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# An Exact Method and Ant Colony Optimization for Single Machine Scheduling Problem With Time Window Periodic Maintenance

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**ABSTRACT** This paper considers a time window periodic maintenance strategy with different duration windows and job scheduling activities in a single machine environment. The aim is to minimize the number of tardy jobs through the integration of production scheduling and periodic maintenance intervals. A mixed-integer linear programming model (MILP) is proposed to optimize small-sized test instances. Furthermore, an ant colony optimization (ACO) algorithm is developed to solve larger sized test instances. Subsequently, to measure the efficiency of the solutions obtained by ACO, Moore's algorithm is also developed to benchmark with ACO. To test the efficiency and the effectiveness of the ACO algorithm, a set of data for small and large sized problems was generated in which several parameters were adopted and then ten replicates were solved for each combination. The small sized instances were solved by the MILP. Then, the results obtained showed that the proposed ACO was able to obtain the exact solutions within reasonable CPU times, thus, it outperformed the CPLEX solver with respect to CPU. The large sized instances were solved by the Moore's algorithm and compared to ACO. Then, the results obtained showed that the ACO outperforms Moore's algorithm for all the instances tested. It can be concluded that the developed ACO is very efficient and effective in solving the problem considered in this paper.

**INDEX TERMS** Scheduling, MILP, single machine, periodic Maintenance, ant colony.

## I. INTRODUCTION

Production scheduling and production planning have a direct impact on an organization's performance [1]. Efficient organizations integrate production scheduling methodologies and maintenance service strategies to make the best use of machine availability and to ensure that the required quality levels are met, within the required time-frames. Previous studies in single machine environments scheduling assume that the production systems are always available at all time horizons and ignore the maintenance aspect. This, in turn, increases the probability of machine breakdowns [2]. Thus, to ensure the optimal availability of production systems, it is necessary to regulate the production schedule by considering intervention dates of maintenance actions. This paper will investigate a time window periodic maintenance strategy with

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different duration windows and job scheduling activities in a single machine environment, aiming to minimize the number of tardy jobs through the integration between production scheduling and periodic maintenance intervals. Two different algorithms, ACO and Moore's, will be tested to obtain a high-quality solution to the proposed problem.

## II. LITERATURE REVIEW

Studying the effects of different types of maintenance (periodic, preventive, among others) on different scheduling environments has received considerable attention for many years now. The periodic maintenance policy has been widely used by Chen [3]. Ma et al. and Sanlaville and Schmidt provided comprehensive reviews for cases where intervention dates are fixed and known at the beginning of a scheduling horizon [4], [5]. Cui and Lu recently studied flexible maintenance and release dates on a single machine environment

with the objective of minimizing the makespan, and presented a mixed-integer linear programming model for small-sized test instances [6]. For small-to-medium sized problems, a heuristic ERD-LPT and a branch-and-bound algorithm were also proposed. The nature of the flexible maintenance methods in their study depends on the machine running time. To perform maintenance activity on the machine, the processing time on the machine must be less than or equal to  $T$ , where  $T$  is the time between two periodic maintenances. Ángel-Bello et al. proposed another mixed-integer linear model for minimizing the makespan [7]. Hou et al. considered the problem of a single machine with periodic consecutive maintenance-availability constraints, and sequence-dependent setup costs [8]. They also aimed to find a schedule with an appropriate maintenance strategy to minimize makespan, by proposing a partial maintenance model and incorporating it into a single machine scheduling problem with a deterioration model. Partial maintenance saves time by restoring the machine to be maintained to an available state on order to return to a production system. Similarly, Chung et al. and considered a single machine scheduling problem with batch setups, positional deterioration effects, and multiple optional rate-modifying activities to minimize the total completion time [9]. Laalaoui and 'Hallah used a two-phase heuristic algorithm and tried to maximize the weighted number of a single machine environment subject to scheduled maintenance periods and a common due date. They showed that the problem was strongly NP-hard, and to solve small-sized instances binary multiple knapsacks were proposed [10]. Similarly, Detti et al. addressed a problem arising in a manufacturing environment concerning the joint scheduling of multiple jobs [11].

Furthermore, a variable neighborhood search algorithm was presented for all-sized problems, the computational result showing the effectiveness of the proposed algorithm. Sbihi and Varnier investigated single machine problem scheduling with two scenarios of maintenance activities, with the aim to minimize the maximum tardiness. The first scenario dealt with the problem of when the time between two maintenance activates is fixed, while the second scenario dealt with the problem of when the time between two maintenance activates was not fixed, but depended on the machine working time [12]. Pacheco et al. also used a variable neighborhood search algorithm and studied the problem of sequencing jobs in a single machine with programmed preventive maintenance and sequence-dependent setup times [13]. Wang et al. studied a single machine scheduling problem where deteriorating jobs and flexible periodic maintenance were considered, using a branch and price algorithm [14]. Sun and Geng also aimed to find an optimal schedule in order to minimize the maximum completion time in single machine scheduling [15]. Low et al. presented six heuristic algorithms based on first fit and best fit, dealing with single machine scheduling problems with availability constraints to minimize the makespan. They considered that the machine should stop to maintain after a periodic time

interval or change tools after a fixed number of jobs had been processed simultaneously [16]. Mashkani and Moslehi examined the minimization of the makespan on a single machine under a new term called bimodal flexible periodic availability constraints. A binary integer mathematical programming model was presented and they provided an efficient branch-and-bound algorithm and heuristic algorithm to solve the problem using several dominance rules [17].

For such cases where periodic maintenance activities are required, Liao proposed a branch-and-bound algorithm and heuristic to minimize the maximum tardiness once maintenance is performed periodically within a fixed time interval [18], Chen proposed a heuristic for the objective of minimizing the mean flow time of jobs [19]. Chen also proposed a branch-and-bound algorithm to find the optimal schedule [3], discussing the scheduling problem on single machine with the objective of minimizing the number of tardy jobs. Likewise, Hong et al. suggested optimal periodic maintenance policies to determine the interval between the periodic maintenance activities taking into consideration the maintenance costs [20], while Shen and Zhu studied a single machine scheduling problem with periodic maintenance, in which the processing time and repair time were nondeterministic. They used LPT algorithms to solve the problem [21].

The number of tardy jobs has long been considered a performance indicator in a number of research papers on single machine scheduling problems. For example, Lee and Kim presented a mixed-integer programming model and a heuristic consisting of two phases [22], the first phase of which was obtaining an initial solution based on Moore's algorithm, the second phase being more for improvement of the initial solution. Liu et al. further investigated the same problem [23], the authors proposing a branch-and-bound algorithm be applied to the obtained optimal solution. Uzsoy and Martin-Vega developed solutions based on Moore's algorithm for problems with other settings [24]. Their problem was solved under the constraint of periodic maintenance when the time between two consecutive maintenances was fixed. Wang and Xu, and Xu and Xu, studied the problem of maintenance duration when dependent on workload time. In their study, the start time for each maintenance was limited to a certain time window [25], [26]. Under the objective of minimizing a maximum lateness minimization [25] and minimizing the makespan [26], different algorithms were presented to solve the problem, the results showing their effectiveness. Likewise, Qamhan et al. also presented an evolutionary discrete firefly algorithm (EDFA) to solve a real-world manufacturing system problem of job scheduling [27]. Touat et al. focused on flexible maintenance under human resource constraints on single machine scheduling problems to minimize the sum of total weighted tardiness [28]. Two strategies using a fuzzy logic hybrid with a genetic algorithm were proposed to find near-optimal solutions. Zammori et al. proposed a hybrid harmony search algorithm with genetic algorithms [29]. They addressed a problem on single machine scheduling subject to planned

TABLE 1. Model notations.

Indices	
$i$	the index of job, $i = 1, 2, \dots, n$ ;
$j$	the index of job position, $j = 1, 2, \dots, n$ ;
$l$	the index of periodic maintenance $l = 1, 2, \dots, L$ ;
Decision variables	
$x_{ijl}$	binary decision variable and $x_{ijl} = 1$ if $i$ processed in position $j$ in the period $l$
$U_{jl}$	binary decision variable and $U_{jl} = 1$ if the job in position $j$ in the period $l$ is tardy.
$f_{jl}$	decision variable, the completion time of job $j$ in period $l$
$q_{jl}$	decision variable for the virtual and actual due date of job $j$ in period $l$
$tm_l$	decision variable, the starting time of maintenance $l$
$fm_l$	decision variable, the completion time of maintenance $l$
Parameters	
$p_i$	processing time of job $i$
$d_i$	due date for job $i$
$M_l$	time duration of maintenance $l$
$T$	presumptive time between two maintenance
$w$	time allowance
$A$	a large enough number

maintenance and sequence-dependent setup times with the objective of minimizing total earliness and tardiness penalties. Later on, Bertolini et al. went on to present and compare new metaheuristics to solve an integrated jobs-maintenance scheduling problem on a single machine subjected to aging and failures [30]. Nie et al. addressed the problem of a fuzzy random time window for maintenance planning on single machine scheduling problems with multi-objective functions of minimizing the total weighted completion time, and maximizing the average timeliness level under a fuzzy environment [31]. Global-local-neighbor particle swarm optimization (PSO) based on the first fit rule as the initial swarm was proposed, and the experimental results showed that the algorithm was practicable and efficient in handling such complex problems. Krim et al. also challenged the single machine scheduling problem using periodic preventive maintenance to minimize the weighted sum of completion times [32]. Results showed that the average percentage error of the best heuristic was less than 10%. Chung et al. addressed the same problem to minimize total completion time with the use of a binary integer programming model [33]. Others such as Chen et al. aimed to minimize the total completion times where the machine had to receive periodical maintenance so that the dirt generated in the process did not exceed the limit [34], while Xu and Xu considered a single machine tool change scheduling problem where tool change durations were workload dependent [35].

In this sense, the addressed problem in this study is to minimize the number of tardy jobs on single machine problem under flexible periodic maintenance within a time window, in addition to the maintenance activates having

different durations. To the best of our knowledge, this problem has not yet been studied. The next section will describe the mixed-integer linear programming model. Section 4 will be devoted to the presentation of the proposed algorithm (ACO). Section 5 will present the experimental results. Finally, section 6 will be dedicated to a conclusion and recommendations for future study.

### III. PROBLEM FORMULATION AND ANALYSIS

#### A. PROBLEM DEFINITION AND ASSUMPTION

The addressed problem can be summarized as the following; There are  $n$  jobs  $J = J_1, J_2, \dots, J_n$  to be processed on a single machine, which the machine can only process one job  $J_i$  at a time. There is no preemption allowed or precedence relationship between the jobs and all jobs are available at time zero. Each job has due date  $d = d_1, d_2, \dots, d_n$ . The machine is not available in the all-time horizon line and it has a  $L$  periodic maintenances  $M = M_1, M_2, \dots, M_L$ , and the durations of different maintenance activate  $M_l$  are not necessarily equal. The time between two maintenance activates is fixed and equal,  $T$ , and each maintenance activity can start in a time window  $T \mp w$  where  $w$  is the time allowance for the starting maintenance activity. The main task is to optimize the scheduling sequence of the  $n$  jobs which minimizes the number of tardy jobs.

#### B. MIXED-INTEGER LINEAR PROGRAMMING MODEL (MILP)

The following notations in Table 1 are used to formulate the problem:

TABLE 2. Jobs data for the given example.

Job	1	2	3	4	5	6	7	8	9	10
$p_i$	47	27	94	90	60	13	39	37	16	79
$d_i$	322	324	278	429	398	352	456	332	364	438

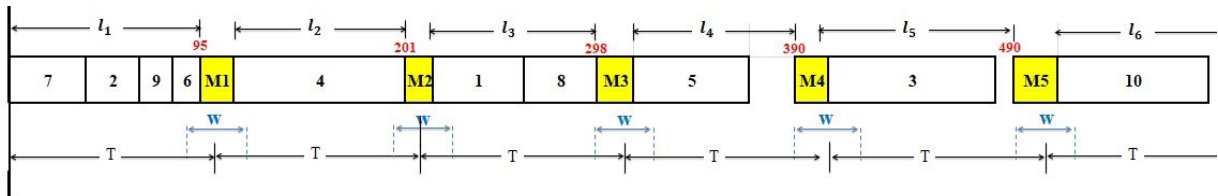


FIGURE 1. Optimal schedule for the example.

TABLE 3. Maintenance data for the given example.

Job	1	2	3	4	5	6	7	8
$M_i$	16	13	18	12	22	18	24	13
	$T=100$				$w=10$			

The MILP model can be formulated as follows:

$$\min \sum U \tag{1}$$

Subject to

$$\sum_{(l=1)}^L \sum_{(i=1)}^n x_{ijl} = 1, \quad j = 1, 2, \dots, n \tag{2}$$

$$\sum_{(l=1)}^L \sum_{(j=1)}^n x_{ijl} = 1, \quad i = 1, 2, \dots, n \tag{3}$$

$$\sum_{(i=1)}^n \sum_{(j=1)}^n p_i x_{ijl} \leq tm_l - fm_{l-1}, \quad l = 1, 2, \dots, L \tag{4}$$

$$fm_0 = 0 \tag{5}$$

$$fm_l = tm_l + M_l, \quad l = 1, 2, \dots, L \tag{6}$$

$$tm_l \geq l * T - w_l, \quad l = 1, 2, \dots, L \tag{7}$$

$$tm_l \leq l * T + w_l, \quad l = 1, 2, \dots, L \tag{8}$$

$$fm_{l-1} + \sum_{(i=1)}^n \sum_{(k=1)}^j p_i x_{ikl} = f_{jl}, \quad j = 1, 2, \dots, n; \quad l = 1, 2, \dots, L \tag{9}$$

$$\sum_{(i=1)}^n d_i x_{ijl} + A \left( 1 - \sum_{(i=1)}^n x_{ijl} \right) = q_{jl}, \quad j = 1, 2, \dots, n; \quad l = 1, 2, \dots, L \tag{10}$$

$$f_{jl} - q_{jl} - AU_{jl} \leq 0, \quad j = 1, 2, \dots, n; \quad l = 1, 2, \dots, L \tag{11}$$

$$x_{ijl}, U_{jl} \text{ binary variables } \in \{0, 1\}, \quad i, j = 1, 2, \dots, n; \quad l = 1, 2, \dots, \tag{12}$$

$$f_{jl}, q_{jl}, tm_l, fm_l \geq 0, \quad i, j = 1, 2, \dots, n \quad \& \quad l = 1, 2, \dots, L \tag{13}$$

Constraint (1) is the objective function to minimize the total number of tardy jobs. Constraints (2 and 3) ensure that

each job occupies only one different position and vice versa. Constraint (4) guarantees that the total processing time in each period  $l$  is in the allowable range between the starting time of maintenance  $l$  and the finishing time of its immediate predecessor  $l-1$ . Constraint (5) fixes the dummy maintenance as the first of the schedule. Constraints (6) to (8) are to calculate maintenance starting time and finishing time. Constraints (9) to (11) are to estimate the number of tardy jobs.

### C. NUMERICAL EXAMPLE

To validate the proposed mixed-integer linear programming model, an instance with 10 jobs ( $n = 10$ ) was tested by using a branch and cut method under CPLEX solver. Table 2 shows the input data for the given example. Figure 1 shows the Gantt chart for the optimal schedule.

The number of required maintenance depends on the total processing time and the presumptive time between two maintenances  $T$ . In Table 3 the maintenances input data for the given example.

### IV. ANT COLONY OPTIMIZATION (ACO)

ACO is one of the algorithms used for the discrete optimization problem, having been applied to solve many optimization problems in various domains. For single machine scheduling problems, we can cite the works of Liao and Juan [36].

This algorithm is inspired by the searching behavior of ants for food, which can be described as follows: A group of ants starts searching in several random directions from the nest (this process is initiated only once). During the passage on any path, the ants produce a chemical pheromone to mark their paths. When an ant finds a source of food, it takes

a quantity of it and returns to the nest by choosing the path with the largest amount of pheromone. The ant will then start searching from the nest again, choosing the path that contains the largest amount of pheromone. The amount of pheromone is updated every time period. The shortest path will always contain the largest amount of pheromone and therefore all the ants will move along it. To optimize the problem under study in this paper we adopted the ACO algorithm which was used in [36], [37]. The following subsections briefly describe the components of the proposed algorithm.

#### A. INITIALIZE THE PHEROMON

The initial pheromone is given by the following formula:

$$\tau_0 = K / (n * \sum U)$$

where K is constant, n is the number of jobs and  $\sum U$  is the number of tardy jobs by applying the initial heuristic.

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#### Algorithm 1 Heuristic for the Initial Solution

---

```

Function initial_sol();
Function Heuristic (i,j); /* apply Moore's
Algorithm then calculate heuristic desirability when
job i occupies position j */
1  $A_n \leftarrow$  order the job in a non – decreasing
of their due dates;
2  $i \leftarrow 1$ ;
while  $i \leq n$  do
3   if  $A_i$  have tardy job
4     Move the longest processing time into R set
5     Update the completion time in A set
6    $i++$ ;
End
7  $i \leftarrow 1$ ; /* Estimate the heuristic desirability Heuristic
(i,j)/
while  $i \leq n$  do
8    $j \leftarrow 1$ ;
while  $j \leq j \max$  do
9      $U \leftarrow$  number_of_Tardy for (Heuristic (i,j));
10     $\eta(i, u) \leftarrow \frac{1}{n*U}$ ;
11     $j++$ ;
End
12  $i++$ ;
end

```

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#### B. A HEURISTIC FOR THE INITIAL SOLUTIO

We implemented Moore's algorithm (Algorithm 1) as a heuristic for the initial solution. The advantage of using this rule is that it estimates the heuristic desirability better than a random search.

#### C. MAIN LOOP

Two parameters to control the termination conditions in the main loop (Algorithm 2): the maximum number of

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#### Algorithm 2 Main ACO Loop

---

```

Function main();
1  $i \leftarrow 1, j \leftarrow 0$ ;
while  $i \leq \text{Itemax} \ \&\& \ j \leq \text{Rmax}$  do
2    $k \leftarrow 1$ 
while  $k \leq \text{Number of ants}$  do
3     Sequence construction ();
4     Local search();
5     Pheromone updating();
6      $U'' \leftarrow$  number_of_Tardy for (ant(k),
Sequence);
if  $U''$  is better than U then
7        $U'' \leftarrow U$ ;
8        $j=0$ ;
else  $j++$ ;
9        $k++$ ;
10       $i++$ ;
end

```

---

non-improvement (Rmax), and the maximum number of iterations (Itemax). In each loop, the algorithm will construct a sequence of n jobs for the m ants, updating the pheromone, initiate local search for the sequence and save the best fit.

#### D. CONSTRUCT THE JOB SEQUENCE FOR EACH ANT

All ants start each loop with an empty sequence, and step by step each ant independently constructs the unscheduled jobs until a feasible solution is obtained. To choose the job j to be processed in the current position i it should be calculated according to the heuristic desirability  $\eta(i, u)$  of this position and the quantity of pheromones  $\tau_i(i, u)$  on the arc of that connection between the two. This choice will be made randomly, with a probability of choosing position j given by:

$$j = \begin{cases} \arg \max_{u \in U} \{ [\tau_i(i, u)]^\alpha [\eta(i, u)]^\beta \} & \text{if } q \leq q_0, \\ S & \text{otherwise,} \end{cases}$$

where: U is the set of unscheduled jobs, q is a random number generated between [0, 1],  $q_0$  is a given number between [0, 1] referring to the relative importance of exploitation,  $\alpha$  and  $\beta$  are two parameters that control the relative importance of pheromones and desirability. From the above formula if  $q \leq q_0$  the maximum value for the unscheduled job j is placed at position; otherwise, the job is selected according to the random variable S which itself is selected from the following probability:

$$p(i, j) = \frac{[\tau_i(i, u)]^\alpha [\eta(i, u)]^\beta}{\sum_{u \in U} [\tau_i(i, u)]^\alpha [\eta(i, u)]^\beta}$$

#### E. LOCAL SEARC

The procedure consists of swapping two jobs selected randomly, for the possibility of improvement (Algorithm 3).

TABLE 4. The generating conditions of test problems.

Group	Processing times	Due Dates	Tardiness factor T	The relative range of due dates R	Maintenance interval	Maintenance time
instances	U(10, 100)	U(a, b)	{0.2, 0.4,0.6}	{0.2,0.5,0. 8}	{0.3,0.4} for small sized {0.1,0.2} for large sized	U(c, d)

$$a = \sum p \left(1 - T - \frac{R}{2}\right) \quad \& \quad b = \sum p \left(1 - T + \frac{R}{2}\right)$$

$$c = 0.02 * \sum p \quad \& \quad d = 0.05 * \sum p$$

The time allowance for the starting maintenance  $w = 0.1 * \text{Maintenance interval}$ .

TABLE 5. Comparison of ACO with CPLEX.

T	R	I	CPU_Time											
			n=10		n=12		CPLEX				ACO			
			Gap	NO	Gap	NO	Ave.	Max.	Min.	Std.	Ave.	Max.	Min.	Std.
0.2	0.2	0.3	0	10	0	10	59.71	205.89	12.22	73.59	0.12	0.14	0.10	0.01
			0.4	0	10	0	10	71.22	341.84	11.89	103.35	0.10	0.12	0.08
0.2	0.5	0.3	0	10	0	10	16.14	30.16	11.33	7.22	0.13	0.15	0.11	0.02
			0.4	0	10	0	10	101.34	720.77	10.85	224.27	0.11	0.14	0.09
0.2	0.8	0.3	0	10	0	10	12.35	20.49	10.64	3.01	0.14	0.16	0.12	0.01
			0.4	0	10	0	10	18.51	86.70	8.98	23.98	0.12	0.15	0.11
0.4	0.2	0.3	0	10	0	10	68.46	415.22	12.37	129.89	0.12	0.13	0.10	0.01
			0.4	0	10	0	10	159.3	676.98	19.66	207.35	0.11	0.12	0.10
0.4	0.5	0.3	0	10	0	10	77.2	374.66	13.81	123.47	0.13	0.14	0.12	0.01
			0.4	0	10	0	10	37.59	194.20	12.29	56.70	0.11	0.12	0.10
0.4	0.8	0.3	0	10	0	10	48.12	160.91	13.01	54.45	0.13	0.15	0.11	0.01
			0.4	0	10	0	10	33.10	79.19	11.48	26.26	0.11	0.13	0.09
0.6	0.2	0.3	0	10	0	10	183.51	664.80	14.72	229.96	0.12	0.14	0.11	0.01
			0.4	0	10	0	10	61.08	232.32	11.20	84.50	0.10	0.13	0.08
0.6	0.5	0.3	0	10	0	10	20.55	68.96	11.01	17.99	0.13	0.14	0.11	0.01
			0.4	0	10	0	10	148.39	731.41	12.83	226.48	0.11	0.12	0.10
0.6	0.8	0.3	0	10	0	10	27.83	114.76	10.72	33.41	0.12	0.15	0.05	0.03
			0.4	0	10	0	10	90.80	614.70	12.36	189.55	0.12	0.13	0.10

**Gap:** is the average relative deviation of the solution from optimal solutions, which were obtained by CPLEX.

**NO:** Number of instances (out of 10 instances) for which the algorithm found optimal solutions.

**Ave:** the average consumed time to obtain the solution for the 10 instances.

**Max:** the maximum consumed time to obtain the solution form the 10 instances.

**Min:** the minimum consumed time to obtain the solution form the 10 instances.

**Std:** the standard deviation of the consumed time from the average.

F. UPDATING THE PHEROMON

At the end of each cycle (all jobs are scheduled for each ant), the pheromone variables are updated according to

the formula:

$$\tau_t(i, j) = (1 - \rho) \tau_t(i, j) + \rho \tau_{t-1}(i, j)$$

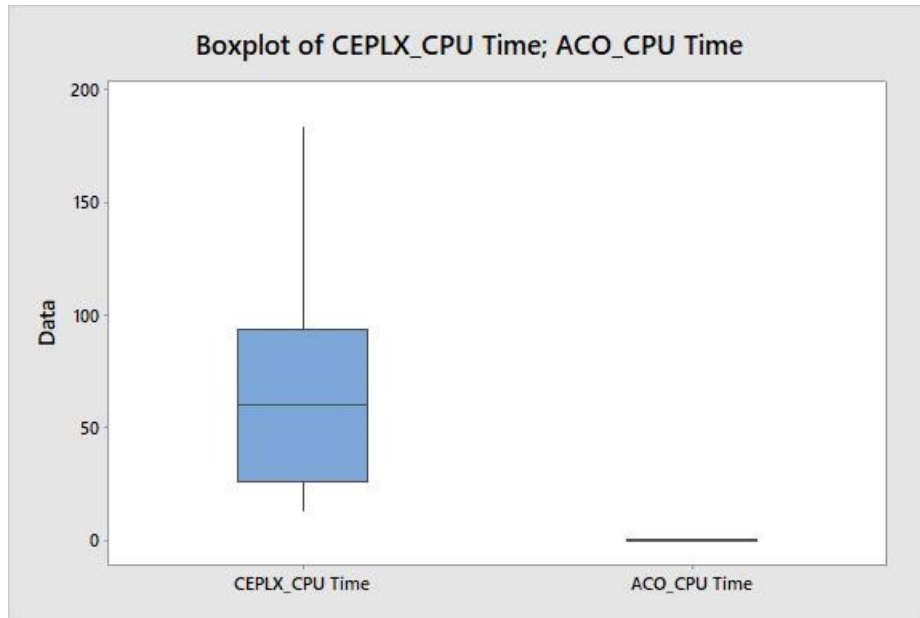


FIGURE 2. Boxplot of consumed CPU time for small-sized instances.

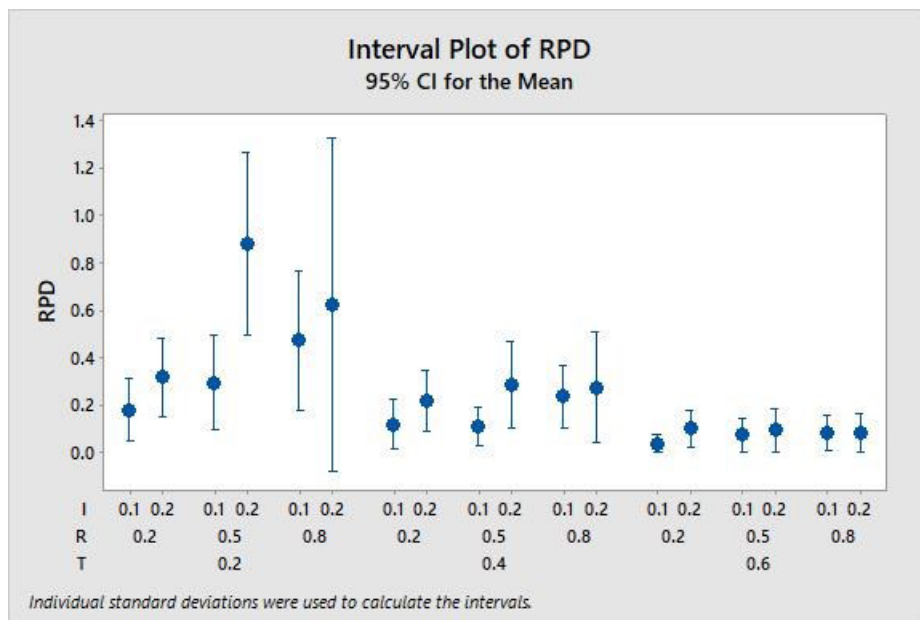


FIGURE 3. Interval Plot of relative percentage deviation for large-size instances.

where  $\rho \in [0, 1]$  represents the coefficient of the evaporation rate of pheromones on the arcs between the time  $t$  and time  $(t-1)$ .

V. EXPERIMENTAL RESULT

Two algorithms, ACO and Moore’s, were coded in C and run on a PC including an Intel Core i3 CPU running at 2.53 GHz and configured with 3 GB of RAM. To test the efficiency and the effectiveness of the ACO algorithm, a set of data was generated using the parameters that provide [22] ten problem instances for each combination. The parameters are listed in Table 4.

For regulation, the algorithm parameters for a series of pilot runs using the algorithm were conducted, including temporarily stopping the part of the local search because it introduced a noise factor for the algorithm parameters. The recommended values for the problem are as follows: Maximum number of iterations = 100, Maximum number of non-improvement = 50, Number of ants = 10,  $\alpha = 0.1$ ,  $\beta = 0.8$ ,  $\rho = 0.05$ ,  $q_0 = 0.9$ .

The computational results are summarized in Tables 5 and 6.

For small-sized instances, those with 10 to 12 jobs, optimal solutions were obtained from CPLEX solver with a one hour

TABLE 6. Comparison of ACO with moore’s algorithm.

T, R	I	n=50						n=100						CPU TIME	
		RPD				HC*	ACO*	RPD				HC*	ACO*	HC	ACO
		Ave.	Max.	Min.	Std.			Ave.	Max.	Min.	Std.				
0.2,0.2	0.1	0.19	0.62	0.00	0.22	0	6	0.17	0.88	0.00	0.34	0	3	0.07	0.89
	0.2	0.36	1.00	0.00	0.38	0	7	0.28	0.84	0.00	0.33	0	7	0.06	0.58
0.2,0.5	0.1	0.46	1.36	0.00	0.53	0	8	0.13	0.50	0.00	0.20	0	5	0.06	0.85
	0.2	0.91	2.75	0.00	0.92	0	8	0.86	1.91	0.00	0.75	0	8	0.06	0.64
0.2,0.8	0.1	0.78	1.75	0.00	0.68	0	7	0.17	1.28	0.00	0.41	0	2	0.08	0.90
	0.2	1.25	5.00	0.00	1.96	0	4	0.00	0.00	0.00	0.00	0	0	0.06	0.71
0.4,0.2	0.1	0.20	0.82	0.00	0.29	0	5	0.04	0.29	0.00	0.09	0	3	0.06	0.88
	0.2	0.21	0.71	0.00	0.30	0	4	0.23	0.81	0.00	0.26	0	6	0.06	0.61
0.4,0.5	0.1	0.14	0.50	0.00	0.16	0	7	0.09	0.49	0.00	0.18	0	2	0.06	0.87
	0.2	0.17	0.80	0.00	0.27	0	5	0.40	1.28	0.00	0.46	0	6	0.06	0.64
0.4,0.8	0.1	0.17	0.50	0.00	0.20	0	7	0.30	0.87	0.00	0.34	0	6	0.07	0.87
	0.2	0.22	1.29	0.00	0.40	0	5	0.33	1.80	0.00	0.59	0	5	0.06	0.70
0.6,0.2	0.1	0.04	0.24	0.00	0.08	0	3	0.03	0.26	0.00	0.08	0	3	0.06	0.95
	0.2	0.10	0.43	0.00	0.14	0	5	0.10	0.51	0.00	0.20	0	3	0.08	0.66
0.6,0.5	0.1	0.14	0.52	0.00	0.19	0	4	0.01	0.09	0.00	0.03	0	1	0.06	0.99
	0.2	0.14	0.67	0.00	0.24	0	5	0.06	0.41	0.00	0.13	0	3	0.06	0.68
0.6,0.8	0.1	0.10	0.50	0.00	0.18	0	3	0.07	0.38	0.00	0.13	0	3	0.05	0.93
	0.2	0.11	0.64	0.00	0.21	0	4	0.07	0.41	0.00	0.14	0	2	0.05	0.22

HC\*: Number of instances (out of 10 instances) for which Moore’s algorithm gave better solutions than ACO.

ACO\*: Number of instances (out of 10 instances) for which ACO gave better solutions than Moore’s algorithm.

Ave: the average relative deviation of the solution from the best-found solutions for the 10 instances.

Max: the maximum relative deviation of the solution from the best-found solutions for the 10 instances.

Min: the minimum relative deviation of the solution from the best-found solutions for the 10 instances.

Std: the standard deviation of the relative deviation from the average.

Algorithm 3 Local Searchc

```

Function Local search ();
1  i ← 1;
  while i ≤ i_max do
2    j ← Rand() % n;
3    k ← Rand() % n;
    if ( j! = k)
4      Swap sequence(k,j);
5      U'' ← number_of_Tardy for
      (ant, sequence(k, j));
      if U'' is better than U then
6        U'' ← U;
7        Sequence ← Swap sequence(j, k);
8    i ++;
  end
    
```

run time limitation. As Table 5 shows, the proposed ACO was able to obtain the exact solutions within reasonable CPU times and outperformed the CPLEX solver CPU as shown in Figure 2. Results of the test on large-size instances, those with 50 to 100 jobs, show that the ACO outperforms Moore’s algorithm for all the instances tested, as shown in Table 6.

In addition, to assess the behavior of the algorithm with different parameters, Figure 3 shows the impact of tardiness factor (T), the relative range of due dates (R) and Maintenance interval factor (I) on the Average Relative Percentage Devotion (ARPD).

VI. CONCLUSION AND RESULTS DISCUSSION

This study proposed two methods to minimize the total number of tardy jobs when scheduling a set of jobs on a single



machine influenced by intervention dates of periodic maintenance actions, with different durations and time windows for starting the maintenance actions. The first method gives an exact solution by using CPLEX solver to solve the proposed mixed-integer linear programming model. A near-optimal solution method using an ACO algorithm has also been presented. Different sets of data were generated to validate and test the quality of the proposed algorithms. The results showed that the ACO algorithm, which was able to obtain exact solutions in reasonable CPU times, outperformed the CPLEX solver. In addition, when the ACO compared to Moore's algorithm, the results showed that the ACO outperforms Moore's algorithm for all the instances tested. It can be concluded that the developed AC is very efficient and effective in solving the problem considered in this paper.

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