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Temperature Sensing Characteristics and Long Term Stability of Power LEDs Used for Voltage vs. Junction Temperature Measurements and Related Procedure

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ABSTRACT A detailed study about the direct measurement of junction temperature T_J of off-the-shelf power light emitting diodes (LED) is presented. The linear dependence on temperature of the voltage drop across the device terminals at a constant current is in particular exploited and fully characterized, in the temperature range from $T = 35\text{ }^\circ\text{C}$ to $135\text{ }^\circ\text{C}$, with tests repeated at one thousand different probe currents. The accurate experimental data, obtained on several LED samples bearing two different part numbers, are reported, showing that they exhibit a high degree of linearity in wide current ranges, a circumstance that allows for a fast and reliable calibration as sensors. The measurement error is also fully characterized in terms of repeatability and stability over time, with measurements repeated after 600, 900, 1200 and 1800 hours of applied electro-thermal stress, demonstrating that the relevant sensor parameters stabilize after a few hundred hours of operation. A full set of parameters is provided for the two device models, allowing the direct use of each LED for the self-monitoring of the junction temperature and ensure compliance with their safe operating area over time. Moreover, a procedure and a simple circuit for the real time measurement of T_J , while the LED is on, are presented. The procedure does not require a stable current source, and relies instead on the application of a sub-threshold current ramp for such a short time that the change in the output light is not perceived by human eyes.

INDEX TERMS LED, light emitting diodes, junction temperature, temperature sensors, diode sensors.

I. INTRODUCTION

The Solid State Lighting (SSL) technology has definitively emerged as the most efficient and long lasting technology for converting electricity into light in almost every application context, from luminaries to flat panel displays, to wide area image projection. In fact, it has brought significant advancements in terms of energy and cost savings. Light emitting diodes (LEDs) are the heart of SSL lighting products and can provide long lifetimes that last well beyond thousands of hours of operation, much longer than most conventional light sources. Moreover, LEDs exhibit the additional advantage that, in most cases, instead of sharply falling to zero, the light

intensity output may slowly fade or the color slowly degrade as the end of life is approaching [1]–[5].

It is well known, however, that LED performances, at least in terms of intensity, lifetime and emission spectrum, degrade faster as their operation temperature increases above certain limits [6]–[12], which unfortunately are set well below those of incandescent bulbs and even of fluorescent lamps. These limits can also be easily reached during normal operation because, despite their excellent conversion efficiency, the LEDs heat up quickly due to their very limited active area and consequent high power density. It turns out that high quality solid-state light sources must always adopt more or less complex temperature control strategies, including passive or active cooling methods [13].

The main thermal parameter of an LED is its junction temperature, T_J . Many methods have been proposed in the

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literature for monitoring the junction temperature based on LED electroluminescence [14], Raman spectroscopy [15], [16], light spectrum [17], liquid crystal thermography [18] or on the use of external temperature sensors that allow estimating the LED junction temperature [19], [20]. All these methods [14]–[20] require an additional external sensor for extracting the actual T_J .

Normally, T_J is estimated starting from the thermally dissipated power P_D and the thermal resistance R_{Θ} of the device, being in fact $T_J = P_D \cdot R_{\Theta} + T_X$, with T_X the environment temperature [21], [22]. However, knowing P_D and R_{Θ} is not straightforward as it may seem, because the former is only a small fraction of the overall electric power dissipated by an LED, with the biggest part converted into light, while measuring the thermal resistance involves complex procedures and its value may change over time and with temperature itself [22].

There are however other ways to monitor an LED T_J , consisting of using its own electrical parameters, e.g. the reverse saturation current I_S [23] or the forward voltage V_F under a constant current [24]–[27], that are in fact both temperature dependent.

In this work we analyze a large set of experimental data showing that the V_F vs. T_J relationship can be optimized to perform an excellent linearity, allowing to easily and reliably measure the internal device temperature, without involving an external temperature sensor. The technique is developed starting from previous studies carried out on diodes of various types and sizes [28]–[31], and is here shown to be perfectly suitable also for LEDs, and further improved to make the measurement faster and the measuring circuit simpler. It is worth noting that a highly linear dependence in a wide temperature range allows the simplest experimental pre-calibration procedure of the device, which can be in fact carried out at just two temperatures.

Once the LED is calibrated, the procedure adopted hereafter allows to calculate T_J by dropping the standard fixed-current approach [22], [24]–[31], and launching instead a current ramp, within an appropriate range, during which random current-voltage measurements are performed until a measurement at the desired probe current is detected.

The sensor sensitivity, together with the linearity of the output characteristics, are analyzed in a wide range of bias currents and temperatures, from 35 °C to 135 °C. The experimental measurements, repeated on 6+6 devices with two different part number, demonstrate the possibility of implementing the new method for monitoring and controlling the LED junction temperature in order to increase its lifetime and performances.

A microcontroller-based circuit is finally presented performing the measurement procedure at regular intervals. The acquisition lasts less than 10 ms, a short enough time to have no practical effects on the light perceived by the human eye.

The paper is organized as follows. In Section II, the linear dependence between the forward voltage falling on an LED and its junction temperature, the experimental setup

and the characterization method are described. Section III reports the experimental results with particular attention to the temperature sensor performance, *i.e.* linearity, sensitivity and temperature error for a single LED.

Afterward, the average characteristic parameters are calculated for each device type, after several operation intervals. In Section IV, an example of a practical circuit for a real-time measurement of the junction temperature of an LED is presented. Finally, conclusions are drawn in Section V.

II. EXPERIMENTAL SETUP AND CHARACTERIZATION METHOD

As well known, the electrical characteristics of power LEDs are similar to those of all diodes. Every diode, either p-i-n, p-n or Schottky, can be used as a temperature sensor when it is crossed by a known current, I_F , kept constant over the whole temperature measuring range [29]–[33]. In fact, a relationship exists in this case between the voltage drop appearing at the junction and T_J , allowing an indirect and accurate temperature measurement. To avoid self-heating effects, the sensor must be biased at low currents, which also optimizes power consumption. For accurate measurements, this relationship must be pre-determined experimentally. However, to understand its origin and the key parameters involved, one can recall that, in its simplest formulation, the diode current I_F at a given applied voltage, V_F , can be modeled by the following formula:

$$I_F = I_S \left(e^{\frac{q(V_F - R_S I_F)}{\eta k T_A}} - 1 \right), \quad (1)$$

where η is the ideality factor, I_S is the saturation current, R_S is a stray series resistance, q is the electron charge, k is the Boltzmann constant and T_A is the device absolute temperature. Note that in (1) V_F is the overall voltage drop externally appearing at the device terminals, while $(V_F - R_S \cdot I_F)$ represents the voltage drop internally appearing at the real device junction. When the diode is forward biased and $q(V_F - R_S \cdot I_F) \gg \eta k T_A$, the relationship between V_F and T_A can be obtained from (1):

$$V_F = \frac{k T_A}{q} \eta \ln \left(\frac{I_F}{I_S} \right) + R_S I_F. \quad (2)$$

In (2), T_A explicitly appears as a linear term, but it also implicitly and non-linearly affects I_S and R_S , while $\eta = 1$ if the device operates in the diffusion regime. However, it has been demonstrated in many diodes [29]–[31], [34] that an excellent linearity between V_F and T_A can be reached, in a wide temperature range, by properly choosing I_F .

In particular, if R_S and I_F are sufficiently small, their product is negligible, and by explicating I_S as [35]:

$$I_S = C T_A^\alpha e^{-\frac{E_g}{k T}}, \quad (3)$$

where C and α are constants, E_g is the extrapolated energy bandgap at 0 K, from (2) we find:

$$V_F = \eta \frac{k}{q} \left[T_A (\ln I_F - \ln C) - \alpha T_A \ln T_A + \frac{E_g}{k} \right]. \quad (4)$$

At a fixed I_F , and constant η , C and α , the only non-linear term in (4) is $\alpha T_A \ln T_A$. However, it can be shown that this term has in fact a high degree of linearity in the temperature range of interest for LEDs, *i.e.* from room temperature to 420 K. It turns out that (4) shows in turn a high degree of linearity with T_A in the same range.

In our study, we focused on two commercial white light power LEDs, denoted hereafter as LED-A [36] and LED-B [37], having respectively a normal operation current of 700 mA at 3.05 V and 1050 mA at 3.02 V. The maximum working temperature is 150 °C for both types.

Firstly, a set of measurements was carried out to identify the most suitable bias current range where these LEDs can work as linear temperature sensors. The used setup was already described in [38]. The tests, made on six devices of each type, consisted in increasing and decreasing the temperature in steps of 10 °C in a thermostatic oven (Fratelli Galli G-2100 [39]) with a regulation accuracy of ± 1 °C. A PT100 temperature sensor (with an accuracy of 0.2 °C) was also tightly placed in contact with the printed circuit board (PCB), made of alumina, hosting the devices under test (DUT), in order to monitor their exact temperature inside the oven, which was gradually varied from 25 °C up to 135 °C and *vice versa*. The current-voltage (I_F - V_F) characteristics were measured with an Agilent 4155C semiconductor parameters analyzer [40], programmed for providing a bias current (I_F) gradually rising from 10 μ A up to 10 mA, in steps of 10 μ A. Note that at these low currents the LEDs emit a very weak radiation, or they give no emission at all. At each step, measurements started only after the settling of a stable temperature for several minutes.

The current-voltage-temperature I_F - V_F - T characteristics were subsequently elaborated and the linear fitting was calculated in order to assess the degree of linearity of the response, the device temperature sensitivity and the root mean square error.

Finally, as better detailed in the next section, the LEDs were driven at a normal operating current and a temperature of 80 °C for 1800 h, and the current-voltage-temperature measurements were repeated to verify the long-term response of the devices.

III. EXPERIMENTAL RESULTS

A. VOLTAGE-TEMPERATURE CHARACTERISTICS

The dc bias current, I_F , was varied in a range from 10 μ A to 10 mA, in steps of 10 μ A, and the corresponding voltage drop V_F across the LED was measured. Typical I_F - V_F characteristics for both LED types are reported in Fig. 1, measured in the temperature range from 25 °C to 135 °C, in steps of 10 °C.

Typical voltage-temperature (V_F - T) characteristics for both LED types, at several probe currents (I_F), are shown in Fig. 2. As expected, at all currents the voltage drop decreases by increasing the temperature. Moreover, in Fig. 2 the linear fittings are also reported, showing that the LED responses have an excellent degree of linearity.

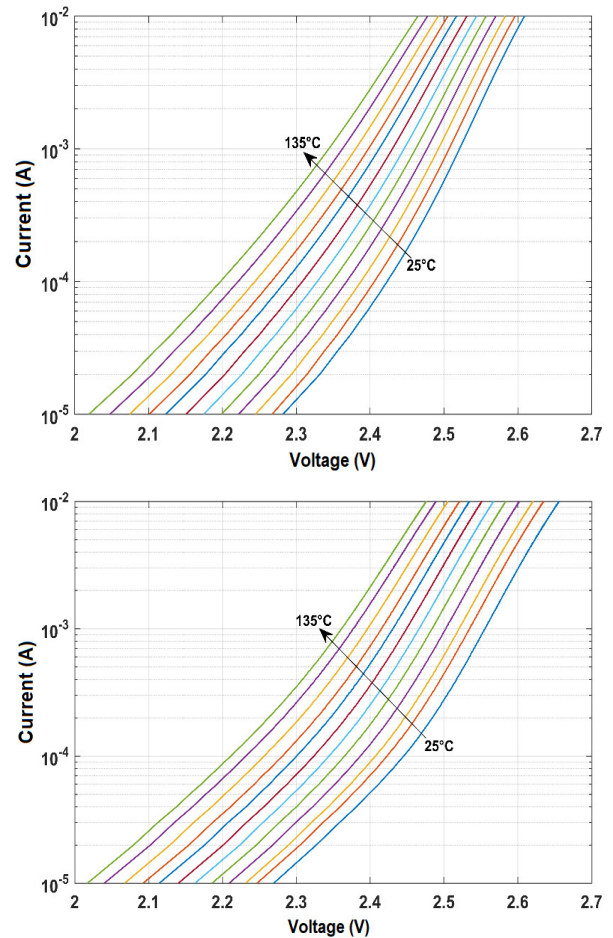


FIGURE 1. Typical current-voltage characteristics of LED-A (top graph) and LED-B (bottom graph) types measured between 25 and 135 °C, in steps of 10° C.

The coefficient of determination R^2 was calculated to evaluate the agreement between the experimental data V_F vs. T at each probe current and their best linear fit, $f_L(T)$. In particular, R^2 allows quantifying the sensor linearity goodness when the experimental data are fitted with a linear model. It was calculated by the following formula [41]:

$$R^2 = 1 - \frac{\sum_{i=1}^n (V_{F,i} - f_{L,i})^2}{\sum_{i=1}^n (V_{F,i} - \bar{V}_F)^2}, \quad (5)$$

where n is the number of the experimental points, $V_{F,i}$ and $f_{L,i}$ are the values provided by the actual measure and by the best linear fit model, respectively, at the i -th temperature, and \bar{V}_F is the average of all measurements.

Another important parameter characterizing the goodness of the linear approximation of a temperature sensor is the temperature error $rmse(^{\circ}C)$, between $f_L(T)$ and the experimental data, evaluated as:

$$rmse = \frac{rmse_{V_F}}{S} = \frac{\sqrt{\frac{\sum_{i=1}^n (V_{F,i} - f_{L,i})^2}{n}}}{S}, \quad (6)$$

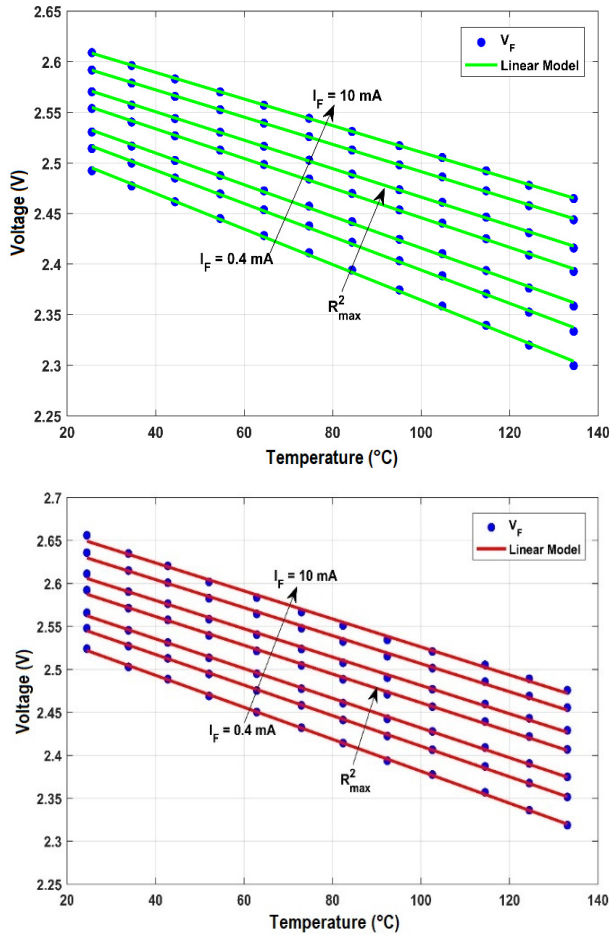


FIGURE 2. Measured (dots) forward voltage V_F versus temperature at seven probe currents I_F (0.4 mA, 0.8 mA, 1.3 mA, 2.4 mA, 3.8 mA, 6.6 mA and 10 mA), for the LED-A (top graph) and LED-B (bottom graph) of Fig. 1. Experimental data are fitted with their best calculated linear models (lines). In both graphs, the R^2_{max} arrow indicate the curve with the highest linearity.

where $rmse_{V_F}$ (V) is the root mean square error of the diode voltage drop, and S (V/°C) is the sensor sensitivity, obtained from the slope of $f_L(T)$. In the temperature range between 25 °C and 135 °C, both samples show a high degree of linearity, as predicated by (4), with an $R^2 > 0.999$ in a wide range of currents (Fig. 2). In particular, the highest linearity with the lowest error is obtained at $I_F \approx 0.4$ mA for LED-A ($R^2 = 0.9998$), while for LED-B the best probe current is $I_F \approx 0.5$ mA ($R^2 = 0.9997$).

B. EVALUATION OF THE AVERAGE SENSING PARAMETERS FOR EACH LED TYPE

After showing the two LEDs’ ability to be used as highly linear temperature sensors, the average characteristics of each LED type was determined on more samples by proceeding with a long campaign of measurements. Six new devices of each type were in fact characterized with the same procedure described above.

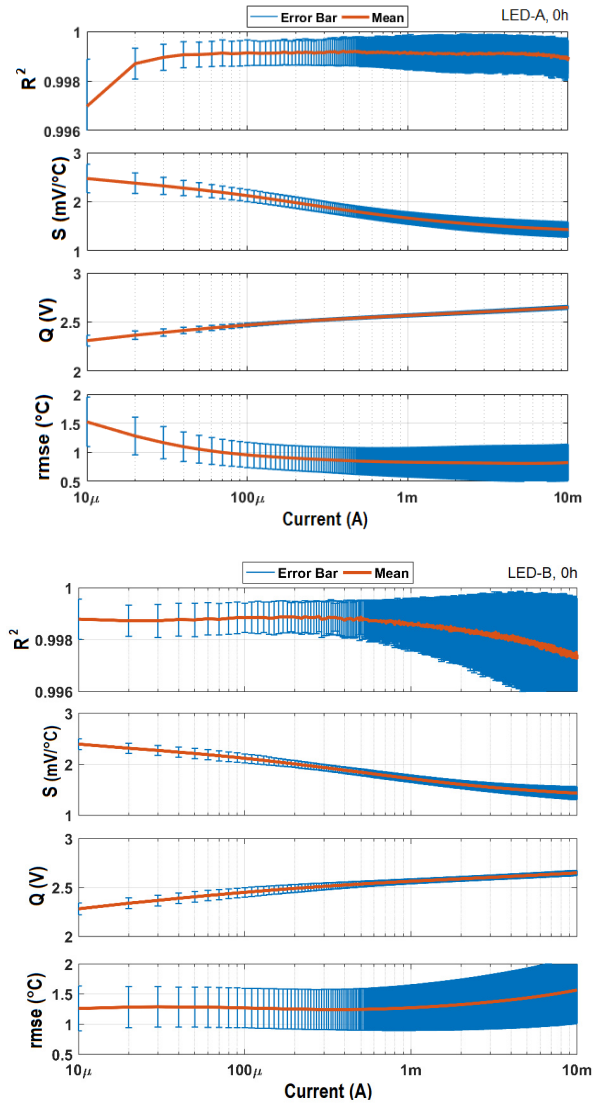


FIGURE 3. Experimental mean values of R^2 , sensitivity S , intercept Q , and root mean square error $rmse$ of the characterized LED-A (top) and LED-B (bottom) samples. Six new samples were characterized for each LED type.

The experimentally determined mean values of S , R^2 and $rmse$, as they were defined above, are shown in Fig. 3 both for LED-A and LED-B devices, together with the corresponding error bars. The reported values were calculated as the arithmetic mean of the experimental values measured on all samples of each LED type, at each probe current. The plots also include the parameter Q (V), which represents the intercept with the x -axis of the linear best fits of Fig. 2, so that the S and Q values provided in Fig. 3 allow to express, at any desired probe current, the correct V_F vs. T relationship in the form:

$$V_F = -S \cdot T + Q, \tag{7}$$

and therefore calculate the actual junction temperature by simply measuring the forward voltage drop, with an approximation given by the $rmse$ provided in the same figure.

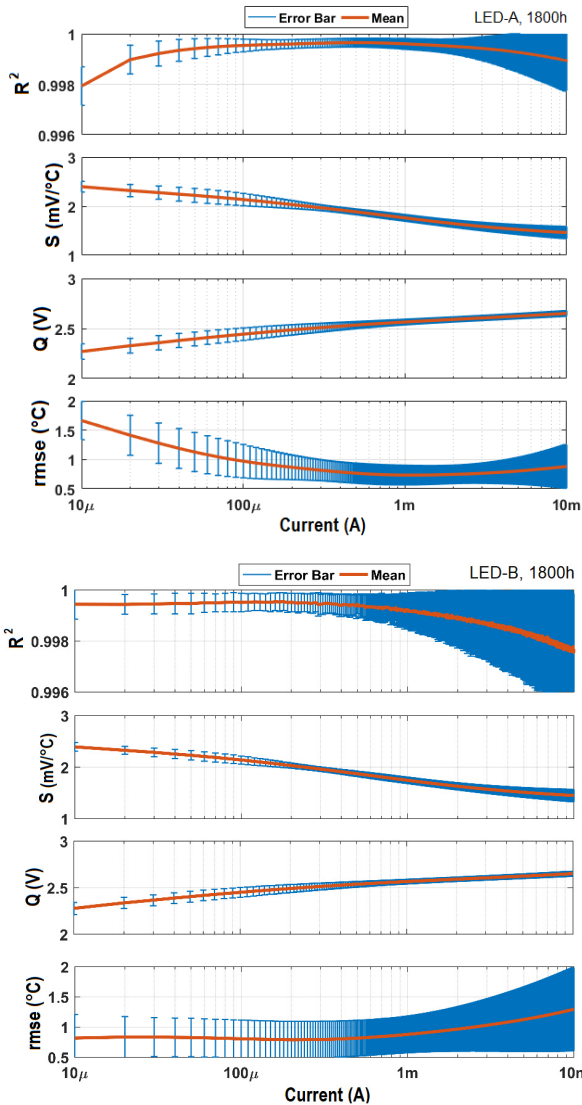


FIGURE 4. Experimental mean values and error bars of R^2 , sensitivity S , intercept Q , and root mean square error $rmse$ of the characterized LED-A (top) and LED-B (bottom) samples of Fig. 3 after 1800 h of operation at $I_F = 500$ mA and a temperature of 80 °C.

C. THERMAL STABILITY

To test the sensor stability over time, measurements were repeated after 600, 900, 1200 and 1800 hours of operation at a bias current of 500 mA and a temperature of 80 °C. After each time period, the LEDs were again fully characterized between room temperature and 135 °C, in the whole current range (10 μ A to 10 mA).

The experimentally determined values of S , Q , R^2 and $rmse$ after 1800 h stress are shown in Fig. 4. The curves do not show an evident deviation from those of new devices (Fig. 3). This is even more clear in Fig. 5, where the same average parameters are directly compared. It also shows that the sensor linearity and error are stable, or even improve with time.

For comparison purposes, the sensing parameters of LED-A, averaged over the six samples, are detailed

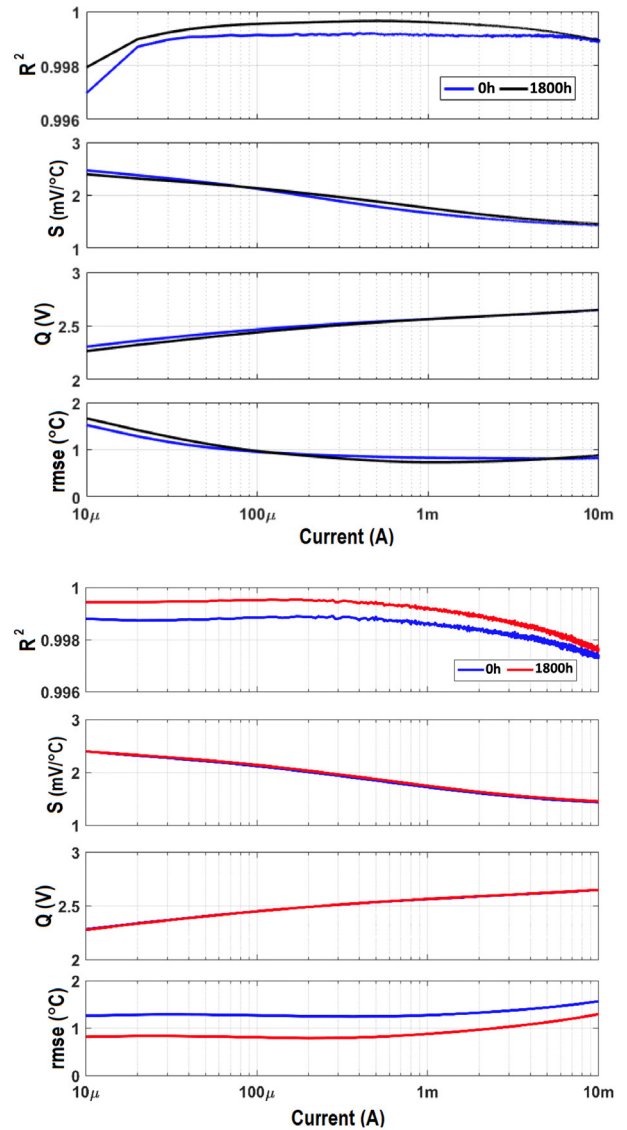


FIGURE 5. Comparison between the experimental mean values of R^2 , sensitivity S , intercept Q , and root mean square error $rmse$ of the characterized LED-A (top) and LED-B (bottom) samples of Fig. 3 at 0 h and after 1800 h of operation at $I_F = 500$ mA and a temperature of 80 °C.

in Table 2 at several probe currents and after a 1800 h stress. At $I_F = 0.6$ mA this LED type shows the best linearity ($R^2 = 0.99964$) and the lowest error ($rmse = 0.75$ °C). A list of the same characteristic values is reported in Table 3 for LED-B type, which shows the best performances at a probe current of 0.3 mA. It is worthwhile noting that an error of the order of 1 °C can be considered small enough for LED temperature monitoring in lighting applications, also considering that we are directly measuring T_J , and not a somehow correlated temperature. Given the small $rmse$, we can expect that these values, obtained on a limited set of devices, would be confirmed on larger sample sets, at least as long as high quality LEDs are concerned.

In order to derive the temperature from the forward voltage appearing on the device, it is highly desirable that the linear

TABLE 1. Table of symbols and units.

Symbol	Units	Quantity
E_g	eV	Energy gap
$f_L(T)$	V	Best linear approximation of experimental V_F vs. T (at fixed I_F)
$f_{L,i}$	V	V_F at the i -th temperature as calculated by the linear model
I_F	A	LED bias current
$I_{F,set}$	A	Desired probe current for LED
I_S	A	reverse saturation current
P_D	W	Power dissipated on LED
q	eV	Electron charge
Q	V	x-axis intercept of the best linear approximation $f_L(T)$
R^2	-	Coefficient of determination of the linear regression (5)
R_S	Ω	Internal stray resistance of LED
R_{θ}	K/W	Thermal resistance of LED (junction to environment)
$rmse$	$^{\circ}C$	Root mean square error of T
$rmse_{VF}$	V	Root mean square error of measured V_F
S	V/ $^{\circ}C$	LED sensitivity, dV_F/dT_J
T	$^{\circ}C$	Device temperature in $^{\circ}C$
T_A	K	Absolute temperature
T_J	$^{\circ}C$	LED junction temperature
T_X	$^{\circ}C$	Environment temperature
V_F	V	Forward voltage drop at LED terminals
$V_{F,i}$	V	Experimental V_F at the i -th temperature
\bar{V}_F	V	Average V_F
$V_{F,n}$	V	Voltage drop across a series of n LEDs
η	-	Current ideality factor

TABLE 2. Sensing parameters of LED-A calculated after a stress of 1800h at 500mA and 80°C.

I_F (mA)	R^2	S (mV/ $^{\circ}C$)	Q (mV)	$rmse$ ($^{\circ}C$)
0.1	0.99954	2.134	2.444	0.97
0.6	0.99964	1.835	2.547	0.75
2.0	0.99949	1.645	2.591	0.76
5.0	0.99928	1.525	2.624	0.80
10.0	0.99894	1.462	2.651	0.88

TABLE 3. Sensing parameters of LED-B calculated after a stress of 1800h at 500mA and 80°C.

I_F (mA)	R^2	S (mV/ $^{\circ}C$)	Q (mV)	$rmse$ ($^{\circ}C$)
0.1	0.99950	2.139	2.449	0.80
0.3	0.99951	1.975	2.508	0.79
2.0	0.99895	1.631	2.590	0.96
5.0	0.99833	1.513	2.623	1.12
10.0	0.99764	1.451	2.649	1.29

relationship (7) remains stable over time, once a proper probe current and the associate S and Q parameters are chosen. The stability of the LED types considered in this work is highlighted in Fig. 6, cumulatively showing the experimental points V_F vs. T at a probe current of 0.5 mA, of new devices and at the end of each stress time periods. The plots

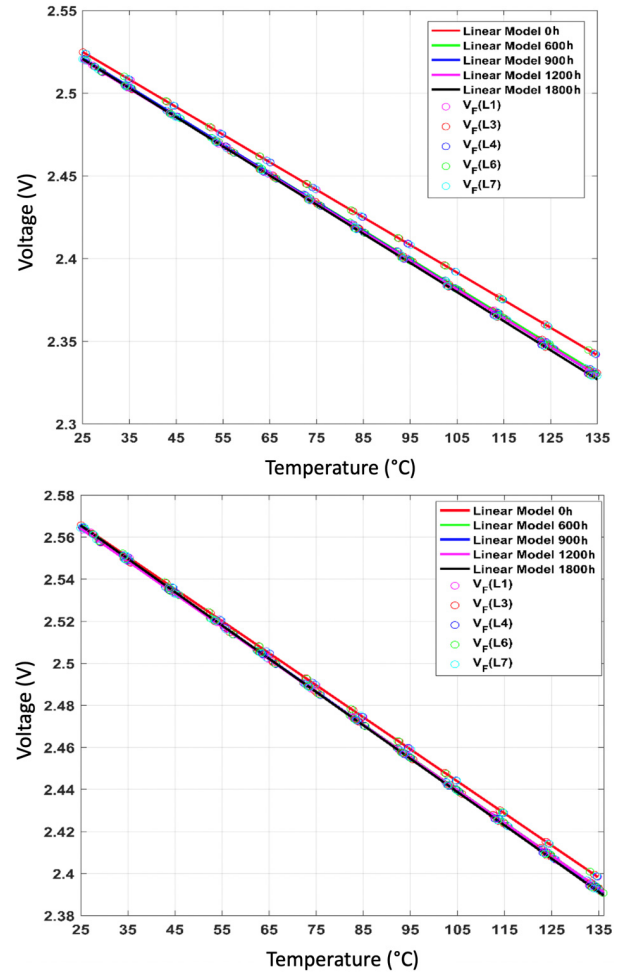


FIGURE 6. Average measured forward voltage V_F (circles) versus temperature at a probe current $I_F = 0.5$ mA for LED-A (top graph) and LED-B (bottom graph) devices. Experimental data are fitted with their best calculated linear models (lines).

demonstrate that the sensing characteristics of the devices stabilize after a few hundred hours of operation.

The high linearity and small $rmse$ shown by these devices allow to assume that this technique could be also applied to a series-connected LEDs, as frequently used in luminaires. In this case, the input-output characteristics for n-series-connected LEDs can be described by the following equation:

$$V_{F,n} = n \cdot (-S \cdot T + Q), \tag{8}$$

where $V_{F,n}$ is the overall voltage appearing across the series, n is the number of LEDs, and S and Q are respectively the average sensitivity and intercept of the y-axis calculated for the LED type. Of course, in this case T represents the average value among the different junction temperatures.

IV. LED JUNCTION TEMPERATURE MEASUREMENT CIRCUIT

A. CIRCUIT

A practical circuit performing the LED junction temperature measurement is shown in Fig. 7. The measurement routine is

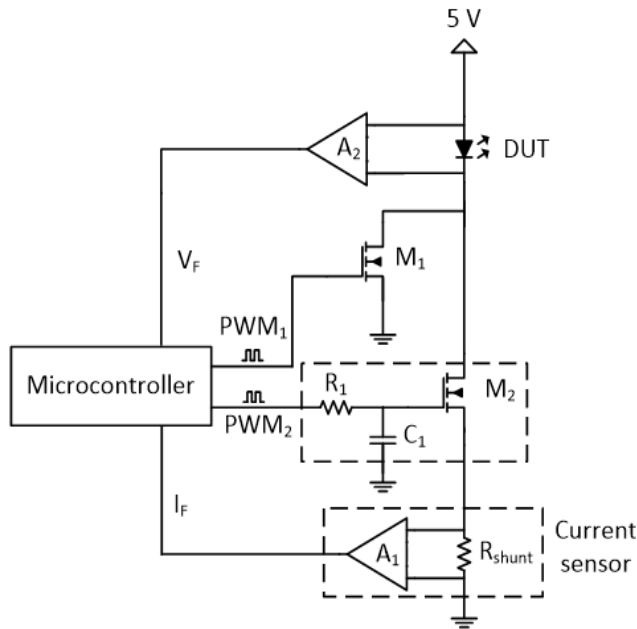


FIGURE 7. LED temperature measurement circuit.

basically governed by an ST NUCLEO-F401RE board [42] mounting an STM32F401RE microcontroller. A firmware was developed to generate two pulse-width modulation signals (PWM_1 and PWM_2) with a frequency of 5 kHz. PWM_1 is used to control the gate of MOSFET M_1 that forward biases the LED during normal operation (LED fully on). In this phase M_2 is off, the current sensor A_1 (Texas Instrument INA285 [43]), with a $1\ \Omega$ shunt-resistor, measures the current through the LED, while the duty cycle of PWM_1 is continuously adjusted to hold this current nearby the desired value, e.g. $I_F = 500\ \text{mA}$.

At the start of the temperature measurement routine, M_1 is turned off (duty cycle of PWM_1 set to zero), while PWM_2 drives the LED by biasing the gate of M_2 through a low pass filter ($R_1 = 2\ \text{k}\Omega$, $C_1 = 5\ \mu\text{F}$). During this phase, which lasts less than 10 ms, the duty cycle of PWM_2 increases progressively in order to bias the LED with a current ramp comprised in a given range, e.g. $0.1\ \text{mA} < I_F < 1\ \text{mA}$. At each sampling time of the analog-digital converter, the actual value of the I_F flowing through the device is measured through A_1 , while the corresponding voltages V_F across the LED is amplified through an instrumentation amplifier A_2 (Analog Devices LT1167 [44]).

The implemented firmware therefore calculates the junction temperature through the following steps:

- 1) while the LED is on, at some time PWM_1 is turned off and a few milliseconds long PWM_2 sequence, with a growing duty-cycle, is applied to M_2 ;
- 2) the values of the actual flowing currents I_F and of the corresponding voltages V_F across the DUT are measured through A_1 and A_2 of Fig. 7 and sampled by the microcontroller with the integrated 12-bit analog-digital converter;

- 3) the microcontroller then selects the (V_F, I_F) couple corresponding to a previously identified probe current $I_{F,set}$. If no measure is found at $I_{F,set}$, the procedure is repeated a few hundred milliseconds later;
- 4) the junction temperature T_J is calculated using (7), for which the values of sensitivity S and of the intercepts with the y axis of the output characteristic Q were previously stored in the microcontroller.

The steps used for temperature calculation are summarized in the flowchart of Fig. 8. This technique avoids the use of a temperature compensated current source to drive the LED at the desired probe current during the measurement routine, but can take seconds before the sought $(V_F, I_{F,set})$ couple is spotted. A more complex closed loop control circuit might be alternatively adopted, imposing the desired probe current $I_{F,set}$. The short acquisition routine (less than 10 ms) is not perceived by the human eye, especially in those cases where it can be randomly applied to LEDs that are parts of a matrix.

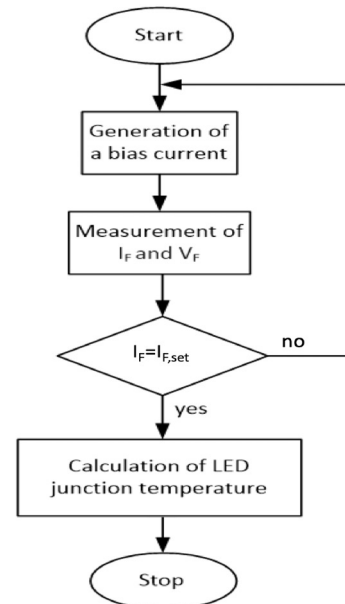


FIGURE 8. Flowchart of the LED junction temperature measuring sequence.

As an example of application, the conceived system could detect when the calculated junction temperature is above a threshold value (e.g. $95\ ^\circ\text{C}$), triggering the necessary countermeasures. A monitoring device, or the system itself, could e.g. issue a request for a temperature reduction action that can be started by reducing the bias current normally flowing through the LED.

B. EXPERIMENTAL RESULTS

In order to evaluate the accuracy of LEDs junction temperature measurement method and circuit, an analysis was carried out by placing five LED-A samples in the oven and gradually heating them up to known and stable temperatures. To prevent self-heating, measurements were performed with the LED

turned-off, by setting PWM_1 to zero. The measurements were carried out from room temperature up to the maximum value of 135 °C. Each measurement was performed only after verifying that the oven temperature had stabilized for a few minutes, so that also the LED junction had itself reached the thermal equilibrium with the oven. Also in this case, the actual oven temperature, and therefore the LED junction temperature, was monitored through a PT100 sensor with an accuracy of 0.2 °C, placed on the PCB very close to the DUT. The junction temperature values calculated through the circuit were then compared with the PT100 temperature.

At each temperature, four consecutive measurements were made, and for each measurement, the error was extracted. In Fig. 9, the experimental data for the five characterized LED-A devices are shown. The corresponding mean error is 1.41 °C. For temperatures above 95 °C, which might be considered as a safety threshold to avoid LED damaging, the error is always lower than 2.1 °C. In spite of the several error sources contributing to this error, including sensor accuracy, measured current and voltage accuracy, and noise, the overall accuracy still appears suitable for practical applications, as the true junction temperature is obtained in this case.

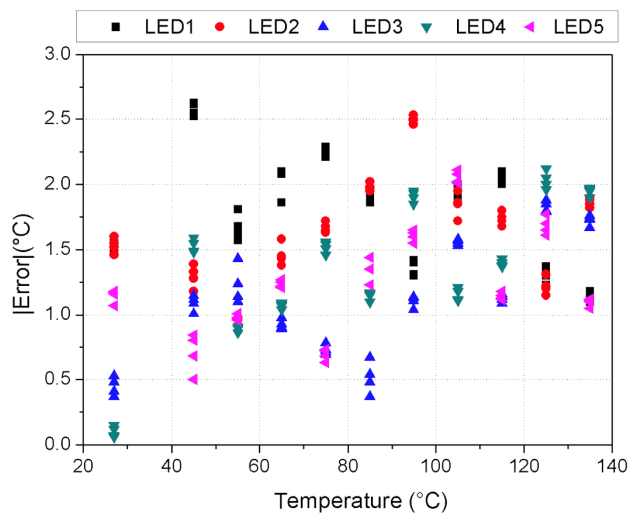


FIGURE 9. Temperature error for five LED-A type devices, using the microcontroller-based acquisition circuit. On the horizontal axis the temperature calculated by the proposed circuit is reported.

V. CONCLUSION

The well-known dependence between temperature and the voltage appearing at diode terminals at a fixed current was fully characterized in off-the-shelf power light emitting diodes from two manufacturers, with the aim of using them as sensors of their own junction temperature, T_J . The experimental measurements were performed on twelve commercial devices at one thousand different probe currents, from 10 μA to 10 mA, and the linear fitting parameters S (slope) and Q (intercept) were calculated for each current, valid in the temperature range from 25 °C to 135 °C, together with the coefficient of determination R^2 and the root mean square error

of T introduced by the linear approximation. The devices showed both a high degree of linearity, with a value of R^2 higher than 0.9999 in a wide current range, and a good sensitivity ($S \approx 2$ mV/°C). The error was calculated to be lower than 1 °C. It has been observed that, after the application of a few hundred hours of current-temperature stress, the LED V_F vs. T characteristics stabilize.

A microcontroller-based circuit was designed and realized for the real-time monitoring of an LED temperature during its normal operation, demonstrating that a precise and stable current source is not necessary for measurements and that the readout technique provides good precision in spite of the simplicity of its implementation. Through experimental tests, it was in fact possible to verify the correctness of measurements and the reliability of the implemented method. It can be suggested that LED manufacturers should provide S and Q to allow an easy determination of their LED T_J through a simple current-voltage measurement.

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