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Development and Characterization of Freestanding Poly (Methyl Methacrylate)/ Monolayer Graphene Membrane

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ABSTRACT Graphene-polymer based materials are gaining more popularity among researchers due to its mechanical properties that are found to be suitable to be used in various micro/nanoscale application requiring highly sensitive sensors. This research ventured into the fabrication and characterization process of a freestanding poly (methyl methacrylate) (PMMA) on monolayer graphene (Gr) yielding a (PMMA/Gr) membrane. In the process of transferring the chemical vapor deposition (CVD) graphene film over a cavity that was developed on a silicon substrate, the wet transfer method was used. Five repetitions of the nanoindentation testing had been carried out on the flexible membrane which resulted in a reproducible deflection, when exerted with a maximum loading of 10 mN. The indented (PMMA/Gr) membrane showed an identical elastic behavior with Young's modulus of 0.18 GPa. The highest deflection of approximately 22 μm at 1.6 mN maximum loads and the tensile stress of 0.58 MPa was obtained from the indentation testing analysis. The combination of PMMA-Graphene materials as a membrane has shown impressive changes to its mechanical properties. Besides maintaining its viscoelastic-plastic behavior which contributed to its flexibility, the presence of a graphene layer provided strong support to prevent damages to the membrane. Meanwhile, PMMA properties with low elastic modulus have contributed to the increased of the mechanical sensitivity of the membrane. Based on this research, the mechanical sensitivity of (PMMA/Gr) is reported to be 0.15 nm/Pa, which is much higher compared to a typical conventional membrane. It was proven that the hybrid (PMMA/Gr) membrane was extremely sensitive to the subjected pressures, thus, shown its potential to be applied as a micro-electro-mechanical systems (MEMS) capacitive pressure sensor.

INDEX TERMS Biomembranes, nanofabrication, microsensors.

I. INTRODUCTION

Graphene membrane has garnered significant popularity due to its extraordinary mechanical, electrical and thermal properties, as well as the ability to produce graphene-based devices. One of the interesting mechanical behaviors of a graphene membrane is that it can be easily constructed using the

transfer method which only utilized the van der Waals (vdW) adhesion between the underlying substrate and the graphene layer to fix the membrane in place. Due to the material properties of the layered graphene-polymer that may not be similar to the material of the bulk polymer [1], [2], it has piqued the interest of many researchers to investigate further on the characterization of the freestanding layered graphene-polymers. Hence, extensive research on the behavior of the freestanding (PMMA/Gr) membranes is crucial in order to

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produce more accurate and precise mechanical properties of graphene-based devices and to determine their suitability for specific applications.

In pressure sensing applications, a highly sensitive membrane is desirable as it will be able to increase the accuracy and effectiveness of a pressure sensor. For a freestanding membrane, the sensitivity can be increased by increasing the area of the suspended membrane, decreasing the dielectric gap or utilizing membrane materials that have lower elastic modulus [3]. Prior to this specific research, the monolayer graphene along with the low elastic modulus and low density of PMMA was utilized. In a hybrid (PMMA/Gr) membrane, the graphene serves as high-conductive layer and provides a strong adhesion between the membrane and the silicon nitride (Si₃N₄) layer as the results of the van der Waals interaction [4]. The PMMA plays two key roles: first, to improve the mechanical sensitivity of the membrane due to its low elastic modulus and second as an efficient holder for the graphene thin film to prevent it from collapsing into the cavity area. Besides, PMMA is basically a biocompatible polyester with high resistance to chemical reactions and most importantly, it does not cause toxicity [5]. The combination of these two materials is believed to improve the displacement and thus, increasing the mechanical sensitivity of the membrane. In a previous study by Ramanathan *et al.*, it was reported that with approximately 1 wt% addition of graphene to PMMA, an increase of approximately 80% in the elastic modulus was achieved and it also led to an increase of approximately 20% in the ultimate tensile strength [6], [7]. Furthermore, interestingly for a defect-free single-layer graphene, its intrinsic strength was recorded to be at 42 N/m, which was equivalent to 130 GPa and was considered to be one of the strongest materials [8]–[10]. In a study conducted by Bles *et al.* [11], [12], the monolayer graphene could be stretched up to 240% of its initial strength without breaking. Based on the above-mentioned features, a hybrid of (PMMA/Gr) membrane is believed to be a promising material in improvising the sensitivity of capacitive MEMS sensing actuators.

To explore the mechanical properties of various materials at the micro or nanoscale level, nanoindentation testing is a well-known technique to be applied. The nanoindentation technique is carried out by exerting a sharp and hard tip into a sample material and simultaneously recording the force-displacement data which will provide the information on the mechanical properties of the material that has been tested [13]. A considerable number of researches has utilized this technique to investigate the mechanical properties of polymers and graphene-based materials [1], [14]–[19]. Kotsilkova *et al.* [1] investigated the mechanical properties of the freestanding and the supported bilayer graphene/poly (methylmethacrylate) films. Wang *et al.* [14] explored mechanical properties of polydimethylsiloxane (PDMS) while Niu *et al.* [15] performed an indentation test of a graphene single layer mounted on a PDMS substrate (graphene/PDMS). Chen *et al.* [16] studied the mechanical properties of the graphene on poly

(ethylene terephthalate) substrate. Zhu *et al.* [17] conducted nanoindentation testing with molecular dynamics (MD) simulations to study the effects of graphene (Gr) coating on the deformation behavior of an (001) orientation copper (Cu) substrate. Zhang and Pan [18] in their study analyzed the mechanical properties and a number of layers of graphene from the nanoindentation. Kang *et al.* [19] had conducted some research on the mechanical properties of the freestanding graphene oxide (GO) films. The experiment was carried out using nanoindentation on the system of a dynamic contact module (DCM).

In this work, the micro-fabrication approach to develop a freestanding monolayer graphene-PMMA (PMMA/Gr) membrane is described as shown in Figure 1. The mechanical properties of materials such as stress-strain, Young's modulus (E_s), tensile stress (σ_{max}) and plasticity index (ψ) were analyzed from the indentation system software. These parameters of the hybrid membrane were investigated and compared with the results from the previous studies. The aim of this study is to determine the material properties of (PMMA/Gr) membrane, which in turn, is expected to significantly assist in the development of MEMS capacitive pressure sensors applications such as microphones, biomedical and biochemical sensors.

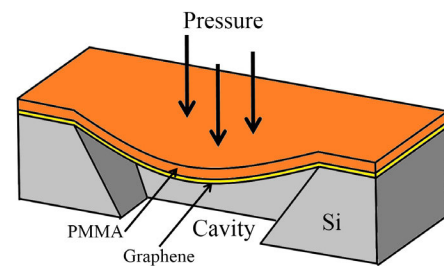


FIGURE 1. Cross-section of a suspended PMMA / Gr membrane.

II. METHODOLOGY

A. FABRICATION OF FREESTANDING (PMMA/Gr) MEMBRANE

The silicon cavity was fabricated using bulk micromachining which involved lithography and wet etching process. The wafers used in this study were supplied by University Wafer Inc., with a thickness of 500 μm , (100) orientation, n-doped and coated with 300 nm silicon nitride on both sides. After dicing the wafer, the samples were cleaned by subsequently sonicated in acetone, methanol and deionized (DI) water. Then, the samples were spin-coated with positive photoresist and were exposed to ultra-violet light. In order to prepare the window pattern for the potassium hydroxide (KOH) wet etching, the silicon nitride layer was removed. Buffered oxide etchant (BOE) etching method was used to remove the nitride layer with the etching rate of 45 nm min^{-1} at 80 $^{\circ}\text{C}$. Finally, wet anisotropic etching was performed by submerging with 45% KOH + 10% surfactant at 80 $^{\circ}\text{C}$ for 6.5 hours to fully etched the silicon cavity. The detailed fabrication process

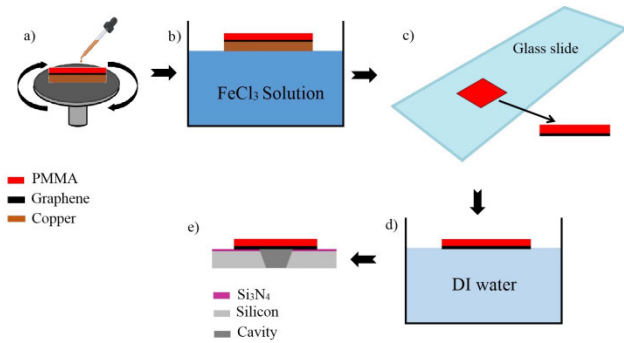


FIGURE 2. Schematic diagram of the (PMMA/Gr) film transfer process to the etched silicon structure. (a) A thin liquid PMMA layer is spin-coated onto CVD graphene on copper; (b) bottom copper layer was then etched by 0.5 M ferric chloride (FeCl₃) solution for 3 hours; (c) The (PMMA/Gr) film is lifted off using glass slide; (d) The (PMMA/Gr) film is transferred to DI water; (e) The (PMMA/Gr) film is transferred onto etched silicon structure.

of wet silicon etching using KOH has been extensively discussed in the previous studies [20]–[22].

The (PMMA/Gr) layer was transferred onto the silicon cavity by employing the wet graphene transfer process as had been discussed in previous studies [23]–[25]. Transferring (PMMA/Gr) layer onto the etched silicon forming a freestanding membrane is a crucial task where any mishandling during the transferring process may cause the membrane to rupture into the cavity area. Figure 2 illustrates the schematic diagram of the (PMMA/Gr) film transfer process to the etched silicon forming a freestanding (PMMA/Gr) membrane. Monolayer CVD graphene films on 18 μm copper were supplied by University Wafer Inc. (known as CVD graphene on copper). PMMA solution (950 PMMA A4, 950 K MW 4 wt% in anisole by MICRO CHEM) was spin-coated on top of the CVD graphene on copper samples at 3000 rpm for 60 s forming a sandwiched layer of PMMA and graphene film (PMMA/Gr). These samples were then dried on a hot plate at 100 °C for 10 min. The bottom copper layer was then etched by 0.5 M ferric chloride (FeCl₃) solution for 3 hours. In order to have a stable and slow etch rate (<500 nm/h), a low concentration of etchant (0.5M) was maintained to avoid the fabrication of copper foil into sub-millimeter grains that might sink and tear the floating graphene layer [26]. In order to remove any residues from the etching process, these samples were then transferred to distilled (DI) water by using the glass slide. The (PMMA/Gr) layer was then picked up onto the target substrate that had been etched (500 μm² square cavity of silicon). The next stage involved draining out the water between the substrate and the graphene and was carried out by holding the samples vertically. The samples were later baked at 100 °C for 20 mins to ensure that any remaining water molecules were removed and to increase adhesion between the graphene and the Si₃N₄ layer.

The surface topography of CVD graphene on copper was characterized by Atomic force microscope (AFM) (Park Systems, NX-10) and the (PMMA/Gr) membrane was

characterized by Field emission scanning electron microscope FESEM (Zeiss, SUPRA 55VP). Raman spectroscopy system (Thermo Scientific, DXR2xi) was utilized to obtain the Raman spectra of the membrane to determine the number of layer and coverage distribution of the graphene. The Raman spectra was excited using a 514-nm laser in the range of 0 – 3000 cm⁻¹.

B. NANOINDENTATION TESTING OF FREESTANDING (PMMA/Gr) MEMBRANE

The nanoindentation test was performed using a calibrated indenter (MicroMaterials NanoTest) that was equipped with a Berkovich diamond tip with a radius of 3.5 μm. During the indentation process, the calibrated tip of the indenter was slowly brought down to touch the surface of the sample. When the tip and the surface of the sample came into contact, the applied force was linearly increased until it reached the maximum peak load and/or maximum penetration depth. At this stage, the force applied was fixed at the range of 0 to 10 mN whilst the loading rate was kept at a constant value of 5 mN/s. This was to reduce the risk of viscoelastic deformation during the loading cycle [27]. For each test, the hold period or the dwell time between the loading and unloading cycle was set at 1s. The dwell settings at each cycle are important as it allows the substrate and the instrument to stabilize before the load and depth values are recorded [28]. To achieve consistencies and repeatability of the results, the test was repeated for another four times using the same sample. In total, five tests were carried out throughout the sample. The diagram in Figure 3 shows the nanoindentation testing with the (PMMA/Gr) membrane being indented at the center of the membrane.

The tensile stress (σ_{max}) of the material using a nanoindentation test can be determined using Equation (1) as [29], [30]:

$$\sigma_{max} = \left(\frac{1 - 2\nu}{2\pi} \right) \left(\frac{4E_r}{3R} \right)^{2/3} (P)^{1/3} \quad (1)$$

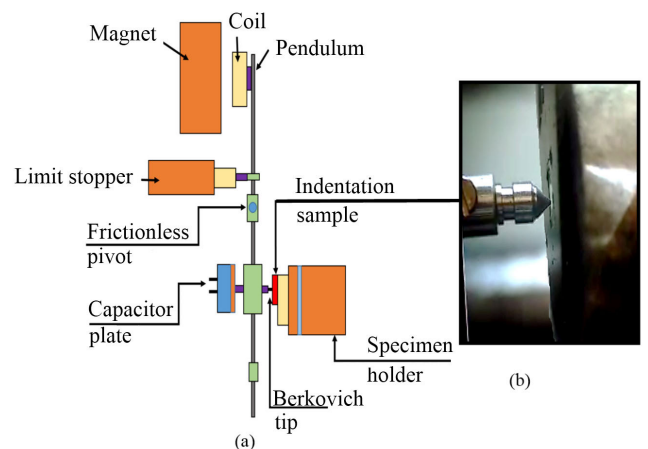


FIGURE 3. a) Indentation testing using MicroMaterials Nano Test. b) Indented (PMMA/Gr) membrane sample by Berkovich tip.

where ν , E_r , R and P are Poisson's ratio, reduced modulus, tip radius and peak load, respectively.

The Young's modulus, E_S of the sensing membrane material can be extracted from stress-strain plot while the plasticity index (ψ) of the material can be defined by calculating the area below the loading and unloading of the load-deflection curve. One of the functions of the plasticity index is to distinguish the elastic-plastic response of a material that is being subjected to external stresses and strains. In the nanoindentation test, the plasticity index of the material can be determined using Equation (2) [2] [31]:

$$\psi = \left(\frac{A_1 - A_2}{A_1} \right) \quad (2)$$

where A_1 and A_2 are the area under the loading and unloading curve, respectively.

III. RESULTS AND DISCUSSION

A. AFM CHARACTERIZATION OF CVD GRAPHENE AND FESEM IMAGES OF FREESTANDING (PMMA/Gr) MEMBRANE

Figure 4(a) shows the three-dimensional surface topography of a $30 \mu\text{m} \times 30 \mu\text{m}$ CVD graphene on copper that has been obtained via the atomic force microscopy (AFM) and Figure 4(b) shows the cross-section elemental AFM analysis of the CVD graphene on copper. According to Figure 4(a), the surface of CVD graphene on copper resembled an island-like shape. The formation of the island-like shape and wrinkles was almost unavoidable for a CVD graphene [12] due to the fact that the copper substrate employed was not entirely flat. Secondly, the CVD was potentially formed due to the difference in the thermal coefficients of the copper substrate ($\sim 20 \times 10^{-6} \text{K}^{-1}$) and graphene ($-8.0 \times 10^{-6} \text{K}^{-1}$) [32]. From Figure 4(b), the peak height of the CVD graphene on copper was approximately 60–100 nm.

The FESEM images on $30\times$ and $150\times$ magnification of (PMMA/Gr) membrane are shown in Figure 4(c) and Figure 4(d), respectively. Both FESEM images showed that the (PMMA/Gr) membrane was well suspended on the approximately $500 \mu\text{m}^2$ silicon cavity area. These results showed that the (PMMA/Gr) film was successfully transferred over to the silicon etched cavity forming a freestanding (PMMA/Gr) membrane. Figure 4(e) shows the cross-section FESEM image of the freestanding (PMMA/Gr) membrane with a measured membrane thickness of approximately $0.5 \mu\text{m}$. The bumpy surface of (PMMA/Gr) membrane shown in Figure 4(e) resulted from the island-like shape of CVD graphene on copper as previously shown by AFM image in Figure 4(a).

B. RAMAN SPECTROSCOPY CHARACTERIZATIONS

Raman spectroscopy had been employed to testify the existence of graphene and the number of graphene layers of the (PMMA/Gr) membrane. Perfect graphene exhibited prominent peaks in the Raman spectrum at G and 2D bands, at about 1580cm^{-1} and 2690cm^{-1} respectively [33]–[35].

The numbers of the graphic layers can be determined by the peak intensity ratio of 2D to peak G (I_{2D}/I_G). As a reference, the ratio for monolayer graphene is $I_{2D}/I_G \sim 2-3$, meanwhile for bilayer graphene, the ratio is $2 > I_{2D}/I_G > 1$ and for multilayer, the ratio is $I_{2D}/I_G < 1$ [36]. Figure 5 presents the Raman spectra of the freestanding (PMMA/Gr) membrane at four different locations from 1000cm^{-1} to 3000cm^{-1} range of Raman shift. According to Figure 5, the intensity of graphene at the 2D band was much higher than the G band for the freestanding membrane indicating that the graphene was prominent which testified the existence of graphene in the membrane.

TABLE 1 shows the Raman peak intensity values of G and 2D bands for the (PMMA/Gr) membrane. Based on TABLE 1, the ratios of I_{2D}/I_G of all four different locations were in the range of 2–3, which proved that the (PMMA/Gr) membrane consisted of mono-layer graphene. The very low intensity of D peak at 1350cm^{-1} (ID) shown in Figure 5 concluded that this sample was composed of high-quality graphene. Figure 6 shows the color contours for peaks 2D and G. The red colors show random distributions of intensity for 2D peak while the blue contours show intensity for G peak. From the color contributions, it showed that the graphene existence was prominent due to a wider coverage of the red contours (2D peak) compared to the blue (G peak) contours.

TABLE 1. Intensity value and ratio of I_{2D}/I_G for (PMMA/Gr) membrane.

Point	I_{2D}	I_G	I_{2D}/I_G
1	31.293	15.215	2.06
2	48.014	23.606	2.03
3	45.957	17.416	2.64
4	60.925	30.236	2.01

C. NANOINDENTATION TESTING

1) LOAD-DEFLECTION CURVE

Figure 7 illustrates the load-deflection curve of (PMMA/Gr) freestanding membranes from the indentation testing. The loading and unloading cycles were repeated at five different locations on the same membrane to test their elastic behavior. From Figure 7, all loading and unloading curves almost completely overlapped and followed a cubic law, indicating the full reversibility of the membrane deformations [37]. The full reversibility of load-deflection curves exhibited an interesting viscoelastic-plastic behavior of the (PMMA/Gr) membrane and showed the highly repeatable loading-unloading cycles without rupturing the membranes. From the indentation, the measured value for maximum deflection, plastic depth, maximum load and reduced modulus were summarized in TABLE 2. According to TABLE 2, it showed that the membrane was stretched plastically with a very high deflection of average $22 \mu\text{m}$ at the maximum load of 1.6 mN. High deflection of the membrane was highly required in

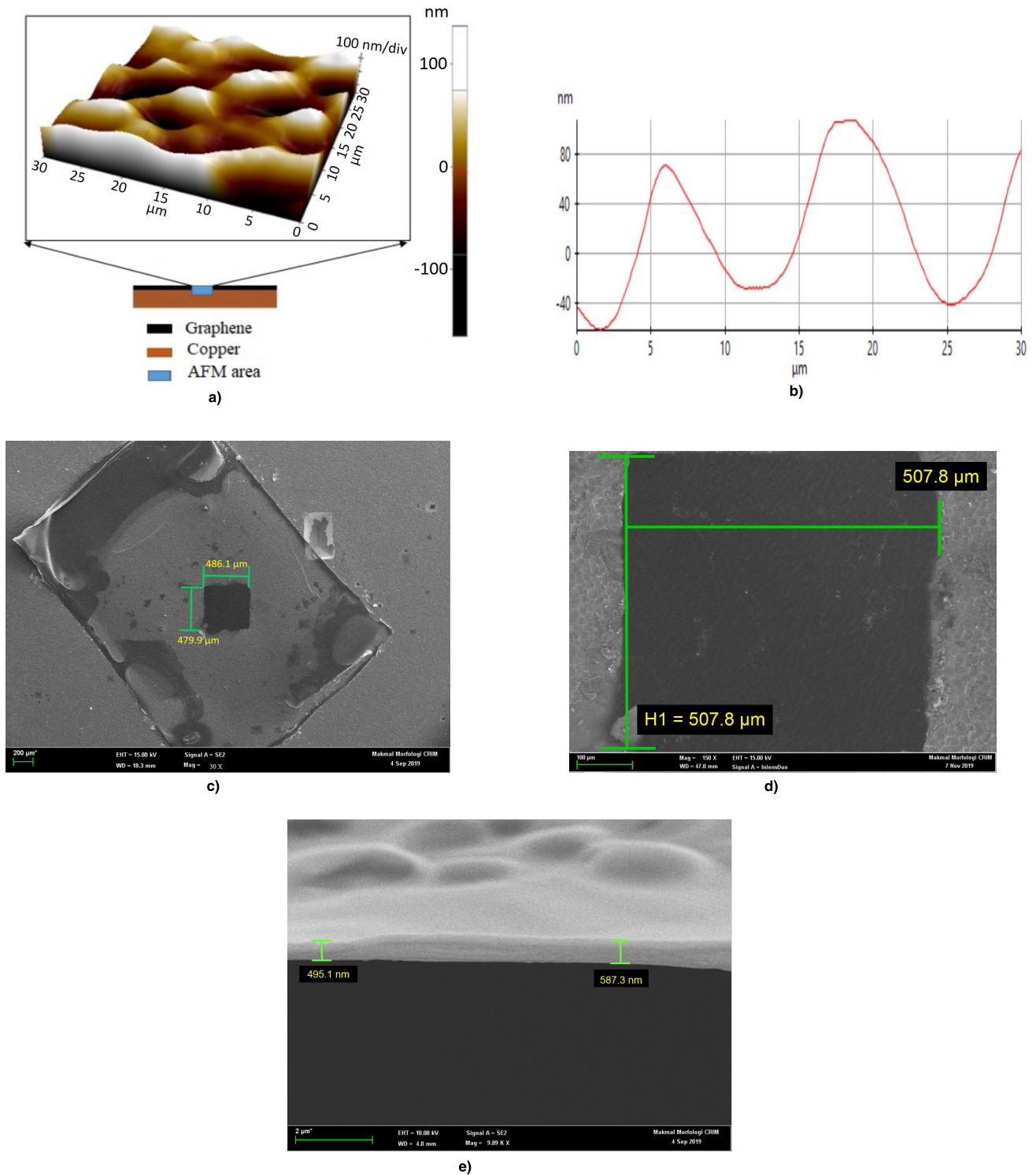


FIGURE 4. a) Three dimensional AFM image of the CVD graphene on the copper surface with the area of AFM is captured. b) Cross-sectional of AFM elemental analysis. c) FESEM image on 30x magnification of the freestanding (PMMA/Gr) membrane. d) FESEM image on 150x magnification of the freestanding (PMMA/Gr) membrane. e) Cross-section FESEM image of the freestanding (PMMA/Gr) membrane.

designing a membrane-based sensor as it would increase the mechanical sensitivity of the sensor [38]. In general, by applying a certain amount of force onto the membrane, the transducers will sense the stress as the result of membrane

deflections. Thus, the mechanical sensitivity of the membrane can be defined by the slope of the pressure versus deflection curve [39], [40]. By calculating the applied load to the projected area, the pressure-induced to the membrane can

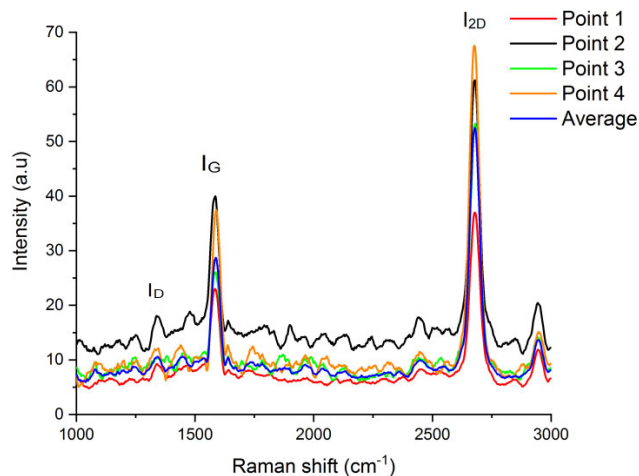


FIGURE 5. Raman peaks (G and 2D) for (PMMA/Gr) membrane.

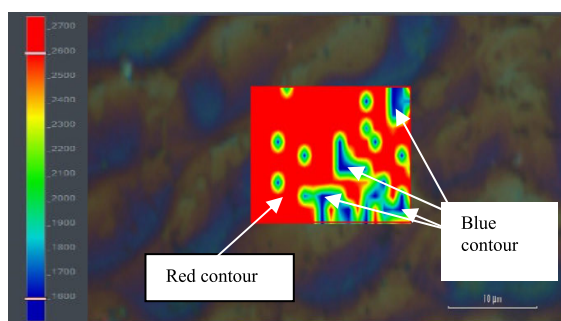


FIGURE 6. Raman mapping of freestanding (PMMA/Gr) membrane.

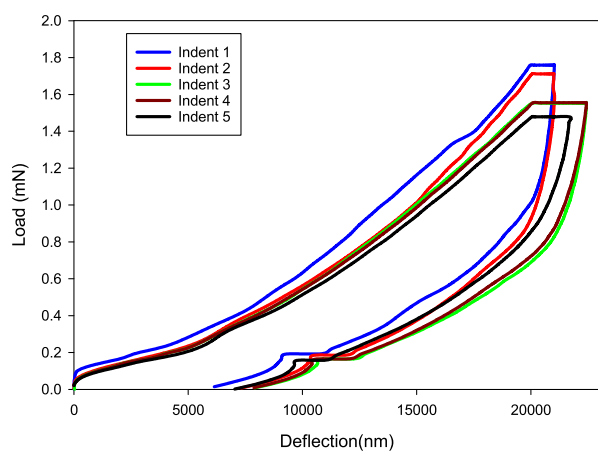


FIGURE 7. Load-deflection curve of freestanding (PMMA/Gr) membrane.

be analyzed, subsequently providing the estimation of the mechanical sensitivity. For Berkovich tip, the projected area, A is estimated as $A \approx 24.5 h_{max}^2$ where h_{max} is the maximum deflection [28]. Hence, the mechanical sensitivity of the (PMMA/Gr) membrane was calculated at approximately 0.15 nm/Pa which was higher compared to a typical conventional membrane [38], [41], [42]. In a previous research conducted by Chen *et al.* [43], the graphene membrane can boost the sensitivity up to 700% increment compared to the silicon membrane. Hence, this study has proven that the

TABLE 2. Mechanical Properties of (PMMA/Gr) membrane from indentation testing.

Indent	Maximum Deflection (nm)	Plastic Depth (nm)	Max Load (mN)	Reduced Modulus, E_r (MPa)
1	21025.95	16382.1	1.76	3.03
2	21031.92	17025.3	1.71	3.29
3	22432.21	17194.8	1.55	2.26
4	22424.16	16934.2	1.55	2.19
5	21696.34	16631.6	1.48	2.30
Average	21722.12	16833.6	1.61	2.61

(PMMA/Gr) membrane is a good choice for low - pressure detection applications which requires high sensitivity especially for biomedical devices such as intracranial, intraocular and bladder MEMS capacitive pressure sensors.

Tensile stress value is one of the imperative properties of a membrane, in which lower tensile stress will contribute to the increase in the mechanical sensitivity of the membrane [44]. By substituting the parameters in Table 2 into the Equation (1) with values of $\nu = 0.345$ for graphene-PMMA layer [45], the tensile stress of (PMMA/Gr) membrane was found to have average tensile stress of 0.58 MPa. The comparison was made with the previous works on tensile stress for various type of membranes' material. In a study conducted by Kotsilkova *et al.* [1], the tensile stress of bilayer graphene-PMMA membrane was reported at 1.35 MPa while Torrkeli *et al.*, reported a value of 2.2 MPa for the tensile stress of polysilicon membrane [46]. In their experiment, Kronast *et al.*, have recorded a value of 0.13 GPa for silicon nitride membrane [47], while tensile stress was recorded at 1.5 GPa by Ganji *et al.*, for their aluminum diaphragm [37]. Based on the previous works, as compared to these notable findings, it is evident that the tensile stress of 0.58 MPa for this monolayer graphene-PMMA membrane under study is one of the lowest, hence contributing to the increased in the mechanical sensitivity of the membrane. In light of this finding, the proposed (PMMA/Gr) membrane is highly recommended to boost the sensitivity of MEMS capacitive pressure sensor devices.

2) PLASTICITY INDEX

The total energy spent and energy released during indentation can be specified by the area below the loading and unloading curve, respectively. During the nanoindentation test, the irreversible work can be estimated based on the difference between the area below the loading and unloading curves. For materials with viscoelastic-plastic behavior, the plasticity index is in the range of $0 < \psi < 1$. Fully-elastic behavior is represented by $\psi = 0$ and the fully plastic behavior of materials is represented by $\psi = 1$ [2]. Figure 8 shows the average area below the loading and unloading curve during five repetitions of the nanoindentation test. According to Figure 8, the area below the loading was greater than the unloading area indicating that the plasticity index should be

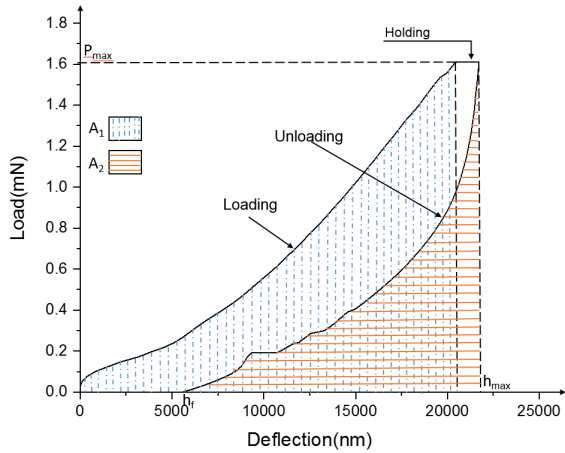


FIGURE 8. The area below the loading and unloading of the load-deflection curve.

TABLE 3. Plasticity index of (PMMA/Gr) membrane.

Indent	Plasticity Index, ψ
1	0.55
2	0.58
3	0.55
4	0.53
5	0.49
Average	0.54

in the range of $0 < \psi < 1$. Referring to TABLE 3, the value of the plasticity index was calculated using Equation (2). From TABLE 3, it can be seen that the (PMMA/Gr) membrane displayed the viscoelastic-plastic behavior with the average plasticity index of 0.54. The results indicated that the membrane had both viscous and elastic characteristics when undergoing deformation.

3) STRESS-STRAIN CURVE

The mechanical properties of the material can be further analyzed by extracting the stress-strain data from the load deflection results. In understanding the mechanics of materials, Young’s modulus, E_s can be found from the slopes of the linear strain-stress curves under elastic deformation. Stress-strain curve for the average value of five repetitions of indentation on freestanding (PMMA/Gr) membrane is shown in Figure 9. From Figure 9, the elastic response of graphene was considered to be nonlinear. This consideration was made based on the fact that the stress-strain curve must reach a maximum point which provided the intrinsic breaking stress value [2]. The gradient of the linear part of the curve will provide Young’s modulus value [48]. The linear region of the curve can be fitted using a linear equation $y = 184.14x - 0.66$, in which the slope was approximately 0.18 GPa, which was Young’s modulus value. The results were found to be competitive with the previous results published by Woo *et al.* [45], which reported a 0.67 GPa of Young’s modulus for the composition consisting

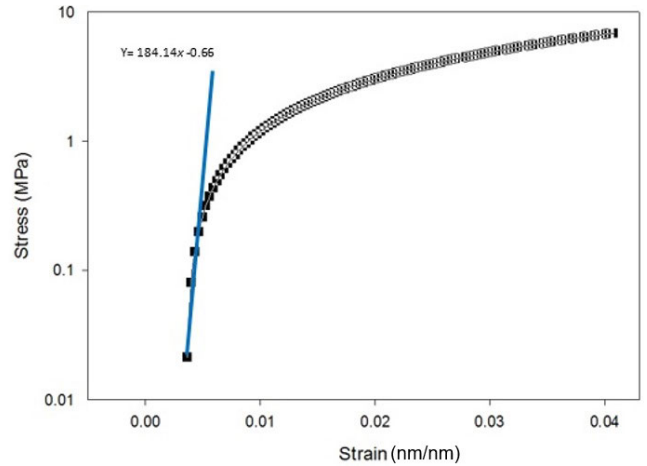


FIGURE 9. Stress-strain curve for a freestanding (PMMA/Gr) membrane.

of 0.3 μm and 3.0 μm of graphene and PMMA layer, respectively. The measured value of E_s for the different compositions can be varied by changing its thickness. According to Woo *et al.* [45], it was discovered that the value of E_s was reduced as a result of decreasing the graphene’s thickness and increasing the PMMA’s thickness. Thus, the obtained results supported the agreement which subsequently tended to reduce the E_s , since the thickness of the (PMMA/Gr) membrane in this study was approximately 0.5 μm - assuming an effective monolayer graphene thickness of 0.335 nm [8]. The lower value of E_s for (PMMA/Gr) membrane supported the idea of contributing to the increased in mechanical sensitivity of the membrane as discussed in the previous section.

IV. CONCLUSION

A hybrid monolayer graphene-PMMA (PMMA/Gr) membrane was fabricated using bulk micromachining and the wet graphene transfer process. The quality of (PMMA/Gr) layer properties was examined using the FESEM and Raman spectroscopy while the mechanical properties of (PMMA/Gr) membrane were determined using nanoindentation testing. From the results of FESEM and Raman, it was shown that the (PMMA/Gr) film had been successfully transferred onto an etched silicon substrate yielding a fully suspended (PMMA/Gr) membrane. The results from the load-displacement curve during the indentation showed that a large displacement was obtained, thus, contributed to a tremendous increase of mechanical sensitivity of the membrane. Through nanoindentation analysis, the (PMMA/Gr) membranes were found to have average tensile stress of 0.58 MPa, which was one of the lowest value from the previous reports for other membrane’s material. This resulted in an increment of mechanical sensitivity of the membrane to be approximately of 0.15 nm/Pa, which showed significant improvement, compared to a typical conventional membrane. These results provide some evidence that the (PMMA/Gr) membrane can be a promising material to be applied as a highly sensitive MEMS pressure sensor suited for low pressure sensing detection.

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