

Comments and Corrections

Corrections to “High-Accuracy Calibration of a Visual Motion Measurement System for Planar 3-DOF Robots Using Gaussian Process”

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In the above paper, in the first paragraph of the last section VI. CONCLUSION, the citation [?] should show as [3].

REFERENCES

- [1] R. Wang and X. Zhang, “Parameters optimization and experiment of a planar parallel 3-DOF nanopositioning system,” *IEEE Trans. Ind. Electron.*, vol. 65, no. 3, pp. 2388–2397, Mar. 2018.

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