

Received July 24, 2019, accepted August 20, 2019, date of publication August 29, 2019, date of current version September 11, 2019.

Digital Object Identifier 10.1109/ACCESS.2019.2938407

# Disruption Management for Vehicle Routing Problem Based on Consumer Value and Improved Tree-Seed Algorithm

XIAHENG ZHANG<sup>1</sup> AND WENYING ZHU<sup>ID</sup><sup>2</sup>

<sup>1</sup>Business School, Northwest University of Political Science and Law, Xi'an 710122, China

<sup>2</sup>School of Economics and Management, Chang'an University, Xi'an 710064, China

Corresponding author: Wenyong Zhu (zwyong@chd.edu.cn)

This work was supported in part by the National Civil Affairs Commission's Ethnic Research Project "Research on the Development of Cross-Border E-commerce in the Northwest Ethnic Areas of the Silk Road Economic Belt" under Grant 2018-GMD-021, and in part by the Young Academic Innovation Team of Northwest University of Political Science and Law.

**ABSTRACT** With the development of logistics, a well-designed distribution plan plays an important role in the distribution process. In order to improve the economic benefit of enterprise and customer satisfaction, this paper introduces the consumer value into disruption management for vehicle routing problem (VRP). Based on the consumer value that computed through expert evaluation and cloud model, the cloud model was adopted to classify the target consumers into three levels. Then, a consumer value-based VRP disruption management was established, which measures the deviations from the perspectives of consumer, distribution centre and driver. After that, the tree-seed algorithm (TSA) was improved by the immune algorithm (IA) to solve the established model, and proved valid through simulation. The research findings shed new light on the routing of distribution vehicles in the event of disruptions.

**INDEX TERMS** Vehicle routing, consumer value, disruption management, improved tree-seed algorithm.

## I. INTRODUCTION

Logistics distribution, an important aspect of modern life, can be improved in many ways. For instance, a well-designed distribution plan helps to minimize the inevitable disruptions in the distribution process. Besides, the logistic enterprise can make more profits and improve consumer satisfaction through proper judgment, classification and management of consumers. So it is significant to consider the consumer value into disruption management for vehicle routing problem.

In 1959, Dantzig and Ramser [1] proposed the vehicle routing problem (VRP) to find the optimal set of routes for a fleet of vehicles to traverse in order to deliver to a given set of customers. Since then, many scholars have attempted to solve the VRP, with the aim to improve logistics distribution. For example, Pillac *et al.* [2] put forward the concept of dynamic degree based on information quality and changes, and utilized the concept to solve the dynamic VRP. Tas *et al.* [3] studied the VRP with flexible time window, and solved the problem with a tabu search algorithm. Ma and Wang [4]

examined the logistics distribution VRP with backhauls, set up a two-way vehicle scheduling model based on mileage and the number of consumers, and solved the model with the particle swarm optimization (PSO), coupling hill-climbing algorithm. Ma *et al.* [5] constructed a VRP model to minimize the distribution cost, which consists of the transport cost and the driver wage. Li *et al.* optimized the carbon emission and velocity of the VRP. Zhou *et al.* [6] designed an encoding method based on the intelligent water drops (IWD) algorithm, and applied it to solve the VRP with soft time window. Pan and Gan examines the carbon emission in the logistics distribution of ordinary cold chains, sets up a model to convert carbon emission into profit, and solves the model by ant colony optimization (ACO).

In the VRP, disruptions often cause delays to logistics distribution and must be well managed [7], [8]. Hu *et al.* reviewed the history of disruption management, summed up the relevant models and algorithms, and pointed out the areas for future research. Wang *et al.* [9] develops a disruption recovery strategy with time window. Hu *et al.* [10] and Yan *et al.* [11] measured the disruptions in logistics distribution against consumer satisfaction, distribution cost

The associate editor coordinating the review of this article and approving it for publication was Sabah Mohammed.

and route error, and established a lexical order multi-objective disruption management model. Ding *et al.* [12] measured disruptions in the light of prospect theory, designed a lexical order multi-objective disruption management model, and improved the ACO to solve the model. Ding *et al.* [13] laid down different strategies for different consumer groups. Wang *et al.* build several disruption models for vehicle scheduling, and evaluate the value of each consumer before assessing consumer satisfaction [13]–[15].

To sum up, most studies on VRP disruption management either neglect consumer value or evaluate the value using a single index. This paper judges the consumer value in an all-round way and considers consumer value into disruption management for vehicle routing problem, then uses the improved tree-seed algorithm to solve the problem. Firstly, consumer value is evaluated iteratively by experts and the cloud model. Then, the consumers were classified by the cloud model based on consumer values. Next, a multi-objective VRP disruption management model was established. Finally, the tree-seed algorithm (TSA) was improved with the immune algorithm (IA) to solve the model [16]–[22], optimize the VRP and minimize the disruptions in logistics distribution.

## II. MODELLING

### A. ASSUMPTIONS

In our research, the VRP is subjected to the following hypotheses:

- (1) The original distribution plan is the optimal solution to the VRP.
- (2) Each vehicle must leave from a distribution center to the target consumer, and return to the distribution center after completing the delivery.
- (3) Each vehicle can serve multiple consumers, but each consumer can only be served by one vehicle.
- (4) No vehicle should be overloaded.
- (5) All vehicles have the same load capacity.
- (6) Consumers always accept the delivered goods, whether they are satisfied with the delivery speed or not.
- (7) Consumer satisfaction is only affected by the delivery time.
- (8) When disruptions occur, the vehicle location becomes a virtual distribution center, while the original distribution center becomes the terminal.

### B. SYMBOLS

Let  $V = \{v_0, v_1, v_2, \dots, v_n\}$  be the set of locations, which  $v_0$  is the distribution center and  $v_1 \dots v_n$  are the  $n$  consumers. The distribution cost and travel time from  $v_i$  to  $v_j$  are respectively denoted as  $C_{ij}$  and  $t_{ij}$ . The demand, service time and time window of  $v_i$  are respectively denoted as  $q_i$ ,  $w_i$  and  $[ET_i, LT_i]$ , where  $[ET_i]$  and  $[LT_i]$  are the earliest and latest arrival times, respectively.

Let  $K = \{v_{m+1}, v_{m+2}, \dots, v_{m+K}\}$  be the set of vehicles, where  $v_{m+1} \dots v_{m+K}$  are the  $K$  vehicles and  $m$  is the number

of unfinished delivery tasks. The load capacity and arrival time of the vehicle are denoted as  $Q$  and  $t_i$ , respectively.

Let  $DS_i$  be the set of unserved consumers. The dissatisfactions of consumer, driver and operator (of the distribution center) are respectively denoted as  $D_{Pi}$ ,  $D_{Ni}$  and  $D_{Fi}$ .

The route error is denoted as  $t_{ijk}$ . The route error equals  $-1$  if the route is in the original plan,  $1$  if the route is in the new plan, and  $0$  if the route is not in either plan.

Two control parameters  $x_{ijk}$  and  $y_{ik}$  were defined. If vehicle  $K$  moves from  $v_i$  to  $v_j$ ,  $x_{ijk}$  is  $1$ ; otherwise,  $x_{ijk}$  is  $0$ . If  $v_i$  is served by vehicle  $K$ ,  $y_{ik}$  is  $1$ ; otherwise,  $y_{ik}$  is  $0$ .

The distribution cost is denoted as  $Z$ . The serial number of nodes are denoted as  $i$  and  $j$ .

### C. INITIAL DISTRIBUTION MODEL

The initial logistics distribution model of the VRP can be established as:

$$\min Z \sum_{i=0}^n \sum_{j=0}^n \sum_{k=1}^K C_{ij} x_{ijk} \tag{1}$$

$$\sum_{i=1}^n q_i y_{ik} \leq Q \tag{2}$$

$$\sum_{k=1}^K y_{0k} \leq K \tag{3}$$

$$\sum_{k=1}^k y_{ik} = 1, \quad i = 1, 2, 3, \dots, n \tag{4}$$

$$\sum_{i=1}^n x_{i0k} = 1, \quad k = 1, 2, 3, \dots, K \tag{5}$$

$$\sum_{i=0}^n x_{ijk} = y_{jk}, \quad j = 1, 2, 3, \dots, n, \tag{6}$$

$$k = 1, 2, 3, \dots, K$$

$$\sum_{j=0}^n x_{ijk} = y_{jk}, \quad i = 1, 2, 3, \dots, n, \tag{7}$$

$$k = 1, 2, 3, \dots, K$$

$$\sum_{k=1}^K \sum_{i=0}^n x_{ijk} (t_i + w_i + t_{ij}) = t_j, \tag{8}$$

$$j = 1, 2, 3, \dots, n$$

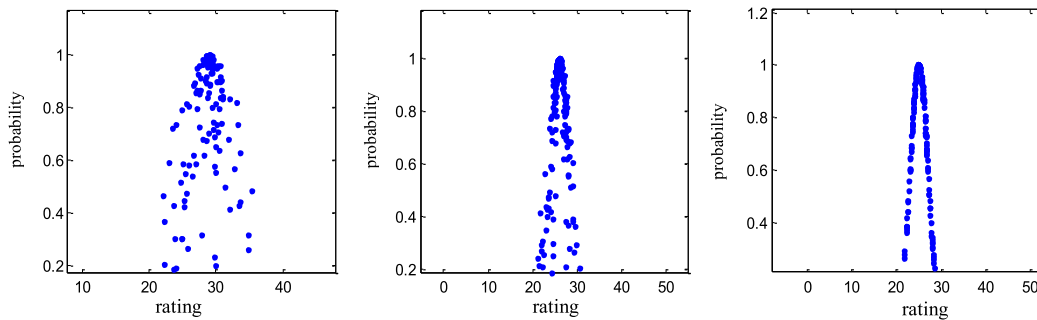
$$t_i \geq ET_i \quad i = 1, 2, 3, \dots, n \tag{9}$$

$$t_i + w_i \leq LT_i \quad i = 1, 2, 3, \dots, n \tag{10}$$

Equation (1) specifies the objective of the model, which is minimal distribution cost. Equation (2) requires that no vehicle should be overloaded. Equation (3) ensures that each vehicle must leave from the distribution center. Equation (4) demands that all consumers should be served, and that each consumer can only be served by one vehicle. Equation (5)

**TABLE 1.** Evaluation index system for consumer value.

Primary level	Secondary level
Current value $A_1$	Service charge $B_1$
	Mean service charge $B_2$
	Delivery time $B_3$
	Profit margin $B_4$
Potential value $A_2$	Age $B_5$
	Income $B_6$
	Education level $B_7$
	Demand increment $B_8$
Relationship value $A_3$	Satisfaction $B_9$
	Relationship-building time $B_{10}$
	Recommendation $B_{11}$



**FIGURE 1.** Expert ratings on the service charge.

**TABLE 2.** The final ratings on the secondary indices.

Secondary level	Rating
Service charge $B_1$	25
Mean service charge $B_2$	17
Delivery time $B_3$	8
Profit margin $B_4$	5
Age $B_5$	11
Income $B_6$	6
Education level $B_7$	7
Demand increment $B_8$	5
Satisfaction $B_9$	8
Relationship-building time $B_{10}$	3
Recommendation $B_{11}$	5

stipulates that the vehicle must return to the distribution center after completing the delivery. Equations (6)~(8) describe the relationship between different variables. Equations (9) and (10) set out the time window requirements of the consumers.

**D. EVALUATION OF CONSUMER VALUE**

Consumer value provides a criterion for consumer classification and lays the basis for disruption management. In this paper, the consumer value is determined by expert evaluation and the cloud model, and then the consumers are classified by the cloud model based on the consumer value.

**1) EVALUATION INDEX SYSTEM FOR CONSUMER VALUE**

To evaluate consumer value, an index system was built up (Table 1), involving 3 primary indices and 11 secondary

indices. The three primary indices reflect the three dimensions of consumer value. Among them, the relationship value was introduced to demonstrate the importance of consumer relations to logistics enterprises.

**2) RATING OF EVALUATION INDICES**

Each index was given a rating determined by ten experts, which was modified iteratively as per the actual situation of the consumer. Taking the service charge for instance, the ratings of the index were corrected round after round based on the ratings given in the previous round. This process terminates only if all experts agree on the index rating. After each round, the expectation, entropy and hyper-entropy were derived by the backward cloud generator. Figure 1 shows the expert ratings on the service charge in each round. Table 2 shows the final ratings on the secondary indices.

### 3) CONSUMER CLASSIFICATION

The consumers were classified by the cloud model. Let  $V = (v_1, v_2, v_3)$  be the set of target consumers. As mentioned above, the expectation, entropy and hyper-entropy were obtained by the backward cloud generator. The membership of each consumer was determined by the X-conditional cloud generator. On this basis, the set of target consumers was divided into  $v_1 = (85 - 100)$  key consumers,  $v_2 = (40 - 85)$  general consumers and  $v_3 = (0 - 40)$  unimportant consumers. The classification results are plotted as Figure 2 below.

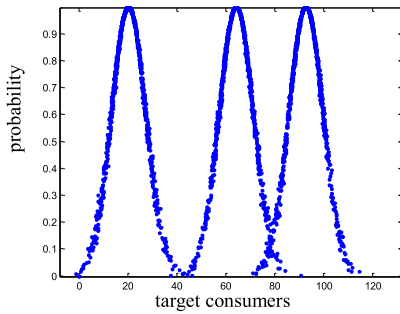


FIGURE 2. The classification results.

### E. EXTRACTION AND MEASUREMENT OF DISRUPTION FACTORS

In this paper, the disruption of logistics distribution system is measured by the dissatisfactions of consumer, driver and operator. The penalty function  $P_i(t_i)$  of consumer satisfaction, which can be determined by both soft and hard time windows, can be expressed as:

$$P_i(t_i) = \begin{cases} M & t_i \leq EC_i \text{ or } t_i \geq LC_i \\ a_i(EC_i - t_i)^{m_i} & EC_i \leq t_i \leq ET_i \\ 0 & ET_i \leq t_i \leq LT_i \\ b_i(t_i - LC_i)^{n_i} & LT_i \leq t_i \leq LC_i \end{cases} \quad (11)$$

where,  $M$  is an infinite number;  $a_i, b_i, m_i$  and  $n_i$  are all penalty coefficients.  $EC_i$  and  $LC_i$  are respectively the earliest and latest delivery times the consumer can tolerate.

Consumer dissatisfaction can be derived from the above equation:

$$D_P = \sum_{i \in DS \cap Z_1} \alpha \cdot P_i(t_i) + \sum_{i \in DS \cap Z_2} \beta \cdot P_i(t_i) + \sum_{i \in DS \cap Z_3} \gamma \cdot P_i(t_i) \quad (12)$$

where,  $Z_1, Z_2$  and  $Z_3$  are the three levels of consumers, respectively.  $\alpha, \beta,$  and  $\gamma$  are indicate value of key consumers, value of general consumers and value of unimportant consumers, respectively.

The operator dissatisfaction was described by its direct cause, the distribution cost deviation:

$$D_F = \sum_{k \in K} \sum_{i \in RT} \sum_{j \in RT} c_{ij} t_{ijk} \quad (13)$$

The driver dissatisfaction was also depicted by its primary cause, the route error:

$$D_N = \sum_{k \in K} \sum_{i \in RT} \sum_{j \in RT} |t_{ijk}| \quad (14)$$

On this basis, a lexical order disruption management model can be established as:

Objective function:

$$\min Lex = (P_1 : D_P, P_2 : D_F, P_3 : D_N) \quad (15)$$

$$\text{s.t. } P_1 \geq P_2 \geq P_3 \quad (16)$$

### III. IMPROVED TSA

The TSA is a new swarm intelligence optimization algorithm. It has been widely applied to tackle complex problems, such as estimating frequency modulated parameters, solving traveling salesman problem (TSP) and dispatching disaster relief materials. In this paper, the TSA is improved by the IA to solve the disruption management for the VRP. Thus, the improved algorithm is denoted as the IATSA. In the IATSA, each tree represents a parent individual and each seed represents a child individual generated of a parent tree. Through the evolution, the seeds around the parent tree always obey the normal distribution.

The main parameters of the algorithm are defined as follows: the position of each seed  $X = \{x_1, x_2, x_3, \dots, x_n\}$ , the population size  $N_1$ , the number of seeds  $N_2$ , the number of trees  $N_3$ , the maximum number of iterations  $N_4$ , the parent distance thresholds  $D_{12}, D_{13}$  and  $D_{23}$ , the mean and variance of normal distribution  $\mu$  and  $\delta^2$ , the optimal tree of each iteration  $P_i$ , the best-known global optimal tree  $G$ .

#### A. ADAPTIVE EXTRACTION OF SEED INFORMATION

The seed information can be extracted adaptively by:

$$P_c = \begin{cases} 1 & f' \geq \bar{f} \\ (\bar{f} - f') / (f_{max} - f') & f' \leq \bar{f} \end{cases} \quad (17)$$

where,  $f_{max}$  is the maximum known fitness;  $\bar{f}$  is the mean fitness of trees;  $f'$  is the fitness of the tree for crossover. The probability of information extraction is constantly adjusted based on the fitness of the tree. The probability is one if the tree's fitness is above average, and relatively low if otherwise.

#### B. ADAPTIVE CONTROL OF SEED EVOLUTION

In the IATSA, the position of the inoculation point is controlled based on the fitness of the tree. The length of the seed population to be inoculated can be computed as:

$$\begin{aligned} l_1 &= f_2 l / (f_1 + f_f) \\ l_2 &= l - l_1 \end{aligned} \quad (18)$$

where,  $f_1$  is the fitness of the optimal tree;  $f_2$  is the fitness of the seed to be inoculated;  $l$  is the length of the seed population;  $l_2$  is the length of the tree population to be inoculated. The value of  $l_2$  is positively correlated with the fitness of the optimal tree.

The flow chart of the IA-SOA is shown in Figure 3 below.

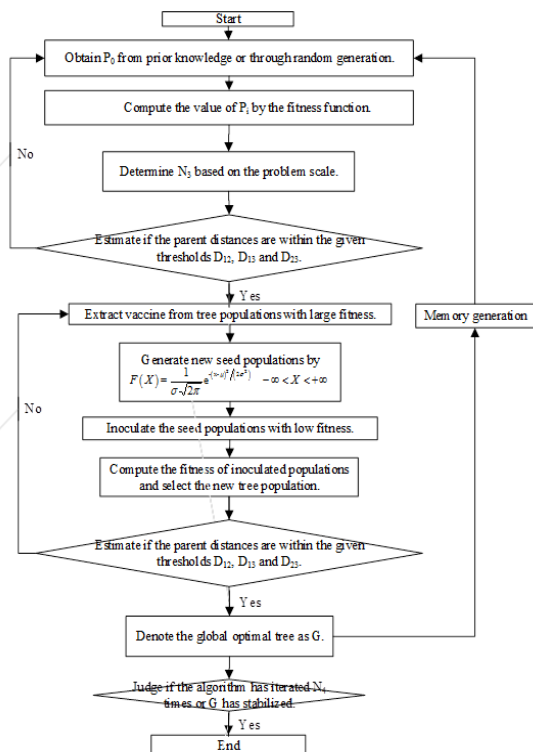


FIGURE 3. The flow chart of IASOA.

IV. SIMULATION

A. DATA SOURCE

The proposed model and algorithm were applied to simulate the logistics distribution between 1 distribution center (Handan Cigarette Distribution Centre, Hebei, China) and 24 consumers. The position coordinates and other

TABLE 3. Consumer information.

Serial No.	X-axis coordinate /km	Y-axis coordinate /km	Demand / piece	Service time /min	Time window /h
1	96	42	22	7	[7:00-10:00]
2	99	23	31	10	[7:00-8:55]
3	100	46	37	12	[7:00-9:05]
4	102	41	36	11	[10:00-13:45]
5	72	52	19	8	[8:00-9:00]
6	75	25	25	9	[10:00-12:00]
7	90	17	30	10.5	[8:00-10:00]
8	50	27	23	8.5	[13:00-18:00]
9	44	23	41	16	[12:10-18:00]
10	116	26	42	16	[8:00-18:00]
11	135	11	31	10	[8:00-10:00]
12	103	56	36	11	[12:15-18:00]
13	141	21	29	9.5	[12:00-18:00]
14	93	4	33	12	[7:00-18:10]
15	62	40	31	11	[12:00-16:00]
16	40	50	33	12	[8:20-18:00]
17	41	13	27	9.5	[8:00-9:40]
18	22	35	48	20	[7:10-9:40]
19	140	56	41	16	[7:10-10:45]
20	142	37	25	9	[8:10-18:00]
21	70	8	21	8	[10:05-13:10]
22	13	18	45	18	[10:30-11:00]
23	33	53	18	7.5	[10:00-17:30]
24	133	11	30	10	[10:30-12:00]

information of all nodes (the center and the consumers) are listed in Tables 3 and 4 below.

B. DATA PROCESSING

Four vehicles were assumed to complete the distribution task. The consumers were divided into three levels based on the evaluation of ten experts. The values of the consumers rated by the experts are listed in Table 5.

The mean rating of each consumer was taken as the final consumer value. The parameters of the IATSA are listed in Table 6.

The expectation, entropy and hyper-entropy of each consumer were obtained by backward cloud generator (Table 7).

The consumers of the distribution centre were divided into three levels by the cloud model. The memberships of the consumers are given in Table 8.

When the distribution process ran to 10:45, the time window was changed as shown in Table 9.

C. RESULTS ANALYSIS

Both the IATSA and the original TSA were adopted to solve the disruption management model. The solutions are as follows.

1) THE SOLUTION OF THE IATSA

The mean consumer satisfaction was 88.22 %, the total route error was 10, and the delivery cost deviation was 71 yuan. The vehicle routing plan of the IATSA is presented in Table 10 and Figure 4.

2) THE SOLUTION OF THE TSA

The mean consumer satisfaction was 75.74 %, the total route error was 12, and the delivery cost deviation was 82 yuan.

TABLE 4. Distance between the nodes.

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	
0	0	3	6	6	7	27	30	29	19	32	29	31	17	47	3	7	4	36	7	8	47	51	65	68	79
1	3	0	3	6	4	29	29	26	16	30	26	29	20	48	3	4	7	33	9	6	45	49	66	68	76
2	6	3	0	8	3	31	28	24	13	29	24	28	23	48	6	1	10	30	11	6	43	46	67	68	74
3	6	6	8	0	6	33	35	32	21	37	26	26	16	41	9	8	5	35	13	4	42	47	71	62	74
4	7	4	3	6	0	33	31	26	15	32	22	25	22	45	8	2	9	30	13	3	41	44	70	65	72
5	27	29	31	33	33	0	27	40	37	30	54	58	31	71	26	32	28	57	20	34	74	77	41	92	105
6	30	29	28	35	31	27	0	17	22	3	43	53	45	76	27	29	34	39	26	34	66	65	46	95	93
7	29	26	24	32	26	40	17	0	11	16	29	42	46	67	26	24	33	23	29	29	52	49	62	86	77
8	19	16	13	21	15	37	22	11	0	22	21	32	36	56	17	13	23	21	21	17	44	43	66	75	72
9	32	30	29	37	32	30	3	16	22	0	43	54	47	77	29	30	36	38	28	35	66	64	47	97	93
10	29	26	24	26	22	54	43	29	21	43	0	15	41	42	29	23	31	14	35	22	23	23	87	59	52
11	31	29	28	26	25	58	53	42	32	54	15	0	37	27	33	27	30	29	38	24	17	24	95	44	49
12	17	20	23	16	22	31	45	46	36	47	41	37	0	42	20	23	13	51	19	20	53	60	71	62	85
13	47	48	48	41	45	71	76	67	56	77	42	27	42	0	50	47	44	57	54	42	32	44	112	20	57
14	3	3	6	9	8	26	27	26	17	29	29	33	20	50	0	6	7	35	6	9	48	52	63	70	80
15	7	4	1	8	2	32	29	24	13	30	23	27	23	47	6	0	10	30	12	5	42	45	68	67	73
16	4	7	10	5	9	28	34	33	23	36	31	30	13	44	7	10	0	39	9	9	47	52	68	65	79
17	36	33	30	35	30	57	39	23	21	38	14	29	51	57	35	30	39	0	40	31	33	27	85	72	55
18	7	9	11	13	13	20	26	29	21	28	35	38	19	54	6	12	9	40	0	15	54	57	58	74	85
19	8	6	6	4	3	34	34	29	17	35	22	24	20	42	9	5	9	31	15	0	40	44	72	62	71
20	47	45	43	42	41	74	66	52	44	66	23	17	53	32	48	42	47	33	54	40	0	12	110	42	32
21	51	49	46	47	44	77	65	49	43	64	23	24	60	44	52	45	52	27	57	44	12	0	110	53	29
22	65	66	67	71	70	41	46	62	66	47	87	95	71	112	63	68	68	85	58	72	110	110	0	132	139
23	68	68	68	62	65	92	95	86	75	97	59	44	62	20	70	67	65	72	74	62	42	53	132	0	55
24	79	76	74	74	72	105	93	77	72	93	52	49	85	57	80	73	79	55	85	71	32	29	139	55	0

TABLE 5. Expert evaluation results.

Serial No.	Key consumer	General consumer	Unimportant consumer	$\Sigma$
Expert 1	0.5	0.3	0.2	1
Expert 2	0.4	0.4	0.2	1
Expert 3	0.6	0.3	0.1	1
Expert 4	0.7	0.2	0.1	1
Expert 5	0.5	0.3	0.2	1
Expert 6	0.4	0.3	0.3	1
Expert 7	0.5	0.3	0.2	1
Expert 8	0.6	0.2	0.2	1
Expert 9	0.5	0.3	0.2	1
Expert 10	0.4	0.4	0.2	1

TABLE 6. Parameter settings.

Parameters	Meaning	Numerical value
$N_1$	Population size	50
$N_2$	Number of seeds	3
$N_3$	Number of trees	3
$N_4$	Number of maximum iterations	100
$D_{31}$	Parent distance threshold	5.85
$D_{32}$	Parent distance threshold	7.91
$D_{21}$	Parent distance threshold	4.63
$\mu$	Mean of normal distribution	2.16
$\delta^2$	Variance of normal distribution	0.44
Q	Vehicle capacity (unit: pieces)	210
$a_i$	Time window coefficient	0.02
$b_i$	Time window coefficient	0.02
$m_i$	Time window coefficient	0.01
$n_i$	Time window coefficient	0.01
$\alpha$	Value of key consumer	0.51
$\beta$	Value of general consumer	0.3
$\gamma$	Value of unimportant consumer	0.19

The vehicle routing plan of the TSA is presented in Table 11 and Figure 5.

According to the above results, it can be seen that the mean consumer satisfaction outputted by the IATSA was 12.48 %

TABLE 7. Cloud model indices of consumers.

Serial No.	Numerical features		
	Ex	En	He
1	78.21	2.34	0.25
2	95.23	2.07	0.51
3	62.54	3.19	0.69
4	81.55	1.93	0.32
5	57.24	2.45	0.67
6	73.12	2.78	0.44
7	76.38	1.90	0.31
8	84.75	2.32	0.38
9	77.90	2.36	0.36
10	87.26	1.32	0.81
11	88.27	2.13	0.45
12	63.78	1.56	0.28
13	88.37	1.89	0.58
14	88.36	1.77	0.52
15	62.56	1.43	0.31
16	78.87	2.21	0.25
17	60.11	1.56	0.24
18	82.55	1.73	0.34
19	53.24	2.42	0.57
20	87.29	1.31	0.80
21	93.23	2.57	0.31
22	88.26	2.12	0.42
23	63.54	3.17	0.66
24	87.23	1.31	0.71

higher than that of the original TSA. Obviously, the route error of the IATSA was 16.67% lower than that of the TSA. It can be observed that the distribution cost deviation of the IATSA was 13.41 % lower than that of the TSA. Figure 4 shows the routing plan of enterprise obtained by the IATSA. The consumers and paths of each vehicle are listed. The first routing is 0-17-9-22-18-8. The second is 0-23-16-15-5. The third is 0-19-3-12-20. The fourth is 0-10-24-14-21. Figure 5 shows the routing plan of enterprise obtained by the IATSA.



TABLE 8. The memberships of the consumers.

Serial No.	Simulated value			Classification result
	Key consumer	General consumer	Unimportant consumer	
1	0	7	3	General consumer
2	10	0	0	Key consumer
3	0	8	2	General consumer
4	0	10	0	General consumer
5	0	0	10	Unimportant consumer
6	8	2	0	Key consumer
7	0	9	1	General consumer
8	1	9	0	General consumer
9	0	7	3	General consumer
10	0	1	9	Unimportant consumer
11	0	2	8	Unimportant consumer
12	9	0	1	Key consumer
13	2	8	0	General consumer
14	0	8	2	General consumer
15	1	8	1	General consumer
16	1	7	2	General consumer
17	2	8	0	General consumer
18	9	1	0	Key consumer
19	0	1	9	Unimportant consumer
20	1	9	0	General consumer
21	3	7	0	General consumer
22	9	0	1	Key consumer
23	1	2	7	Unimportant consumer
24	3	6	1	General consumer

TABLE 9. Distance between the nodes.

No. of disrupted nodes	Original time window	New time window
3	[7:00-9:05]	[12:10-18:00]
9	[12:10-18:00]	[9:10-11:00]
16	[8:20-18:00]	[15:00-18:00]

The consumers and paths of each vehicle are listed. The first routing is 0-17-9-22-18-8. The second is 0-15-6-23-5. The third is 0-3-12-19-20. The fourth is 0-14-24-10-21.

The convergence curves of the consumer satisfaction, the route errors and distribution cost deviations by the IATSA and the TSA are shown in Figure 6, Figure 7, Figure 8, respectively.

Figure 6, Figure 7, Figure 8 all show that the IATSA converges faster than the TSA. Compared with the basic TSA, the IATSA can not only improve the convergence speed, but also improve consumer satisfaction, reduce the route errors

TABLE 10. Vehicle routing plan of the IATSA.

Serial No.	Consumer satisfaction	Route error	Distribution cost deviation /yuan
Route 1	83.32 %	4	28.4
Route 2	77.14 %	0	0
Route 3	78.62 %	2	14.2
Route 4	81.78 %	4	28.4

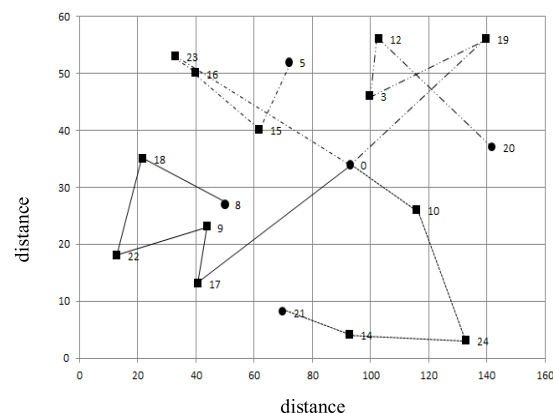


FIGURE 4. The vehicle routing plan of the IATSA.

TABLE 11. Vehicle routing plan by the TSA.

Serial No.	Consumer satisfaction	Route error	Distribution cost deviation /yuan
Route 1	83.32 %	4	27.4
Route 2	72.14 %	4	27.4
Route 3	76.53 %	0	0
Route 4	70.98 %	4	27.4

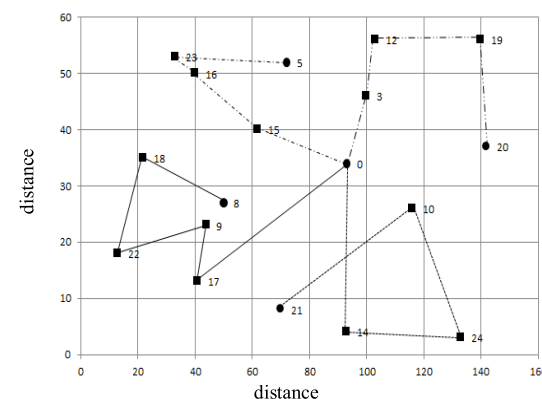


FIGURE 5. The vehicle routing plan of the TSA.

and the distribution cost deviation. It provides a theoretical basis for the enterprises, which want to improve consumer satisfaction, reduce the route errors and the distribution

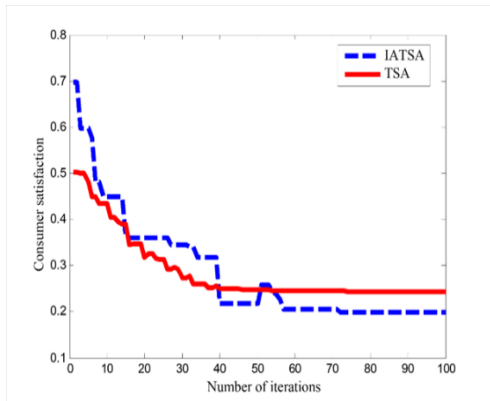


FIGURE 6. Convergence curves of consumer satisfaction.

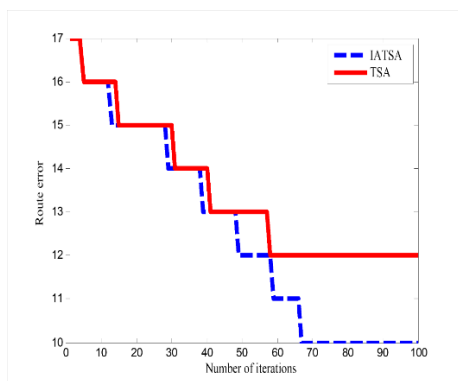


FIGURE 7. Convergence curves of route error.

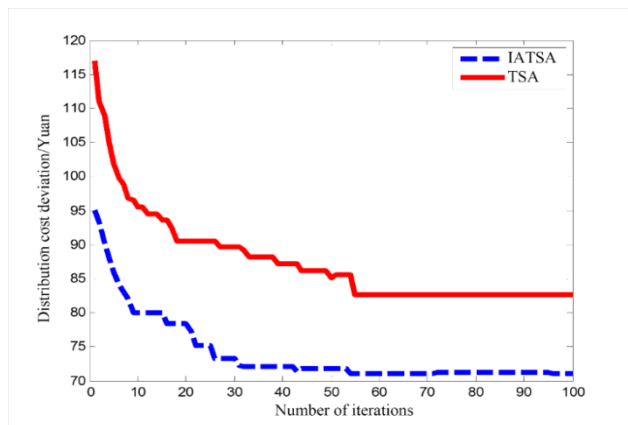


FIGURE 8. Convergence curves of distribution cost deviation.

cost deviation. To sum up, the proposed IATSA outperformed the original TSA in all three aspects, indicating that it could mitigate disruptions in logistics distribution excellently.

### V. CONCLUSION

Considering the lack of research on consumer value in logistics distribution, this paper explores deep into consumer relationship, cloud model and disruption management, and relies

on the cloud model to classify the target consumers based on their values. On this basis, the author set up a distribution management model for the VRP. To solve this model, the TSA was improved with the IA and proved valid through simulation. Some of the parameters were empirically designed, and will be improved in future research.

### REFERENCES

- [1] G. B. Dantzig and J. H. Ramser, "The truck dispatching problem," *Manag. Sci.*, vol. 6, no. 1, pp. 80–91, Oct. 1959.
- [2] V. Pillac, M. Gendreau, C. Guéret, and A. L. Medaglia, "A review of dynamic vehicle routing problems," *Eur. J. Oper. Res.*, vol. 225, no. 1, pp. 1–11, 2013.
- [3] D. Taş, O. Jabali, and T. V. Woensel, "A vehicle routing problem with flexible time windows," *Comput. Oper. Res.*, vol. 52, pp. 39–54, Dec. 2014.
- [4] D. Q. Ma and W. Wang, "Logistics distribution vehicle scheduling based on improved particle swarm optimization," *Comput. Eng. Appl.*, vol. 50, no. 11, pp. 246–250, Nov. 2014.
- [5] Y. H. Ma, T. T. Yao, and F. F. Zhang, "Multi-depot multi-type vehicle scheduling problem and its genetic algorithm," *Math. Pract. Theory*, vol. 44, no. 2, pp. 107–114, 2014.
- [6] H. Zhou, L. Zhang, and Y. Tan, "Adjacent domain renewal intelligent water drops algorithm based soft time window vehicle routing optimization," *Comput. Eng. Appl.*, vol. 51, no. 20, pp. 253–258, 2015.
- [7] A. El Rhalibi and G. Kelleher, "An approach to dynamic vehicle routing, rescheduling and disruption metrics," in *Proc. IEEE Int. Conf. Syst. Man Cybern. Conf. Theme Syst. Secur. Assurance*, vol. 4, Oct. 2003, pp. 3613–3618.
- [8] D. Huisman, R. Freling, and A. P. M. Wagelmans, "A robust solution approach to the dynamic vehicle scheduling problem," *Transp. Sci.*, vol. 38, no. 4, pp. 447–458, 2004.
- [9] X. P. Wang, J. H. Ruan, K. Zhang, and C. Ma, "Study on combinational disruption management for vehicle routing problem with fuzzy time windows," *J. Manage. Sci.*, vol. 14, no. 6, pp. 2–15, Jun. 2011.
- [10] X. P. Hu, L. J. Sun, and Y. N. Wang, "A model for disruption management in urban distribution systems," *J. Manage. Sci. China*, vol. 14, no. 1, pp. 50–60, Jan. 2011.
- [11] Z.-N. Yan, C.-W. Wang, and H. Yu, "Emergency logistics distribution management system of city disaster interference model," *J. Eng. Manage.*, vol. 28, no. 2, pp. 61–65, Feb. 2014.
- [12] Q. Ding, X. Hu, and Y. Jiang, "A model of disruption management based on prospect theory in logistic distribution," *J. Manage. Sci. China*, vol. 17, no. 11, pp. 1–19, Nov. 2014.
- [13] Q. L. Ding, X. Hu, and Y. Wang, "A model of disruption management for solving delivery delay," in *Advances in Intelligent Decision Technologies*, Baltimore, MD, USA, 2010, pp. 227–237.
- [14] X. P. Hu, N. Yu, and Q. L. Ding, "Sequential decision methods for disruption management in distribution," *J. Ind. Eng. Manage.*, vol. 25, no. 2, pp. 186–192, Feb. 2011.
- [15] Q. L. Ding, X. P. Hu, and Y. Jiang, "Two-stage decision-making method of disruption management for solving delay in distribution," *Oper. Res. Manage. Sci.*, vol. 21, no. 6, pp. 84–93, Jun. 2012.
- [16] T. Bikku, "An indigenous tool (NoJavaCloud) to handle virtual nodes to simulate the cloud tasks," *Math. Model. Eng. Problems*, vol. 6, no. 1, pp. 85–91, Jan. 2019.
- [17] Z. Yang and C. Liu, "A multi-objective genetic algorithm for a fuzzy parallel blocking flow shop scheduling problem," *Academic J. Manuf. Eng.*, vol. 16, no. 2, pp. 3–11, Jan. 2018.
- [18] X. P. Yang and X. L. Gao, "Optimization of dynamic and multi-objective flexible job-shop scheduling based on parallel hybrid algorithm," *Int. J. Simul. Model.*, vol. 17, no. 4, pp. 724–733, Apr. 2018.
- [19] Z. Xie and H. Yin, "Selection of optimal cloud services based on quality of service ontology," *Ingenierie des Syst. d'Inf.*, vol. 23, no. 6, pp. 127–141, Dec. 2018.
- [20] M. Mousavi, H. J. Yap, S. N. Musa, and S. Z. M. Dawal, "A fuzzy hybrid GA-PSO algorithm for multi-objective AGV scheduling in FMS," *Int. J. Simul. Model.*, vol. 16, no. 1, pp. 58–71, Jan. 2017.

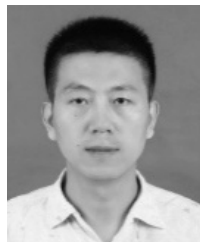


- [21] B. Li, C. Guo, and T. Ning, "An improved bacterial foraging optimization for multi-objective flexible job-shop scheduling problem," *J. European des Systemes Automatises*, vol. 51, nos. 4–6, pp. 323–332, Oct. 2018.
- [22] E. Pourjavad and R. V. Mayorga, "Optimization of a sustainable closed loop supply chain network design under uncertainty using multi-objective evolutionary algorithms," *Adv. Prod. Eng. Manage.*, vol. 13, no. 2, pp. 216–228, Jun. 2018.



**WENYING ZHU** is currently an Associate Professor with the School of Economics and Management, Chang'an University. Her research interests include transportation planning and logistics management.

...



**XIAHENG ZHANG** is currently an Associate Professor with the Business School, Northwest University of Political Science and Law. His research interests include transportation planning and logistics management.