

Received 23 August 2021, accepted 8 October 2021, date of publication 14 October 2021, date of current version 27 October 2021. *Digital Object Identifier 10.1109/ACCESS.2021.3120265*

RecipeBowl: A Cooking Recommender for Ingredients and Recipes Using Set Transformer

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This research was supported by the National Research Foundation of Korea (No. NRF-2020R1A2C3010638), the MSIT(Ministry of Science and ICT), Korea, under the ICT Creative Consilience program(IITP-2021-2020-0-01819) supervised by the IITP(Institute for Information & communications Technology Planning & Evaluation) and SONY AI (https://ai.sony).

ABSTRACT Countless possibilities of recipe combinations challenge us to determine which additional ingredient goes well with others. In this work, we propose RecipeBowl which is a cooking recommendation system that takes a set of ingredients and cooking tags as input and suggests possible ingredient and recipe choices. We formulate a recipe completion task to train RecipeBowl on our constructed dataset where the model predicts a target ingredient previously eliminated from the original recipe. The RecipeBowl consists of a set encoder and a 2-way decoder for prediction. For the set encoder, we utilize the Set Transformer that builds meaningful set representations. Overall, our model builds a set representation of an leave-oneout recipe and maps it to the ingredient and recipe embedding space. Experimental results demonstrate the effectiveness of our approach. Furthermore, analysis on model predictions and interpretations show interesting insights related to cooking knowledge.

INDEX TERMS Food ingredient combination, food ingredient recommendation, food ingredient relations, recipe context learning, recipe recommendation, set representation learning.

I. INTRODUCTION

Finding the right additional ingredients and sample recipes is an essential, yet challenging task in the culinary world due to vast cooking possibilities [1]. Previous works have attempted to build food recommendation systems [2], [3] using small recipe datasets and shallow data-driven approaches. Food pairing tasks [4]–[6] have been proposed, but were limited to one-to-one ingredient recommendation. With multiple ingredients available, a system that is able to provide reasonable ingredient and candidate recipe choices based on sophisticated cooking knowledge may be desirable.

In this work, we propose RecipeBowl, a set-based model that jointly recommends ingredients and recipes. For example in Figure [1,](#page-0-0) given lime, chicken breasts, olive oil and garlic as input set, the user desires to cook an 'easy', 'main dish' grilled in an 'oven' using 'chicken'. In this case, the RecipeBowl suggests ingredients (e.g., balsamic vinegar, cilantro, white wine, rosemary and so on) that are likely to go well with the input set and satisfy the user's needs. Moreover, candidate recipes (e.g. *Easy Garlic Chicken*, *Grilled Pesto*

The associate editor coordinating the review of this manuscript and approving it for publication was K[.](https://orcid.org/0000-0003-4176-0236) C. Santosh[.]

FIGURE 1. Overview of RecipeBowl Cooking Recommender. RecipeBowl takes two types of input then recommends additional ingredients and sample recipes. The bold-faced ingredient (balsamic vinegar) and recipe (Easy Garlic Chicken) are the targets selected from their original recipe.

Chicken and so on) are also provided to guide the user's decisions on cooking.

We formulated a recipe completion task where the model is given a *leave-one-out* set of ingredients and tag information to predict one target ingredient previously excluded from the *original* set. We constructed a dataset based on a large recipe corpus Recipe1M [7]–[9] where each instance consists of an leave-one-out set as input and target ingredient as output. We then trained the model in a supervised learning

setting where it has to predict the target ingredient and its corresponding recipe given the *leave-one-out* set. The main objective is to simultaneously learn two different embedding spaces and push its vector projections towards the actual vector representations in each space. The trained model provides recommendations based on similarity-based rankings calculated between its predicted ingredient/recipe with the actual ones in each of their embedding spaces.

We performed quantitative and qualitative analysis on our model's recommendations to demonstrate the viability of our approach. Experimental results show that our model suggests reasonable ingredients that are relevant to recipe context. Observations on the predicted embedding space in t-sne visualizations, set context vectors in clustermaps and attention weights in heatmaps provide insight of how RecipeBowl utilizes recipe contextual knowledge and derives it from various ingredient combinations.

The major contributions are summarized as follows.

- We formulate a recipe completion task that trains a model on set-to-one prediction in a supervised learning setting.
- We propose RecipeBowl, a two-way cooking recommender model that adopts the Set Transformer [10] framework for building representations of ingredient sets 1
- We introduce a large-scale recipe completion dataset [8], [9] using Tf-Idf scores for selecting optimal target ingredients.
- Both quantitative and qualitative analysis show that RecipeBowl suggests practical choices based on recipe context and ingredient relations.

II. RELATED WORK

A. LEARNING RECIPE REPRESENTATIONS

Cross-modal features, namely text and image features have been widely used for generating recipe representations [7], [11], [12]. These methods require image data to conduct recipe-related tasks. Recently, Li *et al.* has introduced Reciptor, a Set Transformer-based model [10] for learning recipe representations in a unsupervised fashion [9]. The authors pre-trained recipe representations from Recipe1M [8] using two loss functions which are the cosine similarity loss and the triplet loss. The authors of this work demonstrated the Set Transformer's effectiveness by using the pre-trained embeddings for food-related downstream tasks such as cuisine classification.

B. RECOMMENDATION IN FOOD DOMAIN

1) RECOMMENDING INGREDIENTS AND FOOD PAIRINGS Previous works related to food pairing discovery have been introduced where ingredient-ingredient relations are represented as edges in a network and its nodes denote the ingredients. Ahn *et al.* firstly proposed to define food pairings based on the number of flavor compounds shared between two ingredients [4]. Park *et al.* introduced Kitchenette, a Siamese Neural Networks based model trained on a largescale dataset Recipe1M [8] to predict food pairing scores and discover novel ingredient pairings [6]. Haussman *et al.* incorporated semantic-driven knowledge graphs for food recommendation [13]. While the previously mentioned authors either utilized chemical information in ingredients or a large recipe corpus in food pairing related tasks, Park *et al.* further proposed to incorporate both aspects to construct a large scale ingredient-compound network called FlavorGraph using metapaths [14].

Prior works on recommending ingredients have also been proposed. Shino *et al.* used ingredient categories and cooccurrence relations to suggest suitable alternative ingredient for a given recipe [15]. Liu *et al.* extended this approach by considering the diversity of ingredient categories and novelty of ingredient combinations [16]. De Clercq *et al.* used nonnegative matrix factorization and number of shared flavor compounds information to retrieve eliminated ingredients from recipes [3].

2) RECOMMENDING RECIPES

Previous works have focused on personalized recommendation of recipes using various features and employing machine learning-based approaches [17]–[20]. Ge *et al.* proposed to incorporate users' tags and ratings that indicate food preferences in recommendation [17], we employed a similar approach by utilizing recipe tag information such as *main dish*, *5-minute-cooking*. Other works have additionally taken nutrition-related factors into account to provide healthy food recommendations [21]–[24].

Perhaps one of the previous works that is closest to our task formulation is Cueto *et al.* [25]. The authors of this work employed memory-based collaborative filtering approaches to recommend ingredients for a given partial recipe. However, the dataset used in their work is small compared to our work as we trained our deep learning-based model on Recipe1M [8]. Moreover, while Cueto *et al.*'s model suggests only additional ingredients, our model is trained both on ingredient and recipe representations and provides each of their recommendations.

III. DATASET

A. PREPROCESSING ORIGINAL DATASET

We built an extended version of the Reciptor [9] dataset containing 507,834 recipes which is a subset of Recipe1M [7], [8]. Each recipe instance in our preprocessed dataset contains a list of ingredients, cooking instructions and cooking tags (630 unique tags) that were previously extracted from Recipe1M. Since the rich tag information (e.g., easy, healthy, seasonal [preference], main-dish, desserts, fruit [cuisine category], meat, vegetarian, low-calorie [diet information], american, european, asian [regional category]) from Reciptor would be helpful in our task [17], we crafted a 630-dimensional tag information binary vector for each

¹The code for RecipeBowl is available in https://t.ly/rV8t

Recipe	Information	Input Ingredients							Target Ingredients
Easy Garlic Chicken Breasts	Ingredients Score	chicken breasts 0.29	olive oil 0.17	garlic 0.24					lime juice 0.30
Garden Ranch Pizza	Ingredients	red bell peppers	ranch dressing	mozzarella cheese	parmesan cheese	broccoli	garlic clove		pizza crust
	Score	0.13	0.18	0.12	0.09	0.15	0.10		0.22
Creamy French <i>Dressing</i>	Ingredients Score	salt 0.06	garlic 0.14	sugar 0.09	dijon mustard 0.16	tomato paste 0.16	pepper 0.11	olive oil 0.10	red wine vinegar 0.18

TABLE 1. Examples of recipe completion data for RecipeBowl. Lime juice (0.30) in Easy Garlic Chicken Breasts, pizza crust (0.22) in Garden Ranch Pizza, and red wine vinegar (0.18) in Creamy French Dressing are selected as target ingredients.

recipe instance. We prepared 3,729 unique ingredients and a 80%/10%/10% randomly partitioned dataset. Prior to dataset construction, we excluded recipes with few (4 or less) ingredients from each of the partitioned dataset. Therefore, the dataset has 373,760 training recipes, 47,104 validation recipes and 47,104 test recipes.

B. SELECTING TARGET INGREDIENTS

We adopted De Clercq *et al.*'s recipe completion-based approach for training RecipeBowl [3]. The model is trained to predict a target ingredient *x* given a *leave-one-out*set *X* where *x* was previously eliminated from a *original* set *X* ∪ {*x*} of ingredients. Based on the above learning objective, we constructed a dataset for recipe completion where each instance includes an *leave-one-out* ingredient set, target ingredient and cooking tag information. Our main emphasis is to help the model learn cooking context based on the combinatory nature of various ingredients. In De Clercq *et al.*'s work, the target ingredients were selected randomly [3]. Among the randomly selected ingredients, commonly occurring ones such as salt and butter may act as trivial targets. These ingredients may render the model unable to differentiate the characteristics of ingredient combinations.

To prevent this, we selected target ingredients based on their Tf-Idf (Term Frequent-Inverse Document Frequency) score where terms and documents are ingredients and recipes respectively [26]. The Tf-Idf score indicates the relative importance of an ingredient within the recipe based on its occurrence in the whole corpus. We first calculated the Tf-Idf scores based on all ingredients, and then normalized them within each recipe where term frequency for each ingredient is always 1 in each recipe. We selected an ingredient *x* with the highest Tf-Idf score and eliminated it from each recipe.

Conclusively, the inputs for training RecipeBowl on recipe completion is the *leave-one-out* set *X* while the target is *x* for each recipe instance $X \cup \{x\}$. Table [1.](#page-2-0) shows the examples of our recipe completion dataset. In Table [1.](#page-2-0), the normalized Tf-Idf scores in *Creamy French Dressing* are low (e.g. salt (0.06) , sugar (0.09) , olive oil (0.10)). On the other hand, lime juice (0.30) in *Easy Garlic Chicken Breasts*, pizza crust (0.22)

FIGURE 2. Analysis on Target Ingredient Selection.

in *Garden Ranch Pizza* and red wine vinegar (0.18) in *Creamy French Dressing* have the highest normalized Tf-Idf scores.

We further justify our target selection approach by the following analysis. Figure [2.](#page-2-1) shows two distributions of target ingredients based on different selection options (Random and Tf-Idf). The distribution based on random selection is skewed where the highly frequent target ingredients based on random selection are commonly used ingredients (e.g. salt, butter and sugar) in most recipes. On the other hand, the distribution based on Td-Idf selection is relatively uniform which provides a better learning setting for RecipeBowl.

Along with recommending ingredients, RecipeBowl aims to simultaneously suggest recipe candidates. We utilized the pretrained recipe embeddings from Reciptor [9] as ground truths for training the recipe inference task of our model. Since the pretrained embedding vectors include sequential recipe context, we expect RecipeBowl to suggest acceptable recipe candidates and benefit ingredient recommendation.

IV. MODEL

A. OVERVIEW

RecipeBowl takes a set of ingredients as input and predicts a corresponding target ingredient and recipe as output (Figure [3.](#page-3-0)). The ingredients including the target are represented as continuous vectors retrieved from an embedding

FIGURE 3. Overall Model Description for RecipeBowl: An example recipe Easy Garlic Chicken Breasts is shown on the left side. Top K additional ingredient and candidate recipe recommendations are shown on the right side.

lookup table initialized by the ingredient node embeddings from FlavorGraph [14]. The target recipe vectors are pretrained embeddings retrieved from Reciptor [9]. The RecipeBowl consists of the Set Encoder and the 2-way Decoder. The Set Encoder encodes a set of ingredient vectors into a set context embedding space. The 2-way Decoder maps the set context vector into two different embedding spaces of different modality. The model is trained to approximate the predicted vector to its target ingredient and recipe vector in its corresponding embedding space and is trained in a multitask learning fashion.

B. SET ENCODER - LEARNING SET REPRESENTATIONS

We adapt the Set Transformer framework in our model as the Set Encoder module to build latent representations for incomplete sets of ingredients using attention mechanism [10]. In this work, we constructed the Set Transformer as a stack of components including Induced Set Attention Blocks (ISAB) and a Multihead Attention based pooling (PMA) layer. The ISAB is fed with a input set of vectors to calculate selfattention weights between the elements where the final output is also a set of equal size. The PMA layer aggregates the element-wise features by calculating their attention weights on a set of parameterized seed vectors. Both ISAB and PMA layer use Multihead Attention Blocks (MAB) which are the components of the Transformer model originally proposed by Vaswani *et al.* [27]. The MAB computes the attention function with multiple projections of the input queries and keyvalue pairs. Different from the Set Transformer in Li *et al.*'s Reciptor [9], we constructed our version of Set Transformer with one ISAB followed by one PMA layer.

1) MULTIHEAD ATTENTION

Given a set of *n* d_q -dimensional query vectors $\mathbf{Q} \in \mathbb{R}^{n \times d}$ and its corresponding key-value pairs $\mathbf{K} \in \mathbb{R}^{n \times d_k}$, $\mathbf{V} \in \mathbb{R}^{n \times d_v}$, an attention function takes Q as input and produces outputs

using K, V. In our model,
$$
d = d_q = d_k = d_v
$$
 for simplicity.

$$
Attention(Q, K, V) = \phi(QK^{\top})V
$$
 (1)

where ϕ is scaled softmax $\phi(\cdot)$ = softmax(\cdot / √ *d*). The outputs of the above function are expressed as a weighted sum of V where each value's weight is determined by a dot product scalar of its corresponding key and the query.

An extended version of this mechanism called Multihead Attention was introduced by Vaswani *et al.* where multiple projections are applied to the query and key-value vectors to produce different attention-based outputs [27]. The *k*-head attention function has *k* triplets of linear transformations $W_i^{\mathcal{Q}}$ $\mathcal{L}^{Q}_{i}, W^{K}_{i}, W^{V}_{i} (i \in \{1, 2, \ldots, k\})$ each applied to Q, K and *V* respectively. The *k* projections are each then fed into the attention function to produced *k* different outputs which are concatenated *k*-wise and finally projected into a *h*-dimensional space. The Multihead Attention is mathematically expressed as follows,

$$
\text{Multihead}(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = (O_1 \oplus \dots \oplus O_i \oplus \dots \oplus O_k)W^O \quad (2)
$$
\n
$$
O_i = \text{Attention}(\mathbf{Q}W_i^Q, \mathbf{K}W_i^K, \mathbf{V}W_i^V) \quad (3)
$$

where
$$
W_i^Q
$$
, W_i^K , $W_i^V \in \mathbb{R}^{d \times h}$, $W_i^O \in \mathbb{R}^{h \cdot k \times d}$.

2) MULTIHEAD ATTENTION BLOCK

While the query, key and value vectors involved in Multihead Attention may be different, the key and value vectors in the Multihead Attention Block are the same. Given two sets of vectors $X, Y \in \mathbb{R}^{n \times d}$, the MAB is mathematically expressed as follows,

$$
MAB(X, Y) = LayerNorm(H + RFF(H)))
$$
\n(4)
\n
$$
H = LayerNorm(X + Multihead(X, Y, Y))
$$
\n(5)

where RFF is a row-wise feedforward layer and LayerNorm is layer normalization ([28]).

3) SET ATTENTION BLOCK

The Set Attention Block was proposed by Lee *et al.* as an extension of the Multihead Attention Block to calculate selfattention weights between the vectors in a set [10]. The output from the SAB contains element-to-element interactions of the set. Higher order relations between the elements can be modeled through a stack of SABs. Our approach focuses on learning the combinatory nature of ingredients which provides a rationale for using SABs in the model architecture. Given a set of vectors $X \in \mathbb{R}^{n \times d}$, the SAB is expressed as follows,

$$
SAB = MAB(X, X) \tag{6}
$$

4) INDUCED SET ATTENTION BLOCK

Another extension variant of the Multihead Attention Block proposed by Lee *et al.* is the Induced Set Attention Block. The ISAB contains trainable inducing vectors that are fed with the element vectors into the MAB to compute the outputs which are again fed into another MAB with the same element vectors [10]. Given a set of input vectors $X \in \mathbb{R}^{n \times d}$ and a set of inducing vectors $\mathbf{K} \in \mathbb{R}^{\tilde{k} \times d}$, the ISAB is expressed as follows,

$$
ISAB = MAB(X, H) \tag{7}
$$

where $H = \text{MAB}(K, X)$.

5) MULTIHEAD ATTENTION BASED POOLING LAYER

One of the common permutation-invariant methods to aggregate the element-wise representations is element-wise summation [29], [30]. However, Lee *et al.* proposed aggregating the representations by applying multihead attention on another set of *m* parameterized seed vectors $S \in \mathbb{R}^{m \times d}$ [10]. Given a set of *n* ingredient vectors refined by the previous SAB or ISAB, $Z \in \mathbb{R}^{n \times d}$, pooling by Multihead Attention (PMA) is expressed as follows,

$$
PMA = MAB(Z, RFF(S))
$$
 (8)

6) SET TRANSFORMER

Conclusively, given an input set of ingredient vectors $I \in$ $\mathbb{R}^{n \times d}$ the Set Transformer we employed in our work is mathematically expressed as follows,

$S = \text{LayerNorm}(\text{ReLU}(\text{PMA}(I')W_s + b_s))I' = \text{ISAB}(I)$ (9)

where $W_s \in \mathbb{R}^{d \times h}$, $b_s \in \mathbb{R}^h$ are the weights and biases for the final nonlinear transformation in the Set Transformer and $S \in \mathbb{R}^h$ is the final latent representation for the set of ingredients. We denote this as the Set Encoder in our whole model architecture as it encodes a set of ingredients into a latent embedding space.

C. 2-WAY DECODER - PREDICTING INGREDIENTS AND **RECIPES**

The 2-way Decoder takes the set context vector concatenated with a 630-dimensional tag vector as input to generate the

d-dimensional target ingredient vector and *r*-dimensional target recipe vector. The tag vectors are constraints to guide the model's predictive space. Given the encoded set representation **S** $\in \mathbb{R}^d$ and the tag binary vector **T** $\in \{0, 1\}^{630}$, the predicted vectors for both the target ingredient $\hat{y}_p \in \mathbb{R}^d$ and recipe $\hat{y}_q \in \mathbb{R}^r$ are mathematically expressed as follows,

$$
\hat{y}_p = \text{LayerNorm}(\text{ReLU}((\mathbf{S} \oplus \mathbf{T})W_1 + b_1))W_2 + b_2 \quad (10)
$$

$$
\hat{y_q} = \text{LayerNorm}(\text{ReLU}((S \oplus T)W_3 + b_3))W_4 + b_4 \quad (11)
$$

where $W_1, W_3 \in \mathbb{R}^{h \times d}, W_2, W_4 \in \mathbb{R}^{d \times d}$ are trainable weights and $b_1, b_2, b_3, b_4 \in \mathbb{R}^d$ are trainable biases.

D. LOSS OBJECTIVE FUNCTION AND OPTIMIZATION

Given a pair of predicted and its ground truth target vectors (\hat{y}_p, y_p) , we employed a negative likelihood loss function based on a softmax over negative Euclidean distances in the ingredient embedding space [31], [32]. As we trained our model using batch sampling, the softmax for the Euclidean distance between the *i*th pair $(\hat{y}_p(i), y_p(i))$ is calculated over the batch of target ingredient vectors including $y_p(i)$. Given a batch B and model parameters Θ , the loss objective for RecipeBowl is mathematically expressed as follows,

$$
f(x, y) = -\sqrt{|x-y|^2}
$$
 (12)

$$
L_p\left(\hat{y_p}(i), y_p(i), \Theta\right) = -\log \frac{e^{\frac{\Theta(p(i), y_p(k))}{\tau}}}{\sum_{k=0}^{B-1} e^{\frac{f(\hat{y_p}(i), y_p(k))}{\tau}}}
$$
(13)

where τ is a temperature scalar for controlling model optimization [33]. The model is therefore is trained on a distance metric learning setting since the Euclidean distance between the predicted ingredient and target ingredient is minimized [31]. Given the *i*th target ingredient as thet positive sample, we adopted the idea of using all other *B* target ingredients in a batch as negative samples for better optimization [34]. We will denote this scheme as using in-batch negatives.

For training the model on recipe prediction given the *i*th pair (\hat{y}_q, y_q) in the training batch, we employed the cosine embedding loss defined as below,

$$
cosine(x, y) = \frac{x \cdot y}{\|x\| \|y\|}
$$
 (14)

$$
L_q(\hat{y}_q(i), y_q(i), \Theta) = 1 - \text{cosine}(y_q(i), y_q(i)) \quad (15)
$$

Finally, the multi-objective loss function for a batch of quadruplets $(\widehat{y_p}, y_p, \widehat{y_q}, y_q)$ is as below,

$$
L(\widehat{y_p}, y_p, \widehat{y_q}, y_q, \Theta) = \frac{1}{B} \sum_{i=0}^{B-1} L_p(i) + \frac{1}{B} \sum_{i=0}^{B-1} L_q(i) \quad (16)
$$

where $L_p(i)$, $L_q(i)$ are the simplified notations of the loss function for *i*th sample in batch.

V. EXPERIMENTS

A. EXPERIMENTAL SETTING

We conducted experiments to evaluate and compare our proposed RecipeBowl's performance on recipe completion task

with other model options. We firstly performed a simple preliminary experiment by giving each leave-one-out input set of ingredients the same list of ingredients sorted by their occurrence as target ingredient in the whole dataset. We denote this method as Popularity Choice. We selected traditional machine learning approaches for our baseline experiments to evaluate our proposed model architecture. We imported the pre-trained FlavorGraph embeddings and summed each of the input ingredients into a single 300-dimensional continuous vector [14]. We then concatenated it with its corresponding 630-dimensional cooking tag vector. As a result, the dimension of each input vector is 930. The baseline models that were used in this setting are Random Forest Classifier, Logistic Regression and MLP Classifier and were all imported from the Scikit-learn Python package [35]. They are multi-class classification models where the class labels are the 3,729 unique ingredients.

We additionally conducted baseline experiments on various types of Set Encoders to assess the use of our custom Set Transformer while retaining other model features in RecipeBowl such as the Decoder and use of cooking tag vectors. The baseline modules for the Set Encoders are the following,

- **Vanilla Sum:** The ingredient vectors from the Flavor-Graph embedding lookup table are summed into a single set context vector for each recipe input. This resembles the continuous bag-of-words model [36].
- **Bidirectional LSTM:** Previously used in recipe embedding experiments by Li *et al.* [9], this module encodes a sequence of ingredients in both directions into a set context vector.
- **Deep Sets:** Introduced by Zaheer *et al.* and used in Lee *et al.*'s baseline experiments [10], the Deep Sets model is a permutation-invariant deep learning model that builds deeper element-wise and set-wise representations through a stack of layers [30].
- **Reciptor:** Adopted from Li *et al.*'s [9], the Reciptor model is a Set Transformer containing 2 ISABS, 1 PMA and 1 SAB. All inherent MABs have 4 attention heads while each ISAB has 16 trainable inducing vectors and the PMA has 2 trainable seed vectors.

As our version of Set Transformer (1 ISAB, 1 PMA) is used in the RecipeBowl architecture as the Set Encoder, we denote other deep learning model variants by their corresponding Set Encoder since the other components in the model architecture are fixed.

1) MODEL TRAINING AND EVALUATION METRICS

We fit the traditional machine learning models into our large training dataset and evaluated their performance based on the predicted probabilities for each class (3,729 ingredients). The predicted list of probabilities were sorted for evaluative purposes. The deep learning architectures using various Set Encoder modules including RecipeBowl and its ablated versions were trained to the maximum of 60 epochs with early stopping using the AdaBound optimizer [37]. All models were trained on the same training dataset and evaluated on the same test dataset as well. The hyperparameters for RecipeBowl that were estimated using the validation dataset and are available in the anonymous code repository.

We retrieved the predicted ingredient vectors of test dataset from the deep learning models including RecipeBowl, to generate ranking-based recommendation results. We then calculated a pairwise matrix of cosine similarity scores between the vector predictions for the *incomplete* ingredient set in test dataset and 3,729 actual ingredient vectors. We sorted the similarity scores to obtain a ranked list of recommended ingredients. Both lists are used for evaluation based on multi-item recommendation. We used Mean Reciprocal Rank (MRR) and Recall@K (K=1,5,10) to evaluate the recommendation results derived from the scores.

B. EXPERIMENTAL RESULTS

1) MODEL PERFORMANCE

We made 10 different 80%/10%/10% random splits of our dataset to perform the main experiments on the recipe completion task. In addition, the random initialization of trainable parameters in deep learning models is different according to each of the random split. For each model configuration including the traditional machine learning models, we calculated the mean and standard deviation of each evaluation metric MRR, Recall@1, Recall@5 and Recall@10. We also conducted statistical tests to obtain p-values to prove RecipeBowl's statistical significance.

Table [2](#page-6-0) shows the evaluation results of RecipeBowl and other baseline models. Results show that RecipeBowl achieved the highest performance in all metrics (MRR: 0.2261 (0.0020), Recall@1: 0.1358 (0.0020), Recall@5: 0.3166 (0.0021), Recall@10: 0.4072 (0.0023)). According to the results, utilizing several model-related components and additional features such as tag vectors helped RecipeBowl outperform other model options. It is notable that our version of the Set Transformer used in RecipeBowl has less model complexity than Li *et al.*'s version used in Reciptor [9] which led to better generalization results (MRR: 0.2103 (0.0011)).

2) ABLATION STUDY ON GENERAL MODEL ARCHITECTURE

We performed ablation tests to find whether 1) utilizing recipe context information, 2) employing a negative likelihood loss function based on a softmax over euclidean distances with in-batch negatives, 3) using the pre-trained FlavorGraph vectors as initial embeddings for RecipeBowl and 4) adding a Decoder before projecting the set context vectors into another embedding space were effective or detrimental to RecipeBowl's training.

Table 3 shows the ablation results on RecipeBowl. All ablation experiments were performed using the first random split of our dataset. The ablation results illustrate the importance of selecting the right loss criteria for training RecipeBowl. Combining the effects of distance metric learning and in-batch

TABLE 2. Evaluation results. Best results are in bold. All experiments were repeated 10 times with different splits. All results except Popularity Choice have mean and standard deviation for each metric. All results compared to RecipeBowl have a p-value below 0.05 as result of significance test.

Types	Models	MRR	Recall@1	Recall@5	Recall@10
Simple Statistics	Popularity Choice	0.0080	0.0019	0.0019	0.019
Traditional Machine Learning Methods	Random Forest Logistic Regression Simple MLP	0.0077(0.0002) 0.1354(0.0011) 0.1685(0.0031)	0.0019(0.0002) 0.0754(0.0010) 0.0955(0.0006)	0.0083(0.0003) 0.1888(0.0013) 0.2349(0.0028)	0.0155(0.0005) 0.2535(0.0015) 0.3141(0.0053)
Deep Learning Methods	Vanilla Sum Bi-directional LSTM Deep Sets Reciptor RecipeBowl	0.2178(0.0040) 0.2024(0.0071) 0.2126(0.0082) 0.2103(0.0011) 0.2261(0.0020)	0.1300(0.0035) 0.1199(0.0057) 0.1258(0.0065) 0.1249(0.0011) 0.1358(0.0020)	0.3044(0.0046) 0.2831(0.0094) 0.2975(0.0109) 0.2936(0.0015) 0.3166(0.0021)	0.3965(0.0058) 0.3681(0.0104) 0.3872(0.0114) 0.3807(0.0024) 0.4072(0.0023)

TABLE 3. Ablation test results. The best results are in bold. All results were obtained from experiments on the first random split of out dataset.

negatives randomly containing both easy and hard (highly related to targets) ingredient negatives seemingly benefit RecipeBowl's performance.

In terms of model architecture, results show RecipeBowl's dependency on both the 2-way Decoder (MRR: 0.1343) and tag vectors (MRR: 0.1463). Considering the risks of multitask learning, our ablation results show that recipe prediction task does not negatively affect RecipeBowl but rather boosts by a small amount (MRR: 0.2153). Though we imported the pre-trained FlavorGraph embeddings from Park *et al.*'s work, our ablation results show less difference in performance (MRR: 0.2153) leaving room for further investigation.

VI. ANALYSIS

A. RecipeBowl RECOMMENDATIONS

The RecipeBowl accepts any ingredient sets and recommends additional ingredients and candidate recipes which is illustrated in Figure [3.](#page-3-0) In Table [4,](#page-7-0) we show six different user input examples with different cooking tags. Here, we recommend top 10 ingredients and top 5 recipes. Our model made accurate ingredient predictions (bold-faced) for the first four examples. In addition, RecipeBowl provided relevant and plausible alternatives other than the actual target ingredient in those examples. Moreover, RecipeBowl served its purpose as a 2-way recommender given the recommended recipe titles that are relevant to both the user input and cooking tags.

For the last two examples in Table [4,](#page-7-0) although RecipeBowl did not predict the correct target ingredients (bold-faced, torillas, cooked white rice), there were still meaningful suggestions. For the Mexican dish, our model recommended tortilla chips at top 1 while tortillas are ranked third. For the Rice dish, while our model did not predict perfectly (cooked white rice, out of top 10), most of the recommendations are still aligned with the target ingredient (e.g. wild rice, yellow rice). We expect RecipeBowl's flexibility and understanding in cooking to be helpful in making cooking choices.

B. ANALYSIS ON PREDICTIONS IN EMBEDDING SPACE

Figure [4.](#page-7-1) shows the distribution of both target and predicted embeddings vectors. While the predicted ingredients are close to their corresponding targets, the embedding seemed to be clustered into eight categories overall. This shows that the RecipeBowl model learned not only the optimal ingredient for the given set but also recipe categorical features.

Figure [5.](#page-7-2) shows the distribution of sixteen target embeddings and their corresponding predictions which is illustrated in the *Embedding Space* of Figure [3.](#page-3-0) In this analysis, 16 target ingredients were randomly selected according to their ingredient categories along with their predictions in the test dataset. Most of the predicted ingredients tended to form clusters corresponding to the selected targets. Moreover, some target ingredients are centered in the prediction clusters (e.g. mashed bananas, bread, chicken breasts). Interestingly, clusters that belong to the same ingredient category (e.g. pork chops, chicken wings, chicken breasts) tend to be relatively close to each other. We also found target pairs bread flour&yeast and cocoa&chocolate being close to each other along with their prediction clusters. Bread flour and

TABLE 4. RecipeBowl Recommendation Results. Examples of these six cases are all from the test set. For the first four examples, RecipeBowl model accurately predicted the target ingredient (bold-faced), but the last two examples, it did not. However, the recommendations still seem reasonable.

FIGURE 4. Predicted ingredient vector embeddings. (10,000 sampled in test).

yeast are known to be used together in most recipes while cocoa is one of the materials for making chocolate chips. These observations show that the RecipeBowl model learned ingredient relationships during training.

C. ANALYSIS ON SET REPRESENTATION VECTORS

Figure [6.](#page-8-0) shows clustermaps of 150 randomly sampled set context embedding vectors. The *Set Context Embeddings* according to Figure [3](#page-3-0) are the set-wise vectors from the *Set*

FIGURE 5. Predicted ingredient vector embeddings. (Sampled according to 16 target ingredients).

Encoder, prior to being propagated to the *2-way Decoder*. We selected blueberries, apples, buttermilk and chocolate chips from the previous list used in t-sne visualization and extracted incomplete ingredient lists with equal size of 150 containing each of them from the test dataset. We then used the Set Encoder of RecipeBowl to generate 4 groups of 150 set context vectors and visualized a clustermap for each group. We selected blueberries and apples since both of them are fruit ingredients used in a wide variety of dishes.

FIGURE 6. Clustermaps of 150 set context vector embeddings for each target ingredient. The dimension size of each set context vector is 64. The recipe names for each recipe cluster are representative examples.

FIGURE 7. Attention weights of ingredients for each set input. Bold-faced are target ingredients. The rest are input ingredients with attention values transformed by min-max normalization for each recipe.

On the contrary, we additionally selected buttermilk and chocolate chips that may be used in limited recipe categories such as bakery and desserts. The clustermaps shown in Figure [6.](#page-8-0) seemed to show distinctive clusters which brought interesting insight. For example, apples can be used in a wide range of recipes such as sweet desserts (*Caramel Apple*), bakery foods (*Apple Maple Muffin*) or as sauces in meatbased dishes (*Apple Pork Chops*) [38], [39]. Buttermilk is widely used in bakery products due to its nutritional value and taste enhancement features [40]. We can observe that among the sampled 150 set context vectors including buttermilk, most of them were used in bakery recipes (*Basic Chocolate Cake*). Overall, RecipeBowl can distinguish different types of recipe context according to the uses of a particular ingredient. The detailed clustermaps for these ingredients can be found in the code repository.

which ingredient seems to have high influence towards building the set context vector. For *Spicy Tuna Salad Roll*, nori recieved the highest attention which helped RecipeBowl understand the set input is mainly Japanese cuisine. For *BBQ Chicken Pizza*, chicken breasts, fresh cilantro and red onions were majorly attentive interestingly compared to mozzarella cheese. Lastly, the input set for *Casserole Quiche* contained ingredients mainly used in Mexican cuisine such as bell peppers and chili peppers [41], [42]. In turn, we speculate that RecipeBowl was able to predict tortilla chips based on highly

D. ANALYSIS ON ATTENTION WEIGHTS IN SET ENCODER Figure [7.](#page-8-1) shows attention weights of the input ingredients. We extracted and aggregated the attention values computed in the first MAB of the ISAB in RecipeBowl's Set Encoder in Figure [3](#page-3-0) and normalized them with min-max scaling. We studied the recommendation examples and observed attentive values of the above ingredients as tortilla-related ingredients are also commonly used in Mexican dishes.

VII. CONCLUSION AND FUTURE WORK

We introduce RecipeBowl, a set-based cooking recommender for candidate ingredients and recipes. To train the model, we formulate a supervised learning recipe completion setting using an extended dataset from Reciptor [9]) and employing the Set Transformer [10] framework to encode ingredients into a set context representation. Based on the evaluation results from the formulated recipe completion task, our model showed best results among other set encoding variation baselines and traditional machine learning algorithms. Recommendation results demonstrate RecipeBowl's ability to generate both plausible and diverse recommendations for a given set of ingredient. We performed in-depth model analysis on RecipeBowl (illustrated in Figure [3\)](#page-3-0) in a bottomto-top fashion starting from the predicted Embedding Space where the vector embeddings formed meaningful clusters. We also investigated the visualizations of the set context vectors which are the direct outputs from the Set Encoder and examined the attention weights extracted from the Set Encoder itself and found them supportive to our model's performance. In sum, our formulated recipe completion task and set representation approaches were proved to be beneficial in suggesting ingredients and recipes.

For the future work, while RecipeBowl was able to suggest both appropriate ingredients and recipe candidates for a given set of other ingredients, some recipe candidates seemed inconsistent with the suggested ingredients. We plan to improve RecipeBowl by encouraging it to recommend recipe candidates related to some of its suggested ingredients. Though our RecipeBowl exploited our custom-made Set Transformer to be trained successfully on recipe completion, we plan to improve the Set Encoder to extract richer cooking knowledge and provide better interpretability. Since the recipe completion task involves the input ingredient set having only one ingredient removed as the prediction target for each recipe, we acknowledge that the model may have limitations in generating recommendations given a few ingredients. We plan to address this issue in future work by formulating a more suitable task setting. In addition, we plan to incorporate nutritional features and consider dietary requirements during recommendation. Lastly, we plan to release an applicable version of RecipeBowl.

ACKNOWLEDGMENT

(Mogan Gim and Donghyeon Park contributed equally to this work.)

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