

Received July 2, 2020, accepted July 14, 2020, date of publication July 30, 2020, date of current version August 13, 2020. Digital Object Identifier 10.1109/ACCESS.2020.3012967

Computer-Aided Diagnosis and Staging of Pancreatic Cancer Based on CT Images

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This work was supported by the Science and Technology Project on aid to Xinjiang Uygur Autonomous Region under Grant 2019E0215.

ABSTRACT Pancreatic cancer (PC) is a malignant tumor that seriously threatens the survival of patients. Artificial classification has practical difficulties, such as unstable classification accuracy, a heavy workload, and the classification results depend on the subjective judgment of the clinician during the diagnosis and staging of PC. In addition, accurate PC staging could better help clinicians deliver the optimal therapeutic schedule for PC patients of different stages. Therefore, this study proposes a comprehensive medical computer-aided method for preoperative diagnosis and staging of PC based on an ensemble learning-support vector machine (EL-SVM) and computed tomography (CT) images. The least absolute shrinkage and selection operator (LASSO) algorithm was chosen for feature selection. In contrast to no feature selection, the model optimization time decreased by 19.94 seconds while maintaining precision. The EL-SVM learner was used to classify 168 CT images of normal pancreas and different stages of PC. The experimental results demonstrated that the normal pancreas (normal)-pancreatic cancer early stage (early stage) classification accuracy was 86.61%, the normal-pancreatic cancer stage III (stage III) classification accuracy was 87.04%, the normal-pancreatic cancer stage IV (stage IV) classification accuracy was 91.63%, the normal-PC classification accuracy was 87.89%, the early stage-stage III classification accuracy was 75.03%, and the early stage-stage IV classification accuracy was 81.22%, and the stage III-stage IV classification accuracy was 82.48%. Our experimental results prove that our proposed method is feasible and promising for clinical applications for the preoperative diagnosis and staging of PC via CT images.

INDEX TERMS Pancreatic cancer, diagnosis and staging, EL-SVM, CT, LASSO.

I. INTRODUCTION

Pancreatic cancer (PC) is a highly malignant tumor of the digestive tract that presents considerable challenges in both the early screening stage and later treatment [1]–[3]. According to statistics from the American Cancer Society, the death rates of patients with PC continue to increase, ranking fourth in the United States [4]–[7]. It is estimated that approximately 57,600 people will be diagnosed with PC, and approximately 47,050 people will die of PC in 2020, therefore PC is known as an incurable disease [7], [8]. In developing countries, PC is

The associate editor coordinating the review of this manuscript and approving it for publication was Haiyong Zheng^(D).

still widely distributed. Therefore, comprehensive preoperative diagnosis and staging of PC are particularly important, especially in the detection of PC staging, which could better help the clinicians to deliver the optimal therapeutic schedule for different stages of PC and allow the patients to receive early medical interventions before advanced PC are formed [9], [10].

At present, the imaging modalities commonly used in the diagnosis of PC are as follows: (1) Computed tomography (CT) is the common imaging for many patients due to low cost and high penetration. Several studies have shown that CT plays a significant role in the preoperative diagnosis of PC and has become the preferred approach for many

patients with PC screening [1], [5], [11]-[13]. (2) Endoscopic ultrasonography (EUS), including contrast-enhanced harmonic EUS (CH-EUS) and EUS-guided fine needle aspiration (EUS-FNA). When CH-EUS is used in combination with EUS-FNA, it can effectively enhance the sensitivity of EUS-FNA [14]. EUS has high sensitivity and spatial resolution when detecting small-sized pancreatic tumors (<= 1 cm), and it is easy to obtain tissue sections [14]-[16]. However, the accuracy of the preoperative staging of PC and diagnosis between PC and some nonneoplastic lesions are both controversial [1], [12], [16]-[19]. (3) Magnetic resonance imaging (MRI) /magnetic resonance cholangiopancreatography (MRCP). MRI is highly sensitive for the detection of PC liver metastases. However, it needs high cost, low spatial resolution and high expertise. Therefore, MRI has not developed into a widely used imaging modality compared with CT [4], [12], [16], [20], [21]. MRCP can display the pancreatic duct system with a noninvasive delineating method for expert observation, but its diagnostic accuracy is controversial [15], [22]. (4) Endoscopic retrograde cholangiopancreatography (ERCP) is at risk in the diagnosis of PC because of low diagnostic sensitivity [4], [12], [15], [23], [24]. (5) Positron emission tomography (PET) is often used to identify distant metastases and evaluate the effect of treatment, and its anatomical coverage is quite wide. However, its disadvantage is low spatial resolution [1], [22], [24]. PET is currently not recommended, because it cannot notice the information of PC staging [16]. (6) Laparoscopy (LAP) is mainly used to confirm the inspection results [21].

Many research institutions have carried out a series of studies on the diagnosis of PC based on CT images. Qiu et al. [25] proposed a method based on CT images to assist in the diagnosis of PC. The method of combining wavelet transform and a statistical method was used to extract texture features. After using the interactive information method for feature selection, the supported vector machine (SVM) and probabilistic neural network (PNN) classifiers were selected for classification. Through experimental verification, the accuracy of the two classifiers in classifying PC and normal pancreas reached 95.48% and 96.13%, respectively. Although this method can better help clinicians diagnose PC, it only classifies the normal pancreas and PC. Li et al. [26] performed a hybrid feedback-support vector machine-random forest (HFB-SVM-RF) computer-aided diagnosis model for PC. The test results of 80 cases of PET/CT images showed that the average accuracy of the model was 96.47%, and the sensitivity and specificity were both above 95%. Although the model has high classification accuracy, the problem of incomplete experimental objects still exists. Liu et al. [27] proposed the faster region-based convolution network model (Faster R-CNN) artificial intelligence system for PC diagnosis. CT images of 100 PC patients were used for verification, the area under the receiver operating characteristic curve (AUC) value of the model reached 0.9632, and the model could automatically classify a CT image in only 0.2 seconds. Although the subjects of this study included

different stages of PC, there is a lack of further study on the normal pancreas and different stages of PC.

Some research institutions have also paid attention to the ensemble learning of SVM. Shi et al. [28] proposed a computer aided pulmonary nodule detection system for chest radiography. The multiple massive training supported vector machine (MTSVM) model was proposed in this system, which consists of four non-linear SVMs arranged in parallel and one neural network arranged in serial. Each SVM classifier is an expert with excellent classification performance. However, the bagging algorithm was the ensemble learning algorithm used in this paper. Our paper used a bootstrap sampling method to generate different data sets; Then, we generated T base learners for combination, which ensures that each individual basic learner is "good and different". In order to improve the overall classification accuracy, the absolute majority voting method was used to explore the classification problem in this paper.

Aiming at the problems in the current research on the diagnosis of PC based on CT images, this study proposed a method of computer-aided diagnosis and staging of PC based on the ensemble learning-support vector machine (EL-SVM). Firstly, 168 nonenhanced CT images of different stages of PC and normal pancreas were chosen for pancreas segmentation. After extracting 202-dimensional features using six texture analysis methods, feature selection was performed based on the least absolute shrinkage and selection operator (LASSO). Finally, the EL-SVM learner was used to classify CT images of normal pancreas and different stages of PC. By comparing with SVM, the least absolute shrinkage and selection operator-support vector machine (LASSO-SVM), the k-nearest neighbor (KNN), the back propagation (BP) neural network classifiers, Softmax classifier, VGG16 model and DenseNet121 model [29], EL-SVM model achieved better performance for normal pancreas (normal)-pancreatic cancer early stage (early stage), normal-pancreatic cancer stage III (stage III), normal-pancreatic cancer stage IV (stage IV), normal-PC, early stage-stage III, early stage-stage IV, and stage III-stage IV classification. The main contributions of this paper can be listed as follows:

• This study was the first to comprehensively explore early screening and staging of PC by machine learning algorithms, and it shows the great potential of machine learning algorithms to be used in the diagnosis of PC at different stages.

• This study proposed a PC nonenhanced CT image classification model based on the EL-SVM.

• This study has a certain guiding role for junior clinicians in the diagnosis and staging of PC based on CT images, it can be used as a reference for diagnosis and can reduce the workload of clinicians.

II. MATERIALS AND METHODS

Figure 1 shows the overall flowchart for assisted diagnosis and staging of the PC method, which consists of following parts that are processed consecutively: 1) Pancreas region of interest (ROI) segmentation; 2) Feature selection and fusion;



FIGURE 1. Overall flowchart for assisted diagnosis and staging of the PC method. The green boxes in the figure represent the four main parts in this paper.

3) SVM classifier design, optimization and evaluation;4) EL-SVM design and evaluation. In the following sections, we will expand on the details.

A. DATA COLLECTION

This paper selected 54 patients from the First Affiliated Hospital of Xinjiang Medical University, from November 2017 to August 2019, of which 39 cases had PC and 15 cases had normal pancreas. Patients with PC were retrieved from the hospital pathology database, and the stage of PC was referred to the American Joint Committee on Cancer (AJCC) standard [30]. And they were pathologically confirmed after pathology or surgery, as shown in Table 1. The 15 cases of normal pancreas (7 men [mean age, 57.57 ± 14.76 years; range, 36-80 years] and 8 women [mean age, 49 ± 17.20 years;

Characteristic	Value
Sex	
Men	24
Women	15
Age	59.72 ± 12.25
PC stage	
Ι	2(5.13)
Tumor location in the pancreas	
Head and neck	1(2.56)
Uncinate process	0
Body	0
Tail	1(2.56)
II	13(33.33)
Tumor location in the pancreas	
Head and neck	10(25.64)
Uncinate process	2(5.13)
Body	0
Tail	1(2.56)
III	9(23.08)
Tumor location in the pancreas	
Head and neck	7(17.95)
Uncinate process	0
Body	0
Tail	2(5.13)
IV	15(38.46)
Tumor location in the pancreas	
Head and neck	8(20.51)
Uncinate process	1(2.56)
Body	0
Tail	6(15.38)
Tumor maximum diameter (in centimeters)	
Mean ± SD	3.45 ± 2.19
Range	1.50-12.00
Surgery	
Pancreatoduodenectomy	21(53.85)
Distal pancreatectomy	5(12.82)
Biliary stenting	2(5.13)
Pallative surgery	2(5.13)
Needle biopsy of the pancreas	2(5.13)
Exploratory laparotomy	1(2.56)
Removal of intraaddominal foreign body	1(2.56)
<37 U/mL	4(10.26)
> 200 U/mL	7(17.95)
>200 U/mL	28(71.79)

Note-Except for age and tumor maximum diameter (mean \pm SD), values are the number of patients with the percentage in parentheses.

TABLE 2. The obtained experimental images.

	Туре	Number of images
Total		168
Normal		51
	Stage I	5
	Stage II	34
PC	Stage III	26
	Stage IV	52

range, 26-77 years]) were determined by a doctor as having a normal pancreas through routine abdominal CT.

B. PANCREAS SEGMENTATION

Accurate segmentation of the pancreas is still a complex and challenging task. Considering the abdominal features of the pancreas and the variation in the volume and shape of the pancreas presented by the interpatient [31], [32], this paper manually drew the ROI of the pancreas. First, the CT sequence images in DICOM format were converted into JPG format and then imported into LabelMe software where two clinicians (Wei Han has 21 years and Yilidan Reheman has 3 years of clinical experience in abdominal CT) manually drew ROIs along the edge of the pancreas [33]. To improve model generalization ability, we selected 3 cross-sectional images of plain CT scans with significant features from each CT sequence on average [27], [34], [35]. A total of 168 CT images (as shown in Table 2) were evaluated, and a manually drawn ROI flowchart is shown in Figure 2. Pancreatic cancer stage I (stage I) or pancreatic cancer stage II (stage II) can be treated radically by surgical resection [36]; therefore, in this paper, stage I and stage II are collectively referred to as early stage [16], [37]–[40].

C. FEATURE EXTRACTION

We extracted 202-dimensional features using six feature analysis methods, including the shape, gray-level co-occurrence matrix (GLCM), gray-level run-length matrix (GLRLM), gray-level gradient co-occurrence matrix (GLGCM), graylevel difference statistics (GLDS), and wavelet transform, as shown in Table 3.

D. FEATURE SELECTION AND FUSION

The 202-dimensional features are fused together by serial fusion. To avoid the dimensional disaster and low generalization performance of the learner caused by too many features [41], we must use a suitable feature selection algorithm to remove redundant features on the basis of retaining key factors, reduce model complexity, and reduce the waste of time and resources [42]. We compared the three methods of no feature selection, the relevant features (Relief) and LASSO, and the classification results of the comparison are recorded in Table 4.



FIGURE 2. The pancreatic ROI segmentation. A. Normal CT image. B. ROI drawn on a pancreas image with the normal (red area). C. Normal segmentation. D. Stage IV CT image. E. ROI drawn on a pancreas image with the stage IV (red area). F. Stage IV segmentation.

TABLE 3. Extracted features of the six methods.

Methods	Feature name	Total
		number
Shape	height, width, perimeter, area, complexity, rectangularity,	8
	elongation, equivalent area radius	
GLCM	mean and standard deviation of energy, entropy, moment of	8
	inertia, and correlation	
GLRLM	short run emphasis, long run emphasis, gray-level nonuniformity,	7
	run percentage, run-length nonuniformity, low gray-level run	
	emphasis, high-gray level run emphasis	
GLGCM	small grads dominance, big grads dominance, gray asymmetry,	15
	grads asymmetry, energy, gray mean, grads mean, gray variance,	
	grads variance, correlation, gray entropy, grads entropy, entropy,	
	inertia, differ moment	
GLDS	mean, contrast, angular second moment, entropy	4
Wavelet		160
transform		
Total		202

As shown in Table 4, the LASSO selection algorithm not only reduced the dimensions but also retained the key features. Under the premise of ensuring classification accuracy, compared with no feature selection, the optimization time of LASSO algorithm decreased by 19.94 seconds and compared with the Relief feature selection, the optimization time decreased by 7.17 seconds, which verified the feasibility of the LASSO embedded feature selection algorithm selected in this paper. The LASSO algorithm combines L1 norm regularization and a linear regression model so that some unimportant variables in the model were directly compressed to 0 to streamline the model. The LASSO algorithm is shown in Equation (1). In addition, a 10-fold cross-validation method was used to verify the stability of the LASSO algorithm,

Linear kernel	Category	Normal-	Normal-	Normal-	Normal-PC	Early stage-	Early stage-	Stage III-
(Test/training)		early stage	stage III	stage IV		stage III	stage IV	stage IV
	Dimension	202	202	202	202	202	202	202
No feature	Accuracy rate%	73.08/96.88	69.57/100.00	73.33/98.63	72.55/100.00	42.86/88.64	60.71/93.65	68.00/96.23
selection	Time/second	3.06	2.12	3.77	8.71	1.58	2.94	2.15
	Dimension	57	59	30	156	19	25	15
RELIEF feature	Accuracy rate%	65.38/96.88	65.22/98.15	56.67/78.08	68.63/96.58	57.14/68.18	75/79.37	68.00/81.13
selection	Time/second	1.05	0.90	0.94	6.75	0.62	0.77	0.53
	Dimension	26	8	11	19	9	12	4
LASSO feature	Accuracy rate%	76.54/92.19	60.87/97.41	55.33/91.64	70.78/96.15	49.52/85.23	71.43/87.62	66.40/74.53
selection	Time/second	0.68	0.37	0.64	1.48	0.37	0.51	0.34

TABLE 4. Compared feature selection algorithms before and after LASSO and RELIEF to select the optimal solution.



FIGURE 3. Cross-validated MSE of LASSO fit (normal-early stage).

as shown in Figure 3 [43].

$$\min_{\mathbf{w}} \sum_{i=1}^{m} \left(y_i - w^T x_i \right)^2 + \lambda \| \mathbf{w} \|_1$$
(1)

E. SVM CLASSIFIER DESIGN AND IMPLEMENTATION

SVM was introduced by Vapnik [44], because it shows good performance on binary classification tasks, it has gradually developed and is now commonly used to solve multidomain classification matters [45]. The primary target of SVM is to find a "maximum margin" partitioning hyperplane suitable for classification samples so that the classification results are the most robust and have strong generalization capabilities [46]. Due to the existence of the kernel function, the samples of the original space reach the linearly separable high-dimensional feature space through mapping [47]. The kernel function and the feature space show a corresponding relationship, so the choice of the kernel function becomes the largest variable that determines the SVM classification performance. In addition, the selection of optimization algorithms is also quite important. We used multiple experiments and comparisons to attempt to find optimal optimization algorithms and kernel functions so that the SVM achieves the best performance and the largest increase in classification accuracy [46], [48].

F. SVM LEARNER EVALUATION

To better evaluate the reliability of the SVM learner, this paper drew the receiver operating characteristic (ROC) curve to judge the performance of the learner and used the AUC to quantitatively verify the learner generalization ability [49].

According to its real category and the predictor category of the learner, combining the sample divided into the following four cases: true positive (TP), false positive (FP), true negative (TN), false negative (FN), which comprise the confusion matrix. Finally, the horizontal and vertical axes of the ROC curve were calculated, where the horizontal axis represents the false positive rate (FPR) and the vertical axis represents the true positive rate (TPR), defined as Equations (2) and (3), respectively.

$$FPR = \frac{FP}{TN + FP} \tag{2}$$

$$TPR = \frac{TP}{TP + FN} \tag{3}$$

G. EL-SVM MODEL DESIGN

From Table 4, we learned that when we used the LASSO-SVM, although we demonstrated good performance in reducing time cost and dimensions, the classification accuracy was still low, of which normal-stage IV, and early stage-stage III classification accuracy were low. It can be

(Test/	KF	Linear kernel	Polynomial kernel	Gaussian kernel	Sigmoid kernel
training(%)/time)	OA				
Normal-	GS-SVM	76.54/92.19/0.68	59.23/99.06/0.41	77.69/96.25/0.58	53.85/57.81/0.60
early stage	PSO-SVM	65.77/97.81/0.33	63.85/92.66/0.40	74.23/96.09/0.41	64.62/75.47/0.39
	GA-SVM	70.77/95.78/2.41	60.38/100.00/2.07	71.54/100.00/2.12	53.85/57.81/2.14
Normal-stage III	GS-SVM	60.87/97.41/0.37	65.22/100.00/0.34	60.87/100.00/0.32	60.87/68.52/0.56
	PSO-SVM	64.78/100.00/0.30	60.87/68.52/0.30	62.17/100.00/0.28	63.48/86.30/0.28
	GA-SVM	63.91/99.81/1.09	65.22/100.00/1.16	63.48/100.00/1.09	60.87/68.52/1.24
Normal-stag IV	GS-SVM	55.33/91.64/0.64	42.33/99.86/0.58	55.67/100.00/0.59	46.67/50.68/0.57
	PSO-SVM	58.33/91.23/0.41	44.00/87.80/0.42	59.33/89.59/0.44	53.67/77.40/0.38
	GA-SVM	54.67/91.64/1.94	44.33/100.00/1.84	51.33/99.04/1.92	46.67/50.68/1.86
Normal-PC	GS-SVM	70.78/96.15/1.48	71.76/99.83/2.99	66.86/98.46/3.06	72.55/68.38/2.26
	PSO-SVM	72.16/97.44/1.89	72.94/97.44/0.93	73.92/88.29/0.83	76.47/89.15/1.72
	GA-SVM	69.22/96.75/4.07	66.86/100.0/11.52	66.67/98.63/9.27	72.55/68.38/4.26
Early stage-	GS-SVM	49.52/85.23/0.37	45.24/86.14/0.34	52.38/96.36/0.33	57.14/61.36/0.34
stage III	PSO-SVM	48.10/93.96/0.29	55.24/66.14/0.31	53.33/86.14/0.29	53.33/71.82/0.29
	GA-SVM	51.90/77.05/2.31	43.33/91.36/2.25	48.10/82.95/1.21	57.14/61.36/2.36
Early stage-	GS-SVM	71.43/87.62/0.51	65.71/95.24/0.50	74.64/89.68/0.49	57.14/57.14/0.50
stage IV	PSO-SVM	68.93/89.21/0.37	57.14/57.14/0.39	76.43/85.40/0.41	72.86/76.51/0.38
	GA-SVM	73.93/87.46/1.89	67.14/93.81/1.59	72.86/91.11/1.95	59.64/61.43/1.81
Stage III-	GS-SVM	66.40/74.53/0.34	70.80/92.08/.0.34	67.60/89.25/0.36	64.00/67.92/0.34
stage IV	PSO-SVM	66.80/79.06/0.34	68.40/93.02/0.46	63.20/86.42/0.32	64.00/67.92/0.34
	GA-SVM	67.20/83.96/1.94	64.40/93.58/1.98	68.00/91.13/2.94	64.00/67.92/2.51

TABLE 5. Con	mparing three	optimization a	lgorithms (OA) and	four kernel	functions (M	(F) to c	hoose th	ne optimal	Kernel	function and	d optimization a	algorithm.
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TABLE 6. The experimental parameter of GS-SVM, PSO-SVM and GA-SVM.

Classifier	Parameter	Parameter value	Parameter	Parameter value
GS-SVM	Range of C	[2-4, 24]	Range of g	[2 ⁻⁴ , 2 ⁴]
	Step length of C	0.3	Step length of g	0.3
	Range of C	[10 ⁻¹ , 10 ²]	Range of g	[10 ⁻² , 10 ³]
PSO-SVM	Local search capability	1.5	Global search capability	1.7
	Maximum number of generations	50	Maximum number of populations	5
	Range of C	$[0, 10^2]$	Range of g	$[0, 10^3]$
GA-SVM	Maximum number of generations	200	Maximum number of populations	20
	Generation gap	0.9		

known from theory that good generalization performance can be obtained by using weak learner integration, so this paper proposed an EL-SVM to improve the classification accuracy and obtain a model with good generalization performance.

Ensemble learning improves performance by constructing and combining multiple base learners. The key is that the integration individual needs to have certain accuracy and diversity. The bagging algorithm was the ensemble learning algorithm used in this paper [50], [51]. The bagging algorithm is a significant representative of the parallel ensemble learning method; it uses a bootstrap sampling method to generate different initial data sets. T-times bootstrap sampling is performed, and m samples are returned each time; approximately 63.2% of the samples appeared in the training set, and the remaining 36.8% of the uncollected samples were used as the test set to perform an "out-of-bag estimate" of the generalization performance, which was determined from Equation (4). Finally, we generated T differential base learners for combination. The basic flow of the EL-SVM

TABLE 7.	Comparison o	of the results	of the EL-SVM	model and	classifier.
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Test/training (%)	Normal-early stage	Normal-stage III	Normal-stage IV	Normal-PC	Early stage-stage III	Early stage-stage IV	Stage III-stage IV
BP	59.23/95.78	62.18/90.37	77.14/97.26	72.75/88.80	50.95/87.50	57.50/96.51	57.61/90.76
KNN	80.77/91.57	72.18/94.80	81.00/81.10	83.14/86.25	46.67/70.47	65.00/74.77	78.00/87.34
SVM	73.08/96.88	69.57/100.00	73.33/98.63	72.55/100.00	42.86/88.64	60.71/93.65	68.00/96.23
LASSO-SVM	76.54/92.19	60.87/97.41	55.33/91.64	70.78/96.15	49.52/85.23	71.43/87.62	66.40/74.53
EL-SVM	86.61/92.78	87.04/94.67	91.63/100.0	87.89/99.28	75.03/95.69	81.22/96.70	82.48/99.23

TABLE 8. The experimental parameter of BP and KNN.

Classifier	Parameter	Parameter value	Parameter	Parameter value
BP	Maximal iteration times	al iteration times 2000		0.00001
	Display interval	500	Learning rate	0.05
KNN	KNN Number of neighbors		Distance metric	Cosine
	Distance weight	Equal	Standardize data	True



FIGURE 4. EL-SVM algorithm flow.

algorithm is shown in Figure 4.

$$\lim_{m \to \infty} (1 - \frac{1}{m})^m = \frac{1}{e} \approx 0.368 \tag{4}$$

where m is the number of samples of each base learner.

To complete the classification task of EL-SVM, this paper used the absolute majority voting method to select the class with more than half of the predicted votes, otherwise rejecting predictions to improve overall classification accuracy.

H. EL-SVM MODEL EVALUATION

The classification error curve was used to further verify the reliability of the EL-SVM classifier in this paper. The number of base learners was used on the horizontal axis, and the classification error that still existed after ensemble learning was used on the vertical axis.

I. HORIZONTAL COMPARISON WITH OTHER MODELS

We compared SVM, LASSO-SVM, KNN, BP neural network classifier, Softmax classifier, VGG16 model, DenseNet121 model and EL-SVM model [52]. We used the no data augmentation, data augmentation 3 times, data augmentation 6 times, data augmentation 12 times, and data augmentation 24 times to expand the training set, and sequentially import two deep learning models for experimentation. The rest of the models use the no data augmentation data set for classification.

III. RESULTS

The experiments in this paper were based on the MATLAB 2016a platform and PyCharm platform. The LIBSVM toolbox was used for the discrimination and analysis of the SVM algorithm [53].

A. SVM MODEL PARAMETER OPTIMIZATION

Three optimization algorithms were used to build a diagnostic model, including grid search-support vector machine (GS-SVM), particle swarm optimization-support vector machine (PSO-SVM), and genetic algorithms based on support vector machine (GA-SVM), to choose the optimal optimization algorithm and the optimal kernel function, as shown in Table 5 [54]. The primary experimental parameters of GS-SVM, PSO-SVM and GA-SVM are listed in Table 6. To avoid the risk of overfitting, we adopted 5-fold crossvalidation methods.

It can be seen from Table 5 that under the premise of using the grid optimization algorithm, the linear kernel and the Gaussian kernel have little difference in accuracy and optimization time. However, the linear kernel function had the largest growth rate in the later integrated learning classifier and the highest optimization improvement. Therefore, this paper chose a grid search optimization algorithm and linear kernel function to classify pancreatic CT images.

B. EVALUATION OF EL-SVM

To reduce the experimental error and ensure the validity of the experimental results, the results in Table 7 all take the average of 10 experiments in each category [55].



TABLE 9. The experimental parameter of Softmax classifier.





Note-The visual picture of the VGG16 model accuracy. (a) no data augmentation. (b) data augmentation 3 times. (c) data augmentation 6 times. (d) data augmentation 12 times. (e) data augmentation 24 times.

1) COMPARISON OF THE EL-SVM MODEL AND OTHER MODELS

The mainstream classification algorithms the KNN and the BP neural network were compared horizontally with the EL-SVM model in this paper, and the comparison results are shown in Table 7 [56]. The primary experimental parameters of KNN and BP are listed in Table 8. Table 7 shows that after using the ensemble learning algorithm, the classification accuracy of normal pancreas and PC in different stages greatly improved, and the generalization ability was enhanced. The classification accuracy rate of normal-stage IV reached 91.63%, and the classification accuracy of EL-SVM in normal-stage IV was improved by 36.30%, compared with LASSO-SVM. The average classification accuracy of BP was lower than EL-SVM 22.08%, and KNN was lower than EL-SVM classifier in this paper.

This paper also used Softmax classifier for comparison [57]. The 202-dimensional features extracted by the above six texture analysis methods are passed to the Softmax classifier to classify normal pancreas and different stages of PC. Experimental results showed that the average classification accuracy of the Softmax classifier was lower than EL-SVM 14.45%. As shown in Figure 5, the overall performance of EL-SVM is better than Softmax classifier. The primary experimental parameters of Softmax classifier are listed in Table 9.

This work attempted to train two different network structures (VGG16, DenseNet121) and built two models [58]–[61]. The visual images of VGG16 model and DenseNet121 model are placed in Table 10 and Table 11, respectively. It can be seen from the figure that the effects of the two models are not ideal, which also verifies that our proposed EL-SVM is our appropriate choice.

Training acc

25

15

20

Validation acc

TABLE 11. Visual picture of the DenseNet121 model accuracy.



Note-The visual picture of the DenseNet121 model accuracy. (a) no data augmentation. (b) data augmentation 3 times. (c) data augmentation 6 times. (d) data augmentation 12 times. (e) data augmentation 24 times.

TABLE 12. The primary experimental parameter of VGG16 and DenseNet12	!1.
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Architecture model	Parameter	Parameter value	Parameter	Parameter value
	Simulation environment	64-bit Windows 10 operating system	Software	PyCharm
VGG16	Image dimensions	224×224	Loss function	Categorical Cross-entropy
	Batch size	32	Epoch	30
	Learning rate	0.001	Optimization algorithm	Stochastic gradient descent
	Image dimensions	224×224	Loss function	Categorical Cross-entropy
DenseNet121	Batch size	32	Epoch	30
	Learning rate	0.001	Optimization algorithm	Stochastic gradient descent

TABLE 13. The AUC of five classifiers.

AUC	Normal-early stage	Normal-stage III	Normal-stage IV	Normal-PC	Early stage-stage III	Early stage-stage IV	Stage III -stage IV
BP	0.6310	0.6151	0.7098	0.7046	0.5000	0.5833	0.6042
KNN	0.8095	0.7262	0.7991	0.8475	0.4722	0.6250	0.7222
SVM	0.7262	0.7381	0.8393	0.7471	0.3796	0.6302	0.6181
LASSO-SVM	0.7440	0.6905	0.5848	0.7548	0.4259	0.7656	0.7014
EL-SVM	0.8750	0.9444	0.9583	0.9500	0.7500	0.7917	0.8750

TABLE 14. The classification error convergence value.

Classification	Normal-	Normal-stage III	Normal-stage IV	Normal-PC	Early stage-	Early stage-	Stage III-stage IV
	early stage				stage III	stage IV	
Convergence value	0.1333	0.1418	0.0971	0.1307	0.2991	0.2053	0.1954

Note-The convergence value is the classification error convergence value.



FIGURE 5. Softmax classifier ROC curve. Class 0 (normal), class 1(early stage), class 2 (stage III), class 3(stage IV), class 4(PC).



FIGURE 6. SVM classifier ROC curve.

The primary experimental parameters of VGG16 model and DenseNet121 model are listed in Table 12.

2) ROC CURVE AND AUC

We drew the ROC curves of SVM, LASSO-SVM, EL-SVM, BP, and KNN, as shown in Figures 6, 7, 8, 9 and 10, and the corresponding AUC values are given in Table 13.









It can be seen from Table 13, Figure 6, Figure 7, and Figure 8 that the AUC value of EL-SVM for normal-stage IV classification increased by 0.3735 compared to LASSO-SVM and the AUC value of EL-SVM for early stage-stage III classification increased by 0.3241 compared to LASSO-SVM. The average AUC of EL-SVM reached 0.8778, and the AUC of normal-stage IV reached 0.9583, which greatly improved

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FIGURE 9. BP classifier ROC curve.



FIGURE 10. KNN classifier ROC curve.

compared with LASSO-SVM and SVM. The results show that EL-SVM has good feasibility.

From Table 13 and Figures 8, 9 and 10, it can be seen that the AUC values of BP and KNN were lower than those of EL-SVM. The average AUC of BP was lower than that of EL-SVM (0.2567) and that of KNN was lower than that of EL-SVM (0.1633). Therefore, the performance of the KNN and BP neural networks on pancreatic CT images was inferior to that of the EL-SVM model.

3) EL-SVM ERROR CURVE

This paper used 400 base learners for ensemble learning and then drew the classification error curve of EL-SVM as shown in Figure 11. The classification error convergence values are shown in Table 14, which shows that the classification error convergence value of normal-stage IV was the lowest and the classification performance was the best.



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FIGURE 11. EL-SVM error curve.

IV. CONCLUSION

This paper was the first to proposed a classification method of pancreatic CT images based on EL-SVM. We performed experiments on 168 CT images of normal pancreas and different stages of PC, and the results demonstrated that the EL-SVM method obtained the best classification performance. Our study could help solve the problems existing in preoperative PC diagnosis to a certain extent and deliver treatment options for different stages of PC patients, which have certain feasibility and practicability. In the future, we will continue to collect more samples from different central institutions, and establish a classification model with better performance; therefore, it has greater clinical significance for the preoperative diagnosis and staging of PC via CT images.

ACKNOWLEDGMENT

(Min Li and Xiaohan Nie are co-first authors.)

CONFLICTS OF INTEREST

The authors have no relevant financial interests in this article and no potential conflicts of interest to disclose.

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