

Received September 10, 2020, accepted October 5, 2020, date of publication October 8, 2020, date of current version October 28, 2020.

Digital Object Identifier 10.1109/ACCESS.2020.3029656

A Differential Game-Based Approach for School-Enterprise Collaborative R&D Strategy on Digital Twin Technology

HONGFEI GUO^{1,2}, LINSHENG ZHANG³, YU ZHANG⁴, YAPING REN^{1,2},
XIN LIAN², RUI ZHANG⁵, AND NA DING⁶

¹Institute of Physical Internet, Jinan University at Zhuhai Campus, Zhuhai 509070, China

²School of Intelligent Systems Science and Engineering, Jinan University at Zhuhai Campus, Zhuhai 509070, China

³School of Management, Jinan University, Guangzhou 510632, China

⁴Guangzhou Create View Education Technology Company Ltd., Guangzhou 510000, China

⁵College of Electronic Information and Automation, Tianjin University of Science and Technology, Tianjin 300222, China

⁶School of Information Technology in Education, South China Normal University, Guangzhou 510631, China

Corresponding authors: Yaping Ren (renyp@163.com) and Rui Zhang (zhangrui@tust.edu.cn)

This work was supported in part by the Science and Technology Plan Project in Guangzhou under Grant 202002030321, in part by the Science and Technology Plan Project in Inner Mongolia Autonomous Region under Grant 2019GG238, in part by the Guangdong Academic Degree and Graduate Education Reform Research Project under Grant 2019JGXM15, in part by the Guangdong Graduate Education Innovation Project under Grant 82620516, in part by the Guangzhou Leading Innovation Team Program under Grant 201909010006, in part by the Panyun Leading Innovation Team Program under Grant 2018-R01-4, and in part by the Basic and Applied Basic Research Foundation of Guangdong Province of China under Grant 2019A1515110399.

ABSTRACT Digital twin (DT) technology is an effective way to realize intelligent manufacturing, which has been increasingly received attention in both academia and industry. Thus, it is rather necessary and significant to collaboratively accomplish the research and development (R&D) of DT technology (RDDT). To explore a school-enterprise collaborative R&D strategy on DT technology, this paper proposes a differential game-based approach to compute the optimal R&D effort levels and optimal incomes of both parties in the school-enterprise collaborative innovation (SECI) system. First, using Berman's continuous dynamic programming theory, the optimal R&D effort levels, the optimal incomes of both parties, and total optimal income in the SECI system are calculated in three cases: Nash non-cooperative game, Stackelberg master-slave game and cooperative game. Second, the equilibria of the three game cases are analyzed and compared. Finally, a numerical example is used to verify the validity of the conclusion, and we find that the optimal benefit of two parties in cooperative game are significantly better than those of Nash non-cooperative game and Stackelberg master-slave game, which effectively demonstrates the superiority of school-enterprise collaborative R&D on DT technology.

INDEX TERMS School-enterprise collaborative, collaborative research and development strategy, digital twin technology, game theory, differential game.

I. INTRODUCTION

With the introduction of some advanced manufacturing development strategies, representative such as "American Industrial Internet," "German Industry 4.0," "Made in China 2025," the goal of these advanced manufacturing strategies is to achieve the interconnection and intelligent operation of the physical and information worlds [1]–[4]. Intelligent manufacturing, as the development trend of manufacturing industry in future, has received extensive attention [5], [6].

The associate editor coordinating the review of this manuscript and approving it for publication was Xiwang Dong.

Furthermore, digital twin (DT) technology has been widely studied in academia in recent year since it is an effective way for manufacturing enterprises to realize intelligent manufacturing [7], [8]. Manufacturing industry itself is facing the rapid development of technology and tools. However, manufacturing teaching and training have not kept up with the advancement of manufacturing technology, nor have they kept up with the demands of the labour market [9]. Therefore, collaboration between universities and industries is necessary and essential. As an organizational form of collaborative innovation, school-enterprise collaborative R&D (Also known as learning factories) can make up for some

shortcoming of universities and industries [10], and the purpose of which is to align manufacturing training and teaching to the needs of modern industrial practice [11]. Cooperation between universities and enterprises can improve the innovation performance of enterprises and solve the problem of insufficient R&D foundation in universities. Therefore, it is of great significance to coordinate the use of scientific and technological resources and discuss in depth the R&D strategy of DT technology based on school-enterprise collaboration.

Nowadays, collaborative innovation between universities and enterprises has become an increasingly common form of basic research and applied research, which has attracted widespread attention from scholars. For example, Van and Luong [12] proposed the model of skilled worker training basing on the analysis of school-enterprise collaboration factors in training process and labors characteristics in Mekong Delta. Yang [13] evaluated and analyzes the collaborative innovation ability of school-enterprise cooperation through the construction of key evaluation index system and model of the application. Xiao-Mei [14] studied a management mechanism of training base in campus under school-enterprise cooperation to find the insufficient of the mechanism and improve it. Huang *et al.* [15] explored a mode of school-enterprise cooperation in training application-oriented talents, introducing some achievements of the school and pointed out some problems in school-enterprise cooperation. Ralph *et al.* [16] proposed a method about the implementation and operation of an academic learning factory, specifically tailored to the requirements of the metal forming industry. Brenner and Hummel [17] introduce the prototypes of DT in the ESB Logistics Learning Factory while they point out the economic function of DT technology.

In the school-enterprise collaborative innovation (SECI) system, universities and enterprises collaborate based on heterogeneous resources. Universities hope to obtain more scientific research funds and promote the transformation of scientific research results of DT technology through cooperation with manufacturing enterprises [18]. Manufacturing enterprises hope to spread innovation risks and make up for the weakness of their own technology R&D through cooperation with universities to achieve the purpose of intelligent manufacturing [19]. This heterogeneity causes conflicts between the motivations and behavioral objectives of cooperation in SECI system [20], [21].

Due to the long-term and dynamic characteristics of research and development of DT technology (RDDT), the collaborative R&D strategy requires to be self-adjusted between universities and enterprises. The R&D rate and frequency of DT technology increase with the development of scientific and technological information, which means that RDDT in the same space-time area should be considered based on the dynamic behavior of decision-making subjects. Differential game is an important dynamic model to deal with the conflict of competition and cooperation between two parties in a continuous time. Some scholars have introduced it to the research in the related fields of school-enterprise

collaboration. For example, Yu and Shi [22] used the theory of differential game to study the knowledge sharing strategies of universities and enterprises under the collaborative innovation of industry, university and research. Yin and Li [23] presents a stochastic differential game of green building technologies transfer from academic research institutes to building enterprises in the building enterprises-academic research institutes collaborative innovation system. Ma *et al.* [24] aimed at the industry-university-collaborative R&D problem, and used a single research institution and a single enterprise as research objects to construct a differential game model, and analyzed the equilibria results of the three game models.

Form the analysis of above studies, it is a mainstream trend that many scholars use game theory to study school-enterprise collaboration. However, as a new method for manufacturing enterprises to realize intelligent manufacturing, DT technology is still in the initial stage of R&D, and the current research of DT mainly stays in the conceptual research or application of manufacturing enterprises or a certain production field [25]–[28], lacking the endogenous impetus to promote DT technology in the transformation of intelligent manufacturing. Therefore, this paper attempts to use the differential game method to study RDDT of universities and manufacturing enterprises in the SECI system under the dynamic framework. First, using Berman's continuous dynamic programming theory, the optimal R&D effort level, the optimal incomes of both parties, and total optimal income in the SECI system are calculated in three cases: Nash non-cooperative game, Stackelberg master-slave game and cooperative game. Second, the equilibria of the three game cases are analyzed and compared. Finally, a numerical example is used to verify the validity of the conclusion. Hope to provide some suggestions for universities and enterprises on the R&D of DT. Compared with the existing literature, the main contributions of this work are as follows:

- (1) To promote the development of manufacturing and the R&D of DT technology, a school-enterprise collaboration model is built, in which universities are responsible for basic research, and the enterprises are responsible for applied research. The effects of both parties on RDDT were discussed based on the model.
- (2) The R&D subsidies provided by manufacturing enterprises to universities was proposed to coordinate RDDT between universities and enterprises, making universities more willing to research and development DT.
- (3) Through the comparison of the three games, the experimental results show that under the cooperative game situation, universities and enterprises achieve individual Pareto optimality and the effectiveness of our model is proved.

The structure of this paper is organized as follows. In next section, differential game formulations and the analysis of equilibria of the three game cases are provided. Comparative analysis of equilibria results is presented in section III.

TABLE 1. The main notations used in our model.

Notations	Descriptions;
R	Universities
M	Manufacturing enterprises
C_U	R&D effort cost of universities;
C_M	R&D effort cost of manufacturing enterprises;
k_U	R&D effort cost coefficient of universities;
k_M	R&D effort cost coefficient of manufacturing enterprises;
E_U	R&D effort level of universities;
E_M	R&D effort level of manufacturing enterprises;
t	Time;
K	level of RDDT;
α	Impact of the R&D effort level of universities on the total technology level;
β	impact of the R&D effort level of manufacturing enterprises on the total technology level;
δ	Degree of decline in the overall technology level;
π	Total income in the SECI system;
μ_1	Impact of the R&D effort level of universities on the total income;
μ_2	Impact of the R&D effort level of manufacturing enterprises on the total income;
ν	Impact of the DT technology level in the SECI system on the total income;
τ	Income distribution coefficient of universities;
θ	R&D subsidies provided by manufacturing enterprises to universities;
ρ	Discount rates;
J_U	Objective functions of universities;
J_M	Objective functions of manufacturing enterprises;
V_U	Optimal R&D income of universities;
V_M	Optimal R&D income of manufacturing enterprises.

In section IV, we simulate the games and give an analysis of the result. Finally, section V summarizes the paper.

II. MODEL FORMULATIONS AND ANALYSIS

For ease of description, the main body of school-enterprise collaborative R&D strategy can be divided into two main parts: universities and manufacturing enterprises. Universities are mainly responsible for the basic research of DT technology, and manufacturing enterprises are mainly responsible for the application and development work of DT technology. In this paper, the two subjects can be expressed as a university and a manufacturing enterprise in the SECI system. The main notations used in our model are represented as Table 1, and Figure 1 depicts the decision process

A. MODEL FORMULATIONS

Assumption 1: The R&D effort cost of the technology is related to the level of R&D effort. The R&D effort cost of universities and manufacturing enterprises sides at time t

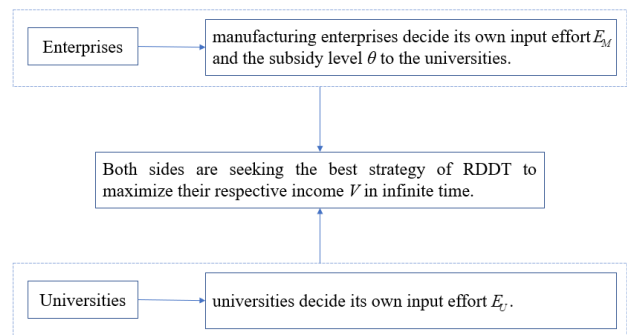


FIGURE 1. Game decision diagram of enterprises and universities.

are defined as $C_U(t)$ and $C_M(t)$, respectively. Furthermore, the R& D effort cost coefficient of both parties are defined as k_U, k_M , respectively. $E_U(t), E_M(t) \geq 0$, represent the level of R&D efforts of both parties at time t , respectively. Considering the convexity of the R&D effort cost [29], the R&D effort

cost of both parties at time t can be

$$C_U(t) = \frac{1}{2}k_U E_U^2(t), \quad C_M(t) = \frac{1}{2}k_M E_M^2(t) \quad (1)$$

Assumption 2: Let $K(t)$ denote the level of RDDT at time t , which affected by the R&D efforts of both parties and the update of DT technology level. Due to RDDT is a dynamic change process, the dynamic equation of the Nerlove-Arrow goodwill model is employed in this problem, and the dynamics level of RDDT can be expressed as

$$\dot{K}(t) = \alpha E_U(t) + \beta E_M(t) - \delta K(t), \quad K(0) = K_0 \quad (2)$$

where K_0 is the initial state in the SECI system; $\alpha, \beta > 0$, indicate the impact of the respective R&D efforts level of universities and manufacturing enterprises on the total technology level, which is effort coefficient. Furthermore, the technology level will decline if it has not been developed. $\delta > 0$ represents the degree of decline in the overall technology level, which is technical attenuation coefficient.

Assumption 3: Let $\pi(t)$ denote the total income in the SECI system at the time t . Therefore, the total income function can be as

$$\pi(t) = \mu_1 E_U(t) + \mu_2 E_M(t) + \nu K(t) \quad (3)$$

where μ_1, μ_2 represent the impact of the respective R&D efforts level of universities and manufacturing enterprises on the total income in the SECI system, which is marginal income coefficient. ν indicates the impact of the DT technology level in the SECI system on the total income, which is the R&D impact coefficient of technology.

Assumption 4: We further assume that the total income in the SECI system is only allocated between the two participants. The income distribution coefficient of universities is τ , and the income distribution coefficient of manufacturing enterprise is $1-\tau$. τ is a constant between $(0,1)$, which is determined in advance by both parties. In order to stimulate the R&D enthusiasm of universities, manufacturing enterprises will provide a certain percentage of R&D investment subsidy $\theta(t)$ to universities, $0 \leq \theta(t) \leq 1$, and we assume that the discount rate ρ on both sides are the same and positive numbers. Both sides are seeking the best strategy of RDDT to maximize their respective income in infinite time.

The objective functions of universities and manufacturing enterprises can be expressed by using the following partial differential equations:

$$J_U = \int_0^\infty e^{-\rho t} [\tau (\mu_1 E_U(t) + \mu_2 E_M(t) + \nu K(t)) - \frac{1}{2}k_U (1 - \theta(t)) E_U^2(t)] dt \quad (4)$$

$$J_M = \int_0^\infty e^{-\rho t} [(1 - \tau) (\mu_1 E_U(t) + \mu_2 E_M(t) + \nu K(t)) - \frac{1}{2}k_M E_M^2(t) - \frac{1}{2}\theta(t)k_U E_U^2(t)] dt \quad (5)$$

There are three control variables, $E_U(t)$, $E_M(t)$ and $\theta(t)$, and a state variable $K(t)$ in the SECI model. Due to the presence of dynamic parameters, the solution will become very difficult. In this paper, to simplify the model, we assume that the parameters in the model are constants and independent of time [29]. In addition, in order to facilitate writing, the time unit t will be omitted in the following text.

B. RESOVING MODEL OF NASH NON-COOPERATIVE GAME

In the process of Nash non-cooperative game, universities and manufacturing enterprises will simultaneously and independently select their optimal effort level of RDDT to maximize their profits. In this case, manufacturing enterprises does not provide R&D investment subsidy to universities, that is $\theta = 0$. In this case, the objective functions of universities and manufacturing enterprises are:

$$J_R = \int_0^\infty e^{-\rho t} \left[\tau (\mu_1 E_U + \mu_2 E_M + \nu K) - \frac{1}{2}k_U E_U^2 \right] dt \quad (6)$$

$$J_M = \int_0^\infty e^{-\rho t} [(1 - \tau) (\mu_1 E_U + \mu_2 E_M + \nu K) - \frac{1}{2}k_M E_M^2] dt \quad (7)$$

In order to get the Nash equilibria state in this situation, it should first be assumed that both universities and manufacturing enterprises have optimal R&D income, which are continuously and marginally differentiable. For all $K \geq 0$, the Hamilton-Jacobi-Bellman (abbreviated as HJB) equation must be satisfied

$$\rho V_U^N = \max_{E_U} \left\{ \tau (\mu_1 E_U + \mu_2 E_M + \nu K) - \frac{1}{2}k_U E_U^2 + V_U^{\prime N} (\alpha E_U + \beta E_M - \delta K) \right\} \quad (8)$$

$$\rho V_M^N = \max_{E_M} \left\{ (1 - \tau) (\mu_1 E_U + \mu_2 E_M + \nu K) - \frac{1}{2}k_M E_M^2 + V_M^{\prime N} (\alpha E_U + \beta E_M - \delta K) \right\} \quad (9)$$

Proposition 1: the optimal R&D incomes of universities and manufacturing enterprises in Nash non-cooperative game situation are respective as follows:

$$V_U^{N*} = \frac{\tau \nu}{\rho + \delta} K + \frac{[(\rho + \delta)\mu_1 \tau + \tau \nu \alpha]^2}{2k_U \rho (\rho + \delta)^2} + \frac{\tau(1 - \tau)[\mu_2(\rho + \delta) + \beta \nu]^2}{k_M \rho (\rho + \delta)^2} \quad (10)$$

$$V_M^{N*} = \frac{(1 - \tau)\nu}{\rho + \delta} K + \frac{\tau(1 - \tau)[\mu_1(\rho + \delta) + \alpha \nu]^2}{k_U \rho (\rho + \delta)^2} + \frac{(1 - \tau)^2[\mu_2(\rho + \delta) + \beta \nu]^2}{2k_M \rho (\rho + \delta)^2} \quad (11)$$

Proof: See the Appendix.

Hence, the optimal total income in the SECI system can be expressed as follows:

$$\begin{aligned}
 V^{N*} &= V_U^{N*} + V_M^{N*} \\
 &= \frac{vK}{\rho + \delta} + \frac{\tau(2 - \tau)[(\rho + \delta)\mu_1\tau + \tau v\alpha]^2}{2k_U\rho(\rho + \delta)^2} \\
 &\quad + \frac{(1 - \tau^2)[\mu_2(\rho + \delta) + \beta v]^2}{2k_M\rho(\rho + \delta)^2} \quad (12)
 \end{aligned}$$

C. RESOLVING MODEL OF STACKELBERG MASTER-SLAVE GAME

In the case of Stackelberg master-slave game, manufacturing enterprises play a leading role in the SECI system. In order to promote RDDT, manufacturing enterprises (the leader) determine an optimal R&D effort level E_M and an optimal subsidy θ , and then universities (the followers) choose their optimal R&D effort level E_U according to the optimal R&D effort level and subsidy of manufacturing enterprises. The income functions of both participants are $V_R(K)$ and $V_M(K)$, respectively, which are continuously and marginally differentiable. Furthermore, for all $K \geq 0$, $V_R^D(K)$ and $V_M^D(K)$ must satisfy the HJB equation. According to the reverse induction method, the optimal control problem of universities is:

$$\begin{aligned}
 \rho V_U^D &= \max_{E_U} [\tau(\mu_1 E_U + \mu_2 E_M + vK) - \frac{1}{2}k_U(1 - \theta)E_U^2 \\
 &\quad + V_U^D(\alpha E_U + \beta E_M - \delta K)] \quad (13)
 \end{aligned}$$

The optimal R&D effort level of DT technology can be computed by setting the first partial derivative equal to zero, and the optimal effort level of universities can be

$$E_U = \frac{\mu_1\tau + \alpha V_U^D}{k_U(1 - \theta)} \quad (14)$$

Manufacturing enterprises will rationally predict that universities will determine its optimal R&D effort level E_M according to formula (14). Therefore, manufacturing enterprises will determine its own optimal R&D effort level E_M and R&D investment subsidy θ based on the rational response of universities to maximize its own benefits. In this situation, the optimal control problem of manufacturing enterprises is

$$\begin{aligned}
 \rho V_M^D &= \max_{E_M, \theta} [(1 - \tau)(\mu_1 E_U + \mu_2 E_M + vK) \\
 &\quad - \frac{1}{2}k_M E_M^2 - \frac{1}{2}\theta k_U E_U^2 \\
 &\quad + \frac{\partial V_M^D}{\partial K}(\alpha E_U + \beta E_M - \delta K)] \quad (15)
 \end{aligned}$$

Proposition 2: the optimal R&D incomes of universities and manufacturing enterprises in Stackelberg master-slave game situation are respective as follows:

$$\begin{aligned}
 V_U^{D*} &= \frac{\tau v}{\rho + \delta} K + \frac{\tau(2 - \tau)[(\rho + \delta)\mu_1 + \alpha v]^2}{4k_U\rho(\rho + \delta)^2} \\
 &\quad + \frac{\tau(1 - \tau)[\mu_2(\rho + \delta) + \beta v]^2}{k_M\rho(\rho + \delta)^2} \quad (16)
 \end{aligned}$$

$$\begin{aligned}
 V_M^{D*} &= \frac{(1 - \tau)v}{\rho + \delta} K + \frac{(2 - \tau)^2[\mu_1(\rho + \delta) + \alpha v]^2}{8k_U\rho(\rho + \delta)^2} \\
 &\quad + \frac{(1 - \tau)^2[\mu_2(\rho + \delta) + \beta v]^2}{2k_M\rho(\rho + \delta)^2} \quad (17)
 \end{aligned}$$

Proof: See the Appendix.

Hence, the optimal total income of RDDT in the SECI system can be expressed as follows:

$$\begin{aligned}
 V^{D*} &= V_U^{D*} + V_M^{D*} = \frac{vK}{\rho + \delta} + \frac{(4 - \tau^2)[(\rho + \delta)\mu_1 + v\alpha]^2}{8k_U\rho(\rho + \delta)^2} \\
 &\quad + \frac{(1 - \tau^2)[\mu_2(\rho + \delta) + \beta v]^2}{2k_M\rho(\rho + \delta)^2} \quad (18)
 \end{aligned}$$

D. RESOLVING MODEL OF COOPERATIVE GAME

In the process of cooperative game, universities and manufacturing enterprises will select their optimal effort level and income functions of RDDT to maximize their total income. Then, DT technology can be further improved through cooperation innovation between universities and manufacturing enterprises. In this case, the R&D subsidy that manufacturing enterprises need to provide to universities is an internal fund transfer. As an internal problem of the SCEI system, the R&D cost subsidy θ can take any value in $[0, 1]$. We have

$$\begin{aligned}
 J &= J_U + J_M = \int_0^\infty e^{-\rho t} \left[(\mu_1 E_U + \mu_2 E_M + vK) \right. \\
 &\quad \left. - \frac{1}{2}k_U E_U^2 - \frac{1}{2}k_M E_M^2 \right] dt \quad (19)
 \end{aligned}$$

In order to obtain the cooperative equilibria state in this situation, it should first be assumed that there is an optimal R&D total income $V^C(K)$ in the SCEI system, which are continuously and marginally differentiable. For all $K \geq 0$, the HJB equation must be satisfied. We have

$$\begin{aligned}
 \rho V^C &= \max_{E_U, E_M} \left[(\mu_1 E_U + \mu_2 E_M + vK) \right. \\
 &\quad \left. - \frac{1}{2}k_U E_U^2 - \frac{1}{2}k_M E_M^2 + V^C(\alpha E_U + \beta E_M - \delta K) \right] \quad (20)
 \end{aligned}$$

Proposition 3: The optimal R&D incomes of universities and manufacturing enterprises in cooperative game situation is respective as follows:

$$\begin{aligned}
 V^{C*} &= \frac{v}{\rho + \delta} K + \frac{[(\rho + \delta)\mu_1 + v\alpha]^2}{2k_U\rho(\rho + \delta)^2} \\
 &\quad + \frac{[\mu_2(\rho + \delta) + \beta v]^2}{2k_M\rho(\rho + \delta)^2} \quad (21)
 \end{aligned}$$

Proof: See the Appendix.

Under this circumstance, universities and manufacturing enterprises distribute the total income in the SECI system in proportions of τ and $1 - \tau$, respectively. We have

$$\begin{aligned}
 V_U^{C*} &= \frac{\tau v}{\rho + \delta} K + \frac{\tau[(\rho + \delta)\mu_1 + v\alpha]^2}{2k_U\rho(\rho + \delta)^2} \\
 &\quad + \frac{\tau[\mu_2(\rho + \delta) + \beta v]^2}{2k_M\rho(\rho + \delta)^2} \quad (22)
 \end{aligned}$$

$$V_M^{C*} = \frac{(1-\tau)v}{\rho+\delta}K + \frac{(1-\tau)[(\rho+\delta)\mu_1 + v\alpha]^2}{2k_U\rho(\rho+\delta)^2} + \frac{(1-\tau)[\mu_2(\rho+\delta) + \beta v]^2}{2k_M\rho(\rho+\delta)^2} \quad (23)$$

III. COMPARATIVE ANALYSIS OF EQUILIBRIA

In the three game cases, the optimal R&D effort level, optimal R&D incomes of both parties and the optimal total R&D income in the SECI system were compared, and some relevant conclusions were obtained.

Corollary 1: In the case of Stackelberg master-slave game, compared with the Nash non-cooperative game situation, the R&D effort level of universities are significantly improved, and the degree of improvement is equal to the R&D investment subsidy coefficient θ , which shows that R&D investment subsidy are used as an incentive mechanism to encourage universities to put more effort into RDDT than when there is no subsidy. In both cases, the R&D effort level of manufacturing enterprises remain unchanged. When universities and manufacturing enterprises engage in a cooperative game, the optimal R&D effort level in the SECI system reach the maximum, and superior to the non-cooperative game situation.

Proof: See the Appendix.

Corollary 2: In the case of Stackelberg master-slave game, the optimal R&D incomes of universities and manufacturing enterprises are better than the Nash non-cooperative game situation, that is when manufacturing enterprises provide R&D subsidy to universities, the R&D income in the SECI system is improved.

Proof: See the Appendix.

Corollary 3: Under the cooperative game, the total income is highest compared with the rest two situations.

Proof: See the Appendix.

It can be seen from Corollary 3 that under the cooperative game situation, the total income in the SECI system reached the highest. If the income distribution plan of both parties is reasonable and feasible, that is the respective optimal R&D income of both parties under the cooperative game situation are higher than non-cooperative cases. As a result, for both parties, collaborative cooperation is Pareto optimality. Therefore, it is necessary to coordinate the R&D strategy of DT technology of both parties. We have

$$V_U^{C*} - V_U^{D*} > 0, V_M^{C*} - V_M^{D*} > 0 \quad (24)$$

$$V_U^{C*} - V_U^{N*} > 0, V_M^{C*} - V_M^{N*} > 0 \quad (25)$$

From Corollary 2, we can get $V_U^{D*} - V_U^{N*} > 0$ and $V_M^{D*} - V_M^{N*} > 0$. So, we only just satisfy formula (24).

Corollary 4: In order to coordinate the cooperation between universities and enterprises and obtain individual Pareto optimality. Hence, the scope of income distribution coefficient of universities can be expressed as follows:

$$\tau \in \left\{ \left[\frac{2k_U A}{4k_U A + k_M B}, \frac{4k_U A}{4k_U A + k_M B} \right], \frac{k_U A}{k_M B} < \frac{1}{2} \right. \\ \left. \left[\frac{2k_U A}{4k_U A + k_M B}, \frac{2}{3} \right), \frac{k_U A}{k_M B} \geq \frac{1}{2} \right.$$

where $[\mu_2(\rho + \delta) + \beta v]^2 = A$ and $[\mu_1(\rho + \delta) + \alpha v]^2 = B$.

Proof: See the Appendix.

IV. NUMERICAL RESULTS

From the above analysis, the optimal level of R&D effort of both parties, their respective optimal income and the total R&D income in the SECI system are all related to the value of model parameters. The parameters are set as follows:

$$\tau \in \left[\frac{2k_U A}{4k_U A + k_M B}, \frac{4k_U A}{4k_U A + k_M B} \right] \quad 0 \leq \frac{k_R A}{k_M B} \leq \frac{1}{2}$$

$$\text{or } \tau \in \left[\frac{2k_U A}{4k_U A + k_M B}, \frac{2}{3} \right), \frac{k_R A}{k_M B} \geq \frac{1}{2}$$

The cooperative game situation not only realizes the Pareto optimality in the SECI system, but also reaches the Pareto optimality of the individual.

According to the relevant [30] and combined with reality, it is assumed that the parameters in the model are set as

$$\rho = 0 = 2, \quad k_U = 0.2, \quad k_M = 0.4, \quad \alpha = 0.3, \\ \beta = 0.2, \quad \delta = 0.1, \quad \mu_1 = 0.6, \quad \mu_2 = 0.5, \\ v = 0.3, \quad K(0) = K_0 = 2$$

Then the value range of the income distribution coefficient of universities τ can be obtained as [401/1611,822/1611]. We take $\tau = 0.4$ to meet its constraints. We can obtain

$$E_U^{N*} = 1.8, E_M^{N*} = 1.05; \quad E_U^{D*} = 3.6, \\ E_M^{D*} = 1.05, \theta^{D*} = 0.5, \\ E_U^{C*} = 4.5, E_M^{C*} = 1.75$$

That satisfies

$$E_U^{N*} < E_U^{D*} < E_U^{C*}, \quad E_M^{N*} = E_M^{D*} < E_M^{C*}, \\ \frac{E_U^{D*} - E_U^{N*}}{E_U^{D*}} = \theta^{D*} = 0.5$$

The above formula is consistent with the conclusion of Corollary 1.

Let $\Delta = \alpha E_U + \beta E_M$, we can get $K' = \Delta - \delta K$. The expression of the special solution function obtained by solving the general solution of the first-order differential equation is: $\Delta/\delta + (K_0 - \Delta/\delta)e^{-\delta t}$. It can be obtained that the optimal income of both parties and total income level in SECI system under the three game cases are:

$$\begin{cases} V_U^{N*} = 6.09 - 2.2e^{-0.1t} \\ V_M^{N*} = 10.4625 - 3.3e^{-0.1t} \\ V^{N*} = 16.5525 - 5.5e^{-0.1t} \\ V_U^{D*} = 9.87 - 4.36e^{-0.1t} \\ V_M^{D*} = 15.3225 - 6.54e^{-0.1t} \\ V^{D*} = 25.1925 - 10.9e^{-0.1t} \\ V_U^{C*} = 12.075 - 6e^{-0.1t} \\ V_M^{C*} = 18.1125 - 9e^{-0.1t} \\ V^{C*} = 30.1875 - 15e^{-0.1t} \end{cases}$$

Using MATLAB to obtain the trend of the optimal R&D income of universities and manufacturing enterprises and the total system income level over time under different game cases, as shown in Figure 2-4.

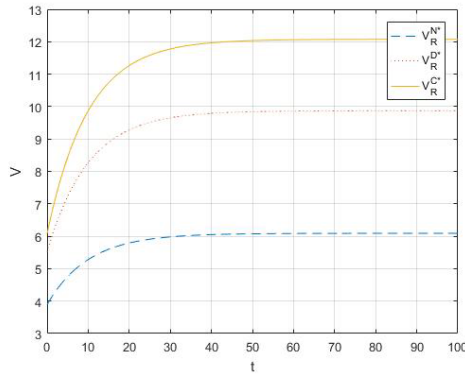


FIGURE 2. Comparative analysis of the optimal R&D income of universities under three cases.

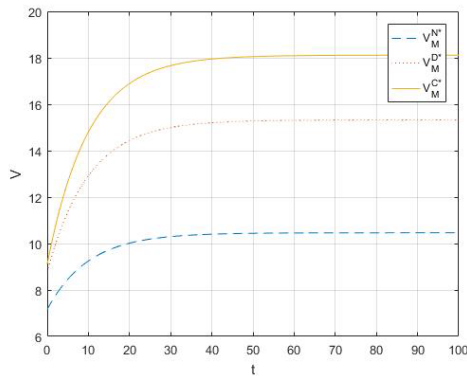


FIGURE 3. Comparative analysis of the optimal R&D income of manufacturing enterprises under three cases.

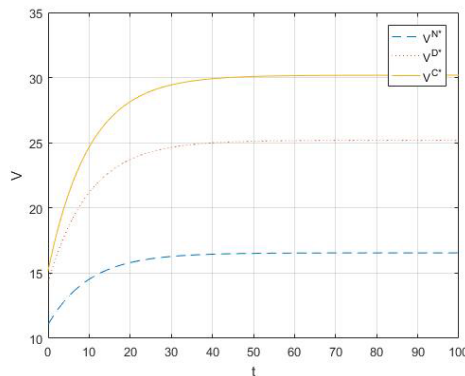


FIGURE 4. Comparative analysis of the total R&D income in the SECI system under three cases.

From Figure 2-4, it can be seen that the optimal R&D incomes of both parties and the total R&D income in the SECI system are positively correlated with time t , and the

change in the early stage is large, and the latter period tends to be stable. The order of the income of the three game cases from high to low is always maintained: cooperative game, Stackelberg master-slave game, Nash non-cooperative game. Consistent with the conclusions of Corollary 2, Corollary 3 and Corollary 4. Obviously, collaborative cooperation is Pareto optimality.

V. CONCLUSION

This paper explores a school-enterprise collaborative R&D strategy on DT technology using differential game model. The income functions of both universities and manufacturing enterprises are established with their R&D effort, respectively. Subsequently, we discuss the total R&D income in the SECI system and the R&D investment subsidy of the manufacturing enterprises to universities. Furthermore, their benefits are calculated and compared in three different situations, that are Nash non-cooperative game, Stackelberg master-slave game and cooperative game. Some conclusions draw from the equilibrium results are as follows.

As an incentive mechanism, the R&D investment subsidies can effectively improve the efforts of universities in the research and development of digital twin. Moreover, the improvement level is equal to the level of subsidies. In addition, universities and manufacturing enterprise can obtain more benefits in cooperative game compared with the other two game situations.

In the work, universities and manufacturing enterprises are regarded as two players in our model. However, the cooperation relationships of them in real world always involve more complex elements. In the future research, it is supposed to build a more comprehensive model. For example, the impact of some government policies and more player are considered in the game. Furthermore, due to the limitation of techniques, the parameters in our model are set to independent of time. Therefore, it is necessary to find a software with highly computing power or a more scientific method to solve this problem. In addition, a more realistic case needs to be studied in the future.

APPENDIX

Proof of Proposition 1: The optimal R&D level of effort of both sides can be computed by setting the first partial derivative equal to zero, and the respective optimal effort level of both parties can be

$$E_U = \frac{\mu_1\tau + \alpha V_U^N}{k_U}, E_M = \frac{\mu_2(1 - \tau) + \beta V_M^N}{k_M} \quad (A.1)$$

Substituting the result of (A.1) into (8) and (9), we can obtain

$$\rho V_U^N = (\tau v - \delta V_U^N) K + \frac{(\mu_1\tau + \alpha V_U^N)^2}{2k_U} + \frac{(\mu_2\tau + \beta V_U^N) [\mu_2(1 - \tau) + \beta V_M^N]}{k_M} \quad (A.2)$$

$$\begin{aligned} \rho V_M^N = & \left[(1 - \tau)v - \delta V_M^N \right] K + \frac{\left[\mu_2(1 - \tau) + \beta V_M^N \right]^2}{2k_M} \\ & + \frac{\left[\mu_1(1 - \tau) + \alpha V_M^N \right] \left(\mu_1\tau + \alpha V_U^N \right)}{k_U} \end{aligned} \quad (A.3)$$

The solution of the HJB equation is a unary function with K as independent variable. We have

$$V_U^N(K) = f_1 K + f_2, \quad V_M^N(K) = g_1 K + g_2 \quad (A.4)$$

where f_1, f_2, g_1 and g_2 are the constants to be solved.

Solving the first partial derivative of formula (A.4), we can get

$$V_U^N = f_1, \quad V_M^N = g_1 \quad (A.5)$$

Substituting the results of (A.4) and (A.5) into (A.2) and (A.3), we can get

$$\begin{aligned} \rho(f_1 K + f_2) = & (\tau v - \delta f_1) K + \frac{(\mu_1\tau + \alpha f_1)^2}{2k_U} \\ & + \frac{(\mu_2\tau + \beta f_1) [\mu_2(1 - \tau) + \beta g_1]}{k_M} \end{aligned} \quad (A.6)$$

$$\begin{aligned} \rho(g_1 K + g_2) = & [(1 - \tau)v - \delta g_1] K + \frac{[\mu_2(1 - \tau) + \beta g_1]^2}{2k_M} \\ & + \frac{[\mu_1(1 - \tau) + \alpha g_1] (\mu_1\tau + \alpha f_1)}{k_U} \end{aligned} \quad (A.7)$$

From the previous assumption, for all $K \geq 0$, $V_U^N(K)$ and $V_M^N(K)$ are continuously and marginally differentiable. We can obtain

$$\begin{cases} f_1 = \frac{\tau v}{\rho + \delta} \\ f_2 = \frac{[(\rho + \delta)\mu_1\tau + \tau v\alpha]^2}{2k_U\rho(\rho + \delta)^2} \\ \quad + \frac{\tau(1 - \tau)[\mu_2(\rho + \delta) + \beta v]^2}{k_U\rho(\rho + \delta)^2} \\ g_1 = \frac{(1 - \tau)v}{\rho + \delta} \\ g_2 = \frac{\tau(1 - \tau)[\mu_1(\rho + \delta) + \alpha v]^2}{k_U\rho(\rho + \delta)^2} \\ \quad + \frac{(1 - \tau)^2[\mu_2(\rho + \delta) + \beta v]^2}{2k_M\rho(\rho + \delta)^2} \end{cases}$$

Substituting the results of f_1 and g_1 into (A.1), we can further get

$$E_U^{N*} = \frac{\tau [\mu_1(\rho + \delta) + \alpha v]}{(\rho + \delta)k_U} \quad (A.8)$$

$$E_M^{N*} = \frac{(1 - \tau) [\mu_2(\rho + \delta) + \beta v]}{(\rho + \delta)k_M} \quad (A.9)$$

Substituting the results of f_1, f_2, g_1 and g_2 into (A.4), we can get

Proof of Proposition 2: Substituting the result of (13) into (14), and performing the indicated maximization and

search for the optimal value of E_M and θ by setting the first partial derivative equal to zero, we can get

$$E_M = \frac{(1 - \tau)\mu_2 + \beta V_M^D}{k_M} \quad (A.10)$$

$$\theta = \frac{(2 - 3\tau)\mu_1 + (2V_M^D - V_U^D)\alpha}{(2 - \tau)\mu_1 + (2V_M^D + V_U^D)\alpha} \quad (A.11)$$

Substituting the results of (13), (A.10) and (A.11) into (12) and (14), we can further get

$$\begin{aligned} \rho V_U^D = & (\tau v - \delta V_U^D) K \\ & + \frac{(\mu_2\tau + \beta V_U^D) [(1 - \tau)\mu_2 + \beta V_M^D]}{k_M} \\ & + \frac{(\mu_1\tau + \alpha V_U^D) [(2 - \tau)\mu_1 + (2V_M^D + V_U^D)\alpha]}{4k_U} \end{aligned} \quad (A.12)$$

$$\begin{aligned} \rho V_M^D = & \left((1 - \tau)v - \delta V_M^D \right) K + \frac{[(1 - \tau)\mu_2 + \beta V_M^D]^2}{2k_M} \\ & + \frac{[(2 - \tau)\mu_1 + (2V_M^D + V_U^D)\alpha]^2}{8k_U} \end{aligned} \quad (A.13)$$

The solution of the HJB equation is a unary function with K as independent variable. We have

$$V_U^D(K) = f_1 K + f_2, \quad V_M^D(K) = g_1 K + g_2 \quad (A.14)$$

where f_1, f_2, g_1 and g_2 are the constants to be solved.

Finding the first partial derivative of formula (A.14), we can get

$$V_U^D = f_1, \quad V_M^D = g_1 \quad (A.15)$$

Substituting the results of (A.14) and (A.15) into (A.12) and (A.13), we can get

$$\begin{aligned} \rho(f_1 K + f_2) = & (\tau v - \delta f_1) K \\ & + \frac{(\mu_2\tau + \beta f_1) [(1 - \tau)\mu_2 + \beta g_1]}{k_M} \\ & + \frac{(\mu_1\tau + \alpha f_1) [(2 - \tau)\mu_1 + (2g_1 + f_1)\alpha]}{4k_U} \end{aligned} \quad (A.16)$$

$$\begin{aligned} \rho(g_1 K + g_2) = & [(1 - \tau)v - \delta g_1] K \\ & + \frac{[(1 - \tau)\mu_2 + \beta g_1]^2}{2k_M} \\ & + \frac{[(2 - \tau)\mu_1 + (2g_1 + f_1)\alpha]^2}{8k_U} \end{aligned} \quad (A.17)$$

From the previous assumption, for all $K \geq 0$, $V_R^D(K)$ and $V_M^D(K)$ are continuously and marginally differentiable.

We can obtain

$$\begin{cases} f_1 = \frac{\tau v}{\rho + \delta} \\ f_2 = \frac{\tau(2 - \tau)[(\rho + \delta)\mu_1 + \alpha v]^2}{4k_U \rho(\rho + \delta)^2 + \frac{\tau(1 - \tau)[\mu_2(\rho + \delta) + \beta v]^2}{k_M \rho(\rho + \delta)^2}} \\ g_1 = \frac{(1 - \tau)v}{\rho + \delta} \\ g_2 = \frac{(2 - \tau)^2[\mu_1(\rho + \delta) + \alpha v]^2}{8k_U \rho(\rho + \delta)^2 + \frac{(1 - \tau)^2[\mu_2(\rho + \delta) + \beta v]^2}{2k_M \rho(\rho + \delta)^2}} \end{cases}$$

Substituting the results of f_1 and g_1 into (13), (A.10) and (A.11), we can further get

$$E_U^{D*} = \frac{(2 - \tau)[\mu_1(\rho + \delta) + \alpha v]}{2(\rho + \delta)k_U} \quad (A.18)$$

$$E_M^{D*} = \frac{(1 - \tau)[\mu_2(\rho + \delta) + \beta v]}{(\rho + \delta)k_M} \quad (A.19)$$

$$\theta = \begin{cases} \frac{2 - 3\tau}{2 - \tau}, & 0 < \tau < \frac{2}{3} \\ 0, & \frac{2}{3} \leq \tau < 1 \end{cases} \quad (A.20)$$

Among them, as a result of $0 < \theta \leq 1$ and $0 < \tau < 1$, we can get $0 < \tau < 2/3$.

Substituting the results of f_1, f_2, g_1 and g_2 into (A.14), we can get

Proof of Proposition 3: The optimal R&D effort level of DT technology can be computed by setting the first partial derivative equal to zero, and the respective optimal effort level of both parties can be

$$E_U^C = \frac{\mu_1 + \alpha V'^C}{k_U}, E_M^C = \frac{\mu_2 + \beta V'^C}{k_M} \quad (A.21)$$

Substituting the result of (A.21) into (19), we can obtain

$$\rho V^C = \frac{(\mu_1 + \alpha V'^C)^2}{2k_U} + \frac{(\mu_2 + \beta V'^C)^2}{2k_M} + (v - \delta V'^C)K \quad (A.22)$$

The solution of the HJB equation is a unary function with K as independent variable. We have

$$V^C(K) = f_1 K + f_2 \quad (A.23)$$

where f_1 and f_2 are the constants to be solved.

Solving the first partial derivative of formula (A.23), we can get

$$V'^C = f_1 \quad (A.24)$$

Substituting the results of (A.23) and (A.24) into (A.22), we can get

$$\rho(f_1 K + f_2) = \frac{(\mu_1 + \alpha f_1)^2}{2k_U} + \frac{(\mu_2 + \beta f_1)^2}{2k_M} + (v - \delta f_1)K \quad (A.25)$$

From the previous assumption, for all $K \geq 0, V^C(K)$ are continuously and marginally differentiable. We can obtain

$$\begin{cases} f_1 = \frac{v}{\rho + \delta} \\ f_2 = \frac{[(\rho + \delta)\mu_1 + \alpha v]^2}{2k_U \rho(\rho + \delta)^2} + \frac{[\mu_2(\rho + \delta) + \beta v]^2}{2k_M \rho(\rho + \delta)^2} \end{cases}$$

Substituting the result of f_1 into (A.21), we can obtain

$$E_U^{C*} = \frac{\mu_1(\rho + \delta) + \alpha v}{(\rho + \delta)k_U} \quad (A.26)$$

$$E_M^{C*} = \frac{\mu_2(\rho + \delta) + \beta v}{(\rho + \delta)k_M} \quad (A.27)$$

Substituting the results of f_1 and f_2 into (A.23), we can get *Proof of Corollary 1:* From (A.8), (A.9), (A.18), (A.19), (A.26), (A.27), ($0 < \tau < 2/3$), there exist

$$\begin{aligned} E_U^{D*} - E_U^{N*} &= \frac{(2 - 3\tau)[\mu_1(\rho + \delta) + \alpha v]}{2(\rho + \delta)k_U} \\ &= \frac{(2 - \tau)[\mu_1(\rho + \delta) + \alpha v]}{2(\rho + \delta)k_U} * \frac{(2 - 3\tau)}{(2 - \tau)} \\ &= E_U^{D*} * \theta > 0 \end{aligned}$$

$$E_U^{C*} - E_U^{D*} = \frac{\tau[\mu_1(\rho + \delta) + \alpha v]}{(\rho + \delta)k_U} > 0$$

$$E_M^{D*} - E_M^{N*} = 0$$

$$E_M^{C*} - E_M^{D*} = \frac{\tau[\mu_2(\rho + \delta) + \alpha v]}{(\rho + \delta)k_M} > 0$$

Corollary 1 is proved.

Proof of Corollary 2: From (10), (11), (16), (17), there exist

$$V_U^{D*} - V_U^{N*} = \frac{\tau(2 - 3\tau)[(\rho + \delta)\mu_1 + \alpha v]^2}{4k_U \rho(\rho + \delta)^2} > 0$$

$$V_M^{D*} - V_M^{N*} = \frac{(3\tau - 2)^2[\mu_1(\rho + \delta) + \alpha v]^2}{8k_U \rho(\rho + \delta)^2} > 0$$

Corollary 2 is proved.

Proof of Corollary 3: From (12), (18) and (21), there exist

$$V^{D*} - V^{N*} = \frac{(3\tau - 2)(\tau - 2)[(\rho + \delta)\mu_1 + \alpha v]^2}{8k_U \rho(\rho + \delta)^2} > 0$$

$$\begin{aligned} V^{C*} - V^{D*} &= \frac{\tau^2[(\rho + \delta)\mu_1 + \alpha v]^2}{8k_U \rho(\rho + \delta)^2} \\ &+ \frac{\tau^2[\mu_2(\rho + \delta) + \beta v]^2}{2k_M \rho(\rho + \delta)^2} > 0 \end{aligned}$$

Corollary 3 is proved.

Proof of Corollary 4: From formula (24), we can get

$$\frac{2k_U A}{4k_U A + k_M B} \leq \tau \leq \frac{4k_U A}{4k_U A + k_M B}$$

According to the previous description, we can get $0 < \tau < 2/3$. Furthermore, we can find:

$$0 < 2k_U A / (4k_U A + k_M B) < 2k_U A / 4k_U A = 1/2 < 2/3$$

Therefore, it is only necessary to discuss the values of $4k_U A / (4k_U A + k_M B)$ and $2/3$. Then, we can determine the value range of the R&D income distribution coefficient τ .

If $4k_{UA}/(4k_{UA} + k_{MB}) \leq 2/3$ (i.e. $0 \leq k_{UA}/k_{MB} \leq 1/2$), we can get $2k_{UA}/(4k_{UA} + k_{MB}) \leq \tau < 4k_{UA}/(4k_{UA} + k_{MB})$. If $4k_{UA}/(4k_{UA} + k_{MB}) \geq 2/3$ (i.e. $k_{UA}/k_{MB} \geq 1/2$), we can get $2k_{UA}/(4k_{UA} + k_{MB}) \leq \tau < 2/3$.

Corollary 4 is proved.

REFERENCES

- [1] F. Tao and Q. Qi, "New IT driven service-oriented smart manufacturing: Framework and characteristics," *IEEE Trans. Syst., Man, Cybern. Syst.*, vol. 49, no. 1, pp. 81–91, Jan. 2019.
- [2] P. Zhao, J. Liu, X. Jing, M. Tang, S. Sheng, H. Zhou, and X. Liu, "The modeling and using strategy for the digital twin in process planning," *IEEE Access*, vol. 8, pp. 41229–41245, 2020.
- [3] F. Tao, Q. Qi, A. Liu, and A. Kusiak, "Data-driven smart manufacturing," *J. Manuf. Syst.*, vol. 48, pp. 157–169, Jul. 2018.
- [4] J. Liu, H. Zhou, G. Tian, X. Liu, and X. Jing, "Digital twin-based process reuse and evaluation approach for smart process planning," *Int. J. Adv. Manuf. Technol.*, vol. 100, nos. 5–8, pp. 1619–1634, Feb. 2019.
- [5] H. Zhang, Q. Liu, X. Chen, D. Zhang, and J. Leng, "A digital twin-based approach for designing and multi-objective optimization of hollow glass production line," *IEEE Access*, vol. 5, pp. 26901–26911, 2017.
- [6] H. Guo, M. Chen, R. Zhang, J. Li, C. Li, T. Qu, G. Q. Huang, Z. He, and Y. Zeng, "Research on improvement of truck vibration based on systematic G8D method," *Shock Vib.*, vol. 2019, pp. 1–11, Jun. 2019.
- [7] J. Liu, H. Zhou, X. Liu, G. Tian, M. Wu, L. Cao, and W. Wang, "Dynamic evaluation method of machining process planning based on digital twin," *IEEE Access*, vol. 7, pp. 19312–19323, 2019.
- [8] D. Jones, C. Snider, A. Nassehi, J. Yon, and B. Hicks, "Characterising the digital twin: A systematic literature review," *CIRP J. Manuf. Sci. Technol.*, vol. 29, pp. 36–52, May 2020.
- [9] L. Rentzos, M. Doukas, D. Mavrikios, D. Mourtzis, and G. Chryssolouris, "Integrating manufacturing education with industrial practice using teaching factory paradigm: A construction equipment application," *Procedia CIRP*, vol. 17, pp. 189–194, Dec. 2014.
- [10] E. Abele, G. Chryssolouris, W. Sihn, J. Metternich, H. ElMaraghy, G. Seliger, G. Sivard, W. ElMaraghy, V. Hummel, M. Tisch, and S. Seifermann, "Learning factories for future oriented research and education in manufacturing," *CIRP Ann.*, vol. 66, no. 2, pp. 803–826, 2017.
- [11] G. Chryssolouris, D. Mavrikios, and L. Rentzos, "The teaching factory: A manufacturing education paradigm," *Procedia CIRP*, vol. 57, pp. 44–48, Oct. 2016.
- [12] B. Van Hong and N. Thi Luong, "School-enterprise collaboration oriented model of skilled worker training in mekong delta region, vietnam," *Amer. J. Educ. Res.*, vol. 6, no. 6, pp. 773–778, Jun. 2018.
- [13] M. Yang, "Evaluating collaborative innovation ability of school-enterprise cooperation," *Open J. Bus. Manage.*, vol. 03, no. 01, pp. 75–82, 2015.
- [14] C. Xiao-mei, "Study on management mechanism of training bases under the collaboration of universities and enterprises," *Laboratory Science*, vol. 1, p. 40, May 2019.
- [15] W. Huang, N. Qiu, F. Wang, C.-Y. Yan, and W.-T. Yi, "Exploration and practice of school-enterprise collaborative education of applied talents," *DEStech Trans. Social Sci., Edu. Hum. Sci.*, May 2019.
- [16] B. J. Ralph, A. Schwarz, and M. Stockinger, "An implementation approach for an academic learning factory for the metal forming industry with special focus on digital twins and finite element analysis," *Procedia Manuf.*, vol. 45, pp. 253–258, Aug. 2020.
- [17] B. Brenner and V. Hummel, "Digital twin as enabler for an innovative digital shopfloor management system in the ESB logistics learning factory at Reutlingen–University," *Procedia Manuf.*, vol. 9, pp. 198–205, Jun. 2017.
- [18] M. Perkmann, "Academic engagement and commercialisation: A review of the literature on university–industry relations," *Res. Policy*, vol. 41, no. 2, pp. 413–431, 2013.
- [19] S. N. Ankrah, "Asking both university and industry actors about their engagement in knowledge transfer: What single-group studies of motives omit," *Technovation*, vol. 32, nos. 2–3, pp. 49–65, 2013.
- [20] R. J. W. Tijssen, T. N. van Leeuwen, and E. van Wijk, "Benchmarking university–industry research cooperation worldwide: Performance measurements and indicators based on co-authorship data for the world's largest universities," *Res. Eval.*, vol. 18, no. 1, pp. 13–24, Mar. 2009.
- [21] A. Trigo and X. Vence, "Scope and patterns of innovation cooperation in spanish service enterprises," *Res. Policy*, vol. 41, no. 3, pp. 602–613, Apr. 2012.
- [22] Y. Yu and Q. F. Shi, "Differential game models of knowledge sharing in industry–university collaborative innovation," *Chin. J. Manag. Sci.*, vol. 21, pp. 684–690, May 2013.
- [23] S. Yin and B. Li, "Transferring green building technologies from academic research institutes to building enterprises in the development of urban green building: A stochastic differential game approach," *Sustain. Cities Soc.*, vol. 39, pp. 631–638, May 2018.
- [24] M. Yong-hong, L. Hai-jiao, and L. Qing, "Differential game study on industry–university synergetic R&D strategy of industrial generic technology," *Chin. J. Manag. Sci.*, vol. 12, pp. 197–207, Oct. 2019.
- [25] J. Sun, Z. Tian, Y. Fu, J. Geng, and C. Liu, "Digital twins in human understanding: A deep learning-based method to recognize personality traits," *Int. J. Comput. Integr. Manuf.*, vol. 15, pp. 1–14, Apr. 2020.
- [26] K. Alexopoulos, N. Nikolakis, and G. Chryssolouris, "Digital twin-driven supervised machine learning for the development of artificial intelligence applications in manufacturing," *Int. J. Comput. Integr. Manuf.*, vol. 2020, pp. 1–11, May 2020.
- [27] J. Leng, D. Yan, Q. Liu, K. Xu, J. L. Zhao, R. Shi, L. Wei, D. Zhang, and X. Chen, "ManuChain: Combining permissioned blockchain with a holistic optimization model as bi-level intelligence for smart manufacturing," *IEEE Trans. Syst., Man, Cybern. Syst.*, vol. 50, no. 1, pp. 182–192, Jan. 2019.
- [28] B. Schleich, N. Anwer, L. Mathieu, and S. Wartzack, "Shaping the digital twin for design and production engineering," *CIRP Ann.*, vol. 66, no. 1, pp. 141–144, 2017.
- [29] H. Guo, "Analysis of environmental policy's impact on remanufacturing decision under the effect of green network using differential game model," *IEEE Access*, vol. 8, pp. 115150–115162, 2020.
- [30] D. Z. Zhao, B. Y. Yuan, and C. Q. Xu, "Dynamic coordination strategy of vertical cooperative on carbon emission reduction in supply chain under low-carbon era," *J. Ind. Eng. Manage.*, vol. 29, no. 1, pp. 146–154, 2016.



HONGFEI GUO received the Ph.D. degree. He is currently the Deputy Dean, an Associate Professor, and a Graduate Supervisor with the Institute of Internet of Things and Logistics Engineering, Jinan University. He serves as a specially appointed as a Grassroots Management Expert of the management promotion of the State-Owned Assets Supervision and Administration Commission of the State Council of the People's Republic of China. He is also an SME Service Consultant

of the Ministry of Industry and Information Technology of the People's Republic of China and the Deputy Secretary–General of the Industrial Engineering Branch of the Chinese Mechanical Engineering Society. His team was selected to the Inner Mongolia "Prairie Talents" High-Level Talent Project, Inner Mongolia "Prairie Talents" Industry Innovation (Entrepreneurship) Talent Team, and Guangzhou Industry Leading Talent Concentration Project–"Innovation Leading Team". His current research interests include industrial Internet of Things, digital twins, and intelligent manufacturing. He has hosted more than 40 scientific research projects and been honored by more than 20 provincial and ministerial awards such as the Second Prize of China's Industry–University–Research Cooperation Innovation Achievement Award, the First Guangdong Science and Technology Cooperation Award, the First Prize of Guangdong's Enterprise Management Modernization Innovation Achievement, the First Prize of the 23rd Inner Mongolia's Enterprise Management Modernization Innovation Achievement, and the Second Prize of Scientific and Technological Progress of Inner Mongolia Autonomous Region.



LINSHENG ZHANG received the B.S. degree in logistics management from Yangtze University, China, in 2019. He is currently pursuing the M.S. degree in management science and engineering with the School of Management, Jinan University, China. His research interest includes intelligent manufacturing.



XIN LIAN is currently pursuing the B.S. degree in Internet of Things with the School of Intelligent Systems Science and Engineering, Jinan University at Zhuhai Campus. Her research interests include digital twins and intelligent manufacturing.



YU ZHANG received the B.S. degree from South China Normal University, Guangzhou, China, in 1995. After graduation, he stayed with the school and participated in the important research work from “The Eighth Five-Year” plan to “The Twelfth Five-Year” plan. He started his own business in 1997 and has successively established many high-tech enterprises. He is currently the Chairman of Guangzhou Create View Education Technology Company, Ltd., and leading the whole company to become one of the influential brands in the fields of interactive flat-screen TV and intelligent education cloud service. He is also serving as the Adjunct Professor of South China Normal University, a Master Student Supervisor, the Executive Director of the Guangzhou Institute of Collaborative Education Science and Technology, the Secretary-General of China Education Information Industry Technology Innovation Strategic Alliance, and the Secretary-General of Guangzhou Education Information Industry Technology Innovation Promotion Association, the Director of Guangdong Interactive Photoelectric Display Engineering Technology Research Center, the Deputy Director of Guangdong Intelligent Learning Engineering Technology Research Center, and the Deputy Director of the Information Technology Committee of Guangzhou Municipal Party Committee of the Democratic League. He has been holding some patents and computer software copyrights, and authored or coauthored books in the applications of wisdom in education.

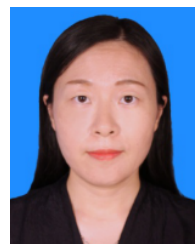


RUI ZHANG received the Ph.D. degree from Tianjin University. He was also a Visiting Scholar with Concordia University. He is currently an Associate Professor and a Master Supervisor of the Tianjin University of Science and Technology. He has published more than 40 academic articles. His six articles were searched by the SCI and 11 articles by the EI. He also presided over or completed many projects such as the NSFC and the NSSP as the Main Executor. He has applied for six invention patents and authorized one patent, applied for more than 20 utility model patents and authorized 16 patents, and obtained eight software copyrights. His research interests include wireless signal perception, the Internet of Things technology and its applications, and spectrum detection technology applications. He has won the Honor of “Young and Middle-Aged Backbone Innovative Talents” by universities in Tianjin. He won the Third Prize of the Tianjin Science and Technology Progress Award in 2017.



YAPING REN received the B.S. degree in communications and transportation engineering from Liaocheng University, Liaocheng, China, in 2014, the M.S. degree from the College of Transportation, Northeast Forestry University, China, in 2016, and the Ph.D. degree from the School of Mechanical Science and Engineering, Huazhong University of Science and Technology (HUST), China, in 2019.

He was also a Visiting Scholar in environmental and ecological engineering (EEE) with Purdue University, USA, from September 2017 to August 2019. He is currently an Associate Professor with the School of Intelligent Systems Science and Engineering, Jinan University at Zhuhai Campus. His research interests include industrial engineering, disassembly planning, transportation planning, decision making, and optimization methods.



NA DING received the B.S. degree from Liaocheng University, Liaocheng, China, and the M.S. degree from South China Normal University, Guangzhou, China, where she is currently pursuing the Ph.D. degree. She has hosted several scientific research projects, such as the major project of cooperation and innovation of production, study, and research in Guangzhou, and Tianhe district science and technology projects, and held some patents and computer software copyrights.

...