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A Hybrid Transforms-Based Robust Video **Zero-Watermarking Algorithm for Resisting High Efficiency Video Coding Compression**

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ABSTRACT With the rampancy of pirated videos, video watermarking for copyright protection has become a widely researched topic. In this paper, zero-watermarking is applied to videos for the first time to resist high efficiency video coding compression, which can improve the robustness of the watermarking algorithm and ensure the videos' quality. A robust video zero-watermarking algorithm based on the discrete wavelet transform, the all phase biorthogonal transform, and singular value decomposition is proposed. Utilizing the properties of hybrid transforms, robust features can be extracted from videos, and robust zero-watermarks can be constructed. Experimental results demonstrate that the proposed algorithm has strong robustness to high efficiency video coding compression attacks with different quantization parameters. In addition, the algorithm can also resist common image processing attacks, geometric attacks, frame-based attacks, and hybrid attacks. Compared with existing video watermarking algorithms, the proposed algorithm can more accurately and completely reconstruct watermark images.

INDEX TERMS Video signal processing, watermarking, video watermarking, zero-watermarking, copyright protection, robustness, high efficiency video coding, discrete wavelet transform, all phase biorthogonal transform, singular value decomposition.

I. INTRODUCTION

With the rapid popularization of Internet technology and the rise of various short video applications, live broadcast, and video-on-demand (VOD) platforms, the number of online videos has increased dramatically. Videos have penetrated all aspects of people's lives. They enrich people's lives and improve their living standards, but they also pose serious threats to information security, especially the security of video data. In recent years, various pirated videos that seriously infringe upon the legitimate rights and interests of the video owners have flooded the Internet. Copyright protection for digital videos is an issue that must be resolved urgently.

Techniques for copyright protection include cryptography [1], steganography [2], digital fingerprinting [3], and digital watermarking [4]–[27]. Among them, digital watermarking is the most commonly used copyright protection technology for digital products due to its good concealment, robustness, and stability. Depending on the differences of the embedding domains, digital watermarking can be divided into two categories: watermarking in the spatial domain [4] and watermarking in the transform domain [5]-[9]. Watermarking algorithms in the spatial domain are easy to implement but have poor robustness. Watermarking algorithms in the transform domain are robust and have wide application ranges. However, both kinds of algorithms achieve watermark insertion by modifying the original carrier data, which will affect the visual quality of the carrier. As more watermark bits are embedded, the robustness will increase, but the invisibility will be diminished. Therefore, the balance between the robustness and invisibility must be considered when embedding watermarks. To address this tension, zero-watermarking

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that does not modify the original carriers was developed. Since each carrier generates its own unique zero-watermark, an intellectual property library must be established to store the zero-watermarks. To date, zero-watermarking technology has been applied to copyright protection in many fields, such as text [10], audio [11], image [12]–[19], video [20]–[24], relational databases [25], and sharing models in cooperative drive engineering [26].

In this paper, zero-watermarking is adopted to resist high efficiency video coding (HEVC) compression for the first time, and a hybrid transforms-based video zero-watermarking algorithm is proposed. The selection of the hybrid transforms is inspired by [27], which is a conventional image watermarking algorithm and proposes a hybrid transforms-based watermarking algorithm with good robustness. The features are extracted according to the parity of the highest bit of the largest singular value in the singular value matrix of the video sequence after the hybrid transforms. The zero-watermark is constructed via XOR operations between the encrypted watermark and the extracted features. The main innovations of this paper are as follows. (1) Zero-watermarking is introduced into videos to resist HEVC compression for the first time. (2) The multiresolution characteristic of the discrete wavelet transform (DWT), the better low-frequency energy gathering characteristic of the all phase biorthogonal transform (APBT), and the stability of singular value decomposition (SVD) are combined to extract robust features from video sequences. (3) Through the watermark postprocessing process, watermark images can be more accurately and completely reconstructed, and the robustness of the algorithm is further improved.

The rest of this paper is organized as follows. Related work is provided in Section II. Section III introduces the three transforms: DWT, APBT, and SVD. The key-frame detection algorithm is also described. Section IV details the proposed algorithm, including the generation and the detection of the zero-watermark. The experimental results and discussion are presented in Section V. Finally, the conclusions and future work are discussed in Section VI.

II. RELATED WORK

Due to the poor robustness of watermarking algorithms in the spatial domain, video watermarking algorithms for copyright protection are mostly concentrated in the transform domain [6]–[9]. Singh [6] embedded watermarks into high-frequency DWT coefficients and used the scale invariant feature transform (SIFT) to improve the method's robustness against rotation attacks. Sathya and Ramakrishnan [7] used the Fibonacci-Lucas transform to scramble watermark images and embedded their singular values into the singular values of video frames' middle-frequency DWT sub-bands. The common disadvantage of these two algorithms is that their robustness to compression attacks is poor. Himeur and Boukabou [8] used the gradient magnitude similarity deviation (GMSD) algorithm to extract key frames and embedded the watermark into the singular values of the low-frequency DWT sub-bands of the key frames. This algorithm is less robust to frame-based attacks, such as frame deletion and frame switching. Gupta *et al.* [9] employed the group search optimization (GSO) method to embed watermarks into lowand middle-frequency DWT coefficients. The main problem with their algorithm is that the embedded watermark has a relatively large impact on the video quality, resulting in low imperceptibility.

With the development of high-definition televisions and movies, the latest video coding standard, H.265/HEVC [28], has been gradually popularized. In the transmission and storage processes, videos will inevitably undergo HEVC compression. Therefore, video watermarking must have high resistance to HEVC compression. There have been some conventional video watermarking algorithms that can resist HEVC compression to a certain extent [29]–[31]. However, when the intensity of HEVC compression is high, the watermark images reconstructed by them will have more obvious false detection bits. In addition, these algorithms embed watermarks by modifying videos, which will decrease the videos' quality. With the development of three-dimensional videos (3DVs), some scholars have begun to study copyright protection for 3DVs [32], [33]. El-Shafai et al. [32] proposed two hybrid watermarking schemes to secure the copyright of 3DVs. One is the homomorphic transform-based SVD in the DWT domain, and the other is the three-level discrete stationary wavelet transform in the discrete cosine transform (DCT) domain. On this basis, the authors combined a wavelet-based fusion technique to improve the capacity and robustness without affecting the perceptual quality of the original 3D-HEVC frames [33]. At present, most video watermarking algorithms are still based on 2D videos.

The appearance of zero-watermarking addresses the tension between imperceptibility and robustness. At present, the studies on zero-watermarking are mostly concentrated in the image field. Ghadi *et al.* [12] used the Jacobian matrix model and Jumana *et al.* [13] used the genetic algorithm (GA) to construct zero-watermarks. To improve the security, many algorithms introduced visual cryptography (VC) to zero-watermarking technology [14]–[16]. To improve the robustness to geometric attacks, Xia *et al.* [17] and Wang *et al.* [18] adopted the polar harmonic transform (PHT) and Tsai *et al.* [19] adopted log-polar mapping (LPM) to construct zero-watermarks. Many image zero-watermarking algorithms can be extended into video zero-watermarking algorithms after being modified.

Compared with the image field, the research on zerowatermarking for video copyright protection is still in its infancy, and the number of existing studies is relatively small. Its overall framework is shown in Fig. 1. Liu [20] proposed a non-negative matrix factorization with sparseness constraints on parts (NMFSCP) method to generate zero-watermarks. This algorithm has strong resistance to geometric attacks, such as rotation and cropping, but it has weak resistance to common image processing attacks, such as noise and filtering. To improve the robustness to



FIGURE 1. Schematic diagram of zero-watermarking algorithms for video copyright protection.

geometric attacks, Li et al. [21] adopted the 2D DWT and 3D DCT to obtain stable low- frequency coefficients, and then they conducted the log-polar transform (LPT) to construct zero-watermarks. This algorithm has weak resistance to cropping attacks. Based on the contour wave transform, the pseudo-3D DCT, and SVD, Li et al. [22] proposed a zero-watermarking algorithm for copyright protection of animation videos. This algorithm is less robust to compression attacks and cut attacks. Liu et al. [23] applied fingerprinting technology to a zero-watermarking algorithm and proposed a hybrid scheme. Its robustness to frame-based attacks is weak. Liu et al. [24] applied zero-watermarking for digital rights management (DRM) of 3DVs. The resistance to rotation and cropping attacks of this algorithm is relatively weak. Although the existing video zero-watermarking algorithms can resist some common image processing attacks and a certain degree of geometric attacks, their robustness still needs to be improved. In addition, all of these algorithms do not consider the resistance to HEVC compression and combinations of multiple attacks.

To improve the robustness against HEVC compression attacks and various common attacks and avoid impacts on the videos' quality, a video zero-watermarking algorithm based on hybrid transforms is proposed in this paper. The DWT is first used to concentrate the energy of video frames into the LL sub-band, which can resist attacks such as cropping and sticking to some extent. Then, using the good lowfrequency energy accumulation characteristics of the APBT, the direct current (DC) coefficient matrix with more concentrated energy can be obtained. Combined with the stability of the singular values obtained via SVD, robust features can be extracted and zero-watermarks can be generated. The combination of these three transforms ensures the robustness of the proposed algorithm. HEVC compression attacks with different quantization parameters (QPs), common image processing attacks, geometric attacks, frame-based attacks, and hybrid attacks are all taken into account. The experimental results show that compared with existing video watermarking algorithms, the proposed algorithm can more accurately and completely reconstruct watermark images.

III. PRELIMINARY CONCEPTS

To improve the robustness of the algorithm, the advantages of the DWT, APBT, and SVD are combined to extract stable



FIGURE 2. Wavelet decomposition diagram of the first frame of the BasketballDrill sequence.

features from video sequences and construct zero-watermarks. To resist various frame-based attacks, the key-frame detection algorithm is used to extract the key frames from each shot of the video sequence. This section mainly introduces the concepts and characteristics of the three transforms and the key-frame detection algorithm.

A. DWT

The wavelet analysis method comes from Fourier analysis. Since it has a high-frequency resolution and low time resolution at low frequencies, it is called an image microscope. Compared with the Fourier transform, the advantage of wavelet analysis is that it has good localization in both the time and frequency domains. In the image processing field, the DWT is obtained by discretizing the scale factor and displacement factor of the continuous wavelet transform. Taking the Y component of the first frame of BasketballDrill as an example, a wavelet image can be obtained after performing the DWT, as shown in Fig. 2.

Obviously, most of the energy of the original image is concentrated in the LL sub-band, which is called the approximate sub-band. The LH, HL, and HH sub-bands contain horizontal edge details, vertical edge details, and diagonal edge details of the image, respectively, and are called detail sub-bands. The DWT has good multiscale and multiresolution characteristics. To improve the robustness of the watermarking algorithms, the LL sub-band is usually selected to embed the watermark.

B. APBT

The APBT is developed on the basis of the DCT. Fig. 3 shows the normalized amplitude-frequency response of each filter in the DCT and APBT matrices. It can be observed that compared with the DCT, the APBT has better low-frequency energy accumulation and high-frequency energy attenuation characteristics. In addition, the APBT can eliminate the blocking artifacts that are caused by the block DCT in JPEG compression at a low bit rate. Currently, the APBT has been applied to many fields, such as image compression and digital watermarking.

The APBT can be divided into different types based on the orthogonal transform matrix. In this paper, the all phase discrete cosine biorthogonal transform (APDCBT) [29] is



FIGURE 3. The normalized amplitude-frequency response of each filter in different matrices: (a) the DCT matrix and (b) the APBT matrix.

used, and its transform matrix can be expressed as follows:

$$B(i,j) = \begin{cases} \frac{N-i}{N^2}, & i = 0, 1, \cdots, N-1, j = 0, \\ \frac{1}{N^2} [(N-i)\cos\frac{ij\pi}{N} - \csc\frac{j\pi}{N}\sin\frac{ij\pi}{N}], \\ & i = 0, 1, \cdots, N-1, j = 1, 2, \cdots, N-1, \end{cases}$$
(1)

where N is the size (height and width) of the image block X. Applying the APBT to X can be expressed as follows:

$$Y = BXB^{\mathrm{T}},\tag{2}$$

where Y is the transform coefficient matrix, and B is the APBT matrix with the same size as X.

C. SVD

SVD is a type of matrix decomposition that can be applied to any matrix. Through SVD, a complex matrix can be expressed by multiplying several smaller and simpler submatrices. These obtained submatrices can describe the important characteristics of the matrix [34]. For any matrix *A*, its SVD can be expressed as follows:

$$A = USV^{\mathrm{T}},\tag{3}$$

where U and V are orthogonal matrices and S is a diagonal matrix. Since matrix S contains the singular values of matrix A, it is called a singular value matrix; it contains the main information of the image and has high stability. Based on this characteristic, SVD is widely used in the field of digital watermarking.

D. KEY-FRAME DETECTION ALGORITHM

A video is composed of a group of image frames and contains multiple shots. The frames that covered in each shot are highly correlated. For a video watermarking algorithm, if the watermark is embedded into the same positions of each frame, it will increase the execution time and lead to poor real-time performance. Furthermore, the watermark may be removed by statistical comparisons and averaging, thereby making the watermarking lose its copyright protection ability. To solve this problem, this paper uses a key-frame detection algorithm based on the correlation between adjacent frames. By comparing the correlation coefficients with the predefined threshold T, the key frames that can represent the main content of the video can be detected. The method for calculating the correlation coefficients is shown in (4), as shown at the bottom of this page where F_k and F_{k+1} are the k-th and (k + 1)-th frames of the video of size $M \times N$, respectively, and μ_{F_k} and $\mu_{F_{k+1}}$ are the mean values of F_k and F_{k+1} , respectively. The pseudocode of the key-frame detection process is shown in Algorithm 1.

IV. PROPOSED VIDEO ZERO-WATERMARKING ALGORITHM

In this section, the proposed video zero-watermarking algorithm based on hybrid transforms is presented in detail. The algorithm consists of two parts: zero-watermark generation and zero-watermark detection. The specific steps are explained in the following subsections.

A. ZERO-WATERMARK GENERATION

Fig. 4 shows the generation process of a zero-watermark, and the specific steps are as follows.

$$\rho_{F_k F_{k+1}} = \frac{\sum_{m=0}^{M-1} \sum_{n=0}^{N-1} [F_k(m,n) - \mu_{F_k}][F_{k+1}(m,n) - \mu_{F_{k+1}}]}{\sqrt{\left(\sum_{m=0}^{M-1} \sum_{n=0}^{N-1} [F_k(m,n) - \mu_{F_k}]^2\right) \left(\sum_{m=0}^{M-1} \sum_{n=0}^{N-1} [F_{k+1}(m,n) - \mu_{F_{k+1}}]^2\right)}},$$
(4)

Algorithm 1 Key-Frame Detection Algorithm

Variable Declaration: BasketballDrill: original video sequence *F*: read the video sequence *Y*: luminance components

Num: number of frames in the video

Count: number of extracted key frames

k: location of a frame in the original video

L: locations of extracted key frames

p: correlation coefficients

T: predefined threshold

Key-Frame Detection Procedure:

1: Read the video sequence and obtain *Y* components *F* ← BasketballDrill.yuv (with size of 832×480) *Y* ← b = b = (*T*, 222, 400, *Y*)

 $Y \leftarrow \text{loadyuv}(F, 832, 480, \text{Num})$

2: Parameter initialization

Count $\leftarrow 1$

L(Count) ← 1 // Take the 1st frame as first key frame 3: Calculate correlation coefficients according to (4)

and record locations of key frames

for k = 2:Num do

 $p \leftarrow \operatorname{Corr2}(F_1, F_k)$

if p < T **then** // *T* is adjusted according to the number of selected key frames from each video. Count = Count + 1

 $L(Count) \leftarrow k$

// Determine the *k*-th frame as a key frame

 $F_1 \leftarrow F_k$ // Replace F_1 with F_k , and continue. end if

end for

End Procedure

Step 1: Apply Algorithm 1 to the video sequence to extract the key frames and record their locations.

Step 2: Process the watermark. Use a pseudorandom number generator to generate a pseudorandom sequence. The XOR operation between the sequence and original watermark W is performed to generate the encrypted watermark.

Step 3: Divide the extracted key frames into n groups according to the size of the watermark image.

Step 4: Obtain Y components of all extracted key frames, and apply the DWT to them to obtain four sub-bands: LL, LH, HL, and HH. In this paper, only the LL sub-bands are selected for the subsequent processing.

Step 5: Apply the block-based APBT to the LL sub-bands to obtain the DC coefficient of each block, and then the DC coefficient matrix D can be obtained.

Step 6: Divide **D** into nonoverlapping 4×4 blocks, and apply SVD to each block to obtain singular value matrices.

Step 7: Extract the highest bit of the maximum singular value of each singular value matrix. If the highest bit is odd, then the feature is defined as 1; otherwise, the feature is defined as 0. After traversing all singular value matrices, the final feature sequence can be obtained.

Step 8: Generate the zero-watermark. Apply XOR between the encrypted watermark and the extracted feature sequence. Note that the encrypted watermark is circularly expanded during XOR operations. A zero-watermark sequence can be generated.

Step 9: Register the zero-watermark with an authority organization.

To more comprehensively illustrate the zero-watermark generation process, its pseudocode is shown in Algorithm 2.

B. ZERO-WATERMARK DETECTION

Fig. 5 illustrates the detection process of the zero-watermark, and the specific steps are as follows.

Step 1: Use the recorded location information to extract the key frames from the suspicious video sequence, and then divide them into n groups.

Step 2: Obtain Y components of all extracted key frames, and apply the DWT to them to obtain the LL sub-bands.

Step 3: Apply the block-based APBT to the LL sub-bands to obtain the DC coefficient of each block. The DC coefficient matrix D^* can be obtained.

Step 4: Divide D^* into 4×4 blocks, and apply SVD to each block to obtain the singular value matrices.

Step 5: Extract the highest bit of the maximum singular value of each singular value matrix. If the highest bit is odd, the feature is 1; otherwise, the feature is 0. After traversing all singular value matrices, the final feature sequence can be obtained.

Step 6: Apply XOR between the registered zero-watermark and the extracted feature sequence from the suspicious video. Multiple encrypted watermarks can be obtained.

Step 7: Use the pseudorandom sequence to decrypt these encrypted watermarks, and then *n* reconstructed watermarks can be generated.

Step 8: Postprocess the watermark. Average these *n* reconstructed watermarks to obtain a watermark w_1 . The final reconstructed watermark W^* can be obtained via (5):

$$W^*(i,j) = \begin{cases} 1, & w_1(i,j) > T_1, \\ 0, & w_1(i,j) \le T_1, \end{cases}$$
(5)

where T_1 is a predefined threshold in the range of [0.1, 0.5].

Step 9: Compare the correlation between W^* and W and evaluate the robustness of the algorithm.

To more comprehensively illustrate the zero-watermark detection process, its pseudocode is shown in Algorithm 3.

V. EXPERIMENTAL RESULTS AND ANALYSIS

In this section, to evaluate the performance of the proposed algorithm, several experiments are performed using MAT-LAB R2014a on an Intel Core i5-4590 3.30 GHz CPU. Twenty video files are prepared as carrier videos. In this paper, we select four representative video sequences of size 832×480 to illustrate experimental results, which include BasketballDrill, BQMall, PartyScene, and RaceHorses [35]. In addition, the performance of the proposed algorithm on other videos with different resolutions, including



FIGURE 4. Framework of the proposed zero-watermark generation process.



FIGURE 5. Framework of the proposed zero-watermark detection process.

FourPeople (1280×720), BQTerrace (1920×1080), and Traffic (2560×1600), is shown in subsection I. The objects in BasketballDrill and RaceHorses move intensely. The objects in Traffic move moderately, and the objects in FourPeople move slowly. BQMall and BQTerrace are inhomogeneous, and PartyScene has complex textures. The first 100 frames of each video are selected for the experiments. A binary image marked "SDU" with a size of 30×26 is used as the watermark image.

Since the zero-watermarking algorithm does not modify the original video, it will not have any impact on the videos' quality. As a result, zero-watermarking algorithms have good imperceptibility. The peak signal-to-noise ratio (PSNR) and structural similarity (SSIM) index are two commonly used indexes to evaluate the imperceptibility, and their definitions are shown as (6) and (7), respectively.

$$PSNR = 10 \log_{10} \frac{255^2}{MSE} (dB),$$
(6)

$$SSIM(f, f_w) = \frac{(2\mu_f \mu_{f_w} + C_1)(2\sigma_{ff_w} + C_2)}{(\mu_f^2 + \mu_{f_w}^2 + C_1)(\sigma_f^2 + \sigma_{f_w}^2 + C_2)}, \quad (7)$$

where the mean square error (MSE) can be defined as:

$$MSE = \frac{1}{M \times N} \sum_{i=1}^{M} \sum_{j=1}^{N} [f(i,j) - f_{w}(i,j)]^{2}, \qquad (8)$$

where f and f_w are the original and watermarked video frames of size $M \times N$, respectively. In addition, μ_f and μ_{f_w} represent the mean values of f and f_w , respectively. σ_f and σ_{f_w} are the variances of f and f_w , respectively. σ_{ff_w} denotes the covariance of f and f_w , and C_1 and C_2 are two constants to maintain the stability. The higher the PSNR and SSIM are, the better the imperceptibility is. The normalized correlation coefficient (NCC) and bit error rate (BER) are selected as robustness evaluation indexes. The higher the NCC and the lower the BER are, the better the robustness of the algorithm is. The definition of the NCC is shown as (9), and the BER is defined in (10):

NCC =
$$\frac{\sum_{i=1}^{M} \sum_{j=1}^{N} W(i, j) \times W^{*}(i, j)}{\sum_{i=1}^{M} \sum_{j=1}^{N} W(i, j)^{2}},$$
(9)

BER =
$$\frac{1}{M \times N} \sum_{i=1}^{M} \sum_{j=1}^{N} |W(i,j) - W^*(i,j)| \times 100\%$$
, (10)

where W and W^* denote the original watermark and extracted watermark of size $M \times N$, respectively. The NCC is adopted to estimate the similarity between W^* and W, and the BER is adopted to estimate the error rate between W^* and W.

Variable Declaration: F_i : read the original video sequence F_i : lexprimes sequence declaration: F_i : lexprimes sequence declaration of extracted key framesCount::::::::::::::::::::::::::::::::::::	Algorithm 2 Zero-Watermark Generation	Algorithm 3 Zero-Watermark Detection
$F:$ read the original video sequence $F_i:$ key-frame sequence $F_i:$ key-frame sequence $F_i:$ extracted key-frame sequence $W_i:$ creather watermark image $W:$ read the watermark image $W:$ reacher watermark $W:$ reacher water mark $W:$ reacher water mark $W:$ reacher of each S_m $F:$ luminance components $D:$ DC coefficient matrix $S:$ singular value of each singular valuematrix in string form $S_m:$ highest bit of each S_m $F_i:$ extracted feature of each block $W:$ generated zero-watermark $W:$ generated zero-watermark $Zero-Watermark Generation Procedure:I: Read the video sequence and extract key framesF \leftarrow BaskethallDrilly uv (video frames with sizef \leftarrow AsstethallDrilly uv (video frames with sizef \leftarrow AsstethallDrill, uv (video frames with sizef \leftarrow AsstethallDrill, uv (video framesW \leftarrow SDU (with size of 30 \times 26)m \leftarrow AsstethallDrill, uv (video frames do$	Variable Declaration:	Variable Declaration:
F_k : key-frame sequence according to the record docations L L : locations of extracted key frames SDU: watermark image m : pseudorandom sequence W : eather watermark image m : pseudorandom sequence W : encrypted watermark S : singular value matrix S : singular value of each singular value matrix in string form S_m : highest bit of each S_m F_c : extracted feature of each block W_c : generated zero-watermark Z tore-Watermark Generation Procedure: 1 F_c : extracted feature of each S_m F_c : extracted feature of each block W_c : generated zero-watermark Z tore-Watermark Generation Procedure: 1 W_c : Coefficient matrix S_m : highest bit of each S_m F_c : extracted feature of each block W_c : generated zero-watermark Z tore-Watermark Demention for coefficient F_c : extracted feature of each block W_c : generated zero-watermark Z tore-Watermark Demention Sequence and extract key frames F_c : extracted feature of each block W_c : generated zero-watermark W_c : SDU (with size of 30 × 26) $m \leftarrow randint(1, 30 × 26)$ $m \leftarrow randint(1, 30 × 26)$ $M_c \leftarrow XOR(W, m)$ 31Item extraction $F^* \leftarrow suspicious BasketballDrill yuvF_k^* = curre extractionT \leftarrow loadynv(F_k^*, 832, 480, 2n)for n groups of key frames do[LL^*, LH^*, HL^*, HH^*] \leftarrow DWT(Y)D \leftarrow APBT(LL)U \leq SV V - SVD(D')S_m^* = num2str(max(S^*))S_m^* = num2str(m$	F: read the original video sequence	F^* : read the suspicious video sequence
<i>L</i> : locations of extracted key frames <i>C</i> ount: number of extracted key frames SDU: watermark image <i>W</i> : read the watermark image <i>w</i> : percented near and intermated image <i>W</i> : read the watermark image <i>w</i> : percented near and <i>w</i> : <i>w</i> : <i>w</i> : number of key-frame groups <i>Y</i> : luminance components <i>D</i> : DC coefficient matrix <i>S</i> : singular value of each singular value matrix in string form <i>S</i> : luminance components <i>D</i> : DC coefficient matrix <i>S</i> : singular value of each singular value matrix in string form <i>S</i> : luminance components <i>D</i> : DC coefficient matrix <i>S</i> : singular value of each singular value matrix in string form <i>S</i> : luminance components <i>D</i> : DC coefficient matrix <i>S</i> : singular value of each singular value matrix in string form <i>S</i> : luminance components <i>D</i> : DC coefficient matrix <i>S</i> : singular value of each singular value matrix in string form <i>S</i> : learnerark <i>Generocealure</i> : <i>I</i> : Read the video sequence and extract key frames <i>F</i> : extracted feature of each block <i>W</i> : generarated zero-watermark <i>F</i> : extracted feature of each block <i>W</i> : generated zero-watermark <i>F</i> : extracted feature of each block <i>W</i> : generated zero-watermark <i>F</i> : deathe suspicious video sequence and extract key frames <i>F</i> : <i>F</i> esture extraction <i>m</i> $\leftarrow randin(1, 30 \times 26)$ <i>w</i> : $\leftarrow XOR(W, R, m)$ <i>I</i> : [<i>L</i> , <i>L</i> , <i>H</i>]. <i>H</i> , <i>H</i> , <i>H</i>] $\leftarrow DNT(Y)$ <i>D</i> : $\leftarrow APBT(1L^*)$ <i>I</i> : <i>R</i> ead the suspicious video sequence frame <i>A</i> <i>I</i> : <i>R</i> ead the suspicious video sequence frame <i>A</i> <i>I</i> : <i>R</i> = 1 <i>e</i> end for <i>I</i> : <i>R</i> = 1 <i>e</i> end for <i>I</i> : <i>R</i> = 1 <i>e</i> end for <i>W</i> : $\leftarrow XOR(W_{E}, F_{w})$ <i>X</i> : <i>C</i> : <i>CoN</i> : <i>W</i> : <i>F</i> : <i>w</i> : <i>x</i> : <i>C</i> : <i>w</i>	F_k : key-frames sequence	F_{k}^{*} : extracted key-frame sequence according to the
Count: number of extracted key frames SDU: vatermark image W_{12} : encrypted watermark w_{12} : encrypted watermark w_{12} : encrypted watermark w_{12} : encrypted watermark D: DC coefficient matrix S_{m}^{*} : maximum singular value of each singular value matrix in string form S_{m}^{*} : ingular value of each singular value matrix in string form S_{m}^{*} : ingular value of each singular value matrix in string form S_{m}^{*} : extracted feature of each block W_{2} : cereated zero-watermark W_{2} : cereater cereatemark W_{2} : cereater cereatemark W_{2} : cereater cereatemark W_{2} : cereater cereatemark W_{2} : cereater cereatemark W_{3} : cereater cereatemark $W_{4} \in \Delta Out \leftarrow Key$ -frame Detection Algorithm 2: Watermark preprocessing $W \leftarrow SDU (With size of 30 \times 26)$ $W_{5} \leftarrow XOR(W, m)$ 3: Feature extraction $m \leftarrow randim(1, 30 \times 26)$ $W_{6} \leftarrow XOR(W, m)$ 3: Feature extraction $m \leftarrow randim(1, 30 \times 26)$ $W_{6} \leftarrow XOR(W, m)$ 3: Feature extraction $m \leftarrow randim(1, 30 \times 26)$ $W_{6} \leftarrow XOR(W, m)$ 3: Feature extraction $m \leftarrow randim(1, 30 \times 26)$ $S_{m} \leftarrow numzert(max(S))$ $S_{m} \leftarrow n$	L: locations of extracted key frames	recorded locations L
SDU: watermark image W: read the watermark image W: read the watermark image W: read the watermark image W: generypted watermark D: DC coefficient matrix S: singular value of each singular value matrix in string form S: imminume components D: DC coefficient matrix S: singular value of each singular value matrix in string form S: singular value of each block W: generypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encrypted watermarks, which contain W_{D_1} , W_{D_2} , W_E ; encore extraction $W \in SDU (With size of 30 × 26)$ $W_E \leftarrow XOR(W, m)$ 3: Feature extraction $W \in SDU(D)$ $S_{mh} \leftarrow S_m(1)$ if mod(S_{mh} , 2) = 1 then $F_{\pi} = 1$ $else F_{\pi}^* = 0$ $end for W_E \leftarrow XOR(W_E, m) // W_D = (W_{D_1}, W_{D_2}, \cdots, W_{D_n})W_E \leftarrow XOR(W_E, F_{mo})End Procedure$	Count: number of extracted key frames	<i>n</i> : number of key-frame groups
W: read the watermark image m: pseudorandom sequenceD: DC coefficient matrix S': singular value of each singular value matrix in string formm: the number of groups of key frames F: buninance components S: singular value matrixD: DC coefficient matrix S': singular value matrixM: the number of groups of key frames F: buninance components S: singular value matrixD: DC coefficient matrix S': singular value matrixM: the number of groups of key frames F: buninance components S: singular value matrixD: DC coefficient matrix S': singular value matrixM: the number of groups of key frames F: buninance components S: singular value matrixD: DC coefficient matrix S': singular value matrixM: the number of groups of key frames f: buninance components S: singular value matrixD: DC coefficient matrix S': singular value matrixM: the number of groups of key frames for disting from 0 S: generated zero-watermarkD: DC coefficient matrix S': singular value matrixM: the disting from 0 S: generated zero-watermarkD: D: coefficient matrix S': singular value matrixM: the wideo sequence and extract key frames for dist of a00 × 260 W: the Count - mod(Count, 2)/2 // Divide key frames into n groupsD: Decoefficient matrixS: the number of groups of key frames do [LL:, LH, H, HL], HD: DWT(Y) D + APBT(LL) D + APBT(LL)D: Hen F: a 1 eds f: a 0 end if end for end if end for <td>SDU: watermark image</td> <td>Y: luminance components</td>	SDU: watermark image	Y: luminance components
m: pseudorandom sequence $W_{\rm fi}:$ encrypted watermark $w_{\rm fi}:$ encomponents $F:$ luminance components $F:$ luminance components $F:$ luminance components $F:$ luminance components $F:$ contracted feature of each singular valuematrix in string form $S_{\rm mi}:$ maximum singular value of each singular valuematrix in string form $S_{\rm mi}:$ maximum singular value of each singular valuematrix instring form $S_{\rm mi}:$ highest bit of each $S_{\rm m}$ $F_{\rm i}:$ extracted feature of each block $W_{\rm i}:$ generated zero-watermark $Zero-Watermark Generation Procedure:1: Read the video sequence and extract key framesF \leftarrow BasketballDrill.yuv (video frames with sizeof 832 × 480F_{\rm i}: L. Court \leftarrow Key-frame Detection Algorithm2: Watermark preprocessingW \leftarrow SDU (with size of 30 × 26)m \leftarrow randim(1, 30 × 26)m \leftarrow randim(1, 30 × 26)W_{\rm E} \leftarrow XOR(W, m)3: Feature extractionn \leftarrow Clount - mod(Count, 2)/2 // Divide key framesinto n groups of key frames do[LL^*, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[U S V] \leftarrow SVD(D)S_{m} \leftarrow mandit(T, S) \sim SD_0S_m \leftarrow mandit(T, S) \sim SD_0S_m \leftarrow nundstr(max(S))S_m \leftarrow nundstr(max(S))$	W: read the watermark image	D^* : DC coefficient matrix
W_E^{\pm} encrypted watermark S_m^{\pm} : impact and use of each singular value m : the number of groups of key frames S_m^{\pm} : impact and use of each singular value $T:$ huminance components $D:$ DC coefficient matrix S_m^{\pm} : singular value matrix S_m^{\pm} : impact bit of each S_m^{\pm} S_m^{\pm} : highest bit of each S_m^{\pm} F_n^{\pm} : extracted feature of each block W_{n-1}^{\pm} : generated zero-watermark W_n^{\pm} : encrypted watermarks, which contain $W_{D_1}, W_{D_2}, \dots, W_{D_n}$ $Zero-Watermark Generation Procedure:T: predefined threshold1: Read the video sequence and extract key framesF \leftarrow BasketballDrill,yuv (video frames with sizeof 832 x 480)F \& L. Count \leftarrow Key-frame Detection AlgorithmZero-Watermark Detection Procedure:1: Read the video sequence and extract key framesmerandim(1, 30 × 26)W \leftarrow SDU (with is zero 30 × 26)m \leftarrow randim(1, 30 × 26)W \leftarrow Count - Mol (Count, 2)]/2 // Divide key framesinto n groups of key frames do[L1, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)W \leftarrow SVD(D)S_m \leftarrow num2str(max(S))S_m^{\pm} \leftarrow and S^{\pm}(1)S_m \leftarrow mun2str(max(S))S_m^{\pm} \leftarrow Sm^{\pm}(1)S_m \leftarrow end ifend ifend ifedf orK_n^{\pm} \leftarrow XOR(W_n, F_n^{\pm})4: Zero-watermark generationW_2 \leftarrow XOR(W_n, F_n)W_2 \leftarrow XOR(W_n, F_n^{\pm})4: Zero-watermark generationW_2 \leftarrow XOR(W_n, F_n^{\pm})4: Zero-watermark generationW_2 \leftarrow XOR(W_n, F_n^{\pm})5: Material sequence F_{sc} can be obtained bycomposing all F_s6: Material F_s6: Material F_s6: Material F$	<i>m</i> : pseudorandom sequence	S^* : singular value matrix
n: the number of groups of key framesn: the number of groups of key framesN: the number of groups of key framesN: D: DC coefficient matrixS: singular value matrixS: singular v	$W_{\rm E}$: encrypted watermark	S_{m}^{*} : maximum singular value of each singular value
Y: luminance components D: DC coefficient matrixS m: maximum singular value matrixD: DC coefficient matrixS singular value matrixS: singular value matrixS m: maximum singular value of each singular value matrix in string form Sm: thighest bit of each Sm m F_: extracted feature of each blockSm: sing form Sm: instruction F_: extracted feature of each blockS m: preudorandom sequence T_: predefined thresholdWith size of 832 × 4800 F_i, L. Count \leftarrow Key-frame Detection AlgorithmThe feature sequence frame Detection Algorithm2: Watermark preprocessing W \leftarrow SDU (with size of 30 × 26) m \leftarrow -randint(1, 30 × 26) WE \leftarrow XOR(W, m)The feature sequence form F*3: Feature extraction n \leftarrow -[Count -mod(Count, 2)]/2 // Divide key frames into n groups of key frames do [LL, LH, HL, HH] \leftarrow DWT(Y) D \leftarrow APBT(LL) [LL, LH, HL, HH] \leftarrow DWT(Y) D \leftarrow APBT(LL) [LL SV] $-$ SVD(D) Sm_h \leftarrow Sm(1) if mod(Sm_h, 2) = 1 then F_s = 1 end if end for // The feature sequence F_sc can be obtained by composing all F_s 3: Obtain encrypted watermarks and decrypt them WE \leftarrow XOR(WE, F_{sc}) End ProcedureWith \leftarrow Methor Mathematic sequence form for (With Size of form for the feature sequence form for (With feature sequence form for th	<i>n</i> : the number of groups of key frames	matrix in string form
D: DC coefficient matrix S: singular value matrix S: singular value matrix S: singular value of each singular value matrix in string form Such: highest bit of each Sing F: extracted feature of each block W: registered zero-watermark Zero-Watermark Generation Procedure: 1: Read the video sequence and extract key frames F ← BasketballDrill.yuv (video frames with size of 832 × 480) F & Count ← Key-frame Detection Algorithm 2: Watermark preprocessing W ← SDU (with size of 30 × 26) m ← randinf(1, 30 × 26) W ← SDU (with size of 30 × 26) m ← randinf(1, 30 × 26) W ← SDU (with size of 30 × 26) m ← randinf(1, 30 × 26) W ← SDU (with size of 30 × 26) m ← randinf(1, 30 × 26) W ← ADBT(LL) [LL, LH, HL, HH] ← DWT(Y) D ← APBT(LL) [US V] ← SVD(D) Smh ← Sm(1) if mod(Smh, 2) = 1 then F_* = 1 end if end for Wz ← XOR(Wz, F_{sc}) Zero-watermark generation Wz ← XOR(Wz, F_{sc}) End Procedure $W_1 ← \frac{W_{p1}+W_{p2}+\dots W_{pn}}{W_{p1}+W_{p2}+\dots W_{pn}}$ (W = $\frac{W_{p1}+W_{p2}+\dots W_{pn}}{W_{p1}+W_{p2}+\dots W_{pn}}$	Y: luminance components	S_{mh}^* : highest bit of each S_m^*
S: singular value matrix S_{mi} : maximum singular value of each singular value matrix in string form S_{mb} : highest bit of each S_m F_c ; extracted feature of each block W_2 ; generated zero-watermark Zero-Watermark Generation Procedure: 1: Read the video sequence and extract key frames $F \leftarrow BasketballDrill.yuv (video frames with size of 832 × 480) F_k, L, Count \leftarrow Key-frame Detection Algorithm2: Watermark preprocessingW \leftarrow SDU (with size of 30 × 26)m \leftarrow randint(1, 30 × 26)W_E \leftarrow XOR(W, m)3: Feature extractionn \leftarrow [Count - mod(Count, 2)]/2 // Divide key frames into n groups of key frames do [LL*, LH*, HL*, HH*] \leftarrow DWT(Y)D \leftarrow APBT(LL)[LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[LL, LH, HL, HH] \leftarrow DWT(Y)S_m \leftarrow num2str(max(S))S_m \leftarrow S_m(1)if mod(S_{mh}, 2) = 1 thenF_s^* = 1end ifend forF_s = 1end$ if end for $F_s = 1$ end if end	D : DC coefficient matrix	F_{c}^{*} : extracted feature of each block
S _m : maximum singular value of each singular value matrix in string form S _m : maximum singular value of each singular value matrix in string form S _m : highest bit of each S _m F _s : extracted feature of each block W _z : generated zero-watermark Zero-Watermark Generation Procedure: 1: Read the video sequence and extract key frames F ← BasketballDrill.yuv (video frames with size of 832 × 480) F _k , L, Count ← Key-frame Detection Algorithm 2: Watermark preprocessing W ← SDU (with size of 30 × 26) m ← randint(1, 30 × 26) W _E ← XOR(W, m) 3: Feature extraction n ← [Count - mod(Count, 2)]/2 // Divide key frames into n groups for n groups of key frames do [LL, LH, HL, HLH] ← DWT(Y) D ← APBT(LL) [U S V] ← SVD(D) S _m ← num2str(max(S)) S _m ← num2str(max(S)) S _m ← num2str(max(S)) S _m ← num2str(max(S)) S _m ← competing all F _s 4: Zero-watermark generation W _z ← XOR(W _E , F _{sc}) End Procedure $W_1 \leftarrow \frac{W_{L}+W_{L}+W_{L}}{W_{L}+W_{D_{2}}+\dots+W_{D_{n}}}$ (W W1 ← $\frac{W_{L}+W_{D_{2}}+\dots+W_{D_{n}}}{W_{L}}$ (W 20, $\frac{W_{L}+W_{D_{2}}+\dots+W_{D_{n}}}{W_{L}}$)	S: singular value matrix	W_{z} : registered zero-watermark
matrix in string form S_{mi} : highest bit of each S_{m} F_{ij} : extracted feature of each block W_{2} : generated zero-watermark Zero-Watermark Generation Procedure: 1: Read the video sequence and extract key frames $F \leftarrow BasketballDrill.yuv (video frames with size of 832 × 480) F_{k,L}, Count \leftarrow Key-frame Detection Algorithm2: Watermark preprocessingW \leftarrow SDU (with size of 30 × 26) m \leftarrow randint(1, 30 × 26)W \leftarrow SDU (with size of 30 × 26) m \leftarrow randint(1, 30 × 26)W \leftarrow SDU (with size of 30 × 26)m \leftarrow randint(1, 30 × 26)W \leftarrow SDU (with size of 30 × 26)m \leftarrow randint(1, 30 × 26)W \leftarrow SDU (with size of 30 × 26)m \leftarrow randint(1, 30 × 26)W \leftarrow AOR(W, m)3: Feature extractionn \leftarrow [Count - mod(Count, 2)]/2 // Divide key frames into n groups of key frames do [LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[U S V I < SV(D)DS_{mh} \leftarrow S_{m}(1)if mod(S_{mh}, 2) = 1 thenF_{s}^{*} = 1end ifend forW_{z} \leftarrow XOR(W_{E}, F_{sc})// The feature sequence F_{sc} can be obtained bycomposing all F_{s}^{*}3: Obtain encrypted watermarks and decrypt themW_{L}^{*} \leftarrow XOR(W_{E}, F_{sc})4: Zero-watermark generationW_{z} \leftarrow XOR(W_{E}, F_{sc})End Procedure$	$S_{\rm m}$: maximum singular value of each singular value	$W_{\rm E}^*$: encrypted watermarks
S _{nh} : highest bit of each S _m <i>F</i> _s : extracted feature of each block <i>W_z</i> : generated zero-watermark Zero-Watermark Generation Procedure: 1: Read the video sequence and extract key frames <i>F</i> ← BasketballDrill.yuv (video frames with size of 832 × 480) 2: Watermark preprocessing <i>W</i> ← SDU (with size of 30 × 26) <i>m</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W</i> , <i>m</i>) 3: Feature extraction <i>n</i> ← randint(1, 30 × 26) <i>W_E</i> ← XOR(<i>W_E</i> , <i>s</i>) = 1 then <i>F_s</i> = 1 else <i>F_s</i> = 0 end if end for <i>V_T</i> The feature sequence <i>F_{se}</i> can be obtained by composing all <i>F_s</i> 4: Zero-watermark generation <i>W_z</i> ← XOR(<i>W_E</i> , <i>F_{se}</i>) End Procedure <i>W_E</i> ← XOR(<i>W_E</i> , <i>F_{se}</i>) End Procedure	matrix in string form	$W_{\rm D}^{\pm}$: decrypted watermarks, which contain $W_{\rm D_1}, W_{\rm D_2},$
$F_s:$ extracted feature of each block $m:$ pseudorandom sequence $F_s:$ extracted zero-watermark $m:$ pseudorandom sequence $V:$ generated zero-watermark $m:$ pseudorandom sequence $V:$ sequence and extract key frames $F \leftarrow$ BasketballDrill.yuv (video frames with size of 832 × 480) $m:$ pseudorandom sequence $V:$ matermark preprocessing $W \leftarrow$ SDU (with size of 30 × 26) $m \leftarrow$ randint(1, 30 × 26) $W_E \leftarrow$ XOR(W, m) $M:$ cattract key frames $F^* \leftarrow$ extracted key-frame sequence from F^* 3: Feature extraction $m \leftarrow$ randint(1, 30 × 26) $W_E \leftarrow$ XOR(W, m) $M:$ cattract key frames do $[LL^*, LH^*, HL^*, HH^*] \leftarrow DWT(Y)$ $D \leftarrow$ APBT(LL) $[LL, LH, HL, HH] \leftarrow DWT(Y)$ $D \leftarrow$ APBT(LL) $[U S V] \leftarrow SVD(D)$ $S_m^* \leftarrow nun2str(max(S))$ $S_m^* \leftarrow nun2str(max(S))$ $S_m^* \leftarrow nun2str(max(S))$ $S_m^* \leftarrow nun2str(max(S))$ $S_m^* \leftarrow Sun(1)$ if mod($S_{mh}^*, 2) = 1$ then $F_s^* = 1$ else $F_s^* = 0$ end if end for M' The feature sequence F_{sc} can be obtained by composing all F_s^* 3: Obtain encrypted watermarks and decrypt them $W_E^* \leftarrow XOR(W_E, F_{sc})$ $W_D^* \leftarrow XOR(W_E, F_{sc})$ 4: Zero-watermark generation $W_2 \leftarrow XOR(W_E, F_{sc})$ $W_1 \leftarrow W_{b+}W_{b-} + W_{b-}$ 4: Zero-watermark generation $W_2 \leftarrow XOR(W_E, F_{sc})$ $W_1 \leftarrow W_{b+}W_{b-} + W_{b-}M_{b-}$ 6: def Procedure $W_1 \leftarrow W_{b+}W_{b-} + W_{b-}M_{b-}$	$S_{\rm mh}$: highest bit of each $S_{\rm m}$	$W_{\rm D}$
W_z : generated zero-watermark $Zero-Watermark Generation Procedure:1: Read the video sequence and extract key framesF \leftarrow BasketballDrill.yuv (video frames with sizeof 832 \times 480)F_k, L, Count \leftarrow Key-frame Detection Algorithm2: Watermark preprocessingW \leftarrow SDU (with size of 30 \times 26)m \leftarrow randint(1, 30 \times 26)W \leftarrow SDU (with size of 30 \times 26)m \leftarrow randint(1, 30 \times 26)W \leftarrow SDU (with size of 30 \times 26)m \leftarrow randint(1, 30 \times 26)W \leftarrow SDU (with size of 30 \times 26)m \leftarrow randint(1, 30 \times 26)W \leftarrow SDU (with size of 30 \times 26)m \leftarrow randint(1, 30 \times 26)W \leftarrow SDU (Wm)3: Feature extractionn \leftarrow [Count - mod(Count, 2)]/2 // Divide key framesinto n groups of key frames do[LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[U S V] \leftarrow SVD(D)S_m \leftarrow nun2str(max(S))from groups of key frames do[LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[U S V] \leftarrow SVD(D)S_m \leftarrow nunztr(max(S))S_m \leftarrow nunztr(ma$	F_s : extracted feature of each block	<i>m</i> : pseudorandom sequence
Zero-Watermark Generation Procedure:1: Read the video sequence and extract key frames $F \leftarrow$ BasketballDrill.yuv (video frames with size of 832 × 480) $F_k, L, Count \leftarrow Key-frame Detection Algorithm2: Watermark preprocessingW \leftarrow SDU (with size of 30 × 26)m \leftarrow randint(1, 30 × 26)W_E \leftarrow XOR(W, m)3: Feature extractionn \leftarrow [Count - mod(Count, 2)]/2 // Divide key framesinto n groups of key frames do[LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[US V] \leftarrow SVD(D)S_m \leftarrow nun2str(max(S))S_m \leftarrow nun2str(max(S))S_m \leftarrow S_m(1)if mod(S_{mh}, 2) = 1 thenF_s = 1end ifend for// The feature sequence F_{se} can be obtained bycomposing all F_s4: Zero-watermark generationW_z \leftarrow XOR(W_E, F_{se})End ProcedureW: \leftarrow Watermark postprocessing and watermark recon-structionW: \leftarrow W_{1+WD_2}+\cdots+W_{Dn}\leftarrow W_{1}+W_{D2}+\cdots+W_{Dn}$	W_{z} : generated zero-watermark	T_1 : predefined threshold
1: Read the video sequence and extract key frames $F \leftarrow BasketballDrill.yuv (video frames with size of 832 × 480) F_k, L, Count ← Key-frame Detection Algorithm2: Watermark preprocessingW \leftarrow SDU (with size of 30 × 26)m \leftarrow randin(1, 30 × 26)W_E \leftarrow XOR(W, m)3: Feature extractionn \leftarrow [Count - mod(Count, 2)]/2 // Divide key frames into n groups of key frames do [LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[US V] \leftarrow SVD(D)S_{m} \leftarrow num2str(max(S))S_{mh} \leftarrow S_{m}(1)if mod(S_{mh}, 2) = 1 thenF_s = 1end ifend ifend for// The feature sequence F_{se} can be obtained bycomposing all F_s4: Zero-watermark generationW_z \leftarrow XOR(W_E, F_{se})End Procedure2: Feature extractionW_z \leftarrow XOR(W_E, F_{se})End ProcedureZero-Watermark Detection Procedure:1: Read the suspicious video sequence and extract keyframesF^* \leftarrow suspicious BasketballDrill.yuv F_*^* \leftarrow suspicious Basket$	Zero-Watermark Generation Procedure:	W^* : final reconstructed watermark
$F \leftarrow$ BasketballDrill.yuv (video frames with size of 832×480)1: Read the suspicious video sequence and extract key frames $F_k, L, Count \leftarrow Key-frame Detection Algorithm1: Read the suspicious video sequence and extract keyframes2: Watermark preprocessingW \leftarrow SDU (with size of 30 \times 26)m \leftarrow randint(1, 30 \times 26)W_E \leftarrow XOR(W, m)1: Read the suspicious video sequence and extract keyframes3: Feature extractionn \leftarrow [Count - mod(Count, 2)]/2 // Divide key framesinto n groups of key frames do[LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[U S V] \leftarrow SVD(D)S_m \leftarrow num2str(max(S))S_m \leftarrow num2str(max(S))S_m \leftarrow num2str(max(S))S_m \leftarrow num2str(max(S))S_m \leftarrow S_m(1)if mod(S_{mh}, 2) = 1 thenF_s = 1end ifend for// The feature sequence F_{se}^* can be obtained bycomposing all F_s1: Read the suspicious video sequence and extract keyframesF^* \leftarrow suspicious BasketballDrill.yuvF_k^* \leftarrow extractionY \leftarrow loadyuv(F_k^*, 832, 480, 2n)for n groups of key frames do[LL^*, LH^*, HL^*, HH^*] \leftarrow DWT(Y)D^* \leftarrow APBT(LL^*)[U^* S^* V^*] \leftarrow SVD(D^*)S_m^* \leftarrow num2str(max(S))S_m^* \leftarrow num2str(max(S))S_m^* \leftarrow S_m^*(1)if mod(S_{mh}, 2) = 1 thenF_s^* = 1else F_s^* = 0end ifend for// The feature sequence F_{se}^* can be obtained bycomposing all F_s^*4: Zero-watermark generationW_{\Sigma} \leftarrow XOR(W_E, F_{se})End Procedure2: Watermark postprocessing and watermark recon-structionW_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\cdots+W_{D_n}}{M_{D_1}^*}4: Watermark postprocessing and watermark recon-structionW_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\cdots+W_{D_n}}{M_{D_1}^*}$	1: Read the video sequence and extract key frames	Zero-Watermark Detection Procedure:
of 832×480) $F_k, L, Count \leftarrow Key-frame Detection Algorithm 2: Watermark preprocessing W \leftarrow SDU (with size of 30 \times 26)m \leftarrow randint(1, 30 \times 26)W_E \leftarrow XOR(W, m)3: Feature extractionn \leftarrow [Count - mod(Count, 2)]/2 // Divide key frames into n groups of key frames do [LL, LH, HL, HL] \leftarrow DWT(Y)D \leftarrow APBT(LL)[U S V] \leftarrow SVD(D)S_m \leftarrow num2str(max(S))S_m \leftarrow num2str(max(S))S_m \leftarrow num2str(max(S))S_m \leftarrow num2str(max(S))S_m \leftarrow num2str(max(S))S_m \leftarrow S_m(1)if mod(S_{mh}^{-}, 2) = 1 thenF_s = 1end ifend ifend forF_s = 1end ifend for W_z \leftarrow XOR(W_z, F_{sc})End ProcedureW_1 \leftarrow \frac{W_{D1}+W_{D2}+\cdots+W_{Dn}}{W_1 \leftarrow 20, \frac{m}{2}}W_1 \leftarrow \frac{W_{D1}+W_{D2}+\cdots+W_{Dn}}{W_1 \leftarrow 20, \frac{m}{2}}$	$F \leftarrow \text{BasketballDrill.vuv}$ (video frames with size	1: Read the suspicious video sequence and extract key
F_k, L , Count \leftarrow Key-frame Detection Algorithm2: Watermark preprocessing $W \leftarrow$ SDU (with size of 30×26) $m \leftarrow$ randint(1, 30×26) $W_E \leftarrow XOR(W, m)$ $F^* \leftarrow$ suspicious BasketballDrill.yuv $F_k^* \leftarrow$ extracted key-frame sequence from F^* 3: Feature extraction $n \leftarrow$ [Count - mod(Count, 2)]/2 // Divide key frames into n groups of key frames do [LL, LH, HL, HH] \leftarrow DWT(Y) $D \leftarrow$ APBT(LL) [U S V] \leftarrow SVD(D) $S_m \leftarrow$ num2str(max(S)) $S_m \leftarrow$ num2str(max(S)) $S_m \leftarrow num2str(max(S))$ $S_m \leftarrow num2str(max(S))$ $S_m \leftarrow S_m(1)$ if mod($S_{mh}^*, 2$) = 1 then $F_s = 1$ $end ifend for// The feature sequence F_{se} can be obtained bycomposing all F_sF^* \leftarrow Suspicious BasketballDrill.yuvF_k^* \leftarrow extracted key-frame sequence from F^*4: Zero-watermark generationW_Z \leftarrow XOR(W_E, F_{se})F^* \leftarrow suspicious BasketballDrill.yuvF_k^* \leftarrow extracted key-frame sequence from F^*4: Zero-watermark generationW_Z \leftarrow XOR(W_E, F_{se})F^* \leftarrow suspicious BasketballDrill.yuvF_k^* \leftarrow extracted key-frame sequence from F^*4: Zero-watermark generationW_Z \leftarrow XOR(W_E, F_{se})F^* \leftarrow suspicious BasketballDrill.yuvF_k^* \leftarrow stracted key-frame sequence from F^*4: Zero-watermark generationW_Z \leftarrow XOR(W_E, F_{se})F^* \leftarrow and procedure4: Watermark postprocessing and watermark reconstructionW_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\cdots+W_{D_n}}{W_{D_n}+W_{D_1}+W_{D_2}+\cdots+W_{D_n}}$	of 832 × 480)	frames
2: Watermark preprocessing $W \leftarrow SDU$ (with size of 30 × 26) $m \leftarrow randint(1, 30 × 26)$ $W_E \leftarrow XOR(W, m)$ 3: Feature extraction $n \leftarrow [Count - mod(Count, 2)]/2 // Divide key frames into n groups for n groups of key frames do [LL, LH, HL, HH] \leftarrow DWT(Y)D \leftarrow APBT(LL)[U S V] \leftarrow SVD(D)S_{mh} \leftarrow S_m(1)if mod(S_{mh}, 2) = 1 thenF_s = 1end for F_s = 1end for F_s = 1end for W_z \leftarrow XOR(W_E, F_{sc})End ProcedureW_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\dots+W_{D_n}}{W_1 \leftarrow W_{D_1}+W_{D_2}+\dots+W_{D_n}}4: Watermark postprocessing and watermark recon-structionW_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\dots+W_{D_n}}{W_1 \leftarrow W_{D_1}+W_{D_2}+\dots+W_{D_n}}$	F_k, L , Count \leftarrow Key-frame Detection Algorithm	$F^* \leftarrow$ suspicious BasketballDrill.yuv
$W \leftarrow SDU (with size of 30 × 26)$ $m \leftarrow randint(1, 30 × 26)$ $W_E \leftarrow XOR(W, m)$ 3: Feature extraction $n \leftarrow [Count - mod(Count, 2)]/2 // Divide key frames into n groups of key frames do [LL^*, LH^*, HL^*, HH^*] \leftarrow DWT(Y) D \leftarrow APBT(LL) [U S V] \leftarrow SVD(D) S_m \leftarrow num2str(max(S)) S_m \leftarrow S_m(1) if mod(S_mh, 2) = 1 then F_s = 1 end if end for // The feature sequence F_{se} can be obtained by composing all F_s 4: Zero-watermark generation W_z \leftarrow XOR(W_E, F_{se}) End Procedure W_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\cdots+W_{D_n}}{(W_1 \leftarrow W_{D_1}+W_{D_2}+\cdots+W_{D_n})}$	2: Watermark preprocessing	$F_{L}^{*} \leftarrow$ extracted key-frame sequence from F^{*}
$m \leftarrow \operatorname{randin}(1, 30 \times 26)$ $W_{\rm E} \leftarrow \operatorname{XOR}(W, m)$ 3: Feature extraction $n \leftarrow [\operatorname{Count} - \operatorname{mod}(\operatorname{Count}, 2)]/2 //\operatorname{Divide key frames}$ into <i>n</i> groups for <i>n</i> groups of key frames do $[\operatorname{LL}, \operatorname{LH}, \operatorname{HL}, \operatorname{HH}] \leftarrow \operatorname{DWT}(Y)$ $D \leftarrow \operatorname{APBT}(\operatorname{LL})$ $[\operatorname{LU} S V] \leftarrow \operatorname{SVD}(D)$ $S_{\rm m} \leftarrow \operatorname{Aml}(1)$ if $\operatorname{mod}(S_{\rm mh}, 2) = 1$ then $F_{\rm s} = 1$ $\operatorname{end} if$ end for $F_{\rm s} = 1$ end if end for $F_{\rm s} = 1$ $\operatorname{end} if$ end for $W_{\rm z} \leftarrow \operatorname{XOR}(W_{\rm E}, F_{\rm se})$ End Procedure $W_{\rm z} \leftarrow \operatorname{XOR}(W_{\rm E}, F_{\rm se})$ $End \operatorname{Procedure}$ $Y \leftarrow \operatorname{loadyuv}(F_{\rm k}^{*}, 832, 480, 2n)$ for <i>n</i> groups of key frames do $[\operatorname{LL}^{*}, \operatorname{LH}^{*}, \operatorname{HL}^{*}, \operatorname{HH}^{*}] \leftarrow \operatorname{DWT}(Y)$ $D^{*} \leftarrow \operatorname{APBT}(\operatorname{LL}^{*})$ $[U^{*} S^{*} V^{*}] \leftarrow \operatorname{SVD}(D^{*})$ $S_{\rm m}^{*} \leftarrow \operatorname{Aml}(\operatorname{aux}(S^{*}))$ $S_{\rm m}^{*} \leftarrow \operatorname{Sm}(1)$ if $\operatorname{mod}(S_{\rm mh}^{*}, 2) = 1$ then $F_{\rm s}^{*} = 1$ $\operatorname{end} if$ end for $W_{\rm s}^{*} \leftarrow \operatorname{XOR}(W_{\rm z}, F_{\rm se}^{*})$ $W_{\rm b}^{*} \leftarrow $	$W \leftarrow \text{SDU}$ (with size of 30×26)	2: Feature extraction \int_{1}^{k}
$W_{E} \leftarrow XOR(W, m)$ 3: Feature extraction $n \leftarrow [Count - mod(Count, 2)]/2$ // Divide key frames into <i>n</i> groups for <i>n</i> groups of key frames do $[LL^{*}, LH^{*}, HL^{*}, HL^{*}] \leftarrow DWT(Y)$ $D \leftarrow APBT(LL)$ $[LJ, LH, HL, HH] \leftarrow DWT(Y)$ $D \leftarrow APBT(LL)$ $[U S V] \leftarrow SVD(D)$ $S_{m} \leftarrow nun2str(max(S))$ $S_{m} \leftarrow S_{m}(1)$ if $mod(S_{mh}, 2) = 1$ then $F_{s} = 1$ $S_{m} \leftarrow S_{m}(1)$ if $mod(S_{mh}, 2) = 1$ then $F_{s} = 1$ end if end if end for // The feature sequence F_{se} can be obtained by composing all F_{s} 4: Zero-watermark generation $W_{z} \leftarrow XOR(W_{E}, F_{se})$ End Procedure $W_{1} \leftarrow \frac{W_{D1}+W_{D2}+\dots+W_{Dn}}{m}$ $for n groups of key frames do [LL^{*}, LH^{*}, HL^{*}, HL^{*}, HH^{*}] \leftarrow DWT(Y)D^{*} \leftarrow APBT(LL^{*})[U^{*} S^{*} V^{*}] \leftarrow SVD(D^{*})S_{m}^{*} \leftarrow nun2str(max(S^{*}))S_{mh}^{*} \leftarrow S_{m}^{*}(1)if mod(S_{mh}^{*}, 2) = 1 thenF_{s}^{*} = 1else F_{s}^{*} = 0end ifend forW_{1} \leftarrow W_{2} + \dots + W_{Dn}W_{1} \leftarrow \frac{W_{D1} + W_{D2} + \dots + W_{Dn}}{m}for M_{1} \leftarrow \frac{W_{D1} + W_{D2} + \dots + W_{Dn}}{m}W_{1} \leftarrow \frac{W_{D1} + W_{D2} + \dots + W_{Dn}}{m}$	$m \leftarrow \text{randint}(1, 30 \times 26)$	$Y \leftarrow \text{loadyuv}(F_{k}^{*}, 832, 480, 2n)$
3: Feature extraction $n \leftarrow [Count - mod(Count, 2)]/2$ // Divide key frames into <i>n</i> groups for <i>n</i> groups of key frames do [LL, LH, HL, HH] \leftarrow DWT(<i>Y</i>) $D \leftarrow APBT(LL)$ [<i>U</i> S V] \leftarrow SVD(<i>D</i>) $S_{mh} \leftarrow S_{m}(1)$ if $mod(S_{mh}, 2) = 1$ then $F_{s} = 1$ end if end for $F_{s} = 1$ end if end for $W_{z} \leftarrow XOR(W_{E}, F_{sc})$ End Procedure S: Feature extraction $W_{z} \leftarrow XOR(W_{E}, F_{sc})$ End Procedure S: Feature extraction $W_{z} \leftarrow XOR(W_{E}, F_{sc})$ End Procedure S: Feature extraction $W_{z} \leftarrow XOR(W_{E}, F_{sc})$ End Procedure S: Feature extraction $W_{z} \leftarrow XOR(W_{E}, F_{sc})$ F: Find Procedure S: Feature extraction $W_{z} \leftarrow XOR(W_{z}, F_{sc})$ F: Find Procedure S: Feature extraction $W_{z} \leftarrow XOR(W_{z}, F_{sc})$ F: Find Procedure F: Find Find Find Find Find Find Find Find	$W_{\rm E} \leftarrow {\rm XOR}(W, m)$	for <i>n</i> groups of key frames do
$n \leftarrow [\text{Count - mod}(\text{Count}, 2)]/2 // \text{Divide key frames} \\ \text{into n groups} \\ \text{for n groups of key frames do \\ [LL, LH, HL, HH] \leftarrow DWT(Y) \\ D \leftarrow \text{APBT}(\text{LL}) \\ [U S V] \leftarrow \text{SVD}(D) \\ S_m \leftarrow \text{num2str}(\text{max}(S)) \\ S_m \leftarrow \text{num2str}(\text{max}(S)) \\ S_m \leftarrow \text{num2str}(\text{max}(S)) \\ S_m \leftarrow \text{Sm}(1) \\ \text{if mod}(S_{\text{mh}}, 2) = 1 \text{ then} \\ F_s = 1 \\ \text{end if} \\ \text{end if} \\ \text{end for} \\ // \text{The feature sequence } F_{\text{se}} \text{ can be obtained by} \\ \text{composing all } F_s \\ \text{4: Zero-watermark generation} \\ W_z \leftarrow \text{XOR}(W_E, F_{\text{se}}) \\ \text{End Procedure} \\ \hline M_z \leftarrow \text{XOR}(W_E, F_{\text{se}}) \\ \hline M_z \leftarrow \text{XOR}(W_E, F_{\text{se}}) \\ \hline M_z \leftarrow \text{XOR}(W_E, F_{\text{se}}) \\ \hline M_z \leftarrow 2\text{OR}(W_E, F_{\text{se}}) \\ \hline M$	3: Feature extraction	$[LL^*, LH^*, HL^*, HH^*] \leftarrow DWT(Y)$
into <i>n</i> groups into <i>n</i> groups for <i>n</i> groups of key frames do [LL, LH, HL, HH] \leftarrow DWT(Y) $D \leftarrow APBT(LL)$ [$U S V] \leftarrow SVD(D)$ $S_m \leftarrow num2str(max(S))$ $S_m \leftarrow num2str(max(S))$ $S_m \leftarrow num2str(max(S))$ $S_m \leftarrow rum2str(max(S))$ $S_m \leftarrow rum2str(max(S))$ $S_m \leftarrow rum2str(max(S))$ $S_m \leftarrow rum2str(max(S))$ $S_m \leftarrow rum2str(max(S))$ $S_m \leftarrow rum2str(max(S))$ $S_m^* \leftarrow S_m^{(1)}$ if mod($S_{mh}, 2) = 1$ then $F_s = 1$ end if end for $F_s = 1$ end if end for I' The feature sequence F_{se} can be obtained by composing all F_s 4: Zero-watermark generation $W_z \leftarrow XOR(W_E, F_{se})$ End Procedure $W_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\dots+W_{D_n}}{T}$ $W_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\dots+W_{D_n}}{T}$	$n \leftarrow [\text{Count - mod}(\text{Count, 2})]/2$ // Divide key frames	$D^* \leftarrow \text{APBT}(\text{LL}^*)$
for <i>n</i> group of key frames do [LL, LH, HL, HH] \leftarrow DWT(<i>Y</i>) $D \leftarrow APBT(LL)$ [$U S V$] $\leftarrow SVD(D)$ $S_m \leftarrow num2str(max(S))$ $S_m \leftarrow num2str(max(S))$ $S_m \leftarrow S_m(1)$ if mod($S_{mh}, 2$) = 1 then $F_s = 1$ end if end for $F_s = 1$ end if end for M' The feature sequence F_{se} can be obtained by composing all F_s 4: Zero-watermark generation $W_z \leftarrow XOR(W_E, F_{se})$ End Procedure $K_z \leftarrow XOR(W_E, F_{se})$ End Procedure $K_z \leftarrow XOR(W_E, F_{se})$ $K_z \leftarrow XOR(W_E, F_$	into <i>n</i> groups	$[U^* S^* V^*] \leftarrow SVD(D^*)$
$[LL, LH, HL, HH] \leftarrow DWT(Y)$ $D \leftarrow APBT(LL)$ $[U S V] \leftarrow SVD(D)$ $S_{m} \leftarrow num2str(max(S))$ $S_{mh} \leftarrow S_{m}(1)$ if $mod(S_{mh}^{*}, 2) = 1$ then $F_{s} = 1$ else $F_{s}^{*} = 0$ end if end for $F_{s} = 1$ else $F_{s}^{*} = 0$ end if end for $F_{s} = 1$ $else F_{s}^{*} = 0$ $end if$ end for $F_{s} = 1$ $Composing all F_{s}$ 4: Zero-watermark generation $W_{z} \leftarrow XOR(W_{E}, F_{se})$ End Procedure $W_{z} \leftarrow XOR(W_{E}, F_{se})$ $End Procedure W_{z} \leftarrow \frac{W_{D_{1}} + W_{D_{2}} + \dots + W_{D_{n}}}{n} W_{z} \leftarrow \frac{W_{D_{1}} + W_{D_{2}} + \dots + W_{D_{n}}}{n}$	for <i>n</i> groups of key frames do	$S_{\rm m}^* \leftarrow {\rm num2str}({\rm max}(S^*))$
$D \leftarrow APBT(LL)$ $[U S V] \leftarrow SVD(D)$ $S_{m} \leftarrow S_{m}(1)$ if mod($S_{mh}, 2) = 1$ then $F_{s} = 1$ end if end for $F_{s} = 1$ end for $F_{s} = 0$ end if end for $M_{z} \leftarrow XOR(W_{E}, F_{se})$ End Procedure $M_{z} \leftarrow XOR(W_{E}, F_{se})$ End Procedure $M_{z} \leftarrow W_{z} \leftarrow W_{z}, F_{se}$ $W_{z} \leftarrow W_{z} \leftarrow W_{z}, F_{ze}$	$[LL, LH, HL, HH] \leftarrow DWT(Y)$	$S_{mh}^{m} \leftarrow S_{m}^{*}(1)$
$[U S V] \leftarrow SVD(D)$ $S_{m} \leftarrow SVD(D)$ $S_{m} \leftarrow N(1)$ if mod($S_{mh}, 2$) = 1 then $F_{s} = 1$ end if end for $F_{s} = 1$ end if end for $F_{s} = 0$ end if end for $M_{z} \leftarrow XOR(W_{E}, F_{se})$ End Procedure $W_{z} \leftarrow XOR(W_{E}, F_{se})$ $End Procedure$ $F_{s} = 0$ $W_{z} \leftarrow W_{z} + W_{z} = W_{z} + W_{z} +$	$D \leftarrow APBT(LL)$	if $mod(S_{mb}^*, 2) = 1$ then
$S_{m} \leftarrow num2str(max(S))$ $S_{mh} \leftarrow S_{m}(1)$ if $mod(S_{mh}, 2) = 1$ then $F_{s} = 1$ end if end for $F_{s} = 0$ end if end for $F_{s} = 0$ end if $F_{s} = 0$ $M_{T} = e^{2} + e^{2$	$[U S V] \leftarrow SVD(D)$	$F_{\rm s}^* = 1$
$S_{mh} \leftarrow S_{m}(1)$ if $mod(S_{mh}, 2) = 1$ then $F_{s} = 1$ end if end for $F_{s} = 0$ end if end for $W_{t} \leftarrow XOR(W_{t}, F_{se})$ End Procedure $W_{t} \leftarrow W_{t} + W_{t} = \{W_{t}, W_{t}, W_{t$	$S_{\rm m} \leftarrow {\rm num2str}({\rm max}(S))$	else $F_{c}^{*}=0$
in $M(Y_{mh}, 2) = 1$ then $F_{s} = 1$ $end for F_{s} = 0end ifend for // The feature sequence F_{se} can be obtained bycomposing all F_{s}4: Zero-watermark generationW_{z} \leftarrow XOR(W_{E}, F_{se})End ProcedureW_{z} \leftarrow W_{z} = \frac{W_{D_{1}}, W_{D_{2}}, \cdots, W_{D_{n}}}{W_{z} + W_{z} + W_{D_{n}}}4: Watermark postprocessing and watermark recon-structionW_{1} \leftarrow \frac{W_{D_{1}}+W_{D_{2}}+\cdots+W_{D_{n}}}{W_{2} + W_{2} + W_{2}$	$S_{\rm mh} \leftarrow S_{\rm m}(1)$	end if
$F_{s} = 1$ $F_{s} = 0$ $W_{s} = V OR(W_{s}, F_{se})$ $W_{b}^{*} \leftarrow XOR(W_{c}, F_{se})$	if $mod(S_{mh}, 2) = 1$ then	end for
else $F_s = 0$ end if end for // The feature sequence F_{se} can be obtained by composing all F_s 4: Zero-watermark generation $W_z \leftarrow XOR(W_E, F_{se})$ End Procedure $W_1 \leftarrow \frac{W_{D_1} + W_{D_2} + \dots + W_{D_n}}{1 + 20}$ $w_1 \leftarrow \frac{W_{D_1} + W_{D_2} + \dots + W_{D_n}}{1 + 20}$	$F_{\rm s} = 1$	// The feature sequence F_{co}^* can be obtained by
end if end for // The feature sequence F_{se} can be obtained by composing all F_s 4: Zero-watermark generation $W_z \leftarrow XOR(W_E, F_{se})$ End Procedure $W_z \leftarrow W_z = W_{ze} + W_{ze} $	else $F_s = 0$	composing all F_c^*
end for // The feature sequence F_{se} can be obtained by composing all F_s 4: Zero-watermark generation $W_z \leftarrow XOR(W_E, F_{se})$ End Procedure $W_E^* \leftarrow XOR(W_E, F_{se})$ $W_D^* \leftarrow XOR(W_E, m)$ // $W_D^* = \{W_{D_1}, W_{D_2}, \dots, W_{D_n}\}$ 4: Watermark postprocessing and watermark recon- struction $w_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\dots+W_{D_n}}{1+20}$	end if	3: Obtain encrypted watermarks and decrypt them
// The feature sequence F_{se} can be obtained by composing all F_s 4: Zero-watermark generation $W_D^E \leftarrow XOR(W_E^*, m)$ // $W_D^* = \{W_{D_1}, W_{D_2}, \cdots, W_{D_n}\}$ 4: Watermark postprocessing and watermark reconstruction $W_L \leftarrow XOR(W_E, F_{se})$ End Procedure $w_1 \leftarrow \frac{W_{D_1} + W_{D_2} + \cdots + W_{D_n}}{1 + 20 n}$	end for	$W_{\rm E}^* \leftarrow {\rm XOR}(W_{\rm Z}, F_{\rm so}^*)$
composing all F_s 4: Zero-watermark generation $W_z \leftarrow XOR(W_E, F_{se})$ End Procedure $W_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\dots+W_{D_n}}{1+20}$ for $i = 1+26$	// The feature sequence F_{se} can be obtained by	$W_{\mathcal{D}}^{\mathbb{H}} \leftarrow \operatorname{XOR}(W_{\mathcal{D}}^{\mathbb{H}}, m) // W_{\mathcal{D}}^{\mathbb{H}} = \{W_{\mathcal{D}_{1}}, W_{\mathcal{D}_{2}}, \cdots, W_{\mathcal{D}_{n}}\}$
4: Zero-watermark generation $W_z \leftarrow XOR(W_E, F_{se})$ End Procedure 4: Watermark postprocessing and watermark recon- $w_1 \leftarrow \frac{W_{D_1}+W_{D_2}+\dots+W_{D_n}}{1+20}$	composing all F_s	$W_{\rm D}$ }
$W_{z} \leftarrow \text{XOR}(W_{E}, F_{se})$ End Procedure $w_{1} \leftarrow \frac{W_{D_{1}} + W_{D_{2}} + \dots + W_{D_{n}}}{n}$ for $i = 1 + 26$	4: Zero-watermark generation	4: Watermark postprocessing and watermark recon-
End Procedure $w_1 \leftarrow \frac{W_{D_1} + W_{D_2} + \dots + W_{D_n}}{n}$ for $i = 1 + 20$	$W_{7} \leftarrow \text{XOR}(W_{\text{F}}, F_{\text{se}})$	struction
$ \begin{array}{c} m_1 \\ n_2 \\ n_3 \\ n_4 $	End Procedure	$\mathbf{w}_1 \leftarrow \frac{\mathbf{w}_{D_1} + \mathbf{w}_{D_2} + \dots + \mathbf{w}_{D_n}}{\mathbf{w}_{D_1} + \mathbf{w}_{D_1} + \mathbf{w}_{D_2} + \mathbf{w}_{D_2} + \mathbf{w}_{D_2} + \mathbf{w}_{D_1} + \mathbf{w}_{D_2} + $
IDE 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		for $i = 1 \cdot 30$ and $i = 1 \cdot 26$
To estimate the robustness of the proposed algorithm to $\mathbf{if } w_1(i, i) > T_1 \mathbf{then}$	To estimate the robustness of the proposed algorithm to	if $w_1(i \ i) > T_1$ then
HEVC compression attacks, HEVC compression attacks with $W^*(i, i) \leftarrow 1$	HEVC compression attacks, HEVC compression attacks with	$W^*(i, i) \leftarrow 1$

To estimate the robustness of the proposed algorithm to HEVC compression attacks, HEVC compression attacks with QPs from 16 to 48 with a step of 8 are applied to video sequences. In addition, the robustness to various common image processing attacks (such as noise, filtering, blurring, and sharpening), rotation, scaling, frame-based attacks, and some hybrid attacks is also tested.

else $W^*(i, j) \leftarrow 0$

end if

end for

End Procedure

Algorithms		[2	9]		[21] and Proposed				
Video sequences	BasketballDrill	BQMall	PartyScene	RaceHorses	BasketballDrill	BQMall	PartyScene	RaceHorses	
Watermarked frames					5.0				
PSNR (dB)	47.3540	49.9318	49.0648	49.8968	Inf	Inf	Inf	Inf	
SSIM	0.9978	0.9991	0.9996	0.9983	1.0000	1.0000	1.0000	1.0000	
Extracted watermarks	SDU	SDU	SDU	SDU	SDU	SDU	SDU	SDU	
NCC	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	
BER	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	

TABLE 1. Comparison of the imperceptibility and robustness without attacks among different algorithms.



-	Quantization	Original video sequences									
Quantization	BasketballDrill		BQI	BQMall		PartyScene		RaceHorses			
	parameter (Qr)	NCC	BER	NCC	BER	NCC	BER	NCC	BER		
	16	0.9997	0.0002	0.9982	0.0019	0.9986	0.0013	0.9981	0.0018		
	24	0.9990	0.0009	0.9973	0.0026	0.9973	0.0031	0.9951	0.0048		
	32	0.9981	0.0019	0.9937	0.0062	0.9939	0.0063	0.9885	0.0113		
	40	0.9955	0.0046	0.9867	0.0131	0.9858	0.0149	0.9746	0.0250		
_	48	0.9898	0.0097	0.9644	0.0340	0.9687	0.0318	0.9489	0.0506		

TABLE 3. The robustness of the proposed algorithm to HEVC compression attacks after watermark postprocessing.

Quantization	Original video sequences								
Qualitization	BasketballDrill		BQMall		PartyScene		RaceHorses		
parameter (Qr)	NCC	BER	NCC	BER	NCC	BER	NCC	BER	
16	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	
24	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	
32	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	
40	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	1.0000	0.0000	
48	1.0000	0.0000	1.0000	0.0000	0.9925	0.0026	1.0000	0.0000	

A. WITHOUT ATTACKS

To evaluate the imperceptibility and effectiveness of the algorithm, we use four representative video sequences as examples. The PSNRs and SSIMs are tested between the watermarked videos and original videos, and the watermarks are extracted from the four watermarked video sequences without attacks. The imperceptibility and robustness of the algorithms presented in [29] and [21] and the proposed algorithm without attacks are reported in Table 1.

In Table 1, [29] is a conventional video watermarking algorithm against HEVC compression attacks, and [21] and the proposed algorithm are two zero-watermarking algorithms. We can observe that the three algorithms can completely extract the watermark without attacks. However, the PSNRs of the two zero-watermarking algorithms are infinite and the SSIMs equal 1, both of which are better than those of [29]. Since zero-watermarking algorithms do not modify the original videos, they have good imperceptibility and video quality.

B. HEVC COMPRESSION ATTACKS

In the storage and transmission processes, it is inevitable for videos to undergo HEVC compression. Therefore, the watermarking algorithm must have the ability to resist HEVC compression attacks. Here, we use HEVC compression attacks with QPs from 16 to 48 with a step of 8 to test the robustness of the proposed algorithm. Taking four representative video sequences as examples, the robustness of the proposed algorithm to HEVC compression attacks before watermark postprocessing is reported in Table 2, and the robustness to HEVC compression attacks after watermark postprocessing is reported in Table 3. In addition, the robustness of the proposed algorithm is compared with [29] and [21] when facing HEVC compression attacks. The NCCs of the algorithms under different QPs are shown in Fig. 6, and the BERs under different QPs are shown in Fig. 7.

The larger the QP is, the greater the compression strength, and the more serious the video distortion. From Table 2 and Table 3, we can conclude that the proposed algorithm has good robustness to HEVC compression attacks for the different QPs before and after watermark postprocessing. Even when the QP is 48 and the video quality has been seriously damaged, the watermark can still be well reconstructed. Through the watermark postprocessing, the robustness of the algorithm is further improved. Fig. 6 and Fig. 7 show that all of the three algorithms can resist HEVC compression attacks, and the resistance of the proposed algorithm is strongest, followed by [21], and the worst is [29].



FIGURE 6. Comparison of the NCCs among different algorithms for HEVC compression attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.



FIGURE 7. Comparison of the BERs among different algorithms for HEVC compression attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.

The reason is that zero-watermarking algorithms construct zero-watermarks by extracting robust features, which usually have good robustness, whereas the conventional video watermarking algorithm may lose the embedded watermark information during HEVC compression, thus resulting in poor resistance to HEVC compression with larger QPs. The experimental results effectively prove the robustness of the proposed algorithm to HEVC compression attacks.

C. NOISE ATTACKS

Noise attacks are one of the most common image processing operations. In this paper, taking BasketballDrill as the object, the robustness of the proposed algorithm to different degrees of Gaussian noise (GN) and salt and pepper noise (SPN) is tested and compared with [29] and [21]. The test results are reported in Table 4. In addition, three other video sequences are also tested to estimate the robustness to noise attacks. The comparison results of the NCCs and BERs are shown in Fig. 8 and Fig. 9, respectively.

With increasing noise intensity, the degree of video quality damage becomes greater, and the difficulty of reconstructing watermarks is also increased. As can be observed from Table 4, the proposed algorithm has high robustness to GN and SPN attacks. In addition, its resistance to noise attacks is better than [29] and [21], especially when the intensity of noise attacks is high. From Fig. 8 and Fig. 9, we can obtain the same conclusion.

D. FILTERING ATTACKS

Filtering attacks are also common image processing operations. In image and video processing, filters are usually used to eliminate noises and smooth images. Common filters include the average filter (AF), median filter (MF), and Gaussian filter (GF). Here, taking the BasketballDrill video sequence as an example, the robustness of the proposed algorithm to the three filters is tested and compared with [29] and [21]. The test results are reported in Table 5. To more comprehensively evaluate the resistance of the algorithms to filtering attacks, three other videos are also tested. Comparisons of the NCCs and BERs are shown in Fig. 10. The template size of all filters that are used in the test is 3×3 .

After suffering filtering attacks, the video will become smooth. Furthermore, different filters have different smoothing effects. Table 5 indicates that the three algorithms have good robustness against filtering attacks, and the proposed algorithm has the robustness that is superior to those of [29] and [21]. Fig. 10 shows that compared with the AF and GF, the robustness of [29] and [21] to MF attacks is relatively weak, while the proposed algorithm has strong robustness to all three filters.

E. BLURRING AND SHARPENING ATTACKS

Blurring and sharpening attacks are two common image processing operations. For blurring attacks, we mainly test disk blurring (DB) and motion blurring (MB) attacks. Sharpening attacks with different pixel radii (0.2 and 1) are also tested. Here, taking the BasketballDrill, BQMall, PartyScene, and RaceHorses sequences as the objects, the robustness of the proposed algorithm to blurring and sharpening attacks is tested and compared with [29] and [21]. The comparison results of the NCCs and the BERs are shown in Fig. 11 and Fig. 12, respectively, where SP represents sharpening attacks.





TABLE 4. Comparison of the robustness among different algorithms to Gaussian noise and salt and pepper noise on BasketballDrill.



FIGURE 8. Comparison of the NCCs among different algorithms for Gaussian noise and salt and pepper noise on different videos: (a) BQMall, (b) PartyScene, and (c) RaceHorses.



FIGURE 9. Comparison of the BERs among different algorithms for Gaussian noise and salt and pepper noise on different videos: (a) BQMall, (b) PartyScene, and (c) RaceHorses.

In addition, the parameters in "()" denote the intensity of the three attacks. For example, DB (2) represents the DB attack of radius 2, and MB (2, 1) represents the MB attack of len 2 and theta 1.

From Fig. 11 and Fig. 12, it can be observed that the three algorithms have good robustness to blurring and sharpening attacks. Among them, the proposed algorithm can completely

tolerate blurring attacks, and its robustness to sharpening attacks is also better than the other two algorithms.

F. GEOMETRIC ATTACKS

Rotation, scaling, and cropping are three common geometric attacks. Since a small geometric attack can lead to the problem of watermarking desynchronization, resulting in the

Algorithr	ns	[29]	[21]	Proposed	[29]	[21]	Proposed	[29]	[21]	Proposed
Filtering att	acks	Ave	erage filter (3	×3)	Me	dian filter (3	×3)	Gau	ssian filter (3	3×3)
Attacked frames										
Extracted wate	ermarks	SDU	SDU	SDU	SDU	SDU	SDU	SDU	SDU	SDU
Dobustness	NCC	0.9925	1.0000	1.0000	0.9910	0.9985	1.0000	0.9940	1.0000	1.0000
Kobustness	BER	0.0090	0.0013	0.0000	0.0103	0.0013	0.0000	0.0077	0.0000	0.0000

TABLE 5. Comparison of the robustness among different algorithms to average filter, median filter, and Gaussian filter attacks on BasketballDrill.



FIGURE 10. Comparison of the robustness among different algorithms to filtering attacks on BQMall, PartyScene, and RaceHorses: (a) NCCs and (b) BERs.



FIGURE 11. Comparison of the NCCs among different algorithms for blurring and sharpening attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.

watermark being unable to be correctly extracted, a considerable number of watermarking algorithms have relatively weak resistance to geometric attacks. Here, [29], [21], and the proposed algorithm are applied to the BasketballDrill, BQMall, PartyScene, and RaceHorses sequences to compare their robustness to rotation, scaling, and cropping attacks. In addition, sticking attacks are also tested. The comparison results of the NCCs and the BERs are shown in Fig. 13 and Fig. 14, respectively, where RT stands for rotation attacks, SL stands for scaling attacks, CP represents cropping attacks, and SK represents sticking attacks.

For most video watermarking algorithms, geometric attacks are relatively difficult to resist. As can be observed

from Fig. 13 and Fig. 14, all of the three algorithms have high resistance to scaling and sticking attacks. In contrast, the robustness of the three algorithms to rotation and cropping attacks is relatively weak. For the four kinds of geometric attacks, the robustness of the proposed algorithm is slightly better than those of [29] and [21].

G. FRAME-BASED ATTACKS

Frame-based attacks are unique attacks in video watermarking, and they mainly include frame switching (FS), frame dropping (FD), frame replacing (FR), and so on. Here, the robustness to these three frame-based attacks is tested on four videos, and the results are compared with those



FIGURE 12. Comparison of the BERs among different algorithms for blurring and sharpening attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.



FIGURE 13. Comparison of the NCCs among different algorithms for geometric attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.



FIGURE 14. Comparison of the BERs among different algorithms for geometric attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.



FIGURE 15. Comparison of the NCCs among different algorithms for frame-based attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.

of [29] and [21]. The comparison results of the NCCs and BERs are shown in Fig. 15 and Fig. 16, respectively, where the number in "()" represents the number of attacked frames in each video. In particular, FS (1&2) represents the switch between the first and second frames of the video.

For FS, FD, and FR attacks, both the location and the number of attacked video frames will affect the experimental

results. Therefore, two frames in different segments of the video are exchanged, and different number of frames are dropped and replaced in this paper. In each frame-based attack, at least one key frame of the video is attacked. Fig. 15 and Fig. 16 show that all of the three algorithms can resist frame-based attacks well. The resistance of the proposed algorithm and [21] is slightly stronger than [29].



FIGURE 16. Comparison of the BERs among different algorithms for frame-based attacks on different videos: (a) BasketballDrill, (b) BQMall, (c) PartyScene, and (d) RaceHorses.



FIGURE 17. Comparison of the robustness among different algorithms to hybrid attacks on BQMall: (a) NCCs and (b) BERs.



FIGURE 18. Robustness of the proposed algorithm under HEVC compression attacks with different QPs on FourPeople, BQTerrace, and Traffic: (a) NCCs and (b) BERs.

Furthermore, the watermark image that is reconstructed by the proposed algorithm is more accurate than those obtained using the other two algorithms.

H. HYBRID ATTACKS

In the actual video transmission process, videos are usually affected by more than one attack. Most video watermarking algorithms do not consider the robustness when multiple attacks are combined. In this paper, to more comprehensively prove the effectiveness of the proposed algorithm, hybrid attacks, which include two and three kinds of attacks, are considered. Taking the BasketballDrill sequence as an example, after suffering hybrid attacks combining two attacks, the first frames of the video are presented in Table 6, and the comparison of the robustness is reported in Table 7. After suffering hybrid attacks combining three attacks, the first frames of the video are presented in Table 8, and the comparison of the robustness is reported in Table 9. In addition, some hybrid attacks are also performed on the BQMall sequence, and the comparisons of the NCCs and BERs to hybrid attacks are shown in Fig. 17.

From Table 7 and Table 9, it can be observed that the proposed algorithm can completely tolerate hybrid attacks combining several common image processing attacks. In contrast, the watermark images that are reconstructed by [29] and [21] have more obvious false detection bits under hybrid attacks. The same conclusion can be drawn from Fig. 17.

According to the results of the evaluation of the robustness to various attacks, compared with [29] and [21], the proposed algorithm has higher robustness, and watermark images can be more accurately and completely reconstructed.



FIGURE 19. Robustness of the proposed algorithm to hybrid attacks on FourPeople, BQTerrace, and Traffic: (a) NCCs and (b) BERs.





TABLE 7. Comparison of the robustness among different algorithms to hybrid attacks combining two attacks on BasketballDrill.

		[29]			[21]		Ι	Proposed	
Attacks	Extracted	Robu	stness	Extracted	Robu	stness	Extracted	Robu	stness
	watermarks	NCC	BER	watermarks	NCC	BER	watermarks	NCC	BER
Gaussian noise(0.01) + HEVC(16)	SDU	0.9925	0.0090	SDU	0.9970	0.0038	SDU	1.0000	0.0000
Average filter (3×3) + HEVC (24)	SDU	0.9940	0.0077	SDU	0.9985	0.0013	SDU	1.0000	0.0000
Median filter (3×3) + HEVC (32)	ŠDU	0.9805	0.0192	SDU	0.9970	0.0026	SDU	1.0000	0.0000
Scaling(0.5) + HEVC(40)	SDU	0.9760	0.0231	SDU	0.9925	0.0064	SDU	1.0000	0.0000
Gaussian noise (0.02) + Average filter (3×3)	SDU	0.9895	0.0115	SDU	0.9970	0.0026	SDU	1.0000	0.0000
Gaussian noise(0.03) + Scaling(0.5)	ŝDU	0.9730	0.0256	SDU	0.9955	0.0038	SDU	1.0000	0.0000
Average filter (3×3) + Scaling(2)	SDU	0.9895	0.0115	SDU	1.0000	0.0000	SDU	1.0000	0.0000
Median filter (3×3) + Scaling (2)	SDU	0.9850	0.0141	SDÙ	0.9985	0.0013	SDU	1.0000	0.0000

I. DIFFERENT RESOLUTIONS ANALYSIS

An effective video watermarking algorithm should also consider the application in different resolution videos and analyze its effects. Here, we select three representative video sequences with different resolutions to illustrate the experimental results, which include FourPeople (1280 \times 720), BQTerrace (1920 \times 1080), and Traffic

 (2560×1600) . HEVC compression attacks with different QPs are tested on the three videos, and the robustness of the proposed algorithm is shown in Fig. 18. In addition, hybrid attacks are also applied to these videos to test the robustness. The NCCs and BERs of the proposed algorithm to hybrid attacks are shown in Fig. 19.

Attacks	Gaussian noise(0.01) + Average	Gaussian noise (0.02) + Median	Gaussian noise(0.03) +	
	filter(3×3) + HEVC(16)	filter (3×3) + HEVC (24)	Scaling(2) + HEVC(32)	
Attacked frames				
Attacks	Average filter (3×3) +	Median filter(3×3) +	Gaussian noise (0.02) + Average	
	Scaling (2) + HEVC (32)	Scaling(0.5) + HEVC(40)	filter (3×3) + Scaling (0.5)	
Attacked frames				

TABLE 8. First frames of the attacked BasketballDrill sequence under hybrid attacks combining three attacks.

TABLE 9. Comparison of the robustness among different algorithms to hybrid attacks combining three attacks on BasketballDrill.

		[29]			[21]			Proposed		
Attacks	Extracted	Robu	stness	Extracted	Robu	stness	Extracted	Robu	stness	
	watermarks	NCC	BER	watermarks	NCC	BER	watermarks	NCC	BER	
Gaussian noise(0.01) + Average filter(3×3) + HEVC(16)	SDU	0.9940	0.0077	SDU	0.9985	0.0026	SDU	1.0000	0.0000	
Gaussian noise(0.02) + Median filter(3×3) + HEVC(24)	SDU	0.9880	0.0128	SDU	0.9970	0.0038	SDU	1.0000	0.0000	
Gaussian noise(0.03) + Scaling(2) + HEVC(32)	ŠDU	0.9730	0.0256	SĐU	0.9985	0.0026	SDU	1.0000	0.0000	
Average filter(3×3) + Scaling(2) + HEVC(32)	SDU	0.9835	0.0167	SDU	0.9955	0.0038	SDU	1.0000	0.0000	
Median filter(3×3) + Scaling(0.5) + HEVC(40)	SDU	0.9715	0.0269	SDU	0.9925	0.0064	SDU	1.0000	0.0000	
Gaussian noise (0.02) + Average filter (3×3) + Scaling (0.5)	SDU	0.9820	0.0179	SDU	0.9955	0.0038	SDU	1.0000	0.0000	

Because each video has its own characteristics, during the complex HEVC compression process, different degrees of distortion may occur due to different block division methods, prediction modes, and so on, resulting in slight differences in the robustness of the proposed algorithm for videos with different resolutions. From Fig. 18, we can observe that the NCC of the proposed algorithm under different QPs is no less than 0.96, and the BER is no greater than 4%, which can further prove the effectiveness of the algorithm against HEVC compression attacks. Fig. 19 shows that the NCC of the proposed algorithm after hybrid attacks is no less than 0.99, while the BER is no greater than 0.8%, which strongly proves that the proposed algorithm is still robust to hybrid attacks when applied to videos with different resolutions.

J. DIFFERENCE ANALYSIS OF EXTRACTED FEATURES

To ensure the uniqueness of zero-watermarks constructed by different videos, the difference between the extracted features should be obvious. Taking the BQMall, FourPeople, BQTerrace, and Traffic as the objects, the percentage of different bits (PDB) between features extracted from them is estimated. The BER is selected as the evaluation index, and the experimental results are shown in Table 10.

TABLE 10.	Percentage	of different	bits between	features	extracted f	rom
BQMall, Fo	urPeople, E	QTerrace, an	d Traffic (%).			

Videos	BQMall	FourPeople	BQTerrace	Traffic
BQMall	0	34.15	53.09	32.69
FourPeople	34.15	0	53.85	36.49
BQTerrace	53.09	53.85	0	52.93
Traffic	32.69	36.49	52.93	0
Random	49.62	50.08	51.20	49.42

In Table 10, "Random" is a random binary sequence with the same size as extracted feature sequences, which is used as a reference. As can be observed from the last row of Table 10, the ideal value for the PDB should be around 50%. The PDBs between features extracted from BQTerrace and features extracted from other videos are close to the ideal value. However, the PDBs between BQMall, FourPeople, and Traffic range from 30% to 40%. Table 10 has shown the obvious difference between extracted features from different videos. However, it can also be concluded that the proposed algorithm may have a certain degree of false-alarm problem for some videos in the detection process. The experimental results from part B to part I show that the BERs of the proposed algorithm for all kinds of tested attacks are no

TABLE 11. Comparison of the execution time for watermark embedding and extraction per frame of the different algorithms (second).

Algorithms	Embeddin	ng time	Extraction time		
Aigonums	BasketballDrill	BQTerrace	BasketballDrill	BQTerrace	
[29]	0.2122	0.3902	0.0494	0.1404	
[21]	0.2461	0.2675	0.1507	0.2457	
Proposed	0.1920	0.2197	0.1033	0.1841	

TABLE 12. Comparisons among different algorithms in terms of the type, transforms, watermark image, watermark preprocessing, capacity, PSNR, SSIM, the resistance to various attacks, and extraction time.

Algorithms	[29]	[21]	Proposed
Algorithm type	Conventional	Zero-	Zero-
Algorithm type	watermarking	watermarking	watermarking
Transforms	ADDT SVD	DWT, 3D-	DWT, APBT,
Transforms	AFB1, SVD	DCT, LPM	SVD
Watermark image	Binary	Binary	Binary
Watermark proprocessing	None	Logistic mon	Pseudorandom
watermark preprocessing	INOILE	Logistic map	sequence
Capacity/per frame (bits)	780	390	390
PSNR (dB)	49.0618	Infinite	Infinite
SSIM	0.9987	1.0000	1.0000
HEVC compression	Yes (3rd)	Yes (2nd)	Yes (1st)
Noise, filtering, blurring, sharpening attacks	Yes (3rd)	Yes (2nd)	Yes (1st)
Geometric attacks	Yes (2nd)	Yes (2nd)	Yes (1st)
Frame-based attacks	Yes (3rd)	Yes (2nd)	Yes (1st)
Hybrid attacks	Yes (3rd)	Yes (2nd)	Yes (1st)
Time/per frame (second)	0.2616	0.3968	0.2953

greater than 4%. Combined with the Table 10, we can set up a criterion for the proposed algorithm, which is that the algorithm is considered invalid when the BER of detected zero-watermarks exceeds 10%, to eliminate its false-alarm problem to some extent.

K. REAL-TIME ANALYSIS

To compare the real-time performance of the three algorithms, we take BasketballDrill and BQTerrace as examples, and the execution times for watermark embedding and extraction per frame are given in Table 11.

From Table 11, we can see that the embedding time per frame of the proposed algorithm is shorter than those of [29] and [21]. However, its extraction time per frame is longer than [29] and shorter than [21]. The reason is that the proposed algorithm uses watermark postprocessing process to improve the robustness. Correspondingly, it also increases the watermark extraction time. Reference [21] uses the pseudo 3D DCT to extract robust features, which also prolong the embedding and extraction time.

To summarize all compared algorithms, some information and performance of them are listed in Table 12, including the algorithm type, transforms, watermark image, watermark preprocessing, capacity, PSNR, SSIM, the resistance to various attacks, and extraction time.

In Table 12, "Yes" means that the algorithm can resist the attacks. "1st", "2nd", and "3rd" represent the level of the robustness to corresponding attacks. Among them, "1st" means that the algorithm has the strongest robustness, while "3rd" means that the algorithm has the weakest robustness. From Table 12, we can observe that the imperceptibility and robustness of zero-watermarking algorithms are better than those of the conventional watermarking algorithm. Since [21] and the proposed algorithm select coefficients with more concentrated energy to generate zero-watermarks, their capacity is lower than that of [29]. Overall, the performance of the proposed algorithm is better than that of the other two algorithms.

VI. CONCLUSION

In this paper, a hybrid transforms-based robust video zerowatermarking algorithm is proposed. It is the first time that the zero-watermarking has been introduced into videos to resist HEVC compression. Combined with the properties of hybrid transforms, robust features can be extracted from videos and robust zero-watermarks can be constructed, which can ensure the robustness of the proposed algorithm. Additionally, the proposed watermark postprocessing process can further improve the accuracy of the extracted watermarks. Since the proposed algorithm does not modify the video, it will not have any impact on the video's quality. The use of a pseudorandom sequence increases the security of the algorithm. The experimental results show that the algorithm can effectively resist HEVC compression attacks with different QPs. In addition, it has high robustness to some common image processing attacks, rotation, scaling, cropping, sticking, frame-based attacks, and hybrid attacks. In the future, we will consider how to improve the resistance to highintensity rotation attacks, completely eliminate the falsealarm problem, and apply the algorithm to 3D HEVC videos.

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