

Comments and Corrections

Corrections to “Multi-Modal Sensor Fusion-Based Semantic Segmentation for Snow Driving Scenarios”

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IN THE above article [1], we had mentioned the SSMA in many result tables, but unfortunately, we had made a mistake in the citation, which would have made the readers unable to link to the original material of the method. The faults in the above article have been corrected in this article. The self-supervised model adaptation (SSMA) [2] is a fusion module combining two feature maps. This module was developed for multi-modal semantic segmentation and achieved the best efficiency in many conditions.

Table II, **Table V**, **Table VI**, and **Table VII** in [1] are corrected to be in sequential order as **Table I**, **Table III**, **Table II**, and **Table IV**, respectively. The citation index of SSMA in all tables is corrected to SSMA [2]. In addition, the citation in **Fig. 12** in the article [1] is also changed to SSMA [2], as shown in **Fig. 1**.

- [2] A. Valada, R. Mohan, and W. Burgard, “Self-supervised model adaptation for multimodal semantic segmentation,” *Int. J. Comput. Vis.*, vol. 128, pp. 1239–1285, Jul. 2019.
- [3] H. Zhao, X. Qi, X. Shen, J. Shi, and J. Jia, “ICNet for real-time semantic segmentation on high-resolution images,” *CoRR*, vol. abs/1704.08545, pp. 1–16, Apr. 2017.
- [4] J. Fu, J. Liu, H. Tian, Z. Fang, and H. Lu, “Dual attention network for scene segmentation,” *CoRR*, vol. abs/1809.02983, pp. 1–10, Sep. 2018.
- [5] Z. Tian, T. He, C. Shen, and Y. Yan, “Decoders matter for semantic segmentation: Data-dependent decoding enables flexible feature aggregation,” in *Proc. IEEE/CVF Conf. Comput. Vis. Pattern Recognit. (CVPR)*, Jun. 2019, pp. 3121–3130.
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- [8] L.-C. Chen, G. Papandreou, F. Schroff, and H. Adam, “Rethinking atrous convolution for semantic image segmentation,” *CoRR*, vol. abs/1706.05587, pp. 1–14, Jun. 2017.

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- [1] S. Vachmanus, A. A. Ravankar, T. Emamu, and Y. Kobayashi, “Multi-modal sensor fusion-based semantic segmentation for snow driving scenarios,” *IEEE Sensors J.*, vol. 21, no. 15, pp. 16839–16851, Aug. 2021.

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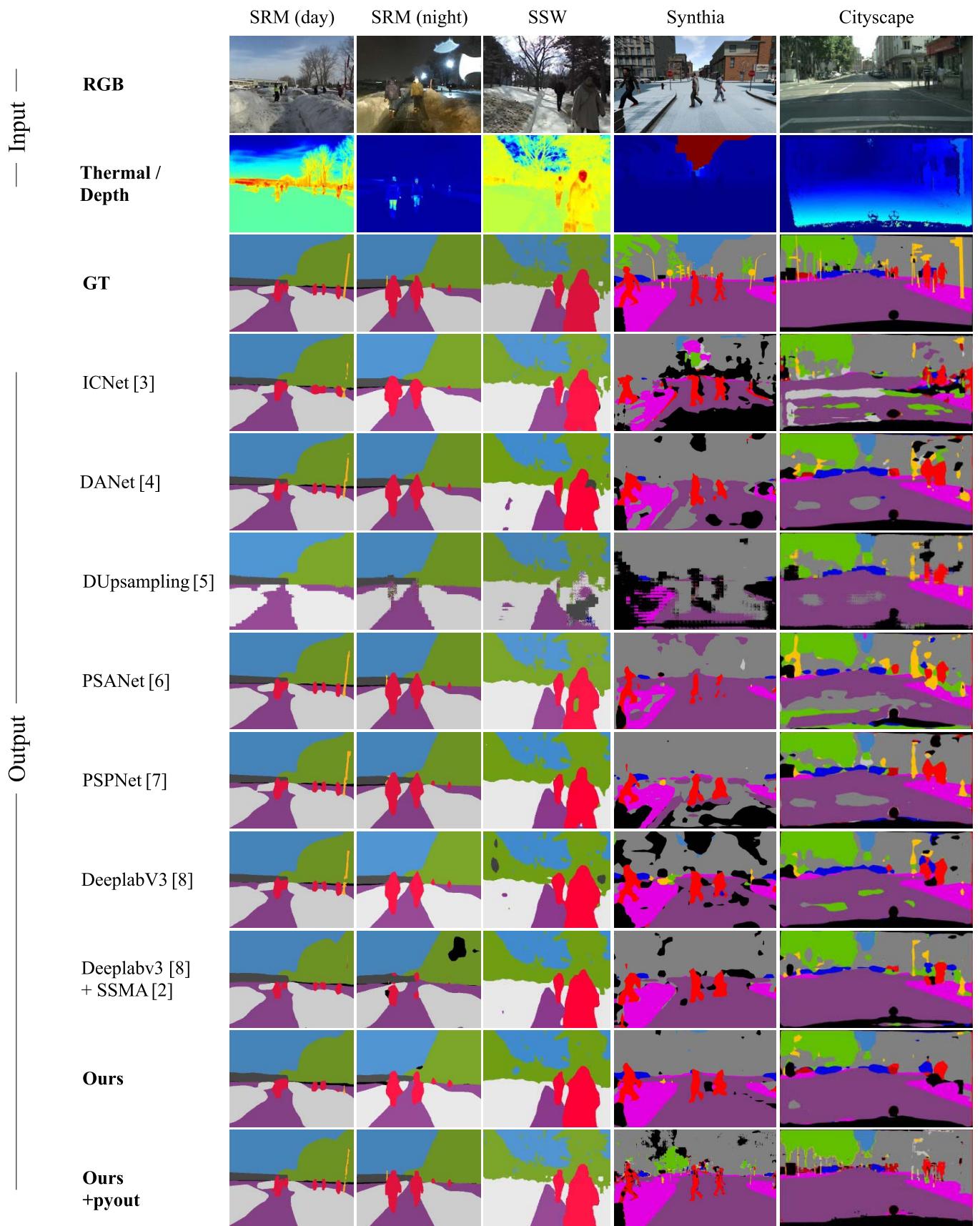
**Fig. 1.** Results of segmentation on all datasets.

TABLE I
THE COMPLEXITY COMPARISON OF NETWORKS

Network	Dataset		Parameters	Memory	MACs	Time
	RGB	T				
ICNet [3]	✓	-	28.29M	0.93G	18.7G	52ms
	✓	✓	30.73M	1.15G	36.65G	112ms
DANet [4]	✓	-	49.62M	1.78G	75.3G	31ms
	✓	✓	49.63M	2.46G	150.6G	63ms
DUpsampling [5]	✓	-	34.53M	1.49G	57.19G	28ms
	✓	✓	39.47M	2.35G	109.78G	58ms
PSANet [6]	✓	-	52.97M	2.19G	144.85G	31ms
	✓	✓	71.85M	3.81G	289.67G	61ms
PSPNet [7]	✓	-	48.76M	1.69G	69.29G	31ms
	✓	✓	67.63M	2.79G	138.58G	59ms
DeeplabV3 [8]	✓	-	41.81M	1.46G	65.3G	31ms
	✓	✓	42.4M	2.21G	130.6G	59ms
DeeplabV3 [8] + SSMA [2]	✓	✓	42.54M	2.53G	130.77G	60ms
Ours	✓	✓	45.5M	2.27G	134.31G	58ms
Ours + pyout	✓	✓	109M	3.53G	393.29G	75ms

M is $\times 10^6$, G is $\times 10^9$

TABLE II
THE SEGMENTATION PERFORMANCE ON THE SRM DATASET AND SSW DATASET

ID	IoU (%)									mIoU(%)	mF1(%)	
	1	2	3	4	5	6	7	8	9			
SRM dataset												
ICNet [3]	83.2	77.0	74.9	24.1	86.6	54.1	66.1	11.7	22.4	55.6	67.0	
DANet [4]	85.4	91.3	85.7	37.7	87.7	91.2	72.4	18.9	35.9	67.4	76.9	
DUpsampling [5]	84.2	90.4	81.0	0.1	87.0	93.7	64.2	0.9	39.9	60.2	67.0	
PSANet [6]	82.4	88.5	80.3	38.7	87.9	91.8	58.9	16.2	47.2	65.8	76.1	
PSPNet [7]	87.3	89.8	83.9	34.6	90.1	88.9	74.1	20.7	52.6	69.1	78.6	
DeeplabV3 [8]	85.0	90.6	82.6	33.4	93.2	95.0	72.9	19.8	59.4	70.2	79.3	
DeeplabV3 [8] + SSMA [2]	85.7	91.4	83.9	36.7	92.5	95.3	74.8	26.6	53.7	71.2	80.4	
Ours	87.5	92.7	85.4	36.4	94.4	95.9	75.8	27.5	63.3	73.2	81.9	
Ours + pyout	91.8	95.5	91.4	53.5	95.6	96.5	81.8	31.9	67.4	78.4	86.5	
SSW dataset												
ICNet [3]	89.4	87.4	88.3	8.2	89.5	92.7	79.7	79.7	24.9	71.1	78.3	
DANet [4]	88.2	86.9	87.2	16.1	86.4	88.1	82.8	78.9	26.2	71.2	79.4	
DUpsampling [5]	87.3	83.7	80.2	0.5	86.9	90.5	1.5	22.2	0.0	50.3	55.7	
PSANet [6]	89.0	87.4	87.5	18.0	87.7	89.7	85.8	70.2	19.4	70.5	78.5	
PSPNet [7]	89.5	87.5	88.5	18.8	86.7	87.8	86.1	83.3	32.1	73.4	81.3	
DeeplabV3 [8]	88.5	86.6	81.6	17.2	83.6	88.7	85.5	81.8	30.6	71.6	80.0	
DeeplabV3 [8] + SSMA [2]	91.9	90.5	89.5	14.1	87.7	89.5	84.5	74.7	21.3	71.5	79.8	
Ours	88.0	86.5	88.5	18.2	87.0	89.2	88.9	85.3	32.2	73.8	81.5	
Ours + pyout	94.1	93.5	92.2	33.8	93.8	95.3	93.7	84.5	49.1	81.1	87.6	

TABLE III
THE COMPARISON OF USING THE THERMAL MAP
IN THE SRM DATASET

Network	Human IoU (%)	
	RGB	RGB-T
ICNet [3]	57.6	66.1
DANet [4]	67.2	72.4
DUpsampling [5]	2.3	64.2
PSANet [6]	68.4	58.9
PSPNet [7]	64.5	74.1
DeeplabV3 [8]	64.9	72.9
DeeplabV3 [8] + SSMA [2]	-	74.8
Ours	-	75.8
Ours + pyout	-	78.4

TABLE IV
THE SEGMENTATION PERFORMANCE ON THE CITYSCAPE
DATASET AND SYNTHIA DATASET

Network	mIoU(%)	mAcc(%)	mF1(%)	Cityscape
				Synthia
ICNet [3]	40.0	96.0	51.7	27.9
DANet [4]	58.6	97.7	70.9	51.3
DUpsampling [5]	53.1	97.4	65.3	33.0
PSANet [6]	48.3	96.0	62.7	55.0
PSPNet [7]	56.1	97.5	68.6	47.1
DeeplabV3 [8]	59.8	97.7	72.3	62.4
DeeplabV3 [8] + SSMA [2]	58.2	97.5	71.4	61.5
Ours	59.6	97.7	73.2	65.1
Ours + pyout	62.6	98.1	73.8	69.4