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November 23 (Mon) Location: Noyori Conference Hall

Opening Rema	arks Conference Room 1
Chairperson:	Fumihito Arai, Nagoya University
09:00-9:20	Prof. Toshio Fukuda, Meijo University, Japan (Honorary Chair) Prof. Tatsuo Arai, Osaka University, Japan (General Co-Chairs) Prof. Fumihito Arai, Nagoya University, Japan (General Co-Chair) Prof. Jun Ota, The University of Tokyo, Japan (General Co-Chair)
Plenary Talk	Conference Room 1
Chairperson:	Fumihito Arai, Nagoya University
09:20-10:10	Plenary Talk 1 Polymer-Based Graphene Biosensors for Biomedical Analysis Prof. Tianhong Cui, Department of Mechanical Engineering, University of Minnesota, USA
10:10-10:20	Coffee Break
Chairperson:	Minoru Seki, Chiba University
10:20-11:10	Plenary Talk 2 Cellular Hydrogel Biopapers: From 3D Cell Culture To Microfluidic Assays Prof. Je Kyun Park, Department of Bio and Brain Engineering, Korea Advanced Institute of Science and Technology (KAIST), Korea
Chairperson:	Makoto Kaneko, Osaka University
11:10-12:00	Plenary Talk 3 Mechanobio-Materials Manipulating Motility and Functions of Stem Cells Prof. Satoru Kidoaki, Institute for Materials Chemistry and Engineering,

Kyushu University, Japan

12:00-13:00 *Lunch*

Poster Area(1st floor)

Poster session I

Chairperson: Masahiro Ohka, Nagoya University Seiichi Hata, Nagoya University Yasuhisa Hasegawai, Nagoya University Yasushi Mae, Osaka University

13:00-14:00

- MP-1 Research on and Education for Navigation Control of an Exploration Rover with Microwave Doppler Sensors Masahiro Isogai, Yasuhiko Nawa and Toru Iijima, Aichi University of Technology
- MP-2 The Viscosity of the Mixture of Water / 2,6-dimethylpyridine / NaBPh4 at Lamellar Phase and Disordered Phase *Hiroaki Maki, Koichiro Sadakane, Takahiro Kenmotsu, Naomichi Ito and Kenichi Yoshikawa, Doshisha University*
- MP-3 Study on Diffusion Process of Nanoparticles in a PDMS Layer using SPT Technique *Ryo Iwao, Yu Matsuda, Hiroki Yamaguchi and Tomohide Niimi, Nagoya University*
- MP-4 Vectorial Flow of Phase-separated Droplets in a Mixture of Water/Organic Solvent Generated by a Focused Laser Shuto Kimura, Takehiro Minami, Koichiro Sadakane and Takahiro Kenmotsu, Doshisha University
- MP-5 Crystal structure induced by mixture of Water/Organic/Antagonistic Salts Naomichi Ito, Koichiro Sadakane, Hiroaki Maki and Takahiro Kenmotsu, Doshisha University
- MP-6 Enhancement of Communication Between Persons and Robots Through Tri-axial Tactile Data *Yuya Oizumi, Kenji Sugiman and Masahiro Ohka, Nagoya University*
- MP-7 A Study of Optimum Stimulus Condition for Inducing Kinesthetic Illusion Yuki Kato, Koichi Akahori, Shunpei Yoshida, Masakazu Honda and Masahiro Ohka, Nagoya University
- MP-8 Design of a Positioning Device using Piezo Element and Investigation of a Simple Compensation Method *Kazuto Miyawaki, Kazuhiko Chiba and Hiromi Isobe, National Institute of Technology, Akita College*

- MP-9 Proposal of Hearing Aid System for Unilateral Deafness Patients Katsutoshi Oe, Takuya Nakano, Masahito Iwae and Kohji Kariya, Daiichi Institute of Technology
- MP-10 Adaptive Impedance Control with Variable Stiffness for Motion and Force Tracking System *Yanling Pei, Goro Obinata, YoungWoo Kim and Jaeryoung Lee, Chubu University*
- MP-11 Development of a Measurement and Real-time Display System for Kinematics and Muscle Synergy of Gait. Arito Yozu, Tetsuro Funato, Dai Owaki and Nobuhiko Haga, The University of Tokyo Hospital
- MP-12 Miniaturization of Wide-range QCR Load Sensor for Biosignal Sensing Yuichi Murozaki, Shinya Sakuma and Fumihito Arai, Nagoya University
- MP-13 Dynamics-based Virtual Holonomic Constraint for PDAC Running Taisuke Kobayashi, Tadayoshi Aoyama, Yasuhisa Hasegawa, Kosuke Sekiyama and Toshio Fukuda, Nagoya University
- MP-14 Effect of Visual Condition on Brain Activity and Motion Accuracy during Cane Usage Yuji Ohmura, Naoki Arizono, Shiro Yano and Toshiyuki Kondo, International University of Health and Welfare
- MP-15 A Shooting Robot based on the Minimum Actuator / Sensor Realization Mizuho Kawakami, Makoto Kaneko and Kouhei Ohnishi, Osaka University
- MP-16 Effect of Olfactory Stimulus on Simultaneous Learning of Conflicting Motor Tasks Daichi Misawa, Toshiyuki Kondo and Shiro Yano, Tokyo University of Agriculture and Technology
- MP-17 Thin-film Thermoelectric Generator with Ball Lens for using Near-infrared Solar Energy Yoshitaka Ito, Mizue Mizoshiri, Masashi Mikami, Tasuku Kondou, Junpei Sakurai and Seiichi Hata, Nagoya University
- MP-18 A Component-Based Framework for Molecular Robotic Development as Smart Drug System Wibowo Adi and Kosuke Sekiyama, Nagoya University
- MP-19 Combinatorial Searching System for Electrolysis Catalytic Materials Masashi Miyamoto, Akira Suzuki, Mizue Mizoshiri, Junpei Sakurai and Seiichi Hata, Nagoya University

MP-20 Fabrication of micro flexible electrode to Stimulate Peripheral Nerve for Rodent Model Masato Sano, Masahiro Nakajima, Masaru Takeuchi, Yasuhisa Hasegawa, Shigeru

Kurimoto, Tomonori Nakano, Hiroaki Shinkai and Hitoshi Hirata, Nagoya University

- MP-21 Unconstraint Measurement of Vital Information Using Near-Infrared Light Sensor Keisuke Takagi, Hisataka Maruyama and Fumihito Arai, Nagoya University
- MP-22 Development of Muscle Biopsy Needle for Extracting Fibrous Muscular Tissue Makoto Nokata and Akari Ushida, Ritsumeikan University
- 14:00-14:05 *Coffee Break*

Session MP1-1: (Organized Session) : Functional Interfaces in Micro-nanofluidics Conference Room 1

Chairperson:	Yoko Yamanishi, Shibaura Institute of Technology Shintaro Itoh, Nagoya University
14:05-14:20	Surface Interaction of Microbubbles and Applications of Hydrogen-Bubble Method for Cleaning and Separation Surface Interaction of Microbubbles and Applications of Hydrogen-Bubble Method for Cleaning and Separation
14:20-14:35	Morphology Control of Protein Microparticles Produced Using Microfluidic Droplets in a Non-equilibrium State Masumi Yamada, Kazuma Takahashi, Ayaka Hori, Sari Sugaya and Minoru Seki, Chiba University
14:35-14:50	Multiple-reagent Layer Laden High-speed Micro-bubbles in Extended Two-dimensional Microchip Yohei Hamano, Takuya Kambayashi and Yoko Yamanishi, Shibaura Institute of Technology
14:50-15:05	Reduction of Viscous Friction by Photoaligned Liquid Crystals at Interface Shintaro Itoh, Yuichi Imura, Kenji Fukuzawa and Hedong Zhang, Nagoya University
15:05-15:20	Expansion of a Linear Range of the Ion-concentration Measurement System using Microfluidic Device with ISFET Sensors Masashi Nobukuni, Akihiko Wakuda, Tsuyoshi Miura and Akira Yamada, Aichi Institute of Technology
15:20-15:35	Analysis of Dynamic Cell Movement under AC Electric Field in 3D Multi-layered Microchannel Masashi Nobukuni, Akihiko Wakuda, Tsuyoshi Miura and Akira Yamada, Aichi Institute of Technology

Session MP2-1: (Organized Session) : Robot System Control and Its Software Conference Room 2

Chairperson:	Jaeryoung Lee, Chubu University Nichoas Melo, Federal University of Rio Grande do Norte (UFRN)
14:05-14:20	Evaluating Emotional Influence in communicating with a robot Ryo Suzuki, Jaeryoung Lee, Goro Obinata, Takenori Suzuki and Kotaro Matsumoto, Chubu University
14:20-14:35	Experimental Study on Bilateral Control Method by Force and Position Fusion Takuya Uesugi, Seisyou Sakoda, Yuusuke Hirama, Woong Choi, Youichi Shigematsu and Nobuto Hirakoso, National Institute of Technology, Gunma College
14:35-14:50	Influence of Different Gait Trajectories in an Lower Limb Active Orthosis Performance Based on User Metabolic Cost and Motors Usage Nicholas de Bastos Melo, Pablo Javier Alsina, Carlos E.T. Dórea and Kassio J. Da Silva Eugenio, Federal University of Rio Grande do Norte
14:50-15:05	Interactive Educational Material for Children with ASD Jaeryoung Lee and Goro Obinata, Chubu University
15:05-15:20	Effectiveness and Service Quality of Robot Museum through Visitors Experience: A Case Study of RoboLife Museum in South Korea <i>Min-Gyu Kim, Hyewon Lee, Jaeryoung Lee, Sonya S. Kwak and</i> <i>Younghwan Joo, Korea Institute of Robot and Convergence</i>
15:20-15:35	Ortholeg 2.0 – A New Design for a Lower Limb Active Orthosis Michal Gloger, Pablo J. Alsina and Nicholas B. Melo, Technical University of Ostrava
15:35-15:45	Coffee Break

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Session MP1-2: (Organized Session) : Young Researchers in Micro-Nano Systems Conference Room 1

Chairperson:	Hisataka Maruyama, Nagoya University Yuta Nakashima, Kumamoto University
15:45-16:00	Functional Vessel Model Having Temperature Indicator for Surgical Simulator Hisataka Maruyama, Takafumi Watanabe, Takeshi Hayakawa, Tomohisa Tanaka, Taisuke Masuda and Fumihito Arai, Nagoya University
16:00-16:15	Cell Adhesion Control of Optically-Driven Microtool Using Thermo-Sensitive Gel and Laser Heating Maki Kikukawa, Takeshi Hayakawa, Hisataka Maruyama and Fumihito Arai, Nagoya University
16:15-16:30	Development and Characterization of Dielectrophoretic Probe Array for Non-invasive Massively Parallel Manipulation of Single Cells <i>Ryosaku Sakamoto, Yuya Matsuse, Moeto Nagai and Takayuki Shibata,</i> <i>Toyohashi University of Technology</i>
16:30-16:45	Measurement of Cell Mechanical Properties by Cell Compression Microdevice Tairo Yokokura, Yuta Nakashima, Yukihiro Yonemoto, Yuki Hikichi and Yoshitaka Nakanishi, Kumamoto University
16:45-17:00	Influence of Droplet Size to Cell Viability in Flash Freezing Method Masato Shinose, Akira Ueno, Shuichi Yamaguchi and Yoshitake Akiyama, Shinshu University

Session MP2-2 (Organized Session): Intelligent Robot Control

Conference Room 2

Chairperson:	Kenichi Ohara, Meijo University Tomohito Takubo, Osaka City University
15:45-16:00	Footstep Planning for Tripod Gait in Obstacle Environment Yuya Atarashi, Tomohito Takubo and Atsushi Ueno, Osaka City University
16:00-16:15	Automatic Generation for Image Information Added Map Considering the Surface Shape Hirofumi Takaishi, Tomohito Takubo and Atsushi Ueno, Osaka City University
16:15-16:30	Development of Multifunctional Robot Hand for Visual Inspection Equipped with 3D Force Sensing Ryo Akiyama, Kazuto Kamiyama, Masaru Kojima, Mitsuhiro Horade, Yasushi Mae and Tatsuo Arai, Osaka University
16:30-16:45	Algal Growth Rate Modelling and Prediction Optimization Using Incorporation of MLP and PSO Algorithm Wisnu Jatmiko, Dwi M J Purnomo, Machmud Alhamidi, Ari Wibisono, Hanif Wisesa, Petrus Mursanto, Anom Bowolaksono, Dian Hendrayanti and Fajar Addana, Universitas Indonesia
16:45-17:00	Manzai Robot System with Scalability based on Distributed Software Components Tomohiro Umetani, Satoshi Aoki, Kazuhiro Akiyama, Ryo Mashimo, Tatsuya Kitamura and Akiyo Nadamoto, Konan University
17:00-17:05	Coffee Break
Plenary Talk	
Chairperson:	Susumu Sugiyama, Ritsumeikan University
17:05-17:55	Plenary Talk 4 MEMS Sensors and Robots Prof. Yutaka Nonomura, Department of Mechatronics Engineering Faculty of Science and Technology, Meijo University, Japan
18:00-19:30	Beer Party

Conference Room 1

November 24 (Tue) Location: Noyori Conference Hall

Session TA1-1: (Organized Session) : Bio-Assembler -1

Chairperson:	Yasushi Mae, Osaka University Itsuki Ajiokai, Tokyo Medical and Dental University
09:00-09:15	3D-Cell Assembly by Control of Cell Surfaces Michiya Matsusaki and Mitsuru Akashi, Osaka University
09:15-09:30	Highly Dynamic Self-Organizing SMG Morphogenesis in 3D Culture Mahmoud Farahat, Gulsan Ara Sathi, Hiroaki Taketa, Masamitsu Oshima, Takuo Kuboki and Takuya Matsumoto, Okayama University
	A Method to Reorganize the Bone Marrow-Like Tissue with Suspension of Bone Marrow Cells <i>Kanae Sayo, Shigehisa Aoki and Nobuhiko Kojima, Yokohama City</i> <i>University</i>
09:45-10:00	Development of a Uniaxial Mechanical Loading Device to Evaluate Osteogenic Differentiation of Stem Cells Seeded on a Scaffold Material Masakazu Yamada, Takahisa Anada, Taisuke Masuda, Teruko Takano-Yamamoto and Osamu Suzuki, Tohoku University
10:00-10:15	Biological and Biomaterial Engineering Approaches for Injured Brain Regeneration Itsuki Ajioka, Tokyo Medical and Dental University (TMDU)

Session TA2-1: (Organized Session) : Bio-manipulation and Its Applications-1 Conference Room 2

Chairperson:	Masahiro Nakajima, Nagoya University Futoshi Iwata, Shizuoka University
09:00-09:15	Inducing Blood Vessel Formation Using Cubic Eggshell with Patterned Surface Wenjing Huang, Fumihito Arai and Tomohiro Kawahara, Kyushu Institute of Technology
09:15-09:30	Measurement of Shear Force and Adhesion Force of a Single Adhesion Cell using Atomic Force Microscopy with a Self-sensitive Cantilever Shigetaka Hashimoto and Futoshi Iwata, Shizuoka University
09:30-09:45	Diffusion of Particles Adhering to Liposomes Kazuki Shigyou, Ken H. Nagai and Tsutomu Hamada, Japan Advanced Institute of Science and Technology
09:45-10:00	Behavior of a Single Muscle Cell Bioactuator on a Biocompatible Fiber String Structure Kohta Ogawa, Kaoru Uesugi and Keisuke Morishima, Osaka University
10:00-10:15	In situ Nanomanipulation with 3D SEM-CT Observation inside Environmental SEM Masahiro Nakajima, Masaru Takeuchi, Toshio Fukuda, Yasuhisa Hasegawa and Qiang Huang, Nagoya University
10:15-10:25	Coffee Break

Session TA1-2: (Organized Session) :Bio-Assembler -2

ConferenceRoom 1

Chairperson:	Masaru Kojima, Osaka University Shinji Sugiura, AIST
10:25-10:40	Stem Cell Separation using Thermoresponsive Copolymer Brushes having Cationic Charge Kenichi Nagase, Yuri Hatakeyama, Tatsuya Shimizu, Katsuhisa Matsuura, Masayuki Yamato, Naoya Takeda and Teruo Okano, Tokyo Women's Medical University
10:40-10:55	Micropatterned Three-Dimensional Culture in Click-Crosslinkable and Photodegradable Gelatin Hydrogels Masato Tamura, Fumiki Yanagawa, Shinji Sugiura, Toshiyuki Takagi, Kimio Sumaru and Toshiyuki Kanamori, National Institute of Advanced Industrial Science and Technology (AIST)
10:55-11:10	Cell Adhesion Control using Microstructured Meshes Induces Self-Assembly-Mediated Organoid Formation by Human iPS Cells Kennedy O. Okeyo, Osamu Kurosawa, Satoshi Yamazaki, Hidehiro Oana, Hidetoshi Kotera and Masao Washizu, The University of Tokyo
11:10-11:25	A new Method for Fabricating Cell-embedded ECM Capsules and ECM-loaded Spheroids <i>Fumiya Tao and Nobuhiko Kojima, Yokohama City University</i>
11:25-11:40	Fabrication of Hepatic Lobule Model based on Electrodeposition Zeyang Liu, Masaru Takeuchi, Masahiro Nakajima, Toshio Fukuda, Yasuhisa Hasegawa and Qiang Huang, Nagoya University
11:40-11:55	Automatic stage construction for the support of micro object grasping Kotaro Yamamoto, Masaru Kojima, Mitsuhiro Horade, Kazuto Kamiyama, Yasushi Mae and Tatsuo Arai, Osaka University

Session TA2-2: (Organized Session) : Human Assistive Technologies

ConferenceRoom 2

Chairperson:	Jian Huang, Huazhong University of Science and Technology
	Takahiro Ikeda, Meijo University
10:25-10:40	Indoor Localization with Incomplete Observation using Set-membership Filter Yuan Wang and Jian Huang, Huazhong University of Science and Technology
10:40-10:55	Automatic Fetal Head Approximation Using Particle Swarm Optimization Based Gaussian Elliptical Path <i>M. Anwar Ma'sum, N. Rahmah, H. R. Sanabila, H. A. Wisesa and W. Jatmiko,</i> <i>Universitas Indonesia</i>
10:55-11:10	Japanese Syllabary Identification Using Myoeletric Potential of Neck Muscles Kentaro Suzuki and Yasuhisa Hasegawa, University of Tsukuba
11:10-11:25	Wearable Input Device by Fingertip Motion Osamu Asai and Yasuhisa Hasegawa, University of Tsukuba
11:25-11:40	Pilot Study on Control of One DoF Manipulator on Quadcopter for Hammering Check Takahiro Ikeda, Kenichi Ohara, Akihiko Ichikawa and Toshio Fukuda, Meijo University

11:55-12:55 *Lunch*

Poster Area(1st floor)

Poster session II

Chairperson Masahiro Ohka, Nagoya University Seiichi Hata, Nagoya University Yasushi Mae, Nagoya University Oi An, The University of Tokyo

12:55-13:55

- TP-01 Construction of Engineered Liver Cancer Tissues with Multichannel Collagen Gel Kazuya Furusawa, Masayuki Tsuchida and Saki Yahata, Hokkaido University
- TP-02 Fabrication of Functional Liver Tissues by Cell Sheet-based Bioassembler Technologies Jun Kobayashi, Yoshikatsu Akiyama, Masayuki Yamato and Teruo Okano, Tokyo Women's Medical University
- TP-03 Generation of Biped Stance Motion in Consideration of Neurological Time Delay through Forward Dynamics Simulation *Ping Jiang, Ryosuke Chiba, Kaoru Takakusaki and Jun Ota, The University of Tokyo*
- TP-04 Investigation of Oxygen Consumption for Micropatterns of Contractile Myotubes by Scanning Electrochemical Microscopy Yuki Igaki, Fumio Mizutani and Tomoyuki Yasukawa, University of Hyogo
- TP-05 One-Step Microfluidic Spinning of Collagen Microfibers and Their Application to Cell Cultivation Sakiko Enomoto, Yuya Yajima, Yuki Watabe, Masumi Yamada, Kazuya Furusawa and Minoru Seki, Chiba University
- TP-06 Estimation of Stress During Car Race with Factor Analysis Daisuke Tomoi, Wen Wen, Hiroshi Yamakawa, Shunsuke Hamasaki, Kaoru Takakusaki, Qi An, Yusuke Tamura, Atsushi Yamashita and Hajime Asama, The University of Tokyo
- TP-07 Observation of the Permeation on the Subcutaneous during the Administration of Drug and Design of a Needle Kento Kawata, Kazuyoshi Tsuchiya, Kagemasa Kajiwara and Minoru Kimura, Tokai University
- TP-08 A New Method for Continuous Sorting of Cells/Particles Using Lattice-shaped Dual-depth Microchannels *Takuma Yanai, Masumi Yamada, Wataru Seko and Minoru Seki, Chiba University*

- TP-09 Transportation of cm-sized Solid Substrate by LaserK. Koyoshi, K. Sadakane, T. Kenmotsu and K. Yoshikawa, Doshisha University
- TP-10 Bayesian Model of the Sense of Agency in Normal Subjects Shiro Yano, Toshiyuki Kondo, Yuichi Yamashita, Tsukasa Okimura, Hiroshi Imamizu and Takaki Maeda, Tokyo University of Agriculture and Technology
- TP-11 On-chip Monitoring of Megakaryocytes in Shear Flow environment Kazuya Tashiro, Shinya Sakuma, Keitaro Ito, Sou Nakamura, Koji Eto, Toshio Fukuda and Fumihito Arai, Nagoya University
- TP-12 Auditory Foot: A Novel Auditory Feedback System Regarding Kinesthesia Dai Owaki, Yusuke Sekiguchi, Akio Ishiguro and Shin-Ichi Izumi, Tohoku University
- TP-13 Stiff consideration of a micro painless needle with polygon section Hideaki Kimoto and Kazuyoshi Tsuchiya, Tokai University
- TP-14 Search of the Best Slot Rate of the Slot Addition Type PZT Actuator in a Hollow Tube Micro Pump Hiromasa Suzuki, Kazuyoshi Tsuchiya and Yasutomo Uetsuji, Tokai University
- TP-15 A Questionnaire-Based Survey Therapist's Response on Emotions Gestures using Humanoid Robot for Autism Mohd Azfar Miskam, Syamimi Shamsuddin, Hanafiah Yussof, Ilmi Mohd Ariffin and Abdul Rahman Omar, Universiti Teknologi MARA
- TP-16 Mechanical Characterization of Floating Cell using Whole Chip Deformation Mechanism Keitaro Ito, Shinya Sakuma, Makoto Kaneko and Fumihito Arai, Nagoya University
- TP-17 Automated Plarform For Rare Cell Isolation And Pick-up Using Air-liquid Interface Control
 Woneui Song, Taisuke Masuda, Hayao Nakanishi and Fumihito Arai, Nagoya University
- TP-18 Ellipse Detection on Embryo Image Using Modification of Arc Particle Swarm Optimization (ArcPSO) Based Arc Segment Arie Rachmad Syulistyo, Hanif Arief Wisesa, Aprinaldi, Anom Bowolaksono, Budi Wiweko and Wisnu Jatmiko, Universitas Indonesia

- TP-19 Evaluating Effect of Sense of Ownership and Sense of Agency on Body Representation Change of Human Upper Limb Shunsuke Hamasaki, Qi An, Wen Wen, Yusuke Tamura, Hiroshi Yamakawa, Atsushi Yamashita, Hajime Asama, Satoshi Shibuya and Yukari Ohki, The University of Tokyo
- TP-20 Automated Construction System for Cellular Tissue Based on Laminar Flow Fibers Masaru Kojima, Mitsuhiro Horade, Akira Fukushima, Kenichi Ohara, Sinji Sakai, Kazuto Kamiyama, Yasushi Mae and Tatsuo Arai, Osaka University
- TP-21 Origami Microfluidics Integrated with Gold Micropatterns Fumiaki Tomoike, Florian Larramendy and Shoji Takeuchi, The University of Tokyo
- TP-22 On-chip Fabrication of Bio-degradable Microstructures Ryota Sakakibara, Masaru Takeuchi, Akihiko Ichikawa, Kenichi Ohara, Masahiro Nakajima, Yasuhisa Hasegawa and Toshio Fukuda, Meijo University
- 13:55-14:00 *Coffee Break*

Plenary Talk

Conference Room 1

- Chairperson: Ota Jun, The University of Tokyo
- 14:00-14:50 Plenary Talk 5
 What Role Motion Plays in Human-robot Interaction? Understanding Non-verbal Communication in HRI
 Prof. Gentiane Venture, Department of Mechanical systems Engineering, Tokyo University of Agriculture and Technology, Japan
- Chairperson: Osamu Suzuki, Tohoku University
- 14:50-15:40 Plenary Talk 6 Engineering Biogenesis of Human Platelet on Chip System Prof. Koji Eto, Center for iPS Cells Research and Application, Kyoto University, Japan

15:40-15:45 *Coffee Break*

Session Session TP1-1: (Organized Session) : Bio-manipulation and Its Applications -2

Conference Room 1

Chairperson:	Masaru Takeuchi, Nagoya University Shinji Deguchi, Nagoya Institute of Technology
15:45-16:00	Microchannels Fabrication by Alginate Fiber Molding Method Masaru Takeuchi, Masahiro Nakajima, Toshio Fukuda and Yasuhisa Hasegawa, Nagoya University
16:00-16:15	Gene Delivery to Animal and Plant Cells using a Nano-needle Array-shaped Photooxidative Cell Membrane Perforator Yukihiro Akiyama, Shunsuke Sakai, Yoshiyuki Suzuki, Shuhei Kashiwazaki, Shogo Unuma, Kei Innomata, Hiroetsu Wabiko and Takashi K. Saito, Akita Prefectural University
16:15-16:30	Molecular Dynamics of Orientation Controlled Muscle Tissue on a Chip Yuki Okino, Toshifumi Asano and Keisuke Morishima, Osaka University
16:30-16:45	Photocontrollable Fusion of Lipid Vesicles Y. Suzuki, K. Shigyo, K. H. Nagai, A. Zinchenko and T. Hamada, Japan Advanced Institute of Science and Technology
16:45-17:00	Characterizing the Biophysical Properties of Individual Actin Stress Fibers Shinji Deguchi and Tsubasa S. Matsui, Nagoya Institute of Technology
Session TP2-1	Organized Session): Embodied-Brain Systems Science: Conference Room 2
Chairperson:	Shinya Aoi, Kyoto University Toshiyuki Kondo, Tokyo University of Agriculture and Technology
15:45-16:00	Modelling Methodology in Embodied-brain Systems Science

- Jun Ota, Hajime Asama, Toshiyuki Kondo, Hirokazu Tanaka, Shiro Yano, Jun Izawa, Shinya Aoi and Ryosuke Chiba, The University of Tokyo
- 16:00-16:15A computational Approach to Detect a Meta-learning of the Cortical Basis
Function during a Motor Adaptation Study.
Daichi Sasaki, Jun Izawa and Masahiko Morita, University of Tsukuba

16:15-16:30	Improvement of Operability of Extra Robotic Thumb Using Tactile Feedback by Electrical Stimulation <i>Masafumi Sobajima, Yuichiro Sato, Wang Xufeng and Yasuhisa Hasegawa,</i> <i>Nagoya University</i>
16:30-16:45	Dynamical model of the Body Sway of Bipedally Standing Rat with Rat with Olivo-cerebellar Dysfunction <i>Sekiya Noro, Tetsuro Funato, Yota Sato, Yamato Sato, Dai Yanagihara,</i>
	Shinya Aoi and Kazuo Tsuchiya, The University of Electro-Communications
16:45-17:00	Kinematic Analysis of Low Dimensional Structure in Walking and Running Shuntaro Ishiduka, Hiroko Oshima, Shinya Aoi, Tetsuro Funato, Nozomi Tomita, Nobutaka Tsujiuchi, Akihito Ito and Kazuo Tsuchiya, Doshisha University

17:00-17:10 *Coffee Break*

Session TP1-2: (Organized Session) : Bio Assembler -3

Conference Room 1

Chairperson:	Kenichi Ohara, Meijo University
	Chia-Hung Dylan Tsai, Osaka University
17:10-17:25	Frequency Responses of On-chip Pressure Sensor with Different Size of Deformation Chamber <i>Chia-Hung Dylan Tsai and Makoto Kaneko, Osaka University</i>
17:25-17:40	Mechanical Measurement of in vitro Tissue by Atomic Force Microscopy Ryosuke Tanaka and Takaharu Okajima, Hokkaido University
17:40-17:55	Development of High Speed Measurement System for Cell-scaffold Interaction Yu Hirano, Masaru Kojima, Mitsuhiro Horade, Kazuto Kamiyama, Yasushi Mae and Tatsuo Arai, Osaka University
17:55-18:10	A method to Measure Displacement of Microscale Structures with High Resolution and Large Stroke for Cellular Characterization <i>Hirotaka Sugiura, Shinya Sakuma, Makoto Kaneko and Fumihito Arai,</i> <i>Nagoya University</i>
18:10-18:25	Cellular Force Measurement by Load Sensor Using Quartz Crystal Resonator Ayaka Sato, Shinya Sakuma, Kou Nakahara, Yuichi Murozaki and Fumihito Arai, Nagoya University

Session TP2-2: Cognitive Robotics

Conference Room 2

Chairperson:	Naoyuki Kubota, Tokyo Metropolitan University		
	Hiroyuki Masuta, Toyama Prefectural University		
17:10-17:25	Robot Interaction for Driving Support in Micro Electric Vehicle Hiroyuki Masuta, Yoshikazu Okajima, Masatoshi Okumura, Tatsuo Motoyoshi, Ken'ichi Koyanagi, Toru Oshima and Eiichi Takayama, Toyan Prefectural University		
17:25-17:40	•	Modeling for Multimodal Interaction with Robot Partner o Chu Kiong and Naoyuki Kubota, University of Malaya	
17:40-17:55		aze Estimation Driven Solution for Interacting Children with ASD Jaibin Cai, Xiaolong Zhou, Hui Yu and Honghai Liu, University of Portsmouth	
18:10-18:25	Content-based Conversation for Robot Partners Based on Life Hub Jinseok Woo, Chiaki Kasuya and Naoyuki Kubota, Tokyo Metropolitan University		
18:35-20:35	Reception Party	Universal Club	

November 25 (Wed) Location: Noyori Conference Hall

Session WA1-1: (Organized Session) : Young Researchers in Biomedical Engineering Conference Room 1

Chairperson:	Taisuke Masuda, Nagoya University Akihiko Ichikawa, Meijo University	
09:00-09:15	Mechanical Characterization of Oocyte Using an Opened Microchannel Environment Kou Nakahara, Shinya Sakuma, Takeshi Hayakawa and Fumihito Arai, Nagoya University	
09:15-09:30	Mechanical Characterization of a Single Synechocystis sp. PCC 6803 Takayuki Hasegawa, Shinya Sakuma, Kei Nanatani, Nobuyuki Uozumi and Fumihito Arai, Nagoya University	
09:30-09:45	Human Sperm Tracking using Particle Swarm Optimization combined with Smoothing Stochastic Sampling on Low Frame Rate Video Aprinaldi, Grafika Jati, Alexander A S Gunawan, Anom Bowolaksono, Silvia Werdhy Lestari and Wisnu Jatmiko, Universitas Indonesia	
09:45-10:00	Local Melting of Hydrogel for Microchannels Fabrication in Cell Structures Tomoyuki Oya, Masaru Takeuchi, Akihiko Ichikawa, Kenichi Ohara, Masahiro Nakajima, Yasuhisa Hasegawa and Toshio Fukuda, Meijo University	
10:00-10:15	Evaluation System for Mechanobiology of Three-dimensional Tissue Multilayered In Vitro Kaoru Uesugi, Akihiro Nishiguchi, Michiya Matsusaki, Mitsuru Akashi and Keisuke Morishima, Osaka University	

Session WA2-1: Robotics and Mechatronics

Conference Room 2

Chairperson:	Kosuke Sekiyama, Nagoya University		
	Takahiro Ikeda, Meijo University		
09:00-09:15	Vision Tracking Application for Mobile Navigation Using Humanoid Robot Nao		
	Ilmi Mohd Ariffin, Ahmad Ismat Hakam Mohamed Rasidi, Hanafiah Yussof,		
	Mohd Azfar Miskam and Abdul Rahman Omar, Universiti Teknologi MARA		
09:15-09:30	Implementation of Grid Mapped Robot Planning Algorithm in a Continuous Map for Fire Fighting Robot		
	Sumarsih Condroayu Purbarani, Qurrotin A'yunina MOA, Grafika Jati,		
	Muhammad Anwar Ma'sum, Hanif Arif Wisesa and Wisnu Jatmiko, Universitas Indonesia		
09:30-09:45	Feasibility Study of Wearable Robot Control based on Upper and Lower Limbs Synergies		
	Modar Hassan, Hideki Kadone, Tomoyuki Ueno, Kenji Suzuki and Yoshiyuki		
	Sankai, University of Tsukuba		
09:45-10:00	In-Vitro DNA-based Finite State Machine		
	Rizki Mardian and Kosuke Sekiyama, Nagoya University		

10:15-10:25 *Coffee Break*

Keynote Talk

Conference	Room	1
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Chairperson:	Yasuhisa Hasegawa, Nagoya University	
10:25-10:55	Keynote Talk 1 Computational biomechanics of blood cell motion Prof. Ken-ichi Tsubota, Department of Mechanical Engineering, Graduate School of Engineering, Chiba University, Japan	
10:55-11:25	Keynote Talk 2 Machine Learning Methods to Control Exoskeleton Robots Dr. Jun Morimoto, Department of Brain Robot Interface, ATR Computational Neuroscience Labs, Japan	
11:25-11:40	Coffee Break	
11:40-12:00	Award Ceremony	Conference Room 1
12:00-13:30	Lunch	
13:30-15:00	Laboratory Tour	Nagoya University