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An Efficient Approach With Application of Linear and Nonlinear Models for Evaluation of Power Transformer Health Index

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ABSTRACT In this paper, efficient and accurate linear and nonlinear models are proposed for indicating comprehensive health requirements of the transformer using health index (HI) concept. The models are established with 336 experimental datasets including oil characteristics and dissolved gas analysis (DGA) of various types of transformers placed in different areas. The significance of DGA parameters in transformer health condition is considered with the inclusive DGA factor (*DGAF*) parameter, which considers the weighting importance of seven dissolved gases. Nonlinear models used in this paper are artificial neural network (ANN) and adaptive neuro-fuzzy inference system (ANFIS), which represent the behavior of transformer insulation parameters. The nonlinear models are compared with multiple linear regression (MLR) which is a linear statistical model. The models are established with 80 percent of the experimental dataset. The other 20 percent of data are utilized for the efficiency assessment of the models. The results demonstrate that the models provide an assessment of the health condition of the transformers comparable to existing models with high accuracy. The contributions of this paper are: 1) Evaluating the overall HI of the transformer employing a complete set of 15 input parameters of transformer oil-paper insulation system. 2) Adding *DGAF*, *%WaterPaper*, *IFT* parameters and showing the importance of these parameters. 3) Regarding the condition of solid insulation of the transformer particularly. 4) Applying a diverse and large practical dataset composed of 336 different transformers located in different country areas. 5) Using the MLR method for three purposes. 6) Providing linear (MLR) and nonlinear (ANN, ANFIS) models for HI calculation of the dataset, simultaneously. 7) Verifying the applicability and efficiency of the ANFIS model for simulating HI value.

INDEX TERMS ANFIS, ANN, condition assessment, health index, lifetime management, MLR, oil-paper insulation system, power transformer.

I. NOMENCLATURE

HI	Health Index
DGA	Dissolved Gas Analysis
MLR	Multiple Linear Regression
ANN	Artificial Neural Network
ANFIS	Adaptive Neuro-Fuzzy Inference System
SVM	Support Vector Machine
<i>DP</i>	Degree of Polymerization
<i>CO₂</i>	Carbon dioxide

<i>CO</i>	Carbon monoxide
<i>H₂</i>	Hydrogen
<i>CH₄</i>	Methane
<i>C₂H₂</i>	Acetylene
<i>C₂H₄</i>	Ethylene
<i>C₂H₆</i>	Ethane
<i>IFT</i>	Interfacial Tension
<i>BDV</i>	Breakdown Voltage
<i>DF</i>	Dissipation Factor at 90°C
<i>Water</i>	Water content in oil at 20°C
<i>%WaterPaper</i>	percent Water in Paper insulation
<i>DGAF</i>	DGA Factor

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<i>TDCG</i>	Total Dissolved Combustible Gas
<i>DCG</i>	Dissolved Combustible Gas
<i>ITRI</i>	Iran Transformer Research Institute
<i>S_i</i>	the score value according to the volume of dissolved gases
<i>W_i</i>	the weighting factor of the dissolved gases
<i>k_j</i>	the value of the <i>jth</i> input parameter
<i>c₀</i>	regression constant
<i>c_j</i>	coefficient of the <i>jth</i> input parameter
<i>p</i>	the number of input parameters
<i>LM</i>	Levenberge-Marquardt
<i>BP</i>	Back-Propagation
<i>a_j</i>	the output of the <i>jth</i> hidden neuron
<i>w_{ij}</i>	the connection weight between input and hidden layer
<i>r</i>	the number of input layer neurons
<i>x_i</i>	the input of the hidden layer
<i>b_j</i>	the bias of the hidden layer
<i>S</i>	the number of hidden layer neurons
<i>w_{jk}</i>	the connection weight between hidden and output layer
<i>b_k</i>	the bias of output layer
<i>a_k</i>	the final output
<i>MF</i>	membership function
<i>TSK</i>	Takagi-Sugeno-Kang
<i>m</i>	the number of rules
<i>A_{ij}</i>	the <i>jth</i> fuzzy set of the <i>ith</i> rule
<i>p_{iq}</i>	consequent parameters of the <i>ith</i> rule
<i>μ_{A_{ij}}</i>	a fuzzy membership function type
<i>c_{ij}</i>	premise parameter which explain Gaussian MF center
<i>σ_{ij}</i>	premise parameter which explain Gaussian MF width
<i>w_i</i>	the firing strength of the <i>ith</i> rule
<i>w̄_i</i>	normalized firing strength of the <i>ith</i> rule
<i>RMSE</i>	root mean squared error
<i>R²</i>	coefficient of determination
<i>MAE</i>	mean absolute error
<i>MRE</i>	mean relative error
<i>y_i^{exp}</i>	the experimental output value for the <i>ith</i> set of data
<i>y_i^{prd}</i>	the predicted output value for the <i>ith</i> set of data
<i>ȳ^{prd}</i>	the average of predicted output values
<i>n</i>	number of samples in the dataset
<i>h_i</i>	leverage value for the <i>ith</i> set of data
<i>e_{s,i}</i>	standardized residuals for the <i>ith</i> set of data
<i>N. Value</i>	normalized Health Index value

II. INTRODUCTION

A. PROBLEM STATEMENT

Continuous performance of power transformers is necessary to maintain the reliability of the power transmission and distribution network. Aging along with changes in loading conditions, weather conditions, faults, and other electrical, chemical, and mechanical stresses, accelerate insulation deterioration of the transformers. Power transformer lifetime

depends directly on the condition of the transformer insulation. Condition assessment of power transformer is necessary to extend transformer lifetime with detecting any probable failure and poor health condition. Some maintenance strategies are developed based on a comprehensive and simultaneous survey of different dissolved gas analysis (DGA) and oil quality related parameters [1]–[3].

The condition of each oil characteristic represents just one feature of the transformer insulation condition using the limits of the parameters related to DGA [4], [5] and oil quality [6]–[9] tests given in standards. But to make proper decisions, the operator needs the comprehensive health assessment of the transformer insulation system and investigation of all DGA [10] and oil-quality parameters. Therefore, some efficient methods are required that can be trained from network history and employed to assess the comprehensive health status of power transformers.

In this paper, the parameters collected from the site and laboratory diagnostic tests, operating observations, and field inspections are utilized for assessing the comprehensive health status of the transformer. The oil-quality test parameters are: breakdown voltage (kV), dissipation factor at 90°C, acidity (mg_{KOH}/g_{oil}), interfacial tension (mN/m), water content in oil at 20°C (ppm), percent water saturation of oil, percent water in paper insulation, degree of polymerization (*DP*), furfural content (ppm), and the DGA test parameters are *CO*, *CO₂*, *H₂*, *CH₄*, *C₂H₂*, *C₂H₄*, and *C₂H₆* gases contents.

Health Index (HI) is the methodology of incorporating different features data to obtain a quantity value for comparison of the comprehensive status of the transformers. The utility uses HI to distinguish between degradation, which requires maintenance schemes, and degradation which demonstrates end of life defined as *DP*=200. HI tool employs the expert's skill to forecast future operation, replace procedures and failure probabilities. HI quantifies the transformer condition based on multiple condition criteria related to the long-term degradation factors that cumulatively results the transformer's end of life.

B. LITERATURE SURVEY

The Health Index concept for assets as we know today is introduced first time by Hughes [11], and continued in [12] with risk factors included in the index which provides a composite health index for network assets, and then used extensively in [13] to describe the impact of preventative maintenance on health index and predict future asset condition based on the current health index and maintenance practices.

After discussing HI for general transmission and distribution assets, an approach to determine the health index especially for power transformers is presented in [14] which shown a realistic and detailed Health Index formulation method for power transformers. For this purpose a simple linear weighting system is used for each parameter, whereas the actual weighting, scoring and limits could vary from one power utility to the other [15], [16].

Some literature provide the incipient fault diagnosis for the transformers and a health index that represents the overall health condition of the transformers with investigation of all DGA and oil-quality parameters altogether is not regarded in them [17]–[21].

HI has been used to evaluate the health status of the transformer in several studies [13]–[16], [22]–[33]. The information required for extracting transformer assessment different indices is presented in the CIGRE 761 technical brochure [34].

Artificial intelligence algorithms such as fuzzy logic [15], fuzzy SVM [16], synthetic minority over-sampling technique [22], binary cat swarm optimization based SVM [23], and multi-agent system [35] are used to obtain transformer health condition. Neural network [17], [18] and neuro-fuzzy [19]–[21] methods are utilized to detect the fault condition of the transformers. A feature selection method using classification techniques to extract the most effective parameters to determine the HI condition is presented in [24]. In [25] at first, statistical analysis of the transformer data is done, and then the HI approach is given for the transformer maintenance. A probabilistic method for transformer HI calculation to deal with data uncertainty is presented in [26], [27]. In [28], the HI decreasing rate is considered to improve the transformer condition assessment. Some regression-based models are simulated for HI prediction in [29]. A statistical distribution method is applied to predict the HI of transformers in [30]. A procedure of calculating health index for oil-paper transformers using binary logistic regression is presented in [31]. A decision-support model determine assets needing additional maintenance or replacement by failure mode and effect analysis is presented in [32]. In [33] the orthogonal wavelet network is used to estimate transformer Health Index using transformer test results. Economic parameters include in the assessment to use the health index result to prioritize maintenance activities is presented in [36].

Some important literature related works are categorized in terms of the input data, classification methods, aggregation methods, output type, advantages and disadvantages of each reference in Tables 1 to 3. Comparison of input data categories for some sample literature are given in Table 1. Comparison of classification methods and aggregation methods for the same sample literature are shown in Table 2. Comparison of output type and advantages and disadvantages for the same sample literature are described in Table 3.

The originality and contributions of the proposed work with respect to the literature to overcome the research gap findings is explained in detail in the next subsection.

C. MAIN CONTRIBUTIONS

In this study, three efficient methods have been proposed for transformer HI calculation. Multiple Linear Regression (MLR) model is developed to obtain the best fit of data using linear regression [37], [38]. MLR method models the linear relationship between HI and transformer insulation parameters. Also, in order to consider the nonlinear

relationship between model parameters, Artificial Neural Network (ANN) and Adaptive Neuro-Fuzzy Inference System (ANFIS) models are used for transformer HI calculation. The different models are implemented using 336 experimental datasets, and their performances are compared.

The originality and the principal contributions of the paper with respect to the literature are addressed as follows:

- I) Evaluating the overall HI of the transformer employing a complete set of eight input parameters of transformer oil-paper insulation system including physical, chemical, mechanical, and electrical aspects of transformer insulation condition. One of the input parameters of this paper is *DGAF* which includes seven dissolved gases with their importance weightings. So, in this paper 15 input parameters are utilized for construction of the models. An increase in the amount of input data results in an improvement of the model's performance.
- II) Utilizing *DGAF* parameter instead of *TDCG* [4] (total dissolved combustible gas), and adding two significant parameters including *IFT* (Interfacial Tension) and *%WaterPaper* (percent Water in Paper insulation) to the input parameters in comparison with the previous works. The importance of adding *DGAF*, *%WaterPaper*, *IFT* parameters is shown with the importance ranking of the input parameters obtained in the results section using the efficient MLR method.
- III) Regarding the condition of solid insulation of the transformer particularly. Due to the importance of paper insulation condition influence on the overall HI of the transformer, in addition to *Furfural* and *CO*, *CO₂* gases, *%WaterPaper* is also considered to monitor accurately the insulating paper condition.
- IV) Applying a diverse and large practical dataset composed of 336 different transformers located in different country areas stabilizes the model to predict a more accurate HI value for each new data.
- V) Using the MLR method for three purposes. Firstly, MLR detect the outliers and bad influential points, which cause problems in model construction. Secondly, the weighting coefficients of the linear model are derived with a reliable and accurate statistical MLR method using the large and diverse dataset. Thirdly, the predicted HI values are obtained by MLR model.
- VI) Providing linear (MLR) and nonlinear (ANN, ANFIS) models for HI calculation of the dataset, simultaneously. A comprehensive assessment is presented comparing three efficient methods with different essences for the HI calculation, including statistical regression and artificial intelligence models to evaluate the performance of the proposed work.
- VII) Verifying the applicability and efficiency of the ANFIS model for simulating HI value using the experimental diverse dataset including 336 set of diagnostic test parameters of power transformers. Also, the results of ANFIS and ANN are compared with each other and with MLR model. Also, the comparison with the

TABLE 1. Comparison of input data categories for some sample literature.

Ref No.	Year	Number of input parameters	Input data										
			Gases in oil				Oil insulation quality					Paper insulation quality	
			Individual gases ¹	Gas ratios	TDCG [4]	DGAF	BDV	DF	Acidity	IFT	Water	Furfural	%WaterPaper
[14]	2009	24	x	x	x	✓	x	✓	✓	✓	✓	✓	x
[15]	2012	6	x	x	✓	x	✓	✓	✓	x	✓	✓	x
[16]	2013	12	✓	x	x	x	✓	✓	✓	x	✓	✓	x
[17]	2003	8	✓	✓	x	x	x	x	x	x	x	x	x
[19]	2012	4	x	✓	x	x	x	x	x	x	x	x	x
[20]	2015	3	x	✓	x	x	x	x	x	x	x	x	x
[21]	2013	3	✓	✓	x	x	x	x	x	x	x	x	x
[22]	2014	12	✓	x	x	x	✓	✓	✓	x	✓	✓	x
[24]	2018	9	✓	x	x	x	✓	x	✓	x	✓	✓	x
[25]	2019	11	x	✓	✓	x	✓	x	x	✓	x	x	x
[27]	2021	9	✓	x	x	x	✓	x	✓	✓	✓	✓	x
[28]	2021	9	✓	x	x	x	✓	x	✓	✓	✓	✓	x
[29]	2021	6	x	x	✓	x	✓	✓	✓	x	✓	✓	x
[31]	2016	6	x	x	✓	x	✓	✓	✓	x	✓	✓	x
[32]	2015	-	x	x	x	x	x	x	x	x	x	x	x
[33]	2015	11	✓	x	x	x	✓	✓	✓	x	✓	✓	x

¹ individual gases means seven dissolved gases including H₂, CH₄, C₂H₆, C₂H₄, C₂H₂, CO and CO₂ are used separately and the degree of importance and weighting factors of gases are not regarded.

TABLE 2. Comparison of classification methods and aggregation methods for some sample literature.

Ref No.	Classification method	Aggregation method								
		Weighted Score Sum	Statistical regression	Worst case	Artificial Intelligence					
					Neural Network	Fuzzy logic	Neuro-Fuzzy combination	ANFIS	Wavelet	
[14]	x	✓	x	x	x	x	x	x	x	x
[15]	x	x	x	x	x	✓	x	x	x	x
[16]	FSVM	✓	x	x	x	x	x	x	x	x
[17]	x	x	x	x	✓	x	x	x	x	x
[19]	x	x	x	x	✓	x	x	✓	x	x
[20]	x	x	x	x	x	✓	x	✓	x	x
[21]	x	x	x	x	✓	✓	✓	✓	x	x
[22]	C4.5, KNN, RBF, SVM	✓	x	x	x	x	x	x	x	x
[24]	RForest, J48, SVM, MLP, kNN	x	x	x	x	x	x	x	x	x
[25]	x	✓	x	x	x	x	x	x	x	x
[27]	x	✓	x	x	x	x	x	x	x	x
[28]	x	✓	x	x	x	x	x	x	x	x
[29]	x	x	✓	x	x	x	x	x	x	x
[31]	x	x	✓	x	x	x	x	x	x	x
[32]	x	x	x	✓	x	x	x	x	x	x
[33]	x	x	x	x	x	x	x	x	x	✓

previous works is made to indicate the accuracy of the presented models. The reason of superior efficiency results of the ANFIS model is due to combining the learning capabilities of neural network and reasoning capabilities of fuzzy logic.

D. PAPER LAYOUT

The remainder of this paper is organized as follows: in Section 2, the dataset including parameters of the transformer diagnostic tests are illustrated. In Section 3, the methodology including MLR, ANN and ANFIS formulation and implementation for determining the HI of the transformer oil-paper insulation system, and error criteria for comparing the models are presented. The results which show the

applicability of the developed ANFIS in predicting transformer HI and comparison of the models based on their deviation (error) from the experimental HI are provided in section 4, followed by the conclusion in Section 5.

III. DATASET OF TRANSFORMER INSULATION PARAMETERS

In this paper, a comprehensive dataset is utilized. The dataset is composed of 336 DGA and oil characteristics test reports of various transformers. The voltage levels and power ranges of transformers in the dataset are different. The transformers are located in varying weather and operating conditions. This dataset includes advanced diagnostic tests of power transformers which are prepared by Iran Transformer Research

TABLE 3. Comparison of output and advantaged and disadvantages for some sample literature.

Ref No.	Output		Main contribution (Advantages)	Disadvantages
	Incipient Fault diagnosis	Health Index		
[14]	×	✓	1) Explaining HI concept in detail. 2) Providing weighing and scores for all-inclusive parameters of different parts of transformer from different aspects.	1) Lack of a specific case study with experimental data. 2) Need for artificial intelligence method to handle its numerous input parameters. 3) Not considering <i>BDV</i> , <i>%WaterPaper</i> parameters.
[15]	×	✓	1) Using real field data for 90 working transformers. 2) Designing membership functions and rules for fuzzy inference system.	1) Using <i>DCG</i> parameter for gases which is the simple sum of <i>DGA</i> gases values. 2) Not considering <i>CO</i> and <i>CO₂</i> gases which contain beneficial details concerning the degradation of paper insulation. 3) The degree of importance and weighting factors of gases are not regarded in <i>DCG</i> . 4) Not considering <i>DGAF</i> , <i>IFT</i> , <i>%WaterPaper</i> parameters.
[16]	×	✓	1) Dealing with the imbalanced training dataset. 2) Adopting majority vote strategy for deciding the final health index level from HIs obtained with four different method. 3) Addressing the details of classification method. 4) Increasing the accuracy of the classification method with SMOTE pre-processing method.	1) Considering individual gases separately. 2) Not using <i>TDCG</i> or <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 3) Not considering <i>IFT</i> , <i>%WaterPaper</i> parameters. 4) Using only one classification method and there is not a comparison between different methods. 5) Providing only HI levels from 1 to 5, and its continuous values are not given. 6) Not using the AI algorithms to handle the large dataset.
[17]	✓	×	1) Using the Evolving Neural Network method which automatically tune the neural network parameters with an evolutionary algorithm. 2) Identifying relationships among dissolved gas contents in transformer oil and corresponding fault types, using the global search capabilities of the evolutionary algorithm and the highly nonlinear mapping nature of the neural networks. 3) Comparing the results with the fuzzy diagnosis system, artificial neural networks, and the IEC/IEEE standards method.	1) Not using <i>TDCG</i> or <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 2) Not considering any of oil and paper insulation quality parameters. 3) Not providing a health index that represents the overall health condition of the transformers with investigation of all <i>DGA</i> and oil-quality parameters altogether.
[19]	✓	×	1) Obtaining fault type diagnosis results using conventional standards, ANN, and ANFIS methods, and comparing the results in detail. 2) Determining location of the fault by the <i>CO₂/CO</i> ratio. 3) Simultaneous fault type and fault location diagnosis using the ANFIS method.	1) Not using <i>TDCG</i> or <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 2) Not considering any of oil and paper insulation quality parameters. 3) Not providing a health index that represents the overall health condition of the transformers with investigation of all <i>DGA</i> and oil-quality parameters altogether.
[20]	✓	×	1) Developing fuzzy logic and ANFIS models for transformer incipient fault diagnosis. 2) Comparing the results of two models obtained with the limitations three standards.	1) Not using <i>TDCG</i> or <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 2) Not considering any of oil and paper insulation quality parameters. 3) Not providing a health index that represents the overall health condition of the transformers with investigation of all <i>DGA</i> and oil-quality parameters altogether.
[21]	✓	×	1) Using Neuro-Fuzzy scheme to identify the deterioration of the insulation paper of power transformer, and to compare its performance over conventional standard methods. 2) Considering <i>CO</i> , <i>CO₂</i> and <i>CO₂/CO</i> ratio to indicate the condition of transformer solid insulation.	1) Not considering <i>Furfural</i> and <i>%WaterPaper</i> important parameters to identify the condition of paper insulation. 2) Not considering other gas contents in oil and oil quality parameters to evaluate the overall health condition of transformers. 3) Not providing a health index that represents the overall health condition of the transformers.
[22]	×	✓	1) Improving the data quality of a training dataset with the SMOTEBoost data pre-processing method. 2) Integrating the SMOTEBoost with four different classification methods including SVM, C4.5, RBF, KNN and comparing the results.	1) Considering individual gases separately. 2) Not using <i>TDCG</i> or <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 3) Not considering <i>IFT</i> , <i>%WaterPaper</i> parameters. 4) Not providing HI values and levels for case study. 5) Not using the AI algorithms to handle the large dataset.
[24]	×	✓	1) Using feature Selection and classification techniques with five different classifier for HI assessment. 2) Comparing the accuracy of the classification methods. 3) Finding the most important measured features to estimate the transformer HI.	1) Not considering the <i>CO</i> and <i>CO₂</i> gases in the inputs. 2) Not using <i>TDCG</i> or <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 3) Not considering <i>DF</i> , <i>IFT</i> , <i>%WaterPaper</i> parameters. 4) Not providing HI values and levels for the case study. 5) Not using the AI algorithms to handle the large dataset.
[25]	×	✓	1) Using the parameters of Electrical, Mechanical, Thermal and Insulation degradation power transformer failure modes. 2) The several causes of failure against each component are detailed for in-depth understanding of maintenance personnel.	1) Not using <i>DF</i> , <i>Acidity</i> and <i>Water</i> parameters of oil insulation. 2) Not considering <i>%WaterPaper</i> and <i>Furfural</i> parameters to determine the solid insulation condition. 3) Not using the AI algorithms to handle the large dataset.
[27]	×	✓	1) Dealing with data uncertainty and unavailability for the transformer HI. 2) Determining the certainty level of the health index. 3) Developing <i>IFT</i> prediction model to handle the unavailable data.	1) Using the weighting factors for parameters to evaluate the HI may change the results if the calculation method of weighting factor is changed. 2) Not using <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 3) Not considering <i>DF</i> and <i>%WaterPaper</i> parameters. 4) Not using the AI algorithms to handle different parameters and the related certainty levels.
[28]	×	✓	1) Considering the trend of health index decreasing rate of transformers corresponding to the operating age. 2) Presenting the transformer risk assessment based on its health index value and the decreasing rate.	1) Using the weighting factors for parameters to evaluate the HI may change the results if the calculation method of weighting factor is changed. 2) Not using <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 3) Not considering <i>DF</i> and <i>%WaterPaper</i> parameters. 4) Not using the AI algorithms to handle different parameters and the related certainty levels.

TABLE 3. (Continued.) Comparison of output and advantaged and disadvantages for some sample literature.

[29]	×	✓	1) Presenting three regression models to determine the transformers HI.	1) Not using <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 2) Not considering <i>IFT</i> , <i>%WaterPaper</i> parameters. 3) Not using the AI algorithms to handle different parameters.
[31]	×	✓	1) Using binary logistic regression to calculate the transformer HI. 2) Observing the effect of deleting two pieces of input data on HI calculation.	1) Obtaining a binary output of healthy or unhealthy for the parameters of transformer. 2) Not using <i>DGAF</i> to consider the degree of importance and weighting factors of gases. 3) Not considering <i>IFT</i> , <i>%WaterPaper</i> parameters. 4) Not using the AI algorithms to handle different parameters.
[32]	×	✓	1) Providing asset health and risk model (AHRM) to prioritize assets requiring additional maintenance or replacement. 2) Using Failure Mode and Effect Analysis (FMEA) to provide information about the worst case scenario for a transformer's failure.	1) Not providing specifically detailed assessment functions. 2) Not providing any case study to evaluate the performance of the model. 3) Not clear which input parameters are used. 4) Not providing HI values and levels.
[33]	×	✓	1) Using Orthogonal Wavelet Network is used to estimate transformer Health Index.	1) Not considering <i>DGAF</i> , <i>IFT</i> , <i>%WaterPaper</i> parameters. 2) Not considering <i>CO</i> and <i>CO₂</i> gases which contain beneficial details concerning the degradation of paper insulation.

Institute (ITRI). It should be noticed that the dataset is not for 336 different transformers. Some sets of data may be related to a transformer in different time intervals. Diagnostic tests related to DGA and oil-paper insulation system are done on transformers placed in various districts of Iran. The transformers of the dataset are applied in different industries and loading conditions.

Therefore, applying such a comprehensive dataset makes the results of the models reasonable. The model closest to the assessment of ITRI could decisively referred as a credible model trained from the comprehensive dataset in the best manner and predict HI accurately.

In this study, eight important parameters from different electrical, physical and chemical tests of power transformer oil-paper insulation, including Interfacial Tension (*IFT*), Breakdown Voltage (*BDV*), *Acidity*, Dissipation Factor at 90°C (*DF*), *Furfural* content, Water content in oil at 20°C (*Water*), percent Water in Paper insulation (*%WaterPaper*), and DGA Factor (*DGAF*) are regarded as the input parameters of the models. The HI parameter is the output of the models.

In this paper, the DGA is not used to specify the type of faults that occurred in the transformer. It helps to assess the comprehensive health status of the transformer. Thus, the values of seven dissolved gases (the DGA parameters) are integrated into one inclusive parameter (*DGAF*) [14]. In [15], the influence of DGA parameters on the HI is examined with the dissolved combustible gas (DCG) parameter. The DCG parameter is defined as the sum of DGA gases values simply excluding *CO* and *CO₂* gases. Two disadvantages of using DCG parameter are: 1) The *CO* and *CO₂* gases which contain beneficial details concerning the degradation of paper insulation are disregarded [4], [5], [16], [21]. 2) The degree of importance and weighting factors of gases are not regarded [14], [16].

The *DGAF* value is obtained using various limits of the dissolved gases given in the standards [4], [5]

as follows [14].

$$DGAF = \frac{\sum_{i=1}^7 S_i \times W_i}{\sum_{i=1}^7 W_i} \quad (1)$$

where *i* is related to seven dissolved gases (*H₂*, *CH₄*, *C₂H₆*, *C₂H₄*, *C₂H₂*, *CO* and *CO₂*), *S_i* is the score value according to the volume of dissolved gases, and *W_i* stands for the weighting factor of the dissolved gases assumed by [14].

In this paper, two parameters *DP* and *percent water saturation of oil* are not considered as the input parameters for the models, because they are highly related to *Furfural* and *Water* parameters, respectively.

In order to deal with the moisture content appropriately, the value of water at oil in a sample temperature should be corrected to a specified temperature. Due to the empirical matters, the specified temperature is considered at 20°C [6]. In this paper, the corrected values of water at 20°C are utilized to facilitate the comparison of the parameters at various oil temperatures [6]. The parameter *percent water saturation of oil* is calculated from the equation: $100 \times [(water\ in\ oil)/(water\ in\ oil\ at\ saturation)]$ [8], [9], where *water in oil at saturation* means the maximum content of water that is soluble in the oil at a particular temperature which is equal to 53 ppm [9] at 20°C. Therefore, *percent water saturation of oil* is not considered as an individual input parameter because it is related to the water content of oil at 20°C (*Water*).

The relation between *DP* and *Furfural* in the dataset is very close to the equation: $DP = (1.51 - \log F)/0.0035$ [39], so *DP* is also not considered as an individual input parameter.

In this paper, two insulation parameters including *IFT* and *%WaterPaper* are also emphasized in the input parameters for a more accurate assessment of transformer overall HI. The *IFT* between oil and water is an excellent indicator to detect the particles of the degradation process and contaminants soluble in the transformer oil. The parameter *IFT* can

be used to detect the deterioration of materials in overloaded transformers [6], [8], [9].

Water content in the oil is measured as one of the routine tests for oil in the transformers. The content of moisture in the oil does not always signify moisture in the paper insulation. In the process of transformer cooling, water tends to return to the paper slowly. The variations in water content of oil slightly affect water content of paper, because about 99 percent of the water exists in the paper insulation.

When a thermal balance between the paper and oil is established, water content in oil could be an accurate indicator of the water content in the paper insulation. Such case usually does not happen in operating transformers [6], [8], [9]. In this paper, due to the significance of the solid insulation condition in specifying the health status of the transformer, in addition to furfural and dissolved carbon oxides in oil, $\%WaterPaper$ is also considered as an individual parameter to evaluate the condition of transformer paper insulation [6], [8], [9], [21].

In this paper, experimental values of HI prepared by transformer experts at ITRI, are utilized as the output parameter of the proposed models.

IV. METHODOLOGY

In this section, MLR, ANN, and ANFIS models are proposed for HI calculation of transformer insulation system. 80% of the dataset is considered as training and 20% of the dataset is utilized as testing objects, randomly. The testing dataset is utilized for evaluating the proficiency of the models. The trained models are utilized to predict HI for testing dataset (unseen data) with possible slightest deviation from the experimental values of HI provided by the ITRI.

A. MULTIPLE LINEAR REGRESSION (MLR) MODEL

MLR is a method utilized to model the linear relationship between input parameters (transformer insulation characteristics) and the output parameter (HI) using regression analysis [37], [38]. Linear regression provides an equation that minimizes the distance between the fitted line and all data points. The slight difference between the experimental and predicted HI values makes a model fits the data well. The most usual error metric used in the linear regression method is the minimization of the sum of the squared errors. The model expresses the value of an output variable as a linear function of the input variables, so the resulting prediction equation for the i^{th} set of data is as follows.

$$y_i^{prd} = c_0 + \sum_{j=1}^p c_j \cdot k_j \quad (2)$$

where k_j is the value of the j^{th} input parameter, c_0 is regression constant, c_j is coefficient of the j^{th} input parameter, p is the number of input parameters, and y_i^{prd} is the predicted output value for the i^{th} set of data.

B. ARTIFICIAL NEURAL NETWORK (ANN) MODEL

The idea of ANN is obtained from the human brain system. The complicated relations of problem data can be modeled

with ANN which is utilized such as a black box model needs no precise details of the problem [17], [18], [40].

ANN is a proficient nonlinear method that evaluates the transformer predicted HI value. ANN model learns the relations between input parameters (transformer insulation characteristics) and output parameter (HI) based on training data.

In order to implement the ANN model, a three-layer feed-forward neural network including one hidden layer trained with the Levenberg-Marquardt (LM) Back-Propagation (BP) algorithm is utilized. Through extensive experiments, it has been demonstrated from a practical viewpoint that neural networks with one hidden layer are preferred to networks with more than one hidden layer. The last-mentioned networks are more vulnerable to fall into a local minimum. In engineering employments, neural networks with one hidden layer are usually utilized [40].

The number of neurons in the input and output layers are specified based on the problem definition. In this study, the input layer has eight neurons and the output layer has one neuron. The number of hidden layer neurons could be considered as an adjustable parameter, which should be optimized.

The weights and biases of the ANN model are adjusted for each training sample to minimize the mean squared error between the predicted value of the network and the experimental one. In the input layer of the network, the summation function is calculated with the inputs, their weights and biases. The output of the j^{th} hidden neuron is attained with the following transfer function.

$$a_j = f_1\left(\sum_{i=1}^r w_{ij}x_i + b_j\right) \quad (3)$$

where r is the number of input layer neurons (input parameters), w_{ij} is the connection weight between input and hidden layer, x_i and b_j are the input and bias of the hidden layer, and a_j is the output of the hidden layer and input of the next layer (output layer).

The final output is calculated as follows.

$$a_k = f_2\left(\sum_{j=1}^S w_{jk}a_j + b_k\right) \quad (4)$$

where S is the number of hidden layer neurons, w_{jk} is connection weight between hidden and output layers, b_k is bias of output layer, and a_k is the final output.

Several linear and nonlinear transfer functions are available for ANN. These transfer functions are nonlinear, continuous and differentiable. So the network could obtain complicated relations between input and output data. In this work, sigmoid $\log\text{sig}$ (f_1) and linear purelin (f_2) transfer functions are utilized in hidden and output layers, respectively.

$$f_1(n) = \frac{1}{1 + e^{-n}} \quad (5)$$

$$f_2(n) = n \quad (6)$$

The implementation diagram of the ANN architecture is illustrated in Fig. 1.

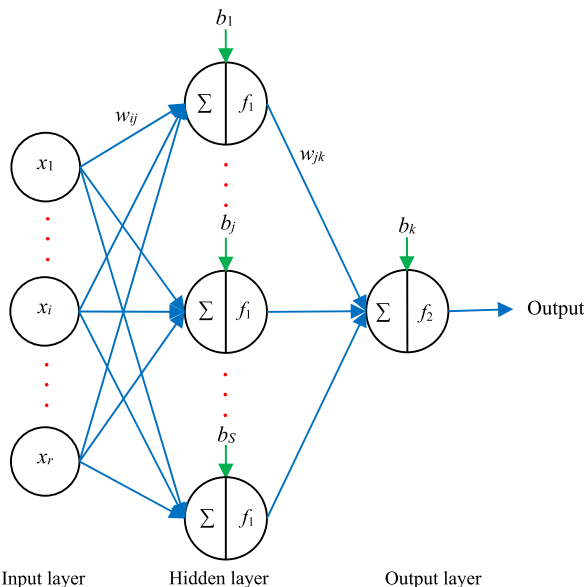


FIGURE 1. Implementation diagram of the ANN architecture.

C. ADAPTIVE NEURO-FUZZY INFERENCE SYSTEM (ANFIS) MODEL

ANFIS is an adaptive network that utilizes neural network learning method and fuzzy inference system to map inputs into the output. It can be used to simulate complex nonlinear problems. The basic of hybrid Neuro-Fuzzy models is application of neural network learning rules to specify the membership function (MF) parameters automatically [19], [20], [38].

ANFIS method suggested by Jang on the basis of TSK (Takagi-Sugeno-Kang) fuzzy inference system which includes the capabilities of both neural network and fuzzy logic methods [41].

The output of TSK fuzzy system is a linear combination of the inputs. Therefore, the output is a decisive number and a defuzzification process is not needed. The \$i^{th}\$ rule of TSK fuzzy system is as follows.

$$\text{If } x_1 \text{ is } A_{i1} \text{ and } x_2 \text{ is } A_{i2} \dots \text{ and } x_r \text{ is } A_{ir}, i \in [1, m]$$

$$\text{Then } y_i = p_{i1}x_1 + p_{i2}x_2 + \dots + p_{ir}x_r + p_{i0} \quad (7)$$

where \$x_j\$ is the \$j^{th}\$ input parameter, \$r\$ is the number of input parameters, \$m\$ is the number of rules, \$A_{ij}\$ is the \$j^{th}\$ fuzzy set of the \$i^{th}\$ rule, and \$p_{iq}\$ are consequent parameters of the \$i^{th}\$ rule.

The ANFIS structure has five layers: fuzzy layer, product layer, normalized layer, defuzzify layer, and total output layer [41].

In the first layer, fuzzy MFs of input parameters are generated as follows.

$$O_{1,i} = \mu_{A_{ij}}(x_j), \quad j \in [1, r] \quad (8)$$

where \$\mu_{A_{ij}}\$ could be any fuzzy MF type. The Gaussian MF is usually used for ANFIS as follows.

$$\mu_{A_{ij}}(x_j) = \exp\left(\frac{-(x_j - c_{ij})^2}{2\sigma_{ij}^2}\right) \quad (9)$$

where \$c_{ij}\$ and \$\sigma_{ij}\$ are premise parameters which explain Gaussian MF center and width, respectively.

The second layer is composed of fixed nodes. Fixed nodes combine the input MFs to calculate the firing strength of the \$i^{th}\$ rule (\$w_i\$) that computes by the algebraic product T-norm as follows.

$$O_{2,i} = w_i = \prod_{j=1}^r \mu_{A_{ij}}(x_j) \quad (10)$$

The third layer applies a normalization function to obtain the normalized firing strength of the \$i^{th}\$ rule as follows.

$$O_{3,i} = \bar{w}_i = \frac{w_i}{\sum_{i=1}^m w_i} \quad (11)$$

In the fourth layer, the nodes are adaptable and every node has the product of equations (7) and (11) as follows.

$$O_{4,i} = \bar{w}_i y_i \quad (12)$$

Finally, the fifth layer is the total output layer that illustrates the overall output as the sum of all input signals as follows.

$$O_{5,1} = \sum_{i=1}^m \bar{w}_i y_i = \frac{\sum_{i=1}^m w_i y_i}{\sum_{i=1}^m w_i} \quad (13)$$

In the ANFIS structure, there are two adaptable layers including layer 1 which has two adjustable parameters (premise parameters \$c_{ij}\$ and \$\sigma_{ij}\$) related to the input MFs, and layer 4 which has \$r+1\$ adjustable parameters (consequent parameters \$p_{iq}\$) of the first-order polynomial.

The overall pseudocode of the proposed ANFIS method is as follows:

```

1 for i ← 0 to firstlayer_nods do
2   | μi ← gussM(x, sig, c);
3 end
4 for i ← 0 to nods do
5   | wi ← rule_layer(μ);
6 end
7 for i ← 0 to nods do
8   | w̄i ← normalize(w);
9 end
10 for i ← 0 to nods do
11   | Fi ← consequent(w̄i, x, l)
12 end
13 for i ← 0 to nods do
14   | Y ← Y + Fi;
15 end
    
```

The five loops of ANFIS method are shown in the above pseudocode. In the first loop all membership degrees are calculated by Gaussian function. *firstlayer_nods* value represents the number of nodes. In the remaining loops the results of layer two to five are evaluated. *nods* value represents the number of nodes in these layers. Functions of *rule_layer*, *normalize* and *consequent* are explained in (10) to (12).

In this study, the ANFIS model with eight inputs and one output is utilized based on the subtractive clustering algorithm. The subtractive clustering algorithm itself identifies

the number of clusters. In this algorithm, the number of fuzzy rules is only associated with the number of clusters. Therefore, it is a proper method to solve problems which have a large number of inputs.

The ANFIS utilizes a hybrid learning method to train the network which is a combination of least-squares and back-propagation gradient descent methods. The hybrid learning approach is effectively attains the optimal premise parameters in layer 1 and consequent parameters in layer 4 [41].

The implementation diagram of the ANFIS structure consists of five layers is shown in Fig. 2.

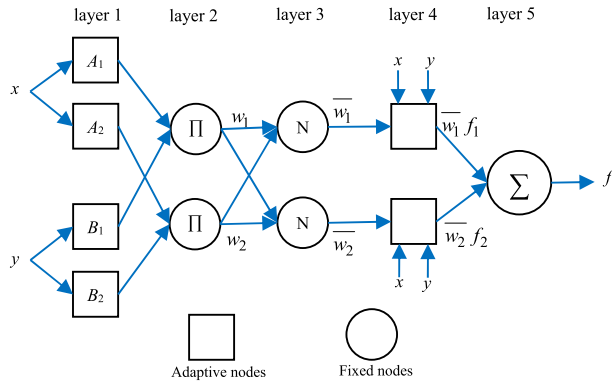


FIGURE 2. Implementation diagram of the ANFIS structure.

D. ERROR CRITERIA

A combination of error metrics is often required to evaluate the model performance. In this paper, four statistical error criteria including root mean squared error (RMSE), coefficient of determination (R²), mean absolute error (MAE), and mean relative error (MRE) have been utilized to determine the performance and predictive capabilities of the models. The error criteria equations are as follows.

$$RMSE = \sqrt{\frac{\sum_{i=1}^n (y_i^{exp} - y_i^{prd})^2}{n}} \tag{14}$$

$$R^2 = 1 - \frac{\sum_{i=1}^n (y_i^{exp} - y_i^{prd})^2}{\sum_{i=1}^n (y_i^{exp} - \bar{y}^{prd})^2} \tag{15}$$

$$MAE = \frac{\sum_{i=1}^n |y_i^{exp} - y_i^{prd}|}{n} \tag{16}$$

$$MRE\% = \frac{\sum_{i=1}^n \left| \frac{y_i^{exp} - y_i^{prd}}{y_i^{exp}} \right|}{n} \times 100 \tag{17}$$

where y_i^{exp} and y_i^{prd} are the experimental and predicted output values for the i^{th} set of data, respectively, \bar{y}^{prd} is the average of predicted output values, and n is number of samples in the dataset.

The best agreement between the predicted and experimental values should have RMSE, MAE, and MRE of zero and R² equals to one. Therefore, these error measures could illustrate the different meanings of training quality indices.

R² is a measure ranges from 0 to 1 that shows the global fit of the model. In this paper, R² is used to measure the

agreement between experimental and predicted values of each model. The closer R² is to 1, the stronger this agreement.

V. RESULTS AND DISCUSSION

The quality of the training dataset may considerably affect the efficiency of the intelligent methods of transformer condition evaluation. In this paper, a diverse and large dataset contains almost all possible conditions (good, fair, poor) assumed in [6] for each input parameter is used which stabilizes the model to predict HI value closest to ITRI assessment for each new data.

A. CHECKING QUALITY OF THE DATASET

At first, MLR analysis is done with all 336 sets of data to examine data quality and detect the outliers and influential points, which cause problems in model construction.

The applicability domain of the MLR model is examined by Williams plot [38], which is an efficient method to find both the response outliers and the structurally influential points in the model. This plot is obtained from the calculation of the standardized residuals and leverage values for each set of data. The leverage value (h_i) for the i^{th} set of data is obtained as follows.

$$h_i = x_i(X^T X)^{-1} x_i^T \tag{18}$$

where h_i is the leverage value, X is $(r+1) \times n$ matrix including r input parameters for each of n data sets and a column with elements equal to one for the regression constant, and x_i is the i^{th} row vector of X .

The standardized residuals ($e_{s,i}$) for the i^{th} set of data is defined as follows.

$$e_{s,i} = \frac{y_i^{exp} - y_i^{prd}}{\sqrt{mse \times (1 - h_i)}} \tag{19}$$

where mse is the mean squared error of the model between the predicted and experimental HI values.

In the Williams plot, structurally influential sets have leverage values greater than critical hat value ($h^* = 3(r+1)/n$). Moreover, sets of data with the standardized residuals greater than three standard deviation units (3σ) are considered as outliers. Fig. 3 shows the Williams plot that has four zones. Zones 1, 2, 3 and 4 indicate regular sets, good influential high leverage sets, bad influential high leverage sets, and high residual outlier sets of data, respectively.

It can be described from Fig. 3 that the majority of datasets are placed inside the applicability domain and there is no outlier (Zone 4) and there is only one bad influential point (Zone 3) in the dataset. The high leverage data sets that have small residuals (Zone 2) are related to some of transformers with Poor or Very Poor experimental HI condition. They are good influential points that make the model stable and more accurate. But the bad influential points (Zone 3) with simultaneously high leverage and high residual values which could probably be associated with the wrong measurements, destabilize the model and should be removed from the dataset to avoid decreasing the accuracy of the model. The RMSE of the model decreases 4.093% from 0.2150 to 0.2062 by removing the bad influential point of zones 3 and 4.

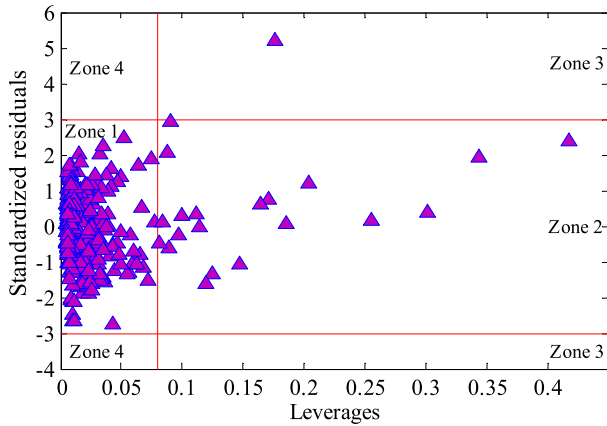


FIGURE 3. Williams plot of MLR model for all 336 data sets ($h^* = 0.0804$).

TABLE 4. Comparison of average RMSE for different ANN configurations.

No. of hidden neurons	Best	Worst	Average	Standard deviation
1	0.1817	0.4203	0.2039	0.0369
2	0.1587	0.8805	0.1974	0.0718
3	0.1585	0.2642	0.1928	0.0208
4	0.1521	0.3175	0.1941	0.0247
5	0.1545	0.2846	0.1973	0.0261
6	0.1530	0.3122	0.1993	0.0239
7	0.1578	0.2665	0.2050	0.0240
8	0.1560	0.3490	0.2048	0.0305

By removing the bad influential point from the dataset, the remaining 335 datasets are divided randomly into training and testing subsets. 268 training datasets have been utilized to build the proposed MLR, ANN and ANFIS models, whereas the remaining 67 testing datasets being used to indicate the efficiency of the trained models in HI evaluation using the transformer insulation parameters.

B. MLR MODEL

The linear model constructed with training dataset by MLR method given in equation (2) between transformer insulation parameters and HI value for the i^{th} set of data is as follows.

$$\begin{aligned}
 HI_i = & b_0 + b_1 \times BDV_i + b_2 \times DF_i + b_3 \times Acidity_i \\
 & + b_4 \times IFT_i + b_5 \times Water_i + b_6 \times \% WaterPaper_i \\
 & + b_7 \times Furfural_i + b_8 \times DGAF_i
 \end{aligned} \tag{20}$$

where regression coefficients calculated by MLR model are:

$$\begin{aligned}
 b_0 = & 4.232062, b_1 = 0.005507, b_2 = -0.572687 \\
 b_3 = & -0.755662, b_4 = 0.016234, b_5 = -0.003760 \\
 b_6 = & -0.155216, b_7 = -0.406599, b_8 = -1.107828
 \end{aligned}$$

It can be seen that the sign of the coefficients of *BDV* and *IFT* parameters is positive and the other six parameters have a negative sign. The physical concepts of transformer insulation parameters given in standards [6]–[9] confirm that the values of *BDV* and *IFT* parameters have a positive relationship with the transformer insulation condition (the higher the *BDV* and *IFT* values, the better the transformer insulation condition), and the other six parameters have a negative relationship with the transformer insulation condition.

In order to make the MLR model coefficient values comparable and investigate the significance of each transformer insulation parameter on the evaluation of HI condition, the parameters should be standardized. For this purpose, HI and transformer insulation parameters are standardized such that their mean values be zero and standard deviation values be one. By doing MLR analysis on this standardized dataset, the model coefficients are calculated as:

$$\begin{aligned}
 b_{0,Std} = & -2.47 \times 10^{-15}, b_{1,Std} = 0.097379, \\
 b_{2,Std} = & -0.129512 \\
 b_{3,Std} = & -0.032724, b_{4,Std} = 0.145306, \\
 b_{5,Std} = & -0.032088 \\
 b_{6,Std} = & -0.297996, b_{7,Std} = -0.200335, \\
 b_{8,Std} = & -0.630401
 \end{aligned}$$

The standardization of the regression coefficients makes it possible to emphasize the parameters with larger absolute standardized coefficients. So importance ranking of insulation parameters becomes as follows.

$$\begin{aligned}
 DGAF > \% WaterPaper > Furfural > IFT > \\
 DF > BDV > Acidity > Water
 \end{aligned} \tag{21}$$

It could be seen that *DGAF* has the highest effect on transformer HI value, and also *%WaterPaper* and *Furfural* are two next significant parameters. Moreover, it can be illustrated that two insulation parameters, *IFT* and *%WaterPaper* considered in addition to the parameters of the previous works, have a considerable effect on HI value.

C. ANN MODEL

ANN operates based on the setting of parameters of its architecture. The selection of initial values of its weights and biases has a significant effect on the network’s performance. Because a nonlinear optimization method (BP LM training algorithm) is used in ANN structure, it may not certainly results in a specific solution at each run. Finding an appropriate architecture for ANN is a difficult task. The optimum number of neurons in the hidden layer is determined by trial and error.

The optimal number of hidden neurons can be determined by comparison of the average calculated RMSE of the networks. In Table 4, the average and standard deviation of RMSE for the testing dataset are given for the different number of hidden neurons for 100 trails.

It can be inferred from Table 4 that if the hidden layer has three neurons, the ANN model results in minimum average and standard deviation of RMSE.

The weight and bias values of the optimal ANN configuration (with three hidden neurons) is shown in Table 5.

D. ANFIS MODEL

In this paper, the ANFIS model with subtractive clustering algorithm and hybrid learning method is utilized. The premise and consequent parameters for the optimal ANFIS model are shown in Tables 6 and 7.

TABLE 5. Weight and bias values of the optimal ANN configuration.

Neuron	Hidden layer								Output layer		
	Weights (w_i)								Biases (b_i)	Weights (w_k)	Bias (b_k)
	BDV	DF	Acidity	IFT	Water	%WaterPaper	Furfural	DGAF		HI	
1	-0.9258	-0.7170	-0.4882	1.9495	0.7331	0.7496	-1.8650	0.2665	-4.7442	0.0482	-2.3370
2	-0.7620	-0.0472	0.4166	0.5275	0.0391	0.2876	0.3427	-0.1545	0.2880	3.7228	
3	-0.8379	-0.4300	0.4703	-0.2455	2.5903	-0.1090	0.3305	1.8010	-3.3066	1.0211	

TABLE 6. Premise parameters of the optimal ANFIS model.

	BDV	DF	Acidity	IFT	Water	%WaterPaper	Furfural	DGAF
	$[\sigma_{11}, c_{11}]$	$[\sigma_{12}, c_{12}]$	$[\sigma_{13}, c_{13}]$	$[\sigma_{14}, c_{14}]$	$[\sigma_{15}, c_{15}]$	$[\sigma_{16}, c_{16}]$	$[\sigma_{17}, c_{17}]$	$[\sigma_{18}, c_{18}]$
Rule 1	[10.43,75.00]	[0.210,-0.0013]	[0.019,0.064]	[3.90,33.80]	[5.39,2.3]	[0.620,1.90]	[0.387,0.113]	[0.254,1.014]
Rule 2	[10.42,78.58]	[0.107,-0.0110]	[0.028,0.114]	[3.90,31.79]	[5.39,2.5]	[0.628,2.84]	[0.437,0.189]	[0.284,0.986]
Rule 3	[10.43,73.20]	[0.173,0.0361]	[0.028,0.115]	[3.92,33.20]	[5.39,5.7]	[0.691,3.07]	[0.408,0.167]	[0.263,1.060]

TABLE 7. Consequent parameters of the optimal ANFIS model.

	p_{i1}	p_{i2}	p_{i3}	p_{i4}	p_{i5}	p_{i6}	p_{i7}	p_{i8}	p_{i0}
Rule 1	-0.0028	-0.1754	-1.1681	0.0173	0.0172	-0.3335	-0.6692	-1.5059	5.6211
Rule 2	-0.0181	-0.8560	-0.8000	0.0810	-0.1170	0.0080	-0.2878	-1.2710	5.0134
Rule 3	0.0067	-0.1821	-0.4437	-0.0047	0.0047	0.0723	-0.4196	-1.1370	3.3676

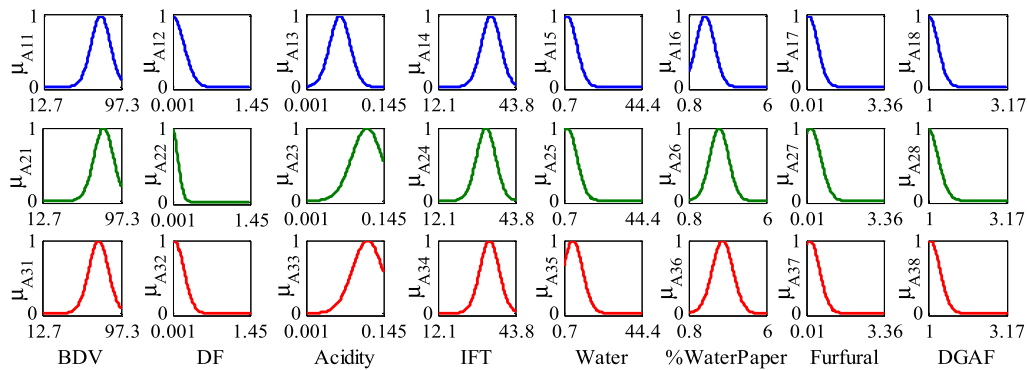


FIGURE 4. Fuzzy membership functions used in the optimal ANFIS model.

For example, from (7), Rule 1 becomes as:

If x_1 is A_{11} and x_2 is A_{12} and x_3 is A_{13} and x_4 is A_{14} and x_5 is A_{15} and x_6 is A_{16} and x_7 is A_{17} and x_8 is A_{18}

Then $y_1 = -0.0028x_1 - 0.1754x_2 - 1.1681x_3 + 0.0173x_4 + 0.0172x_5 - 0.3335x_6 - 0.6692x_7 - 1.5059x_8 + 5.6211$

where, $x_1, x_2, x_3, x_4, x_5, x_6, x_7,$ and x_8 are *BDV, DF, Acidity, IFT, Water, %WaterPaper, Furfural,* and *DGAF* parameters, respectively.

The Gaussian type fuzzy MFs $\mu_{A_{ij}}$ for the j^{th} input parameter and the i^{th} rule, generated with equation (9) are shown in Fig. 4.

E. COMPARISON OF THE MODELS AND DISCUSSION

Unlike the ANN model, the MLR and ANFIS models are robust and result in exactly the same error criteria and HI values at each run. In Table 8, the error criteria of HI calculation for the proposed MLR, ANN and ANFIS models are provided.

The small values of the RMSE, MAE, MRE and values proximate to one of R^2 in Table 8 demonstrate the agreement

TABLE 8. Error criteria of MLR, ANN and ANFIS models.

	Error criteria	RMSE	R^2	MAE	MRE%
MLR	Train dataset	0.2056	0.9061	0.1657	6.0770
	Test dataset	0.2117	0.9026	0.1708	6.3760
	Total dataset	0.2068	0.9046	0.1667	6.1368
ANN	Train dataset	0.1812	0.9272	0.1436	5.2596
	Test dataset	0.1928	0.9182	0.1482	5.5636
	Total dataset	0.1836	0.9250	0.1445	5.3204
ANFIS	Train dataset	0.1433	0.9544	0.1157	4.0021
	Test dataset	0.1588	0.9430	0.1248	4.4763
	Total dataset	0.1465	0.9520	0.1175	4.0970

of the proposed models with the experimental model of ITRI. It could be observed from Table 8 that the ANFIS model provides superior results for train, test and total datasets. This superior efficiency results from combining the learning capabilities of neural network and reasoning capabilities of fuzzy logic in the ANFIS.

In order to specify the overall health status of a transformer, the HI values are normalized on the scale of 0 (thoroughly degraded transformer) to 1 (excellent condition). Table 9 presents the categories of HI values and correlates them to

TABLE 9. Transformer health condition based on the normalized HI value [13], [14].

HI	Condition	Probability of failure	Expected Lifetime	Requirements
0.85–1	Very Good	Low (0%)	More than 15 years	Normal maintenance
0.7–0.85	Good	Low but a slight increasing (less than 1.6%)	More than 10 years	Normal maintenance
0.5–0.7	Fair	Fast increasing but less than probability at mean age (between 1.6% and 6.9%)	Up to 10 years	Increase diagnostic testing, possible corrective measures or replacement depending on criticality
0.3–0.5	Poor	More than probability at mean age and increasing (between 6.9% and 14.2%)	Less than 3 years	Start planning process to replace or rebuild considering risk and consequences of failure
0–0.3	Very Poor	Very High, more than double the probability at mean age (more than 14.2%)	At the end of life	Immediately assess risk, replace or rebuild based on assessment

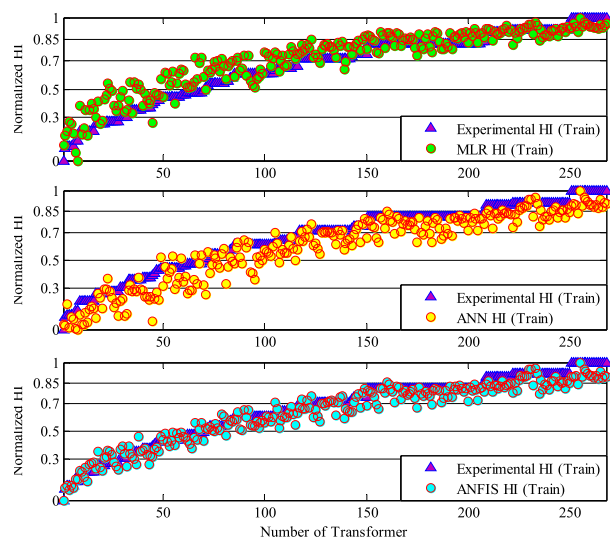


FIGURE 5. Comparison of experimental normalized HI with MLR, ANN and ANFIS models for training dataset.

the failure probability, expected lifetime and required actions. HI values are classified into condition categories from “Very Good” to “Very Poor”. The health status of each transformer is specified by the ranges of HI values defined in [13], [14].

The comparison of experimental normalized HI values and those predicted by proposed MLR, ANN and ANFIS models are given in Fig. 5 for 268 training datasets of transformers.

The comparison of experimental normalized HI values and those predicted by proposed MLR, ANN and ANFIS models are given in Fig. 6 for 67 testing datasets of transformers.

It can be considered from Figs. 5 and 6 that HI values for transformers of the training and testing datasets are placed in various health condition zones of Table 9.

The normalized HI values predicted by the ANFIS model (the most precise and robust model), against experimental HI for 335 training and testing datasets are illustrated in Fig. 7.

The health condition of Table 9 is the same for experimental and predicted HI values for data points placed in diagonal grids of Fig. 7. But datasets in nondiagonal grids pertain to the cases that the predicted condition is not the same as the experiment. For example, the health condition for cases in Grid 1 is Poor for predicted HI and Very Poor

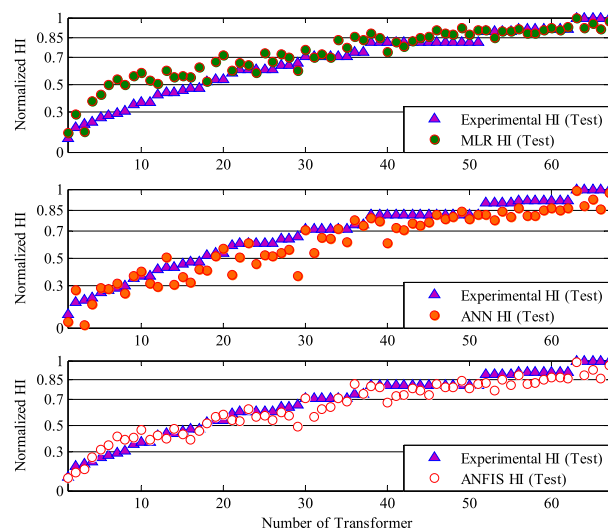


FIGURE 6. Comparison of experimental normalized HI with MLR, ANN and ANFIS models for testing dataset.

for experimental HI. About the cases of Grid 2, the predicted and experimental HI values have Fair and Good health conditions, respectively. It is concluded from Fig. 7 that the accuracy of the predicted model is high with this comprehensive dataset, because about 80% of datasets are placed at diagonal grids.

Also, the other cases are adjacent to the diagonal line. These cases are located at the border of two condition zones. For these datasets, the experimental HI specifies that the transformer is at the end of one condition zone, and the predicted HI specifies that the transformer is at the beginning of the adjoining condition zone. Therefore, results prove that the predicted and experimental HI values are considerably in agreement.

The test data which are the input parameters of the presented models are shown in Table 10 for 15 sample transformers of the 336 datasets. These data include Age at the test date, voltage ratio, power rating, Top oil temperature, Breakdown Voltage (*BDV*), Dissipation Factor at 90°C (*DF*), Acidity, Interfacial Tension (*IFT*), Water content in oil at 20°C (*Water*), Percent Water in Paper insulation (*%WaterPaper*), Furaldehyde content (*Furfural*), Dissolved Gas Analysis Factor (*DGAF*) parameters.

TABLE 10. Input parameters for 15 sample transformers.

Transformer No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Age (Years)	7	7	7	10	7	7	40	7	14	9	7	13	11	10	12
Voltage ratio (kV)	410 / 15.75	410 / 15.75	245 / 15.75	245 / 15.75	245 / 15.75	245 / 15.75	230 / 13.2	245 / 15.75	400 / 15.75	400 / 132	245 / 15.75	400 / 15.75	410 / 15.75	245 / 15.75	410 / 13.8
Power rating (MVA)	100	100	215	215	215	215	84	215	94	200	215	94	100	215	160
Top oil Temp. (°C)	31	34	60	60	58	49	35	60	38	50	60	36	52	54	40
BDV (kV)	21.80	12.70	89.60	74.59	74.58	75.21	49.80	74.46	75.50	75.00	75.90	73.10	75.50	78.31	75.00
DF	0.008 / 8	0.005 / 8	0.013 / 3	0.048 / 6	0.015 / 7	0.088 / 9	0.074 / 8	0.010 / 5	0.006 / 8	0.009 / 5	0.019 / 1	0.009 / 2	0.009 / 2	0.018 / 4	0.001 / 3
Acidity (mg _{KOH} /g _{oil})	0.01	0.03	0.01	0.08	0.05	0.10	0.12	0.06	0.06	0.06	0.07	0.06	0.06	0.07	0.06
IFT (mN/m)	35.00	30.40	22.78	30.10	34.20	33.10	20.80	36.40	34.20	33.10	35.90	33.50	31.60	29.30	36.40
Water (ppm)	32.20	44.40	12.00	2.10	1.50	2.90	6.90	1.60	3.00	1.50	1.60	4.00	1.00	1.60	0.70
%WaterPaper	6.00	6.00	4.90	1.80	1.40	2.20	3.40	1.40	2.20	1.40	1.40	2.60	1.00	1.40	0.80
Furfural (ppm)	0.09	0.09	0.44	0.20	0.08	0.18	0.58	0.11	0.17	0.11	0.12	0.18	0.11	0.22	0.09
DGAF	2.17	1.78	1.83	2.11	2.00	2.00	1.00	1.72	1.44	1.28	1.22	1.17	1.00	1.00	1.00

TABLE 11. Comparison of HI condition obtained by different methods for 15 sample transformers.

Transformer No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
HI ₁	N. Value	0.0847	0.2542	0.2712	0.4068	0.4915	0.3051	0.5254	0.5763	0.6441	0.7458	0.7458	0.8136	0.9153	0.9153	1.0000
	Condition	5	5	5	4	4	4	3	3	3	2	2	2	1	1	1
HI ₂ [16]	N. Value	0.6754	0.5943	0.5323	0.3153	0.2086	0.3314	0.4418	0.2341	0.2155	0.1414	0.1298	0.1575	0.0835	0.0835	0.0000
	Condition	4	4	4	3	2	3	3	2	2	1	1	2	1	1	1
HI ₃ [42]	Fault Type	T1	T1	T2	T1	T1	T1	Normal	DT	DT	T3	T2	T3	Normal	Normal	Normal
	Condition	3	3	4	3	3	3	1	4	4	5	4	5	1	1	1
HI ₄ [43]	Condition	5	5	2	1	1	1	4	1	1	1	1	1	1	1	1
HI ₅ [44]	N. Value	0.5165	0.5118	0.3599	0.3077	0.2580	0.2851	0.2611	0.2038	0.1881	0.1465	0.1236	0.1608	0.0986	0.1167	0.0717
	Condition	4	4	3	3	2	3	2	2	2	1	1	1	1	1	1
HI ₆	N. Value	0.1777	0.2596	0.3876	0.4767	0.5892	0.5031	0.6325	0.6952	0.7363	0.8395	0.8708	0.8053	0.9536	0.9069	0.9927
	Condition	5	5	4	4	3	3	3	3	2	2	1	2	1	1	1
HI ₇	N. Value	0.0264	0.2257	0.0967	0.2163	0.3199	0.2452	0.5584	0.4882	0.5731	0.7486	0.7960	0.6898	0.9382	0.8419	1.0000
	Condition	5	5	5	5	4	5	3	4	3	2	2	3	1	2	1
HI ₈	N. Value	0.0864	0.2390	0.2248	0.3648	0.4289	0.3935	0.5132	0.5692	0.6119	0.7737	0.8114	0.7112	0.9464	0.8640	1.0000
	Condition	5	5	5	4	4	4	3	3	3	2	2	2	1	1	1

The output parameter of the presented models is the normalized Health Index value (N. Value). The condition of the transformers is obtained from the normalized value of HI. A comparison of the experimental HI as the reference value with some previous works and also with the presented model of this paper for the above-mentioned 15 sample transformers are given in Table 11.

In Table 11, Condition of 1,2,3,4,5 are referred to Very Good, Good, Fair, Poor, Very Poor conditions of the transformers, respectively. HI₁ is the experimental HI which is prepared by transformer experts at ITRI. In this paper, the experimental HI is considered as the reference value for the

validation of the proposed models. The experimental HI values are obtained using utility expert comments. In addition to the results of oil characteristic tests, utility experts have more information about the transformers. The transformer expert may know about maintenance history, loading history, operating conditions, and they have the specialty to analyze the data and assessment of transformer condition. HI₂ is obtained from the method based on industry standards explained in [16]. HI₃ is obtained with the Duval's Triangle [42]. In Duval's Triangle PD=partial discharges, D1=discharges of low energy, D2=discharges of high energy, T1=thermal faults of temperature < 300 °C, T2=thermal faults of

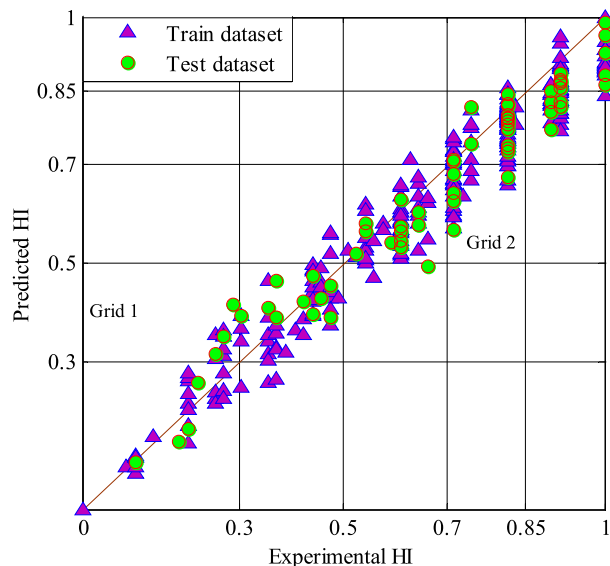


FIGURE 7. Predicted HI by ANFIS vs. experimental HI for all 335 datasets.

temperature $300\text{ }^{\circ}\text{C} < T < 700\text{ }^{\circ}\text{C}$, T3 = thermal faults of temperature $> 700\text{ }^{\circ}\text{C}$, DT = mixtures of thermal and electrical faults. HI₄ is obtained with the Fuzzy C-Means (FCM) method [43]. FCM is a clustering method in which a data point relates to a cluster to some degree by a membership function. HI₅ is obtained with the correlation coefficients between the health index and the input parameters [44].

HI₆, HI₇ and HI₈ are the health index values obtained from the MLR, ANN, and ANFIS models presented in this paper, respectively. The accuracy of the presented ANFIS model could be demonstrated from the comparison given in Table 11. It could be seen that for the sample transformers, there is no difference between the condition obtained by the ANFIS model and the experimental ones. But the other methods associate with some deviations from the experimental conditions. However, the results of MLR and ANN models are also acceptable in comparison with the other above-mentioned methods.

VI. CONCLUSION

In this paper, the procedure of combining transformer insulation specifications and dissolved gas analysis data to provide a single numerical Health Index value as a comparative measure of the overall status of the transformer is presented. The HI is calculated for 336 experimental field datasets of transformers with different voltage levels and power ranges in different weather and operating conditions. Also, employing an inclusive DGAF parameter which considers seven dissolved gases regarding their importance, provides a relative indication of transformer DGA condition. Two parameters of transformer insulation including IFT and %WaterPaper as two significant oil characteristics are also included in the models.

In this paper, the linear model MLR and nonlinear ANN and ANFIS models are proposed for predicting transformer HI value. The training process of the models is performed

with 268 datasets and then the proficiency of the models is proved with other 67 testing datasets. It is demonstrated from the results that the most accurate and robust model is the ANFIS model.

Although the linear and nonlinear presented models provide good results, the ANFIS model is somehow superior.

In 80% of cases, prediction of health condition by ANFIS exactly matches the ITRI experimental health condition assessment. In the other ones, predictions are placed at the border of two adjoining conditions zones. So its performance sounds reliable for such a diverse dataset. The presented procedure assists the operator in recognizing the distinction between degradation which requires maintenance and diagnosis plans, and degradation that specifies end of life defined by $DP=200$ and direct asset management decisions.

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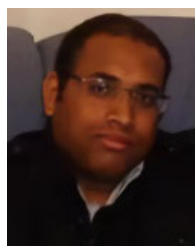
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