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Improving Recurrent Neural Network Responsiveness to Acute Clinical Events

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ABSTRACT Predictive models in acute care settings must immediately recognize precipitous changes in a patient's status when presented with data reflecting such changes. Recurrent neural networks (RNN) have become popular for clinical decision support models but exhibit a delayed response to acute events. New information must propagate through the RNN's cell state before the total impact is reflected in the model's predictions. Input data perseveration is a method to train more responsive RNN-based models. Input data is replicated *k* times during training and deployment. Each replication propagates through the cell state and output of the RNN, but only the output at the final replication is maintained and broadcast as the prediction for evaluation. De-identified Electronic Medical Records (EMR) of 12, 826 patients admitted to a tertiary care pediatric academic center between 01/2009-02/2019 were analyzed. A baseline Long Short-Term Memory (LSTM) model $(k = 1)$, four LSTMs with increasing amounts of input data perseveration $(k = 2)$ to *k* = 5), and an LSTM with an attention mechanism were trained to predict ICU-mortality. Performance of models was compared using Area Under the Receiver Operating Characteristic Curve (AUROC) after increasing periods of observation from one to 12 hours. The average variation of the change in predicted mortality immediately following defined acute events measured responsiveness. The AUROC gains due to input perseveration were larger at the earlier times of prediction $(<$ 6 hours), increasing at the first hour from 0.77 with no input data perseveration to 0.83 when $k = 5$. An LSTM with $k = 5$ was $2 - 3$ times more responsive to acute events than a baseline LSTM.

INDEX TERMS Electronic medical records, health and safety, Kalman filters, long short-term memory, machine learning, performance evaluation, predictive models, real time systems, recurrent neural networks, time series analysis.

I. INTRODUCTION

A. THE PROBLEM

Critical care environments require rapid decision making. To be meaningful, predictive models in these settings must immediately recognize precipitous changes in a patient's state when presented with data reflecting such changes [1], [2]. Newly acquired patient data must be integrated quickly with previous data and the model's predictions rapidly updated to inform clinical decisions in a timely fashion.

Long Short-Term Memory (LSTM) models [3] are a type of Recurrent Neural Network (RNN) architecture and have become increasingly popular for modeling tasks in clinical settings [4]–[10]. In particular, they previously have been shown to achieve significantly higher predictive performance

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than clinical severity of illness (SOI) scores based on assessing a child's risk of mortality in an intensive care unit (ICU) [11]. Critical care requires constant re-evaluations of a patient's status, and the desire for a tool that automatically and continuously evaluates a patient's status in the ICU is underscored by studies investigating the continuous application of static clinical scores [12]–[14]. The RNN is suited for providing automatic and continuous patient monitoring and assessment because of its ability to make ongoing concurrent predictions with new data integrated into the patient's historic context, instead of merely recalculating a new prediction at a single isolated time. The RNN requires computational cycles to incorporate new data into its memory cell [15], which results in a behavior that is recognized but not well described in the literature: when integrating new data, there is a delay between the input and a change in the prediction [16]. This characteristic is frequently observed in stock prediction

tasks where the apparent predictive capability of a model is comparable to a model that predicts the last observed stock price [17], [18]. The intersection of deep learning and healthcare, though ever widening, has a paucity of literature on this phenomenon. Commonly reported metrics such as area under the receiver operating characteristic curve, sensitivity, specificity, and mean absolute errors reflect only the accuracy of the final predictions but do not account for this time lag.

In critical care applications, we have noticed two distinct but related observable effects of the time lag. The first occurs during what we refer to as a *pipe-up* period, during which the initial input propagates through the memory cell to overcome the initialized cell state before that input significantly influences the predictions. The second occurs during subsequent times when new information only slightly changes the overall prediction of a model at the time of input, again requiring propagation through the memory cell before fully augmenting the model's prediction. The first phenomenon is a special case of the second. These two effects are further illustrated in Sections [II-D](#page-3-0) and [III.](#page-4-0)

B. PROPOSED SOLUTION

This work aims to enable more timely changes in RNN predictions when a model is presented with data indicating acute clinical events. Because the RNN requires computational cycles to incorporate new data into its memory cell, and because ICU EMR data is usually presented hourly, we reasoned that repeating computational cycles at the time new data becomes available, that is *perseverating* the data presentation to the network, would decrease the response time of the RNN predictions. Instead of giving newly available input data to an RNN model only once, the input is replicated, or *perseverated*, and given to the model multiple times, during both training and deployment, with only the prediction of the final perseveration maintained and made visible to the end-user. This technique of *perseverating* an input *k* times provides additional computational cycles for new data to be incorporated into the model's internal states before a prediction is broadcast. We hypothesized that the resultant model would react to acute events more quickly than traditionally trained LSTMs, reduce the *pipe-up* time to overcome the initialized cell state, and still maintain overall model performance.

C. RELATED WORKS

Since the seminal paper by R.E. Kalman in 1960 describing what is now called the Kalman Filter [19], engineers have been aware of the tradeoff between integrating historical data and responding to new data. Most training techniques used in modern deep learning affect the balance between relying on historical trends and responding to new information; such techniques include dropout, optimizers, and activation functions [20]–[23]. Generating an appropriate target vector (e.g. using changes in values between consecutive time points instead of predicting raw values) is another training technique that can prevent generation of an auto-correlation model [16].

Attention mechanisms [24] are sometimes used to manage the balance between historical and new data by appending the entire input sequence to the final hidden layer of an RNN. Doing so affords the model another opportunity to learn model weights which expose the moments in time series data most relevant to the predictions. Attention networks were originally developed for post-hoc sequence-to-sequence modeling tasks such as image captioning and neural machine translation which permit access to the entire input sequence when making predictions [24], [25]. An attention mechanism was applied by Zhang, *et al.* to predict risk of future hospitalization using medical records from a fixed observation window [26].

While an attention mechanism allows the model to weight isolated time vectors that are important to the target prediction, *input perseveration* allows all information to propagate through both the input and the memory cell and enables the existing machinery of the RNN (namely *backpropogation*) to determine the magnitude of their contribution.

II. METHODS

A. CLINICAL DATA SOURCES

Data for this work were extracted from de-identified observational clinical data collected in Electronic Medical Records (EMR, Cerner) in the Pediatric Intensive Care Unit (PICU) of Children's Hospital Los Angeles (CHLA) between January 2009 and February 2019. The CHLA Institutional Review Board (IRB) reviewed the study protocol and waived the need for IRB approval. A patient record included static information such as gender, race, and discharge disposition at the end of an ICU *episode*, defined as a contiguous admission in the PICU. A patient may have multiple episodes. The EMR for an episode also contained irregularly, sparsely and asynchronously *charted* measurements of physiologic observations (e.g. heart rate, blood pressure), laboratory results (e.g. creatinine, glucose level), drugs (e.g. epinephrine, furosemide) and interventions (e.g. intubation, oxygen level). Episodes without discharge disposition were excluded, leaving 12,826 episodes (9,250 patients) in the final dataset.

Prior to any of the computational experiments described here, the episodes were randomly partitioned into three sets: a training set for deriving model weights, a validation set for optimizing hyper-parameters, and a holdout test set for measuring performance. To minimize bias in the performance evaluation metrics, partitioning was done at the patient level, i.e. all episodes from a single patient belonged to only one of these sets: 60% in the training set, 20% in the validation set, and 20% in the test set. No other stratification was applied. Table [1](#page-2-0) displays basic characteristics of the resulting data partitions.

Preprocessing steps described in previous work [27] converted each episode data to a matrix structure amenable to machine learning model development. A row of values in this matrix represented measurements (recorded or imputed) of

TABLE 1. Basic demographics of data used in this study for each data partition.

FIGURE 1. The perseverating recurrent neural network (PRNN) is an RNN with repeating inputs. Each input vector, $x(t_j)$, associated with a particular time, t_i , is replicated \bm{k} times, and only the output from the last replication, $y(t_i)$, is considered as the prediction for that time. The diagram above illustrates the process for $k = 3$.

different variables at one particular time, while a column contained values of a single variable at different times. A summary of the preprocessing may be found in Appendix [A.](#page-7-0) A complete list of variables used as model inputs can be found in Appendix [B.](#page-10-0) Note that diagnoses, while available in the EMR, were not used as input features.

B. TARGET OUTCOME

ICU mortality was chosen as the target outcome because it is a simple, unambiguous outcome. Importantly, risk of mortality (ROM) is used commonly as a proxy for severity of illness in critical care [13], [28]–[30]. The overall mortality rate of the data was 3.7% (Table [1\)](#page-2-0).

C. RNN MODELS

Many-to-many recurrent neural network models, consisting of stacked Long Short-Term Memory (LSTM) layers followed by a dense layer, were trained to predict ROM in the ICU of each patient episode. All the models output a probability of mortality at each distinct time where an observation or measurement of the patient was made, generating a trajectory of scores that reflect the changing status of a patient during their ICU episode.

The *baseline* RNN model was trained in the traditional manner: when the model acquired new data $x(t_i)$, it generated and immediately broadcast a prediction $y(t_i)$. Other models which share the architecture of the baseline RNN model were

FIGURE 2. Overview of a standard RNN model with a causal attention layer.

trained using input *perseveration*: the same $x(t_i)$ vector was repeatedly given as input to the RNN model *k* times, where *k* is a controllable parameter. While all *k* outputs – corresponding to the *k* times that $x(t_i)$ was given to the model – were used for optimization during training, only the last one was maintained and broadcast as the prediction at time *tⁱ* during performance assessment and deployment. Figure [1](#page-2-1) illustrates a *Perseverated Recurrent Neural Network* (PRNN) model with $k = 3$. A python implementation of a perseveration layer written with PyTorch 1.7.1 can be found in Appendix [D.](#page-10-1) Note that the baseline RNN can be considered as a PRNN with $k = 1$. Input perseveration provides the internal cell state memory of the RNN additional computational cycles to incorporate the current state of the patient into the final prediction.

An attention network using the same hyperparameters of the baseline RNN model was also implemented. Most attention networks have access to the entire sequence of inputs – both past and future relative to the current one – when making a prediction at any point in time. However, continuous monitoring of patient status precludes access to future information, available in a retrospective study but not in a real deployment scenario. Therefore, the attention layer between the last hidden layer and output layer used a *causal mask* that exposed only the inputs up to the time when a prediction is being made [31]. This ensured that the network did not use future information to make its predictions while affording it another opportunity to consider the totality of information up to the current time. See Figure [2](#page-2-2) for a diagram of the model.

All six models – baseline RNN $(k = 1)$, PRNN for $k = 2, 3, 4, 5$, and attention RNN – were implemented and

TABLE 2. Hyperparameters for all permutations of the PRNN.

Hyperparameter	Value
Number of LSTM Layers	3
Hidden Units in LSTM Layers	[128, 256, 128]
Batch Size	32
Initial Learning Rate	$1e-5$
Loss	binary cross-entropy
Optimizer	rmsprop
Dropout	0.2
Recurrent Dropout	0.2
Regularizer	0.0001
Output Activation	sigmoid

trained using Keras 2.0.7 with the Theano 1.0.2 backend [32], [33]. For each model, weights were optimized on the training and validation sets; performance was computed on the validation set after every epoch (i.e. a full cycle through the training set), and the best performing weights were saved as the final model. Table [2](#page-3-1) displays the hyperparameters that were used for all six models. The final models were assessed for performance metrics on the test set.

D. MODEL ASSESSMENTS

Standard metrics such as the Area Under the Receiver Operating Characteristic Curve (AUROC), precision, and recall scores for a binary classification task can capture a model's overall predictive performance. These metrics at a single time point do not measure the lag phenomenon displayed by LSTMs that, although known, is rarely commented on in the literature. The trajectory of ROM predictions should reflect the evolving state of a patient which can have instantaneous changes. Metrics were designed to quantify a model's pipeup behavior and its ability to capture rapid changes resulting from clinically adverse events. AUROC was used to compare overall predictive performance for the main task – predicting ICU mortality.

1) PIPE-UP BEHAVIOR

A model's prediction at the first time point is a function of its model weights, initial state of its memory cells and the first input. Of these, only the first input varies across different patient episodes; therefore, the distribution of a model's prediction at the first time point of all episodes indicates the model's level of reliance on the first input data. We refer to this period as the *pipe-up* period.

The mean and standard deviation of the distribution of all $\hat{y}_p(t_0)$ predictions, where $\hat{y}_p(t_0)$ represents the first prediction for patient episode *p*, were computed for all survivors and non-survivors in the test set. These metrics were computed for all six RNN models and used to compare their responsiveness to the first available information about a patient episode.

Additionally, to assess the temporal increase in responsiveness, the AUROCs for the $k = 1$ and $k = 5$ models described in the previous section were computed for increasing periods of observation from one to 12 hours.

2) RESPONSIVENESS TO ACUTE EVENTS

The models were also assessed for their initial responses to clinically adverse events using an average variation metric computed from the predictions during such periods. In consultation with clinicians, the times when any of the following occurred were defined as acute time points or intervals:

- 1) a patient's heart rate fell to 0;
- 2) there was a *substantial* decrease in heart rate, mean arterial pressure, Glasgow Coma Score, blood oxygen level (SpO2), arterial blood gas (ABG) pH, and venous blood gas (VBG) pH between two consecutive recordings;
- 3) there was a *substantial* increase in creatinine levels or inotrope score between two consecutive recordings.

We quantified *substantial* changes as those that were in the top or bottom *X* percentile $(X \in \{5.0, 1.0, 0.5\})$ of inter-measurement changes. For example, a time point *tⁱ* was considered acute in terms of creatinine when the *increase* in creatinine level from t_{i-1} to t_i was in the top *X* percentile of all creatinine level percent changes between any two consecutive time points in the test dataset. Similarly, acute time points for heart rate were those times when the *decrease* in heart rate was in the bottom $X\%$ of all heart rate changes between any two consecutive time points of all test set episodes. Table [3](#page-4-1) shows the specific percent change thresholds indicating *acute* changes in a patient. Thus, a 32% drop in heart rate between two consecutive measurements would be in the top percentile, while a 70% increase in inotrope score would be in the top fifth percentile.

Applying three percentile-based thresholds to define acute patient state changes meant a total of 25 acuity definitions (2 * 3 increases in measured variables, 6 * 3 decreases in measured variables, and zero heart rate) used to assess models' responses when such events occur. It is important to note that these are not proposed as general definitions of clinical acuity. They were designed to capture events that indicate precipitous changes in a patient's state with high specificity.

Each defined acute event, denoted by *E*, identified a set of *acute time points*, denoted by $S_E(p)$, for each patient episode *p*. Changes in a model's mortality prediction at these time points were evaluated through an average temporal variation metric given by:

$$
V_E(p) = \frac{100}{|S_E(p)|} \sum_{t_i \in S_E(p)} |\hat{y}_p(t_i) - \hat{y}_p(t_{i-1})|, \tag{1}
$$

where $\hat{y}_p(t_i)$ is the prediction for patient episode *p* at time point t_i , and $|S_E(p)|$ is the number of time points in $S_E(p)$. This metric measures how much the predicted ROM (scaled to [0, 100]) changed, on average, at the defined acute time points of an episode. Model *A* having a higher $V_E(p)$ than model *B* means that when both models were presented with data reflecting a precipitous change in a patient's state, model *A*'s prediction underwent a greater change than model *B*'s prediction, indicating that model *A* had a more pronounced response to the acute event. The average of this metric across

TABLE 3. Thresholds of percent change used to define acute changes in patient state. Negative thresholds correspond to the bottom p % of changes and positive thresholds correspond to the top p % of changes, for $p \in [5, 1, 0.5].$

	5%	1%	0.5%
Heart Rate	-18.8	-31.6	-37.1
Mean Arterial Pressure	-23.5	-38.1	-44.2
Glascow Coma Score	-50.0	-72.7	-72.7
Pulse Oximetry	-5.6	-20.2	-35.1
ABG pH	-1.5	-2.9	-3.5
VBG pH	-1.4	-2.6	-3.1
Inotrope Score	66.7	150.0	250.0
Creatinine	33.3	60.5	81.8

 N_p episodes gives a measure of the model's overall responsiveness to acute event *E* of those episodes:

$$
\bar{V}_E = \frac{1}{N_p} \sum_p V_E(p). \tag{2}
$$

3) OVERALL PREDICTIVE PERFORMANCE

Model predictions at ICU admission and at 1, 3, 6, 12, and 24 hours after ICU admission were evaluated for predictive performance via the AUROC. Performance was only measured for episodes lasting at least 24 hours to maintain a consistent cohort across time slices ($n = 2130$, mortality rate $= 0.046$.

III. RESULTS

Figure [3](#page-4-2) illustrates trajectories of ROM predictions from two models, the baseline RNN $(k = 1)$ and a PRNN with $k = 5$, for two non-surviving episodes. In the first episode (top), the patient had a rapid desaturation event (Sp02 dropping from 100% to 33%) 6 hours after ICU admission. When presented with this defined acute event, the baseline RNN's mortality prediction increased from 0.031 to 0.065, while the PRNN $(k = 5)$ model's mortality prediction increased from 0.035 to 0.265. In the second episode (bottom), the patient's Glasgow Coma Score decreased from 7 to 4. When presented with this defined acute event, the baseline RNN's ROM prediction increased from 0.24 to 0.30, while the PRNN $(k = 5)$ model's ROM prediction increased from 0.31 to 0.50. In either case, the PRNN model's immediate response to an acute event was more pronounced than that of the baseline RNN model. Further, the trajectory of the baseline RNN's predictions after either acute event appears to lag behind that of the PRNN by about 1-2 hours.

The remainder of this section describes the results from aggregating the assessment metrics described in Section [II-D](#page-3-0) across episodes in the test dataset.

A. PIPE-UP BEHAVIOR

Figure [4](#page-5-0) shows the distribution of ROM predictions at the first observation. The mean mortality prediction for survivors decreased with the perseveration parameter *k*, going from 0.32 $(k = 1)$ to 0.10 $(k = 5)$. For both survivors and non-survivors, the standard deviation of the ROM predictions

FIGURE 3. Two examples of predictions following acute events in two individual patient episodes. The blue curves correspond to the baseline $(k = 1)$ model, while the orange curves correspond to the PRNN model with $k = 5$. The dotted vertical lines denote onset of an acute event for each patient: (A) a patient whose oxygen saturation decreased from 100% to 33%; (B) a patient's Glasgow Coma Score decreasing from 7 to 4, indicating significantly reduced levels of consciousness.

increased with *k*. The increase in standard deviation was greater in the non-survivors, going from 0.03 ($k = 1$) to 0.13 $(k = 5)$.

Figure [5](#page-5-1) shows the AUROCs of the $k = 1$ and $k = 5$ models at the first 12 hours of each episode. The $k = 1$ curve is shifted to the right of the $k = 5$ curve by approximately one hour.

B. RESPONSIVENESS TO ACUTE EVENTS

Figure [6](#page-6-0) displays the average variation, \bar{V}_E , as a function of *k* and acuity definitions. Two trends are apparent. First is the behavior of \overrightarrow{V}_E as a function of percentile change in a given physiologic observation or intervention. For each model, the resulting average variation increased as the change in a physiologic or intervention variable became more severe (i.e. from 95.0 to 99.5 percentile). Generally, the average variation increased monotonically as *k* increased across all definitions

FIGURE 4. Distribution of model predictions at the first available observation for survivors and non-survivors.

FIGURE 5. Performance for two models ($k = 1$ and $k = 5$) over the first 12 hours of an ICU episode.

of acuity. The attention layer generally demonstrated lower average variation than the $k = 1$ model.

C. OVERALL PREDICTIVE PERFORMANCE

Table [4](#page-5-2) summarizes the AUROC of model predictions at different times after ICU admission of all episodes in the test set that lasted at least 24 hours. The AUROC gains due to input perseveration were larger at the earlier times of prediction $(t \leq 6$ hours), increasing at the first hour from 0.77 when k=1 to 0.83 when $k = 5$. By the 12th hour, the AUROC did not significantly change with the perseveration parameter *k*. For all models, performance increased with greater observation time and reduced lead time [34]. Adding an attention layer had similar performance as the baseline model $(k = 1)$ at **TABLE 4.** Test set AUROCs for the mortality prediction at admission and after 1, 3, 6, 12, and 24 hours of observation. Only the patient episodes lasting at least 24 hours of ICU time were evaluated.

all evaluation times. The complete ROC curves for each time slice can be found in Appendix [C.](#page-10-2)

IV. DISCUSSION

Real time predictions for ICU mortality are proxies for severity of illness [13], [28], [30], [35] and should reflect condition or status in response to a change in observations of the patient. The examples in Figure 3 show that the mortality model trained with input perseveration (PRNN with $k = 5$) responded more pronouncedly and immediately than the traditionally trained model $(k = 1)$ when both were presented with data reflecting acute changes. Subsequent to the acute changes, the responses of the traditional RNN appeared to lag behind the PRNN's. Standard metrics such as AUROCs for classification or mean absolute errors for continuous regression at a single time point do not elucidate this predictive lag and other deleterious behaviors that can be detrimental in critical or intensive care settings where rapid recognition and response are crucial.

Input perseveration provides the RNN's internal cells additional computational cycles to incorporate the current state of the patient into the final prediction. The effect of this method was demonstrated by metrics designed to capture a model's initial responses to newly acquired data.

FIGURE 6. Comparison of the average variation metric \bar{V}_E of different models as defined by Equation [2](#page-4-3) across all test set episodes, where the events are defined by: A) a 95th percentile change; B) a 99th percentile change; C) a 99.5th percentile change; D) a cardiac arrest.

The variation metric described in Section [II-D2](#page-3-2) compares the models' initial responses to data indicating precipitous changes in a patient's status. These changes may require quick reaction time from the care team, therefore rapid responsiveness of the predictions is important. The comparison of variation metrics from the different models (Figure [6\)](#page-6-0) shows that the LSTM became more responsive to acute clinical events as the level of perseveration, *k*, increased. When *k* increased from 1 to 5, the variation metric corresponding to the defined precipitous events increased by a factor of 2-3 times. This means that the predicted mortality risk after an acute event was 2-3 times more pronounced when perseveration was set to $k = 5$ compared to a baseline LSTM $(k = 1)$ or an attention network. The results also show that a given model's responsiveness increased with more acute events (i.e. those belonging to higher percentile changes for a given physiologic or intervention variable). These are consistent with expectations about the variation metric. For example, one would expect the increases in ROM predictions to be greater for large drops in blood gasses than for less severe drops.

Figure [4](#page-5-0) compares the distributions of initial predictions from the different models. Since the first prediction is a function of both the initial input (which varies across episodes) and the initial cell state memory (which is fixed), a wider distribution of these predictions across episodes indicates a higher reliance on the initial input. This is important because children admitted to the PICU have different severities of illness [28], [30]. Increasing *k* resulted in a wider distribution of predictions as measured by the standard deviation. The increase was greater for the non-surviving population $(\sigma = 0.03 \text{ when } k = 1 \text{ to } \sigma = 0.13 \text{ when } k = 5) \text{ relative to }$ the surviving population. This is again consistent with clinical expectations that the non-surviving population would have a broader range of initial SOI scores (especially in the tail) than the surviving population.

Increasing the first prediction's reliance on the initial measurement – as achieved by the PRNN models with higher *k* – also resulted in higher AUROC at ICU admission (Table [4\)](#page-5-2). As the models observed the patient longer, their AUROCs increased as expected. Importantly, the increase of AUROC due to perseveration was greater at the early hours $(t < 3)$ when information is most scarce, with the 1-hour AUROC increasing from 0.77 when $k = 1$ to 0.83 when $k = 5$. This means that LSTM-based predictive clinical models relying on scarce data for early detection could benefit from the perseveration approach.

Figure [5](#page-5-1) and Table [4](#page-5-2) demonstrate that a PRNN model $(k = 5)$ more quickly overcame the initialization state of the network during the *pipe-up* period than the baseline model $(k = 1)$. A clear translation of approximately 1 hour indicates the ability of the PRNN model to more quickly integrate the patient observations and provide more responsive predictions to a clinical team.

Adding a causal attention layer to the baseline $(k = 1)$ model had no apparent performance improvement in any of the metrics. The attention network theoretically can put more weight to the most recent state than to the previous ones. The results indicate that this mechanism did not improve on what the baseline LSTM's gates were already doing, but persistently giving the same input to the model – i.e. perseverating the input – did.

There are limitations to the perseverated input approach. Although LSTMs are theoretically good at understanding temporal trends through their memory cells, there remain practical limitations to how long prior information can be maintained to inform future predictions [36], [37]. The PRNN has the potential to exacerbate these algorithmic deficiencies

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TABLE 5. EMR variables (demographics, vitals and labs) in patient episode matrix. The superscript ⁺ indicates the variable is binary, while * indicates the variable is ordinal. Variables without any superscripts are real-valued.

because of the memory cell's prolonged exposure to the same data. A comprehensive assessment of the impact of a potential reduction in temporal memory was not performed. Nevertheless, the basic data perseveration technique can easily be generalized to any sequential data.

Further, perseveration increases the number of sequences requiring computation. Perseveration is used during both training and inference, and the compute time scales linearly for both, commensurate with the level of perseveration. Training time for $k = 1$ required 6 hours and 8 minutes, while $k = 5$ required 41 hours and 14 minutes. Nevertheless, the time required for inference is on the order of 30*ms* for $k = 1$ (baseline) and 150*ms* for $k = 5$ on an NVIDIA Titan RTX. Since the recording frequency is approximately every 15 minutes, these computational burdens do not hinder deployment.

Finally, this proof-of-concept study used only a single clinical outcome (ICU mortality) and data from a single center. Future work will examine the effect of perseverating the data input on other important clinical tasks such as risk of desaturation, sepsis, and renal failure.

V. CONCLUSION

This work demonstrates that perseverated data input increases the responsiveness of LSTM models, in both timeliness and magnitude, to a variety of acute changes to patient state. After acute events, the magnitude of prediction changes was 2-3 times greater when the input was perseverated. Pipeup performance showed approximately an hour improvement in the ability to understand a patient. These enable quicker evaluation of patients which is critical in an acute clinical setting.

TABLE 6. EMR variables (drugs and interventions) in baseline patient episode matrix. The superscript ⁺ indicates the variable is binary, while * indicates the variable is ordinal. Variables without any superscripts are real-valued.

APPENDIX A DATA PREPROCESSING OVERVIEW

Disparate measurements of a common underlying physiologic measure were grouped into a single variable when deemed medically appropriate by an pediatric intensivist. For instance, systolic blood pressures (SBP) measured either invasively via a catheter or non-invasively via a cuff were grouped into a single variable representing SBP. Drugs or interventions which were administered in less than one percent of episodes in the training set were excluded. Measurements incompatible with human life were removed from the dataset, such as heart rates exceeding 400 beats per minute. Means and standard deviations derived from the training set were used to transform physiologic variables and laboratory measurements to have zero mean and unit variance. Therapies applied to the patient were scaled to be between 0 and 1 using clinically defined upper limits (with zero indicating absence of therapy). No age normalization was performed on the data

FIGURE 7. Complete ROC curves for (a) $t = 0$, (b) $t = 1$, (c) $t = 3$, (d) $t = 6$, (e) $t = 12$, and (f) $t = 24$.

as age was used as an input feature. Diagnoses were not used as model inputs.

EMR measurements were sparsely, asynchronously, and irregularly charted. The median time between measurements was 22 minutes with a minimum interval of one minute. Missing measurements for any drugs or interventions were simply set to zero to indicate absence of treatment. If at any time there was at least one recorded measurement for

```
import torch
```

```
class Perseverate(torch.nn.Module):
 "" Data augmentation layer that repeats sequences k times
def_init_ (self, k):
    The Initialize the transform layer
       k: integer number of perseverations to augment
    \mathbf{r}self.k = ksuper(Perseverate, self). __init__()
 def forward(self, xs, ys, **args):
    "" repeat input k times
       xs: input x torch.tensor
        ys: output y torch.tensor
    \mathbf{r}xs = xs.\nrepeat_\ninterleave(self.k, axis=0)ys = ys.request_interestleave(self.k, axis=0)return xs, ys
def invert_output(self, ys, y0s):
    "' strip all perseverated elements except the final output
        ys: y truth torch.tensor
        y0s: y pred torch.tensor
    \mathbf{r}ys = ys(self.k-1::self.k]y0s = y0s[self.k-1::self.k]return ys, y0s
```
Listing 1. Code snippet for data perseveration augmentation layer in python.

a physiologic observation or laboratory measurement it was forward filled until another measurement was recorded. This reflects the charting practices of the nurses within the ICU. If there was no recorded physiologic or laboratory value for an entire episode a mean value generated from the training set population was used.

It should be noted that many variables are symbolic representations of symptoms or signs observed within the ICU (such as Glasgow Coma Score or FLACC Pain scores) but were processed in the same manner as direct observations such as heart rate or temperature.

APPENDIX B

EMR VARIABLES

See Table 5 and 6.

APPENDIX C RECEIVER OPERATING CHARACTERISTIC CURVES FOR EACH TIME SLICE

See Figure 7.

APPENDIX D PERSEVERATION CODE

See Listing 1.

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