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RESEARCH ARTICLE

Deep Learning Model Development for Detecting Coffee Tree Changes Based on Sentinel-2 Imagery in Vietnam

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ABSTRACT Scientists and land managers have spent considerable time and resources monitoring coffee forests in the great basalt plateau. Deep learning models for coffee classification using remote sensing data have developed into a tool that may eventually replace manual image interpretation. This study proposes a U-Net model for classifying coffee planting regions using Sentinel-2 data, which aid in the annual monitoring of coffee plantation area changes. Numerous optimizer methods were evaluated and compared to support-vector-machine and random-forest methods. Twelve U-Net models were trained and compared in total. The trained deep learning models outperformed the two benchmark methods. As a result, the U-Net model with the Adadelta optimizer and $128 \times 128 \times 4$ input data size was chosen due to its near-95 percent accuracy and 0.12 loss function value. The model was used to successfully detect location of the Vietnamese coffee ecosystem. The Net-Adadelta-128 model's output is consistent with data from statistical reports, which estimated the area of the coffee land cover to be 684, 681, and 676 thousand hectares in 2019, 2020, and 2021, respectively. The best U-Net model, which takes approximately 30 minutes to create a new classification for 55,000 square kilometres, may one day be used for coffee research and management.

INDEX TERMS Deep learning, coffee, U-Net, loss function, optimization.

I. INTRODUCTION

Each year, consumers drink over 400 billion cups of coffee, sustaining a worldwide business worth more than \$100 billion USD [1], [2], [3]. As a result, coffee is a significant worldwide commodity that is critical to the economy of a number of tropical nations. Before coming a major commercial commodity around the globe, coffee plants were discovered for the first time in Ethiopia's highlands in the 9th century [4]. The French missionaries first planted them in Vietnam in 1857 [5], [6]. As the second largest coffee exporter in the world, Vietnam

produces 2.7 million tons of coffee per hectare on a total area of about 670,000 ha [7]. Compared to 1980, Vietnam's coffee area in 2000 increased 23 times and its production increased 83 times [8]. Therefore, Vietnam has a high potential to become the largest coffee exporter in the world if the farmers and forestry managers have good management policies with support from high technology in the 21st century [9]. It has been raised the issue of how coffee production impacts the regeneration, maintenance, or removal of tropical forests. Therefore, mapping coffee plantations is critical for determining the geographic locations of coffee production hubs. When it comes to monitoring and mapping vegetation, remote sensing technology has been extensively shown to

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be a cost-effective, rapid, and efficient approach [10], [11]. Additionally, the use of machine learning to remote sensing analysis seeks to enhance the lives of coffee farmworkers and their families, boost the productivity of current coffee production regions, and avert either forest clearance or depletion of other natural resources [7], [12].

However, it is difficult to detect or classify precisely the coffee land cover based on pixel-based methods due to the differences in their canopy structures. Meanwhile, monoculture coffee systems have transitioned to unshaded systems, while the number of canopy forms and management methods have diversified among shaded systems [13]. It makes their ecosystem services and environmental effects more diverse, compared to the traditional plantation methods [2]. Four typical shaded coffee systems that are often identified based on their variety of vertical and compositional shading, include (1) rustic polyculture, (2) traditional polyculture, (3) commercial polyculture, and (4) shaded monoculture [13]. In rustic polyculture systems, the forest canopy remains intact and understory changes are limited. Coffee and other shade-tolerant plants are included in conventional polyculture systems to preserve the canopy integrity, but growers must completely replace the understory with coffee plants. Commercial polyculture methods eliminate both the understory and canopy, replacing these elements with coffee and other commercially valuable smaller trees. Shaded monoculture, a kind of contemporary shaded system, is produced by eliminating both the canopy and understory and replacing them with a leguminous canopy that is nearly entirely dedicated to shading the coffee below.

With the variety of coffee land cover shape, the object-based classification based on the integration of remote sensing data and deep learning models therefore can become a potential method to identify this land cover on remote sensing data [10]. This integration is a subset of artificial intelligence in which computers learn from samples, human knowledge, raw data, previous outcomes and new data sources [14], [13], [15], [16]. Artificial neural networks are made up of linked nodes that seem to mimic the structure of a massive brain's neural network [17]. Based on the programmed neural networks, humans can anticipate land use/cover changes and natural disasters and make intelligent choices in real-time without human involvement [18]. Nowadays, different types of neural networks have been developed in deep learning fields. Deep learning (DL) has been applied in remote sensing studies to identify ships and turtles, and also to classify complex ecosystems such as wetlands and estuaries [19], [20], [21]. DL models may provide a wide range of information that can benefit global investments in coffee production in mountain communities, which include the promotion of biodiversity, less deforestation, and sustainable production.

In recent years, the DL has significantly changed the state of the art in processing remote sensing data [16], [22]. These previously underutilized technologies include unsupervised learning, Random Forest, pixel-based, and Support Vector Machines. The applications of DL may increase the

efficacy and accuracy of land cover categorization models in real-time and on a geographical scale while reducing the costs of physical-based models [23], [24]. Many kinds of DL models, including Bayesian, Convolutional, U-Net, Mask-RCNN, and different lightweight-structured models (such as MobileNet, ShuffleNet) have developed in recent years [10], [25]. Most studies used satellite images provided by the Moderate Resolution Imaging Spectroradiometer (MODIS), Landsat, and Sentinel-2 for coffee classification [10], [26], [27], [28]. The aim of this study is to (1) develop an effective DL model for coffee land-cover classification based on remote sensing images, and (2) apply the DL model for monitoring the changes of coffee farming areas in the central highlands of Vietnam. The main contributions of this research article are listed below:

- Why combine machine learning and medium-resolution images for coffee land cover monitoring?
- Is it possible to use U-Net networks to classify coffee plantation area on Sentinel-2 image?
- How do coffee land cover changes in Vietnam?

II. MATERIAL AND METHODS

A. RESEARCH AREA

From 1980s to 2010s, the coffee production in Vietnam did not have effective technological pest control for Arabica type, the government has advocated to expand the Arabica coffee area on the basalt red soil in the Central Highlands provinces, especially Daklak province – selected as the focus area in this study [29] (Figure 1). In which, Robusta coffee accounts for 93%, Arabica coffee is over 6% and jackfruit coffee is less than 1%. Up to now, the area produces about 1 million tons of coffee of all kinds, but there is still a significant lack of Arabica coffee output [30].

In sampling area (more information in section 2.2), coffee is the main plants of Dak Lak province. In the period 2015-2020, the area of coffee tended to slightly decrease in order to increase its production. In 2020, the area of coffee was 202,140 ha, a decrease of 1,217 ha compared to 2015 [31]. The average yield was 23.54 quintals/ha, and the total output was estimated at 468,200 tons, an increase of 23,156 tons compared to 2015. Based on the application of irrigation technology in the coffee production since 2010, farmers in Buon Ma Thuot city have been able to control soil moisture, yield increased from 1.6 tons/ha in 2009 to 4 tons/ha in 2011, reducing 20 labor/year and saving 40% of irrigation water. Successful application of new foliar fertilizer product increased yield by 5 – 30 [32].

Nowadays, raw coffee is a key export product of the province, accounting for more than 86% of the local export products, contributing over 60% of the total annual budget revenue of the locality [33]. Coffee beans have been exported to 60 countries. However, only 10% of the coffee production area in the province is in specialized farming areas that are managed by high-technological companies, the remaining coffee area is managed by the local

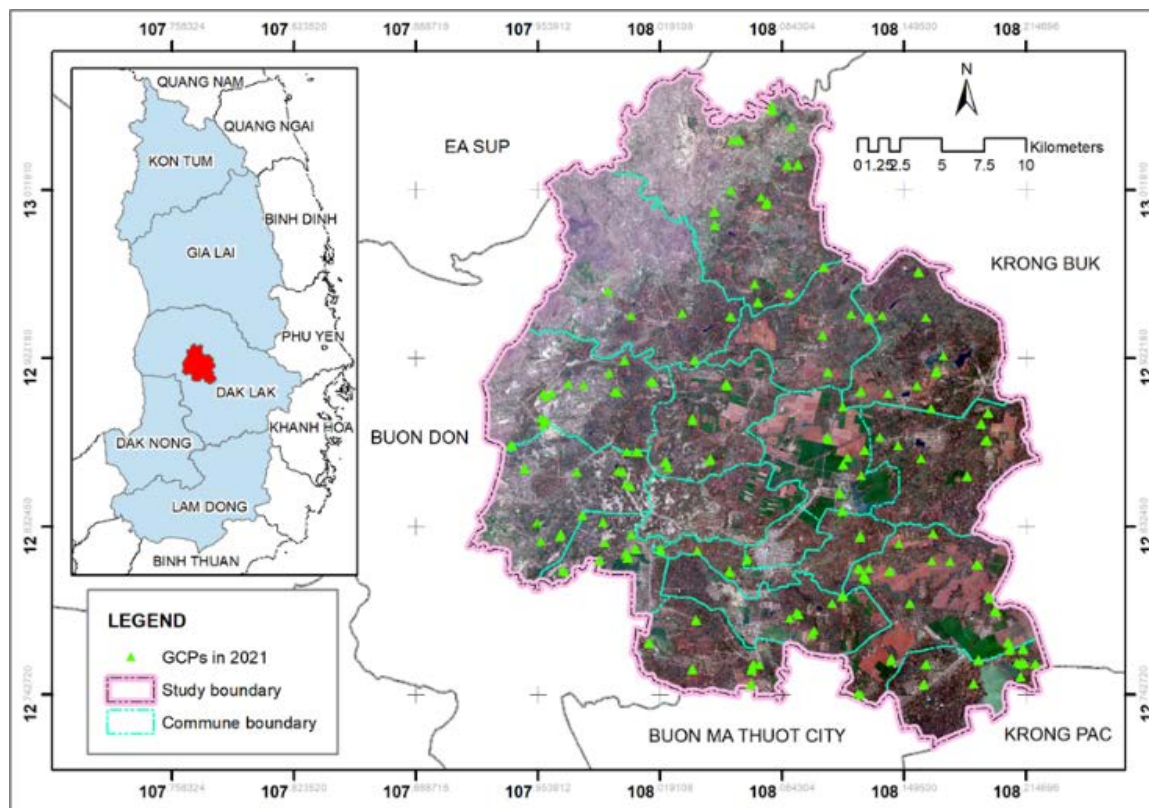


FIGURE 1. The research area with the location of coffee samples in the center part of Daklak province, Vietnam.

households [32]. It reduced the total production of coffee over a long-term period. The plantation based on a monocultural coffee model with fruit trees (such as Avocado and Pepper) provide more than three times of economic value in industrial farms than traditional planting. Due to the coffee farms have been mainly belonged to local households, the coffee plantation in Dak Lak is fragmented and heterogeneous [34]. The use of low-resolution remote sensing image such as MODIS data are difficult to identify coffee growing areas. It is necessary to integrate this data with medium-or high-resolution remote sensing data to more accurately determine the location of coffee growing areas in the province.

B. PROCESSING DATA

In order to collect information for image interpretation, verify the results of image classification and determine the ecological conditions related to the distribution of coffee trees in the study area, the study conducted fieldwork in the years 10/2020 and 09/2021 to collect coating status information. The collected information is designed on the field survey form. The total number of collected points is 249 ground control points. These points are collected according to the criteria of uniform distribution over the whole Cu M’gar district, Dak Lak province. At each survey site, the authors collect information about the current state of the land cover such as coordinates, type of cover, quality of vegetation cover, soil type, four-dimensional photographs and description of telltale signs on high-resolution satellite images. The data

collected in the field is standardized and updated into the field database to interpret remote sensing images and analyze information on ecological conditions related to the distribution of coffee trees for the land-cover classification in the research areas.

C. U-NET ARCHITECTURE FOR COFFEE TREE DETECTION

The U-Net approach was initially designed for various image segmentation in environmental and geographical fields [22], [35]. It consists of two paths: one contracting (on the left) and one expanding (on the right). The contracting path may be compared to a standard convolutional neural network (CNN) extractor. The right-hand side executes up-sampling operations, or the conversion of prediction values to the initial image size. Figure 2 depicts the U-Net architecture. As with a CNN, a U-layers Net’s are composed of three-dimensional neurons: width, length, and depth [16]. The thickness of an image is determined by the amount of input bands or variables. For instance, in this study, the image’s depth parameter is the number of UAV bands — the red, green, blue, and near-infrared spectral bands.

D. PROCESSING DATA

As a result, the three dimensions of the input sub-images are width, height, and number of bands. Besides the number of bands is fixed at four, the width and height are changed to choose the optimal size. It is explained in detail in the optimization section. Rather of constructing neurons using

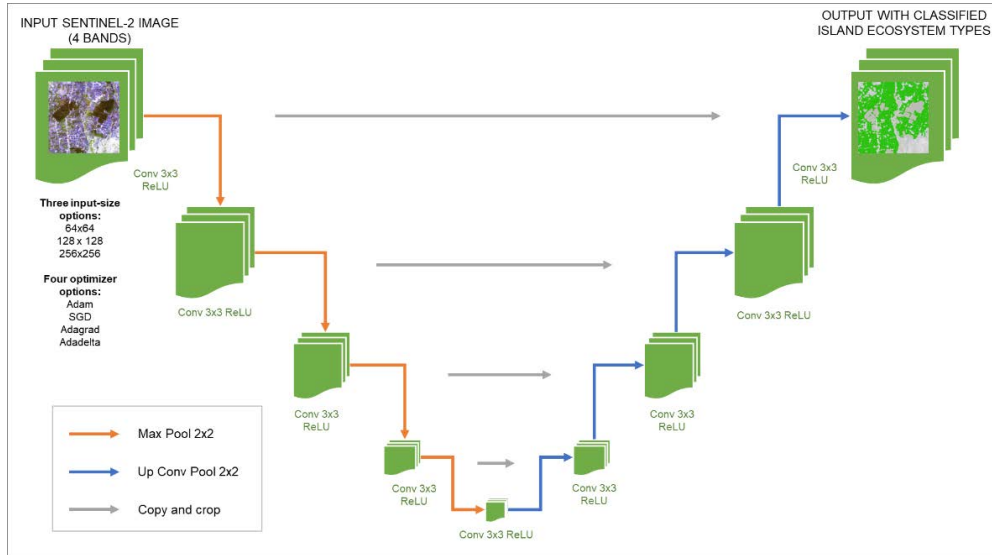


FIGURE 2. The architecture of a convolutional neural network for land cover detection.

complete sub-images at once, the neurons in a layer were constructed using tiny matrices of sub-images [36], [37].

Each layer of the U-Net transforms original input into new states using a predefined function. Six significant sorts of layers are frequently used to construct U-Net architectures: (1) INPUT Layer, (2) Convolutional Layer (CONV), (3) Batch Normalization Layer, (4) Pooling Layer (POOL), and (5) Concatenate Layer. As follows, these six-layer types were combined to make a complete U-Net architecture:

The raw pixel values of all the sub-images with four bands are copied to the training model using the INPUT layer. CONV layers use a collection of filters to determine the outputs of neurons. ‘‘ConvTrans’’ is a transposed convolution matrix, which increases the size of a smaller matrix by up-sampling it. To be able to filter out sub-images, the filter weight and length must be less than those of the input sub-images. The filter traveled from one end of the sub-images to the other. Each time an input is supplied, new pixel values are calculated by using the functions assigned to the filters (more detailed in section 2.4). Based on a proposed idea in the work by [36], [38], the authors used a total of 19 CONV layers in this study. To keep training and validation time to a minimum, the 19 CONV layers utilize filters ranging from 16 to 256. Each filter has a width and length that are set to 3*3.

After all CONV layers have been trained, converting data from one scale to another before arriving to a new computation is one usage of the BATCH NORMALIZATION layer. This layer is used to minimize the changes in activation functions when they are distributed during training. This issue is sometimes referred to as an internal covariate shift [39]. the four parameters that comprise the batch normalization will be employed. Using the mean (β) and standard deviation (or variance - γ) parameter of the data in the current batch, the current batch-specific mean and standard deviation are

applied to each input layer to normalize it.

$$y_i = \gamma \hat{x}_i + \beta \tag{1}$$

whereas the β and γ are trainable parameters, \hat{x}_i can be calculated by using mean (μ_B) and variance (σ_B^2) of mini-batch $B = \{x_1 \dots x_m\}$ as the following Equation 2-4:

$$\mu_B \leftarrow \frac{1}{m} \sum_{i=1}^m x_i \tag{2}$$

$$\sigma_B^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_B)^2 \tag{3}$$

$$\hat{x}_i \leftarrow \frac{x_i - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}} \tag{4}$$

- POOL layer resized width and height of data to a 2×2 spatial matrix based on downscaling process.

- Concatenate layer is utilized to merge the pieces of data on a contracting path with the information on an expanded path [35]. When the data for the prior layers was first contracted, it was simplified in order to facilitate the acquisition of fresh data, which allowed the U-Net models to integrate the data from the previous layers to generate a more accurate forecast.

- Instead of training the data on the original network, the DROPOUT layer randomly deactivates the neurons. Deactivating superfluous neurons reduces overfitting and generalization mistakes. A dropout value of 0.5 is often used to keep every node’s output in a concealed layer. A value close to 1.0 is often used to retain visible layer inputs [40].

The blocks in green color shown in Figure 2 are the input and output of each calculation layer, whereas the processing layers are presented in arrows. Excepting the last convolutional layer, the other 18 CONV layers are always processed before the batch normalization layers. In the contracting path,

the POOL layers run before the Dropout layers to downscale data. Meanwhile, the transposed convolution matrixes integrated with the Dropout layers are used for the upscaling process in the expansive layers.

The final Conv2D layer's output is a vector with six values, corresponding to 2 land cover types corresponding to coffee and non-coffee land covers. Based on 76 layers (1xINPUT, 19xCONV, 4xConv2DTrans, 4xPOOL, 18xBatch-Normalization, 4xConcatenate, 18x Activation, and 8x Dropout layers), the trained U-Net transformed the initial pixel values in input sub-images to the land cover classes. 23 CONV and 18 Batch Normalization layers contain parameters that can be optimized to improve U-Net model's performance and accuracy. The parameters in the CONV and Batch Normalization layers are changed with alternative choices of activation and optimizer functions. It will be explained in detail in section 2.4. The accuracy of both training and testing data was checked during U-Net development to avoid overfitting and under-fitting issues. The best U-Net will be chosen if it is land cover prediction is compatible with the labels assigned in the input image from the training and testing data. The equation 5 were used to calculate the accuracy of all training models:

$$ACC = \frac{2TP}{2TP + FP + FN} \quad (5)$$

TP and FP are the true/false positive values, whereas TN and FN are true/false negative values between prediction and ground truth points. In order to better identify mining ecosystem types, we will use a trained model that has the lowest values of all loss functions. The min and max ACC values for training and testing data were collected for the duration of 50 epochs throughout the training phase to study how the ACC fluctuated. Even though the optimal ACC value will be computed in the trained models, the ACC value observed to verify the correctness of outcome models would still use training data.

Minimizing the Cost function (C) or Loss function, which are both convex functions, involves selecting optimal values for the weights [41]. Weight values, training pictures, and labeled output results all have a role in the loss function. Furthermore, the weight values may help to minimize the loss function, which ultimately helps to provide better predictions for future training data. Accordingly, When the full training sub-image data set was put in, the average loss values were calculated by the sixth equation:

$$\mathcal{J} = \frac{1}{n} \sum_{x=1}^n \mathcal{L}^{(x)} \quad (6)$$

with n denoting the size of the training data collection and $L(x)$ denoting the loss value associated with a particular training sub-image during the training phase.

The U-Net model is created using the Keras API, which makes it simple to manipulate using Tensorflow - the Google-developed open-source machine learning framework [42], [43], [44]. During training, we measure the performance criteria that include test and validation accuracy. The

U-Net training procedure can go no farther than 100 loops (or epochs - times through the training data), however if the coefficient on the training data set converges, the process may be terminated.

E. OTHER METHODS FOR MODIFYING U-NET FRAMEWORK

To build the U-Net, three kinds of functions may be chosen: analyzing input size and optimizer technique. These functions choose optimum parameters for hidden layer filters during new prediction. Firstly, the analyzing size of sub-images that were cut from the original images with four bands can decide whether the computer can identify all characteristics of objects or not. If the sub-image size is small, although the computer has more samples for training and testing, the coffee region cannot be fully on one sub-image and the computer cannot learn all characteristics of this region, leading to the reduction of accuracy. However, the higher sub-image size can provide more information for the computer to identify coffee tree objects, it can reduce the number of input samples. Therefore, it requires more samples for training and testing data. Additionally, a large sub-image can contain much information of other objects. It also can make noise in the region between two objects. In this study, three options of input sizes were chosen are $64 \times 64 \times 4$; $128 \times 128 \times 4$; and $256 \times 256 \times 4$.

To remove the cost functions, optimization techniques using a stochastic gradient descent algorithm are frequently used. This technique improves accuracy and reduces loss by updating weights in the negative gradient direction [45], [46]. During optimization, the trained models' (or loss function's) errors must be computed frequently. Each epoch of data flowing through the U-Net model requires updating the weights of filters depending on optimizer functions [16]. It will use the previous parameters' gradient decline to determine the best position for the new ones. Thus, the new filter weight will be computed using the updated parameters. The new filters may distinguish virtually identical objects on satellite images, lowering the next evaluation's loss value. Filter settings and weights directly influence the 19 CONV layers during U-Net construction. Four optimizer functions were chosen for comparison in this study include: (1) Adam (Adaptive Moment Estimation), (2) Traditional SGD (Stochastic Gradient Descent algorithm), and (3) Adagrad (Adaptive Gradient Algorithm), and (4) Adadelta. Table 1 describes various optimization methods. Final results should be greatest accuracy and lowest loss function values.

F. COFFEE LAND COVER CHANGES USING TRAINED U-NET MODELS

One of the most essential functions of coffee classification system is to assess the changes of this land use/cover over-time [22]. This research examines the changes of coffee land cover types in Central Highland region, Vietnam. Due to the Sentinel-2 sensor was launched since 2014 and the cloud and shadows affected land covers in mountainous areas,

TABLE 1. Different optimization algorithms for training parameters of the U-Net model in coffee classification, adapted from [43], [44], [45], [46], [47].

Formula	Models	Optimizer options	Algorithms
7	UN-Adam	Adam	$\theta_{t+1} = \theta_t - \frac{\eta}{\sqrt{\hat{s}_t + \epsilon}} \hat{f}_t$
8	UN-SGD	SGD	$\theta_{t+1} = \theta_t - \eta_t \cdot \nabla_{\theta} Q(\theta_t; x^{(i)}, y^{(i)})$
9	UN-Adagrad	Adagrad	$\theta_{t+1} = \theta_t - \frac{\eta}{\sqrt{G_t + \epsilon}} g_t$
10	UN-Adadelta	Adadelta	$\Delta\theta = -\frac{RMS[\Delta\theta]_{t-1}}{RMS[g]_t} g_t$ and $\theta_{t+1} = \theta_t + \Delta\theta_t$

θ – parameter value; η – the learning rates; t – time step; $\epsilon = 10^{-8}$; g_t is – gradient; f & s – estimates of first and second moments; η – step size.

54 images were collected from 2019 to 2021 to assess the changes of coffee land cover during three years. Furthermore, section 2.2 and 2.3 describes images gathering and pre-processing as well. The new image was fed into the trained U-Net, and then the model accessed the trained parameters to generate 76 intermediate matrixes. In addition, the model applies the trained spatial matrices to transform the new images into specific spatial matrices and generates the final land cover classes for every pixel. No further training data is required.

III. RESULTS

A. MODEL PERFORMANCE IN MODEL TRAINING PROCESS

12 U-Net models were trained using a variety of different training sizes, filter counts, and optimizer strategies. To compare the performance of these U-Net models, the total accuracy and loss function values were employed (Table 2). Although there was no evident trend in the loss and accuracy values as the training size increased, the training size of $256 \times 256 \times 4$ produced the more accurate prediction in all situations of the optimizer approaches. In four different types of optimizer algorithms, the UNet-SGD models performed the least well. These models typically have an average loss value of 0.41 and an average accuracy of 80%. Compared to the models using SVM and Random Forest methods, all 12 trained U-Net models provided a higher accuracy although their training time is significantly longer.

Five U-Net models achieved greater than 94% accuracy: UNet-Adam-64, UNet-Adam-256, UNet-Adadelta-128, UNet-Adagrad-128 and UNet-Adagrad-256. The UNet-Adadelta-128 model, in particular, was found to perform the best, with an accuracy of nearly 95 percent and a loss function value of 0.12. (Figure 3 and Table 2). By and large, the values of the loss and accuracy fluctuated over the first 15 epochs before converging over the final 50. The UNet-Adam-256 model has a speedier convergence procedure. The UNet-Adagrad-128 and UNet-Adadelta-128 model were trained in nearly 40 minutes, slower than other models. Meanwhile,

TABLE 2. The performance of 14-trained models for classify coffee land cover.

No.	Model	Training size	Loss	Accuracy	Training time (s)
1	Unet-Adam-64	64	0.13	94.3	1443
2	Unet-Adam-128	128	0.14	93.6	2607
3	Unet-Adam-256	256	0.12	94.9	2081
4	Unet-Adadelta-64	64	0.15	93.3	1230
5	Unet-Adadelta-128	128	0.12	94.9	2373
6	Unet-Adadelta-256	256	0.26	88.1	1098
7	Unet-SGD-64	64	0.32	85.7	904
8	Unet-SGD-128	128	0.53	72.4	863
9	Unet-SGD-256	256	0.4	82.1	983
10	Unet-Adagrad-64	64	0.16	93.5	1482
11	Unet-Adagrad-128	128	0.13	94.2	2323
12	Unet-Adagrad-256	256	0.14	94.2	2036
13	SVM			68.9	762
14	Random Forest			65.4	645

while the UNet-Adam-64 model was trained in more than 24 minutes but its performance is the lowest, compared to others.

B. MODEL PERFORMANCE IN NEW INTERPRETATION

Due to the model performance values of the best five U-Net models are nearly similar, they were used to interpreted coffee land cover in the Central Highlands, Vietnam. Based on 54 Sentinel-2 images, three large images with nearly 55,000km² was generated for three years (2019, 2020 and 2021). The models using $64 \times 64 \times 4$ input images took more than 100 minutes for new interpretation. The models using $128 \times 128 \times 4$ input images interpreted new data three time faster than the Unet-Adam-64 model (Table 3). Meanwhile, the models with $256 \times 256 \times 4$ input images are six times faster than the Unet-Adam-64 model at processing new data. In Figure 4, the coffee land covers were separated well with residential and forest areas. Meanwhile, the wetland areas could not be separated well by the U-Net-Adagrad-128 and U-Net-Adagrad-256 models. Two models using Adam optimizer functions interpreted commercial polyculture coffee land cover that is mixed by more than one species of shade trees. As a result, the U-Net-Adadelta-128 mode provide more accurate results in more than 35 minutes per one image for all cases than other models.

C. COFFEE LAND COVER IN VIETNAM

The coffee land cover maps in the Central Highlands, Vietnam in 2019, 2020 and 2021 are shown in Figure 5. In five results, the U-Net-Adam-64 model interpreted a narrow area of the coffee land cover, especially in 2021, the coffee area of only 440,000 ha was identified. The interpretation from

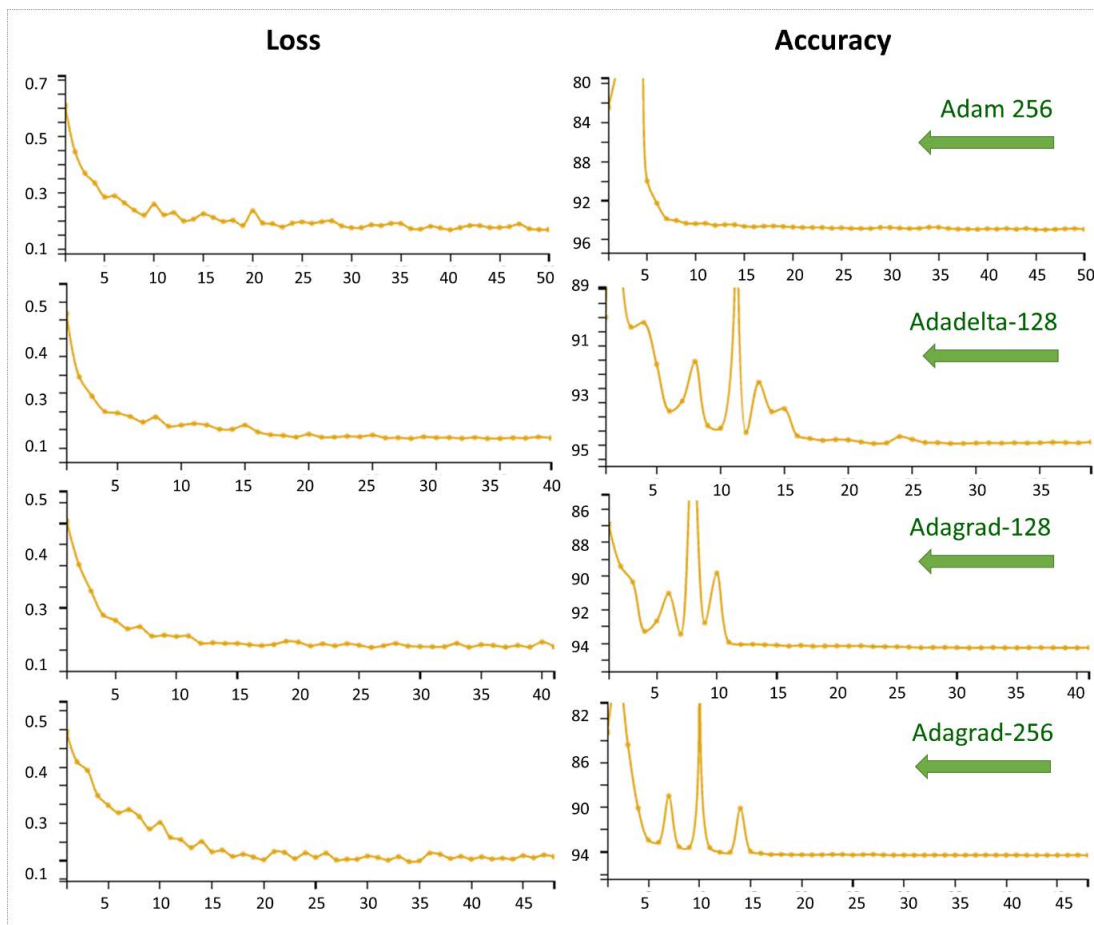


FIGURE 3. The training process over 50 epochs of the best for U-Net models for coffee classification.

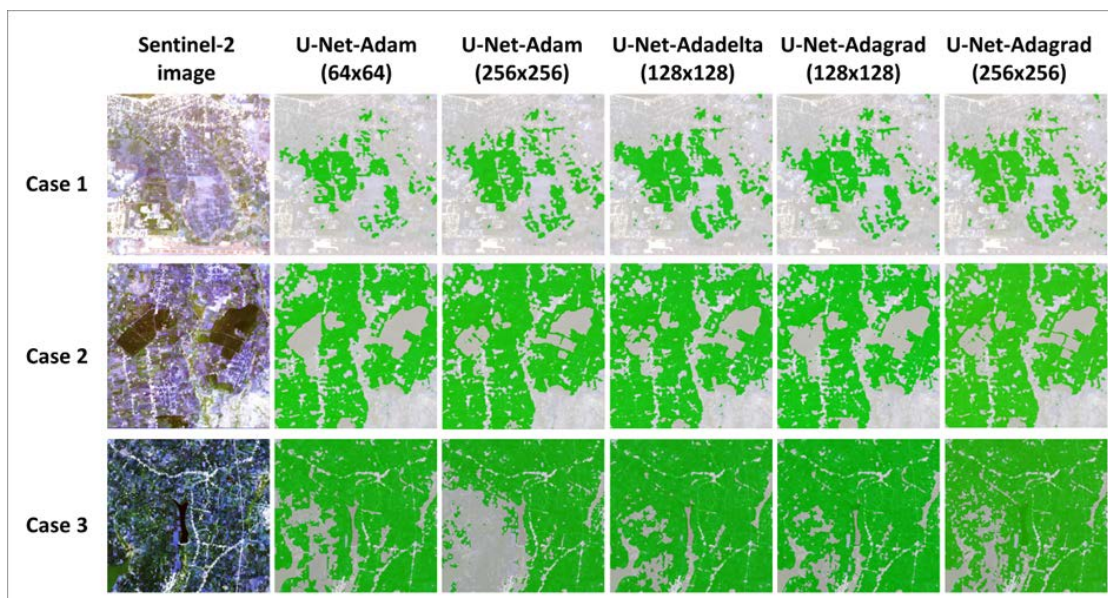


FIGURE 4. Coffee land cover classification in Central Highland province, Vietnam based on the best five U-Net models.

U-Net-Adam-256, U-Net-Adagrad-128 and U-Net-Adagrad-256 models has more fluctuated with an increase in 2019 and

a decrease in 2020. Meanwhile, the coffee area in the research area has been increasing slightly since 2015 (Figure 6). The

TABLE 3. Interpretation time of the best-five u-net models for coffee land cover.

No.	Optimizer	Time to analyze Sentinel-2 image (s)		
		2019	2020	2021
1	Unet-Adam-64	6,496	5,212	6,585
2	Unet-Adam-256	1,245	1,101	1,279
3	Unet-Adadelta-128	2,119	1,189	2,249
4	Unet-Adagrad-128	2,140	1,797	2,240
5	Unet-Adagrad-256	1,265	1,032	1,275

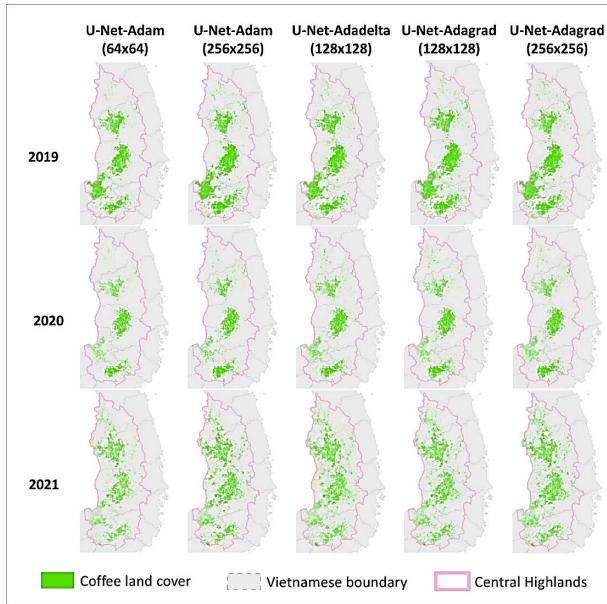


FIGURE 5. Coffee land cover interpretation based on the trained U-Net models using the best five optimizer functions in the Central Highlands, Vietnam.

outcome from the U-Net-Adadelta-128 model is close to the recorded from the statistical report when the area of the coffee land cover was interpreted at 694, 566 and 726 thousand hectares, respectively for the years 2019, 2020 and 2021. The significant reduction of the coffee plantation area was recorded in statistical data, as well as in the interpretation from all U-Net models. Since local statistics often only update the total area of coffee plantations, including the area of newly harvested and newly planted trees, it causes a discrepancy between the interpretation results and the statistical data. In general, the fluctuation trend of the coffee plantation area interpreted from U-Net models is harmonized with the statistical report data.

IV. DISCUSSION

A. ADVANCE OF DEEP LEARNING MODELS FOR COFFEE DETECTION

Separation of coffee plantation area from other land uses/covers is directly related to local water quality and land management, help to predict precisely the annual quality

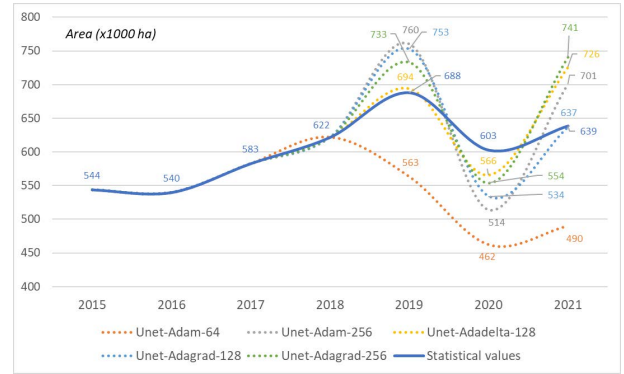


FIGURE 6. Areal changes of coffee land cover based on interpretation from the best five U-Net models and statistical reports.

and productivity of this industrial plant. Several researchers, including [48], [49], [50], [51], all used low/medium-spatial resolution satellite images for classify coffee plantation area mixed with different land covers, instead of separating coffee plantation area from all others in this study. The accuracy of coffee separation reached about 58% with the use of Landsat TM data [50]. The polyculture coffee system in Vietnam is planted in high heterogeneity areas, which are known to be hard to detect due to lack of spatial information. The research took specific characteristics of the Sentinel-2 images, such as texture, shape, and spatial distribution to train final U-Net prediction models. Therefore, the input samples collected for pixel-based classification is ineffective to serve as a mask. In this study, a mask was created in the form of an object generalization for training U-Net models. According to the results, this study proved that the modified U-Net architecture is able to generate coffee land cover maps that outperform Random Forest and SVM benchmark classifications.

Additionally, the conventional approach shows a better performance in identifying coffee plantation area from digital images using trained U-Net models. Related to the time and effort expense, scientists usually interpret land-use types from satellite images by using a lots of ground control points. For the whole interpretation process, they must put in a lot of effort in both your working environment and living space. Therefore, a land-use map for a given period may take as long as a month or a year. Additionally, the collected ground control points cannot be used for new regions. Based on the DL models, users may now quickly produce coffee plantation maps using trained U-Net-Adadelta-128 model (about 30 minutes for 55,000 km² in this study). Additionally, the trained models might be utilized in other coffee regions based on free satellite images obtained from the Sentinel-2 sensor.

B. UPDATING COFFEE DETECTION MODELS

In the model development process, the comparison between the model outcomes with the field surveys showed that 6.4% of the coffee area is difficult to be classified with other types. Therefore, the initial sample was updated before the standard input data for the models were obtained. Compared

with the field sites, some areas of coffee growing for about 7-8 years (1) are cut down for new development, or (2) converted from low-yielding old coffee areas to other perennial cash crops were classified into annual crops and bare ground. In the study area, some annual trees are intercropped with the coffee trees, that has not yet closed its canopy. So, when the annual trees are harvested, the area that is mixed with the coffee trees. According to the growth cycle, old coffee is cut down after about 15 years and planted with other annual trees. On the other hand, coffee in the Central Highlands is often intercropped with many different types of shade trees such as cashew, pepper, fruit trees, etc., except in more homogeneous farming areas. Therefore, it is difficult for coffee in the Central Highlands to separate each type of coffee that is intercropped with other large trees in the image classification process. In the process of classifying the current state of the coffee land cover, the area of young coffee was included in the annual tree class. The area of young coffee that has not yet closed its canopy was separated from the annual tree when analyzing the series of fluctuations in many time periods. While classifying the area of coffee trees, it was found that most of the errors of the coffee class were related to annual trees, bare land and sparse forest and shrubs. The results showed that the newly planted coffee areas have similar reflectance spectrum with the annual tree class. In the Central Highlands, some annual trees are intercropped with the area of unclosed coffee, so when classifying this area of young coffee, it was confused with the annual crop. These issues reduced the accuracy of the models significantly. To improve this issue, it is better to use the multi-temporal remote sensing images to detect the area of other annual plants in the research study.

The fact is that 80% of the coffee area in Dak Lak is owned by households, so it is difficult to form a homogeneous and sustainable production. In order to improve this issue, managers need to conduct a clear review and assessment, to remove unsuitability areas for cultivating coffee trees. In addition, the government should ban the spontaneous development of coffee outside the planning area; encourage the expansion of certified coffee production programs. Therefore, the supporting high-tech tools based on AI models and multi-temporal remote sensing images can completely help with these tasks. For example, AI models that select ecologically suitability areas for coffee trees, whereas other models can be developed to monitor the area of coffee trees using high-resolution satellite images based on unmanned aerial vehicles. It can become a promising approach for the sustainable development of the coffee production in tropical countries in the future.

V. CONCLUSION

Based on the application of a U-Net model to categorize coffee plantation areas in the Central Highlands, Vietnam, the individual study questions stated in the introduction section were addressed. The combination can save the time and

expense to collect samples when land-use planning managers, scientists, and other users require to interpret coffee plantation areas from updated Sentinel-2 images. Once a U-Net model is trained completely, the new samples can be updated to the model and be used to analyze rapidly new data. The best U-Net model with a nearly 95% accuracy rate interpreted effectively the location of the coffee plantation area in the largest coffee exporter region in Vietnam, using data acquired from the Sentinel-2 data. The outcomes from the U-Net-Adadelta-128 model are in harmony with the records from statistical reports. In the future, this model can become a promising tool for forestry managers in charge of coffee plantation management.

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CONFLICT DECLARATION

Authors have no conflict of interest.

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