

NF-GAT: A Node Feature-based Graph Attention Network for ASD Classification

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Abstract— Goal: The purpose of this paper is to recognize autism spectrum disorders (ASD) using graph attention network. **Methods:** we propose a node features graph attention network (NF-GAT) for learning functional connectivity (FC) features to achieve ASD diagnosis. Firstly, node features are modelled based on functional magnetic resonance imaging (fMRI) data, with each subject modelled as a graph. Next, we use the graph attention layer to learn the node features and gets the node information of different nodes for ASD classification. **Results:** Compared with other models, the NF-GAT has significant advantages in terms of classification results. **Conclusions:** NF-GAT can be effectively used for ASD classification.

Index Terms—Autism spectrum disorder, Graphical attention network, Functional connectivity, Classification

Significance Statement - A deep learning model, NF-GAT, is constructed, which uses rs-fMRI data to define node features and graph attention network to recognize ASD.

I. INTRODUCTION

AUTISM spectrum disorder (ASD) [1] is a serious mental illness that affects the social behavior and communication

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skills of individuals. Due to its non-invasive, high temporal and spatial resolution [2], fMRI has been widely used in clinical and basic research in a variety of disciplines, including brain neuroscience, cognitive science and psychology [3-5]. Resting-state functional magnetic resonance imaging (rs-fMRI) data have been used to study ASD [6].

In computer-aided diagnosis, machine learning [7] and deep learning [8] have made good achievements in the classification and recognition of ASDs. However, graph structures such as knowledge graphs, brain connections, etc. are often irregular data structures which belong to non-Euclidean space [9]. Irregular data are difficult to be processed by convolutional neural networks (CNN) [10]. At the same time, many researchers have found that graph neural networks (GNNs) are powerful in modelling non-Euclidean data such as brain connectivity networks [11-13]. Graph convolutional networks (GCNs) are one of GNNs, which nicely extend convolutional operations to the graph domain. As brain connectivity graphs are irregular graph structures, GCNs are well suited to handle such data structures. For example, Parisot *et al.* [14] first proposed an application of GCNs to ASD classification. The classification performance of this method is significant improved to traditional machine learning methods. Jiang *et al.* [12] considered both the topological information of fMRI data and the correlation between subjects and used hierarchical GCN learn features for ASD classification. Wen *et al.* [13] used different thresholds to obtain different views, and then used GCN to learn common features between different views for ASD classification.

The above algorithm is well applied in emotion recognition. However, the performance suffers from several limitations due to a variety of problems. Firstly, the GCN-based classification algorithm requires the entire graph structure as the input of the model. Secondly, the GCN model is largely constrained by the graph structure, and the trained model cannot be applied to graphs of different structures. Thirdly, in the GCN model, all edges in the graph have the same weight. To solve these problems, Velicković *et al.* [15] proposed a graph attention network (GAT). GAT aggregates only the features of a node's neighboring nodes as the new features of that node by introducing an attention mechanism when aggregating feature information. At the same time, GAT can learn different weights between nodes, so that each input of GAT is not the whole graph structure but a part of the graph, and which can be applied to different graph structures to capture the correlation between nodes greatly. On the basis of GAT, we construct a

GAT based on node features (NF-GAT), which mainly uses rs-fMRI data to construct brain graph structures through brain atlas and define nodal features, and then learn node features through the graph attention layer to finally achieve the ASD classification. The main contributions are summarized as follows:

- 1) We propose NF-GAT model that can apply the learned node features to the ASD classification, and the experimental results verify the effectiveness of the proposed algorithm.
- 2) We give a new way to construct nodal features based on rs-fMRI data, which can facilitate the use of functional brain

information for ASD classification.

- 3) The node features are mapped by a function and then weighted sum, and experiments show that the NF-GAT can better improve the classification performance.

II. MATERIALS AND METHODS

We construct NF-GAT to extract features from brain functional networks and to classify ASD. The proposed method is described below.

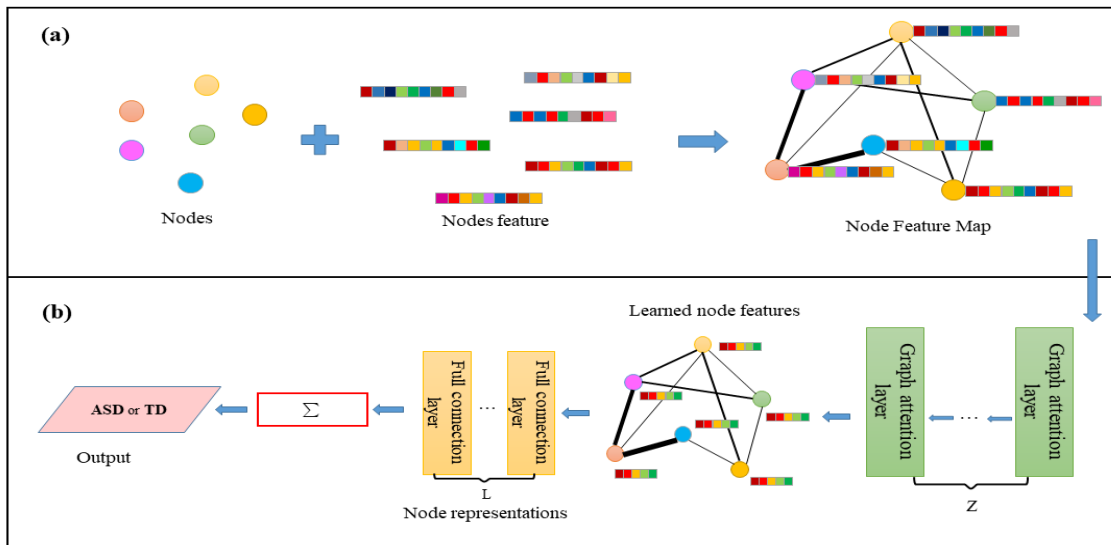


Fig. 1. The structure of NF-GAT

A. Data sets

The datasets used in this paper are drawn from the public database which is Autism Brain Imaging Data Exchange I (ABIDE I) database [16]. Table I summarizes the demographic information for subjects. There are a total of 1112 subjects in the ABIDE dataset. And after pre-processing operation and the high-quality visual examination, 871 subjects are selected for the experiment.

TABLE I
SUBJECT DEMOGRAPHIC-INFORMATION (MEAN ± STD)

Site	ASD		TD	
	Age(year)	Sex(M/F)	Age(year)	Sex(M/F)
Pitt	18.3 ± 7.0	21/3	18.7 ± 6.7	22/4
Olin	17.1 ± 3.3	11/3	16.9 ± 3.6	13/0
OHSU	11.4 ± 2.2	12/0	10.2 ± 1.0	13/0
SDSU	15.3 ± 1.8	8/0	14.0 ± 1.9	13/6
Trinity	17.0 ± 3.2	19/0	17.1 ± 3.8	25/0
UM	12.9 ± 2.5	38/9	15.4 ± 3.4	55/18
USM	23.6 ± 8.4	43/0	20.9 ± 8.3	24/0
Yale	13.1 ± 3.0	14/8	13.6 ± 2.1	11/8
CMU	26.0 ± 5.4	4/2	27.8 ± 4.4	3/2
Leuven	17.0 ± 4.1	23/3	18.4 ± 5.0	26/4
KKI	10.7 ± 1.3	9/3	10.1 ± 1.2	15/6
NYU	14.8 ± 7.1	64/10	15.8 ± 6.2	72/26
Stanford	10.2 ± 1.6	9/3	9.8 ± 1.7	9/4
UCLA	13.1 ± 2.4	42/6	12.7 ± 2.1	32/5
MaxMun	28.4 ± 13.2	16/3	25.2 ± 8.4	26/1
Caltech	24.0 ± 7.6	4/1	28.2 ± 12.2	6/4
SBL	34.0 ± 6.6	12/0	33.6 ± 6.8	14/0
Total	17.1 ± 8.0	349/54	16.8 ± 7.2	378/90

B. Construction of functional connectivity features

FC features are constructed by calculating similarity on pre-processed fMRI data. The process of constructing FC features is as follows. Firstly, the brain is divided into N ROIs by using the Harvard Oxford (HO) atlas [17]. Secondly, the Pearson correlation coefficient is used to calculate the correlation, which can be defined as R_{ij} between brain region r_i and r_j . Finally, a correlation coefficient matrix of $N \times N$ is constructed for each subject, where N is the number of ROIs. This matrix is the functional connectivity matrix (FCM), which can be expressed as:

$$M = \begin{bmatrix} R_{11} & R_{12} & \cdots & R_{1N} \\ R_{21} & R_{22} & \cdots & R_{2N} \\ \vdots & \vdots & \vdots & \vdots \\ R_{N1} & R_{N2} & \cdots & R_{NN} \end{bmatrix} \quad (1)$$

Each row vector \vec{h}_i of the FCM is chosen for the FC features. \vec{h}_i can be expressed as:

$$\vec{h}_i = R_{i1}, R_{i2}, \dots, R_{iN} \quad (2)$$

C. NF-GAT model

The NF-GAT model structure is shown in Fig. 1. The NF-GAT model is mainly divided into two parts: the construction of the node feature graph and GAT. In the first part,

each ROI is used as a node. Combining FC features extracted from fMRI data, we construct a graph containing node features and connecting edges between nodes for each subject. The graph of each subject is described as $\mathbf{G} = \mathbf{h}, \mathbf{R}$, where \mathbf{h} is the node feature set and \mathbf{R} is the edge connected between any two nodes. The second part is the GAT, which can learn the node features and achieve ASD recognition.

1) Construction of the node feature graph

Each ROI is defined as a node. The weight value of the edge is the absolute value of R_{ij} , i.e. $|R_{ij}|$. The set of edges is defined by $\mathbf{R} = |R_{i1}|, |R_{i2}|, \dots, |R_{ij}|$, $i, j \in 1, 110$. Each row of constructed FC features is used as a node feature, and all the nodes are combined together to obtain the set of node features $\mathbf{h} = \vec{h}_1, \vec{h}_2, \dots, \vec{h}_N$, $\vec{h}_i \in \mathbb{R}^F$, where F is the node feature dimension. Let the nodal feature graph constructed for each subject be $\mathbf{G} = \mathbf{h}, \mathbf{R}$.

2) Graph attention layers and attention mechanisms

The graph attention layer (GAL) proposed by Veličković *et al.* [15] is used for learning node representations. We set the number Z of GAL to 2. The input to the GAL is the node features $\mathbf{h} = \vec{h}_1, \vec{h}_2, \dots, \vec{h}_N$, $\vec{h}_i \in \mathbb{R}^F$ and the output is a new set of node features $\mathbf{h}' = \vec{h}'_1, \vec{h}'_2, \dots, \vec{h}'_N$, $\vec{h}'_i \in \mathbb{R}^{F'}$. A weight matrix $\mathbf{W} \in \mathbb{R}^{F' \times F}$ is trained for all nodes. To calculate the node representation, the one-hop neighborhood nodes of the node are aggregated for each node by using self-attentive mechanism.

The attention coefficient is defined as:

$$c_{ij} = a(\mathbf{W}\vec{h}_i, \mathbf{W}\vec{h}_j) \quad (3)$$

where $a: \mathbb{R}^{F'} \times \mathbb{R}^{F'} \rightarrow \mathbb{R}$ is a shared attention mechanism that includes both self-attention and neighborhood attention, and the c_{ij} indicates the importance of node j to node i .

Softmax is introduced to regularize all neighboring nodes $j \in N_i$ of i , that is:

$$m_{ij} = \text{softmax } c_{ij} = \frac{\exp c_{ij}}{\sum_{k \in N_i} \exp c_{ik}} \quad (4)$$

The attention mechanism a is a single-layer feedforward neural network, $\vec{a} \in \mathbb{R}^{2F'}$ is the weight matrix which connected the layers in the neural network to each other, and a LeakyReLU is also added to the output layer. To sum up, the attention cross correlation coefficient can be obtained by:

$$m_{ij} = \text{softmax } \text{LeakyReLU } c_{ij} = \frac{\exp \text{LeakyReLU } \vec{a}^T [\mathbf{W}\vec{h}_i \parallel \mathbf{W}\vec{h}_j]}{\sum_{k \in N_i} \exp \text{LeakyReLU } \vec{a}^T [\mathbf{W}\vec{h}_i \parallel \mathbf{W}\vec{h}_k]} \quad (5)$$

where T represents matrix transposition and \parallel represents joining the left and right matrices together.

The attention coefficients between the different nodes after

regularization are obtained by the above operation and could be used to predict the output features of each node as shown in (6).

$$\vec{h}'_i = \sigma \left(\sum_{j \in N_i} m_{ij} \mathbf{W} \vec{h}_j \right) \quad (6)$$

where σ is the non-linear activation function, and j traversed in $j \in N_i$ represents all nodes adjacent to i .

3) Multi-head attention

We use an attention mechanism constructed by a multi-head attention extension. The features learned by multiple attention heads can describe signals from different sides. Specifically, K independent self-attention mechanisms can be defined as (7), and then we connect the node feature representations obtained by each attention to establish the final node representation, which can be calculated as follows:

$$\vec{h}'_i = \parallel_{k=1}^K \sigma \left(\sum_{j \in N_i} m_{ij}^k \mathbf{W}^k \vec{h}_j \right) \quad (7)$$

where K denotes the number of the attention heads, $K=3$. m_{ij}^k is the normalized attention coefficient calculated from the k -th attention head. \mathbf{W}^k denotes the weight matrix of the input linear transformation under the k -th attention head with the size of $\frac{F'}{K} \times F$.

Since the intermediate layer is the node feature representation obtained by each attention connected with an output dimension of $K F'$. For the final GAL performing multiple attentions, K -averaging is used in the final layer instead of the connection operation to make the final output is the same as the initial input dimension and delay the application of the final non-linear function, the node representation in the final layer is:

$$\vec{h}'_i = \sigma \left(\frac{1}{K} \sum_{k=1}^K \sum_{j \in N_i} m_{ij}^k \mathbf{W}^k \vec{h}_j \right) \quad (8)$$

The multi-head attention of the node \vec{h}'_i on its neighborhood is updated with the target node based on the calculated weights.

4) Classification

The node features are transformed into node information through a two-layer full connection layer. In first full connection layer, the \vec{h}'_i is mapped to the node information of each node I_i by the sigmoid function, which is:

$$I_i = \text{sigmoid}(\mathbf{W}' \vec{h}'_i) \quad (9)$$

where $\mathbf{W}' \in 1 \times F'$ is a shared weighted vector.

In second full connection layer, a weight is assigned to each node's information to be used in calculating each node's contribution to the final predicted outcome, and the weight is calculated as:

$$\mathbf{E} = \text{softmax } \mathbf{W}^E \mathbf{I} \quad (10)$$

where $\mathbf{W}^E \in N \times N$, $\mathbf{I} = I_1, I_2, \dots, I_N$, and finally the weights \mathbf{E} are linearly weighted sum with the nodes \mathbf{I} to obtain the predictions of the NF-GAT model, that is:

$$p = \sum_{i=1}^N E_i I_i \quad (11)$$

III. RESULTS

A. Model training and algorithm evaluation indicators

The NF-GAT model is based on the Python language and implemented by using the TensorFlow framework. A 10-fold cross validation is used to evaluate the model's performance. The model training details are shown in Table II. The loss function is a cross-entropy loss function, which is defined as

$$L = -[y \log \hat{y} + 1 - y \log 1 - \hat{y}] \quad (12)$$

TABLE II
MODEL TRAINING DETAILS

Name	Parameter
Operating system	Ubuntu 18.4
RAM	32G
CPU	Intel(R) Xeon(R) CPU I7
GPU	NVIDIA 2080Ti
Optimizer	Adam
Learning Rate	0.00005
Dropout	0.1
Batch size	10
Maximum training epoch	1000
Early stop mechanism	30

TABLE III
CLASSIFICATION RESULTS OF DIFFERENT ALGORITHMS ON THE ABIDE I DATASET

Categories	Methods	Atlas	Accuracy	Sensitivity	Specificity	F1	AUC
Traditional methods	SVM	HO	65.44%	58.12%	72.15%	61.75%	65.13%
	RF	HO	66.02%	57.89%	73.47%	62.05%	65.68%
	GB	HO	62.68%	58.86%	66.20%	60.23%	62.53%
Non-graph deep learning methods	FCNN [17]	HO	69.81%	63.05%	75.63%	65.82%	72.62%
	PCCE+CNN [7]	HO	70.31%	71.67%	73.33%	-	73.00%
	IRHL-FC [8]	AAL	69.19%	64.79%	73.46%	-	76.00%
GCN methods	sGCN [11]	CC200	67.54%	64.73%	60.12%	-	64.11%
	DeepGCN [19]	HO	73.71%	-	-	69.68%	75.00%
	Hi-GCN [12]	AAL	67.23%	65.93%	68.43%	-	74.00%
	MVS-GCN [13]	CC200	69.89%	70.18%	63.05%	-	69.11%
GAT methods	GAT-LI [20]	HO	68.02%	74.06%	62.26%	69.31%	73.58%
	FC-HAT [21]	AAL	70.90%	70.00%	72.30%	-	-
Our method	NF-GAT	HO	74.28%	71.29%	77.05%	72.76%	81.41%

TABLE IV
RESULTS OF ABLATION EXPERIMENTS

Methods	Accuracy	Sensitivity	Specificity	F1	MCC
Flatten-GAT	71.41%	69.14%	73.52%	69.85%	42.82%
Average-GAT	71.63%	66.93%	75.91%	68.59%	44.08%
NF-GAT	74.28%	71.29%	77.05%	72.76%	48.60%

The classification results of the different algorithms are shown in Table III. The best results are shown in bold. As can be seen, the NF-GAT outperforms other state-of-the-art classification methods. Firstly, compared with the traditional classification, our method has improved significantly. Secondly, compared with FCNN, NF-GAT achieves 4.47%, 8.24%, 1.42%, 6.94% and 8.79% improvement in five evaluation metrics. NF-GAT uses the GAL to learn node features, focus on the features of neighboring nodes and can assign different weights to different nodes in a neighborhood. So NF-GAT is better than GCN methods. At the same time, our method is roughly about 4% higher than FC-HAT in terms of accuracy, which may be due to the fact that the brain graph features learned by the hypergraph method cannot distinguish well

We use *accuracy*, *sensitivity*, *specificity*, *F1 value*, area under curve (*AUC*) and matthews correlation coefficient (*MCC*) as objective evaluation metrics. The *MCC* is defined as

$$MCC = \frac{TP \times TN - FP \times FN}{\sqrt{(TP + FP) \times (TP + FN) \times (TN + FP) \times (TN + FN)}} \quad (13)$$

where *TP* is the true positive rate, *FP* is the false positive rate, *TN* is the true negative rate, *FN* is the false negative rate. The *MCC* is essentially a correlation coefficient between the actual category and the predicted binary classification, which returns a value between -1 and +1. +1 indicates a perfect prediction, 0 indicates a random prediction, and -1 indicates that the predicted outcome is the opposite of the actual.

B. Comparison with other algorithms

To verify the effectiveness of the proposed model, we compare the NF-GAT with several other state-of-the-art ASD classification models.

The input of the traditional method is to remove the lower triangular and diagonal parts of the FCM. The remain part of the FCM is flatten into a one-dimensional vector as the classification features, whose dimension size is $\lfloor N \times (N - 1) / 2 \rfloor$.

between ASD and TD. In summary, the NF-GAT outperforms other classification methods in ASD classification.

C. Ablation study

To demonstrate the validity of the proposed model framework, an ablation study is conducted. 1) We splice the learned node feature vectors together and spread them into a one dimensional vector as the input of subsequent network for classification, and name the model Flatten-GAT. 2) We average the node information to instead of weighted summation. Equation (11) changes as (14). The model is named Average-GAT. The comparison results are shown in Table IV.

$$p = \frac{\sum_{i=1}^N I_i}{N} \quad (14)$$

In Table IV, our model achieves the best overall performance. The poor performance of the Flatten-GAT may be due to the loss of node information in the process of spreading the learned node feature vectors into a one-dimensional vector. The objective metrics of the Average-GAT are not as good as the NF-GAT due to averaging the information of each node, ignoring the different contributions of different nodes to the classification.

IV. DISCUSSION

It can be seen from Table III that different classification methods use different brain atlases. In order to test whether the results observed above depend on the choice of brain atlas, the NF-GAT is evaluated on six brain atlases other than the HO atlas, which are the Anatomical Automatic Labeling (AAL) atlas [22], the Cambion Craddock 200 (CC200) atlas [23], the Cameron Craddock 400 (CC400) atlas [24], Talariach and Tournoux (TT) atlas [25], Eikhoff-Zilles (EZ) atlas [26], and Dosenbach 160 atlas [27]. The information of these seven brain atlas is shown in Table V.

TABLE V
DIFFERENT BRAIN ATLASES AND THEIR NUMBER OF ROIS

Atlas	Number of ROIS
HO	110
AAL	116
CC200	200
CC400	392
TT	97
EZ	116
Dosenbach160	161

The classification performance on the above atlases is shown in Fig. 2. The NF-GAT shows the best performance on all the metrics of the HO atlas, especially compared with the Dosenbach160 atlas, the accuracy is improved by about 13.3%. This suggests that the HO atlas contains more features for classification than the other brain atlases. Therefore, all other experiments in this paper are conducted on the HO atlas.

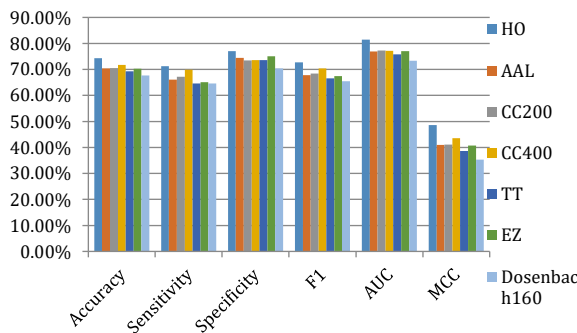


Fig. 2. Results of NF-GAT on seven brain atlases

Furthermore, we compared with Flatten-GAT and Average-GAT on several brain atlases. The results are shown in Supplementary Materials section. The classification result is related to each node, so we use BrainNet Viewer [28] shown the contribution of each node to the classification, the detailed analysis is included in the Supplementary Materials section.

V. CONCLUSION

A deep learning model, NF-GAT, is constructed, which uses rs-fMRI data to define node features and graph attention network to recognize ASD. A graph containing node features and connected edges between nodes is constructed for each subject, the node features are learned through the GAL. The node features are subjected to a function graph and the weighted sum of the node features is ultimately used to predict the probability of ASD. The results show that our model outperforms other models. Because the phenotypic information of the subjects also affects the classification, the work of this method is not enough. In addition, ASD classification studies should consider the effects of different atlases in future.

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