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A Cross-Layered Theoretical Model of IEEE 1901 Power-Line Communication Networks Considering Retransmission Protocols

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ABSTRACT Power-line communication (PLC) is a promising communication technology of constructing IoT (internet of things) systems, and it employs IEEE 1901 as its medium access control (MAC) protocol. Current studies about IEEE 1901 MAC performance analysis do not consider the influence of physical layer's retransmission protocols, i.e., ARQ (automatic repeat request) and HARQ-CC (hybrid ARQ with chase combining). Moreover, how 1901 protocol affect the energy consumption in PLC networks, and whether 1901 protocol has bound performance are also unsolved in these existing works. Focusing on the above problems, we put forward a cross-layered theoretical model to insightfully analyze 1901 protocol, where the impacts of physical layer's retransmission protocols (ARQ and HARQ-CC), channel fading modes and practical configurations (buffer size, finite traffic load, etc.) are comprehensively taken into consideration in the modeling process. On this basis, we derive the closed-form expressions of 1901 MAC metrics considering retransmission protocols. Furthermore, we construct an energy consumption model, and provide the bound performance analysis for 1901 protocol. Finally, we evaluate the performance of 1901 protocol under different retransmission protocols and system parameters, and verify the proposed cross-layered theoretical model.

INDEX TERMS Power-line communication (PLC), retransmission protocols, medium access control, IEEE 1901, cross-layered theoretical model, performance evaluation.

I. INTRODUCTION

PLC (Power-line communication) network provides an attractive communication medium for home access networks and industrial IoT (internet of things) due to its low cost installations and broad coverage feature [1]–[4]. It also finds applications in diverse domains such as realtime energy management systems, future hybrid networks and cooperative communication systems [5]–[9]. The MAC (medium access control) protocol of PLC networks, IEEE 1901, uses a special CSMA/CA (carrier sense multiple access with collision avoidance) mechanism, having some similarities to that of IEEE 802.11, and it plays a prominent role in the network performance [10]–[13]. The main difference between these two CSMA/CA mechanisms is that the 1901 protocol employs not

only a backoff counter but also a so called deferral counter, which provides a novel approach to contention resolution, namely, 1901 can react to contention when it senses the medium busy during a certain number of time slots (determined by its deferral counter), while 802.11 only reacts to contention after detecting a collision [10]. As a consequence, compared with 802.11 protocol, 1901 has larger state space and more complicated state transition.

A. DRAWBACKS AND MOTIVATION

Currently, some valuable studies have paid attention to performance analysis of 1901 protocol for PLC networks [14]–[22]. However, all these works [14]–[22] do not consider the impact of physical layer's retransmission protocols [23]–[30] on 1901's MAC performance. Furthermore, how IEEE 1901 protocol affect the energy consumption in PLC networks, and whether 1901 protocol has bound

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performance are also neglected in the above works. Therefore, it's still challenging to propose an insightful theoretical framework, which can investigate the MAC performance of IEEE 1901 PLC networks under the influence of retransmission protocols, evaluate the energy consumption and analyze the bound performance of 1901 protocol.

From the viewpoint of engineering application, PLC networks can utilize the entire available bandwidth (1.8–80 MHz). The recent standard of PLC technology can guarantee a high performance communication mechanism by providing data rates of more than 1.5 Gbps [9], [12]. Until now, PLC networks have achieved great commercial success. Based on HomePlug alliance's statistic result, more than 200 million PLC-based devices have been used worldwide. Dozens of companies begin to develop and design embedded PLC-based devices and smart chips (following the standard of IEEE 1901 protocol) [12]. Current PLC-based applications related to IoT (internet of things) have been associated with Smart Grid/Home/Meter [31]–[33], Underground power transmission [34], Intelligent Mining [35], in-vehicle communication [36], photovoltaic system [37], hybrid intelligence communication [7], [38] and Industry 4.0 [39]. As a consequence, thoroughly analyzing IEEE 1901 PLC networks is valuable for practical IoT system construction.

B. TASKS AND CONTRIBUTIONS

The main objective of the paper is to analyze the MAC performance of 1901 considering retransmission protocols, examine the energy consumption due to 1901 protocol, and make a bound performance analysis for 1901. The core contributions of the paper are:

- We propose a cross-layered theoretical model for IEEE 1901 protocol considering the impact of retransmission protocols. To establish this model, a two-dimension Markov chain (T-D MC) is employed to depict the CSMA/CA mechanism of IEEE 1901. Besides considering the impacts of practical environment configurations (e.g., buffer size, finite traffic load, and deferral counter process (DCP) of 1901), we emphatically analyze the impacts of physical layer's retransmission protocols (ARQ and HARQ-CC) and detailed channel fading modes (containing Rayleigh fading and Nakagami- u fading) on 1901 MAC performance. On the basis, we derive the closed-form expressions of typical MAC metrics of 1901 (containing system throughput, MAC service time, packet drop probability, packet blocking probability and etc) under the influence of retransmission protocols. To the best of our knowledge, this should be the first cross-layered theoretical framework, which can reflect the impact of physical layer's retransmission protocols on IEEE 1901.
- We put forward an energy consumption model to evaluate the consumed power of transmitting one successful bit in IEEE 1901 PLC networks.
- We examine the bound performance of two 1901 MAC metrics (system throughput and successful transmission

probability). Through using differential method, we reveal that the bounds of these two MAC metrics depend significantly on the network size.

- We conduct extensive simulation experiments to verify the proposed cross-layered theoretical model, and draw key insights into the MAC performance of 1901 under different retransmission protocols and system parameters.

C. PAPER OUTLINE

The remainder of our paper is organized as follows. A brief overview of IEEE 1901 and retransmission protocols (containing ARQ and HARQ-CC) is presented in Section 2. Related works are reviewed in Section 3. The system model is proposed in Section 4. We verify our cross-layered theoretical model via simulations in Section 5. Finally, conclusions are summarized in Section 6.

II. OVERVIEW OF IEEE 1901 AND RETRANSMISSION PROTOCOLS

A. IEEE 1901 PROTOCOL

The CSMA/CA mechanism of 1901 protocol employs two counters: a backoff counter and a deferral counter. The backoff counter process (BCP) of 1901 is similar to that of 802.11. When the station has a new packet to transmit, the backoff stage k is initialized to 1 and a random backoff counter is uniformly selected among $[1, \dots, W_1]$, where W_1 represents the maximum backoff counter used at backoff stage 1. If the station senses the medium to be idle, the backoff counter is decreased by 1 at each slot time, and it is frozen when the medium is sensed busy. In case the medium is sensed busy, the value of the backoff counter is also decreased by 1 once the medium is sensed idle again [15]. When the value of the backoff counter is decreased to 1, the station attempts to transmit the packet. If suffering a collision, the station jumps to the next backoff stage (backoff stage 2) and repeats the same process as backoff stage 1. When the station is already at the last backoff stage m and the transmission attempt suffers a collision, it re-enters the last backoff stage.

TABLE 1. The maximum backoff counter W_k and the value of d_k for 1901 protocol.

Priority class:	CA0	CA1	CA2	CA3
backoff stage k	W_k	d_k	W_k	d_k
1	8	0	8	0
2	16	1	16	1
3	32	3	16	3
4	64	15	32	15

The standard 1901 has four priority classes (CA0 – CA3), and two priority classes (CA0/CA1 or CA2/CA3) constitute a priority type [20]. In addition, it has only four backoff stages (i.e., $m = 4$), and the value of maximum backoff counter W_k at stage k depends on its corresponding priority class (shown in Table 1).

Different from 802.11, the additional deferral counter of 1901 allows a station in PLC networks to enter the next

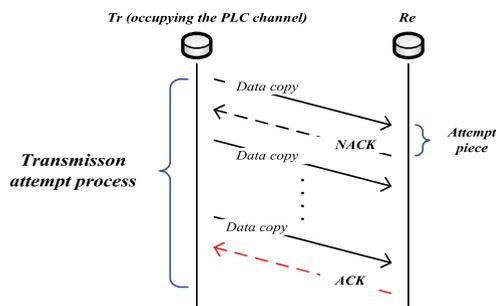


FIGURE 1. A successful transmission attempt process (Tr denotes the transmitter, Re the receiver).

backoff stage even if it does not attempt a transmission. When the station enters backoff stage k , the initial value of the deferral counter is set to $d_k + 1$ (the value of d_k is given in Table 1). After sensing that the medium is busy, the station decreases $d_k + 1$ by 1 (in addition to executing the BCP). If the medium is sensed busy and the value of the deferral counter is 1 (i.e., sensing the medium busy $d_k + 1$ times), and it re-draws the backoff counter without attempting a transmission (if the station is already at the last backoff stage, it re-enters this stage) [20].

B. RETRANSMISSION PROTOCOLS: ARQ AND HARQ-CC

In practical network scenario, when the station occupies the PLC channel (through 1901's CSMA/CA mechanism) and attempts to transmit its packet, it begins to execute retransmission protocols¹ [23]–[30],[40]–[42]. In the basic ARQ, for decoding, the receiver uses the packet received in the current attempt fragment only, and discards all the erroneously received copies of this packet. In HARQ-CC, the receiver tries to decode the packet received in the current attempt fragment by maximal ratio combining (MRC) it with all the previously received copies of the same packet. In other words, for basic ARQ, we say that the packet is received in outage, if the signal-to-noise ratio (SNR) of the packet received in an attempt fragment is less than the minimum SNR required for successful decoding (i.e., threshold SNR). For HARQ-CC, the packet remains in outage if the accumulated SNR (from the first attempt fragment to current attempt fragment) is less than the minimum SNR required for successful decoding. For every transmission attempt process, a data packet can be transmitted at most M times (i.e., one transmission attempt process contains no more than M attempt fragments). After each attempt fragment, the transmitter receives an acknowledgment (ACK) if the packet is successfully delivered, or else a negative ACK (NACK). If the packet is not successfully delivered by the deadline, it would be dropped (Fig.1 shows a successful transmission attempt process under the influence of retransmission protocols).

¹Physical layer's retransmission protocols are used not only for PLC networks, but also for wireless networks following NDMA MAC standard [40]–[42].

III. RELATED WORK

Up to now, several meaningful works have been proposed to analyze IEEE 1901 protocol.² In [14], a semi-Markov based analytical model was established to depict the CSMA/CA mechanism of 1901 protocol in saturated conditions. Vlachou *et al.* designed a series of Renewal theory based analytical models for IEEE 1901 protocol under saturated conditions [15]–[19]. These studies can be summarized as four parts: (1) Constructing the basic analytical model and proving the model admits a unique solution [14], [15]; (2) Examining the performance tradeoff between delay and throughput [17]; (3) Further optimizing 1901 MAC performance on the basic model [18]; (4) Analyzing the performance and stability of 1901 protocol under the coupling condition [19]. Cano *et al.* put forward a theoretical model of IEEE 1901 protocol for saturated PLC networks using renewal process theorem. In [21], Hao *et al.* provided a unified 1901 protocol analysis framework in unsaturated, single-hop environment. Then they continued to construct a theoretical model of 1901 protocol for multi-hop PLC networks [22]. As mentioned previously, these studies do not consider the impact of physical layer's retransmission protocols on MAC performance of 1901, and how to evaluate the energy consumption caused by 1901 protocol. Moreover, they do not make a bound performance analysis for 1901 protocol.

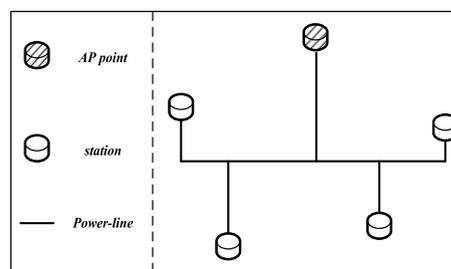


FIGURE 2. A simple case of converged PLC network, where stations transmit their packets to the AP.

IV. SYSTEM MODEL

In this part, we construct the cross-layered theoretical model of IEEE 1901 protocol (the notation of essential results is given in Table 2). The PLC network adopts a converged topology, in which stations deliver their packets to the access point (AP) (shown in Fig.2). The detailed modeling process contains four steps: (1) Establishing the base model to describe the CSMA/CA mechanism of 1901 protocol considering the impact of physical layer's retransmission protocols; (2) Deriving the closed-form expressions of typical MAC metrics under the influence of retransmission protocols; (3) Analyzing the energy consumption of transmitting a successful bit in IEEE 1901 PLC networks; (4) Making the bound performance analysis for 1901.

The cross-layered theoretical model is constructed under the following assumptions:

²We only introduce the related works focusing on IEEE 1901 protocol analysis, the studies about 1901 protocol modification are not discussed here.

TABLE 2. Notation list relevant to the results derived by the cross-layered theoretical model.

Notation	Definition
N	Number of stations
M	Number of attempt fragments
X	Transmission distance
$X_{k,r}$	A station at backoff stage k selects the backoff counter r ($W_k \geq r \geq d_k + 1$) and senses the medium busy no more than d_k times
Y_k	A station at backoff stage k triggers the DCP
p	Conditional collision probability of the station
τ	Probability that a station attempts to transmit its HOL packet in a slot time
p_{tr}	Probability that at least one station attempts to transmit its HOL in a slot time
p_{idle}	Probability that the medium is idle
N_0	Average noise power of white Gaussian noise $\mathcal{N}(0, N_0)$
η	Threshold value of SNR
$f_{\Xi}(\zeta) \Xi \in [RF, NF]$	Probability density function of channel gain ζ under Rayleigh fading (or Nakagami- u fading) channel
$F_{\Xi}(\Omega) \Xi \in [RF, NF]$	Cumulative distribution function of power gain Ω under Rayleigh fading (or Nakagami- u fading) channel
$P_{w_t}/P_{w_r}/P_{w_o}$	Transmission/receiving/overhearing power
$P_{out,x}^{ARQ} (P_{out}^{ARQ})$	Probability that the SNR of the x th attempt fragment is less than η when using ARQ protocol
$P_{out,1 \rightarrow x}^{HARQ} (P_{out}^{HARQ})$	Probability that the accumulated SNR up to the x th attempt fragment is still less than η when using HARQ-CC protocol
$p_x^s(x)$	Probability that a successful transmission using x attempt fragments
PDP^{κ}	Packet dropping probability during transmission attempt process
P_{suc}	Successful transmission probability
$T_s(x)$	Time duration that a successful transmission using x attempt fragments
T_c	Time duration that the medium is busy due to the collision
T_{drop}	Time duration of "dropping packet"
E_{slot}	Average size of slot time
S	System throughput
ν	Probability that no packet arrives the buffer during a virtual slot time
Ar_a	Probability that a packets arrive to the station buffer during the medium service time
μ_a	Probability that there are a packets in the buffer upon a departure
P_a	Steady state probability of a packets in the buffer
$E[T_{mac}]$	Average medium service time
$E[Q]$	Average queue length
P_b	Packet blocking probability
T_{busy}	Total time duration where energy is spent by transmitting, receiving or dropping data packet
EBP	Expected total energy cost of transmitting one successful bit

- Each station has finite buffer size (denoted by K), and packets would be rejected because of overflow of the station buffer (denoted by packet blocking probability P_b).
- Station attempts to transmit its HOL (head of line) packet with a constant transmission probability τ , and it collides with an independent probability p .
- All stations are in the same carrier sensing region, where hidden terminal and exposed terminal problems do not happen. Furthermore, Each station receives packets from the upper layer based on Poisson process with an average arrival rate λ .
- The PLC channel fading mode follows a typical distribution (Rayleigh or Nakagami- u fading) without considering the interference. The average noise power of white Gaussian noise $\mathcal{N}(0, N_0)$ is N_0 .

A. BASE MODEL: CSMA/CA MECHANISM OF 1901 CONSIDERING RETRANSMISSION PROTOCOLS

According to the standard of 1901 protocol, a station at backoff stage k jumps to the next backoff stage $k + 1$ by two approaches: (1) attempting an unsuccessful transmission due to collision or (2) sensing the medium busy ($d_k + 1$) times. Let r be the selected backoff counter at stage k , if $r < d_k + 1$ or $r \geq d_k + 1$ and the station senses the medium is busy no more than d_k times, it uses the first approach to jump to the next stage. Otherwise, it adopts the DCP to enter the next backoff stage.

Let $\frac{X_{k,r}}{W_k}$ denotes the probability that a station chooses an initial backoff counter r ($W_k \geq r \geq d_k + 1$) and senses the

medium busy no more than d_k times, and $\frac{Y_k}{W_k}$ the probability that a station triggers the DCP at backoff stage k . We can express $X_{k,r}$ and Y_k as follows:

$$\begin{cases} X_{k,r} = \sum_{h=0}^{d_k} C_r^h \cdot p^h (1-p)^{r-h}; & r \in [d_k + 1, W_k] \\ Y_k = \sum_{r=d_k+1}^{W_k} (1 - X_{k,r}) \end{cases} \quad (1)$$

Now we can provide the structure of T-D MC for IEEE 1901 protocol (shown in Fig.2). Considering the impacts of buffer size and traffic load, BCP and DCP cannot be triggered when there is no packet in the station buffer. For this purpose, we introduce \mathbf{E} (E) to represent the empty state of the station buffer. The non-empty state is divided into two categories: (1) **BCP** ($d_{k,r}; r \in [1, W_k]$) and (2) **DCP** ($d_{k,j}; j \in [1, d_k + 1]$). $E, b_{k,r}$ and $d_{k,j}$ denote the steady probabilities of the Markov chain, respectively. In addition, we define F_k ($k \in [1, m]$) as the probability that a station jumps from the transient state [43], [44] that it prepares a new HOL packet and begins to execute the CSMA/CA mechanism of 1901 to the backoff stage k , and F_k is written as (the detailed derivation process is given in **Appendix A**)

$$\begin{cases} F_1 = 1; & k = 1 \\ F_k = \prod_{h=1}^{k-1} (p + \frac{(1-p)Y_h}{W_h}); & k \in [2, m-1] \\ F_m = \frac{(p + \frac{(1-p)Y_{m-1}}{W_{m-1}})}{1 - (p + \frac{(1-p)Y_m}{W_m})} \cdot F_{m-1}; & k = m \end{cases} \quad (2)$$

We further let μ_0 be the stationary probability that the buffer of station is empty upon a departure, ν be the transition

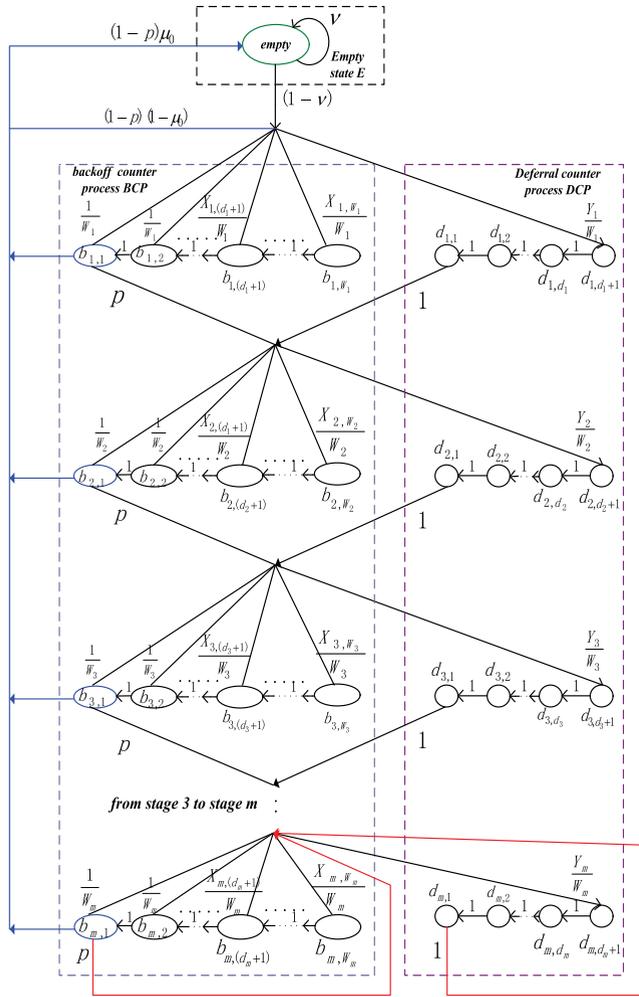


FIGURE 3. T-D MC for IEEE 1901 protocol.

probability that no packet arrives at station's buffer during a slot time, thus, based on the above derivation, the transmission attempt probability τ for a station can be expressed as (see the bottom of the page, the detailed derivation process is given in **Appendix B**)

Hence, the probability that a station fails to transmit its HOL packet due to a collision, i.e., the conditional collision probability p is given by

$$p = 1 - (1 - \tau)^{N-1} \quad (4)$$

The probability p_{tr} that at least one station tries to accomplish a transmission, and the probability p_{idle} that the medium is sensed to be idle can be expressed respectively as:

$$p_{tr} = 1 - (1 - \tau)^N \quad (5)$$

$$p_{idle} = 1 - p_{tr} = (1 - \tau)^N \quad (6)$$

Since physical layer's retransmission protocols are considered in our work, the calculation of successful transmission probability P_{suc} , system throughput S , expected MAC service time $E[T_{mac}]$ and etc would be different from previous works [14]–[22]. We have assumed PLC channel to be Rayleigh fading or Nakagami- u fading, the corresponding PDF (Probability Density Function) $f_{\Xi}(\cdot) | \Xi \in (RF, NF)^3$ of channel gain ζ can be expressed respectively as:

For Rayleigh fading (RF) channel mode

$$f_{RF}(\zeta) = \frac{\zeta}{\sigma_R^2} \cdot \exp\left(-\frac{\zeta^2}{2\sigma_R^2}\right) \quad (7)$$

For Nakagami- u fading (NF) channel mode

$$f_{NF}(\zeta) = \frac{2u^u}{\Gamma(u)} \cdot \zeta^{2u-1} \cdot \exp(-u \cdot \zeta^2) \quad (8)$$

where σ_R^2 represents the scale parameter of Rayleigh distribution, u the Nakagami factor and $\Gamma(\cdot)$ the gamma function, respectively.

Accordingly, the CDF (Cumulative Distribution Function) $F_{\Xi}(\cdot) | \Xi \in (RF, NF)$ of power gain Ω (note that $\Omega = \zeta^2$)⁴ under Rayleigh/Nakagami- u fading mode can be derived as⁵:

$$F_{RF}(\Omega) = 1 - \exp\left(-\frac{\zeta^2}{2\sigma_R^2}\right) = 1 - \exp\left(-\frac{\Omega}{2\sigma_R^2}\right) \quad (9)$$

$$F_{NF}(\Omega) = 1 - \exp(-u\zeta^2) \sum_{j=1}^{u-1} \frac{(u\zeta^2)^j}{j!} \\ = \frac{\gamma(u, u\zeta^2)}{\Gamma(u)} = \frac{\gamma(u, u\Omega)}{\Gamma(u)} \quad (10)$$

where $\gamma(\cdot)$ denotes the lower incomplete gamma function.

Let Pw_t be the transmission power of each attempt fragment, N_0 the average noise power of white Gaussian noise

³RF denotes the Rayleigh fading, and NF the Nakagami- u fading.

⁴The relationship between channel gain and power gain has been verified in many existing literatures, e.g., [23]–[26].

⁵The detailed derivation process from $f_{\Xi}(\zeta)$ to $F_{\Xi}(\Omega)$ is shown in [45].

$$\tau = \frac{\sum_{k=1}^m b_{k,1}}{\sum_{k=1}^m (\sum_{g=1}^{W_k} b_{k,g} + \sum_{j=1}^{d_k+1} d_{k,j}) + E} = \frac{A}{B} \quad \text{where :} \\ A = \sum_{k=1}^m \left[\frac{F_k \cdot d_k}{W_k} + \frac{F_k}{W_k} \sum_{r=d_k+1}^{W_k} X_{k,r} \right]; \\ B = \sum_{k=1}^m \left[(d_k + 1) \frac{Y_k \cdot F_k}{W_k} + \frac{F_k}{W_k} \sum_{r=d_k+1}^{W_k} (r - d_k) X_{k,r} + \left(\frac{d_k F_k}{W_k} \sum_{r=d_k+1}^{W_k} X_{k,r} + \frac{F_k}{W_k} \frac{d_k(d_k + 1)}{2} \right) \right] + \frac{\mu_0}{1 - \nu} \quad (3)$$

$\mathcal{N}(0, N_0)$, X the transmission distance, α the path loss exponent and η the threshold SNR (i.e., the required minimum SNR). If using ARQ protocol at the physical layer, we can write the probability $P_{out,x}^{ARQ}$ that the x th attempt fragment fails (from physical layer's perspective) as⁶

$$\begin{aligned}
 P_{out,x}^{ARQ} &= \text{prb}\{SNR \leq \eta | x \in [1, M]\} \\
 &= \text{prb}\left\{\frac{P_{w_t} \cdot \Omega \cdot X^{-\alpha}}{N_0} \leq \eta\right\} \\
 &\stackrel{a}{=} \text{prb}\left\{\Omega \leq \frac{\eta \cdot N_0}{P_{w_t} \cdot X^{-\alpha}}\right\} \\
 &\stackrel{b}{=} \begin{cases} F_{RF}\left(\frac{\eta \cdot N_0}{P_{w_t} \cdot X^{-\alpha}}\right) = 1 - \exp\left[-\frac{\eta \cdot N_0}{P_{w_t} \cdot X^{-\alpha}}\right] | RF \\ F_{NF}\left(\frac{\eta \cdot N_0}{P_{w_t} \cdot X^{-\alpha}}\right) = \gamma(u, u \frac{\eta \cdot N_0}{P_{w_t} \cdot X^{-\alpha}}) / \Gamma(u) | NF \end{cases} \quad (11)
 \end{aligned}$$

Remark 1: Since x cannot affect the value of $P_{out,x}^{ARQ}$ (proved by Eq.11), in the following analysis process, we use P_{out}^{ARQ} as the simplified form to replace $P_{out,x}^{ARQ}$. In addition, P_{w_t} is generally expanded as $P_{w_t} = C_1 + C_2 \cdot X^{-\alpha}$, where C_1 and C_2 are two constants.

While using HARQ-CC protocol at the physical layer, we say the packet remains in outage if the accumulated SNR, up to and including the SNR of the packet received in the x th round (i.e., from the 1st attempt fragment to current attempt fragment) is less than η . Therefore, the probability that transmission attempt fails until the x th attempt fragment $P_{out,1 \rightarrow x}^{HARQ}$ (from physical layer's perspective) can be given by

$$\begin{aligned}
 P_{out,1 \rightarrow x}^{HARQ} &= \text{prb}\left\{\sum_{\varepsilon=1}^x SNR \leq \eta | x \in [1, M]\right\} \\
 &= \text{prb}\left\{\frac{\sum_{\varepsilon=1}^x P_{w_t} \cdot \Omega \cdot X^{-\alpha}}{N_0} \leq \eta\right\} \\
 &\stackrel{a}{=} \text{prb}\left\{\Omega \leq \frac{\eta \cdot N_0}{x \cdot P_{w_t} \cdot X^{-\alpha}}\right\} \\
 &\stackrel{b}{=} \begin{cases} F_{RF}\left(\frac{\eta \cdot N_0}{x \cdot P_{w_t} \cdot X^{-\alpha}}\right) = 1 - \exp\left[-\frac{\eta \cdot N_0}{x \cdot P_{w_t} \cdot X^{-\alpha}}\right] | RF \\ F_{NF}\left(\frac{\eta \cdot N_0}{x \cdot P_{w_t} \cdot X^{-\alpha}}\right) = \gamma(u, u \frac{\eta \cdot N_0}{x \cdot P_{w_t} \cdot X^{-\alpha}}) / \Gamma(u) | NF \end{cases} \quad (12)
 \end{aligned}$$

When a station successfully occupies the channel (through the CSMA/CA mechanism of 1901), and begins to transmit its HOL packet, it initializes the retransmission protocol (ARQ or HARQ-CC). Thus, the probability $p_s^\kappa(x)$ ($\kappa \in \{ARQ, HARQ\}$) that a successful transmission using $x | x \in [1, M]$ attempt fragments can be given by

$$p_s^{ARQ}(x) = \binom{N}{1} \tau (1-p) \underbrace{[P_{out}^{ARQ}]^{(x-1)}}_{a1} \underbrace{(1 - P_{out}^{ARQ})}_{a2} \quad (13)$$

$$p_s^{HARQ}(x) = \binom{N}{1} \tau (1-p) \underbrace{P_{out,1 \rightarrow x-1}^{HARQ}}_{b1} \underbrace{(1 - P_{out,1 \rightarrow x}^{HARQ})^7}_{b2} \quad (14)$$

⁶ $\text{prb}\{\chi\}$ represents the probability case χ happens.

Remark 2: In Eqs.13-14, part ‘‘a1’’ denotes the case that the transmission attempt process from the 1st time to the x th time are all failed (i.e., the SNR of each attempt fragment is less than η in previous $x - 1$ times), part ‘‘a2’’ the x th attempt successes (i.e., the SNR of the x th attempt fragment is larger than η); Part ‘‘b1’’ the case that accumulated SNR from the 1st attempt fragment to the $(x - 1)$ th attempt fragment is less than η (i.e., the packet remains in outage up to the $x - 1$ th attempt fragment), ‘‘b2’’ the case that accumulated SNR from the 1st attempt fragment to the x th attempt fragment is larger than η . Operator $\binom{N}{1} \tau (1 - p)$ denotes there is one station that successfully occupies the channel through executing the CSMA/CA mechanism of 1901.

The successful transmission probability P_{suc}^κ ($\kappa \in \{ARQ, HARQ\}$) can be accordingly denoted as

$$P_{suc}^\kappa = \sum_{x=1}^M p_s^\kappa(x) \quad (15)$$

A packet is dropped if all attempt fragments fail, therefore, the packet drop probability (caused by retransmission protocols) during one transmission attempt process PDP^κ ($\kappa \in \{ARQ, HARQ\}$) can be written as:

$$\begin{aligned}
 PDP^{ARQ} &= \binom{N}{1} \tau \cdot (1-p) - \sum_{x=1}^M p_s^{ARQ}(x) \\
 &= \binom{N}{1} \tau \cdot (1-p) \cdot [P_{out}^{ARQ}]^M \quad (16) \\
 PDP^{HARQ} &= \binom{N}{1} \tau \cdot (1-p) - \sum_{x=1}^M p_s^{HARQ}(x) \\
 &= \binom{N}{1} \tau \cdot (1-p) \cdot P_{out,1 \rightarrow M}^{HARQ} \quad (17)
 \end{aligned}$$

If the packet fails to be delivered in an attempt fragment, the receiver replies a NACK frame, else (successfully delivered in an attempt fragment), the receiver replies an ACK frame (the time sequence is shown in Fig.4). Thus, the time duration of a successful transmission $T_s(x)$ can be given by

$$\begin{aligned}
 T_s(x) &= 2PRS + (x - 1) \cdot (D + RIFS + NACK) \\
 &\quad + D + RIFS + ACK + CIFS \quad | x \in [1, M] \quad (18)
 \end{aligned}$$

where PRS , D , $RIFS$, $CIFS$, ACK and $NACK$ represent the priority tone slot, duration of data packet, response inter-frame space, contention inter-frame space, acknowledgment frame and negative acknowledgment frame, respectively (defined by the time sequence of IEEE 1901 standard [10]).

The time duration that the packet is dropped T_{dp} , and the time duration that medium is sensed busy due to the collision T_c can be respectively expressed as ($EIFS$ is the extended inter-frame space):

$$T_{dp} = 2PRS + M \cdot (D + RIFS + NACK) + CIFS \quad (19)$$

$$T_c = EIFS \quad (20)$$

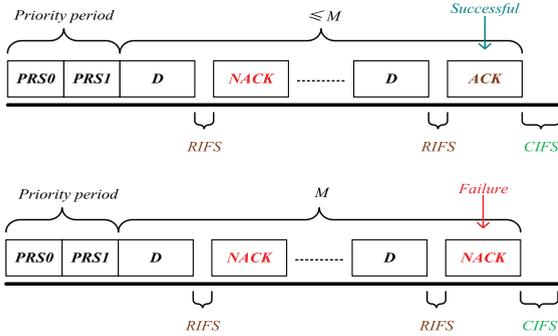


FIGURE 4. The time sequence of 1901 considering retransmission protocols.

Accordingly, the average size of slot time $E[slot]$ can be written as

$$E[slot] = \sigma \cdot p_{idle} + \sum_{x=1}^M T_s(x) \cdot p_s^k(x) + T_c \cdot [p_{tr} - (\sum_{x=1}^M p_s^k(x) + PDP^k)] + T_{dp} \cdot PDP^k \quad (21)$$

where σ is the duration of the idle slot time.

Now, the system throughput S for IEEE 1901 PLC networks considering retransmission protocols can be given by

$$S = \frac{E[\text{payload transmitted in a slot time}]}{E[slot]} = \frac{\sum_{x=1}^M p_s^k(x) \cdot L}{E[slot]} \quad (22)$$

where L represents the size of data packet.

Remark 3: The value of S is determined by the detailed retransmission protocol and channel fading mode.

Since the station receives packets based on Poisson process, the probability ν that no packet arrives during a slot time is approximately expressed as

$$\nu \doteq \exp\{-\lambda \cdot E[slot]\} \quad (23)$$

B. THE MAC METRICS OF 1901 CONSIDERING RETRANSMISSION PROTOCOLS

It's easy to find that μ_0 relies on the buffer size and packet arrival process, hence a queue model is established to derive μ_0 and capture the queueing process of the station. We define P_a as the probability of a packets in the station buffer, μ_a the probability of a packets in the station buffer upon a departure and Ar_a the probability that a packets arrive at the station buffer during the MAC service time T_{mac} [21]. Then, the transition matrix Ar is denoted as

$$Ar = \begin{bmatrix} Ar_0 & Ar_1 & Ar_2 & \cdots & Ar_{K-2} & 1 - \sum_{a=0}^{K-2} Ar_a \\ Ar_0 & Ar_1 & Ar_2 & \cdots & Ar_{K-2} & 1 - \sum_{a=0}^{K-2} Ar_a \\ 0 & Ar_0 & Ar_1 & \cdots & Ar_{K-3} & 1 - \sum_{a=0}^{K-3} Ar_a \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & Ar_0 & 1 - Ar_0 \end{bmatrix} \quad (24)$$

where K represents the buffer size of the station.

Let $\mu = [\mu_0 \ \mu_1 \ \cdots \ \mu_{K-1}]$, the relationship between μ and Ar can be represented as following

$$\mu \cdot Ar = \mu \quad (25)$$

Since Poisson arrival is assumed, the expression of Ar_a is written as

$$Ar_a \doteq \sum_{r=0}^{\infty} \frac{\exp\{-\lambda[(r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)]\}}{a!} \cdot \frac{\{\lambda[(r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)]\}^a}{a!} \cdot Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} \quad (26)$$

where $Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\}$ in Eq.26 can be respectively expanded as follows (please refer to [21] for detailed derivation process):

For ($k = 1$), we have

$$\begin{cases} Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} = \frac{1}{W_1}; r \in [1, d_1] \\ Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} = \frac{X_{1,r}}{W_1}; r \in [d_1 + 1, W_1] \end{cases} \quad (27)$$

For ($k \in [2, m-1]$), we have

$$\begin{cases} Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} = \frac{\prod_{t=1}^{k-1} p + [(1-p) \cdot \frac{Y_t}{W_t}]}{W_k}; r \in [1, d_k] \\ Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} = \prod_{t=1}^{k-1} p + [(1-p) \cdot \frac{Y_t}{W_t}] \cdot \frac{X_{k,r}}{W_k}; r \in [d_k + 1, W_k] \end{cases} \quad (28)$$

For ($k = m$), we have

$$\begin{cases} Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} = \frac{\prod_{t=1}^{m-1} \{p + [(1-p) \cdot \frac{Y_t}{W_t}]\}}{W_m [1 - p - (1-p) \cdot \frac{Y_m}{W_m}]}; r \in [1, d_m] \\ Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} = \frac{\prod_{t=1}^{m-1} \{p + [(1-p) \cdot \frac{Y_t}{W_t}]\}}{[1 - p - (1-p) \cdot \frac{Y_m}{W_m}]} \cdot \frac{X_{m,r}}{W_m}; r \in [d_m + 1, W_m] \end{cases} \quad (29)$$

Accordingly, the expected MAC service time $E[T_{mac}]$ considering retransmission protocols is given by

$$E[T_{mac}] = \sum_{r=0}^{\infty} Prb\{T_{mac} = (r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)\} \cdot [(r-1)E[slot] + \sum_{x=1}^M T_s(x)p_s(x)] \quad (30)$$

Based on the knowledge of $M/G/1/K$ queueing system [43], P_a is obtained as

$$\begin{cases} P_a = \frac{\mu_a}{\mu_0 + \lambda E[T_{mac}]}; & a \in [0, K - 1] \\ P_K = 1 - \frac{1}{\mu_0 + \lambda E[T_{mac}]}; & a = K \end{cases} \quad (31)$$

In addition, the average queue length $E[Q]$ and packet blocking probability P_b considering retransmission protocols can be derived as follows:

$$E[Q] = \sum_{a=0}^K a \cdot P_a \quad (32)$$

$$P_b = 1 - \frac{1}{\mu_0 + \lambda \cdot E[T_{mac}]} \quad (33)$$

Remark 4: In the previous analysis, we provide the T-D MC for 1901 MAC protocol considering retransmission protocols. That is because the following steady states exist in slot time T [44]:

$$\begin{cases} \lim_{T \rightarrow \infty} Prob\{empty(T)\} = E \\ \lim_{T \rightarrow \infty} Prob\{b_s(T)=k, b(T)=r\} = b_{k,r} \\ \lim_{T \rightarrow \infty} Prob\{d_s(T)=k, d(T)=j\} = d_{k,j} \\ \lim_{T \rightarrow \infty} Prob\{\mu_r(T)\} = \mu_r \end{cases} \quad (34)$$

where $s(T)$, $b(T)$ and $d(T)$ represent the values of backoff stage, backoff counter, and deferral counter, respectively.

C. THE ENERGY CONSUMPTION MODEL FOR IEEE 1901 PROTOCOL

In this section, we propose an energy consumption model to find out the consumed power for successfully delivering one bit of data packet in the IEEE 1901 PLC network considering retransmission protocols. The expected total energy cost of transmitting one successful bit from the station to the destination is called Energy Per Bit (EPB), which contains three parts: the energy consumption of transmitting per bit E_t , the energy consumption of receiving per bit E_r , and the energy consumption of overhearing for other stations (i.e., be in the idle state) E_{oh} [46]. Hence, we have the following equation

$$EPB = E_t + E_r + E_{oh} \quad (35)$$

Let the receiving power and overhearing power be P_{wr} and $P_{w_{oh}}$ (two constants), respectively. Since a data packet may be dropped during executing the retransmission protocol, the average time duration $Avg[T_s]^k$ for a specific successful transmission can be given by

$$Avg[T_s]^k = \begin{cases} \sum_{x=1}^M \frac{P_s^{ARQ}(x)}{\tau} \cdot T_s(x) & or \\ \sum_{x=1}^M \frac{P_s^{HARQ}(x)}{\tau} \cdot T_s(x) \end{cases} \quad (36)$$

Similarly, the average time duration $Avg[T_{dp}]^k$ for a specific “dropping packet” is expressed as

$$Avg[T_{dp}]^k = \begin{cases} \frac{PDP_s^{ARQ}}{\tau} \cdot T_{dp} & or \\ \frac{PDP_s^{HARQ}}{\tau} \cdot T_{dp} \end{cases} \quad (37)$$

Thus, the total time duration T_{busy} where energy is spent by transmitting, receiving or dropping data packet can be written as

$$T_{busy} = Avg[T_s]^k + Avg[T_{dp}]^k \quad (38)$$

Remark 5: A specific successful transmission or dropping packet means that the station having occupied the PLC channel definitely carries out its data transmission attempt process, and other stations do not transmit their packet at the same slot time. That’s the reason we have Eqs.36-37.

Accordingly, E_t and E_r can be expressed as follows:

$$E_t = \frac{1}{L} \cdot T_{busy} \cdot P_{wt} \quad (39)$$

$$E_r = \frac{1}{L} \cdot T_{busy} \cdot P_{wr} \quad (40)$$

A station tries to transmit its HOL packet, the other $N - 1$ stations would be overhearing the PLC channel. Therefore, we can obtain E_{oh} , and express it as

$$E_{oh} = (N - 1) \cdot \frac{1}{L} \cdot T_{busy} \cdot P_{w_{oh}} \quad (41)$$

D. BOUND PERFORMANCE ANALYSIS FOR IEEE 1901 PROTOCOL

In this sub-section, we select two metrics, system throughput S and successful transmission probability P_{suc}^k , to analyze whether the 1901 protocol has bound performance under the influence of retransmission protocols.

Firstly, we consider the bound performance of system throughput S .

Lemma 1: The bound performance of system throughput S of IEEE 1901 PLC network (considering retransmission protocols) yields the following approximate solution $\tau_{optimal}$, i.e.,

$$\tau_{optimal} \doteq \frac{\sqrt{(N^2\sigma^2 + 2\sigma(T_c - \sigma))N(N - 1) - N\sigma}}{N(N - 1)(T_c - \sigma)} \quad (42)$$

Proof 1: Further extending Eq.22, we can get

$$S = \frac{N \cdot L \cdot A \cdot \tau(1 - p)}{\sigma(1 - \tau)^{N-1} + B \cdot N\tau(1 - p) + T_c(1 - (1 - \tau)^N)}$$

where A and B are respectively denoted as:

$$A = \begin{cases} \sum_{x=1}^M (P_{out}^{ARQ})^{(x-1)}(1 - P_{out}^{ARQ}) & or \\ \sum_{x=1}^M P_{out,1 \rightarrow x-1}^{HARQ}(1 - P_{out,1 \rightarrow x}^{HARQ}) \end{cases} \quad (43)$$

$$B = \begin{cases} [\sum_{x=1}^M (P_{out}^{ARQ})^{(x-1)}(1 - P_{out}^{ARQ})T_s(x) \\ - \sum_{x=1}^M (P_{out}^{ARQ})^{(x-1)}(1 - P_{out}^{ARQ})T_c] \\ + (T_{dp} - T_c)(P_{out}^{ARQ})^M \text{ or} \\ [\sum_{x=1}^M P_{out,1 \rightarrow x}^{HARQ}(1 - P_{out,1 \rightarrow x}^{HARQ})T_s(x) \\ - \sum_{x=1}^M P_{out,1 \rightarrow x}^{HARQ}(1 - P_{out,1 \rightarrow x}^{HARQ})T_c] \\ + (T_{dp} - T_c)P_{out,1 \rightarrow M}^{HARQ} \end{cases} \quad (44)$$

Clearly, P_{out}^{ARQ} or $P_{out,1 \rightarrow x}^{HARQ}$ is determined by the transmission power P_{w_t} , distance X , path loss exponent α , channel fading mode, and detailed retransmission protocol (recalling Eqs.11-12), hence A and B can be regarded as two constants in the derivation process.

Let $F(\tau) = \frac{\tau(1-p)}{\sigma(1-\tau)^{N-1} + B \cdot N\tau(1-p) + T_c(1-(1-\tau)^N)}$, to get the bound performance of system throughput S , we have $F'(\tau) = 0$, i.e.,

$$F'(\tau) = 0 = \frac{\sigma(1-\tau)^{2N-2} + T_c[(1-N\tau)(1-\tau)^{N-2} - (1-\tau)^{2N-2}]}{[\sigma(1-\tau)^{N-1} + B \cdot N\tau(1-p) + T_c(1-(1-\tau)^N)]^2} \quad (45)$$

Simplifying Eq.45, we can derive the following relation expression

$$T_c(1 - N\tau) = (T_c - \sigma)(1 - \tau)^N \quad (46)$$

Using Taylor formula [45] (i.e., $(1 - \tau)^N \approx 1 - N\tau + \frac{N(N-1)}{2}\tau^2$), Eq.46 can be simplified as

$$(T_c - \sigma) \frac{N(N-1)}{2} \tau^2 + N\sigma\tau - \sigma = 0 \quad (47)$$

Solving Eq.47, we have the conclusion of Lemma 1.

For network size $N \rightarrow +\infty$, $\tau_{optimal}$ can be further written as

$$\lim_{N \rightarrow +\infty} \tau_{optimal} \approx \frac{\sqrt{1 + 2(T_c/\sigma)} - 1}{N(T_c/\sigma)} \approx \frac{1}{N\sqrt{0.5T_c/\sigma}} \quad (48)$$

Let $\rho = \sqrt{0.5T_c/\sigma}$, for $N \rightarrow +\infty$, the probability p_{tr} , p_{idle} and p can be approximately re-written as:

$$\begin{cases} \lim_{N \rightarrow +\infty} p_{tr} = \\ 1 - (1 - \tau)^N = 1 - (1 - \frac{1}{N\rho})^N \approx 1 - \exp(-\frac{1}{\rho}); \\ \lim_{N \rightarrow +\infty} p_{idle} = (1 - \tau)^N \approx \exp(-\frac{1}{\rho}); \\ \lim_{N \rightarrow +\infty} p = 1 - (1 - \tau)^{N-1} \approx 1 - \exp(-\frac{1}{\rho}) \end{cases} \quad (49)$$

With this, the upper bound system throughput S of IEEE 1901 PLC network considering retransmission protocols for $N \rightarrow +\infty$ can be given by (the two constants A and B have been shown in Eqs.43-44)

$$\lim_{N \rightarrow +\infty} S = L \cdot A \cdot \frac{\frac{1}{\rho} \cdot \exp(-\frac{1}{\rho})}{\sigma \cdot \exp(-\frac{1}{\rho}) + B \cdot \frac{1}{\rho} \exp(-\frac{1}{\rho}) + T_c \cdot [1 - \exp(-\frac{1}{\rho})]} \quad (50)$$

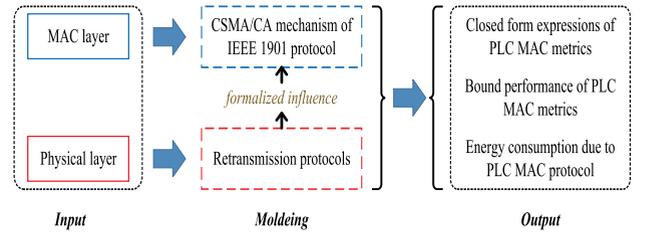


FIGURE 5. The methodology of the proposed cross-layered theoretical model.

Secondly, we analyze the bound performance of successful transmission probability P_{suc}^{κ} .

Lemma 2: The bound performance of successful transmission probability P_{suc}^{κ} for 1901 protocol (considering retransmission protocols) yields the following solution $\tau'_{optimal}$, i.e.,

$$\tau'_{optimal} = \frac{1}{N} \quad (51)$$

Proof 2: Reviewing Eq.15, we can expand P_{suc}^{κ} as

$$P_{suc}^{\kappa} = \sum_{x=1}^M P_s^{\kappa}(x) = \tau \cdot (1 - p) \cdot C_3 \cdot N$$

where C_3 is expanded as

$$C_3 = \begin{cases} \sum_{x=1}^M [(P_{out}^{ARQ})^{(x-1)}(1 - P_{out}^{ARQ})]; \\ \sum_{x=1}^M [P_{out,1 \rightarrow x}^{HARQ}(1 - P_{out,1 \rightarrow x}^{HARQ})] \end{cases}$$

Since C_3 can be seen as a constant, we denote $H(\tau) = C_3 \cdot N \cdot \tau \cdot (1 - p)$, and take the derivative of $H(\tau)$

$$H'(\tau) = N \cdot C_3 \cdot [\tau(1 - p)]^{(1)} = [\tau(1 - \tau)^{N-1}]^{(1)} = N \cdot C_3 \cdot (1 - N\tau) \cdot (1 - \tau)^{N-2} \quad (52)$$

Let $H'(\tau) = 0$, we can derive the optimal solution of Lemma 2, i.e., $\tau'_{optimal} = \frac{1}{N}$ (note that $\tau < 1$).

Under the case of $N \rightarrow +\infty$, P_{suc}^{κ} is expressed as

$$\lim_{N \rightarrow +\infty} P_{suc}^{\kappa} = \exp(-1) \cdot C_3 \quad (53)$$

Clearly, $\tau_{optimal}$ and $\tau'_{optimal}$ are the functions of N , we assert that the bounds of S and P_{suc}^{κ} rely significantly on the network size N .

Now we use Fig.5 to summarize the methodology of the proposed cross-layered theoretical model.

V. PERFORMANCE EVALUATION

In this part, we evaluate the performance of IEEE 1901 under the influence of two retransmission protocols (ARQ and HARQ-CC), and verify the proposed cross-layered theoretical model. We developed simulations in Matlab. To realize the CSMA/CA mechanism of 1901 protocol, we add a parallel deferral counter window on the base of using backoff counter window. The parameters used in the simulation are shown in Table 1 and Table 3 (system parameters). In the simulation, a converged topology based PLC network is organized,

TABLE 3. System parameters.

Generic Parameter	Size
Medium bit rate (R)	10Mbps
Idle slot (σ)	35.84us
Priority slot (PRS)	35.84us
$CIFS$	100.00us
$RIFS$	140.00us
$NACK$	110.48us
ACK	110.48us
$EIFS$	2920.64us
L (packet size)	5000.00bits
M (number of attempt fragments)	4
m (maximum backoff stage)	4
C_1	1w
C_2	0.5w
α (path loss exponent)	2.6
Pw_r	1w
Pw_{oh}	0.5w
N_0 (Average noise power)	10dBm
σ_R^2 (Scale parameter of Rayleigh distribution)	0.5
u (Nakagami factor)	3
K (buffer size)	1

in which there are N stations and an access point (used to receive packets), and the transmission distance between each station and access point is assumed to be Xm . The MAC layer of each station receives packets from the upper layer based on Poisson process with an average arrival rate λ . Stations transmit data packets to the access point through a PLC channel without considering the interference between stations. The PLC channel is assumed to have a typical fading mode (Rayleigh fading or Nakagami- u fading). All stations have the same priority type (CA0/CA1) and the same finite buffer size K , in which packets follow FIFO (first in first out) rule. In addition, each simulation experiment is split in 31 batches, and each batch consists of 5000 packets (for per station). The statistics of first batch is discarded to avoid initial distortions, and the considered performance measures are derived from the remaining 20 batches. All simulation results are with 0.95 confidence interval between $[0.91Avg(\cdot), 1.06Avg(\cdot)]$, where $Avg(\cdot)$ represents the average simulation result. The proposed cross-layered theoretical model is solved by using Fixed Point Iteration (FPI) method [47], where the fixed iteration is carried with a precision of 10^{-5} .

As PLC network's MAC layer introduces some overhead due to priority type, acknowledgment (negative acknowledgment) and inter-frame spaces, in simulations, the data packet transmission is preceded by two priority tone slots PRS and is followed by a response inter-frame space $RIFS$ and an acknowledgment frame ACK (or $NACK$). Finally, the contention inter-frame space $CIFS$ is used. A data packet corresponds to a frame duration D ($D = \frac{L}{R}$). In case of a collision, the stations differ their transmission for an extended inter-frame space $EIFS$ (verified by Eqs.18-20).

We select five significant metrics to measure the performance of IEEE 1901 PLC networks under the influence of different retransmission protocols and channel fading modes, i.e.,

(1) System throughput S : the metric can objectively reflect the impact of 1901 protocol on data transmission efficiency.

(2) Expected MAC service time $E[T_{mac}]$: this metric can objectively reflect the service efficiency of using 1901 protocol at MAC layer.

(3) Packet drop probability PDP^K : this metric can comprehensively reflect the impacts of PLC physical layer's retransmission protocols and channel fading type on the possibility of failure transmission.

(4) Packet blocking probability P_b : this metric can objectively reflect the possibility that the finite buffer size is fully-loaded caused by executing 1901 protocol.

(5) Expected total energy cost of transmitting one successful bit EPB : this metric can objectively reflect the impact of 1901 protocol on energy consumption for finishing one successful transmission.

The experiments are totally divided into four groups: Firstly, we investigate the relationship between network size and IEEE 1901's performance; Secondly, we test the 1901's performance under different traffic load (i.e., arrival rate); Thirdly, we study the impact of threshold SNR (η) on 1901's performance; Finally, we examine the impact of transmission distance Xm on 1901's performance.

A. THE IMPACT OF NETWORK SIZE

In this simulation group, we set the threshold SNR $\eta = -4dB$, transmission distance $X = 8m$, average packet arrival rate $\lambda = 50$, and the number of stations N varies in $[2, 20]$. Fig.6 shows the simulation and analysis results including the system throughput S , MAC service time $E[T_{mac}]$, packet drop probability PDP^K , packet blocking probability P_b and total energy cost of transmitting one successful bit EPB for priority type CA0/CA1 with different network sizes.

We can see that as the network size N increases, the system throughput increases first, then decreases. The reason is that the system throughput is affected not only by the successful transmission probability but also by the duration of average slot time (verified by Eq.22). The change rule of system throughput also reflects the channel utilization. Namely, with the increase of network size N , more stations contend the PLC channel, thus the channel utilization is enhanced (until reaching to the optimal utilization), however as the channel contention continuously intensifies, the channel utilization would be degraded. Since the increasing network size N would enhance the frequency of contention, the data packet has to wait a longer time duration to get the medium service, and the buffer of station is easier to be fully-loaded. Therefore, we can observe that the MAC service time and packet blocking probability increase with the increasing network size N . The packet drop probability increases with the increasing network size N , since the network size has a positive influence on the performance of packet drop probability (this conclusion can be demonstrated by Eqs.16-17). The total energy cost of transmitting one successful bit EPB increases with network size N . That is because with the increase of network size N , more stations would overhear the channel state,

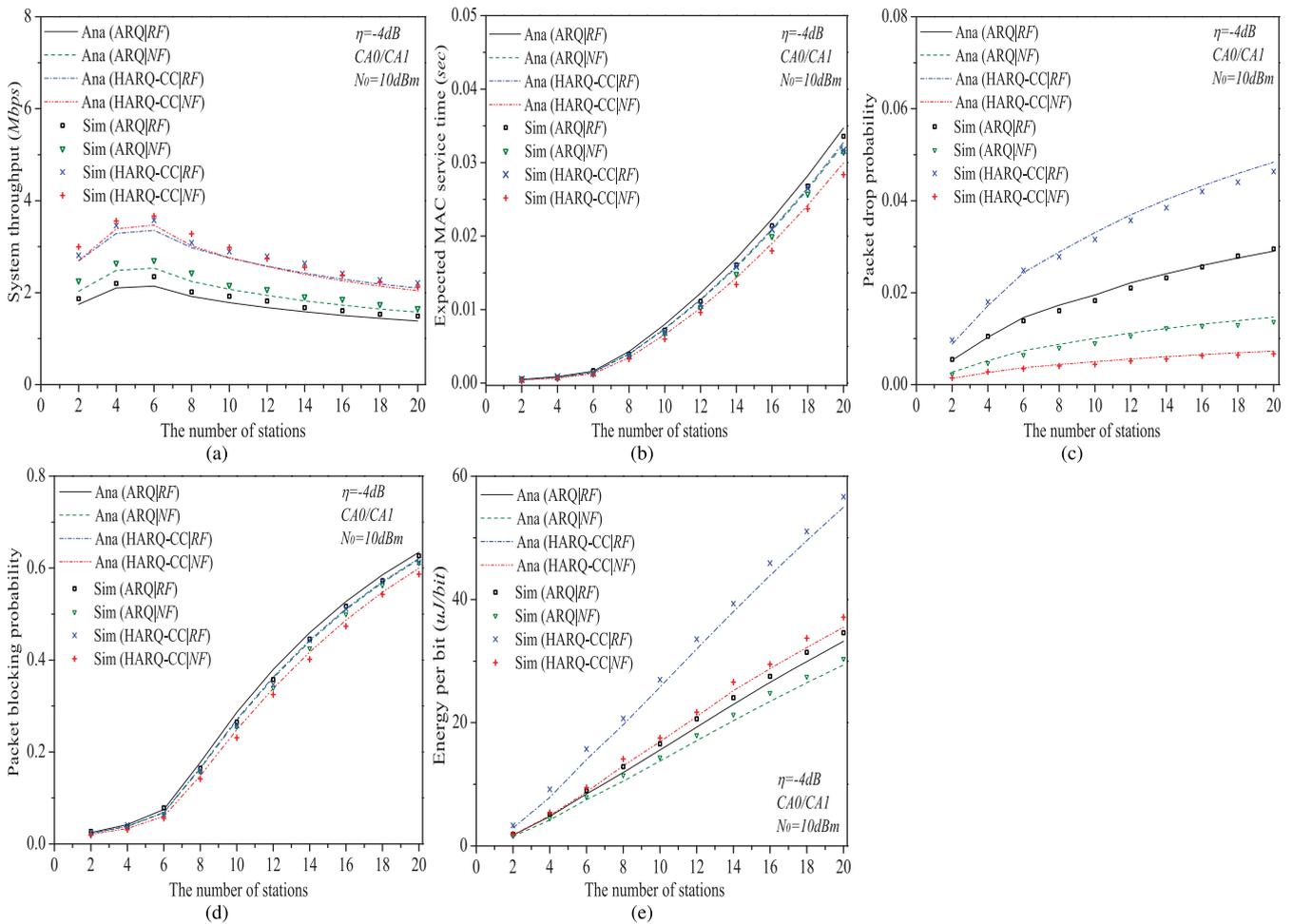


FIGURE 6. The MAC performance of 1901 protocol under different network size.

which accordingly enhances the total energy consumption of transmitting one successful bit (verified by Eq.41).

Here is an example of system throughput S ($N \in [2, 20]$). For using ARQ at physical layer, the simulation result of S varies from 1.87Mbps to 2.35Mbps, then to 1.49Mbps under RF channel; From 2.26Mbps to 2.71Mbps, then to 1.66Mbps under NF channel. The analysis result of S varies from 1.75Mbps to 2.14Mbps, then to 1.38Mbps under RF channel; From 2.03Mbps to 2.54Mbps, then to 1.58Mbps under NF channel.

For using HARQ-CC, the simulation result of S varies from 2.81Mbps to 3.58Mbps, then to 2.21Mbps under RF channel; From 3.00Mbps to 3.67Mbps, then to 2.13Mbps under NF channel. The analysis result of S varies from 2.69Mbps to 3.36Mbps, then to 2.10Mbps under RF channel; From 2.70Mbps to 3.47Mbps, then to 2.05Mbps under NF channel.

B. THE IMPACT OF TRAFFIC RATE

In this simulation group, we set the threshold SNR $\eta = -3\text{dB}$, transmission distance $X = 8\text{m}$, number of stations $N = 30$, and the average packet arrival rate λ varies in $[0.1, 20]$.

Fig.7 shows the simulation and analysis results including the system throughput S , expected MAC service time $E[T_{mac}]$, packet drop probability PDP^k , packet blocking probability P_b and total energy cost of transmitting one successful bit EPB for priority type CA0/CA1 with different traffic rates.

We can see that as the packet arrival rate λ increases, the system throughput increases first, then slowly decreases. The reason is that as the packet arrival rate increases, the transmission attempt frequency of station increases, so the channel utilization is enhanced (until reaching to the optimal utilization). However, as the transmission attempt frequency continuously intensifies, the collision frequency accordingly increases and the channel utilization would be decreased. Since the increasing λ would enhance the channel contention frequency (i.e., increasing the collision probability of stations), the data packet has to wait a longer time duration to get the medium service, and the buffer of station is easier to be fully-loaded. Therefore, as is shown in Fig.7, the MAC service time and packet blocking probability increase with the increasing packet arrival rate. The packet drop probability increases with the increasing λ . The most possible reason is

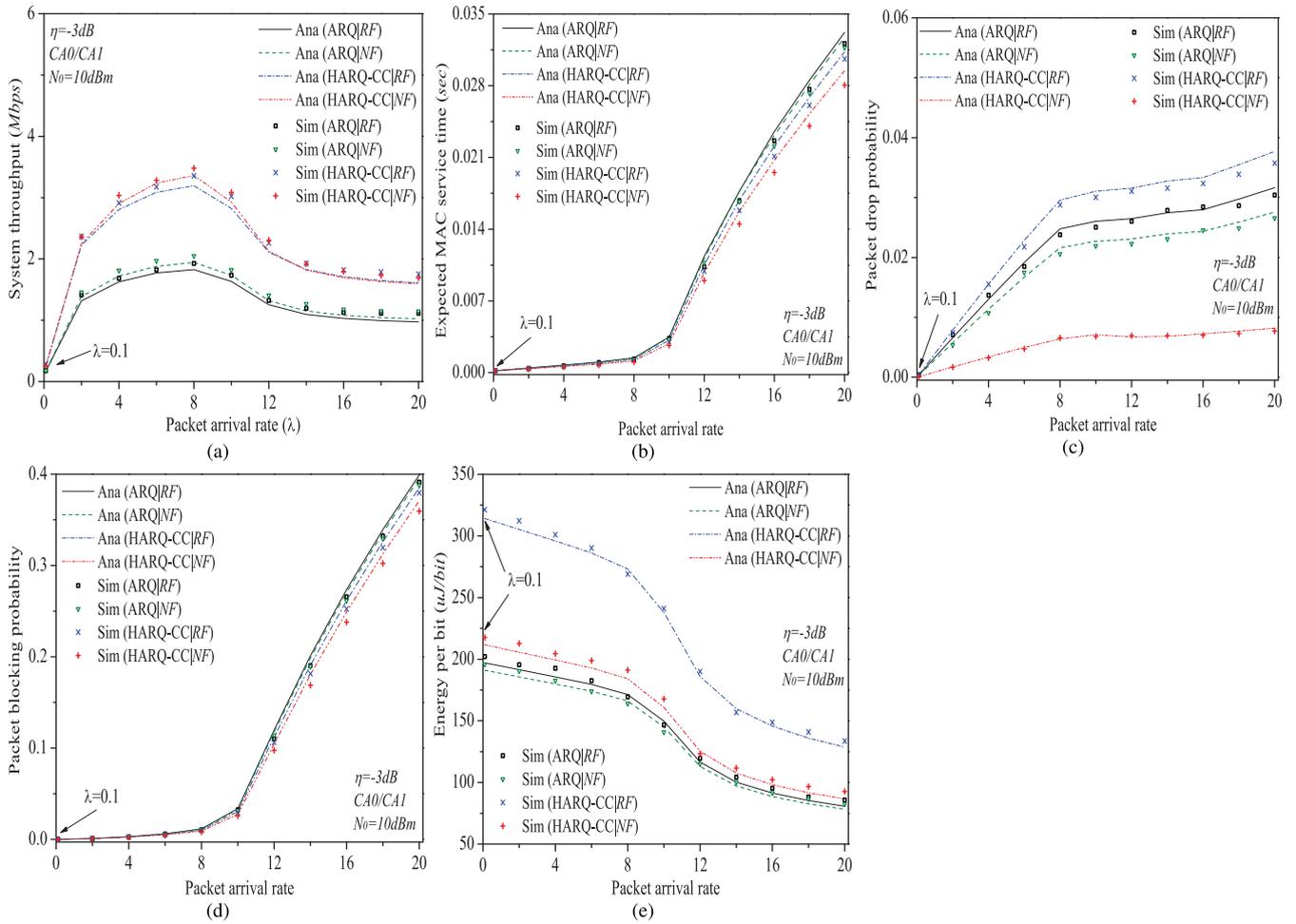


FIGURE 7. The MAC performance of 1901 protocol under different traffic rate.

that although the collision probability p and the transmission attempt probability τ increase with the increasing λ , nevertheless, the value of τ is still smaller than $\tau'_{optimal} = \frac{1}{N}$ (reviewing Eqs.52 and Lemma 2) under the condition of $\lambda \in [0.1, 20]$. Hence, operator function $\tau(1 - p)$ in Eqs.13-14 is still monotone increasing, and it would lead to the change rule of packet drop probability. The total energy cost of transmitting one successful bit EPB decreases with the increasing λ . The most possible reason is that as the packet arrival rate increases, the transmission attempt probability τ increases, the practical transmission interval is reduced, i.e., a specific successful transmission or dropping packet decreases may need shorter time duration (verified by Eqs.36-37). As a consequence, the time duration T_{busy} is shortened (i.e., the total energy cost of transmitting one successful bit decreases).

Here is an example of packet drop probability PDP^k ($\lambda \in [0.1, 20]$). For using ARQ protocol at physical layer, the analysis result of PDP^{ARQ} varies from 3.34×10^{-4} to 0.032 under RF channel; From 2.92×10^{-4} to 0.028 under NF channel. The simulation result of PDP^{ARQ} varies from 3.75×10^{-4} to

0.030 under RF channel; From 2.62×10^{-4} to 0.027 under NF channel.

For using HARQ-CC, the analysis result of PDP^{HARQ} varies from 3.99×10^{-4} to 0.038 under RF channel; From 8.65×10^{-4} to 0.0082 under NF channel. The simulation result of PDP^{HARQ} varies from 3.60×10^{-4} to 0.036 under RF channel; From 9.24×10^{-4} to 0.0077 under NF channel.

C. THE IMPACT OF THRESHOLD SNR

In this simulation group, we set the number of stations $N = 25$, average packet arrival rate $\lambda = 40$, transmission distance $X = 8m$ and the threshold SNR η varies in $[-5dB, 2dB]$. Fig.8 shows the simulation and analysis results including the system throughput S , expected MAC service time $E[T_{mac}]$, packet drop probability PDP^k , packet blocking probability P_b and total energy cost of transmitting one successful bit EPB for priority type $CA0/CA1$ with different threshold SNR .

We can see that as the threshold SNR η increases, the system throughput decreases. The reason is that as the threshold SNR η increases, the SNR of transmission attempt is more possible to be less than η . As a consequence, the packet

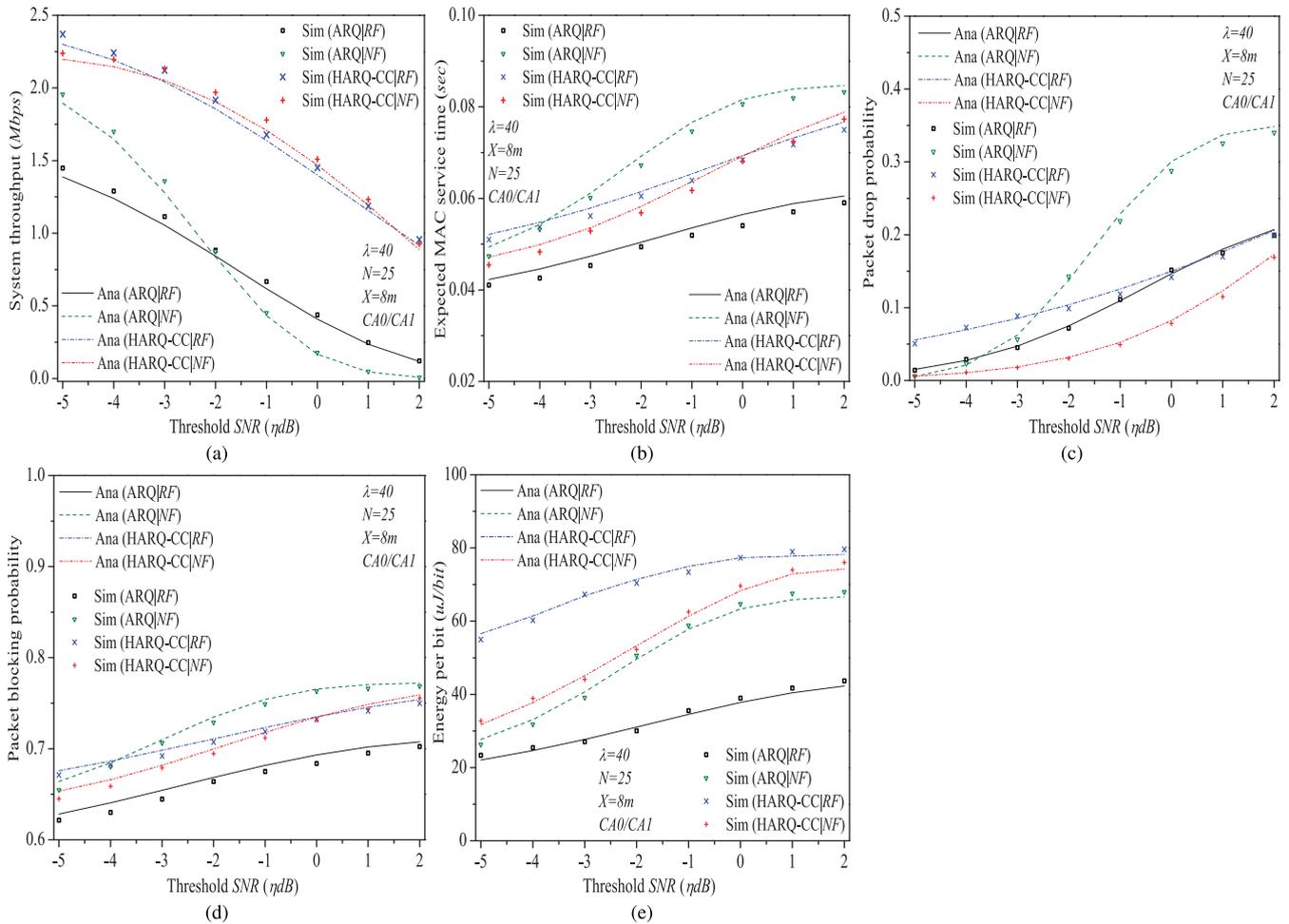


FIGURE 8. The MAC performance of 1901 protocol under different threshold SNR.

has a higher probability to be received in outage (proved by Eqs.11-12), i.e., the unsuccessful probability of transmission attempt is enhanced (the overall transmission efficiency is reduced). Due to the increase of η , the station occupying PLC channel may need more attempt fragments to accomplish one successful transmission (i.e., spending more time). The data packet has to wait longer in the station, and the buffer is easier to be fully-loaded. Hence, we can find that the MAC service time and packet blocking probability increases with the increasing η . The packet drop probability increases with the increasing η , since the increasing η would enlarge the value of $P_{out,x}^{ARQ}/P_{out,1 \rightarrow x}^{HARQ}$ that finally causes the increase of PDP^κ (verified by Eqs.16-17). The total energy cost of transmitting one successful bit EPB increases with the increasing η . The most possible reason is that with the increase of η , a station needs more attempt fragments to finish one successful transmission. Therefore, the practical duration of successful transmission is enhanced, which accordingly results the time duration of T_{busy} to be longer (i.e., the total energy consumption of transmitting one successful bit increases).

Here is an example of expected MAC service time $E[T_{mac}]$ ($\eta \in [-5dB, 2dB]$). For using ARQ at physical layer, the analysis result of $E[T_{mac}]$ varies from 0.0422s to 0.0605s under *RF* channel; From 0.0494s to 0.0846s under *NF* channel. The simulation result of $E[T_{mac}]$ varies from 0.0411s to 0.0590s under *RF* channel; From 0.0472s to 0.0832s under *NF* channel.

For using HARQ-CC, the analysis result of $E[T_{mac}]$ varies from 0.0521s to 0.0767s under *RF* channel; From 0.0472s to 0.0788s under *NF* channel. The simulation result of $E[T_{mac}]$ varies from 0.0507s to 0.0750s under *RF* channel; From 0.0455s to 0.0772s under *NF* channel.

D. THE IMPACT OF TRANSMISSION DISTANCE

In this simulation group, we set the number of stations $N = 25$, average packet arrival rate $\lambda = 40$, threshold SNR $\eta = 0dB$ and the transmission distance X varies in $[3m, 10m]$. Fig.9 shows the simulation and analysis results including the system throughput S , expected MAC service time $E[T_{mac}]$, packet drop probability PDP^κ , packet blocking probability P_b and total energy cost of transmitting one successful bit

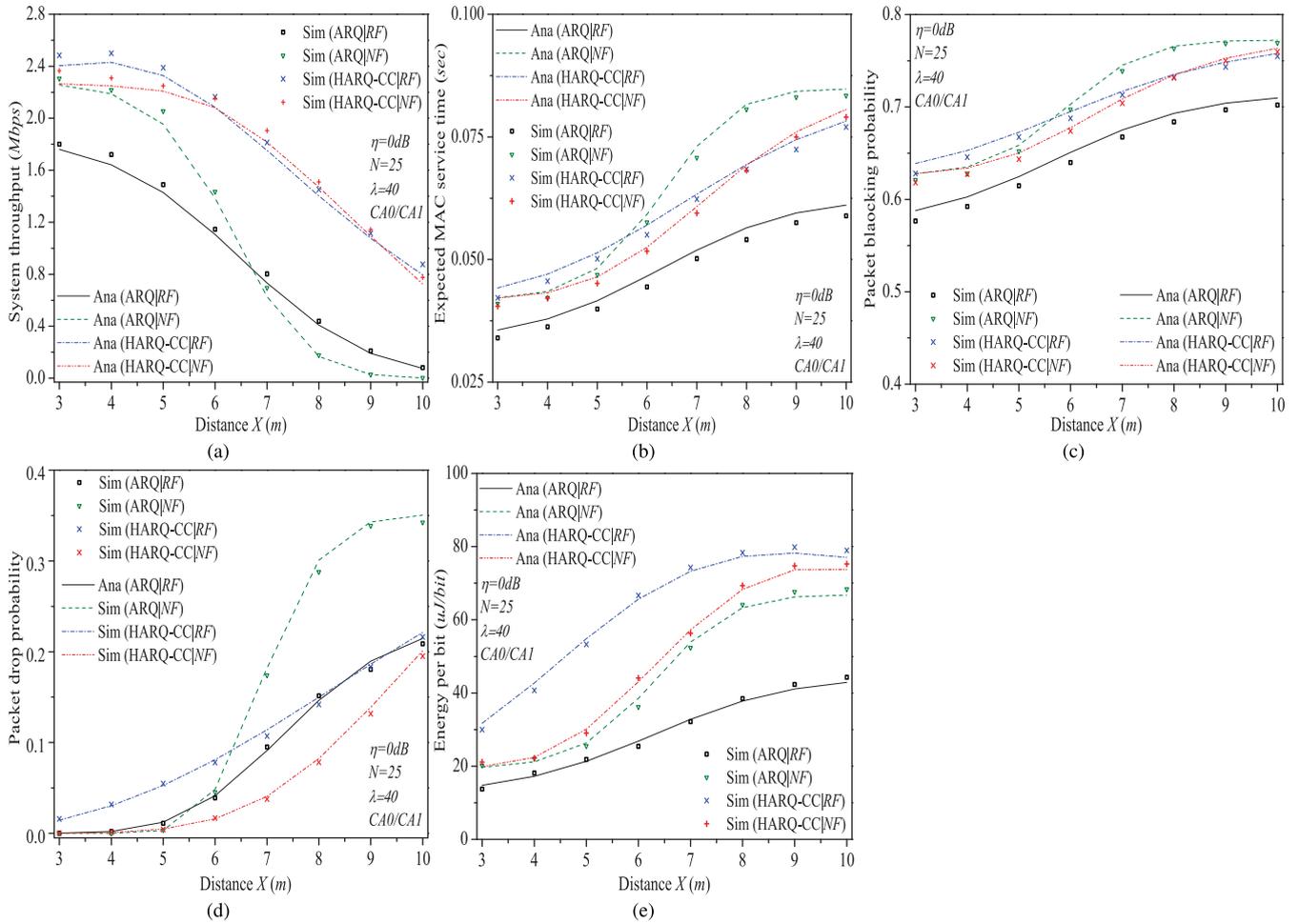


FIGURE 9. The MAC performance of 1901 protocol under different Distance X .

EPB for priority type CA0/CA1 with different transmission distance X .

We can see that as the transmission distance X increases, the system throughput decreases. The reason is that as the transmission distance X increases, the SNR of transmission attempt is easier to be less than η (this conclusion can be verified by Eqs.11-12). Accordingly, the packet has a higher probability to be received in outage, i.e., the overall transmission efficiency is decreased. The MAC service time and packet blocking probability increase with the increasing X . That is because with the increase of X , the probability of unsuccessful attempt is enhanced (received in outage), and the station occupying PLC channel may need more attempt fragments to finish a successful transmission (i.e., spending more time). As a result, the data packet has to wait longer in the station, and the buffer is easier to be fully-loaded. The packet drop probability increases with the increasing X , since the increasing X would enhance the value of $P_{out,x}^{ARQ}/P_{out,1 \rightarrow x}^{HARQ}$ that finally causes the increase of PDP^k (proved by Eqs.16-17). In overall, the total energy cost of transmitting one successful bit EPB increases with the increasing X . The most possible reason is that as X increases, a station needs

more attempt fragments to finish one successful transmission. Consequently, the practical duration of successful transmission is enhanced, which accordingly results the time duration of T_{busy} to be longer (i.e., the total energy consumption of transmitting one successful bit increases).

Here is an example of energy cost of transmitting one successful bit EPB ($X \in [3m, 10m]$). For using ARQ protocol at physical layer, the simulation result of EPB varies from $13.77\mu J/bit$ to $44.31\mu J/bit$ under RF channel; From $20.21\mu J/bit$ to $68.37\mu J/bit$ under NF channel. The analysis result of EPB varies from $14.80\mu J/bit$ to $42.93\mu J/bit$ under RF channel; From $19.72\mu J/bit$ to $66.78\mu J/bit$ under NF channel.

For using HARQ-CC, the simulation result of EPB varies from $30.00\mu J/bit$ to $78.95\mu J/bit$ under RF channel; From $21.10\mu J/bit$ to $75.24\mu J/bit$ under NF channel. The analysis result of EPB varies from $31.74\mu J/bit$ to $77.10\mu J/bit$ under RF channel; From $19.86\mu J/bit$ to $73.71\mu J/bit$ under NF channel.

As shown in Fig.6-Fig.9, under different retransmission protocols and channel fading modes, there always exists a good fit between analysis and simulation results, which

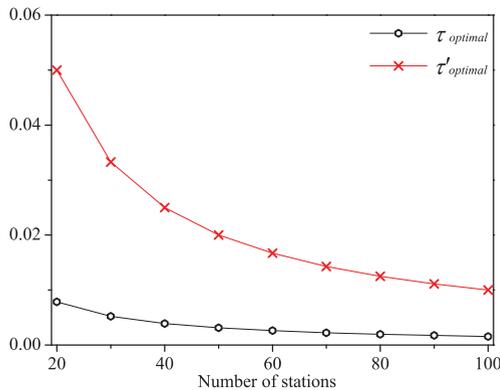


FIGURE 10. The values of $\tau_{optimal}$ and $\tau'_{optimal}$.

TABLE 4. The theoretical bound performance of P_{suc}^k .

N	RF P_{suc}^{ARQ}	NF P_{suc}^{HARQ}	RF P_{suc}^{ARQ}	NF P_{suc}^{HARQ}
20	0.3324	0.3546	0.4758	0.4245
30	0.3295	0.3516	0.4718	0.4209
40	0.3282	0.3501	0.4697	0.4191
50	0.3274	0.3492	0.4686	0.4180
60	0.3268	0.3486	0.4678	0.4173
70	0.3264	0.3482	0.4672	0.4168
80	0.3261	0.3479	0.4668	0.4164
90	0.3259	0.3476	0.4664	0.4162
100	0.3257	0.3475	0.4662	0.4159

proves that the proposed cross-layered theoretical model is accurate. Here we do not show the results of priority type CA2/CA3, since their change rules are similar to that of CA0/CA1.

Fig.10 shows the results of $\tau_{optimal}$ and $\tau'_{optimal}$ for $N \in [20, 100]$. We find that as the number of stations N increases, the values of $\tau_{optimal}$ and $\tau'_{optimal}$ decrease (proved by Eq.42 and Eq.51). For computational tractability, we further let $X = 8m$, $\eta = -4dB$, the theoretical bound values of successful transmission probability P_{suc}^k under different retransmission protocols $\kappa \in [ARQ, HARQ]$ and channel fading modes $[RF, NF]$ can be calculated in Table 4 ($N \in [20, 100]$).

VI. CONCLUSION

In this paper, we propose a cross-layered theoretical model of performance analysis for IEEE 1901 PLC networks considering retransmission protocols. In the modeling process, we firstly establish a T-D MC to depict the CSMA/CA mechanism of IEEE 1901, where the impacts of physical layer's retransmission protocols, channel fading modes and general practical environment configurations are comprehensively considered. On the basis, we derive the closed-form expressions of typical MAC metrics of 1901 under the influence of retransmission protocols. Next, we propose an energy consumption model to evaluate the consumed power of transmitting one successful bit. In addition, we make a bound

performance analysis for 1901's MAC metrics, i.e., the system throughput and successful transmission probability. We reveal that these two metrics depend significantly on the network size. Extensive simulation experiments verify that our proposed cross-layered theoretical model can accurately evaluate the performance of 1901 protocol under different retransmission protocols and system parameters. Our work can efficiently provide guidance for constructing practical PLC systems, and further optimizing PLC MAC layer.

Our work has numerous extensions. An immediate extension is to study the performance under a network environment with hidden terminals. In addition, how to optimize the MAC performance of IEEE 1901 protocol and reduce the system energy consumption on the basis of this work should be examined in our future study.

APPENDIX A THE DERIVATION PROCESS OF EQ.2

In Section 4, we have defined F_k , i.e., the probability that a station jumps from the transient state [43], [44] that it prepares a new HOL packet and begins to execute the CSMA/CA mechanism of 1901 to the backoff stage k ($k \in [1, m]$). Since a station at the above mentioned transient state would definitely enter the backoff stage 1, we have

$$F_1 = 1 \tag{54}$$

Based on the 1901 standard, a station tries to enter the next backoff stage through experiencing the collision or triggering the DCP. Thus, the probability $P_{(k \rightarrow k+1)}$ that a station at backoff stage k jumps to backoff stage $k + 1$ can be written as

$$P_{(k \rightarrow k+1)} = p + [(1 - p) \cdot \frac{Y_k}{W_k}]; 1 \leq k \leq m - 1 \tag{55}$$

Hence, the probability F_k for $k \in [2, m - 1]$ can be accordingly expressed as

$$F_k = F_1 \cdot \prod_{t=1}^{k-1} P_{(t \rightarrow t+1)} = \prod_{t=1}^{k-1} \{p + [(1 - p) \cdot \frac{Y_t}{W_t}]\} \quad k \in [2, m - 1] \tag{56}$$

Because of the reentrancy of the last backoff stage m (shown in T-D MC), the probability that the station jumps from the transient state that it prepares new HOL packet and begins to execute the CSMA/CA mechanism of 1901 to the last backoff stage m can be denoted as

$$F_m = F_{m-1} \cdot [p + (1 - p) \cdot \frac{Y_{m-1}}{W_{m-1}}] \cdot \{1 + \sum_{q=1}^{+\infty} [p + (1 - p) \cdot \frac{Y_m}{W_m}]^q\} = \prod_{t=1}^{m-1} \{p + [(1 - p) \cdot \frac{Y_t}{W_t}]\} \cdot \frac{1}{1 - p - (1 - p) \cdot \frac{Y_m}{W_m}} = \{p + [(1 - p) \cdot \frac{Y_{m-1}}{W_{m-1}}]\} \cdot \frac{1}{1 - p - (1 - p) \cdot \frac{Y_m}{W_m}} \cdot F_{m-1} \tag{57}$$

Gathering the above conclusions (i.e., Eqs.54-57), we derive Eq.2.

APPENDIX B THE DERIVATION PROCESS OF τ FOR A STATION

We use recursion method to derive the expression of τ . According to the one-step transition probability of T-D MC,⁸ we can get the probability of transient state [43], [44] Ψ that a station prepares a new HOL packet and begins to execute the CSMA/CA mechanism of 1901 protocol, i.e.,

$$\Psi = \sum_{k=1}^m b_{k,1} \cdot (1-p)(1-\mu_0) + E(1-\nu) \quad (58)$$

Combining the definition of F_k (shown in Appendix A), $b_{k,g}$ (or $d_{k,j}$) is determined by the probability that the station at the transient state (i.e., Ψ), the probability that the station jumps from the transient state to the backoff stage k ($k \in [1, m]$), i.e., F_k , and the probability of entering the state $b_{k,g}$ (or $d_{k,j}$) at backoff stage k . Therefore, using the balance equation method [43], the expressions of $b_{k,g}$ and $d_{k,j}$ can be expressed respectively as:

$$\begin{cases} b_{k,W_k} = \Psi \cdot F_k \cdot \frac{X_{k,W_k}}{W_k} \\ b_{k,g} = \Psi \cdot F_k \cdot \frac{X_{k,g}}{W_k} + 1 \cdot b_{k,g+1}; & g \in [d_k + 1, W_k - 1] \\ b_{k,d_k} = \Psi \cdot F_k \cdot \frac{1}{W_k} + 1 \cdot b_{k,d_k+1} \\ b_{k,g} = \Psi \cdot F_k \cdot \frac{1}{W_k} + 1 \cdot b_{k,g+1}; & g \in [1, d_k - 1] \\ d_{k,d_k+1} = \Psi \cdot F_k \cdot \frac{Y_k}{W_k} \\ d_{k,j} = 1 \cdot d_{k,j+1}; & j \in [1, d_k] \end{cases} \quad (59)$$

Further using recursion strategy, we can derive the expanded expressions for $b_{k,g}$ and $d_{k,j}$

$$\begin{cases} b_{k,g} = \Psi \cdot F_k \cdot \left[\sum_{h=d_k+1}^{W_k} \frac{X_{k,h}}{W_k} + \sum_{h=g}^{d_k} \frac{1}{W_k} \right]; & g \in [1, d_k] \\ b_{k,g} = \Psi \cdot F_k \cdot \sum_{h=g}^{W_k} \frac{X_{k,h}}{W_k}; & g \in [d_k + 1, W_k] \\ d_{k,j} = \Psi \cdot F_k \cdot \frac{Y_k}{W_k}; & j \in [1, d_k + 1] \end{cases} \quad (60)$$

In addition, the empty state probability E can be written as (using balance equation method)

$$\begin{aligned} E &= E\nu + \sum_{k=1}^m b_{k,1}(1-p)(1-\mu_0) \\ &= \frac{\Psi(1-\mu_0)}{1-\nu} \end{aligned} \quad (61)$$

Through the above derivation, we can finally expand $\tau = \frac{\sum_{k=1}^m b_{k,1}}{\sum_{k=1}^m (b_{k,g} + d_{k,j}) + E}$ as Eq.3.

⁸The one-step transition probabilities can be directly derived by T-D MC, thus we do not show them anymore.

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