

# The Marshall-Olkin Odd Burr III-G Family: Theory, Estimation, and Engineering Applications

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**ABSTRACT** We propose a new flexible class called the Marshall-Olkin odd Burr III family for generating continuous distributions and derive some of its statistical properties. We provide three special models which accommodate symmetrical, right-skewed and left-skewed shaped densities as well as bathtub, decreasing, increasing, reversed-J shaped and upside-down bathtub failure rate functions. The parameters are estimated by maximum likelihood, least squares and a percentile method. Some simulations investigate the accuracy of the three methods. We illustrate the utility of a special model through three applications to engineering field.

**INDEX TERMS** Burr III distribution, engineering data, exponential distribution, parameter estimation, maximum likelihood, stochastic ordering.

## I. INTRODUCTION

There has been an increasing motivation for constructing new generated families of continuous distributions by adding shape parameters to a baseline distribution due to desirable properties of the generated models. Some well-known generated families were introduced recently such as the Marshall-Olkin-G (Marshall and Olkin, 1997), exponentiated-G (Gupta *et al.*, 1998), Kumaraswamy-G (Cordeiro and de Castro, 2011), Lomax-G (Cordeiro *et al.*, 2014), Kumaraswamy Marshall-Olkin-G (Alizadeh *et al.*, 2015), odd Burr generalized-G (Alizadeh *et al.*, 2016), generalized odd log-logistic-G (Cordeiro *et al.*, 2017), generalized tan family (Al-Mofleh, 2018), generalized odd Lindley-G (Afify *et al.*, 2019), odd Lomax-G (Cordeiro *et al.*, 2019) and odd Dagum-G (Afify and Alizadeh, 2020) among others.

Jamal *et al.* (2017) proposed the *odd Burr-III-G* (OBIII-G for short) class, based on the Burr III distribution, by introducing two extra parameters to a baseline G distribution to obtain a more flexible class. Let  $G(x; \delta)$  be the parent cumulative distribution function (cdf) with parameter vector  $\delta$ , and  $\bar{G}(x; \delta) = 1 - G(x; \delta)$ . The OBIII-G family cdf

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follows by integrating the Burr III density with positive shape parameters  $b$  and  $c$ , namely

$$W_{OBIII}(x; \delta) = bc \int_0^{\frac{G(x; \delta)}{\bar{G}(x; \delta)}} w^{-c-1} (1 + w^{-c})^{-b-1} dw$$

$$= \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b}, \quad x > 0. \quad (1)$$

By differentiating (1), we obtain its probability density function (pdf)

$$w_{OBIII}(x; \delta) = \frac{cbg(x; \delta)\bar{G}^{-c-1}(x; \delta)}{G^{c-1}(x; \delta)} \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b-1}.$$

Marshall and Olkin (1997) proposed a general method to construct new models by adding a shape parameter to a specified distribution. Let  $W(x; \delta)$  and  $w(x; \delta)$  be the cdf and pdf of a specified distribution G. The cdf and pdf of the *Marshall-Olkin-G* (MO-G) class have the forms

$$F_{MO}(x; \alpha, \delta) = \frac{W(x; \delta)}{\phi + (1 - \phi)W(x; \delta)}, \quad \phi > 0, \quad (3)$$

and

$$f_{MO}(x) = \frac{\phi w(x; \delta)}{[\phi + (1 - \phi)W(x; \delta)]^2}, \tag{4}$$

respectively. Clearly,  $F_{MO}(x; \phi, \delta)$  reduces to  $W(x; \delta)$  when  $\phi = 1$ . For different values of  $\phi$ ,  $F_{MO}(x)$  can have more flexibility than  $W(x; \delta)$ .

We propose and study a new generator called the *Marshall-Olkin odd Burr III-G* (MOOB-G) family by taking (1) as the baseline cdf in Equation (3). Thus, the cdf of the MOOB-G family has the form

$$F_{MOOB}(x; \phi, c, b, \delta) = \frac{\left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b}}{1 - (1 - \phi) \left( 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b} \right)}, \quad x > 0, \tag{5}$$

where  $\phi > 0$ ,  $b > 0$  and  $c > 0$  are the shape parameters and  $\delta$  is the baseline parameter vector.

The cdf (5) can be explained by combining the Burr III distribution to generate  $W(x)$  with the distribution of an unknown geometric number  $N$  of independent risk factors or components generated by the baseline odds ratio. Let  $T$  be a random variable (rv) having cdf  $G(t; \delta)$  describing a stochastic system and  $Z$  be a rv representing the *odds ratio*. The risk that a system having the lifetime  $T$  will be not working at time  $z$  is  $G(z; \delta)/\bar{G}(z; \delta)$ . If the randomness of the odds ratio  $Z$  is modeled by the Burr III distribution given by Equation (1), the cdf of  $Z$  can be written as  $Pr(Z \leq z) = H(z; b, c, \delta)$ . Further, consider a sequence of independent and identically distributed (iid) odds ratio rvs  $Z_1, Z_2, \dots$  with associated risks  $H(z; b, c, \delta)$ . We define the minimum odds ratio  $X = \min\{Z_1, \dots, Z_N\}$ , where  $N$  is an unknown number described by a discrete geometric random variable (with support in  $\{1, 2, \dots\}$  and probability parameter  $\phi$ ) independent of the  $Z_i$ 's. The probability generating function (pgf) of  $N$  takes the form  $E(s^N) = \tau(s; \phi) = \phi s [1 - (1 - \phi)s]^{-1}$ . Under this set-up and  $0 < \phi < 1$ , the cdf of  $X$  is given by (5). For the case  $\phi > 1$ , the cdf of  $X$  is equal to (5) if  $N$  has a geometric rv with probability  $1/\phi$ .

Furthermore, the sub-models of the MOOB-G family can provide symmetrical, left-skewed, symmetrical, right-skewed, and reversed-J densities, and upside-down bathtub, increasing, decreasing, bathtub, and reversed-J shaped hazard rates. These sub-models are also capable of modeling different shapes of aging and failure criteria. Hence, the MOOB-G family can be a useful alternative to many classes for modeling skewed data in real-life applications.

The pdf corresponding to (5) has the form

$$f_{MOOB}(x; \phi, c, b, \delta) = \frac{\phi c b g(x; \delta) \bar{G}^{c-1}(x; \delta) \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b-1}}{G^{c+1}(x; \delta) \left[ 1 - (1 - \phi) \left( 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b} \right) \right]^2}. \tag{6}$$

For  $c = b = 1$ , we obtain as a special case the MO-G family (Marshall and Olkin, 1997). The MOOB-G family is identical to the OBIII-G class (Jamal et al., 2017) when  $\phi = 1$  and it reduces to the baseline G distribution when  $\phi = c = b = 1$ . The MOOB-G family can be quite effective for real data analysis.

Henceforth, let  $X \sim \text{MOOB-G}(\phi, b, c, \delta)$  be a rv with density (6). The hazard rate function (hrf) of  $X$  is (7), as shown at the bottom of the next page.

The quantile function (qf) of  $X$  (for  $0 < u < 1$ ) follows by inverting (5) as

$$Q_{MOOB}(u) = F_{MOOB}^{-1}(u) = G^{-1} \left\{ \frac{\left[ \left( \frac{u\phi}{1-\phi u} \right)^{-\frac{1}{b}} - 1 \right]^{-\frac{1}{c}}}{1 + \left[ \left( \frac{u\phi}{1-\phi u} \right)^{-\frac{1}{b}} - 1 \right]^{-\frac{1}{c}}} \right\}. \tag{8}$$

We organize the article as follows. In Section 2, we define three special models in the new family. In Section 3, we obtain a useful linear representation for the family density. Some of its mathematical properties are reported in Section 4. In Section 5, we discuss the estimation of the unknown parameters using three methods (maximum likelihood, least squares and percentile estimation). In Section 6, some simulation results validate the proposed methods. The usefulness of the new family is illustrated in Section 7 using three applications. Finally, some conclusions are addressed in Section 8.

## II. THREE SPECIAL DISTRIBUTIONS

In this section, we present three special distributions of the MOOB-G family by choosing some baseline distributions commonly used in lifetime data analysis along with their density and hazard rate plots.

### A. MOOB-EXPONENTIAL (MOOB-EX)

Consider the exponential (Ex) distribution with parameter  $a > 0$  and cdf  $G(x) = 1 - \exp(-ax)$ ,  $x > 0$ . Then, the MOOB-Ex density follows from (6) as  $f(x)$ , shown at the bottom of the next page.

The MOOB-Ex distribution includes the OBIII-Ex distribution (Jamal et al., 2017) when  $\phi = 1$ . For  $\phi = b = c = 1$ , we obtain the Ex distribution. The MO-Ex distribution (Marshall and Olkin, 1997) follows when  $b = c = 1$ . Some plots of the density and hrf of the MOOB-Ex distribution are shown in Figure 1. They show that the MOOB-Ex density can be reversed J-shape, right-skewed, left-skewed and concave down, whereas the hrf can be decreasing, increasing or bathtub.

### B. MOOB-LOMAX (MOOB-LX)

The cdf of the Lomax (Lx) distribution is  $G(x) = 1 - (1 + x/d)^{-a}$ , where  $a > 0$  and  $d > 0$ . Then, the MOOB-Lx density can be expressed from (6) as shown at the bottom of the next page.

Three special cases of the MOOB-Lx distribution are: the MO-Lx distribution (Ghitany et al., 2007)

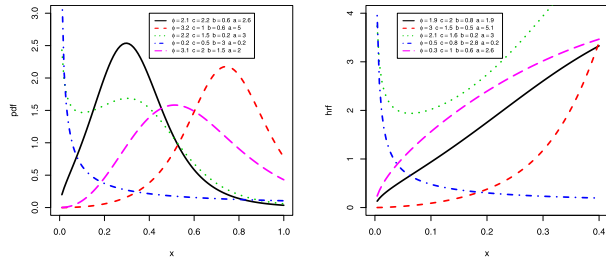


FIGURE 1. Density and hrf plots of the MOOB-Ex distribution.

when  $b = c = 1$ ; the OBIII-Lx distribution (Jamal et al., 2017) when  $\phi = 1$ ; the Lx distribution when  $\phi = b = c = 1$ . Some plots of the density and hrf of this distribution are given in Figure 2. They show that the pdf can be unimodal, reversed J-shape and right-skewed, and the hrf can be increasing, decreasing, bathtub or unimodal.

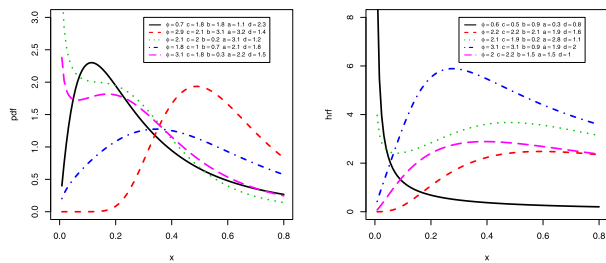


FIGURE 2. Density and hrf plots of the MOOB-Lx distribution.

C. MOOB-LINDLEY (MOOB-LI)

Consider the cdf  $G(x) = 1 - \frac{1+a+ax}{1+a} \exp(-ax)$ ,  $a > 0$ , of the Lindley (Li) distribution. Then, the pdf of the MOOB-Li density follows from (6) as  $f(x)$ , shown at the bottom of the next page.

Three special cases of the MOOB-Li distribution are: the MO-Li distribution (Ghitany et al., 2012) when  $b = c = 1$ ; the OBIII-Li distribution (Jamal et al., 2017) when  $\phi = 1$ ; the Li distribution when  $\phi = b = c = 1$ . Some plots of

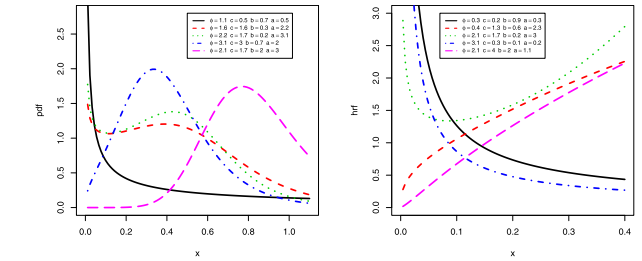


FIGURE 3. Density and hrf plots of the MOOB-Li distribution.

the density and hrf of this distribution are given in Figure 3 for some scenarios. They show that the density can be unimodal, bimodal and reversed J-shape, and that the hrf can be decreasing, increasing, or bathtub.

III. LINEAR REPRESENTATION

Following Cordeiro et al. (2014), we obtain a linear representation for the MO-G density

$$f_{MO}(x) = \begin{cases} \sum_{j=0}^{\infty} p_j h_{j+1}(x) & \text{if } \phi \in (0, 1), \\ \sum_{j=0}^{\infty} q_j h_{j+1}(x) & \text{if } \phi > 1, \end{cases}$$

where (for  $j = 0, 1, 2, \dots$ )

$$\begin{cases} p_j = \frac{\phi(-1)^j}{j+1} \sum_{l=j}^{\infty} \binom{l}{j} (l+1) \phi^l & \text{if } \phi \in (0, 1), \\ q_j = \phi^{-1} (1 - \phi^{-1})^j & \text{if } \phi > 1, \end{cases}$$

and

$$h_{j+1}(x) = (j+1) c b \frac{g(x; \delta) G^{1-c}(x; \delta)}{[1 - G(x; \delta)]^{-c-1}} \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-(j+1)b-1} \quad (9)$$

$$h_{MOOB}(x; \phi, c, b, \delta) = \frac{\phi c b g(x; \delta) \bar{G}^{c-1}(x; \delta) G^{-c-1}(x; \delta) \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b-1}}{\left( 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b} \right) \left[ 1 - (1 - \phi) \left( 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1 - G(x; \delta)} \right]^{-c} \right\}^{-b} \right) \right]} \quad (7)$$

$$f(x) = \frac{\phi c b a \exp(-acx) [1 - \exp(-ax)]^{-c-1} \left\{ 1 + \left[ \frac{1 - \exp(-ax)}{\exp(-ax)} \right]^{-c} \right\}^{-b-1}}{\left[ 1 - (1 - \phi) \left( 1 - \left\{ 1 + \left[ \frac{1 - \exp(-ax)}{\exp(-ax)} \right]^{-c} \right\}^{-b} \right) \right]^2}$$

$$f(x) = \frac{\phi c b \frac{a}{d} \left( 1 + \frac{x}{d} \right)^{-a-1} \left[ \left( 1 + \frac{x}{d} \right)^{-a} \right]^{c-1} \left\{ 1 + \left[ \left( 1 + \frac{x}{d} \right)^a - 1 \right]^{-c} \right\}^{-b-1}}{\left[ 1 - \left( 1 + \frac{x}{d} \right)^{-a} \right]^{c+1} \left[ 1 - (1 - \phi) \left( 1 - \left\{ 1 + \left[ \left( 1 + \frac{x}{d} \right)^a - 1 \right]^{-c} \right\}^{-b} \right) \right]^2}$$

Consider the power series (which converges everywhere)

$$(1+z)^{-d} = \sum_{i=0}^{\infty} \binom{-d}{i} z^i. \tag{10}$$

Applying (10) to (9) leads to

$$\begin{aligned} h_{j+1}(x) &= (j+1)cbg(x;\delta) \\ &\times \sum_{i=0}^{\infty} \binom{-(j+1)b-1}{i} G^{1-(i+1)c}(x;\delta) [1-G(x;\delta)]^{(i+1)c+1}. \end{aligned}$$

By expanding the binomial term in power series, we can write

$$h_{j+1}(x) = g(x;\delta) \sum_{i,r=0}^{\infty} A_{i,r}^{(j+1)} G^{r+1-(i+1)c}(x;\delta), \tag{11}$$

where (for  $i, r \geq 0$ )

$$A_{i,r}^{(j+1)} = (j+1)cb(-1)^r \binom{-(j+1)b-1}{i} \binom{(i+1)c+1}{r}.$$

For any real  $a$ , the following power series (converges everywhere) holds

$$G(x;\delta)^a = \sum_{m=0}^{\infty} s_m(a) G(x;\delta)^m, \tag{12}$$

where

$$s_m(a) = \sum_{n=m}^{\infty} (-1)^{n+m} \binom{a}{n} \binom{n}{m}.$$

Applying (12) to equation (11) and changing the order of the sums, we can write

$$h_{j+1}(x) = \sum_{m=0}^{\infty} B_m^{(j+1)} \pi_{m+1}(x),$$

where  $\pi_{m+1}(x) = (m+1)g(x;\delta)G(x;\delta)^m$  is the exponentiated-G (exp-G) density with power parameter  $m+1$  (for  $m \geq 0$ ) and

$$B_m^{(j+1)} = (m+1)^{-1} \sum_{i,r=0}^{\infty} A_{i,r}^{(j+1)} s_m(r+1-(i+1)c).$$

Hence, the density of  $X$  is rewritten as

$$f_{\text{MOOB}}(x) = \begin{cases} \sum_{m=0}^{\infty} v_m \pi_{m+1}(x) & \text{if } \phi \in (0, 1), \\ \sum_{m=0}^{\infty} w_m \pi_{m+1}(x) & \text{if } \phi > 1, \end{cases} \tag{13}$$

where

$$v_m = \sum_{m=0}^{\infty} p_j B_m^{(j+1)}$$

and

$$w_m = \sum_{m=0}^{\infty} q_j B_m^{(j+1)}.$$

Equation (13) proves that the density of  $X$  is a linear combination of exp-G densities and then some MOOB-G properties (see Section 4.2) can follow from those of the exp-G distribution. We can adopt at most ten terms for each sum in (13) to provide accurate results in most analytical platforms.

#### IV. THE MOOB-G PROPERTIES

##### A. SHAPES AND ASYMPTOTICS

We can determine, numerically, the critical points of the density and hazard rate functions of  $X$ . For the density, they are the roots of the equation:

$$\begin{aligned} &\frac{g'(x;\delta)}{g(x;\delta)} - (c-1) \frac{g(x;\delta)}{1-G(x;\delta)} - (c+1) \frac{g(x;\delta)}{G(x;\delta)} \\ &- (b+1) \frac{c g(x;\delta) \bar{G}^{c-1}(x;\delta)}{G^{c+1}(x) \left\{ 1 + \left[ \frac{G(x;\delta)}{1-G(x;\delta)} \right]^{-c} \right\}} \\ &+ \frac{2cb\phi g(x;\delta) \bar{G}^{c-1}(x;\delta) \left\{ 1 + \left[ \frac{G(x;\delta)}{1-G(x;\delta)} \right]^{-c} \right\}^{-b-1}}{\left[ 1 - (1-\phi) \left( 1 - \left\{ 1 + \left[ \frac{G(x;\delta)}{1-G(x;\delta)} \right]^{-c} \right\}^{-b} \right) \right]} + \end{aligned}$$

For the hazard rate, they follow from the equation

$$\begin{aligned} &\frac{g'(x;\delta)}{g(x;\delta)} - (c-1) \frac{g(x;\delta)}{1-G(x;\delta)} - (c+1) \frac{g(x;\delta)}{G(x;\delta)} \\ &- (b+1) \frac{c g(x;\delta) \bar{G}^{c-1}(x;\delta)}{G^{c+1}(x;\delta) \left\{ 1 + \left[ \frac{G(x;\delta)}{1-G(x;\delta)} \right]^{-c} \right\}} \\ &\times \frac{bc^2 g(x;\delta) \bar{G}^{c-1}(x;\delta) \left\{ 1 + \left[ \frac{G(x;\delta)}{1-G(x;\delta)} \right]^{-c} \right\}^{-b-1}}{G^{c+1}(x;\delta) \left( 1 - \left\{ 1 + \left[ \frac{G(x;\delta)}{1-G(x;\delta)} \right]^{-c} \right\}^{-b} \right)} \end{aligned}$$

$$f(x) = \frac{\phi cb \frac{a^2}{a+1} (1+x) \exp(-ax) \left[ \frac{1+a+ax}{1+a} \exp(-ax) \right]^{c-1} \left\{ 1 + \left[ \frac{1 - \frac{1+a+ax}{1+a} \exp(-ax)}{\frac{1+a+ax}{1+a} \exp(-ax)} \right]^{-c} \right\}^{-b-1}}{\left[ 1 - \frac{1+a+ax}{1+a} \exp(-ax) \right]^{c+1} \left[ 1 - (1-\phi) \left( 1 - \left\{ 1 + \left[ \frac{1 - \frac{1+a+ax}{1+a} \exp(-ax)}{\frac{1+a+ax}{1+a} \exp(-ax)} \right]^{-c} \right\}^{-b} \right) \right]^2}.$$

$$+ \frac{\phi bc^2 g(x; \delta) \bar{G}^{c-1}(x; \delta) \left\{ 1 + \left[ \frac{G(x; \delta)}{1-G(x; \delta)} \right]^{-c} \right\}^{-b-1}}{G^{c+1}(x; \delta) \left[ 1 - (1-\phi) \left( 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1-G(x; \delta)} \right]^{-c} \right\}^{-b} \right) \right]}$$

We can examine the critical points of the pdf and hrf of  $X$  from the last two equations by using many easy-to-use programming environments including Matlab, Mathematica, Maple and Ox.

The tail behaviors of the cdf, pdf and hrf of  $X$  are (when  $G(x; \delta) \rightarrow 0$ )

$$\begin{aligned} F(x) &\sim \left( \frac{1}{\phi} \right) G(x; \delta)^{bc}, \\ f(x) &\sim \left( \frac{1}{\phi} \right) bc g(x; \delta) [G(x; \delta)]^{bc-1}, \\ h(x) &\sim \left( \frac{1}{\phi} \right) bc g(x; \delta) [G(x; \delta)]^{bc-1}. \end{aligned}$$

If  $x \rightarrow \infty$ ,

$$\begin{aligned} F(x) &\sim 1 - \phi b [1 - G(x; \delta)]^c, \\ f(x) &\sim \phi bc g(x; \delta) [1 - G(x; \delta)]^{c-1}, \\ h(x) &\sim \frac{c g(x; \delta)}{1 - G(x; \delta)}. \end{aligned}$$

**B. MOMENTS**

Let  $Y_{m+1}$  be the exp-G rv with power parameter  $m + 1$ . The  $r$ th moment of  $X$  follows from (13) as

$$\mu'_r = E(X^r) \begin{cases} \sum_{m=0}^{\infty} v_m E(Y_{m+1}^r) & \text{if } \phi \in (0, 1), \\ \sum_{m=0}^{\infty} w_m E(Y_{m+1}^r) & \text{if } \phi > 1. \end{cases}$$

Similarly, the  $r$ th incomplete moment of  $X$  can be expressed as

$$\varphi_r(t) = \begin{cases} \sum_{m=0}^{\infty} v_m \int_{-\infty}^t x^r \pi_{m+1}(x) & \text{if } \phi \in (0, 1), \\ \sum_{m=0}^{\infty} w_m \int_{-\infty}^t x^r \pi_{m+1}(x) & \text{if } \phi > 1. \end{cases}$$

The integral in the last two equations represents the  $r$ th incomplete moment of  $Y_{m+1}$ .

The moment generating function (mgf) of  $X$  comes from (13) as

$$M_X(t) = \begin{cases} \sum_{m=0}^{\infty} v_m M_{m+1}(t) & \text{if } \phi \in (0, 1), \\ \sum_{m=0}^{\infty} w_m M_{m+1}(t) & \text{if } \phi > 1, \end{cases}$$

where  $M_{m+1}(t)$  is the mgf of  $Y_{m+1}$  (for  $m \geq 0$ ). Then,  $M_X(t)$  can be obtained from the exp-G generating function.

We provide some numerical values of the first four moments denoted by  $\mu'_r$  ( $r = 1, 2, 3, 4$ ), variance  $\sigma^2$ , skewness ( $Sk$ ), and kurtosis ( $Kur$ ) of the MOOB-Ex distribution for different parameter values. Table 1 lists these numerical values.

**TABLE 1. The Numerical Values of the First Four Moments,  $\sigma^2$ ,  $Sk$ , and  $Kur$  of the MOOB-Ex Distribution for Some Parametric Values.**

$(\phi, c, b, a)$	$\mu'_1$	$\mu'_2$	$\mu'_3$	$\mu'_4$	$\sigma^2$	$Sk$	$Kur$
(0.5,0.5,0.5,0.5)	1.01372	7.59493	92.21433	1492.68605	6.56726	4.23045	27.08413
(1.5,0.5,0.5,0.5)	2.39992	20.55147	262.73193	4359.96201	14.791845	2.50333	10.20705
(3.0,0.5,0.5,0.5)	3.80713	36.54753	493.08842	8422.16504	22.05318	1.79623	4.89005
(6.0,0.5,0.5,0.5)	5.63804	61.65663	893.12122	15906.37333	29.86875	1.27843	0.98814
(0.5,2.0,0.5,0.5)	0.81273	1.24493	2.90042	9.44915	0.58443	2.10122	21.66604
(0.5,6.0,0.5,0.5)	1.075824	1.27863	1.65062	2.29803	0.12123	0.33354	508.17355
(6.0,6.0,0.5,0.5)	1.568364	2.59465	4.50321	8.19189	0.13489	0.22435	1238.51904
(0.5,0.5,2.0,0.5)	3.56625	29.48014	365.49743	5952.57802	16.76208	2.05188	6.60155
(6.0,6.0,6.0,0.5)	2.12327	4.63435	10.41455	24.14698	0.12608	0.88032	3506.16206
(0.5,2.0,2.0,2.0)	0.43354	0.23535	0.16176	0.14166	0.04738	1.80974	258.12465
(6.0,6.0,6.0,6.0)	0.17699	0.03213	0.00603	0.00112	0.00081	0.87983	44376.80374

**C. STOCHASTIC ORDERING**

The stress strength model has been widely used in applications of engineering and physics. Consider two independent rvs  $X_1 \sim \text{MOOB-G}(\phi_1, c, b, \delta)$  and  $X_2 \sim \text{MOOB-G}(\phi_2, c, b, \delta)$ . The stress strength model can be expressed as

$$f(x) = \frac{\phi_1 c b g(x; \delta) \bar{G}^{c-1}(x; \delta) \left\{ 1 + \left[ \frac{G(x; \delta)}{1-G(x; \delta)} \right]^{-c} \right\}^{-b-1}}{G^{c+1}(x; \delta) \left[ 1 - (1-\phi_1) \left( 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1-G(x; \delta)} \right]^{-c} \right\}^{-b} \right) \right]^2}$$

and

$$g(x) = \frac{\phi_2 c b g(x; \delta) \bar{G}^{c-1}(x; \delta) \left\{ 1 + \left[ \frac{G(x; \delta)}{1-G(x; \delta)} \right]^{-c} \right\}^{-b-1}}{G^{c+1}(x; \delta) \left[ 1 - (1-\phi_2) \left( 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1-G(x; \delta)} \right]^{-c} \right\}^{-b} \right) \right]^2}$$

Then, the ratio  $\frac{f(x)}{g(x)}$  takes the form

$$\frac{f(x)}{g(x)} = \frac{\phi_1}{\phi_2} \left( \frac{1 - \bar{\phi}_1 z}{1 - \bar{\phi}_2 z} \right)^2,$$

where  $z = 1 - \left\{ 1 + \left[ \frac{G(x; \delta)}{1-G(x; \delta)} \right]^{-c} \right\}^{-b}$ .

By differentiating the last equation in relation to  $x$ , we have

$$\frac{d}{dx} \frac{f(x)}{g(x)} = \frac{\phi_1}{\phi_2} 2 \left( \frac{1 - \bar{\phi}_1 z}{1 - \bar{\phi}_2 z} \right) \frac{(\bar{\phi}_1 - \bar{\phi}_2) z'}{(1 - \bar{\phi}_2 z)^2}.$$

After some algebra, we obtain

$$\frac{d}{dx} \frac{f(x)}{g(x)} = 2 \frac{\phi_1}{\phi_2} (\bar{\phi}_1 - \bar{\phi}_2) z \left[ \frac{1 - \bar{\phi}_1 z'}{(1 - \bar{\phi}_2 z)^3} \right],$$

where  $\frac{dz}{dx} = z'$ . Finally, if  $\phi_2 < \phi_1$  then  $\frac{d}{dx} \frac{f(x)}{g(x)} < 0$  and the likelihood ratio exists  $X <_{lr} Y$ .

**V. ESTIMATION METHODS**

Let  $x_1, \dots, x_n$  be the observations from the MOOB-G family with vector of parameters  $\theta = (\phi, c, b, \delta^T)^T$ . This section is devoted to address the maximum likelihood, least squares method and a percentile method to estimate  $\theta$  from complete samples only. The performances of the three methods are investigated through Monte Carlo simulations using **Mathematica** software.

**A. MAXIMUM LIKELIHOOD**

By maximizing the total log-likelihood function

$$\begin{aligned} \ell(\theta) = & n \log(\phi c b) + \sum_{i=1}^n \log g(x_i; \delta) \\ & + (c - 1) \sum_{i=1}^n \log \bar{G}(x_i; \delta) \\ & - (c + 1) \sum_{i=1}^n \log G(x_i; \delta) \\ & - (b + 1) \sum_{i=1}^n \log(z_i) \\ & - 2 \sum_{i=1}^n \log \left[ 1 - (1 - \phi)(1 - z_i^{-b}) \right], \end{aligned} \quad (14)$$

where  $z_i = 1 + \left[ \frac{G(x_i; \delta)}{\bar{G}(x_i; \delta)} \right]^{-c}$ , we can find the maximum likelihood estimates (MLEs) of the parameters in  $\theta$ .

Equation (14) can be maximized either directly under statistical computing environment such as Ox (sub-routine MaxBFGS), SAS (PROC NL MIXED), R, Maple or Mathematica or by solving the nonlinear likelihood equations by differentiating (14). The distributions in the MOOB-G family can also be fitted to real data using the *AdequacyModel* package (see <https://www.r-project.org/>). We can compute the MLEs, their standard errors and goodness-of-fit statistics from this package by defining only the pdf and cdf of the distribution under study.

The score functions for the model parameters are

$$\begin{aligned} U_\phi = & \frac{n}{\phi} - 2 \sum_{i=1}^n \left[ \frac{1 - z_i^{-b}}{1 - (1 - \phi)(1 - z_i^{-b})} \right], \\ U_c = & \frac{n}{c} + \sum_{i=1}^n \log \bar{G}(x_i; \delta) - \sum_{i=1}^n \log G(x_i; \delta) \\ & + (b + 1) \sum_{i=1}^n \frac{\log \left[ \frac{G(x_i; \delta)}{\bar{G}(x_i; \delta)} \right]}{z_i \left[ \frac{G(x_i; \delta)}{\bar{G}(x_i; \delta)} \right]^c} \\ & + 2b(1 - \phi) \sum_{i=1}^n \frac{\left[ \frac{G(x_i; \delta)}{\bar{G}(x_i; \delta)} \right]^{-c} \log \left[ \frac{G(x_i; \delta)}{\bar{G}(x_i; \delta)} \right]}{z_i^{b+1} \left[ 1 - (1 - \phi)(1 - z_i^{-b}) \right]}, \\ U_b = & \frac{n}{b} - \sum_{i=1}^n \log(z_i) + 2(1 - \phi) \sum_{i=1}^n \frac{z_i^{-b} \log(z_i)}{1 - (1 - \phi)(1 - z_i^{-b})} \end{aligned}$$

and  $U_\delta$ , as shown at the bottom of the next page, where the vectors

$$\begin{aligned} g'(x_i; \delta) = & \frac{\partial g(x_i; \delta)}{\partial \delta}, \quad G'(x_i; \delta) = \frac{\partial G(x_i; \delta)}{\partial \delta}, \\ \bar{G}'(x_i; \delta) = & \frac{\partial \bar{G}(x_i; \delta)}{\partial \delta} \end{aligned}$$

have the same dimension of  $\delta$ . These equations can be solved numerically from the statistical software above.

**B. LEAST SQUARES**

Suppose that  $x_{1:n}, \dots, x_{n:n}$  are the ordered observations from  $F(x; \phi, c, b, \delta)$  given by (5). Note that  $E[F(X_{i:n})] = \frac{i}{n+1}$ .

Hence, The least square estimates (LSEs) can be determined by minimizing the function

$$S(\theta) = \sum_{i=1}^n \left[ F(x_{i:n}; \phi, c, b, \delta) - \frac{i}{n+1} \right]^2,$$

with respect to the model parameters. The LSEs of  $\phi, c, b$  and  $\delta$  can be found by solving the nonlinear equations

$$\begin{aligned} \frac{\partial S(\theta)}{\partial \phi} = & 2 \sum_{i=1}^n \left[ F(x_{i:n}; \phi, c, b, \delta) - \frac{i}{n+1} \right] \\ & F'(x_{i:n}; \phi, c, b, \delta)_\phi = 0, \\ \frac{\partial S(\theta)}{\partial c} = & 2 \sum_{i=1}^n \left[ F(x_{i:n}; \phi, c, b, \delta) - \frac{i}{n+1} \right] \\ & F'(x_{i:n}; \phi, c, b, \delta)_c = 0, \\ \frac{\partial S(\theta)}{\partial b} = & 2 \sum_{i=1}^n \left[ F(x_{i:n}; \phi, c, b, \delta) - \frac{i}{n+1} \right] \\ & F'(x_{i:n}; \phi, c, b, \delta)_b = 0, \\ \frac{\partial S(\theta)}{\partial \delta} = & 2 \sum_{i=1}^n \left[ F(x_{i:n}; \phi, c, b, \delta) - \frac{i}{n+1} \right] \\ & F'(x_{i:n}; \phi, c, b, \delta)_\delta = 0, \end{aligned}$$

where  $F'(x_{i:n}; \theta)_\eta = \frac{\partial F(x_{i:n}; \theta)}{\partial \eta}$  for any component  $\eta$  of  $\theta = (\phi, c, b, \delta^T)^T$ . We can solve these equations numerically to obtain the estimates  $\hat{\phi}_{LSE}, \hat{c}_{LSE}, \hat{b}_{LSE}$  and  $\hat{\delta}_{LSE}$ .

**C. PERCENTILE ESTIMATION**

Let  $p_i = i/(n + 1)$  be an estimate of  $F(x_{i:n}; \phi, c, b, \delta)$  for  $i = 1, \dots, n$ . Let  $Q_{p_i}(\phi, c, b, \delta)$  be the qf obtained from (8) by setting  $u = p_i = i/(n + 1)$ .

Then, the percentile estimates (PCEs) of the unknown parameters  $\phi, c, b$  and  $\delta$  can be derived by minimizing

$$M(\theta) = \sum_{i=1}^n [x_{i:n} - Q_{p_i}(\phi, c, b, \delta)]^2,$$

with respect to the model parameters or by solving the nonlinear equations

$$\frac{\partial M(\theta)}{\partial \phi} = 2 \sum_{i=1}^n [x_{i:n} - Q_{p_i}(\phi, c, b, \delta)] Q'_{p_i}(\phi, c, b, \delta)_\phi = 0,$$



TABLE 2. MSEs and AEs for the MOOB-Ex Distribution.

n	Parameters	PCE		LSE		MLE	
		MSEs	AEs	MSEs	AEs	MSEs	AEs
50	$\phi = 0.8$	0.02365	0.75625	0.00017	0.80106	0.00434	0.80357
	$c = 1.5$	0.25885	1.23699	0.00022	1.49488	0.07658	1.54477
	$b = 1.5$	0.71613	1.35755	0.00141	1.50163	0.05512	1.52599
	$a = 0.1$	0.84259	0.11118	0.00002	0.09983	0.00068	0.10578
100	$\phi = 0.8$	0.01321	0.78389	0.00008	0.80075	0.00217	0.80243
	$c = 1.5$	0.16421	1.34225	0.00010	1.49735	0.03669	1.52211
	$b = 1.5$	0.48057	1.44864	0.00068	1.50144	0.02620	1.51526
	$a = 0.1$	0.21325	0.12854	$8.0 \times 10^{-6}$	0.09985	0.00029	0.10257
150	$\phi = 0.8$	0.00887	0.78580	0.00006	0.80035	0.00146	0.80162
	$c = 1.5$	0.13359	1.36533	0.00007	1.49780	0.02210	1.50604
	$b = 1.5$	0.27976	1.42857	0.00049	1.50037	0.01713	1.50409
	$a = 0.1$	0.00572	0.12464	$5.7 \times 10^{-6}$	0.09994	0.00018	0.10173
50	$\phi = 1.0$	0.04069	0.96196	0.00026	1.00020	0.00683	1.00309
	$c = 1.5$	0.23737	1.24107	0.00030	1.49469	0.08615	1.55098
	$b = 1.5$	0.70676	1.40265	0.00125	1.49882	0.04643	1.52109
	$a = 0.1$	3.72914	0.17824	0.00002	0.10010	0.00078	0.10653
100	$\phi = 1.0$	0.02105	0.96477	0.00013	1.00065	0.00360	1.00476
	$c = 1.5$	0.16594	1.28907	0.00016	1.49715	0.03910	1.51671
	$b = 1.5$	0.34082	1.35769	0.00060	1.50069	0.02483	1.51584
	$a = 0.1$	0.96345	0.18612	$8.3 \times 10^{-6}$	0.09991	0.00031	0.10224
150	$\phi = 1.0$	0.01473	0.98425	0.00009	0.99984	0.00208	1.00137
	$c = 1.5$	0.11425	1.37234	0.00011	1.49878	0.02417	1.52061
	$b = 1.5$	0.25914	1.43886	0.00041	1.49927	0.01389	1.51116
	$a = 0.1$	0.01012	0.12758	$5.8 \times 10^{-6}$	0.10009	0.00017	0.10170
50	$\phi = 0.8$	0.02536	0.77259	0.00016	0.799946	0.004175	0.801616
	$c = 1.2$	0.16312	1.01736	0.00013	1.19658	0.051372	1.24173
	$b = 1.5$	0.94427	1.45910	0.00133	1.49845	0.056156	1.53026
	$a = 0.1$	1.03099	0.10954	0.00001	0.100097	0.000439	0.104232
100	$\phi = 0.8$	0.01358	0.77540	0.00008	0.799989	0.002182	0.805079
	$c = 1.2$	0.11915	1.05245	0.00006	1.19798	0.023637	1.22275
	$b = 1.5$	0.47563	1.40783	0.00068	1.49914	0.028053	1.52768
	$a = 0.1$	0.03915	0.12168	$5.5 \times 10^{-6}$	0.100039	0.000172	0.101079
150	$\phi = 0.8$	0.00960	0.78691	0.00006	0.800086	0.001586	0.802496
	$c = 1.2$	0.08960	1.09502	0.00004	1.19861	0.015888	1.2125
	$b = 1.5$	0.31271	1.44252	0.00049	1.49971	0.018424	1.51332
	$a = 0.1$	0.00555	0.11745	$3.9 \times 10^{-6}$	0.100006	0.000135	0.101127

TABLE 3. MSEs and AEs for the MOOB-Ex Distribution.

n	Parameters	PCE		LSE		MLE	
		MSEs	AEs	MSEs	AEs	MSEs	AEs
50	$\phi = 0.8$	0.02536	0.77259	0.00016	0.799946	0.004175	0.801616
	$c = 1.2$	0.16312	1.01736	0.00013	1.19658	0.051372	1.24173
	$b = 1.5$	0.94427	1.45910	0.00133	1.49845	0.056156	1.53026
	$a = 0.1$	1.03099	0.10954	0.00001	0.100097	0.000439	0.104232
100	$\phi = 0.8$	0.01358	0.77540	0.00008	0.799989	0.002182	0.805079
	$c = 1.2$	0.11915	1.05245	0.00006	1.19798	0.023637	1.22275
	$b = 1.5$	0.47563	1.40783	0.00068	1.49914	0.028053	1.52768
	$a = 0.1$	0.03915	0.12168	$5.5 \times 10^{-6}$	0.100039	0.000172	0.101079
150	$\phi = 0.8$	0.00960	0.78691	0.00006	0.800086	0.001586	0.802496
	$c = 1.2$	0.08960	1.09502	0.00004	1.19861	0.015888	1.2125
	$b = 1.5$	0.31271	1.44252	0.00049	1.49971	0.018424	1.51332
	$a = 0.1$	0.00555	0.11745	$3.9 \times 10^{-6}$	0.100006	0.000135	0.101127
50	$\phi = 0.8$	0.02432	0.76639	0.00015	0.800011	0.00465	0.804949
	$c = 0.5$	0.02824	0.41767	0.00002	0.498403	0.00821	0.512498
	$b = 1.5$	0.84333	1.41064	0.00124	1.49842	0.05688	1.53309
	$a = 0.1$	0.00060	0.10965	$2.6 \times 10^{-6}$	0.099916	0.00016	0.101204
100	$\phi = 0.8$	0.01349	0.78085	0.00009	0.799835	0.00212	0.801308
	$c = 0.5$	0.02093	0.44062	0.00001	0.499353	0.00411	0.507379
	$b = 1.5$	0.46569	1.42331	0.00075	1.49887	0.02445	1.50984
	$a = 0.1$	0.00020	0.10484	$1.5 \times 10^{-6}$	0.099994	0.00008	0.101055
150	$\phi = 0.8$	0.00944	0.78068	0.00005	0.800283	0.00147	0.801575
	$c = 0.5$	0.01567	0.44618	$7.0 \times 10^{-6}$	0.499417	0.00250	0.50372
	$b = 1.5$	0.28886	1.39817	0.00045	1.50033	0.01760	1.51024
	$a = 0.1$	0.00013	0.10386	$9.4 \times 10^{-7}$	0.099934	0.00005	0.100361
50	$\phi = 0.8$	0.02432	0.76639	0.00015	0.800011	0.00465	0.804949
	$c = 0.5$	0.02824	0.41767	0.00002	0.498403	0.00821	0.512498
	$b = 1.5$	0.84333	1.41064	0.00124	1.49842	0.05688	1.53309
	$a = 0.1$	0.00060	0.10965	$2.6 \times 10^{-6}$	0.099916	0.00016	0.101204
100	$\phi = 0.8$	0.01349	0.78085	0.00009	0.799835	0.00212	0.801308
	$c = 0.5$	0.02093	0.44062	0.00001	0.499353	0.00411	0.507379
	$b = 1.5$	0.46569	1.42331	0.00075	1.49887	0.02445	1.50984
	$a = 0.1$	0.00020	0.10484	$1.5 \times 10^{-6}$	0.099994	0.00008	0.101055
150	$\phi = 0.8$	0.00944	0.78068	0.00005	0.800283	0.00147	0.801575
	$c = 0.5$	0.01567	0.44618	$7.0 \times 10^{-6}$	0.499417	0.00250	0.50372
	$b = 1.5$	0.28886	1.39817	0.00045	1.50033	0.01760	1.51024
	$a = 0.1$	0.00013	0.10386	$9.4 \times 10^{-7}$	0.099934	0.00005	0.100361

where  $Q'_{p_i}(\theta)_\eta = \frac{\partial Q_{p_i}(\theta)}{\partial \eta}$ , and  $\eta$  denotes any component of  $\theta = (\phi, c, b, \delta)^T$ . The software mentioned before can produce the PCEs  $\hat{\phi}_{PCE}, \hat{c}_{PCE}, \hat{b}_{PCE}$  and  $\hat{\delta}_{PCE}$ .

VI. SIMULATION STUDY

We perform a detailed simulation study to compare the precision of the estimators of the unknown parameters for the MOOB-Ex and MOOB-Li distributions. The adequacy of these estimators is based on the mean squared

$$\frac{\partial M(\theta)}{\partial c} = 2 \sum_{i=1}^n [x_{i:n} - Q_{p_i}(\phi, c, b, \delta)] Q'_{p_i}(\phi, c, b, \delta)_c = 0,$$

$$\frac{\partial M(\theta)}{\partial b} = 2 \sum_{i=1}^n [x_{i:n} - Q_{p_i}(\phi, c, b, \delta)] Q'_{p_i}(\phi, c, b, \delta)_b = 0,$$

$$\frac{\partial M(\theta)}{\partial \delta} = 2 \sum_{i=1}^n [x_{i:n} - Q_{p_i}(\phi, c, b, \delta)] Q'_{p_i}(\phi, c, b, \delta)_\delta = 0,$$

$$U_\delta = \sum_{i=1}^n \frac{g'(x_i; \delta)}{g(x_i; \delta)} + (c - 1) \sum_{i=1}^n \frac{\bar{G}'(x_i; \delta)}{\bar{G}(x_i; \delta)} - (c + 1) \sum_{i=1}^n \frac{G'(x_i; \delta)}{G(x_i; \delta)}$$

$$- 2bc(1 - \phi) \sum_{i=1}^n \frac{[\bar{G}(x_i; \delta)G'(x_i; \delta) - G(x_i; \delta)\bar{G}'(x_i; \delta)] \left[ \frac{G(x_i; \delta)}{\bar{G}(x_i; \delta)} \right]^{-c-1}}{z_i^{b+1} \bar{G}^2(x_i; \delta) [1 - (1 - \phi)(1 - z_i^{-b})]}$$

$$+ c(b + 1) \sum_{i=1}^n \frac{[\bar{G}(x_i; \delta)G'(x_i; \delta) - G(x_i; \delta)\bar{G}'(x_i; \delta)] \left[ \frac{G(x_i; \delta)}{\bar{G}(x_i; \delta)} \right]^{-c-1}}{z_i^{-b-1} \bar{G}^2(x_i; \delta)},$$

**TABLE 4. MSEs and AEs for the MOOB-Li Distribution.**

<i>n</i>	Parameters	PCE		LSE		MLE	
		MSEs	AEs	MSEs	AEs	MSEs	AEs
100	$\phi = 0.8$	0.01253	0.78171	0.000095	0.80014	0.00199	0.80171
	$c = 1.2$	0.10817	1.06704	0.000073	1.19807	0.02433	1.22297
	$b = 1.5$	0.45130	1.43071	0.000770	1.49966	0.02378	1.51413
	$a = 0.2$	2.84033	0.32391	0.000062	0.20018	0.00037	0.20441
200	$\phi = 0.8$	0.00572	0.78111	0.000035	0.79908	0.00109	0.80122
	$c = 1.2$	0.06754	1.07868	0.000026	1.19964	0.01069	1.20482
	$b = 1.5$	0.16729	1.37291	0.000296	1.49702	0.01312	1.50620
	$a = 0.2$	0.05805	0.23124	0.000023	0.20083	0.00019	0.20326
300	$\phi = 0.8$	0.00338	0.80643	0.000033	0.79962	0.00073	0.80051
	$c = 1.2$	0.04194	1.16965	0.000019	1.19947	0.00751	1.20957
	$b = 1.5$	0.12041	1.51267	0.000273	1.49856	0.00847	1.50422
	$a = 0.2$	0.00432	0.21070	0.000021	0.20042	0.00014	0.20334
100	$\phi = 0.8$	0.01235	0.78462	0.000092	0.80037	0.00212	0.80048
	$c = 1.2$	0.10346	1.09470	0.000072	1.19889	0.02330	1.20695
	$b = 1.5$	0.34968	1.45164	0.000756	1.50072	0.02655	1.50455
	$a = 0.4$	9.79763	0.29146	0.000211	0.40007	0.00142	0.40450
200	$\phi = 0.8$	0.00782	0.78891	0.000039	0.79965	0.00114	0.80177
	$c = 1.2$	0.08537	1.09970	0.000030	1.19896	0.01078	1.20280
	$b = 1.5$	0.26358	1.43599	0.000329	1.49838	0.01347	1.50732
	$a = 0.4$	0.73616	0.39329	0.000089	0.40075	0.00070	0.40123
300	$\phi = 0.8$	0.00487	0.79675	0.000033	0.79959	0.00070	0.80018
	$c = 1.2$	0.04968	1.13262	0.000019	1.19940	0.00742	1.20812
	$b = 1.5$	0.15738	1.46643	0.000285	1.49844	0.00850	1.50393
	$a = 0.4$	0.02012	0.44780	0.000075	0.40081	0.00045	0.40180
100	$\phi = 1.0$	0.02260	0.96963	0.000110	1.00246	0.00345	1.00839
	$c = 1.2$	0.13029	1.05072	0.000067	1.19751	0.02130	1.21385
	$b = 1.2$	0.24491	1.11514	0.000321	1.20374	0.01484	1.21295
	$a = 0.2$	0.17225	0.29510	0.000039	0.19866	0.00034	0.20346
200	$\phi = 1.0$	0.01196	0.97503	0.000059	0.99981	0.00177	1.00297
	$c = 1.2$	0.07520	1.10694	0.000028	1.19886	0.01033	1.21157
	$b = 1.2$	0.14519	1.13300	0.000180	1.19930	0.00740	1.20903
	$a = 0.2$	0.01558	0.25013	0.000020	0.20018	0.00018	0.20338
300	$\phi = 1.0$	0.00700	0.98475	0.000049	1.00067	0.00093	0.99932
	$c = 1.2$	0.05078	1.11803	0.000018	1.19875	0.00851	1.20972
	$b = 1.2$	0.07234	1.13296	0.000150	1.20085	0.00490	1.20132
	$a = 0.2$	0.00543	0.22710	0.000017	0.19963	0.00010	0.20367

errors (MSEs). All calculations are done automatically using *Mathematica*. We generate 1,000 samples of the MOOB-Ex and MOOB-Li distributions. We take  $n = 50, 100, 150$  for the MOOB-Ex model and  $n = 100, 200, 300$  for the MOOB-Li model. The average estimates (AEs) and MSEs of the MLEs, LSEs and PCEs for the MOOB-Ex distribution are given in Tables 2-3. Further, the AEs and MSEs of the MLEs, LSEs and PCEs for the MOOB-Li distribution are listed in Tables 4-5. We note that all the estimators reveal the consistency property. Also, the figures in these tables indicate that the LSEs produce the best results for estimating the parameters of the MOOB-Ex and MOOB-Li distributions in terms of their MSEs in most cases.

**VII. DATA ANALYSIS**

We prove the flexibility of the MOOB-Ex distribution by comparing with some competitive distributions given in Table 6 by means of three real data sets. The Cramér-Von Mises (CVM), Anderson-Darling (AD) and the Kolmogorov-Smirnov (KS) statistics and the KS  $p$ -values of

**TABLE 5. MSEs and AEs for the MOOB-Li Distribution.**

<i>n</i>	Parameters	PCE		LSE		MLE	
		MSEs	AEs	MSEs	AEs	MSEs	AEs
100	$\phi = 1.0$	0.02272	0.95928	0.000112	0.99882	0.00345	1.00314
	$c = 1.2$	0.12127	1.01203	0.000082	1.19912	0.02367	1.21599
	$b = 1.5$	0.42624	1.33600	0.000555	1.49673	0.02402	1.51442
	$a = 0.4$	1.50032	0.60642	0.000192	0.40181	0.00187	0.41363
200	$\phi = 1.0$	0.00807	0.99090	0.000089	0.99933	0.00163	1.00299
	$c = 1.2$	0.05484	1.09804	0.000046	1.19959	0.01204	1.21115
	$b = 1.5$	0.13158	1.41557	0.000443	1.49819	0.01131	1.51026
	$a = 0.4$	0.42930	0.52371	0.000154	0.40131	0.00085	0.41112
300	$\phi = 1.0$	0.00736	0.99045	0.000041	1.00101	0.00112	1.00175
	$c = 1.2$	0.03898	1.11307	0.000025	1.19878	0.00756	1.20942
	$b = 1.5$	0.11452	1.42561	0.000203	1.50205	0.00846	1.50871
	$a = 0.4$	0.02820	0.45983	0.000068	0.39882	0.00061	0.41046
100	$\phi = 1.0$	0.01752	0.98113	0.000149	1.00032	0.00344	1.00215
	$c = 1.2$	0.10692	1.07976	0.000116	1.19808	0.02024	1.20220
	$b = 1.5$	0.33369	1.42923	0.000702	1.50009	0.02270	1.50538
	$a = 0.2$	0.58235	0.29580	0.000062	0.20012	0.00045	0.20678
200	$\phi = 1.0$	0.01549	0.99755	0.000061	1.00027	0.00144	1.00414
	$c = 1.2$	0.07721	1.11020	0.000043	1.19886	0.00977	1.21151
	$b = 1.5$	0.31670	1.48354	0.000296	1.50018	0.00981	1.51313
	$a = 0.2$	0.05843	0.25663	0.000026	0.19992	0.00018	0.20463
300	$\phi = 1.0$	0.00723	0.99707	0.000058	1.00007	0.00095	1.00175
	$c = 1.2$	0.04531	1.13246	0.000044	1.19929	0.00737	1.20519
	$b = 1.5$	0.19654	1.46842	0.000274	1.49991	0.00625	1.50616
	$a = 0.2$	0.00716	0.22467	0.000026	0.20008	0.00014	0.20478
100	$\phi = 1.0$	0.02080	0.94871	0.000132	1.00032	0.00378	1.00260
	$c = 1.2$	0.09971	1.02132	0.000186	1.19857	0.02372	1.22277
	$b = 1.8$	0.46374	1.57681	0.000896	1.80027	0.03382	1.80983
	$a = 0.2$	0.32599	0.20543	0.000071	0.20021	0.00083	0.21135
200	$\phi = 1.0$	0.01101	0.97917	0.000053	0.99984	0.00162	1.00139
	$c = 1.2$	0.04883	1.11342	0.000077	1.19948	0.01095	1.21745
	$b = 1.8$	0.23897	1.70458	0.000365	1.79920	0.01556	1.81480
	$a = 0.2$	0.04207	0.25224	0.000029	0.20025	0.00033	0.20855
300	$\phi = 1.0$	0.00716	0.98468	0.000045	0.99965	0.00128	1.00125
	$c = 1.2$	0.04786	1.08239	0.000064	1.19978	0.00796	1.20972
	$b = 1.8$	0.19775	1.67096	0.000303	1.79874	0.01161	1.80970
	$a = 0.2$	0.01421	0.24958	0.000024	0.20034	0.00024	0.20811

the last one are calculated for the fitted distributions using the R software.

The first data set refers to 63 observations of the strengths of 1.5 cm glass fibres (see, Smith and Naylor, 1987) analyzed by Alizadeh *et al.* (2020). The second data set represents 74 observations of the gauge lengths of 20 mm (see, Kundu and Raqab, 2009) analyzed by Afify and Mohamed (2020). The third data set consists of 100 observations of breaking stress of carbon fibres (in Gba) (see, Nichols and Padgett, 2006) analyzed by Cordeiro *et al.* (2017).

Tables 7-9 report the values of the goodness-of-fit measures, the MLEs and associated standard errors (SEs) (in parentheses) for the MOOB-Ex model and other fitted distributions. Some of the fitted distributions in Tables 7-9 have very large SEs compared with their MLEs, whereas all MLEs for the fitted MOOB-Ex distribution are accurate.

Figures 4, 6 and 8 display some plots of the fitted densities for these sets. Further, the corresponding PP plots for the fitted distributions are given in Figures 5, 7 and 9. These plots



TABLE 6. Some Competitive Models for the MOOB-Ex Distribution.

Distribution	Author(s)
Exponential (Ex)	
Marshall-Olkin Nadarajah-Haghighi (MONH)	Lemonte et al. (2016)
Odd exponentiated half-logistic Ex (OEHLEx)	Afify et al. (2018)
Beta generalized Ex (BGEx)	Barreto-Souza et al. (2010)
Kumaraswamy transmuted Ex (KTEEx)	Afify et al. (2016)
Kumaraswamy Ex (KEx)	-
Marshall-Olkin Ex (MOEx)	Marshall and Olkin (1997)
Beta Ex (BEx)	Nadarajah and Kotz (2006)

TABLE 7. Goodness-of-Fit Measures, MLEs and (SEs) for Data Set I.

Model	CVM	AD	KS	KS <i>p</i> -value	MLEs		
MOOB-Ex ( $\phi, c, b, a$ )	0.0407	0.2512	0.0758	0.8612	4.1455 (3.8866)	12.9915 (2.7502)	0.1652 (0.0834)
MONH ( $\phi, \lambda, \theta$ )	0.1015	0.5750	0.0955	0.6132	8.5199 (17.310)	0.1516 (0.3563)	162.103 (173.39)
OEHLEx ( $\phi, \lambda, a$ )	0.1356	0.7698	0.1227	0.2982	1.5776 (0.5047)	0.0345 (0.0334)	2.4614 (0.4798)
BGEx ( $a, b, \lambda, \phi$ )	0.2021	1.1211	0.1469	0.1314	0.5583 (0.2513)	224589.2 (72373.3)	0.1810 (0.0955)
KTEEx ( $a, b, \lambda, \phi$ )	0.2496	1.3697	0.1574	0.0879	4.8796 (2.0384)	2145.5 (4196.05)	0.2910 (0.1283)
KEx ( $a, b, \lambda$ )	0.2687	1.4724	0.1614	0.0749	6.8785 (1.1075)	2553.2 (5216.1)	0.2373 (0.1228)
MOEx ( $\phi, \lambda$ )	0.2596	1.4304	0.1254	0.2750	8247.4 (7982.2)	5.8503 (0.6033)	
BEx ( $a, b, \lambda$ )	0.5686	3.1184	0.2163	0.0054	17.4699 (3.0852)	154.884 (242.09)	0.0711 (0.1054)
Ex ( $a$ )	0.5702	3.1270	0.4179	0.0000	0.6636 (0.0836)		

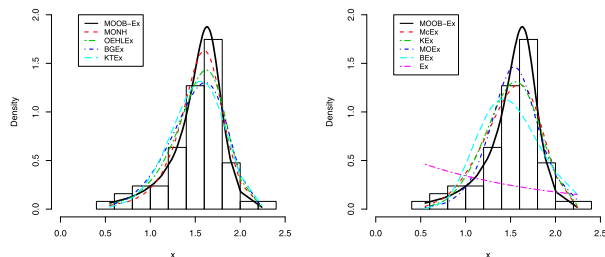


FIGURE 4. The fitted MOOB-Ex density and other densities for data set I.

TABLE 8. Goodness-of-Fit Measures, MLEs and (SEs) for Data Set II.

Model	CVM	AD	KS	KS <i>p</i> -value	MLEs		
MOOB-Ex ( $\phi, c, b, a$ )	0.0233	0.1738	0.0496	0.9932	0.3270 (0.4850)	11.5848 (4.5771)	0.4421 (0.1682)
MONH ( $\phi, \eta, \theta$ )	0.0336	0.2310	0.0569	0.9698	2.1710 (1.4589)	0.5784 (0.6743)	389.87 (540.85)
OEHLEx ( $\phi, \eta, a$ )	0.0264	0.1995	0.0545	0.9802	3.8721 (1.9472)	0.3004 (0.2850)	0.8837 (0.2609)
BGEx ( $a, b, \eta, \phi$ )	0.0267	0.2132	0.0576	0.9663	0.5689 (0.9764)	29.513 (87.479)	0.6648 (0.9665)
KTEEx ( $a, b, \eta, \phi$ )	0.0267	0.2097	0.0575	0.9673	8.8699 (16.810)	112.545 (627.38)	-0.1036 (0.9223)
KEx ( $a, b, \eta$ )	0.0267	0.2104	0.0574	0.9674	9.1401 (4.7605)	127.95 (457.29)	0.3340 (0.3569)
MOEx ( $\phi, \eta$ )	0.0443	0.2723	0.0598	0.9537	8104.8 (7212.5)	3.6184 (0.3468)	
BEx ( $a, b, \eta$ )	0.0874	0.5737	0.0682	0.8809	24.317 (3.9884)	92.491 (154.90)	0.0947 (0.1426)
Ex ( $a$ )	0.0875	0.5749	0.4495	0.0000	0.4037 (0.0469)		

also reveal that the MOOB-Ex distribution yields the best fit to all data sets.

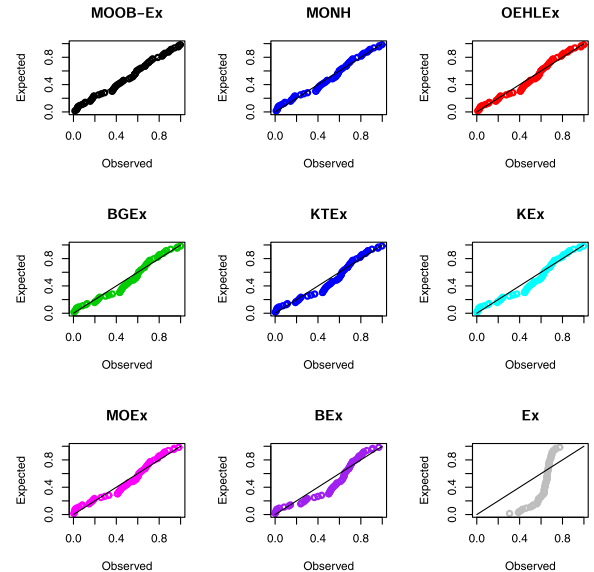


FIGURE 5. PP plots of the MOOB-Ex distribution and other models for data set I.

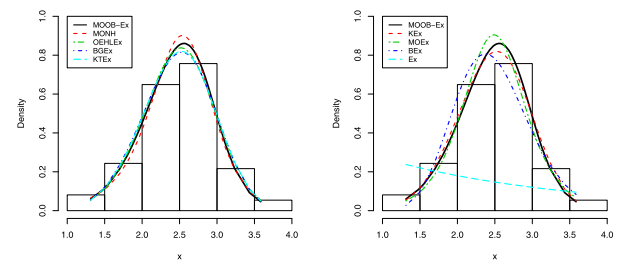


FIGURE 6. The fitted MOOB-Ex density and other densities for data set II.

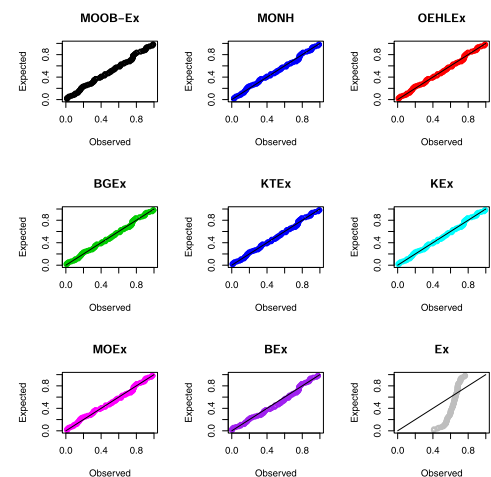


FIGURE 7. PP plots of the MOOB-Ex distribution and other models for data set II.

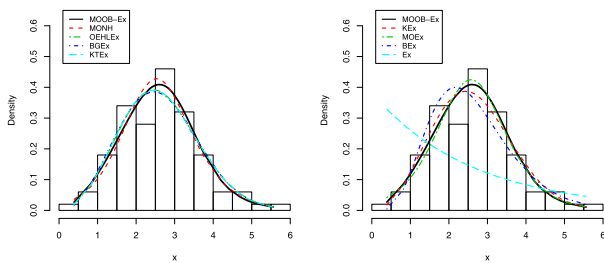
The hrf plots of the MOOB-Ex model and the TTT plots for the three data sets are, respectively, displayed in Figures 8-10. The TTT plots are concave indicating that the three data sets have increasing hazard rates as shown from the hrf plots of the three data sets.

**TABLE 9.** Goodness-of-Fit Measures, MLEs and (SEs) for Data Set III.

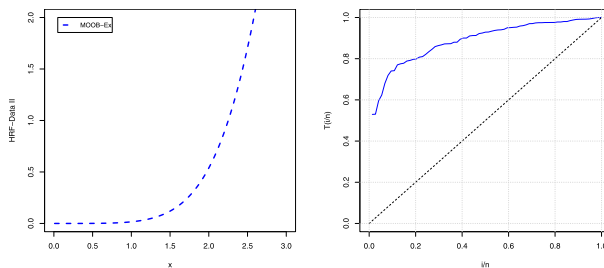
Model	CVM	AD	KS	KS <i>p</i> -value	MLEs			
MOOB-Ex ( $\phi, c, b, a$ )	0.0515	0.3223	0.0575	0.8945	0.5399 (0.6185)	5.2672 (1.5128)	0.4555 (0.1408)	0.1955 (0.0390)
MONH ( $\phi, \eta, \theta$ )	0.0730	0.4305	0.0639	0.8084	0.8254 (0.4280)	3.0008 (5.2241)	145.189 (300.701)	
OEHLEx ( $\phi, \lambda, a$ )	0.0682	0.4011	0.0639	0.8087	2.7130 (0.7321)	2.1000 (1.4127)	0.2669 (0.1041)	
BGEx ( $a, b, \lambda, \phi$ )	0.0678	0.4007	0.0641	0.8064	0.5169 (0.8818)	10.7682 (27.8992)	0.3452 (0.5755)	7.1016 (14.7598)
KTEEx ( $a, b, \eta, \phi$ )	0.0685	0.4007	0.0645	0.7995	2.6891 (3.2607)	19.4945 (38.5474)	-0.6237 (1.7109)	0.2270 (0.1943)
KEEx ( $a, b, \eta$ )	0.0699	0.4091	0.0646	0.7967	3.2780 (0.8372)	63.2256 (217.67)	0.1134 (0.1823)	
MOEx ( $\phi, \eta$ )	0.0631	0.4102	0.0592	0.8746	75.6861 (33.4913)	1.6757 (0.1534)		
BEx ( $a, b, \eta$ )	0.1483	0.7589	0.0935	0.3461	5.9605 (0.8218)	34.5462 (61.1416)	0.0615 (0.1021)	
Ex ( <i>a</i> )	0.1493	0.7643	0.3206	0.0000	0.3815 (0.0381)			

**TABLE 10.** The Estimates of the MOOB-Ex Parameters for the Three Data Sets.

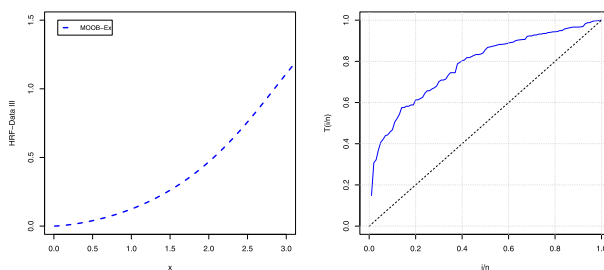
Method	$\hat{\phi}$	$\hat{c}$	$\hat{b}$	$\hat{a}$	$-\hat{\ell}$	CVM	AD	KS	KS <i>p</i> -value
Strengths of 1.5 cm glass fibres data									
MLE	4.1455	12.992	0.1652	0.4177	10.295	0.0407	0.2512	0.0758	0.8612
LSE	28.816	13.791	0.0322	0.4252	11.817	0.0352	0.2803	0.0607	0.9744
PCE	4.3044	11.583	0.1577	0.4149	10.873	0.05024	0.3003	0.0928	0.6497
Gauge lengths of 20 mm data									
MLE	0.3270	11.5848	0.4421	0.2269	51.165	0.0233	0.1738	0.0496	0.9932
LSE	0.3809	12.7094	0.3674	0.2258	51.327	0.0231	0.1867	0.0546	0.9800
PCE	0.7130	9.1599	0.4843	0.2433	51.458	0.02759	0.1883	0.0533	0.9847
Breaking stress of carbon fibres data									
MLE	0.5399	5.2672	0.4555	0.1955	141.096	0.0515	0.3223	0.0575	0.8945
LSE	0.8400	6.8485	0.2748	0.19407	142.517	0.0557	0.4884	0.0413	0.9956
PCE	0.9149	4.3532	0.4955	0.2176	141.385	0.0605	0.3518	0.0605	0.8572



**FIGURE 8.** The fitted MOOB-Ex density and other densities for data set III.

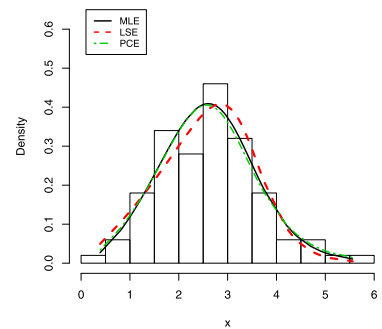
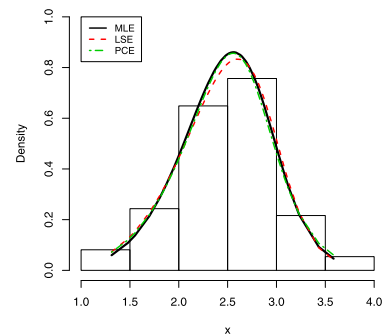
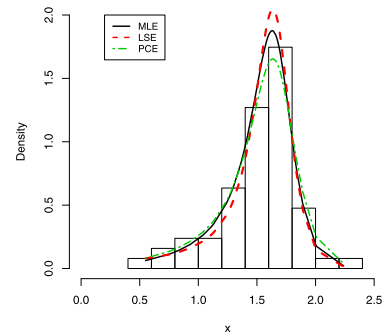


**FIGURE 9.** The hrf plot of the MOOB-Ex model and TTT plot for data set II.



**FIGURE 10.** The hrf plot of the MOOB-Ex model and TTT plot for data set III.

Further, we adopt the three estimation methods discussed in Section 5 to estimate the MOOB-Ex parameters from the three data sets. Table 10 provides the estimates of the MOOB-Ex parameters for these data sets, and the maximized log-likelihoods values ( $-\hat{\ell}$ ) and the CVM, AD and KS statistics and *p*-values. Based on the KS and *p*-values in



**FIGURE 11.** The fitted MOOB-Ex density for data set I (left), for data II (middle) and for data III (right).

Table 10, we note that the LSE provides the best estimates of the MOOB-Ex parameters for the first and third data sets, whereas the ML method is recommended to estimate the MOOB-Ex parameters for the second data set. However, all estimation methods perform very well for the three data sets.

The histograms of the three data sets and the fitted MOOB-Ex densities using the three estimation methods, for the three data sets, are displayed in Figure 11.

## VIII. CONCLUSION

We propose a new class of distributions with three additional shape parameters, called Marshall-Olkin odd Burr III-G (MOOB-G) family, from any baseline continuous distribution  $G$ . The new MOOB-G family extends the Marshall-Olkin-G and odd Burr III-G classes and distributions and three of its special models, called MOOB-exponential, MOOB-Lindley, and MOOB-Lomax distributions are discussed. The family density can be expressed as linear combination of exponentiated-G densities. We explore some mathematical properties of the MOOB-G family. The parameters of the proposed family are estimated by three approaches, called maximum likelihood, least squares and percentile methods. The performance of the three methods are assessed via simulation results obtained for the MOOB-exponential and MOOB-Lindley distributions. Three real data examples show empirically that the MOOB-exponential distribution provides better fits to these data than other known extensions of the exponential model.

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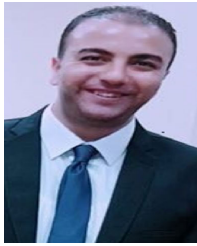
Program in statistics. He has published more than 440 research articles in international scientific journals with referee practice, in 2020, and supervised more than 65 M.Sc. dissertations and D.Sc. theses.



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