = \zeta^{i}, \\ (u|_{\mathcal{N}(m)}\setminus n,H_{m}|_{\mathcal{N}(m)}\setminus n^{i})} = (\zeta^{i},H_{mn}) + z_{m}}} P(e|_{\mathcal{N}(m)\setminus n} = u|_{\mathcal{N}(m)\setminus n}) \right)$$

$$\times P(e_{n} = \zeta^{i})$$
(17)

where $P(e|_{\mathcal{N}(m)\setminus n} = u|_{\mathcal{N}(m)\setminus n}) = \prod_{n' \in \mathcal{N}(m)\setminus n} P(e_{n'} = u_{n'})$ after $P(e_n = \zeta^i)$ is separated.⁵ It is similar for approximating $P(e_n = 0, \text{ syndrome } z)$. When the Tanner graph is a tree, the (proportional) approximation in (17) becomes an equality after iterative updates [by a flow described after (24)]. The approximation is usually good for a sparse *H*, and then we have the $\Gamma_n^{(i)}$ for (14) expressed as in shown (18) and (19) at the bottom of the page.

The numerator (or denominator) in the logarithm of (19) is close to the usual sum-product computation of BP over GF(2), which has efficient hyperbolic tangent rule for computation [7], [25, Sec. 2.5.2]; however, $u|_{\mathcal{N}(m)\setminus n}$ here is a vector in GF(q^2) $|^{\mathcal{N}(m)|-1}$, rather than GF(2) $|^{\mathcal{N}(m)|-1}$. Thus, it needs simplification before we can reach an efficient computation. The trick is to describe the likelihood of commutation and anticommutation of e_n and H_{mn} by a Bernoulli (binary) random variable. At qudit *n*, if $H_{mn} = \eta \neq 0$, then the required random variable would be $\langle e_n, \eta \rangle \in \{0, 1\}$.

Definition 6: For an LLR-type vector, such as Λ_n in Definition 4, we define a belief-quantization operator λ_η : $\mathbb{R}^{q^2-1} \to \mathbb{R}$ for $\eta \in \mathrm{GF}(q^2) \setminus \{0\}$ by

$$\lambda_{\eta}(\Lambda_n) = \ln \frac{\sum_{\xi \in \mathrm{GF}(q^2): \langle \xi, \eta \rangle = 0} P(e_n = \xi)}{\sum_{\xi \in \mathrm{GF}(q^2): \langle \xi, \eta \rangle = 1} P(e_n = \xi)}$$

⁵To get the result of (17), one can also start from the Bayes' theorem: $P(e_n = \zeta^i, \text{ syndrome } z) = P(\text{syndrome } z \mid e_n = \zeta^i) \times P(e_n = \zeta^i).$

$$=\ln\frac{1+\sum_{i:\langle\zeta^{i},\eta\rangle=0}e^{-\Lambda_{n}^{(i)}}}{\sum_{i:\langle\zeta^{i},\eta\rangle=1}e^{-\Lambda_{n}^{(i)}}}.$$
(20)

Note that

$$\lambda_{\eta}(\Lambda_n) = \ln \frac{P(\langle e_n, \eta \rangle = 0)}{P(\langle e_n, \eta \rangle = 1)}$$
(21)

which is the LLR of the binary random variable $\langle e_n, \eta \rangle$ and this term features the major difference between our algorithm and the classical nonbinary LLR-BP [38].

Having the scalar information $\lambda_{H_{mn}}(\Lambda_n)$ for each edge (m, n), where $H_{mn} \neq 0$, BP completes the update (19) by the tanh rule mentioned in [24] and [40], [25, Sec. 2.5.2], defined as follows. For two scalars $x, y \in \mathbb{R}$

$$x \boxplus y \triangleq 2 \tanh^{-1} \left(\tanh \frac{x}{2} \times \tanh \frac{y}{2} \right).$$
 (22)

More generally, for *k* scalars $x_1, \ldots, x_k \in \mathbb{R}$

$$\underset{n=1}{\overset{k}{\boxplus}} x_n \triangleq 2 \tanh^{-1} \left(\prod_{n=1}^k \tanh \frac{x_n}{2} \right).$$
 (23)

Then, the update (19) can be computed by the tanh rule

$$\Gamma_{n}^{(i)} = \Lambda_{n}^{(i)} + \sum_{\substack{m \in \mathcal{M}(n)\\\langle \zeta^{i}, H_{nn}\rangle = 1}} (-1)^{z_{m}} \left(\underset{n' \in \mathcal{N}(m) \setminus n}{\boxplus} \lambda_{H_{nn'}}(\Lambda_{n'}) \right)$$
(24)

which completes the computation of the first iteration. We show that (19) and (24) are equivalent in Appendix A.

To iteratively update $\Gamma_n^{(i)}$, BP performs the message passing [19], [21] by exchanging two types of messages: variableto-check messages $\lambda_{H_{mn}}(\Gamma_{n \to m})$ and check-to-variable messages $\Delta_{m \to n}$, where $\Gamma_{n \to m} = \Lambda_n$ for the initialization. The proposed LLR-BP decoding algorithm is shown in Algorithm 1. Note that in the conventional BP, if *H* is over GF(q^2), each message is a vector of length q^2 [34]–[36], [11]–[13], but we need only scalar messages in our refined algorithm. We remark that in (26) and (27), the summation is restricted to the anticommute part. This is nontrivial and is different from the conventional approach.

We explain the messages. First, write (16) as

$$\langle e_n, H_{mn} \rangle = z_m + \sum_{n' \in \mathcal{N}(m) \setminus n} \langle e_{n'}, H_{mn'} \rangle.$$

This suggests that the information from a neighboring check m, together with the syndrome bit z_m , will tell us

$$\Gamma_{n}^{(i)} = \Lambda_{n}^{(i)} + \sum_{m \in \mathcal{M}(n)} \ln \frac{\sum_{\substack{\langle u | \mathcal{M}(m) \setminus n: \\ = \langle 0, H_{mn} \rangle + z_{m}}} \left(\prod_{n' \in \mathcal{N}(m) \setminus n} P(e_{n'} = u_{n'}) \right)}{\sum_{\substack{\langle u | \mathcal{M}(m) \setminus n: \\ = \langle 0, H_{mn} \rangle + z_{m}}} \left(\prod_{n' \in \mathcal{N}(m) \setminus n} P(e_{n'} = u_{n'}) \right)} \right)$$
(18)
$$= \Lambda_{n}^{(i)} + \sum_{\substack{m \in \mathcal{M}(n) \\ \langle \zeta^{i}, H_{mn} \rangle = 1}} (-1)^{z_{m}} \ln \frac{\sum_{\substack{u | \mathcal{M}(m) \setminus n: \\ \langle u | \mathcal{M}(m) \setminus n: H_{m} | \mathcal{M}(m) \setminus n \rangle = 0}} \left(\prod_{n' \in \mathcal{N}(m) \setminus n} P(e_{n'} = u_{n'}) \right)}{\sum_{\substack{u | \mathcal{M}(m) \setminus n: \\ \langle u | \mathcal{M}(m) \setminus n: H_{m} | \mathcal{M}(m) \setminus n \rangle = 1}} \left(\prod_{n' \in \mathcal{N}(m) \setminus n} P(e_{n'} = u_{n'}) \right)} \right)$$
(19)

Algorithm 1: LLR-BP for Decoding Quantum Codes Over $GF(q = 2^l)$ With Binary Syndrome.

Input: $H \in GF(q^2)^{M \times N}$, $z \in \{0, 1\}^M$, $T_{\max} \in \mathbb{Z}_+$, and LLR vectors $\{\Lambda_n \in \mathbb{R}^{q^2-1}\}_{n=1}^N$. **Initialization**: For n = 1 to N and $m \in \mathcal{M}(n)$, let

$$\Gamma_{n \to m} = \Lambda_n$$

and compute $\lambda_{H_{mn}}(\Gamma_{n \to m})$.

Horizontal step: For m = 1 to M and $n \in \mathcal{N}(m)$, compute

$$\Delta_{m \to n} = (-1)^{z_m} \bigoplus_{n' \in \mathcal{N}(m) \setminus n} \lambda_{H_{mn'}}(\Gamma_{n' \to m}).$$
(25)

Vertical step: For n = 1 to N and $m \in \mathcal{M}(n)$, compute

$$\Gamma_{n \to m}^{(i)} = \Lambda_n^{(i)} + \sum_{\substack{m' \in \mathcal{M}(n) \setminus m \\ \langle \xi^i, H_{m'n} \rangle = 1}} \Delta_{m' \to n}, \forall i = 0, \dots, q^2 - 2,$$
(26)

and compute $\lambda_{H_{mn}}(\Gamma_{n \to m})$.

Hard-decision step: For n = 1 to N, compute

$$\Gamma_n^{(i)} = \Lambda_n^{(i)} + \sum_{\substack{m \in \mathcal{M}(n)\\ \langle \zeta^i, H_{mn} \rangle = 1}} \Delta_{m \to n}, \forall i = 0, \dots, q^2 - 2.$$

(27) • Let $\hat{e} = (\hat{e}_1, \dots, \hat{e}_N)$, where $\hat{e}_n = 0$, if $\Gamma_n^{(i)} > 0$ for $i = 0, \dots, q^2 - 2$, and $\hat{e}_n = \arg \min_{\zeta^i \in GF(q^2)} \Gamma_n^{(i)}$, otherwise.

The horizontal, vertical, and hard-decision steps are iterated until that the inferred \hat{e} has syndrome *z* (i.e., $\langle \hat{e}, H \rangle = z$) or that the maximum number of iterations T_{max} is reached.

the likelihood of the error e_n commuting with H_{mn} or not, which can be quantified by a scalar. Thus, $\lambda_{H_{mn}}(\Gamma_{n\to m})$ is the (scalar) message that variable node *n* has to send to check node *m*, where $\Gamma_{n\to m}$ initialized to Λ_n . Then, check node *m* combines the incoming $\lambda_{H_{mn'}}(\Gamma_{n'\to m})$ and generates $\Delta_{m\to n}$ (25), which is the (scalar) message that check node *m* has to send to variable node *n*.

Consequently, variable node *n* collects the messages $\Delta_{m \to n}$ for $m \in \mathcal{M}(n)$, together with the initial belief Λ_n , to update the running belief Γ_n (27). Updating $\Gamma_{n \to m}$ (26) can be simplified by, for each entry *i*, $\Gamma_{n \to m}^{(i)} = \Gamma_n^{(i)} - \Delta_{m \to n}$, if $\langle \zeta^i, H_{mn} \rangle = 1$, and $\Gamma_{n \to m}^{(i)} = \Gamma_n^{(i)}$, otherwise. Then, the updated $\Gamma_{n \to m}$ is used to update the message $\lambda_{H_{mn}}(\Gamma_{n \to m})$, which will be sent to check node *m* for the next iteration. (The computations may be further simplified as in Remark 4.) The two types of message passing (*m*-to-*n* and *n*-to-*m*) are iterated until a stop criterion is achieved.

Note that the estimate of $\Gamma_n^{(i)}$ by BP is very good if the neighboring messages incoming to a node are nearly independent [7, Sec. 4.2] (e.g., when the parity checks have small overlap). In particular, if the Tanner graph is a tree, BP is exact and converges quickly. Quantum codes inevitably have

correlated (dependent) messages due to short cycles. We will discuss more in the section of simulations (see Section IV).

B. SOME REMARKS

Remark 1: The computations in (20)–(23) can be efficiently computed by numerical or lookup-table methods [7], such as the Jacobian logarithm [38]–[41]. The function $\lambda_{\eta}(\cdot)$ can be computed by repeatedly using a function $f : \mathbb{R}^2 \to \mathbb{R}$ defined by $f(x, y) \triangleq \ln(e^x + e^y) = \max(x, y) + \ln(1 + e^{-|x-y|})$. Since $\ln(1 + e^{-|x-y|}) \in [0, \ln(2)] \subset [0, 0.69315]$, it can be implemented by a lookup-table or any numerical methods. The multiplications can be avoided if the lookup-table method is used. As in [40], $x \boxplus y = \ln \frac{1+e^{x+y}}{e^x+x^y}$ $= \ln(1 + e^{x+y}) - \ln(e^x + x^y)$, which can also be computed by f.

Remark 2: When q = 2, the LLR-BP in Algorithm 1 is equivalent to the refined linear-domain BP for binary quantum codes [16, Algorithm 3]. The linear-domain algorithm can also be extended to $q = 2^{l}$. A linear-domain algorithm is suitable for a decoder with fast floating-point multiplication.

Remark 3: Algorithm 1 is specified using a *parallel schedule*. Other schedules can also be used (e.g., a *serial schedule* is used in [16, Algorithms 2 and 4]).

Remark 4: The computations in Algorithm 1 may be simplified. First, compute (27) but do not compute (26). Then, it is not hard to show that (26) can be omitted and

$$\lambda_{H_{mn}}(\Gamma_{n \to m}) = \lambda_{H_{mn}}(\Gamma_n) - \Delta_{m \to n}.$$
 (28)

Similarly, to compute each $\Delta_{m \to n}$ in (25), one can first compute $\Omega_m \triangleq \bigoplus_{n \in \mathcal{N}(m)} \lambda_{H_{mn}}(\Gamma_{n \to m})$ and then compute $\Delta_{m \to n} = \Omega_m \boxminus \lambda_{H_{mn}}(\Gamma_{n \to m})$,⁶ where

$$x \boxminus y = 2 \tanh^{-1} \left(\tanh \frac{x}{2} / \tanh \frac{y}{2} \right)$$

for $x, y \in \mathbb{R}$ such that $y \neq 0$ and |x| < |y|.

Remark 5: It is known that using a conventional BP over $GF(q^2)$ has a high check-node complexity $O(q^2 \log q^2)$ per edge, which dominates the complexity of BP [13], [35], [36]. Since Algorithm 1 uses scalar messages, the check-node complexity is O(1) per edge, independent of q. Beside the low complexity, using scalar messages has advantages in performance as explained in the following.

Since only scalar messages are exchanged in Algorithm 1, it is straightforward to apply the techniques of *message nor-malization* or *message offset* to improve the performance of BP when the messages are overestimated [45]–[47].

1) Message normalization by $\alpha_c > 0$: the message $\Delta_{m \to n}$ in (25) is normalized to $\Delta_{m \to n} / \alpha_c$ prior to the subsequent computations of the algorithm.

⁶This may be an approximation since, before computing Ω_m , a tiny disturbance needs to be introduced to $\lambda_{H_{mn}}(\Gamma_{n\to m})$ if it is zero. Then when using $x \boxminus y$, it can be guaranteed that $y \neq 0$ and |x| < |y|. This does not affect the performance in simulations if the disturbance is small enough.

Message offset by β > 0: the message Δ_{m→n} in (25) is offset to sign(Δ_{m→n}) × max(0, |Δ_{m→n}| − β) prior to the subsequent computations of the algorithm.

Messages are overestimated because the overlap between two parity checks is not small, causing (unreliable) dependent messages passing in the Tanner graph. Quantum stabilizer codes inevitably have this issue and can suffer significant BP performance loss or have high error-floors [10]–[18].

Remark 6: In the linear-domain algorithm [16], it needs to compute $(\cdot)^{1/\alpha}$ for message normalization or $(\cdot) \times 1/e^{\beta}$ for message offset. Applying message normalization or offset in LLR-BP is much simpler as shown earlier.

Remark 7: For the implementation cost, a practical concern is that, compared to a linear-domain algorithm, an LLR algorithm can be implemented with smaller bit-width (e.g., each scalar is represented by the six most significant bits (MSBs) for decoding classical binary codes as suggested by Gallager [7]). This will be discussed more in the following section. Since $\lambda_{\eta}(\cdot)$ and the operation \boxplus can be approximately computed using looking-up tables (Remark 1), the LLR algorithm with message normalization or offset does not need multiplications. (If α_c is used, choose $1/\alpha_c$ to be a value with smaller bit-width and then the computation of $(\cdot) \times 1/\alpha_c$ only takes several bitwise-shifts and additions.)

Remark 8: Suppose that *H* is constructed from \tilde{H} by the CSS extension (11). If a binary syndrome $z \in \{0, 1\}^M$ is obtained according to *H*, a nonbinary syndrome $\tilde{z} \in \text{GF}(2^{2l})^{\frac{M}{2l}}$ can be derived from $z \in \{0, 1\}^{M, 7}$ Then, the classical nonbinary BP (referred to as CBP_{q^2}) can decode the syndrome \tilde{z} according to \tilde{H} . (See Appendix B.)

On the other hand, given a parity-check matrix $\tilde{H} \in$ GF(2^{*l*})^{*M'*×*N*} of a classical linear code over GF(2^{*l*}) with short cycles, \tilde{H} can be extended as an additive check matrix $H \in$ GF(2^{*l*})^{*lM'*×*N*} by a step like (11). Then, we can use a decoding strategy like Algorithm 1 (possibly with α_c or β) to improve the BP performance on this classical code.

Although (H, z) and (\tilde{H}, \tilde{z}) in Remark 8 contain the same amount of information, the results of using Algorithm 1 on (H, z) and using CBP_{q^2} on (\tilde{H}, \tilde{z}) would be different. The major difference is that CBP_{q^2} is more likely to have overestimated messages when there are short cycles. This is a disadvantage of using CBP_{q^2} even if the quantum code is obtained from a classical linear code. For comparison, we provide a detailed discussion in Appendix B using Steane's code [3]. In the comparison, Algorithm 1 indeed handles the message-overestimate problem better. In the following simulations, we will focus on the performance of Algorithm 1.

IV. SIMULATION RESULTS

Several advantages of using the scalar-based LLR-BP algorithm are suggested in the abovementioned remarks. In this section, we provide numerical results to show these advantages, focusing on how good performance can be achieved

⁷See [13, Table 5] for the case of q = 2; this can be generalized to $q = 2^{l}$.

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with low complexity. Algorithm 1 supports $q = 2^l$, so it will be referred to as LLR-BP_{q²}, depending on the q used. For q = 2 ($q^2 = 4$), Algorithm 1 is referred to as LLR-BP₄. Its linear-domain analogue [16, Algorithm 3] is referred to as linear-BP₄.

In decoding, the number of short cycles is positively correlated with the (mean) *row-density* of the check matrix, $\kappa = \frac{1}{M} \sum_{m=1}^{M} |H_m|/N$. We will consider codes with κ from small to large. The first is a [[129, 28]]₂ hypergraph-product (HP) code with $\kappa \approx 5.9/129 \approx 0.0457$, the second is a [[256, 32]]₂ bicycle code with $\kappa = 16/256 = 0.0625$, and the third is a [[126, 28]]₂ generalized bicycle (GB) code with $\kappa = 10/126 = 0.0794$. Then, we construct [[256, 32]]_{q=4} and [[126, 28]]_{q=4} codes by using (11) and (12) from the second and third codes, respectively. Note that (11) or (12) will result in much more short cycles.

It is known that the BP performance on quantum codes may be improved by using a serial schedule [16], [50], [51]. A fully parallel implementation of message passing is preferred for faster decoding. Herein, we demonstrate LLR- BP_{q^2} for q = 2 or 4 with the parallel schedule and try to improve the decoding performance.

A scalar can be represented as a floating-point number

$$(-1)^{b_0} \times 1.(b_1b_2...b_{k-1})_2 \times 2^{\exp}$$

as in the IEEE 754 standard [52], where $b_0, b_1, \ldots, b_{k-1} \in \{0, 1\}$ and k is called the bit-width. Using a larger k increases the precision (for both additions or multiplications) but also increases the physical hardware area and computation time. We use the [[129, 28]] HP code to show that LLR-BP requires a smaller k compared to linear-domain BP (see Section IV-A). This is consistent with the classical case, despite that the HP code has many short cycles.

Next, we describe the details of the simulations. We will evaluate the performance of various decoding setups and consider the generalized depolarizing errors (Definition 5) on certain quantum stabilizer codes. Each initial LLR vector Λ_n in $\{\Lambda_n\}_{n=1}^N$ is set to

$$\Lambda_n = \left(\ln \frac{(1-\epsilon_0)}{\epsilon_0/(q^2-1)}, \dots, \ln \frac{(1-\epsilon_0)}{\epsilon_0/(q^2-1)}\right) \in \mathbb{R}^{q^2-1}$$
(29)

where ϵ_0 is chosen to be the depolarizing error rate ϵ or a certain constant independent of ϵ . The reasons to choose ϵ_0 a constant are related to the performance [53], as well as the complexity, and will be seen later. Using a constant ϵ_0 also avoids the need to probe or estimate the channel statistic ϵ .

For each simulation of a data point, we try to collect at least 100 logical errors, i.e., $\hat{e} - e \notin \operatorname{row}(H)$. Let $C = \operatorname{row}(H)$. A logical error occurs when the syndrome is falsely matched $(\hat{e} - e \in C^{\perp} \setminus C)$ or T_{\max} is reached but the syndrome is mismatched $(\hat{e} - e \notin C^{\perp})$. We will try to minimize the maximum number of iterations T_{\max} or match it to the literature.

For comparison, consider a *generalized* bounded-distance decoding (BDD) with a lookup-table to have logical error



FIGURE 2. Performance curves of various decoders on the [[129, 28, 3]] HP code. The [LP19] curve is converted from [18], using (31).

rate

$$P_{e,BDD}(N,t,\gamma) = 1 - \left(\sum_{j=0}^{t} \gamma_j {N \choose j} \epsilon^j (1-\epsilon)^{N-j}\right) \quad (30)$$

where *t* is the (error-)correction radius and γ_j is the percentage of weight-*j* errors to be corrected. We simply denote it by $P_{e,BDD}(N, t)$ if $\gamma_j = 100\%$ for all $j \le t$. Also, we redraw the performance curves given in the literature. If it is based on independent *X*–*Z* channel with a cross probability ϵ_b , it will be rescaled according to a conversion rule in [10]:

$$\epsilon = 3\epsilon_b/2. \tag{31}$$

Using this rule may slightly overestimate the performance in the depolarizing channel but it is acceptable.

In the following, we may omit q when referring to an $[[N, K, D]]_{q=2}$ code. All tested codes are nondegenerate, and for degenerate codes the readers can refer to [54].

A. [[129, 28, 3]] HP CODE

First, we consider a [[129, 28, 3]] HP code [44], which is constructed with the [7, 4, 3] and [15, 7, 5] BCH codes, discussed in [16], [18], and [51]. The performance of BP decoding on this code is bad with the parallel schedule. It can be improved by using a serial schedule [16], [51] or using a neural-network based BP₂ (NBP) [18]. Herein, we show that it can be improved by using message offset with low complexity, while keeping the parallel schedule.

If a correction radius of t = 2 is considered, this code is known to have $\gamma_0 = 1$, $\gamma_1 = 1$ and $\gamma_2 \approx 98.73\%$ [51]. We plot the performance curves of LLR-BP₄, linear-BP₄, NBP, and the lookup-table decoders $P_{e,BDD}(N, t = 1)$ and $P_{e,BDD}(N, t = 2, \gamma_2 = 98.73\%)$ in Fig. 2. Due to the many short cycles in the Tanner graph, LLR-BP₄ does not perform well. However, after applying a message offset with $\beta = 0.5$, its performance is close to the lookup-table decoder. We also do simulations by truncating all messages to some bit-width k. The required bit-width is about k = 5 or 6, which is close to Gallager's expectation in Remark 7, though sometimes larger bit-width may be needed due to the short cycles.

When initializing Λ_n (29), we use a fixed $\epsilon_0 = 0.02$ (also truncated to k MSBs). Otherwise, if $\epsilon_0 = \epsilon$, then $|\Lambda_n^{(i)}|$ becomes too-large when ϵ gets small: it will be insensitive to small $|\Delta_{m\to n}|$ when performing (26) or (27), causing ineffective message passing. In the simulations, it only needs a maximum number of iterations $T_{\text{max}} = 3$, so the complexity is very low. (The bad performance of LLR-BP₄ without message offset is irrelevant to constant ϵ_0 or $T_{\text{max}} = 3$.) On the other hand, if linear-BP₄ is used, then it requires bitwidth k = 11 based on the choice of $e^{\beta} = 2$ for message offset, which can be implemented by bitwise-shift. In linear domain, one may also consider $e^{\beta} = 1.6$: this only needs k = 10 to achieve the same performance but implementing $(\cdot) \times 1/e^{\beta} \approx (\cdot) \times 0.625$ (Remark 6) needs a multiplication or two bitwise-shifts with one addition.

We choose an offset β (which is like a threshold) and a constant ϵ_0 (29) by the following criteria, together with some presimulations like [16, Fig. 11]. We need $|\Delta_{m \to n}|$ large enough to pass the threshold β . The magnitude $|\Delta_{m \to n}|$ would increase with the number of iterations [7]. Since we use a small $T_{\text{max}} = 3$ for this code, β cannot be too large. ($\beta = 0.5$ here is comparatively small than $\beta = 2.75$ for the other cases with larger T_{max} that will be discussed later.) Also, we need small enough ϵ_0 to have large enough $|\Delta_n|$, so that $|\Delta_{m \to n}|$ is large enough to pass the threshold β . Thus we have large $|\Lambda_n|$ but relatively smaller $|\Delta_{m \to n}|$ due to small $T_{\text{max}} = 3$. Consequently, k should be large enough as discussed in the last paragraph. (Using a k smaller than the lower bounds suggested in Fig. 2 can cause large performance degradation, due to ineffective message passing.)

On the other hand, using α_c (which will be used later) does not require a fixed ϵ_0 since there is no threshold effect of β . There is a certain systematic way to choose the normalization value [54, Sec. III-B and Fig. 3]. To choose a better normalization value, some presimulations are useful [16, Fig. 9].

Finally, we use (31) to redraw the NBP performance curve given in [18]. (The NBP is also efficient in run-time, but 12 iterations are needed.) The curve shows that using a trained neural-network decoder is able to have a better performance for large ϵ but is hard to achieve a low error-floor for small ϵ .

B. BINARY QUANTUM BICYCLE CODES

Second, we simulate bicycle codes [10] and GB codes [43] as in [15, Fig. 5]. We construct the [[126, 28, 8]] GB code defined in [15] (to be decoded with $T_{\text{max}} = 32$) and a [[256, 32]] random bicycle code discussed in [16] (to be decoded with $T_{\text{max}} = 12$). The results are shown in Fig. 3.

For reference, the curve denoted [PK19] is the result for the GB code given in [15], which is based on a layered (serial) schedule. We show that BP with parallel schedule works as well on this GB code. It can be further improved by using α_c . (Using β with proper ϵ_0 also



FIGURE 3. Performance curves of various decoders on the [[126, 28, 8]] GB code and the [[256, 32]] random bicycle codes. The [PK19] curve is from [15]. The [LP19] curves are converted from [18], using (31).

works.) Gallager estimated that BP would have performance close to $P_{e,BDD}(N, t \approx d)$ [7], much better than the typical BDD performance $P_{e,BDD}(N, t \approx d/2)$. We draw the case $P_{e,BDD}(N, t \approx d)$ for reference. The simulation results agree with Gallager's expectation.

For the [[256, 32]] (random) bicycle code, it has a high error-floor [16] (due to random construction [55]). We show that using $\beta = 2.75$ with $\epsilon_0 = 5 \times 10^{-3}$ significantly improves the error-floor. (Using α_c also works.) The code's check matrix has a constant row-weight 16, and thus, the code distance $D \leq 16$, due to a row-deletion step in the bicycle construction [10]. (Increasing the row-weight may lead to some unwanted side-effects in the BP performance such as delayed waterfall roll-off [10, Fig. 6].) If $D \approx 16$, this code may have BP performance approaching $P_{e,BDD}(N, t = 16)$ by Gallager's expectation. Increasing T_{max} can achieve this performance. For the convenience of discussion, we will show this for the case of q = 4 in the following section. [The qudit-wise error correction capability would be at least the same as the case of q = 2 by using the CSS extension (11).]

The performance curves (labeled [LP19] BP₂ and NBP) of another random [[256, 32]] bicycle code in [18] are rescaled by (31) and also plotted in Fig. 3 for comparison. Although NBP improves from BP₂ by several orders of magnitude, the resultant performance is not good enough because the original error-floor of [LP19] BP₂ is too-high. From our experience, this is likely because the binary generator vector used for construction has many consecutive ones, causing too-many short cycles in the Tanner graph. Using the random bicycle construction appropriately,⁸ the curves we obtained have much lower error-floors.



FIG. 4. Performance of Algorithm 1 on the [[256, 32]]_{q=4} random bicycle code. *D* is unknown but \leq 16. When β is applied, a fixed $\epsilon_0 = 5 \times 10^{-3}$ is used for initializing Λ_n (29) to prevent delayed waterfall roll-off.

C. NONBINARY QUANTUM BICYCLE CODES

Herein, we extend the previous [[256, 32]] bicycle code and [[126, 28]] GB code to q = 4 by (11) and (12), respectively. The previous [[256, 32]] code has a check matrix $H = \begin{bmatrix} \tilde{H} \\ \omega_0 \tilde{H} \end{bmatrix}$, where \tilde{H} is a binary matrix such that $\tilde{H}\tilde{H}^T = O$ and ω_0 is a primitive element of GF(4). By the CSS extension, we have the following check matrix for a [[256, 32]]₄ code

$$H = \begin{bmatrix} \tilde{H} \\ \omega \tilde{H} \\ \omega^2 \tilde{H} \\ \omega^3 \tilde{H} \end{bmatrix}$$

where ω is a primitive element of GF(16).

We perform the decoding of this $[[256, 32]]_4$ code in the q^2 -ary symmetric channel (Definition 5) by Algorithm 1 (now LLR-BP₁₆). Different values of T_{max} are considered, and the results are shown in Fig. 4. Using either α_c or β improves the BP performance (to a similar level), and we show the case of using β . Several BDD cases are also provided. It can be seen that using β significantly improves the error-floor performance even with small $T_{\text{max}} = 6$. For $T_{\text{max}} = 12$, the performance trend is similar to the corresponding case in Fig. 3. By increasing T_{max} from 12 to 25, the performance improves by about half an order of magnitude. With message offset, there is no significant improvement if T_{max} is further increased to 50. The CSS extension does not increase D, so the code still has $D \leq 16$. With enough T_{max} , Algorithm 1 with message offset may have performance close to $P_{e,BDD}(N, t = 16)$ at logical error rate around 10^{-5} .

⁸Our [[256, 32]] bicycle code is constructed by a binary generator vector with ones at bits 1, 3, 9, 59, 68, 69, 107, 112; and in the row-deletion step, rows 1, 2, 12, 59, 60, 68, 70, 73, 74, 76, 91, 92, 100, 115, 117, 120 are deleted. For this code size, a purely random construction is usually fine to achieve a good performance by proper message normalization or offset; It is more important to make sure that there are no more than three consecutive ones in the generator vector. The row-deletion becomes tricky (to prevent too irregular Tanner graphs) only when *N* is large (e.g., N > 3000) [55].



FIG. 5. Performance of Algorithm 1 on the $[[126, 28, 8]]_{q=4}$ GB code.

We remark that the high error-floor problem can be improved by carefully doing the row-deletion during the bicycle construction [10], [55]. However, as $D \leq 16$, the performance limit is still about $P_{e,BDD}(N, t = 16)$, and this is roughly achieved by using α_c or β even with random construction. Thus, Algorithm 1 (with proper message normalization or offset) has stable performance regardless of the code construction. This provides more code candidates in applications and more flexibility when designing the stabilizer measurements (rows of H) for physical implementations.

The previous [[126, 28, 8]] GB code has a binary check matrix $H \equiv \begin{bmatrix} H_X & O \\ O & H_Z \end{bmatrix}$ with $H_X \neq H_Z$, and we generalize it as a $[[126, 28, 8]]_{q=4}^{23}$ code by the generalized CSS extension (12). The decoding performance of LLR-BP₁₆ on this code is shown in Fig. 5. Compared to the corresponding case in Fig. 3 ([[126, 28]] curves therein), the raw BP does not perform well here. Using either α_c or β improves the performance (to a similar level). Here, we demonstrate the case of using α_c . The generalized CSS extension (12) induces more short cycles, causing more overestimated messages and degrading the raw BP performance. Applying message normalization significantly improves BP even with small $T_{\text{max}} = 6$. For large $T_{\text{max}} \ge 25$, using message normalization achieves much better performance close to $P_{e,BDD}(N, t = 12)$ at logical error rate 10^{-6} , which means that most errors of weight ≤ 12 are corrected, despite that the minimum distance D = 8only.

V. CONCLUSION AND DISCUSSIONS

We proposed an efficient scalar-based LLR-BP algorithm for decoding quantum codes over $GF(2^l)$, which extended our previous work [16]. This is especially useful when many qubits are grouped into a qudit and a nonbinary decoder is

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used; our demonstrations showed that correlated noise can be well handled by the nonbinary BP.

The check-node complexity in our scalar-based LLR-BP reduces from $O(2^{2l} \log 2^{2l})$ to O(1) per edge. This saves the decoding time and keep the quantum coherence better. Moreover, the LLR algorithm can be implemented with additions and lookup-tables without multiplications. It also has other advantages, such as the smaller bit-width and the convenience for message normalization or offset. Using message normalization or offset to improve the performance of decoding nonbinary quantum codes is very important since they may have more check rows and more short cycles. Computer simulations were conducted, showing that good performances can be achieved by this low-complexity approach. The algorithm has stable performance for various quantum codes and constructions.

Our LLR method naturally extends to a joint decoding of data-syndrome errors by BP [51].

Although our criterion of a successful decoding is $\hat{e} - e \in \text{row}(H)$, \hat{e} rarely converges to a degenerate error that is not e when the decoding succeeds in the simulations of this article. This is because the tested codes are nondegenerate, so BP converges in a way more like classical decoding.

Topological codes are highly degenerate and have stabilizers of low weight around 4 to 6 [56], [57] (causing the *classical* minimum distance \leq 4 or 6 because the code is self-orthogonal). Using the proposed BP algorithm on these degenerate codes has a bad decoding performance. However, further modification on BP to handle these degenerate codes is possible and this is addressed in [54].⁹

A quantum BCH/RS code [58]–[61] has numerous short cycles in its Tanner graph since its parity-check matrix is of high density. We tested two MDS Hermitianorthogonal BCH codes [[17, 9, 5]]₄ and [[17, 13, 3]]₄ in [61] and found that message normalization can improve the scalar-based BP by roughly an order of magnitude. However, it is still far from any good BDD benchmark due to the many short cycles. Preprocessing on the paritycheck matrix [62], [63] or postprocessing by ordered statistics decoding [64], [65] improve BP on classical BCH/RS codes. Our decoder may also be improved through these techniques.

Our approach could be extended to quantum codes over $GF(p^l)$ for a prime p. This would reduce the check-node complexity from $O(p^{2l} \log p^{2l})$ to $O(p \log p)$ per edge and such nonbinary BP still maintains the correlations between the p^{2l} errors in the error basis. The measurement (trace inner product) outcomes would be in GF(p) as in Definition 1. Given nonzero $\eta \in GF(q^2 = p^{2l})$, Corollary 2 should be generalized that the q^2 elements of $GF(q^2)$ are partitioned into p groups (each with q^2/p elements). Each BP message is a probability vector over GF(p) in linear domain, where each entry is the sum of the probabilities of q^2/p elements.

⁹The achieved threshold is roughly 16% and 17.5% for decoding surface codes and toric codes, respectively, as shown in [54, Figs. 14 and 21].

The check-node computation (convolution of two probability vectors over GF(p)) can be done by FFT [35], [36].

APPENDIX A

BASIC VARIABLE-NODE AND CHECK-NODE UPDATE RULES

Herein we show that (19) is equivalent to (24) by using Definition 6 and the tanh rule (22), (23). The derivation is similar to the BP₂ case [25, Sec. 2.5.2]. It suffices to focus on the update for n = 1 with one row H_m . We assume that $\mathcal{N}(m) = \{1, 2, \dots, |H_m|\}$ without loss of generality and prove by induction on $|H_m|$. The strategy is to go through the basic variable-node and check-node update rules [24, Sec. V-E].

If the row is with $|H_m| = 1$, it is trivial that $\Gamma_n^{(i)} = \Lambda_n^{(i)}$. If the row is with two nonzero entries, consider

$$H_m|_{\mathcal{N}(m)=\{1,2\}} = [\eta, \xi].$$

For n = 1, (19) becomes

$$\Gamma_1^{(i)} = \Lambda_1^{(i)} + \langle \zeta^i, \eta \rangle (-1)^{z_m} \lambda_{\xi}(\Lambda_2)$$
(32)

by using (21). The result is identical to (24) for $|H_m| = 2$. Equation (32) is called the basic variable-node update rule.

Now suppose that the belief of n = 1 is to be updated by one weight-three row H_m with

$$H_m|_{\mathcal{N}(m)=\{1,2,3\}} = [\eta, \xi, \xi'].$$

For $\zeta^i \in GF(q^2)$ such that $\langle \zeta^i, \eta \rangle = 0$, both (19) and (24) have the same result

$$\Gamma_{1}^{(i)} = \Lambda_{1}^{(i)} \quad (i.e., no update is needed if \langle \zeta^{i}, \eta \rangle = 0).$$

For $\zeta^{i} \in GF(q^{2})$ such that $\langle \zeta^{i}, \eta \rangle = 1$, if $z_{m} = 0$ in (19)
$$\Gamma_{1}^{(i)} = \Lambda_{1}^{(i)} + \ln \frac{\sum_{\tau,\tau': \langle \tau, \xi \rangle + \langle \tau', \xi' \rangle = 0}^{P(e_{2}=\tau)P(e_{3}=\tau')}}{\sum_{\tau,\tau': \langle \tau, \xi \rangle + \langle \tau', \xi' \rangle = 1}^{P(e_{2}=\tau)P(e_{3}=\tau')}}$$
$$= \Lambda_{1}^{(i)} + \ln \frac{P(\langle e_{2}, \xi \rangle = 0)P(\langle e_{3}, \xi' \rangle = 0) + P(\langle e_{2}, \xi \rangle = 1)P(\langle e_{3}, \xi' \rangle = 1)}{P(\langle e_{2}, \xi \rangle = 0)P(\langle e_{3}, \xi' \rangle = 1) + P(\langle e_{2}, \xi \rangle = 1)P(\langle e_{3}, \xi' \rangle = 0)}$$

where the log term equals the LLR of $\langle e_2, \xi \rangle + \langle e_3, \xi' \rangle$

(mod 2)

$$\begin{split} &= \Lambda_1^{(i)} + \ln \frac{(P(\langle e_2, \xi \rangle = 0) / P(\langle e_2, \xi \rangle = 1))(P(\langle e_3, \xi' \rangle = 0) / P(\langle e_3, \xi' \rangle = 1)) + 1}{P(\langle e_2, \xi \rangle = 0) / P(\langle e_2, \xi \rangle = 1) + P(\langle e_3, \xi' \rangle = 0) / P(\langle e_3, \xi' \rangle = 1)} \\ &= \Lambda_1^{(i)} + \ln \frac{e^x e^y + 1}{e^x + e^y}, \quad \text{where } x = \lambda_{\xi}(\Lambda_2), \ y = \lambda_{\xi'}(\Lambda_3) \\ &= \Lambda_1^{(i)} + \ln \frac{(e^x + 1)(e^y + 1) + (e^x - 1)(e^y - 1)}{(e^x + 1)(e^y + 1) - (e^x - 1)(e^y - 1)} \\ &= \Lambda_1^{(i)} + 2 \tanh^{-1} \left(\frac{e^x - 1}{e^x + 1} \times \frac{e^y - 1}{e^y + 1} \right) \\ &= \Lambda_1^{(i)} + (\lambda_{\xi}(\Lambda_2) \boxplus \lambda_{\xi'}(\Lambda_3)) \quad \text{by (22).} \end{split}$$

In general, we have for $\langle \zeta^i, \eta \rangle \in \{0, 1\}$ and $z_m \in \{0, 1\}$

$$\Gamma_1^{(i)} = \Lambda_1^{(i)} + \langle \zeta^i, \eta \rangle (-1)^{z_m} (\lambda_{\xi}(\Lambda_2) \boxplus \lambda_{\xi'}(\Lambda_3))$$
(33)

which is identical to (24) for $|H_m| = 3$. The combining $(\lambda_{\xi}(\Lambda_2), \lambda_{\xi'}(\Lambda_3)) \mapsto \lambda_{\xi}(\Lambda_2) \boxplus \lambda_{\xi'}(\Lambda_3)$ is called the basic check-node update rule.

Now assume that the belief of n = 1 is to be updated by one weight-four row H_m with $H_m|_{\mathcal{N}(m)} = [\eta, \xi, \xi', \xi'']$. Consider $\langle e_2, \xi \rangle + \langle e_3, \xi' \rangle \pmod{2}$ as a binary random variable; then its LLR is $\lambda_{\xi}(\Lambda_2) \boxplus \lambda_{\xi'}(\Lambda_3)$ by the abovementioned derivation. We can further consider a binary random variable ($\langle e_2, \xi \rangle + \langle e_3, \xi' \rangle$) + $\langle e_4, \xi'' \rangle \pmod{2}$; then its LLR is ($\lambda_{\xi}(\Lambda_2) \boxplus \lambda_{\xi'}(\Lambda_3)$) $\boxplus \lambda_{\xi''}(\Lambda_4)$ by the same reason. Thus, similar to (33) we have

$$\Gamma_{1}^{(i)} = \Lambda_{1}^{(i)} + \langle \zeta^{i}, \eta \rangle (-1)^{z_{m}} \left(\lambda_{\xi}(\Lambda_{2}) \boxplus \lambda_{\xi'}(\Lambda_{3}) \right) \boxplus \lambda_{\xi''}(\Lambda_{4})$$
$$= \Lambda_{n=1}^{(i)} + \langle \zeta^{i}, H_{mn} \rangle (-1)^{z_{m}} \stackrel{4}{\boxplus} \lambda_{H_{mn'}}(\Lambda_{n'}) \quad \text{by (23).}$$

That is, (19) and (24) are equivalent for $|H_m| = 4$. By inducion on $|H_m|$ using the same trick and by joining more rows, we have that (19) and (24) are equivalent.

APPENDIX B COMPARISON OF ALGORITHM 1 AND THE CLASSICAL NONBINARY BP

Conventionally one would like to use classical nonbinary BP to decode quantum codes since they can be considered as special nonbinary codes. We will compare this direct use of classical nonbinary BP with our LLR-BP in Algorithm 1.

We first describe the decoding of binary quantum codes (q = 2). Suppose that $H \in GF(4)^{M \times N}$ and $z \in \{0, 1\}^M$ are given. For convenience, we describe the BP in linear domain with initial beliefs $\{p_n = (p_n^I, p_n^X, p_n^Y, p_n^Z) \in \mathbb{R}^4\}_{n=1}^N$ and running beliefs $\{q_n = (q_n^I, q_n^X, q_n^Y, q_n^Z) \in \mathbb{R}^4\}_{n=1}^N$. Also, the variable-to-check and check-to-variable messages are denoted by $\{q_{nm} = q_{n \to m} \in \mathbb{R}^4\}_{(m,n):H_{mn} \neq 0}$ and $\{r_{mn} = r_{m \to n} \in \mathbb{R}^4\}_{(m,n):H_{mn} \neq 0}$, respectively. Initially, $q_{nm} = p_n$ for each edge (m, n). The following methods are considered in [12] and [13].

1) [12, (13)–(16)] or [13, (31)–(34)]: If the binary quantum code corresponds to an additive code over GF(4), convert the syndrome $z \in \{0, 1\}^M$ to a syndrome $\tilde{z} \in$ GF(4)^{*M*} such that each $z_m = tr(\tilde{z}_m)$. Thus, $\{r_{mn}\}$ can be generated from $\{q_{nm}\}$ using the classical nonbinary BP. Suppose that each $r_{mn} = (r_{mn}^I, r_{mn}^X, r_{mn}^Y, r_{mn}^Z)$ is generated, where $\sum_W r_{mn}^W = 1$. According to the properties in Example 1, do a *post average* as specified in [12] and [13]. For example, if $z_m = 0$ and the edge (m, n) is of type *X*, then the post average rescales the vector as

$$\tilde{r}_{mn} = \left(\frac{r_{mn}^{I} + r_{mn}^{X}}{2}, \frac{r_{mn}^{I} + r_{mn}^{X}}{2}, \frac{r_{mn}^{Y} + r_{mn}^{Z}}{2}, \frac{r_{mn}^{Y} + r_{mn}^{Z}}{2}\right).$$

Then, $q_n^W = a_n p_n^W \prod_{m \in \mathcal{M}(n)} \tilde{r}_{mn}^W$ for all W and n, where a_n is a scalar such that $\sum_W q_n^W = 1$.

2) [13, (44)–(47)] (only for linear codes): If the binary quantum code corresponds to a linear classical code over GF(4), assume that the given H = $\begin{bmatrix} \tilde{H} \\ \omega \tilde{H} \end{bmatrix}$, where $\tilde{H} \in \mathrm{GF}(4)^{\frac{M}{2} \times N}$ is a parity-check matrix of the linear code. Then, one can treat M syndrome bits $\{z_m \in \{0, 1\}\}_{m=1}^{M}$ as M/2 quaternary digits $\{\tilde{z}_m \in \mathrm{GF}(4)\}_{m=1}^{M/2}$, and $\tilde{z} \in \mathrm{GF}(4)^{M/2}$ is regarded as the syndrome generated by the unknown error and the parity-check matrix \tilde{H} . Using the classical nonbinary BP can decode the syndrome. Note that there is no post average on $r_{mn} = (r_{mn}^I, r_{mn}^X, r_{mn}^Y)$, and q_n^W is updated by $q_n^W = a_n p_n^W \prod_{m \in \mathcal{M}(n)} r_{mn}^W$ for all W and n, where a_n is a scalar such that $\sum_W q_n^W = 1$.

Both methods can be generalized to $q = 2^l$, and the checknode complexity is $O(2^{2l} \log 2^{2l})$ per edge. By a derivation like (17)–(24), it can be shown that method 1, after generalized, is equivalent to Algorithm 1 in the sense that they have the same decoding output if no message normalization or offset is considered. However, Algorithm 1 has a check-node complexity O(1) per edge and is more efficient.

If the code is linear, a generalized method 2 for $q = 2^{l}$ is also efficient since the number of checks becomes $\frac{M}{2l}$. However, method 2 tends to have more biased messages r_{mn} , while method 1 and Algorithm 1 tend to have more fair messages \tilde{r}_{mn} . Consequently, method 2 may have overestimated messages. For comparison, we generalize method 2 for $q = 2^{l}$. Let CBP_{q^2} be the classical nonbinary BP (such as [38]) with input: $\tilde{H} \in \text{GF}(q^2)^{\frac{M}{2l} \times N}$, $\tilde{z} \in \text{GF}(q^2)^{\frac{M}{2l}}$, $T_{\text{max}} \in \mathbb{Z}_+$, and $\{\Lambda_n \in \mathbb{R}^{q^2-1}\}_{n=1}^N$; and with output $\hat{e} \in \text{GF}(q^2)^N$. Then, we can impose on CBP_{q^2} with method 2 to solve the decoding problem, as in Algorithm 2.¹⁰

The complexity of each algorithm (or method) is as follows. Let |H| be the number of nonzero entries in H. The variable-node complexity is $O(q^2)$ per edge for each algorithm. Consider the computation flow as in Remark 4.

Algorithm 1 has complexity $|H|O(q^2) + |H|O(1) = O(|H|q^2)$.

A generalized method 1 has complexity $|H|O(q^2) + |H|O(q^2 \log q^2) = O(|H|q^2 \log q^2).$

Algorithm 2 has $|\tilde{H}| = |H|/2l$, where $2l = \log_2(q^2)$. Thus, Algorithm 2 has complexity $|\tilde{H}|O(q^2) + |\tilde{H}|O(q^2\log_2(q^2)) = O(|H|q^2)$ but is only applicable to linear codes.

In [13], method 1 is called *standard nonbinary BP* (though with additional post average) and method 2 is called *modified nonbinary BP* (though it is the check matrix that is modified, not CBP). The authors in [13] recommended to use method 2 for linear codes because of fewer short cycles in \tilde{H} . However, we take issue on method 2 since it may have many overestimated messages to perform less well as shown as follows.

Algorithm 2 : A Decoding Method for Quantum Codes Over GF(q) That Correspond to Classical Linear Codes Over $GF(q^2)$

Input: $H \in GF(q^2)^{M \times N}$ (where $q = 2^l$), $z \in \{0, 1\}^M$, $T_{\max} \in \mathbb{Z}_+, \{\Lambda_n \in \mathbb{R}^{q^2 - 1}\}_{n=1}^N$, and a BP oracle CBP_{q^2} . **Initialization**: • Derive $\tilde{H} \in GF(q^2)^{\frac{M}{2l} \times N}$ from H. • Convert z to $\tilde{z} \in GF(q^2)^{\frac{M}{2l}}$ according to the relation between H and \tilde{H} .

Decoding: run $\hat{e} = \operatorname{CBP}_{q^2}(\tilde{H}, \tilde{z}, T_{\max}, \{\Lambda_n\}_{n=1}^N).$

A. COMPARING ALGORITHMS 1 AND 2 BY USING $[[7, 1, 3]]_q$

Steane's code [3] is a $[[7, 1, 3]]_2$ code with a check matrix $H \in GF(4)^{6\times7}$ extended from a classical Hamming code with a binary parity-check matrix $\tilde{H} \in GF(2)^{3\times7}$ by (11).

We consider to generalize Steane's code by writing $\tilde{H} = \tilde{H}^{(r)}$ to mean that the (binary) \tilde{H} has *r* rows (checks); then the corresponding (q^2 -ary) $H = H^{(r)}$ has 2lr rows for $q = 2^l$ as in (11). The (binary) $\tilde{H}^{(3)}$ can be cyclicly generated by the vector (1011100) with three rows as

$$\tilde{H}^{(3)} = \begin{bmatrix} 1 \ 0 \ 1 \ 1 \ 1 \ 0 \ 0 \\ 0 \ 1 \ 0 \ 1 \ 1 \ 1 \ 0 \\ 0 \ 0 \ 1 \ 0 \ 1 \ 1 \ 1 \end{bmatrix}$$

which has an irregular Tanner graph. If we cyclicly generate seven rows, then the resultant (binary) $\tilde{H}^{(7)}$ has a regular Tanner graph, which provides the same error-correction capability for each qudit. BP on $\tilde{H}^{(7)}$ still has overestimated messages but the incorrect dependency may cancel out.

First, consider the case of q = 2. The $(q^2$ -ary) $H^{(3)}$ and $H^{(7)}$ have 6 and 14 rows, respectively (i.e., Algorithm 1 on $H^{(r)}$ encounters more short cycles than CBP_{q^2} on $\tilde{H}^{(r)}$). The decoding results of Algorithms 1 and 2 are shown in Fig. 6. If the input matrix has (r = 3), both algorithms do not perform well since the Tanner graph is irregular. For a particular error $e = (0000\omega^2 00)$, both decoders converge to a large-weight $\hat{e} = (00\omega^2 \omega^2 \omega^2 \omega^2 0)$ due to overestimated messages. This is improved if the decoding is based on (r = 7). Babar *et al.* [13] considered a fixed initialization $\epsilon_0 = 0.26$ for (29). We adopt a similar value $\epsilon_0 \approx 0.24$ and it indeed improves for the case of (r = 3) when q = 2, as also shown in Fig. 6.

Note that, when q = 2, the code has 2^6 different error syndromes, corresponding to the zero vector (no error), 21 weight-one errors, and 42 weight-two errors. Thus, $\gamma_2 = \frac{42}{\binom{7}{2} \times 3^2} \approx 22.22\%$ in (30). Algorithm 1 is able to achieve this (optimum) correction capability, while Algorithm 2 cannot. This is indicated by two BDD curves in Fig. 6.

¹⁰CBP_{q²} therein is assumed with Hermitian inner product. If it is with Euclidean inner product, simply do conjugate $[\tilde{H}_{mn}^{q}]$ before using CBP_{q²}.



FIG. 6. Decoding $[[7, 1, 3]]_q$ codes for q = 2 and q = 4 with a maximum number of 10 iterations, over the channel in Definition 5. When q = 4, the curves are similar to those of q = 2, except for one case as shown in the figure.



FIG. 7. Decoding on error (100000ω) by Algorithm 1 with q = 2: successful.



FIG. 8. Decoding on error (100000ω) by Algorithm 2 with q = 2: failed. The convention of labels is the same as that in Fig. 7. The decoder runs to a large-weight state (111111ω) at iteration 10 after hard-decision, and will be trapped around (0000000) after iteration 10.

Note that for large ϵ , Algorithm 1 with (r = 7) has performance better than $P_{e,BDD}(N, t = 2, \gamma_2 = 22.22\%)$ because of degeneracy.¹¹

For a specific weight-two error (100000ω) , we plot the decoding output probabilities based on (r = 7) and $\epsilon_0 = 0.1$ in Figs. 7 and 8 for Algorithms 1 and 2, respectively. Algorithm 1 successfully converges, while Algorithm 2 is trapped around the zero vector. (Algorithm 2 runs into a large-weight error before trapped, due to overestimated messages.)

Next, consider the case of q = 4. The (binary) $\tilde{H}^{(r)}$ still has r rows, but the $(q^2$ -ary) $H^{(r)}$ has 4r rows and has much more short cycles compared to the case of q = 2 (2r rows). However, the results are similar except that Algorithm 2 with (r = 3) and $\epsilon_0 \approx 0.24$ does not perform well. We plot this case in Fig. 6. (We scan many values of ϵ_0 , including the value 0.26 used in [13], and also try $\epsilon_0 = \epsilon$, but none of the values provide the improvement like the case of q = 2.)

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¹¹Given a specific syndrome, the decoder may always output the same low-weight error, but for large ϵ , many high-weight degenerate errors occur with high probabilities and will be counted as decoding success.

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