

Comments and Corrections

Correction to “Joint Velocity Ambiguity Resolution and Ego-Motion Estimation Method for mmWave Radar”

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The affiliation of the author in [1] is incomplete. The corrected affiliation of the authors is as follows.

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REFERENCE

- [1] Z. Zeng, X. Liang, X. Dang, and Y. Li, “Joint velocity ambiguity resolution and ego-motion estimation method for mmWave radar,” *IEEE Robot. Automat. Lett.*, vol. 8, no. 8, pp. 4753–4760, Aug. 2023, doi: [10.1109/LRA.2023.3289398](https://doi.org/10.1109/LRA.2023.3289398).

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