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Influence of Time Delay on Bifurcation in Fractional Order BAM Neural Networks With Four Delays

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ABSTRACT Over the past several decades, numerous scholars have studied the stability and Hopf bifurcation problem of integer-order delayed neural networks. However, the fruits about the stability and Hopf bifurcation for fractional-order delayed neural networks are very scarce. In this paper, we will consider the stability and the existence of Hopf bifurcation of fractional-order bidirectional associative memory (BAM) neural networks with four delays. A set of sufficient criteria to ensure the stability and the existence of Hopf bifurcation for the fractional-order BAM neural networks with four delays are established by choosing the sum of two different delays as a bifurcation parameter. This paper manifests that the delay has an important influence on the stability and Hopf bifurcation of involved networks. An example is displayed to test the rationality of the derived theoretical findings. The derived results of this paper are new and play a key role in optimizing networks and improving human life.

INDEX TERMS BAM neural networks, stability, Hopf bifurcation, fractional order, delay.

I. INTRODUCTION

At present, neural networks have attracted a great deal of attention from various areas due to their promising application in signal and image processing, optimization solvers, intelligent control, quadratic optimization, automatic control and so on [1]. Since the classical work of Marcus and Westervelt [2], great progress on the research on neural networks has been made during the last few decades. The study on the dynamical behavior of neural networks plays an important role in designing neural networks and serving human beings.

Since the neuron amplifiers and the communication time between two neurons have the finite switching speed, so it is suitable to introduce the time delay into neural networks. The investigation shows that time delay can affect the dynamics of neural networks. Based on this point, the impact of

time delay on the dynamical behaviors of delayed neural networks has become a hot topic and focus issue in mathematical fields and various engineering disciplines. In recent years, numerous excellent and interesting results on various dynamics on delayed neural networks are springing up. For example, Li *et al.* [3] investigated the periodicity and stability of impulsive neural networks, Li and Yang [4], Li and Li [5], and Aouiti *et al.* [6] considered the almost automorphic solution, almost periodic solution, pseudo almost periodic solution of neural networks, Xu and Li [7], [8] pointed out that leakage delay and proportional delay has important effect on the global exponential convergence of neural networks, Long [9] established new sufficient conditions to ensure the existence and global exponential stability of involved neural networks. For more detailed works, we refer the readers to [10]–[29].

The fractional calculus is generalization of ordinary differentiation and integration to arbitrary non-integer order [27], [30], [57]–[60]. No progress about the fractional

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calculus has been made for a long time in virtue of the lack of actual background and theoretical basis. Until recently, a lot of researchers find that fractional-order differential equations are important instruments which can be used to model various phenomena in many areas and describe memory, hereditary nature of all sorts of materials and processes. Thus it is more reasonable to depict the objective problems by fractional-order derivatives than the classical integer-order ones. The research shows that fractional-order differential equations have widely applied in numerous fields such as material sciences, fluid mechanics, biology, medicine, etc. [31]. Based on the idea, the incorporation of memory element into neural networks will display great theoretical value and practical significance. Nowadays, the study on fractional-order neural networks has become a hot issue with great development prospect. Many outstanding results on this aspect have been available. For instance, Ding et al. [30] studied the global Mittag-Leffler synchronization for fractional-order neural networks, Yang et al. [31] obtained the sufficient conditions to ensure the finite-time stability of fractional-order delayed neural networks, Chen et al. [32] discussed the global Mittag-Leffler stability and synchronization issue of memristor-based fractional-order neural networks. For more related works, we refer the readers to [33]–[37], [61]–[63].

Hopf bifurcation is an important dynamical behavior of delayed differential equations. Hopf bifurcation phenomena of integer-order neural networks have been widely studied. A great deal of significant results have been reported (see [38]–[44]). However, the analysis methods on Hopf bifurcation of inter-order systems can not be simply applied to focus on the Hopf bifurcation of fractional-order differential equations. Recently, some authors have analyzed Hopf bifurcation problems for fractional-order neural networks (see [45]–[53]).

Here we would like to point out that the majority of the papers mentioned above consider the Hopf bifurcation of neural networks with single delay. Up to now, there are rare papers that handle the Hopf bifurcation problem of neural networks with multiple delays. Due to the increase of the number of delay, the characteristic equation of involved neural networks will be more complicated than that of neural networks with single delay. Maybe we will face some new challenge.

Stimulated by the discussion above, it is necessary for us to investigate the Hopf bifurcation of neural networks with multiple delays. It is well known that the delayed BAM neural networks take the following form:

$$\begin{cases} \dot{u}_l(t) = -\alpha_l u_l(t) + \sum_{p=1}^m a_{pl} h_l(v_p(t - \sigma_{pl})) + U_l, \\ \dot{v}_p(t) = -\beta_p v_p(t) + \sum_{l=1}^n b_{lp} r_p(u_l(t - \varrho_{lp})) + V_p, \end{cases} \quad (1)$$

where $l = 1, 2, \dots, n; p = 1, 2, \dots, m$, $a_{pl}, b_{lp} (l = 1, 2, \dots, n; p = 1, 2, \dots, m)$ are the connection weights

through neurons in two layers: the U -layer and V -layer; α_l and β_p describe the stability of internal neuron processes on the U -layer and V -layer, respectively. On the U -layer, the neurons whose states are denoted by $u_l(t)$ receive the inputs U_l and the inputs outputted by those neurons in the J -layer via activation functions h_l , while on the V -layer, the neurons whose associated states are denoted by $v_p(t)$ receive the inputs V_p and the inputs outputted by those neurons in the U -layer via activation functions r_p (see [49]). Although system (1) can be mathematically regarded as Hopfied-type neural networks with dimension $n + m$, it is really produces many nice properties due to the special structure of connection weights and has practical applications in storing paired patterns or memories. In details, one can see [50].

For model (1), Huang et al. [48] assumed that there are two neurons on the U -layer and one neuron on the V -layer and the time delay from the neuron v_1 on V -layer to neurons u_1, u_2 on U -layer are σ_1 and σ_2 , respectively; The time delays from the neurons u_1 and u_2 on U -layer to the neuron v_1 on V -layer are σ_3 and σ_4 , respectively. Then he obtain the following simplified BAM neural network

$$\begin{cases} \dot{u}_1(t) = -\alpha_1 u_1(t) + \gamma_{11} h_1(v_1(t - \sigma_1)), \\ \dot{u}_2(t) = -\alpha_2 u_2(t) + \gamma_{12} h_2(v_1(t - \sigma_2)), \\ \dot{v}_1(t) = -\alpha_3 v_1(t) + \gamma_{13} h_3(u_1(t - \sigma_3)) \\ \quad + \gamma_{23} h_3(u_2(t - \sigma_4)), \end{cases} \quad (2)$$

where $\alpha_i (i = 1, 2)$ and α_3 describe the stability of internal neuron processes on the U -layer and V -layer, respectively, $\gamma_{11}, \gamma_{12}, \gamma_{13}, \gamma_{23}$ are the connection weights through neurons in two layers, h_1, h_2 and h_3 stand for different activation functions, $\sigma_i (i = 1, 2, 3, 4)$ is time delay. Taking the sum of the delays $\sigma = \sigma_1 + \sigma_3 = \sigma_2 + \sigma_4$ as a parameter, the author investigated the stability and the existence of Hopf bifurcation and Hopf bifurcation nature. In addition, the estimation of the length of delay to preserve stability had been analyzed. The global existence of Hopf bifurcation of system (2) was studied by S^1 -equivariant degree ([51-52]).

Based on the analysis above, we establish a fractional-order version of model (2) as follows:

$$\begin{cases} \mathcal{D}^\vartheta u_1(t) = -\alpha_1 u_1(t) + \gamma_{11} h_1(v_1(t - \sigma_1)), \\ \mathcal{D}^\vartheta u_2(t) = -\alpha_2 u_2(t) + \gamma_{12} h_2(v_1(t - \sigma_2)), \\ \mathcal{D}^\vartheta v_1(t) = -\alpha_3 v_1(t) + \gamma_{13} h_3(u_1(t - \sigma_3)) \\ \quad + \gamma_{23} h_3(u_2(t - \sigma_4)), \end{cases} \quad (3)$$

where $\vartheta \in (0, 1]$ and $\alpha_i > 0 (i = 1, 2, 3)$. All other parameters have the same implication as those in (2).

The main object of this article is to consider the impact of time delay on the stability and the existence of Hopf bifurcation of system (3).

In order to obtain the key results of system (3), the following assumptions are made:

- (A1) For $i = 1, 2, 3$, $\alpha_i > 0$, $h_i \in C^1$, $h_i(0) = 0$.
- (A2) $\sigma_1 + \sigma_3 = \sigma_2 + \sigma_4 = \sigma$.

The highlights of this manuscript are listed as follows:

(a) We extend the integer-order neural networks with multiple delays to fractional-order neural networks with multiple delays, which can describe the memory and hereditary properties of neural networks better.

(b) The sufficient conditions of stability and the existence of Hopf bifurcation of fractional-order neural networks with multiple delays have been established. The study shows that the delay has important influence on the stability and the existence of Hopf bifurcation of involved networks.

(c) Up to now, there are rare papers that investigate the Hopf bifurcation on fractional-order differential models with multiple delays. Many works focus on the Hopf bifurcation of fractional-order differential equations with single delay. Our obtained results enrich the Hopf bifurcation theory of fractional-order delayed differential equations and complete the earlier published manuscripts.

(d) The idea of this research can be transferred to discuss numerous other fractional-order delayed differential models.

The rest of this article is planned as follows. In segment 2, we some notations and preliminary results on fractional calculus are prepared. In segment 3, the influence of delay on stability and Hopf bifurcation of (3) has been revealed. Numerical simulations to illustrate the correctness of the theoretical findings are conducted in segment 4. At last, a brief conclusion is included.

II. PRELIMINARY RESULTS

In this section, the related knowledge about fractional calculus will be prepared.

Definition 1 [54]: The fractional integral of order θ for a function $h(\varsigma)$ is defined as follows:

$$I^\vartheta h(\varsigma) = \frac{1}{\Gamma(\vartheta)} \int_{\varsigma_0}^{\varsigma} (\varsigma - s)^{\vartheta-1} h(s) ds,$$

where $\varsigma \geq \varsigma_0$, $\vartheta > 0$, $\Gamma(s) = \int_0^\infty \zeta^{s-1} e^{-\zeta} d\zeta$.

Definition 2 [54]: Let $h(\varsigma) \in (I[\varsigma_0, \infty), R)$. Define the Caputo fractional-order derivative of order ϑ as follows:

$$\mathcal{D}^\vartheta h(\varsigma) = \frac{1}{\Gamma(\iota - \vartheta)} \int_{\varsigma_0}^{\varsigma} \frac{h^{(\iota)}(s)}{(\varsigma - s)^{\vartheta-\iota+1}} ds,$$

where $\varsigma \geq \varsigma_0$ and ι is a positive integer which satisfies $\iota - 1 \leq \vartheta < \iota$. Typically, if $0 < \vartheta < 1$, then

$$\mathcal{D}^\vartheta h(\nu) = \frac{1}{\Gamma(1 - \vartheta)} \int_{\varsigma_0}^{\nu} \frac{h'(s)}{(\nu - s)^\vartheta} ds.$$

Lemma 1 [55]: Give the autonomous system $\mathcal{D}^\vartheta z = \mathcal{A}z$, $z(0) = z_0$ where $0 < \vartheta < 1$, $z \in R^m$, $\mathcal{A} \in R^{m \times m}$. Let $\lambda_i (i = 1, 2, \dots, m)$ be the root of the characteristic equation of $\mathcal{D}^\vartheta z = \mathcal{A}z$. Then system $\mathcal{D}^\vartheta z = \mathcal{A}z$ is asymptotically stable $\Leftrightarrow |\arg(\lambda_i)| > \frac{\vartheta\pi}{2} (i = 1, 2, \dots, m)$. this system is stable $\Leftrightarrow |\arg(\lambda_i)| > \frac{\vartheta\pi}{2} (i = 1, 2, \dots, m)$ and those critical eigenvalues that satisfy $|\arg(\lambda_i)| = \frac{\vartheta\pi}{2} (i = 1, 2, \dots, m)$ possess geometric multiplicity one.

III. IMPACT OF DELAY ON HOPF BIFURCATION FOR FRACTIONAL BAM NEURAL NETWORKS

In this section, we will discuss the impact of time delay on the Hopf bifurcation of the fractional BAM neural networks. By (A1), we know that the equilibrium point of system is the zero.

Let $w_1(t) = u_1(t - \sigma_3)$, $w_2(t) = u_2(t - \sigma_4)$, $w_3(t) = v_1(t)$. Then (3) can be written as

$$\begin{cases} \mathcal{D}^\vartheta w_1(t) = -\alpha_1 w_1(t) + \gamma_{11} h_1(w_3(t - \sigma)), \\ \mathcal{D}^\vartheta w_2(t) = -\alpha_2 w_2(t) + \gamma_{12} h_2(w_3(t - \sigma)), \\ \mathcal{D}^\vartheta w_3(t) = -\alpha_3 w_3(t) + \gamma_{13} h_3(w_1(t)) \\ \quad + \gamma_{23} h_3(w_2(t)). \end{cases} \quad (4)$$

The linear equation of (4) near the zero equilibrium point can be written as follows:

$$\begin{cases} \mathcal{D}^\vartheta w_1(t) = -\alpha_1 w_1(t) + \rho_{11} w_3(t - \sigma), \\ \mathcal{D}^\vartheta w_2(t) = -\alpha_2 w_2(t) + \rho_{12} w_3(t - \sigma), \\ \mathcal{D}^\vartheta w_3(t) = -\alpha_3 w_3(t) + \rho_{13} w_1(t) + \rho_{23} w_2(t), \end{cases} \quad (5)$$

where $\rho_{1l} = \gamma_{1l} h'_l(0) (l = 1, 2, 3)$, $\rho_{23} = \gamma_{23} h'_3(0)$. The corresponding characteristic equation of (5) is given by

$$\det \begin{bmatrix} s^\vartheta + \alpha_1 & 0 & -\rho_{11} e^{-s\sigma} \\ 0 & s^\vartheta + \alpha_2 & -\rho_{12} e^{-s\sigma} \\ -\rho_{13} & -\rho_{23} & s^\vartheta + \alpha_3 \end{bmatrix}. \quad (6)$$

Then

$$s^{3\vartheta} + a_1 s^{2\vartheta} + a_2 s^\vartheta + a_3 + (a_4 s^\vartheta + a_5) e^{-s\sigma} = 0, \quad (7)$$

where

$$\begin{aligned} a_1 &= \alpha_1 \alpha_2 \alpha_3, \\ a_2 &= \alpha_1 \alpha_2 + \alpha_1 \alpha_3 + \alpha_2 \alpha_3, \\ a_3 &= \alpha_1 \alpha_2 \alpha_3, \\ a_4 &= -(\rho_{11} \rho_{13} + \rho_{12} \rho_{23}), \\ a_5 &= -(\rho_{11} \rho_{13} \alpha_2 + \rho_{12} \rho_{23} \alpha_1). \end{aligned}$$

Denote

$$\begin{aligned} A_1(s) &= s^{3\vartheta} + a_1 s^{2\vartheta} + a_2 s^\vartheta + a_3, \\ A_2(s) &= a_4 s^\vartheta + a_5. \end{aligned}$$

Then (7) takes the form:

$$\mathcal{A}_1(s) + \mathcal{A}_2(s) e^{-s\sigma} = 0. \quad (8)$$

If $s = i\varphi = \varphi (\cos \frac{\pi}{2} + i \sin \frac{\pi}{2})$ is a root of (8). By (8), one gets

$$\begin{cases} \mathcal{A}_{2R}(\varphi) \cos \varphi\sigma + \mathcal{A}_{2I}(\varphi) \sin \varphi\sigma = -\mathcal{A}_{1R}(\varphi), \\ \mathcal{A}_{2I}(\varphi) \cos \varphi\sigma - \mathcal{A}_{2R}(\varphi) \sin \varphi\sigma = -\mathcal{A}_{1I}(\varphi), \end{cases} \quad (9)$$

where \mathcal{A}_{iR} , \mathcal{A}_{iI} are the real parts and imaginary parts of $\mathcal{A}_i(s) (i = 1, 2)$, respectively, which are given by

$$\begin{aligned} \mathcal{A}_{1R}(\varphi) &= \varphi^{3\vartheta} \cos \frac{3\pi\vartheta}{2} + a_1 \varphi^{2\vartheta} \cos \vartheta\pi \\ &\quad + a_2 \varphi^\vartheta \cos \frac{\pi\vartheta}{2} + a_3, \end{aligned}$$

$$\begin{aligned} \mathcal{A}_{1I}(\varphi) &= \varphi^{3\vartheta} \sin \frac{3\pi\vartheta}{2} + a_1\varphi^{2\vartheta} \sin \vartheta\pi \\ &\quad + a_2\varphi^\vartheta \sin \frac{\pi\vartheta}{2}, \\ \mathcal{A}_{2R}(\varphi) &= a_4\varphi^\vartheta \cos \frac{\pi\vartheta}{2} + a_5, \\ \mathcal{A}_{2I}(\varphi) &= a_4\varphi^\vartheta \sin \frac{\pi\vartheta}{2}. \end{aligned}$$

By (9), one has

$$\begin{cases} \cos \varphi\sigma = -\frac{\mathcal{A}_{1R}(\varphi)\mathcal{A}_{2R}(\varphi) + \mathcal{A}_{1I}(\varphi)\mathcal{A}_{2I}(\varphi)}{(\mathcal{A}_{2R}(\varphi))^2 + (\mathcal{A}_{2I}(\varphi))^2}, \\ \sin \varphi\sigma = \frac{\mathcal{A}_{1I}(\varphi)\mathcal{A}_{2R}(\varphi) - \mathcal{A}_{1R}(\varphi)\mathcal{A}_{2I}(\varphi)}{(\mathcal{A}_{2R}(\varphi))^2 + (\mathcal{A}_{2I}(\varphi))^2}. \end{cases} \quad (10)$$

By (10), we get

$$\begin{aligned} &[\mathcal{A}_{1R}(\varphi)\mathcal{A}_{2R}(\varphi) + \mathcal{A}_{1I}(\varphi)\mathcal{A}_{2I}(\varphi)]^2 \\ &\quad + [\mathcal{A}_{1I}(\varphi)\mathcal{A}_{2R}(\varphi) - \mathcal{A}_{1R}(\varphi)\mathcal{A}_{2I}(\varphi)]^2 \\ &= [(\mathcal{A}_{2R}(\varphi))^2 + (\mathcal{A}_{2I}(\varphi))^2]^2. \end{aligned} \quad (11)$$

Notice that

$$\begin{aligned} &[\mathcal{A}_{1R}(\varphi)\mathcal{A}_{2R}(\varphi) + \mathcal{A}_{1I}(\varphi)\mathcal{A}_{2I}(\varphi)]^2 \\ &= b_1\varphi^{8\vartheta} + b_2\varphi^{7\vartheta} + b_3\varphi^{6\vartheta} + b_4\varphi^{5\vartheta} + b_5\varphi^{4\vartheta} \\ &\quad + b_6\varphi^{3\vartheta} + b_7\varphi^{2\vartheta} + b_8\varphi^\vartheta + b_9, \end{aligned} \quad (12)$$

$$\begin{aligned} &[\mathcal{A}_{1I}(\varphi)\mathcal{A}_{2R}(\varphi) - \mathcal{A}_{1R}(\varphi)\mathcal{A}_{2I}(\varphi)]^2 \\ &= c_1\varphi^{8\vartheta} + c_2\varphi^{7\vartheta} + c_3\varphi^{6\vartheta} + c_4\varphi^{5\vartheta} \\ &\quad + c_5\varphi^{4\vartheta} + c_6\varphi^{3\vartheta} + c_7\varphi^{2\vartheta}, \end{aligned} \quad (13)$$

$$\begin{aligned} &[(\mathcal{A}_{2R}(\varphi))^2 + (\mathcal{A}_{2I}(\varphi))^2]^2 \\ &= d_1\varphi^{2\vartheta} + d_2\varphi^\vartheta + d_3, \end{aligned} \quad (14)$$

where

$$b_1 = a_4^2 \left(\cos \frac{3\pi\vartheta}{2} \cos \frac{\pi\vartheta}{2} + \sin \frac{3\pi\vartheta}{2} \sin \frac{\pi\vartheta}{2} \right)^2,$$

$$\begin{aligned} b_2 &= 2a_4 \left(\cos \frac{3\pi\vartheta}{2} \cos \frac{\pi\vartheta}{2} + \sin \frac{3\pi\vartheta}{2} \sin \frac{\pi\vartheta}{2} \right) \\ &\quad \times \left[a_1a_4 \left(\cos \pi\vartheta \cos \frac{\pi\vartheta}{2} + \sin \pi\vartheta \sin \frac{\pi\vartheta}{2} \right) \right. \\ &\quad \left. + a_5 \cos \frac{3\pi\vartheta}{2} \right], \end{aligned}$$

$$\begin{aligned} b_3 &= 2a_4 \left(\cos \pi\vartheta \cos \frac{\pi\vartheta}{2} + \sin \pi\vartheta \sin \frac{\pi\vartheta}{2} \right) \\ &\quad \times (a_2a_4 + a_1a_5 \cos \pi\vartheta) \\ &\quad \times \left[a_1a_4 \left(\cos \pi\vartheta \cos \frac{\pi\vartheta}{2} + \sin \pi\vartheta \sin \frac{\pi\vartheta}{2} \right) \right. \\ &\quad \left. + a_5 \cos \frac{3\pi\vartheta}{2} \right]^2, \end{aligned}$$

$$\begin{aligned} b_4 &= 2 \left[a_1a_4 \left(\cos \pi\vartheta \cos \frac{\pi\vartheta}{2} + \sin \pi\vartheta \sin \frac{\pi\vartheta}{2} \right) \right. \\ &\quad \left. + a_5 \cos \frac{3\pi\vartheta}{2} \right] (a_2a_4 + a_1a_5 \cos \pi\vartheta), \end{aligned}$$

$$b_5 = (a_2a_4 + a_1a_5 \cos \pi\vartheta)^2 + 2a_3a_4a_5$$

$$\begin{aligned} &\times \left(\cos \frac{\pi\vartheta}{2} \cos \frac{3\pi\vartheta}{2} + \sin \frac{\pi\vartheta}{2} \sin \frac{3\pi\vartheta}{2} \right) \\ &\times 2 \left[a_1a_4 \left(\cos \pi\vartheta \cos \frac{\pi\vartheta}{2} + \sin \pi\vartheta \sin \frac{\pi\vartheta}{2} \right) \right. \end{aligned}$$

$$\left. + a_5 \cos \frac{3\pi\vartheta}{2} \right] \left(a_3a_4 + a_2a_5 \cos \frac{\pi\vartheta}{2} \right),$$

$$b_6 = 2a_3a_5(a_1a_4 \cos \pi\vartheta \cos \frac{\pi\vartheta}{2} + a_5 \cos \frac{3\pi\vartheta}{2}$$

$$\begin{aligned} &\quad + a_1a_4 \sin \pi\vartheta \sin \frac{\pi\vartheta}{2} + 2(a_2a_4 \\ &\quad + a_1a_5 \cos \pi\vartheta)(a_3a_4 + a_2a_5) \cos \frac{\pi\vartheta}{2}, \end{aligned}$$

$$b_7 = 2a_3a_5(a_2a_4 + a_1a_5 \cos \pi\vartheta),$$

$$b_8 = 2a_3a_5(a_3a_5 + a_2a_4) \cos \frac{\pi\vartheta}{2},$$

$$b_9 = (a_3a_5)^2,$$

$$c_1 = \left[a_4 \sin \frac{3\pi\vartheta}{2} \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right) \right]^2,$$

$$c_2 = 2a_4 \sin \frac{3\pi\vartheta}{2} \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right)$$

$$\times \left[a_1a_4 \cos \pi\vartheta \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right) \right.$$

$$\left. + a_5 \sin \frac{3\pi\vartheta}{2} \right],$$

$$c_3 = \left[a_1a_4 \sin \pi\vartheta \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right) \right.$$

$$\left. + a_5 \sin \frac{3\pi\vartheta}{2} \right]^2$$

$$+ 2a_4 \sin \frac{3\pi\vartheta}{2} \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right)$$

$$\times \left[a_2a_4 \left(\cos \frac{\pi\vartheta}{2} \sin \frac{\pi\vartheta}{2} - \sin^2 \frac{\pi\vartheta}{2} \right) \right.$$

$$\left. + a_1a_5 \sin \pi\vartheta \right],$$

$$c_4 = 2a_2a_4a_5 \sin \frac{\pi\vartheta}{2} \sin \frac{3\pi\vartheta}{2} \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right)$$

$$+ 2 \left[a_1a_4 \sin \pi\vartheta \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right) \right.$$

$$\left. + a_5 \sin \frac{3\pi\vartheta}{2} \right]$$

$$\times \left[a_2a_4 \left(\cos \frac{\pi\vartheta}{2} \sin \frac{\pi\vartheta}{2} - \sin^2 \frac{\pi\vartheta}{2} \right) \right.$$

$$\left. + a_1a_5 \sin \pi\vartheta \right],$$

$$c_5 = \left[a_2a_4 \left(\cos \frac{\pi\vartheta}{2} \sin \frac{\pi\vartheta}{2} - \sin^2 \frac{\pi\vartheta}{2} \right) \right.$$

$$\left. + a_1a_5 \sin \pi\vartheta \right]^2$$

$$+ 2 \left[a_1a_4 \sin \pi\vartheta \left(\cos \frac{\pi\vartheta}{2} - \sin \frac{\pi\vartheta}{2} \right) \right.$$

$$\left. + a_5 \sin \frac{3\pi\vartheta}{2} \right] a_2a_5 \sin \frac{\pi\vartheta}{2},$$

$$c_6 = 2 \left[a_2a_4 \left(\cos \frac{\pi\vartheta}{2} \sin \frac{\pi\vartheta}{2} - \sin^2 \frac{\pi\vartheta}{2} \right) \right.$$

$$\begin{aligned}
 &+a_1a_5 \sin \pi \vartheta] a_2a_5 \sin \frac{\pi \vartheta}{2}, \\
 c_7 &= \left(a_2a_5 \sin \frac{\pi \vartheta}{2} \right)^2, \\
 d_1 &= a_4^2, \\
 d_2 &= 2a_4a_5 \cos \frac{\pi \vartheta}{2}, \\
 d_3 &= a_5^2.
 \end{aligned}$$

It follows from (11) that

$$\begin{aligned}
 K_1\varphi^{8\vartheta} + K_2\varphi^{7\vartheta} + K_3\varphi^{6\vartheta} + K_4\varphi^{5\vartheta} + K_5\varphi^{4\vartheta} \\
 + K_6\varphi^{3\vartheta} + K_7\varphi^{2\vartheta} + K_8\varphi^\vartheta + K_9 = 0, \quad (15)
 \end{aligned}$$

where $K_i = b_i + c_i (i = 1, 2, 3, 4, 5, 6)$, $K_7 = b_7 + c_7 - d_1$, $K_8 = b_8 - d_2$, $K_9 = b_9 - d_3$.

Denote

$$\begin{aligned}
 g(\varphi) &= K_1\varphi^{8\vartheta} + K_2\varphi^{7\vartheta} + K_3\varphi^{6\vartheta} + K_4\varphi^{5\vartheta} \\
 &+ K_5\varphi^{4\vartheta} + K_6\varphi^{3\vartheta} + K_7\varphi^{2\vartheta} + K_8\varphi^\vartheta + K_9. \quad (16)
 \end{aligned}$$

and

$$\begin{aligned}
 l(\mu) &= K_1\mu^8 + K_2\mu^7 + K_3\mu^6 + K_4\mu^5 + K_5\mu^4 \\
 &+ K_6\mu^3 + K_7\mu^2 + K_8\mu + K_9. \quad (17)
 \end{aligned}$$

The following hypothesis is given:

(A3) $\alpha_1\alpha_2\alpha_3 - (\rho_{11}\rho_{13}\alpha_2 + \rho_{12}\rho_{23}\alpha_1) \neq 0$.

Lemma 2: For (7), the following results are true:

- (a) If $K_i > 0 (i = 1, 2, \dots, 9)$ holds, then (7) has no root with zero real parts.
- (b) If $K_9 < 0$, then (7) has at least pair of purely imaginary roots.
- (c) If $K_9 > 0$ and $\exists \theta_0 > 0$ which satisfies $l(\theta_0) < 0$, then (3.4) has at least two pairs of purely imaginary roots.
- (d) If $K_i > 0 (i = 1, 2, \dots, 7)$, $K_8 < 0$, $K_9 > 0$ and $\exists \theta_0 > 0$ which satisfies $l(\theta_0) < 0$, then (7) has at least two pairs of purely imaginary roots.
- (e) If $K_i > 0 (i = 1, 2, \dots, 6)$, $K_7 < 0$, $K_9 > 0$ and $\exists \theta_0 > 0$ such that $l(\theta_0) < 0$, then (7) has at least two pairs of purely imaginary roots.

Proof: We will prove the five cases, respectively.

(a) It follows from (16) that

$$\begin{aligned}
 \frac{dg(\varphi)}{d\varphi} &= 8\vartheta K_1\varphi^{8\vartheta-1} + 7\vartheta K_2\varphi^{7\vartheta-1} + 6\vartheta K_3\varphi^{6\vartheta} \\
 &+ 5\vartheta K_4\varphi^{5\vartheta-1} + 4\vartheta K_5\varphi^{4\vartheta-1} + 3\vartheta K_6\varphi^{3\vartheta-1} \\
 &+ 2\vartheta K_7\varphi^{2\vartheta-1} + \vartheta K_8\varphi^{\vartheta-1}.
 \end{aligned}$$

In view of $K_i > 0 (i = 1, 2, \dots, 9)$, we know that $\frac{dg(\varphi)}{d\varphi} > 0 \forall \varphi > 0$. Notice that $g(0) = K_9 > 0$, then Eq. (15) has no positive real root. By (A3), one knows that $a_3 + a_5 \neq 0$, then $s = 0$ is not the root of (7). The proof of (a) is complete.

(b) Obviously, $g(0) = K_9 < 0$ and $\lim_{\varphi \rightarrow +\infty} g(\varphi) = +\infty$. Then (15) has at least one positive real root. Thus (7) has at least one pair of purely imaginary roots. The proof of (b) is complete.

(c) Since $l(0) = K_9 > 0$, $l(\theta_0) < 0 (\theta_0 > 0)$ and $\lim_{\mu \rightarrow +\infty} l(\mu) = +\infty$, then $\exists \theta_{01} \in (0, \theta_0)$ and $\theta_{02} \in (\theta_0, +\infty)$ which satisfy $l(\theta_{01}) = l(\theta_{02}) = 0$. Then Eq. (15) has at least two positive real roots. Thus (7) has at least two pairs of purely imaginary roots. The proof of (c) ends.

(d) Clearly, in view of $K_i > 0 (i = 1, 2, \dots, 7)$, one has $\frac{d^2l(\mu)}{d\mu^2} > 0, \forall \mu > 0$. In addition, $\frac{dl(\mu)}{d\mu}|_{\mu=0} = K_8 < 0$ and $\lim_{\mu \rightarrow +\infty} \frac{dl(\mu)}{d\mu} = +\infty$, then $\frac{dl(\mu)}{d\mu} = 0$ has only one positive real root. So $l(\mu)$ has a unique stationary point for $\mu > 0$. Since $l(0) = K_9 > 0$, $l(\theta_0) < 0 (\theta_0 > 0)$ and $\lim_{\mu \rightarrow +\infty} l(\mu) = +\infty$, one can conclude that $l(\mu) = 0$ has two positive real roots. Hence $g(\varphi)$ has two positive real roots. Thus (7) has two pairs of purely imaginary roots. The proof of (d) is complete.

(e) According to $l(0) = K_9 > 0$ and $l(\theta_0) < 0, \forall \theta_0 > 0$, $\exists \theta_1 \in (0, \theta_0)$ which satisfies $\frac{dl(\mu)}{d\mu}|_{\mu=\theta_1} < 0$. According to $\lim_{\mu \rightarrow +\infty} \frac{dl(\mu)}{d\mu} = +\infty$, one has that $\frac{dl(\mu)}{d\mu} = 0$ has at least one positive real root. Notice that $\frac{d^3l(\mu)}{d\mu^3} > 0 (\mu > 0)$, $\frac{d^2l(\mu)}{d\mu^2}|_{\mu=0} = 2K_7 < 0$ and $\lim_{\mu \rightarrow +\infty} \frac{d^2l(\mu)}{d\mu^2} = +\infty$. Thus $\frac{d^2l(\mu)}{d\mu^2} = 0$ has only one positive real root. Then $\frac{dl(\mu)}{d\mu}$ has only the unique stationary point for $\mu > 0$, which implies that $\frac{dl(\mu)}{d\mu} = 0$ has at most two positive real roots and $l(\mu) = 0$ has at most three positive real roots. In addition, in view of $l(0) = K_9 > 0$, $l(\theta_0) < 0 (\theta_0 > 0)$ and $\lim_{\mu \rightarrow +\infty} \frac{dl(\mu)}{d\mu} = +\infty$, one has that $l(\mu) = 0$ may have $2j (j = 1, 2, 3, 4)$ positive real roots. Therefore $l(\mu) = 0$ has two positive real roots and $g(\varphi) = 0$ has two positive real roots. So (7) has two pairs of purely imaginary roots. The proof of (e) ends.

Without loss of generality, if (15) has nine positive real roots $\varphi_j (j = 1, 2, \dots, 9)$. By (10), one gets

$$\begin{aligned}
 \sigma_j^k &= \frac{1}{\varphi_j} \left[\arccos \left(-\frac{\mathcal{A}_{1R}(\varphi)\mathcal{A}_{2R}(\varphi) + \mathcal{A}_{1I}(\varphi)\mathcal{A}_{2I}(\varphi)}{(\mathcal{A}_{2R}(\varphi))^2 + (\mathcal{A}_{2I}(\varphi))^2} \right) \right. \\
 &\quad \left. + 2l\pi \right], \quad (18)
 \end{aligned}$$

where $l = 0, 1, 2, \dots, j = 1, 2, \dots, 9$. Denote

$$\sigma_0 = \min_{j=1,2,\dots,9} \{\sigma_j^0\}, \varphi_0 = \varphi|_{\sigma=\sigma_0}. \quad (19)$$

Now we give the following hypotheses:

(A4) $\mathcal{L}_1\mathcal{S}_1 + \mathcal{L}_2\mathcal{S}_2 > 0$, where

$$\begin{aligned}
 \mathcal{L}_1 &= 3\vartheta\varphi_0^{3\vartheta-1} \cos \frac{(3\vartheta-1)\pi}{2} + 2a_1\vartheta\varphi_0^{2\vartheta-1} \\
 &\times \cos \frac{(2\vartheta-1)\pi}{2} + a_2\vartheta\varphi_0^{(\vartheta-1)} \cos \frac{(\vartheta-1)\pi}{2} \\
 &+ a_4\vartheta\varphi_0^{\vartheta-1} \left[\cos \frac{(\vartheta-1)\pi}{2} \cos \varphi_0\sigma_0 \right. \\
 &\quad \left. + \cos \frac{(\vartheta-1)\pi}{2} \cos \varphi_0\sigma_0 \right], \\
 \mathcal{L}_2 &= 3\vartheta\varphi_0^{3\vartheta-1} \sin \frac{(3\vartheta-1)\pi}{2} + 2a_1\vartheta\varphi_0^{2\vartheta-1} \\
 &\times \sin \frac{(2\vartheta-1)\pi}{2} + a_2\vartheta\varphi_0^{(\vartheta-1)} \sin \frac{(\vartheta-1)\pi}{2}
 \end{aligned}$$

$$+a_4 \vartheta \varphi_0^{\vartheta-1} \left[\cos \frac{(\vartheta-1)\pi}{2} \sin \varphi_0 \sigma_0 - \sin \frac{(\vartheta-1)\pi}{2} \cos \varphi_0 \sigma_0 \right],$$

$$S_1 = -a_4 \varphi_0^{\vartheta+1} \sin \frac{\vartheta \pi}{2},$$

$$S_2 = \varphi_0 \left(a_4 \varphi_0^{\vartheta} \cos \frac{\vartheta \pi}{2} + a_5 \right).$$

Lemma 3: If $s(\sigma) = \mu(\sigma) + i\varphi(\sigma)$ is the root of (7) around $\sigma = \sigma_0$ satisfying $\mu(\sigma_0) = 0, \varphi(\sigma_0) = \varphi_0$, then $Re \left[\frac{ds}{d\sigma} \right] \Big|_{\sigma=\sigma_0, \varphi=\varphi_0} \neq 0$.

Proof: By (7), one gets

$$\left[\frac{ds}{d\sigma} \right]^{-1} = \frac{p(s)}{q(s)} - \frac{\sigma}{s}, \tag{20}$$

where

$$p(s) = 3\vartheta s^{3\vartheta-1} + 2a_1 \vartheta s^{2\vartheta-1} + a_2 \vartheta s^{\vartheta-1} + a_4 \vartheta s^{\vartheta-1} e^{-s\sigma},$$

$$q(s) = s(a_4 s^{\vartheta} + a_5).$$

Then

$$Re \left\{ \left[\frac{ds}{d\sigma} \right]^{-1} \right\} = Re \left\{ \frac{p(s)}{q(s)} \right\}. \tag{21}$$

Therefore

$$Re \left\{ \left[\frac{ds}{d\sigma} \right]^{-1} \right\} \Big|_{\sigma=\sigma_0, \varphi=\varphi_0} = Re \left\{ \frac{p(s)}{q(s)} \right\} \Big|_{\sigma=\sigma_0, \varphi=\varphi_0} = \frac{\mathcal{L}_1 S_1 + \mathcal{L}_2 S_2}{S_1^2 + S_2^2}.$$

By (A4), one has

$$Re \left\{ \left[\frac{ds}{d\sigma} \right]^{-1} \right\} \Big|_{\sigma=\sigma_0, \varphi=\varphi_0} > 0.$$

Then the transversality condition holds. This ends the proof of Lemma 2.

Now we consider the stability of (1.3) with $\sigma = 0$. The following assumption is given:

$$(A5) \ a_1 > 0, a_1(a_2 + a_4) > a_3 + a_5, a_1(a_2 + a_4)(a_3 + a_5) > (a_3 + a_5)^2.$$

It is not difficult to obtain the following lemma.

Lemma 3: If $\sigma = 0$ and (A5) are true, then model (3) is asymptotically stable.

Proof: Let $\sigma = 0$, then (7) can be written as follows:

$$\lambda^3 + a_1 \lambda^2 + (a_2 + a_4)\lambda + (a_3 + a_5) = 0. \tag{22}$$

By (A5), one has that all the roots λ_i of (21) satisfies $|\arg(\lambda_i)| > \frac{\vartheta \pi}{2} (i = 1, 2, 3, 4)$ According to Lemma 2, one can conclude that model (3) with $\sigma = 0$ is asymptotically stable. This ends the proof of Lemma 3.

Theorem 1: For model (3), if (A1)-(A5) hold true, then the zero equilibrium point is global asymptotically stable when

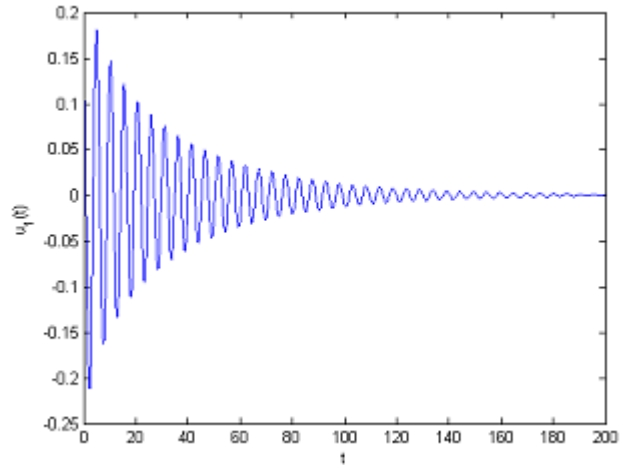


FIGURE 1. The relation of t and $u_1(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

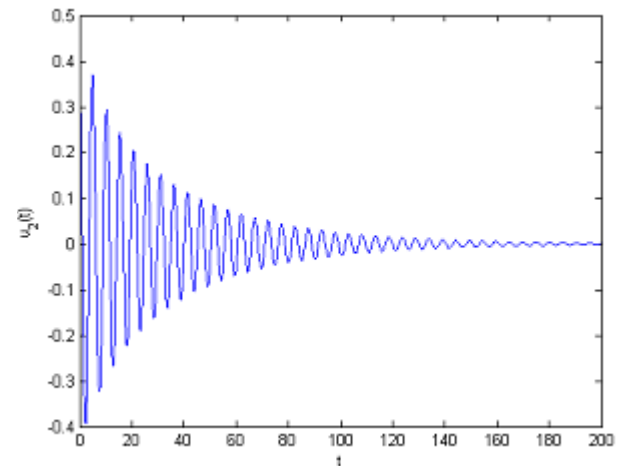


FIGURE 2. The relation of t and $u_2(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

$\sigma \in [0, \sigma_0)$ and a Hopf bifurcation appears around the zero equilibrium point for $\sigma = \sigma_0$.

Remark 1: In [38]–[44], [56], the authors studied the stability and Hopf bifurcation of integer-order neural networks delays. In this article, we study the stability and Hopf bifurcation of fractional-order neural networks with four different delays. All the derived results in [38]–[44], [56] can not be applied to (3) to obtain the stability and the existence of Hopf bifurcation for (3). Based on the reason, the main results of this article on the stability and the existence of Hopf bifurcation for (3) are completely new and complete previous publications.

Remark 2: Huang and Cao [45] discussed the effect of leakage delay on bifurcation in high-order fractional BAM neural networks. In [47], the authors investigated the control problem of bifurcation for a delayed fractional gene regulatory network. In [48], the authors studied the bifurcation behavior on fractional complex-valued neural network. In [49], Huang et al. discussed the effect of leakage delay

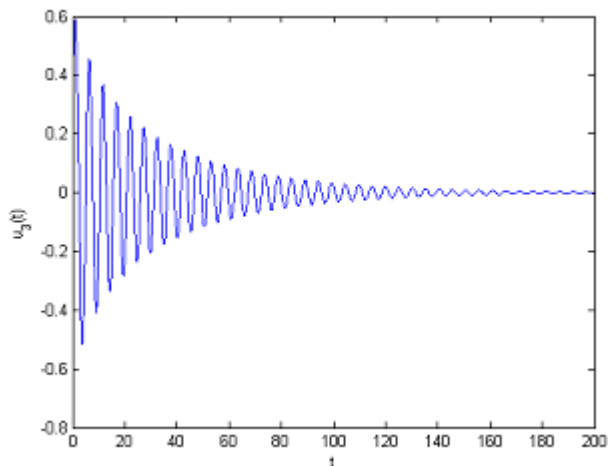


FIGURE 3. The relation of t and $u_3(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

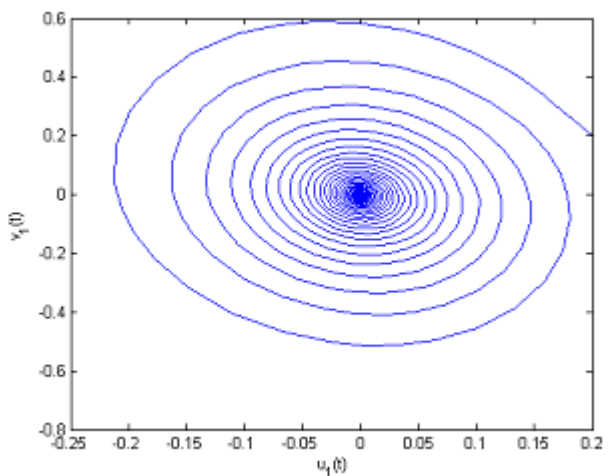


FIGURE 4. The relation of $u_1(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

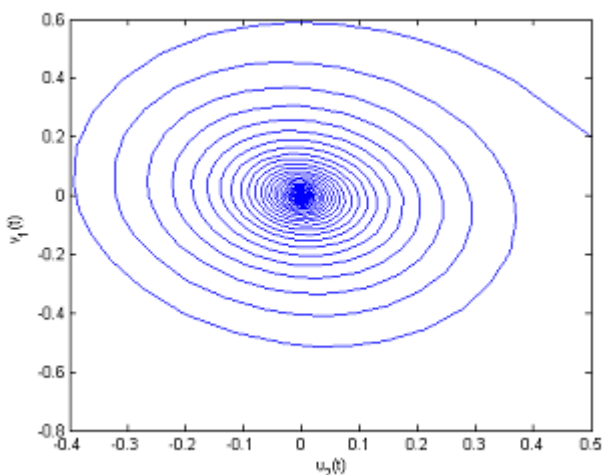


FIGURE 5. The relation of $u_2(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

on bifurcation for fractional BAM neural networks. All the publications [45], [47]–[49] only involve a single delay. In this article, we investigate the Hopf bifurcation of involved

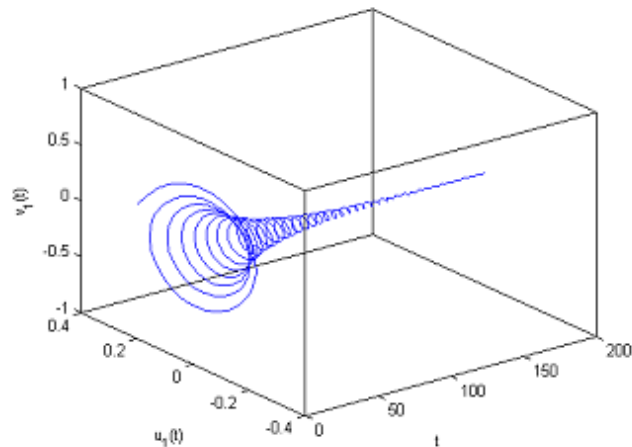


FIGURE 6. The relation of $t, u_1(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

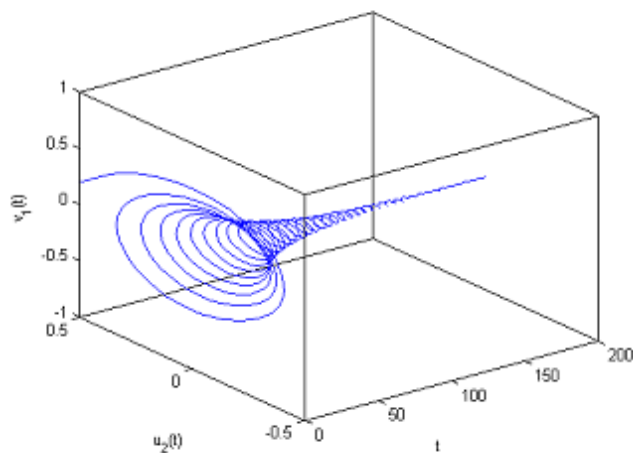


FIGURE 7. The relation of $t, u_2(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

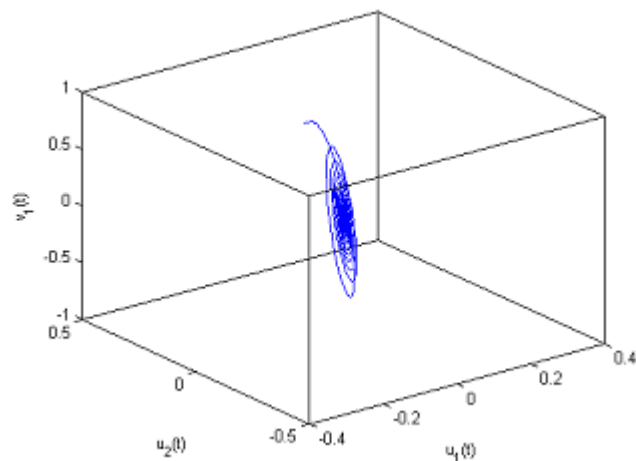


FIGURE 8. The relation of $u_1(t), u_2(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$.

models with four different delays by choosing the sum of two different delays as bifurcation parameter. Up to now, there are few results on Hopf bifurcation of fractional-order systems with multiple delays. From the viewpoint, the main results of

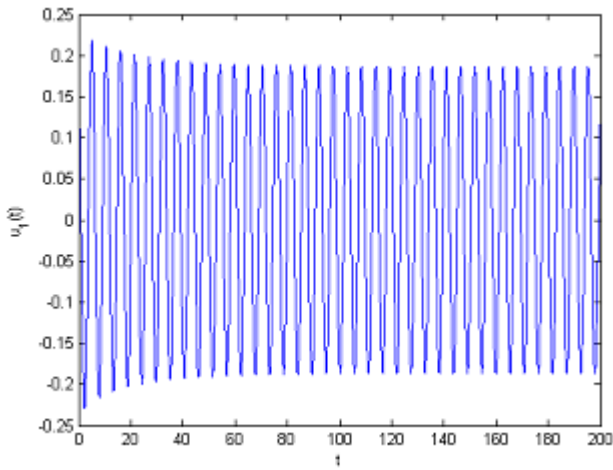


FIGURE 9. The relation of t and $u_1(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

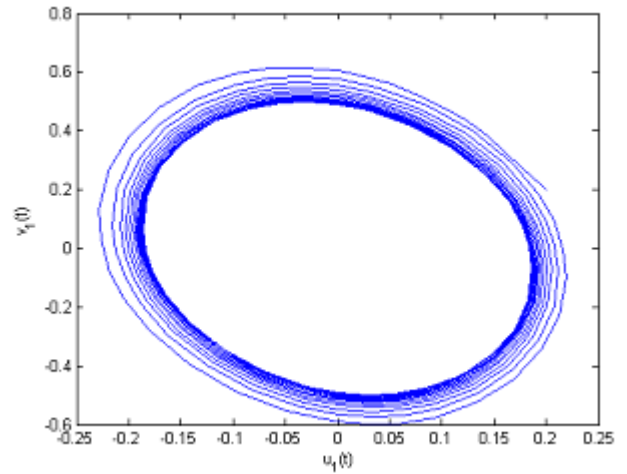


FIGURE 12. The relation of $u_1(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

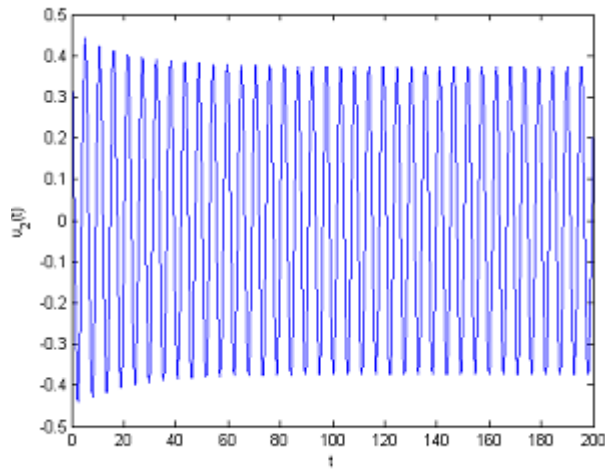


FIGURE 10. The relation of t and $u_2(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

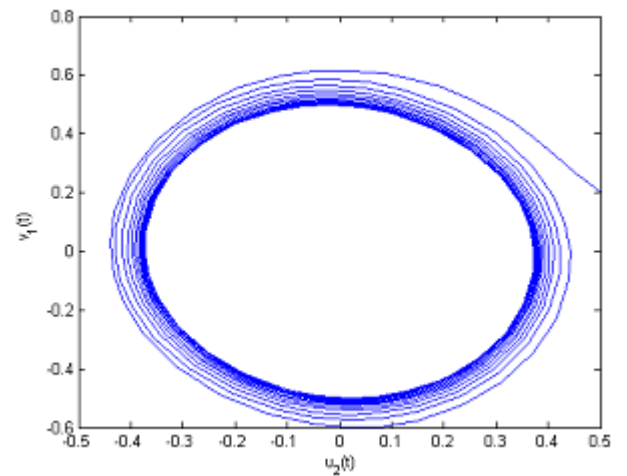


FIGURE 13. The relation of $u_2(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

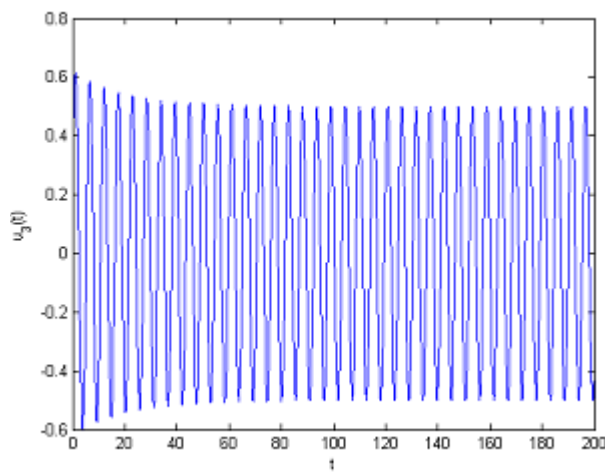


FIGURE 11. The relation of t and $u_3(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

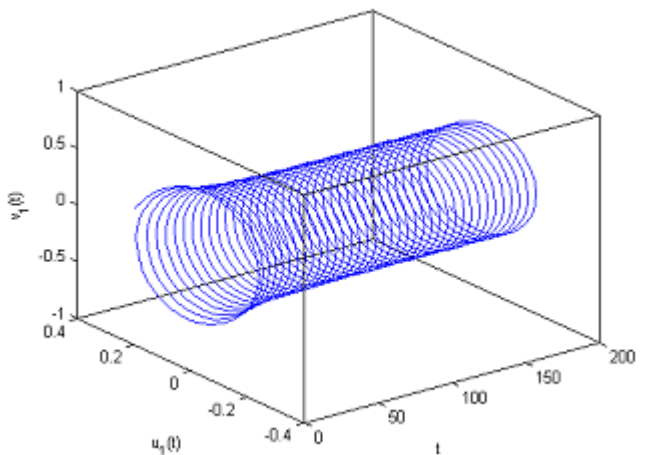


FIGURE 14. The relation of $t, u_1(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

this article on stability and existence of Hopf bifurcation of neural networks are essentially innovative.

Remark 3: The results on the considered fractional-order neural networks with four delays can not extend the

result with n -delays since the characteristic equation of fractional-order neural networks with n -delays is more complex.

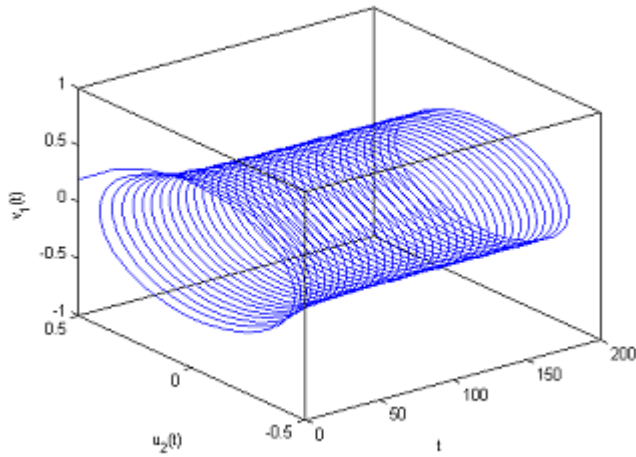


FIGURE 15. The relation of t , $u_2(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

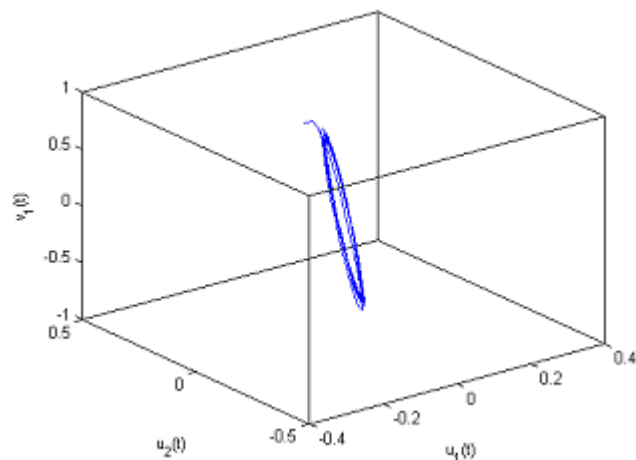


FIGURE 16. The relation of $u_1(t)$, $u_2(t)$ and $v_1(t)$ when $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6, \sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$.

Remark 4: In order to obtain the stability and the existence of Hopfbifurcation of model (3), we carried out some complex computation. If the parameters are given, we can compute corresponding value by computer.

IV. COMPUTER SIMULATIONS

Consider the following fractional-order model:

$$\begin{cases} \mathcal{D}^\vartheta u_1(t) = -0.5u_1(t) - 0.5 \tanh(v_1(t - \sigma_1)), \\ \mathcal{D}^\vartheta u_2(t) = -0.5u_2(t) - \tanh(v_1(t - \sigma_2)), \\ \mathcal{D}^\vartheta v_1(t) = -0.5v_1(t) + 2 \tanh(u_1(t - \sigma_3)) \\ \quad + 0.6 \tanh(u_2(t - \sigma_4)). \end{cases} \quad (23)$$

All the coefficients and functions are same as those in Xu [38]. Set $\vartheta = 0.82$. Then $\varphi_0 = 0.6759$ and $\sigma_0 = 1.7664$. We can verify that (A1)-(A5) of Theorem 1 are fulfilled. Let $\sigma_1 = 1, \sigma_2 = 0.7, \sigma_3 = 0.5, \sigma_4 = 0.8$, then $\sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.5 < \sigma_0 = 1.7664$. In this case, we can conclude that the zero equilibrium point of model (23) is locally asymptotically stable.

Figures 1-8 indicate that the zero equilibrium point of model (23) is locally asymptotically stable for $\sigma \in [0, \sigma_0)$. Let $\sigma_1 = 1, \sigma_2 = 1.2, \sigma_3 = 0.8, \sigma_4 = 0.6$, then $\sigma = \sigma_1 + \sigma_3 = \sigma_1 + \sigma_3 = 1.8 > \sigma_0 = 1.7664$. In this case, model (23) becomes unstable and a Hopf bifurcation exists. Figures 9-16 manifest that model (23) becomes unstable and a Hopf bifurcation takes place for $\sigma \in [\sigma_0, +\infty)$. In addition, we can see that the order can postpone the onset of Hopf bifurcation (compared with Xu [38]).

V. CONCLUSIONS

The bifurcation issue of fractional order delayed BAM neural networks has been analyzed in details. By discussing the distribution of characteristic roots of corresponding characteristic equation of involved system and choosing the sum of different delays as bifurcation parameter, we establish a set of sufficient conditions to ensure the stability and the existence of Hopf bifurcation of considered neural networks. The study reveals that the delay has important effect on the stability and Hopf bifurcation of involved neural networks. We find that when the sum of delays remain the suitable interval, then the equilibrium point of involved system is locally asymptotically stable, while the Hopf bifurcation appears when the sum of delays exceed some critical values. The obtained results on the stability and the existence of Hopf bifurcation of fractional order delayed BAM neural networks can be applied to design and optimize neural networks. It will be widely applied in artificial intelligence, automatic control, disease diagnosis, image processing, etc. So we can say that the study of this manuscript plays an important role in serving human beings.

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