

Energy Buffer-Aided Wireless-Powered Relaying System for Self-Sustainable Implant WBAN

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ABSTRACT Wireless body area networks (WBANs) can provide continuous monitoring of human biological signals. Due to the limited energy of the sensors, wireless-powered system has been adopted to prolong network lifetime for implant WBANs. In this paper, we propose an energy buffer-aided wireless-powered relaying system for self-sustainable implant WBAN. The proposed system is composed of an off-body access point (AP) and many users, where an implant device is placed in body while a dual-mode wearable device with an energy buffer is attached on body for each user. In the downlink, the dual-mode wearable device simultaneously harvests energy that is stored in the energy buffer from a radio-frequency signal broadcasted by the AP and provides energy supply via wireless energy transfer to the implant device. In the uplink, the implant device uses harvested energy to transmit its collected data to the wearable device. Then the wearable device adopts the stored energy to decode and forward the data to the AP in an orthogonal multiple access way. We investigate two transmission policies for the wearable device, namely best-effort policy (BEP) and on-off policy (OOP). We derive the limiting distribution of the energy for both the BEP and OOP. Furthermore, the outage probability and average throughput of the proposed system with both the BEP and OOP are analyzed. Simulation results are presented to validate the analytical expressions and provide some useful insights.

INDEX TERMS Implant wireless body area network, best-effort policy, on-off policy, energy buffer, relaying system.

I. INTRODUCTION

WIRELESS body area networks (WBANs) that comprise low-power devices in, on, or around the human

body are designed and developed to monitor physiological signals for a variety of healthcare applications in rehabilitation, sports, military and defense [2]. In particular, the

implant device for implant WBAN is small in size and its battery has a limited capacity. Due to the limited capacity, scarce energy in the implant WBAN hinders its development [3]. Moreover, the implant device is usually involved with an invasive surgery for the implant WBAN [4]. Hence, it requires stringent-miniaturisation, reliability, low-power consumption, and long lifetime. The issues of the reliable data transmission and energy supply for implanted WBAN have become a research focus.

To realize high-reliability data transmission and save the energy of the implant device, relaying technologies have been introduced into the implant WBAN [5], [6], [7], [8], [9]. More specifically, the performance of relaying implant WBAN has been evaluated in terms of the bit error rate (BER) and outage probability [5]. In [6], a distributed beamforming scheme for the energy efficiency optimization has been proposed in ultra-wideband based relaying implant WBAN. In [7], a distributed reception method for the non-coherent system in the implant WBAN has been designed. However, the performance of the relaying implant WBAN is limited by the in-body link. To address this drawback, a data buffer-aided relaying framework has been proposed for implant WBAN [8]. In [9], two link-selection protocols for a data buffer-aided relaying implant WBAN has been designed and analyzed in terms of BER and average delay. Although the relaying implant WBAN can achieve the reliability and save the energy of the implant device, the energy from the battery attached to the implant device could be exhausted. Therefore the energy supply of implanted devices has received increasing attention.

To provide continuous energy self-sustaining, energy-harvesting has emerged as a promising technology to supply the implant device with permanent and sufficient power [10].¹ It can eliminate the need for bulky batteries or drastically reduce the size of their rechargeable batteries [12], which can further bring implant miniaturization to millimeter scales [13]. This method is to make the implant device energy self-sustaining by scavenging the energy from a variety of sources available in the ambient environment or the body itself [14]. However, opportunistic energy harvesting from the human body such as biochemical [15] and biomechanical [16] energy or renewable energy sources such as solar [17] and heat energy [18] is in general intermittent and uncontrollable. In contrast, wireless power transfer (WPT) system is partially controllable and can provide a perpetual energy source and continuous operation of the low-power devices [19], [20], [21], [22]. Near-field based WPT systems have been adopted to charge and communicate with the biomedical implant devices [23], [24]. However, the distance between the power supply and the implant device cannot exceed few centimeters. Radio frequency (RF)-based WPT

system can extend the distance between the power supply and the implant device, which can achieve a few meters [11]. In [11], RF-based WPT system for the implant device has been developed. In [25], the electromagnetic compatibility of RF-based WPT system for the wearable and implant devices has been investigated. Recently, the performance of WPT system for the implant WBAN has been investigated in [26]. Based on above works, it is interesting to combine relaying with WPT systems in WBAN.

To integrate the advantages of relaying and WPT systems, relaying WPT system has been applied into the WBAN [27], [28], [29], [30], [31]. More specifically, in [27], spectral efficiency of the relaying WPT-based WBAN system has been studied over a block fading channel. In [28], an optimal strategy for the relaying WPT-based WBAN system has been proposed to achieve the maximum throughput. In [29], a relay selection protocol for the relaying WPT-based WBAN system with data buffer has been designed. In [30], a cooperative communication framework for the WPT-based WBAN system with full duplex has been constructed and its throughput maximization problem has been investigated under the limited delay. Recently, a dynamic weights algorithm for the relaying WPT-based system has been designed in [31]. In such system, the relay and sensors collect energy from the AP and use the harvested energy to transmit information to the AP by using time division multiple access. However, in these works [27], [28], [29], [30], [31], all of them utilize relaying and WPT in WBAN, but energy harvesting nodes of these systems use a harvest-use (HU) architecture, which does not buffer the energy for use in future time slots and limits system performance. Moreover, they do not manage the energy. To solve this problem, an energy buffer can be equipped at the energy-harvesting nodes, which can use the harvest-store-use (HSU) architecture [32] and the energy is managed. Recently, two online simple policies, i.e., best-effort policy (BEP) and on-off policy (OOP), have been proposed for the energy buffer aided point-to-point WPT system [33]. The proposed system in this paper adds relaying to the energy buffer-aided point-to-point WPT system, and the BEP and OOP are re-modeled and derived. In such system, a discrete-time continuous-state Markov chain model is used to model the energy buffer accurately. The performance of a two-hop network with energy buffer-aided relay has been analyzed in [34], while an incremental relay has been adopted to improve the spectral efficiency in [35]. In [36], [37], the performance of a two-hop network with energy buffer-aided source has been analyzed. Hence, introducing energy buffer at the relay or/and the source can significantly improve the performance of the wireless-powered relaying systems. However, in these works [34], [35], [36], [37], which manage the energy in the energy buffer, the energy is collected from the environment. The source of energy in the environment is unstable and random. To address this problem, the proposed system in this paper obtains the energy from the RF signals broadcasted by the AP.

¹Charging implanted devices is a big challenge in practical application scenarios. The emergence of in-vivo networking (IVN) can help to solve this issue. IVN can integrate coherently-incoherent beamforming into a complete system that optimally provides power and communicates with deep-tissue biosensors and bioactuators [11].

With the above motivation, in this paper, we propose an energy buffer-aided wireless-powered relaying system for self-sustainable implant WBAN, which includes an off-body access point (AP) and one group of users. For each user, an implant device and a dual-mode wearable device are equipped in and on human body, respectively.² Because the implant device is generally implanted in the tissue of the human, it requires miniaturization and free battery [11], [41]. To ensure the reliable power supply and safety, the energy of the implant device is provided via the wearable device due to the uncontrollable AP.³ Moreover, the wearable device on the human body can attach to the battery to store the energy from the AP. Due to these requirements, the implant device and the wearable device adopt HU and HSU architectures, respectively.

The main results and contributions of this paper are summarized as follows.

- 1) An energy buffer-aided wireless-powered relaying system for implant WBAN is proposed. The proposed system not only can provide reliable energy supply for the implant device that is not dependent on the AP and transmit the collected data of the implant device without any external power supply, but also can ensure the safety for the human health.
- 2) In the proposed system, the dual-mode wearable device adopts BEP and OOP to manage the energy in the energy buffer. The limiting distributions of the energy in the energy buffer for both the BEP and OOP are derived by using a continuous state space Markov chain. Furthermore, the outage probability and average throughput of the proposed system with the BEP and OOP are analyzed.
- 3) Simulations are conducted to verify the accuracy of the theoretical analysis and demonstrate that both the BEP and OOP possess better performance compared with the existing battery-less relaying system. Furthermore, some useful insights are given to show the design rules for the implant WBAN.

The remainder of this paper is organized as follows. In Section II, we show the system model of the proposed system. In Section III, we derive the limiting distribution of the energy buffer. We analyze the performance of the proposed system in Section IV. The results and discussion are presented in Section V. Section VI concludes the paper.

²In WBAN standard [5], [38], [39], [40], the implant device works at the Medical Implant Communication Service (MICS) frequency band (402–405 MHz), while the wearable device works at the Industrial, Scientific and Medical (ISM) frequency band (2360–2400 MHz). Hence, the wearable device is designed in dual-mode.

³In fact, the battery of the wearable device can be easily replaced or can be recharged. When human body is not within the scope of the AP, the wearable device can keep providing the energy for the implant device. In addition, to avoid electromagnetic emissions that could be harmful for the human health, the transmitted power of the relay should be below the specific absorption rate (SAR) limit [24]. However, the existing implant WBAN systems, for example [11], [26], mainly consider the harvested energy from the uncontrollable AP.

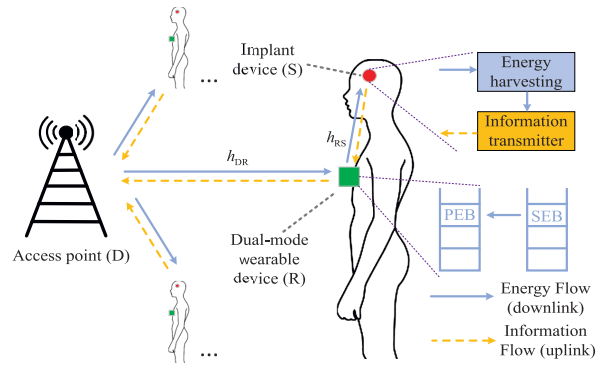


FIGURE 1. An energy buffer-aided wireless-powered relaying system for implant WBAN.

Notations: Bold lowercase letters denote vectors (e.g., \mathbf{a}), while bold capital letters represent matrices (e.g., \mathbf{A}). $\mathbb{E}(x)$ is the expectation of x , $\Re\{x\}$ denotes the real part of x , and $j = \sqrt{-1}$ is the imaginary unit. \mathbf{x}^T denotes the transpose of vector \mathbf{x} . $\mathbb{P}\{x\}$ denotes the probability of x , and $\mathbf{1}$ denotes an all-one vector.

II. SYSTEM MODEL

This section first describes the proposed system and its transmission interval, and then presents phase I, phase II, and phase III of the interval.

We consider a wireless-powered relaying system for implant WBAN,⁴ as shown in Fig. 1, which includes an off-body AP (D) and one group of uniformly distributed users. Each user has an implant device (S) and a dual-mode wearable device (R) that are placed in and on body, respectively. In the considered system, D is equipped with a power supply, whereas S and R are powered wirelessly. R is equipped with an energy buffer (e.g., a rechargeable battery or a large super-capacitor) that can store and release energy. It should be noted that because the batteries cannot charge and discharge at the same time, the harvested energy is stored in a secondary energy buffer (SEB), and the energy is drawn for the transmission from a primary energy buffer (PEB) [34]. In the downlink, R uses HSU architecture to harvest energy that will be stored in the energy buffer from a RF signal broadcasted by D. Moreover, because S is often implanted in the tissue of the human, it requires miniaturization and free battery. To ensure the reliable power supply and the safety, R provides energy supply via wireless energy transfer to S, which adopts the HU architecture (e.g., the super-capacitors based architectures [45]). Moreover, in the uplink, S transmits the collected information by using the harvested energy to R. Noted that, in this phase, the interference between users generally cannot happen due to the deep fading. In addition, R can adopt the stored energy to decode and forward the data from the users to the AP simultaneously in an orthogonal multiple access (OMA) way.

⁴In fact, the proposed system can be used for wireless deep brain stimulation (DBS), pacemaker, spinal cord stimulators, etc. [42], [43], [44]. In addition, implanted devices that are swallowed or injected into the body can be used to decode brain circuits, deliver drugs, or monitor vital signs within the body [11].

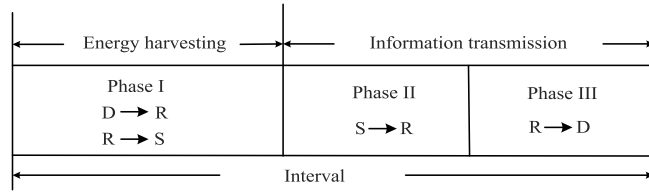


FIGURE 2. Wireless power transfer and information transmission at each interval.

Two OMA methods, i.e., frequency division multiple access (FDMA) or time division multiple access (TDMA), can be adopted for multiple WBANs to eliminate the interference. In this sense, we only consider an AP and a user in the following.

The wireless power transfer and information transmission at each interval is shown in Fig. 2. Let $B(i)$ denote the energy level in the energy buffer at the i -th interval, P_{RS} denote the transmit power from R to S, and M denote a constant power that is used for information transmission from R to D. At R, two different policies, i.e., BEP and OOP, are considered. Considering the $(i + 1)$ -th interval, the basic principle is described as follows. In phase I, D sends the RF signal to R, and R harvests the energy that will be stored in the energy buffer. At this time, the energy level in the energy buffer is $B(i + 1)$. In this phase, for the BEP, when $B(i + 1) > P_{RS}$, R transmits RF signal to S and S harvests the energy, otherwise, R remains silent and waits for the next interval. For the OOP, when $B(i + 1) \geq M + P_{RS}$, R transmits RF signal to S and S harvests the energy, otherwise, R remains silent and waits for the next interval. In phase II, S uses the harvested energy to transmit its collected data to R. In phase III, R uses the stored energy to decode and forward the data to D. In this phase, for the BEP, if the energy in the buffer is enough, R transmits the information to D with a constant power M , otherwise, R transmits with a lower power. For the OOP, R always transmits the information to D with a constant power M . The detail information of the signal model is given as follows.

In phase I, D transmits RF signal to R and R transmits RF signal to S. The received signal at R can be given by

$$y_{DR} = \sqrt{\ell P_D} h_{DR} s_1 + n_R, \quad (1)$$

where P_D is the transmit power at D, h_{DR} is the Nakagami- m fading channel from D to R,⁵ s_1 is the energy-carrying signal with zero mean and unit power, $\ell = \frac{1}{(d_{RD})^\alpha}$ denotes the path loss factor between D and R, d_{RD} is the distance between D and R, α is the path loss exponent, and n_R is complex additive Gaussian white noise (AWGN) with zero mean and variance $N_{0,R}$. The harvested energy in the i -th interval is given by $X(i) = \eta \ell P_D |h_{DR}|^2$, where η is the energy-harvesting efficiency and $|h_{DR}|^2$ follows Gamma distribution with an integer shape parameter m and the scale parameter $\Omega_{DR} = \mathbb{E}(|h_{DR}|^2)$. In addition, the harvested energy $X(i)$ is

⁵Generally, the channel gain from D to R can be modeled by the log-normal and Nakagami- m distributions [5], [46]. In fact, Nakagami- m distribution can be used to represent the log-normal distribution in an accurate manner [47], [48], [49].

TABLE 1. Parameters for path loss models for different tissues.

Implant body	$P_L(d_0)$	n	σ_p
Deep tissue	47.14	4.26	7.85
Near surface	49.81	4.22	6.81

an independent and identically distributed (i.i.d.) stationary and ergodic process with mean $\bar{X} = \eta \ell P_D \Omega_{DR}$.

Moreover, the received signal at S can be written as

$$y_{RS} = \sqrt{P_{RS}} h_{RS} s_1 + n_S, \quad (2)$$

where h_{RS} is the log-normal fading channel from R to S, and n_S is also complex AWGN with zero mean and variance $N_{0,S}$. The statistical path loss between S and R is expressed as

$$P_L(d) = P_L(d_0) + 10n \log_{10} \frac{d_{SR}}{d_0} + p, \quad (3)$$

where d_{SR} is the distance of SR link, p follows normal distribution with zero mean and variance σ_p^2 , $P_L(d_0)$ is the path loss at a reference distance $d_0 = 50$ mm, n is the path loss exponent, and these parameters are shown in Table 1 [5]. The harvested energy at S is given by $P_S = \eta P_{RS} |h_{RS}|^2$, where $|h_{RS}|^2$ follows log-normal distribution and it uses a linear EH model.⁶ According to [5], the probability density function (PDF) of $x = |h_{RS}|^2 = 10^{-\frac{P_L(d)}{10}}$ can be given by

$$q(x) = \frac{1}{\sqrt{2\pi\sigma_s^2} x} e^{-\frac{(\ln(x) - \ln(a))^2}{2\sigma_s^2}}, \quad (4)$$

where $\sigma_s = \frac{\sigma_p \ln(10)}{10}$ and $a = 10^{-\frac{P_L(d_0) + 10n \log_{10} \frac{d_{SR}}{d_0}}{10}}$.

In phase II, the harvested energy P_S is used to transmit the collected data s_2 from S to R. The received signal at R can be written as

$$y_{SR} = \sqrt{P_S} h_{SR} s_2 + n_R, \quad (5)$$

where $h_{SR} = h_{RS}$ due to the channel reciprocity. The SNR at R can be defined as $\gamma_{SR} = \frac{P_S |h_{SR}|^2}{N_{0,R}}$, which follows log-normal distribution.

In phase III, R first decodes the received signal y_{SR} from S, and then forwards the estimated data \hat{s}_2 to D. The received signal at D can be given by

$$y_{RD} = \sqrt{\ell P_{RD}} h_{RD} \hat{s}_2 + n_D, \quad (6)$$

where P_{RD} is the transmit power at R, $h_{RD} = h_{DR}$ due to the channel reciprocity, and n_D is also complex AWGN with zero mean and variance $N_{0,D}$. Hence, $\Omega_{RD} = \mathbb{E}(|h_{RD}|^2) = \Omega_{DR}$. The SNR at D can be defined as $\gamma_{RD} = \frac{\ell P_{RD} |h_{RD}|^2}{N_{0,D}}$, which follows Gamma distribution.

⁶In practical situations, a nonlinear EH model is usually considered [50], [51]. However, due to the increased complexity of the energy expression with nonlinear models, it becomes more difficult to calculate the effective distribution of signal-to-noise ratios (SNRs) and derive outage probability for the proposed system. To simplify the analysis, a linear EH model [52] is adopted in this paper. The above nonlinearity issues will be left as our future investigation.

According to the above principle, the update equation of the energy buffer for the BEP can be given by

$$B(i+1) = \min(B(i) + X(i), K), B(i) \leq P_{RS} \quad (7a)$$

$$B(i+1) = \min(X(i), K), P_{RS} < B(i) \leq M + P_{RS} \quad (7b)$$

$$B(i+1) = \min(B(i) - P_{RS} - M + X(i), K), B(i) > M + P_{RS}, \quad (7c)$$

while for the OOP it can be written as

$$B(i+1) = \min(B(i) + X(i), K), B(i) \leq M + P_{RS} \quad (8a)$$

$$B(i+1) = \min(B(i) - P_{RS} - M + X(i), K), B(i) > M + P_{RS}. \quad (8b)$$

where K denotes the buffer size of the energy buffer and $\min(a, b)$ returns the minimum of a and b .

III. LIMITING DISTRIBUTION OF THE ENERGY BUFFER

A. LIMITING DISTRIBUTION OF THE BEP

Let $g(x)$ on $(0, \infty)$ be the limiting PDF of the stored energy. $f(x)$ and $F(x)$ are the PDF and cumulative distribution function (CDF) of $\{X(i)\}$, respectively. Consider the buffer of size $K = l(M + P_{RS}) + \Delta$, where $l \in \mathbb{Z}^+$, \mathbb{Z}^+ denotes the positive integers and $P_{RS} \leq \Delta < M + P_{RS}$. We set $B(i+1) = x$ and $B(i) = u$, thus (7) can be written as

$$x = \min(u + X(i), K), u \leq P_{RS} \quad (9a)$$

$$x = \min(X(i), K), P_{RS} < u \leq M + P_{RS} \quad (9b)$$

$$x = \min(u - P_{RS} - M + X(i), K), u > M + P_{RS}. \quad (9c)$$

Referred to [33], using (9), $g(x)$ is computed as

$$g(x) = \begin{cases} \int_{u=0}^x f(x-u)g(u)du + f(x) \int_{u=P_{RS}}^{M+P_{RS}} g(u)du \\ + \int_{u=M+P_{RS}}^{M+P_{RS}+x} f(x-u+P_{RS}+M)g(u)du, & 0 \leq x < P_{RS} \\ \int_{u=0}^{P_{RS}} f(x-u)g(u)du + f(x) \int_{u=P_{RS}}^{M+P_{RS}} g(u)du \\ + \int_{u=M+P_{RS}}^{M+P_{RS}+x} f(x-u+P_{RS}+M)g(u)du, & P_{RS} \leq x < K - M - P_{RS} \\ \int_{u=0}^{P_{RS}} f(x-u)g(u)du + f(x) \int_{u=P_{RS}}^{M+P_{RS}} g(u)du \\ + \int_{u=M+P_{RS}}^K f(x-u+P_{RS}+M)g(u)du \\ + \pi(K)f(x-K+P_{RS}+M), & K - M - P_{RS} \leq x < K, \end{cases} \quad (10)$$

where the probability of a full buffer $\pi(K)$ is given by

$$\pi(K) = \frac{1}{1 - F(M + P_{RS})} \left[\int_{u=0}^{P_{RS}} F(K-u)g(u)du + F(K) \int_{u=P_{RS}}^{M+P_{RS}} g(u)du + \int_{u=M+P_{RS}}^K F(K-u+P_{RS}+M)g(u)du \right], \quad (11)$$

Because $X(i)$ follows Gamma distribution, its PDF and CDF are given by $f(x) = \frac{\lambda^m}{\Gamma(m)} x^{m-1} e^{-\lambda x}$, and $F(x) = e^{-\lambda x} \sum_{r=0}^{m-1} \frac{(\lambda x)^r}{r!}$, respectively, where $\lambda = \frac{m}{\bar{X}}$ and $m \in \{1, 2, \dots\}$. To find the performance at optimal M , $\delta = \frac{M+P_{RS}}{\bar{X}}$ is defined as the ratio of transmission energy threshold to \bar{X} . The complementary cumulative distribution function (CCDF) is written as $\bar{F}(x) = 1 - F(x)$. Hence, $g(x)$ can be calculated as (II), where $n = 0, \dots, l'$, $l' = \begin{cases} l-1, & \Delta = 0 \\ l, & \Delta \neq 0 \end{cases}$ $C_1(x) = x^{m-1} + \frac{1}{m} \sum_{k=0}^{m-1} \Re\{(\lambda e^{j\eta_k})^{-(m-1)} e^{\lambda x e^{j\eta_k}} \gamma(m, \lambda x e^{j\eta_k})\}$, $C_2(x, v) = x^{m+v} + \frac{1}{m} \sum_{k=0}^{m-1} \Re\{(\lambda e^{j\eta_k})^{-(m+v)} e^{\lambda x e^{j\eta_k}} \gamma(m+v+1, \lambda x e^{j\eta_k})\}$, $\eta_k = \frac{2\pi k}{m}$, and α_r can be obtained by solving $\alpha + A\alpha = \mathbf{1}$. The s -row and r -column expression for A is given by (13), as shown at the bottom of the next page. The derivation of (II) is provided in Appendix A.

B. LIMITING DISTRIBUTION OF THE OOP

We consider the buffer of size $K = l(M + P_{RS})$ with $l \in \{3, 4, \dots\}$. $f(x)$ and $F(x)$ are the same as these for BEP. Similarly, (8) can be written as

$$x = \min(u + X(i), K), u \leq M + P_{RS} \quad (15a)$$

$$x = \min(u - P_{RS} - M + X(i), K), u > M + P_{RS}. \quad (15b)$$

Using (15), $g(x)$ is computed as

$$g(x) = \begin{cases} \int_{u=M+P_{RS}}^{M+P_{RS}+x} f(x-u+P_{RS}+M)g(u)du \\ + \int_{u=0}^x f(x-u)g(u)du, & 0 \leq x < M + P_{RS} \\ \int_{u=M+P_{RS}}^{M+P_{RS}+x} f(x-u+P_{RS}+M)g(u)du \\ + \int_{u=0}^{M+P_{RS}} f(x-u)g(u)du, & M + P_{RS} \leq x < K - M - P_{RS} \\ \int_{u=0}^{M+P_{RS}} f(x-u)g(u)du \\ + \int_{u=M+P_{RS}}^K f(x-u+P_{RS}+M)g(u)du \\ + \pi(K)f(x-K+P_{RS}+M), & K - M - P_{RS} \leq x < K, \end{cases} \quad (16)$$

where $\pi(K)$ is given by

$$\pi(K) = \frac{1}{1 - F(M + P_{RS})} \left[\int_{u=0}^{M+P_{RS}} F(K-u)g(u)du + \int_{u=M+P_{RS}}^K F(K-u+P_{RS}+M)g(u)du \right]. \quad (17)$$

Referring to [33], $g(x)$ can be further calculated as (34), where $n = 0, \dots, l-2$, and $C_3(x, v) = x^{m+v} + \frac{1}{m} \sum_{k=0}^{m-1} \Re\{(\lambda e^{j\eta_k})^{-(m+v)} e^{\lambda x e^{j\eta_k}} \gamma(m+v+1, \lambda x e^{j\eta_k})\}$.

IV. PERFORMANCE ANALYSIS

In this section, the outage probability and average throughput of the proposed system are derived. The outage probability for the proposed system is derived as

$$P_{\text{out}} = \mathbb{P}\{\min(\gamma_{\text{SR}}, \gamma_{\text{RD}}) < \gamma_{\text{thr}}\}$$

$$\begin{aligned} &= 1 - \mathbb{P}\{\gamma_{\text{SR}} > \gamma_{\text{thr}}\}\mathbb{P}\{\gamma_{\text{RD}} > \gamma_{\text{thr}}\} \\ &= 1 - (1 - P_{\text{out_SR}})(1 - P_{\text{out_RD}}) \\ &= P_{\text{out_SR}} + P_{\text{out_RD}} - P_{\text{out_SR}}P_{\text{out_RD}}, \quad (18) \end{aligned}$$

where $\gamma_{\text{thr}} = 2^{R_t} - 1$ and R_t in bits per channel use (bpcu) denotes the transmission rate, without loss of generality, we

$$g(x) = \begin{cases} g_p(x) = e^{-\lambda x} \sum_{r=0}^{m-1} \frac{\alpha_r}{r} \left[\sum_{z=0}^{l-1} \lambda^m e^{-\lambda(z(M+P_{\text{RS}})+P_{\text{RS}})} \sum_{v=0}^{(z+1)m-1-r} \frac{(z(M+P_{\text{RS}})+P_{\text{RS}}-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)v(m-1)} \right. \\ \times \lambda^{(z+1)m-1-r-v} \gamma(v+1, \lambda M) C_1(x) - \sum_{z=1}^{l-1} \lambda^m e^{-\lambda(z(M+P_{\text{RS}})+P_{\text{RS}})} \sum_{v=0}^{zm-1} \frac{(z(M+P_{\text{RS}})+P_{\text{RS}}-K)^{zm-1-v}}{(zm-1-v)v(m-1)} \\ \times \lambda^{zm-1-v} \gamma(v+1, \lambda M) C_1(x) + \lambda^m e^{-\lambda(l(M+P_{\text{RS}})+P_{\text{RS}})} \sum_{v=0}^{(l+1)m-1-r} \frac{(l(M+P_{\text{RS}})+P_{\text{RS}}-K)^{(l+1)m-1-r-v}}{((l+1)m-1-r-v)v(m-1)} \\ \times \lambda^{(l+1)m-1-r-v} \gamma(v+1, \lambda(K-(l(M+P_{\text{RS}})+P_{\text{RS}}))) C_1(x) - \lambda^m e^{-\lambda(l(M+P_{\text{RS}})+P_{\text{RS}})} \\ \times \sum_{v=0}^{lm-1} \frac{(l(M+P_{\text{RS}})+P_{\text{RS}}-K)^{lm-1-v}}{(lm-1-v)v(m-1)} \lambda^{lm-1-v} \gamma(v+1, \lambda(K-(l(M+P_{\text{RS}})+P_{\text{RS}}))) C_1(x) \\ \left. + \sum_{z=0}^{l-1} \lambda^{(z+2)m-r} e^{-\lambda(z+1)(M+P_{\text{RS}})} \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{\text{RS}})-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)(m+v)} C_2(x, v) \right. \\ \left. - \sum_{z=1}^{l-1} \lambda^{(z+1)m} e^{-\lambda(z+1)(M+P_{\text{RS}})} \sum_{v=0}^{zm-1} \frac{((z+1)(M+P_{\text{RS}})-K)^{zm-1-v}}{(zm-1-v)(m+v)} C_2(x, v) \right], \quad 0 \leq x < P_{\text{RS}} \quad (12a) \\ g_n(x) = e^{-\lambda x} \sum_{r=0}^{m-1} \frac{\alpha_r}{r} \left[\sum_{z=0}^n \lambda^{(z+1)m-r} e^{-z\lambda(M+P_{\text{RS}})} \frac{(z(M+P_{\text{RS}})+x-K)^{(z+1)m-1-r}}{((z+1)m-1-r)} \right. \\ \left. - \sum_{z=1}^n \lambda^{zm} e^{-z\lambda(M+P_{\text{RS}})} \frac{(z(M+P_{\text{RS}})+x-K)^{zm-1}}{(zm-1)} \right], \quad [K-(n+1)(M+P_{\text{RS}})]^+ \leq x < K-n(M+P_{\text{RS}}), \quad (12b) \end{cases}$$

$$\begin{aligned} A_{\text{sr}} &= \frac{1}{r!} \left[\sum_{z=0}^{l-1} e^{-\lambda(z(M+P_{\text{RS}})+P_{\text{RS}})} \sum_{v=0}^{(z+1)m-1-r} \frac{(z(M+P_{\text{RS}})+P_{\text{RS}}-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!v!} \lambda^{(z+1)m-1-r-v} \gamma(v+1, \lambda M) \right. \\ &\times (\lambda^m H_1 - K^s \lambda^s - \lambda^{m+s} F_1(s)) - \sum_{z=1}^{l-1} e^{-\lambda(z(M+P_{\text{RS}})+P_{\text{RS}})} \sum_{v=0}^{zm-1} \frac{(z(M+P_{\text{RS}})+P_{\text{RS}}-K)^{zm-1-v}}{(zm-1-v)!v!} \lambda^{zm-1-v} \\ &\times \gamma(v+1, \lambda M) (\lambda^m H_1 - K^s \lambda^s - \lambda^{m+s} F_1(s)) + e^{-\lambda(l(M+P_{\text{RS}})+P_{\text{RS}})} \sum_{v=0}^{(l+1)m-1-r} \frac{(l(M+P_{\text{RS}})+P_{\text{RS}}-K)^{(l+1)m-1-r-v}}{((l+1)m-1-r-v)!v!} \\ &\times \lambda^{(l+1)m-1-r-v} \gamma(v+1, \lambda(K-(l(M+P_{\text{RS}})+P_{\text{RS}}))) (\lambda^m H_1 - K^s \lambda^s - \lambda^{m+s} F_1(s)) - e^{-\lambda(l(M+P_{\text{RS}})+P_{\text{RS}})} \\ &\times \sum_{v=0}^{lm-1} \frac{(l(M+P_{\text{RS}})+P_{\text{RS}}-K)^{lm-1-v}}{(lm-1-v)!v!} \lambda^{lm-1-v} \gamma(v+1, \lambda(K-(l(M+P_{\text{RS}})+P_{\text{RS}}))) (\lambda^m H_1 - K^s \lambda^s - \lambda^{m+s} F_1(s)) \\ &+ \sum_{z=0}^{l-1} \lambda^{(z+2)m-r} e^{-\lambda(z+1)(M+P_{\text{RS}})} \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{\text{RS}})-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!} (H_2(v) - \lambda^s F_2(v, s)) \\ &- \sum_{z=1}^{l-1} \lambda^{(z+1)m} e^{-\lambda(z+1)(M+P_{\text{RS}})} \sum_{v=0}^{zm-1} \frac{((z+1)(M+P_{\text{RS}})-K)^{zm-1-v}}{(zm-1-v)!} (H_2(v) - \lambda^s F_2(v, s)) \\ &+ \sum_{z=0}^l e^{-\lambda(z(M+P_{\text{RS}})+P_{\text{RS}})} \sum_{v=zm}^{(z+1)m-1-r} \frac{(\lambda(z(M+P_{\text{RS}})+P_{\text{RS}}-K))^v}{v!} + K^s \lambda^s \sum_{z=0}^{l-1} \lambda^{zm} e^{-\lambda(z+1)(M+P_{\text{RS}})} \\ &\times \sum_{v=0}^s \binom{s}{v} K^{-v} v! \left(\lambda^{m-r} \frac{((z+1)(M+P_{\text{RS}})-K)^{(z+1)m-r+v}}{((z+1)m-r+v)!} - \frac{((z+1)(M+P_{\text{RS}})-K)^{zm+v}}{(zm+v)!} \right) \Big]. \quad (13) \end{aligned}$$

set $R_f = R_{SR} = R_{RD}$, where R_{SR} is the transmission rate of the SR link and R_{RD} is the transmission rate of the RD link, $P_{\text{out_SR}}$ and $P_{\text{out_RD}}$ are the outage probabilities of the SR link and RD link, respectively. The average throughput of the considered system can be obtained as $T = R_f(1 - P_{\text{out}})$.

According to the CDF of the log-normal distribution, the outage probability $P_{\text{out_SR}}$ can be calculated as

$$P_{\text{out_SR}} = \mathbb{P}\{\gamma_{SR} < \gamma_{\text{thr}}\} = \frac{1}{2} + \frac{1}{2} \operatorname{erf}\left(\frac{\ln(\gamma_{\text{thr}}) - \mu}{2\sigma_s}\right), \quad (19)$$

where $\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$, $\mu = \ln\left(\frac{\eta P_{RS} a^2}{N_{0,R}}\right)$.

In the following, the derivation of $P_{\text{out_RD}}$ for both the BEP and OOP is given.

A. BEP

For the BEP, $P_{\text{out_RD}}$ can be obtained as

$$P_{\text{out_RD}} = P_M P_{\text{out}}|_{P_{RD}=M} + P_{\text{out}}|_{B(i) < P_{RS}} \\ + \int_{P_{RS}}^{M+P_{RS}} \mathbb{P}\left\{\frac{[x - P_{RS}]^+ \ell |h_{RD}|^2}{N_{0,D}} < \gamma_{\text{thr}}\right\} g(x) dx, \quad (20)$$

where $P_M = \mathbb{P}\{P_{RD} = M\}$ is defined as the probability that the RD link transmits with power M , $P_{\text{out}}|_{P_{RD}=M}$ is the outage probability that the transmit power $P_{RD} = M$, $P_{\text{out}}|_{B(i) < P_{RS}}$ is the probability that the stored energy at R is less than P_{RS} .

1) DERIVATION OF P_M

P_M is calculated as

$$P_M = \int_0^K g(x) dx + \pi(K) \\ = \sum_{r=0}^{M+P_{RS}} \frac{\alpha_r}{r!} \sum_{z=0}^{l-1} e^{-\lambda(z+1)(M+P_{RS})} \\ \times \sum_{v=z}^{(z+1)m-1-r} \frac{(\lambda((z+1)(M+P_{RS}) - K))^v}{v!}. \quad (21)$$

2) DERIVATION OF $P_{\text{out}}|_{P_{RD}=M}$

$P_{\text{out}}|_{P_{RD}=M}$ can be computed as

$$P_{\text{out}}|_{P_{RD}=M} = \mathbb{P}\left\{\frac{\ell M |h_{RD}|^2}{N_{0,D}} < \gamma_{\text{thr}}\right\} \\ = \mathbb{P}\left\{|h_{RD}|^2 < \frac{\gamma_{\text{thr}} N_{0,D}}{\ell M}\right\} \\ = \frac{\gamma\left(m, \frac{E}{M}\right)}{\Gamma(m)}, \quad (22)$$

where $E = \frac{m \gamma_{\text{thr}} N_{0,D}}{\ell \Omega_{RD}}$ and $\gamma(m, x) = (m-1)!(1 - e^{-x} \sum_{n=0}^{m-1} \frac{x^n}{n!})$.

3) CLOSED FORM OF THE INTEGRAL IN (20)

Since the transmission is also allowed when the stored energy is more than P_{RS} but less than $M + P_{RS}$, it is necessary to solve the last term in (20). It can be calculated as

$$\int_{P_{RS}}^{M+P_{RS}} \mathbb{P}\left\{\frac{[x - P_{RS}]^+ \ell |h_{RD}|^2}{N_{0,D}} < \gamma_{\text{thr}}\right\} g(x) dx \\ = \int_{P_{RS}}^{M+P_{RS}} \frac{\gamma\left(m, \frac{E}{x - P_{RS}}\right)}{\Gamma(m)} g(x) dx \\ = \int_{P_{RS}}^{M+P_{RS}} g(x) dx - \int_{P_{RS}}^{M+P_{RS}} e^{-\frac{E}{x - P_{RS}}} \sum_{v=0}^{m-1} \frac{\left(\frac{E}{x - P_{RS}}\right)^v}{v!} g(x) dx \\ = 1 - P_M - P_{\text{out}}|_{B(i) < P_{RS}} \\ - \underbrace{\sum_{v=0}^{m-1} \frac{E^v}{v!} \int_{P_{RS}}^{M+P_{RS}} \frac{e^{-\frac{E}{x - P_{RS}}}}{(x - P_{RS})^v} g(x) dx}_{I_t}. \quad (23)$$

In (23), I_t can be obtained as

$$I_t = \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \left[\sum_{z=0}^{l'} \lambda^{(z+1)m-r} e^{-\lambda(z(M+P_{RS})+P_{RS})} D^{(z+1)m-r-v} \right. \\ \times N\left(v, \frac{E}{D}, \lambda D, \frac{K - (z(M+P_{RS}) + P_{RS})}{D}, (z+1)m - r - 1\right) \\ \left. - \sum_{z=1}^{l'} \lambda^{z m} e^{-\lambda(z(M+P_{RS})+P_{RS})} D^{z m - v} \right]$$

$$g(x) = \begin{cases} \left[\begin{aligned} g_{l-1}(x) &= e^{-\lambda x} \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \left[\sum_{z=0}^{l-2} \lambda^{(z+2)m-r} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{RS}) - K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)(m+v)} C_3(x, v) \right. \\ &\quad \left. - \sum_{z=1}^{l-2} \lambda^{(z+1)m} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{z m - 1} \frac{((z+1)(M+P_{RS}) - K)^{z m - 1 - v}}{(z m - 1 - v)(m+v)} C_3(x, v) \right], \quad 0 \leq x < M + P_{RS} \end{aligned} \right] \quad (14a) \\ \left[\begin{aligned} g_n(x) &= e^{-\lambda x} \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \left[\sum_{z=0}^n \lambda^{(z+1)m-r} e^{-z\lambda(M+P_{RS})} \frac{(z(M+P_{RS}) + x - K)^{(z+1)m-1-r}}{((z+1)m-1-r)} - \sum_{z=1}^n \lambda^{z m} e^{-z\lambda(M+P_{RS})} \right. \\ &\quad \left. \times \frac{(z(M+P_{RS}) + x - K)^{z m - 1}}{(z m - 1)} \right], \quad [K - (n+1)(M+P_{RS})]^+ \leq x < K - n(M+P_{RS}) \end{aligned} \right] \quad (14b) \end{cases}$$

$$\times N\left(v, \frac{E}{D}, \lambda D, \frac{K - (z(M + P_{RS}) + P_{RS})}{D}, zm - 1\right), \quad (24)$$

where $l' = \begin{cases} l - 1, & \Delta < P_{RS} \\ l, & \Delta > P_{RS} \end{cases}$, $D = \begin{cases} M, & z < l \\ \Delta - P_{RS}, & z = l \end{cases}$, and

$$N(v, a, b, c, d) = \int_0^1 \frac{e^{-\frac{a}{x} - bx} (x-c)^d}{x^v d!} dx.$$

Substituting (21), (22), and (23) into (20), the outage probability $P_{\text{out_RD}}$ can be obtained by

$$P_{\text{out_RD}} = P_M P_{\text{out}}|_{P_{RD}=M} + 1 - P_M - \sum_{v=0}^{m-1} \frac{E^v}{v!} I_r. \quad (25)$$

Hence, combining (19) and (26) with (18), the outage probability of the considered system for the BEP can be obtained. Also, the corresponding average throughput can be calculated.

B. OOP

The outage probability $P_{\text{out_RD}}$ for the OOP is given by

$$P_{\text{out_RD}} = P_M P_{\text{out}}|_{P_{RD}=M} + 1 - P_M, \quad (26)$$

where $P_{\text{out}}|_{P_{RD}=M}$ is the same as the BEP and

$$P_M = \int_{M+P_{RS}}^K g(x) dx + \pi(K) \\ = \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \sum_{z=0}^{l-2} e^{-\lambda(z+1)(M+P_{RS})} \\ \times \sum_{v=zm}^{(z+1)m-1-r} \frac{(\lambda((z+1)(M+P_{RS}) - K))^v}{v!}. \quad (27)$$

Substituting (27) and (22) into (26), the outage probability $P_{\text{out_RD}}$ can be obtained. Similarly, combining (19) and (26) with (18), the outage probability of the considered system for the OOP can be obtained. Also, the corresponding average throughput can be calculated.

V. RESULTS AND DISCUSSIONS

In this section, we present simulated results to validate the analytical expressions and obtain some insights. To verify the superiority of the BEP and OOP, a buffer-less policy (BLP)⁷ is adopted as a benchmark scheme [31], where R is not equipped with energy buffer. Figs. 3 and 4 illustrate the effects of distances d_{RD} and d_{SR} on the amount of harvested energy at R and S. As d_{RD} (or d_{SR}) increases, the amount of energy harvested by R (or S) decreases. In addition, as P_D (or P_{RS}) increases, the amount of energy harvested by R (or S) increases. From Fig. 3, it can be seen that when $P_D = 1$ W and $d_{RD} = 1$ m, the energy collected by R is enough for the usage of the relay. To ensure that the transmitted power of the relay is below the SAR limit, the value of P_{RS} should be not larger than 10 mW. From Fig. 4, it is observed

⁷BLP uses all the energy collected in one time slot to transmit information [33].

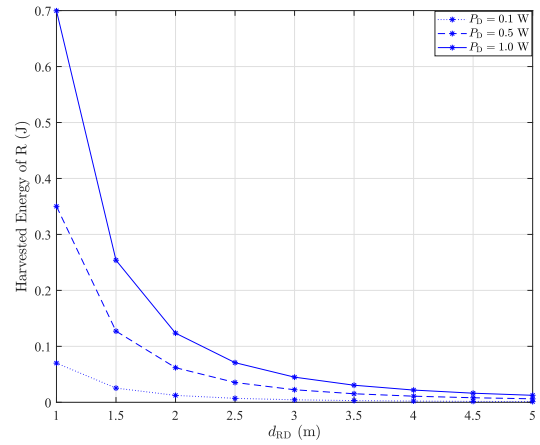


FIGURE 3. Effect of distance d_{RD} on the amount of the harvested energy at R, where $d_{SR} = 50$ mm, and $R_t = 2$ BPCU.

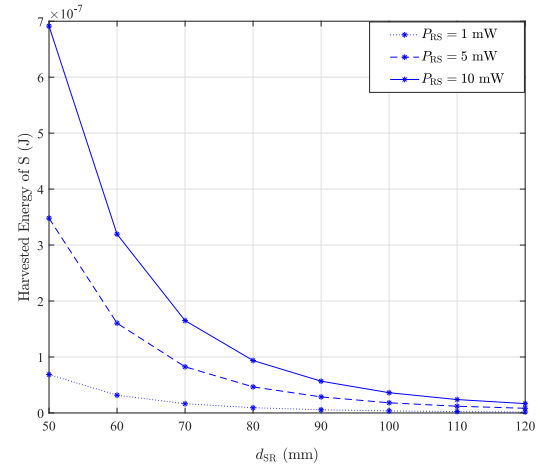


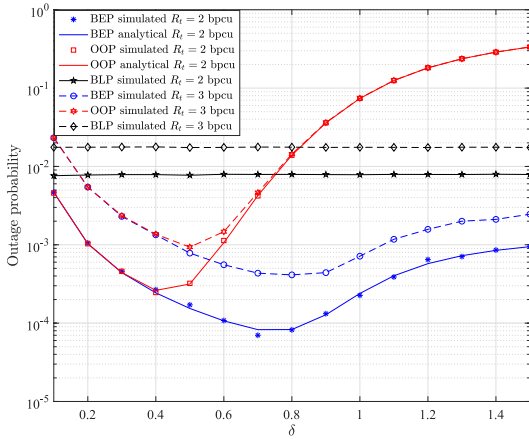
FIGURE 4. Effect of distance d_{SR} on the amount of the harvested energy at S, where $d_{RD} = 1$ m, and $R_t = 2$ BPCU.

that the energy collected by S is less than 25 μ W, which avoids electromagnetic emissions that could be harmful for the human health [40]. For safety reasons, the simulation parameters are shown in Table 2.

Fig. 5 shows the outage probability versus δ for the BEP, OOP and BLP with different values of R_t , where $m = 2$, $l = 4$, and $d_{RD} = 1$ m. First, it can be observed that the theoretical curves well match with the simulated curves, which validates the accuracy of the theoretical analysis. Moreover, there is an optimal δ that achieves the best performance for the BEP and OOP. When $\delta \leq 0.4$, the same performance of the BEP and OOP are obtained because the energy in the buffer is always beyond the threshold $M + P_{RS}$. When $\delta > 0.4$, the BEP has better performance than the OOP. The reason is that the energy in the buffer is less than $M + P_{RS}$. Thus, the outage occurs for the OOP while it does not for the BEP. Furthermore, with the increase of R_t , the performance of the BEP, OOP, and BLP are worse. In addition, it is observed that the BEP and OOP with the optimal value of δ may obtain better performance than the BLP.

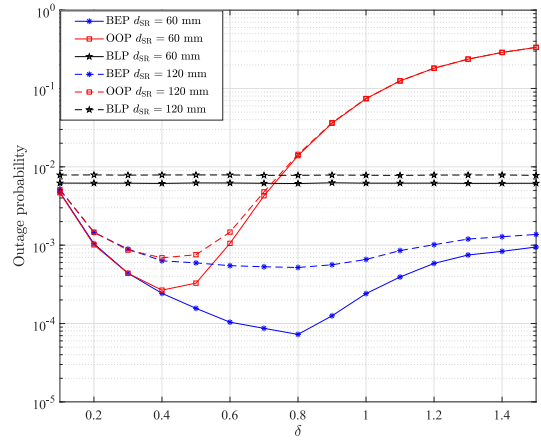
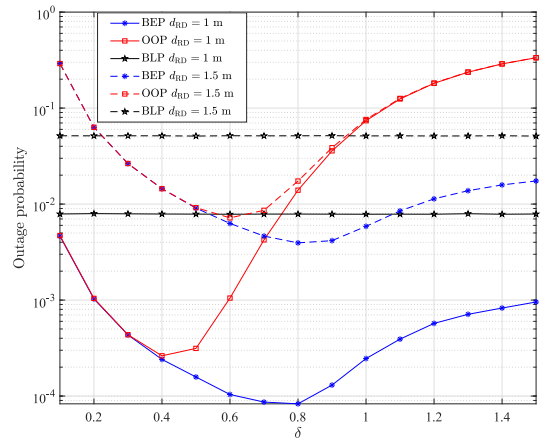
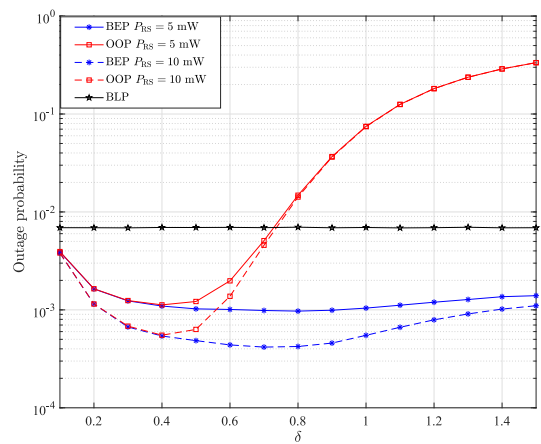
TABLE 2. Simulation parameters.

Parameter	Value
Conversion efficiency	$\eta = 0.85$
Path loss exponent	$\alpha = 2.5$
Noise power at R	$N_{0,R} = -124$ dBm
Noise power at D	$N_{0,D} = 0$ dBm
DR transmit power	$P_D = 1$ W
RS transmit power	$P_{RS} = 10$ mW
Integer shape parameter	$m = 2$


FIGURE 5. Outage probabilities versus δ for the BEP, OOP and BLP with different values of R_t , where $d_{SR} = 50$ mm, $d_{RD} = 1$ m, and $l = 4$.

Figs. 6, 7, and 8 depict the outage probability versus δ for the BEP, OOP and BLP with different values of d_{SR} , d_{RD} , and P_{RS} , respectively. First, it can be seen from Fig. 6 that with the increase of d_{SR} performance of the three policies are worse due to the serious path loss of the SR link. In particular, when the implant device is implanted very deep, the BLP obtains better performance than the BEP and OOP. The reason is that there is not enough energy in the implant device. To ensure the better performance and provide self-sustainable capability of the proposed system, it can increase the value of P_{RS} , as shown in Fig. 8. Second, it is observed from Fig. 7 that when the AP is far away from the human body, performance of three policies are worse due to serious path loss of the RD link. On the other words, when the human body is not within the scope of the AP, the two systems cannot provide the self-sustainable capability. Fortunately, the proposed system can start the backup battery of the wearable device to wirelessly power the implant device, thus it can keep working. In this sense, the proposed system is not dependent on the AP compared with the existing system with the BLP that the harvested energy is from the AP.

Fig. 9 illustrates the outage probability versus δ for the BEP and OOP with different values of l . With the increase of l (i.e., buffer size K of the energy buffer), the performance of the BEP and OOP significantly improves. For the low buffer size, the BEP has better performance than the OOP


FIGURE 6. Outage probability versus δ for the BEP, OOP and BLP with different values of d_{SR} , where $R_t = 2$ BPCU, $d_{RD} = 1$ m, and $l = 4$.

FIGURE 7. Outage probability versus δ for the BEP, OOP and BLP with different values of d_{RD} , where $d_{SR} = 50$ mm, $R_t = 2$ BPCU, and $l = 4$.

FIGURE 8. Outage probability versus δ for the BEP, OOP and BLP with different values of P_{RS} , where $d_{SR} = 120$ mm, $d_{RD} = 1$ m, $R_t = 2$ BPCU, and $l = 4$.

at the optimal value of δ . The reason is that the OOP policy is not allowed to transmit at a low power and makes the probability of buffer overflow higher. For the large buffer

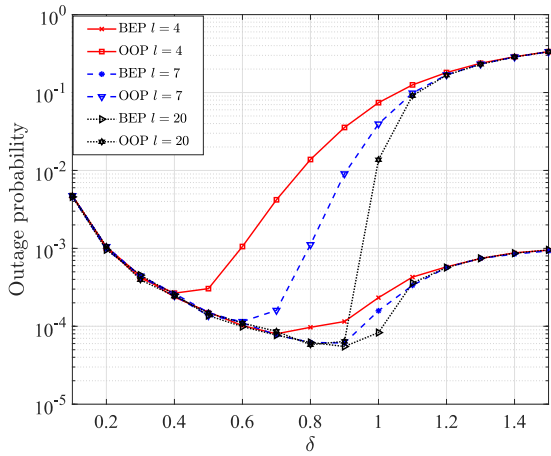


FIGURE 9. Outage probability versus δ for the BEP and OOP with different values of l , where $R_t = 2$ bpcu, $d_{SR} = 50$ mm, and $d_{RD} = 1$ m.

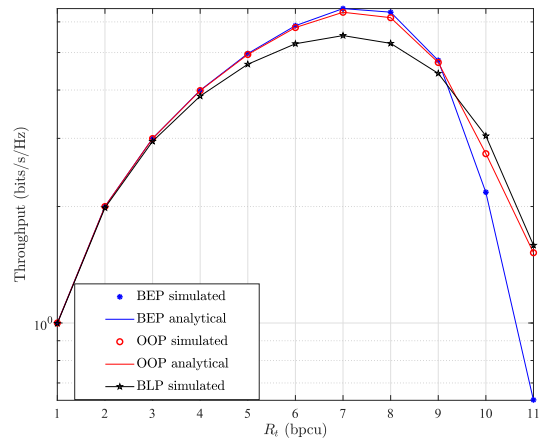


FIGURE 11. Average throughput versus R_t for the BEP, OOP and BLP, where $l = 4$, $d_{SR} = 50$ mm, and $d_{RD} = 1$ m.

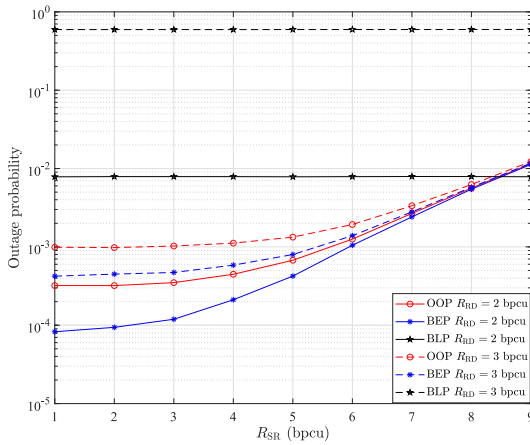


FIGURE 10. Outage probability versus R_{SR} for the BEP and OOP with different values of R_{RD} , where $\delta = 0.7$, $d_{SR} = 50$ mm, and $d_{RD} = 1$ m.

size, performance of the OOP is close to or the same as that of the BEP at the optimal value of δ .

Fig. 10 shows the outage probability versus R_{SR} for the BEP and OOP with different values of R_{RD} , where $\delta = 0.7$, $d_{SR} = 50$ mm, and $d_{RD} = 1$ m. Firstly, it can be seen that the outage performance of all three policies becomes worse as R_{SR} increases. Secondly, the increase of R_{RD} also makes the outage performance worse. This is because the bandwidth of the system cannot meet the requirement of the transmission rate as the transmission rate increases, thus making the outage performance worse. Besides, the outage performance of BEP is better than that of OOP and BLP.

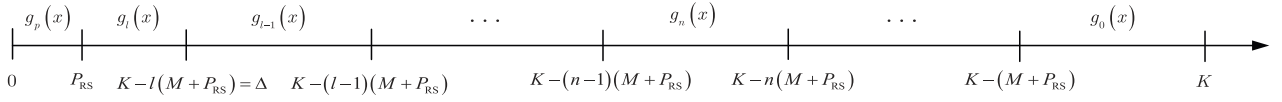
Fig. 11 depicts the average throughput versus R_t for the BEP, OOP and BLP, where $m = 2$, $l = 4$, and $d_{RD} = 1$ m. The average throughput of the BEP and OOP, with the optimal value of δ is obtained for each R_t . For low transmission rates, although the two policies have better outage performance at a small value of R_t , they have low average throughput. For medium transmission rates, the average throughput of the BEP is superior to that of the OOP and BLP. For high transmission rates, the average throughput

of the BLP is close to that of the OOP, which is superior to that of the BEP.

Remark 1: From the above discussions, it is clear that the change for each parameter causes a consequent change in the system performance. First, it can be seen from Fig. 5, 6, and 7 that the system outage performance deteriorates with the increase of R_t , d_{SR} , and d_{RD} , respectively. In order to obtain better system performance, the transmission rate R_t of the system should not be set too large, and the distance between the AP and the user should not be too far. Moreover, it can be seen from Fig. 8 and 9 that with the increase of P_{RS} and l , the system performance becomes better. An appropriate increase in P_{RS} and l can improve the system outage performance. This is because the increase of P_{RS} is harmful to the human body and its value cannot exceed 10 mW. In addition, the increase of l makes the buffer capacity increase, and the device is configured with larger buffer, which will cause a certain burden and increase the complexity of the system.

VI. CONCLUSION

In this paper, we have proposed an energy buffer aided wireless-powered relaying system for implant WBAN. The proposed system can provide the self-sustainable capability and the energy supply of the implant device is not dependent on the AP compared with the existing systems adopting BLP. Moreover, we have derived the limiting distribution of the energy for both the BEP and OOP. Furthermore, we have analyzed the outage probability and average throughput of the proposed system with the BEP and OOP. Simulation results show that both the BEP and OOP with optimal value of δ not only can provide better outage performance than that of the BLP, but also have high average throughput than that of the BLP for medium transmission rates. In addition, when the implant device is implanted very deep, the BEP and OOP can obtain better performance than the BLP by increasing the buffer size. Thanks to the aforementioned advantages, the proposed system can be considered as a promising candidate


 FIGURE 12. Segmentation of $g(x)$ for the BEP.

for self-sustainable implant WBAN applications. In future work, a data buffer can be added to the system model, where the tradeoff between the delay and BER will be further studied.

APPENDIX DERIVATION OF $G(X)$ FOR THE BEP

Substituting $f(x)$, $F(x)$ and $\bar{F}(x)$ into (10) and (11), $g(x)$ and $\pi(K)$ can be obtained and given in (23) and (29), as

shown at the bottom of the page, respectively. Let $I_1(r) = \int_{u=0}^{P_{RS}} (K-u)^r e^{\lambda u} g(u) du$, $I_2(r) = K^r \int_{u=P_{RS}}^{M+P_{RS}} g(u) du$, $I_3(r) = \int_{u=M+P_{RS}}^K (K-u+P_{RS}+M)^r e^{-\lambda(M+P_{RS}-u)} g(u) du$, $\alpha_r = \lambda^r [I_1(r) + I_2(r) + I_3(r) + (M+P_{RS})^r \pi(K) e^{-\lambda(M+P_{RS}-K)}]$, $g(x)$ can be given in (23) and $\pi(K) = e^{-\lambda K} \sum_{r=0}^{m-1} \frac{\alpha_r}{r!}$.

$$g(x) = \left[\begin{array}{l} \frac{\lambda^m e^{-\lambda x}}{(m-1)} \left[\int_{u=0}^x (x-u)^{m-1} e^{\lambda u} g(u) du + x^{m-1} \int_{u=P_{RS}}^{M+P_{RS}} g(u) du \right. \\ \left. + \int_{u=M+P_{RS}}^{M+P_{RS}+x} (x-u+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-u)} g(u) du \right], \quad 0 \leq x < P_{RS} \end{array} \right] \quad (28a)$$

$$g(x) = \left[\begin{array}{l} \frac{\lambda^m e^{-\lambda x}}{(m-1)} \left[\int_{u=0}^{P_{RS}} (x-u)^{m-1} e^{\lambda u} g(u) du + x^{m-1} \int_{u=P_{RS}}^{M+P_{RS}} g(u) du \right. \\ \left. + \int_{u=M+P_{RS}}^{M+P_{RS}+x} (x-u+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-u)} g(u) du \right], \quad P_{RS} \leq x < K - M - P_{RS} \end{array} \right] \quad (28b)$$

$$g(x) = \left[\begin{array}{l} \frac{\lambda^m e^{-\lambda x}}{(m-1)} \left[\int_{u=0}^{P_{RS}} (x-u)^{m-1} e^{\lambda u} g(u) du + x^{m-1} \int_{u=P_{RS}}^{M+P_{RS}} g(u) du + \pi(K) (x-K+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-K)} \right. \\ \left. + \int_{u=M+P_{RS}}^K (x-u+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-u)} g(u) du \right], \quad K - M - P_{RS} \leq x < K. \end{array} \right] \quad (28c)$$

$$\pi(K) = \frac{e^{-\lambda K}}{1 - e^{-\lambda(M+P_{RS})} \sum_{r=0}^{m-1} \frac{(\lambda(M+P_{RS}))^r}{r!}} \left[\sum_{r=0}^{m-1} \frac{\lambda^r}{r!} \left(\underbrace{\int_{u=0}^{P_{RS}} (K-u)^r e^{\lambda u} g(u) du}_{I_1(r)} + \underbrace{K^r \int_{u=P_{RS}}^{M+P_{RS}} g(u) du}_{I_2(r)} \right) \right. \\ \left. + \underbrace{\int_{u=M+P_{RS}}^K (K-u+P_{RS}+M)^r e^{-\lambda(M+P_{RS}-u)} g(u) du}_{I_3(r)} \right]. \quad (29)$$

As shown in Fig. 11, $g_n(x) \triangleq g(x)$, $[K - (n + 1)(M + P_{RS})]^+ \leq x < K - n(M + P_{RS})$, where $n = 0, \dots, l'$, $l' = \begin{cases} l - 1, & \Delta = 0 \\ l, & \Delta \neq 0 \end{cases}$, ($l \in \mathbb{Z}^+$). When $K - 2(M + P_{RS})x < K - M - P_{RS}$, combining (23)(b) with (23)(c), and using

$$\int_{u=b}^a (b-u)^c (u-a)^d du = -(b-a)^{c+d+1} \frac{c!d!}{(c+d+1)!}, \quad (31)$$

with $b < a$, $c, d \in \mathbb{N}$, $a = K$, $b = M + P_{RS} + x$, $c = m - 1$, and $d = m - 1 - r$, $g_1(x)$ is calculated as

$$g_1(x) = \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \left[\sum_{r=0}^{m-1} \binom{m-1}{r} \alpha_r \lambda^{-r} \left((x-K)^{m-1-r} + \lambda^m e^{-\lambda(M+P_{RS})} \frac{(m-1-r)!}{(2m-1-r)!} (M+P_{RS}+x-K)^{2m-1-r} - e^{-\lambda(M+P_{RS}-K)} \pi(K) (M+P_{RS}+x-K)^{m-1} \right] \right]. \quad (32)$$

To obtain $g_2(x)$, I_4 in (23)(b) is rewritten as

$$I_4 = \int_{u=M+P_{RS}+x}^K B(x,u) g_0(u) du + \int_{u=M+P_{RS}+x}^{K-M-P_{RS}} B(x,u) (g_1(u) - g_0(u)) du, \quad (33)$$

where $B(x, u) = (x - u + P_{RS} + M)^{m-1} e^{-\lambda(M+P_{RS}-u)}$.

By using the method of solving $g_1(x)$, when $K - 3(M + P_{RS}) \leq x < K - 2(M + P_{RS})$, one can obtain $g_2(x)$ as

$$g_2(x) = \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \left[\sum_{r=0}^{m-1} \binom{m-1}{r} \alpha_r \lambda^{-r} \left((x-K)^{m-1-r} \right. \right.$$

$$\left. \left. + \lambda^m e^{-\lambda(M+P_{RS})} \frac{(m-1-r)!}{(2m-1-r)!} (M+P_{RS}+x-K)^{2m-1-r} + \lambda^{2m} e^{-2\lambda(M+P_{RS})} \frac{(m-1-r)!}{(3m-1-r)!} (2(M+P_{RS})+x-K)^{3m-1-r} - e^{-\lambda(M+P_{RS})} e^{\lambda K} \pi(K) (M+P_{RS}+x-K)^{m-1} - \lambda^m \times e^{-2\lambda(M+P_{RS})} e^{\lambda K} \pi(K) (2(M+P_{RS})+x-K)^{2m-1} \frac{(m-1)!}{(2m-1)!} \right]. \quad (34)$$

Similarly, for $n \geq 3$, one can get

$$g_n(x) = \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \left[\sum_{z=0}^n \lambda^{zm} e^{-z\lambda(M+P_{RS})} \sum_{r=0}^{m-1} \alpha_r \lambda^{-r} \binom{m-1}{r} \times \frac{(m-1-r)!}{((z+1)m-1-r)!} (z(M+P_{RS})+x-K)^{(z+1)m-1-r} - \sum_{z=1}^n \lambda^{(z-1)m} e^{-z\lambda(M+P_{RS})} e^{\lambda K} \pi(K) \times \frac{(m-1)!}{(zm-1)!} (z(M+P_{RS})+x-K)^{zm-1} \right]. \quad (35)$$

Substituting $\pi(K)$ in (35), $g_n(x)$ can be written as

$$g_n(x) = e^{-\lambda x} \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \left[\sum_{z=0}^n \lambda^{(z+1)m-r} e^{-z\lambda(M+P_{RS})} \times \frac{(z(M+P_{RS})+x-K)^{(z+1)m-1-r}}{((z+1)m-1-r)!} - \sum_{z=1}^n \lambda^{zm} e^{-z\lambda(M+P_{RS})} \frac{(z(M+P_{RS})+x-K)^{zm-1}}{(zm-1)!} \right]. \quad (36)$$

When $0 \leq x < P_{RS}$, we set $g_p(x) = g(x)$. (37)(a) can be written as

$$g_p(x) = \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \left[\int_{u=0}^x (x-u)^{m-1} e^{\lambda u} g_p(u) du \right.$$

$$g(x) = \begin{cases} \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \left[\int_{u=0}^x (x-u)^{m-1} e^{\lambda u} g(u) du + x^{m-1} \int_{u=P_{RS}}^{M+P_{RS}} g(u) du + \int_{u=M+P_{RS}}^{M+P_{RS}+x} (x-u+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-u)} g(u) du \right], & 0 \leq x < P_{RS} \quad (30a) \\ g_0(x) - \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \left[\underbrace{\int_{u=M+P_{RS}+x}^K (x-u+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-u)} g(u) du}_{I_4} + \pi(K) (x-K+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-K)} \right], & P_{RS} \leq x < K - M - P_{RS} \quad (30b) \\ \triangleq g_0(x) = \frac{\lambda^{m-r} e^{-\lambda x}}{(m-1)!} \sum_{r=0}^{m-1} \binom{m-1}{r} (x-K)^{m-1-r} \alpha_r, & K - M - P_{RS} \leq x < K. \quad (30c) \end{cases}$$

$$\begin{aligned}
 & +x^{m-1} \left(\int_{u=P_{RS}}^{K-l(M+P_{RS})} g_l(u)du + \int_{u=K-l(M+P_{RS})}^{M+P_{RS}} g_{l-1}(u)du \right) \\
 & + \int_{u=M+P_{RS}}^{M+P_{RS}+x} (x-u+P_{RS}+M)^{m-1} e^{-\lambda(M+P_{RS}-u)} g_{l-1}(u)du \Big]. \tag{37}
 \end{aligned}$$

(37) can be rewritten as

$$g_p(x) = T(x) + I_S(x). \tag{39}$$

Let $I_S(x) = \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \int_{u=0}^x (x-u)^{m-1} e^{\lambda u} g_p(u)du$ and

Next, similar to the method for I_4 , T_{ab} can be rewritten as

$$T(x) = \frac{\lambda^m e^{-\lambda x}}{(m-1)!} \left[x^{m-1} \left(\underbrace{\int_{u=P_{RS}}^{K-l(M+P_{RS})} g_l(u)du}_{T_a} + \underbrace{\int_{u=K-l(M+P_{RS})}^{M+P_{RS}} g_{l-1}(u)du}_{T_b} \right) \right]$$

$$T_{ab} = \underbrace{\int_{u=P_{RS}}^{M+P_{RS}} g_{l-1}(u)du}_{T_a} + \underbrace{\int_{P_{RS}}^{K-l(M+P_{RS})} g_l(u) - g_{l-1}(u)du}_{T_b}. \tag{40}$$

$$\begin{aligned}
 T(x) = & e^{-\lambda x} \sum_{r=0}^{m-1} \frac{\alpha^r}{r!} \left[\sum_{z=0}^{l-1} \lambda^m e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{(z(M+P_{RS})+P_{RS}-K)^{(z+1)m-1-r-v} x^{m-1}}{((z+1)m-1-r-v)!v!(m-1)!} \lambda^{(z+1)m-1-r-v} \gamma(v+1, \lambda M) \right. \\
 & - \sum_{z=1}^{l-1} \lambda^m e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{zm-1} \frac{(z(M+P_{RS})+P_{RS}-K)^{zm-1-v} x^{m-1}}{(zm-1-v)!v!(m-1)!} \lambda^{zm-1-v} \gamma(v+1, \lambda M) \\
 & + \lambda^m e^{-\lambda(l(M+P_{RS})+P_{RS})} \sum_{v=0}^{(l+1)m-1-r} \frac{(l(M+P_{RS})+P_{RS}-K)^{(l+1)m-1-r-v} x^{m-1}}{((l+1)m-1-r-v)!v!(m-1)!} \lambda^{(l+1)m-1-r-v} \gamma(v+1, \lambda(K - (l(M+P_{RS}) + P_{RS}))) \\
 & - \lambda^m e^{-\lambda(l(M+P_{RS})+P_{RS})} \sum_{v=0}^{lm-1} \frac{(l(M+P_{RS})+P_{RS}-K)^{lm-1-v} x^{m-1}}{(lm-1-v)!v!(m-1)!} \lambda^{lm-1-v} \gamma(v+1, \lambda(K - (l(M+P_{RS}) + P_{RS}))) \\
 & + \sum_{z=0}^{l-1} \lambda^{(z+2)m-r} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{RS})-K)^{(z+1)m-1-r-v} x^{m+v}}{((z+1)m-1-r-v)!(m+v)!} \\
 & \left. - \sum_{z=1}^{l-1} \lambda^{(z+1)m} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{qm-1} \frac{((z+1)(M+P_{RS})-K)^{zm-1-v} x^{m+v}}{(zm-1-v)!(m+v)!} \right] \tag{42}
 \end{aligned}$$

$$\begin{aligned}
 d_{sr} = & \frac{\lambda^s}{r!} \left[\sum_{z=0}^{l-1} e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{(z(M+P_{RS})+P_{RS}-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!v!} \lambda^{(z+1)m-1-r-v} \gamma(v+1, \lambda M) (K^s + \lambda^m F_1(s)) \right. \\
 & - \sum_{z=1}^{l-1} e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{zm-1} \frac{(z(M+P_{RS})+P_{RS}-K)^{zm-1-v}}{(zm-1-v)!v!} \lambda^{zm-1-v} \gamma(v+1, \lambda M) (K^s + \lambda^m F_1(s)) + e^{-\lambda(l(M+P_{RS})+P_{RS})} \\
 & \times \sum_{v=0}^{(l+1)m-1-r} \frac{(l(M+P_{RS})+P_{RS}-K)^{(l+1)m-1-r-v}}{((l+1)m-1-r-v)!v!} \lambda^{(l+1)m-1-r-v} \gamma(v+1, \lambda(K - (l(M+P_{RS}) + P_{RS}))) (K^s + \lambda^m F_1(s)) \\
 & - e^{-\lambda(l(M+P_{RS})+P_{RS})} \sum_{v=0}^{lm-1} \frac{(l(M+P_{RS})+P_{RS}-K)^{lm-1-v}}{(lm-1-v)!v!} \lambda^{lm-1-v} \gamma(v+1, \lambda(K - (l(M+P_{RS}) + P_{RS}))) (K^s + \lambda^m F_1(s)) \\
 & - \sum_{z=0}^{l-1} \lambda^{z+2} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^s \binom{s}{v} K^{s-v} v! \left(\lambda^{m-r} \frac{((z+1)(M+P_{RS})-K)^{(z+1)m-r+v}}{((z+1)m-r+v)!} - \frac{((z+1)(M+P_{RS})-K)^{z+m+v}}{(z+m+v)!} \right) \\
 & + \sum_{z=0}^{l-1} \lambda^{(z+2)m-r} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{RS})-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!} F_2(v, s) \\
 & \left. - \sum_{z=1}^{l-1} \lambda^{(z+1)m} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{zm-1} \frac{((z+1)(M+P_{RS})-K)^{zm-1-v}}{(zm-1-v)!} F_2(v, s) \right], \tag{44}
 \end{aligned}$$

Substituting (36) in T_a , T_b and T_c , one can obtain

$$T_a = \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \left[\sum_{z=0}^{l-1} e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{(z(M+P_{RS})+P_{RS}-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!v!} \times \lambda^{(z+1)m-1-r-v} \gamma(v+1, \lambda M) \right] \quad (41a)$$

$$T_b = \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \left[e^{-\lambda(l(M+P_{RS})+P_{RS})} \sum_{v=0}^{(l+1)m-1-r} \frac{(l(M+P_{RS})+P_{RS}-K)^{(l+1)m-1-r-v}}{((l+1)m-1-r-v)!v!} \times \lambda^{(l+1)m-1-r-v} \gamma(v+1, \lambda(K-(l(M+P_{RS})+P_{RS}))) \right]$$

$$\begin{aligned} \in t_{u=0}^K g(u) du + \pi(K) &= \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} \left[\sum_{z=0}^{l-1} \lambda^m e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{(z(M+P_{RS})+P_{RS}-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!v!} \lambda^{(z+1)m-1-r-v} \right. \\ &\times \gamma(v+1, \lambda M) H_1 - \sum_{z=1}^{l-1} \lambda^m e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{zm-1} \frac{(z(M+P_{RS})+P_{RS}-K)^{zm-1-v}}{(zm-1-v)!v!} \lambda^{zm-1-v} \gamma(v+1, \lambda M) H_1 \\ &+ \lambda^m e^{-\lambda(l(M+P_{RS})+P_{RS})} \sum_{v=0}^{(l+1)m-1-r} \frac{(l(M+P_{RS})+P_{RS}-K)^{(l+1)m-1-r-v}}{((l+1)m-1-r-v)!v!} \lambda^{(l+1)m-1-r-v} \gamma(v+1, \lambda(K-(l(M+P_{RS})+P_{RS}))) H_1 \\ &- \lambda^m e^{-\lambda(l(M+P_{RS})+P_{RS})} \sum_{v=0}^{lm-1} \frac{(l(M+P_{RS})+P_{RS}-K)^{lm-1-v}}{(lm-1-v)!v!} \lambda^{lm-1-v} \gamma(v+1, \lambda(K-(l(M+P_{RS})+P_{RS}))) H_1 \\ &+ \sum_{z=0}^{l-1} \lambda^{(z+2)m-r} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{RS})-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!} H_2(v) \\ &- \sum_{z=1}^{l-1} \lambda^{(z+1)m} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{zm-1} \frac{((z+1)(M+P_{RS})-K)^{zm-1-v}}{(zm-1-v)!} H_2(v) \\ &\left. + \sum_{z=0}^l e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=zm}^{(z+1)m-1-r} \frac{(\lambda(z(M+P_{RS})+P_{RS}-K))^v}{v!} \right], \quad (47) \end{aligned}$$

$$\begin{aligned} b_r &= \frac{1}{r!} \left[\sum_{z=0}^{l-1} \lambda^m e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{(z(M+P_{RS})+P_{RS}-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!v!} \lambda^{(z+1)m-1-r-v} \gamma(v+1, \lambda M) H_1 \right. \\ &- \sum_{z=1}^{l-1} \lambda^m e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=0}^{zm-1} \frac{(z(M+P_{RS})+P_{RS}-K)^{zm-1-v}}{(zm-1-v)!v!} \lambda^{zm-1-v} \gamma(v+1, \lambda M) H_1 + \lambda^m e^{-\lambda(l(M+P_{RS})+P_{RS})} \\ &\times \sum_{v=0}^{(l+1)m-1-r} \frac{(l(M+P_{RS})+P_{RS}-K)^{(l+1)m-1-r-v}}{((l+1)m-1-r-v)!v!} \lambda^{(l+1)m-1-r-v} \gamma(v+1, \lambda(K-(l(M+P_{RS})+P_{RS}))) H_1 \\ &- \lambda^m e^{-\lambda(l(M+P_{RS})+P_{RS})} \sum_{v=0}^{lm-1} \frac{(l(M+P_{RS})+P_{RS}-K)^{lm-1-v}}{(lm-1-v)!v!} \lambda^{lm-1-v} \gamma(v+1, \lambda(K-(l(M+P_{RS})+P_{RS}))) H_1 \\ &+ \sum_{z=0}^{l-1} \lambda^{(z+2)m-r} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{RS})-K)^{(z+1)m-1-r-v}}{((z+1)m-1-r-v)!} H_2(v) \\ &- \sum_{z=1}^{l-1} \lambda^{(z+1)m} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{zm-1} \frac{((z+1)(M+P_{RS})-K)^{zm-1-v}}{(zm-1-v)!} H_2(v) \\ &\left. + \sum_{z=0}^l e^{-\lambda(z(M+P_{RS})+P_{RS})} \sum_{v=zm}^{(z+1)m-1-r} \frac{(\lambda(z(M+P_{RS})+P_{RS}-K))^v}{v!} \right]. \quad (53) \end{aligned}$$

$$-e^{-\lambda((M+P_{RS})+P_{RS})} \sum_{v=0}^{l-1} \frac{(l(M+P_{RS})+P_{RS}-K)^{lm-1-v}}{(lm-1-v)!v!}, \quad (41b)$$

$$T_c = \sum_{r=0}^{m-1} \frac{\alpha_r}{r!} (m-1)! \left[\sum_{z=0}^{l-1} \lambda^{(z+1)m-r} e^{-\lambda(z+1)(M+P_{RS})} \right. \\ \times \sum_{v=0}^{(z+1)m-1-r} \frac{((z+1)(M+P_{RS})-K)^{(z+1)m-1-r-v} x^{m+v}}{((z+1)m-1-r-v)!(m+v)!} \\ \left. - \sum_{z=1}^{l-1} \lambda^{zm} e^{-\lambda(z+1)(M+P_{RS})} \sum_{v=0}^{qm-1} \frac{((z+1)(M+P_{RS})-K)^{zm-1-v} x^{m+v}}{(zm-1-v)!(m+v)!} \right]. \quad (41c)$$

Substituting (41) into (38), one can get $T(x)$ as (42), as shown at the bottom of the p. 13. Then, one can obtain $g_p(x)$ as (37)(a). Next, we need to get the coefficients α_r . One defines

$$\alpha_s \triangleq \sum_{r=0}^{m-1} \alpha_r d_{sr} = \lambda^s [I_1(s) + I_2(s) + I_3(s) \\ + (M+P_{RS})^s e^{-\lambda(M+P_{RS})} \sum_{r=0}^{m-1} \frac{\alpha_r}{r!}], \quad s = 0, \dots, m-1 \quad (43)$$

$$\text{where } I_1(s) = \int_{u=0}^{P_{RS}} (K-u)^s e^{\lambda u} g(u) du, \quad I_2(s) = \\ K^s \int_{u=P_{RS}}^{M+P_{RS}} g(u) du, \quad I_3(s) = \int_{u=M+P_{RS}}^K (K-u+P_{RS}+M)^s \\ e^{-\lambda(M+P_{RS}-u)} g(u) du.$$

Then, one can get d_{sr} as (44), as shown at the bottom of the p. 13 where

$$F_1(s) = \sum_{b=0}^s \binom{s}{b} (K-P_{RS})^{s-b} \left[\frac{b! P_{RS}^{m+b}}{(m+b)!} \right. \\ \left. + \frac{1}{m} \sum_{k=0}^{m-1} \Re \left\{ e^{\lambda P_{RS} e^{jnk}} (\lambda e^{jnk})^{-(m+b)} \right. \right. \\ \left. \left. \gamma(b+1, \lambda P_{RS} e^{jnk}) \right. \right. \\ \left. \left. - \sum_{w=0}^{m-1} \frac{b! P_{RS}^{w+b+1}}{(w+b+1)!} (\lambda e^{jnk})^{w-(m-1)} \right\} \right], \quad (45)$$

$$F_2(v, s) = \sum_{b=0}^s \binom{s}{b} (K-P_{RS})^{s-b} \left[\frac{b! P_{RS}^{m+v+b+1}}{(m+v+b+1)!} \right. \\ \left. + \frac{1}{m} \sum_{k=0}^{m-1} \Re \left\{ e^{\lambda P_{RS} e^{jnk}} (\lambda e^{jnk})^{-(m+v+b+1)} \right. \right. \\ \left. \left. \gamma(b+1, \lambda P_{RS} e^{jnk}) \right. \right. \\ \left. \left. - \sum_{w=0}^{m+v} \frac{b! P_{RS}^{w+b+1}}{(w+b+1)!} (\lambda e^{jnk})^{w-(m+v)} \right\} \right]. \quad (46)$$

Using $\int_{u=0}^K g(u) du + \pi(K) = 1$, one can get (47), as shown at the bottom of the previous page,

where

$$H_1 = \lambda^{-m} \left[\frac{\gamma(m, \lambda P_{RS})}{(m-1)!} + \frac{1}{m} \sum_{k=0}^{m-1} \Re \{ \rho_{1k} \right. \\ \left. - \sum_{w=0}^{m-1} \frac{e^{jnk(w-(m-1))}}{w!} \gamma(w+1, \lambda P_{RS}) \right\}], \quad (48)$$

$$H_2(v) = \lambda^{-(m+v+1)} \left[\frac{\gamma(m+v+1, \lambda P_{RS})}{(m+v)!} + \frac{1}{m} \sum_{k=0}^{m-1} \Re \{ \rho_{2k} \right. \\ \left. - \sum_{w=0}^{m+v} \frac{e^{jnk(w-(m+v))}}{w!} \gamma(w+1, \lambda P_{RS}) \right\}], \quad (49)$$

$$\rho_{1k} = \begin{cases} \frac{1-e^{-\lambda P_{RS}(1-e^{jnk})}}{1-e^{jnk}} e^{-jnk(m-1)}, & k \neq 0 \\ \lambda P_{RS}, & k = 0 \end{cases} \quad (50)$$

$$\rho_{2k} = \begin{cases} \frac{1-e^{-\lambda P_{RS}(1-e^{jnk})}}{1-e^{jnk}} e^{-jnk(m+v)}, & k \neq 0 \\ \lambda P_{RS}, & k = 0 \end{cases} \quad (51)$$

Let

$$\int_{u=0}^K g(u) du + \pi(K) \triangleq \sum_{r=0}^{m-1} \alpha_r b_r = 1, \quad (52)$$

where b_r can be obtained by (53), as shown at the bottom of the previous page.

Combining (43) with (52), we can obtain $\alpha_s + \sum_{r=0}^{m-1} \alpha_r (b_r - d_{sr}) = 1, s = 0, \dots, m-1$, which is a non-homogeneous system of linear equations and it can be written as $\mathbf{A} + \mathbf{A}\boldsymbol{\alpha} = \mathbf{1}$. The s -row and r -column expression for \mathbf{A} can be expressed as $A_{sr} = b_r - d_{sr}$, which is detailed in (13).

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