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Capacity-Achieving Signals for Point-to-Point and Multiple-Access Channels Under Non-Gaussian Noise and Peak Power Constraint

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ABSTRACT This paper generalizes and proves the discrete and finite nature of the capacity-achieving signaling schemes for general classes of non-Gaussian point-to-point and multiple-access channels (MACs) under peak power constraints. Specifically, we first investigate the detailed characteristics of capacity-achieving inputs for a single-user channel that is impaired by two types of noise: a Gaussian mixture (GM) noise Z consisting of Gaussian elements with arbitrary means and the interference U with an arbitrary distribution. The only very mild condition imposed on U is that its second moment is finite. To this end, one of the important results is the establishment of the Kuhn–Tucker condition (KTC) on a capacity-achieving input and the proof of analyticity of the KTC using Fubini–Tonelli's and Morera's theorems. Using the Bolzano–Weierstrass's and Identity's theorems, we then show that a capacity-achieving input is continuous if and only if the KTC function is zero on the entire real line. However, by examining an upper bound on the tail of the output PDF, it is demonstrated that the KTC function must be bounded away from zero. As such, any capacity-achieving input must be discrete with a finite number of mass points. Finally, we exploit U having an arbitrary distribution to show that the optimal input distributions that achieve the sum-capacity of an M-user MAC under GM noise are discrete and finite. We also prove that there exist at least two distinct points that achieve the sum capacity on the rate region.

INDEX TERMS Channel capacity, Gaussian mixture, multiple access channels, non-Gaussian interference, optimal inputs.

I. INTRODUCTION

The presence of multi-tier heterogeneous architectures mixed with limited spectral resources in current and future wired and wireless communication systems leads to increased co-channel interference, which is intermittent and asynchronous with the main communication. In many cases, the aggregate co-channel interference plus noise cannot be treated as Gaussian [2]–[7]. Examples of such channels include impulsive interference channels in digital subscriber line (DSL) [8]–[10], power line communications (PLC) [4], [11]–[14], underwater acoustic channels [15]–[17], and heterogeneous wireless networks involving marcocells, microcells, femtocells, device-to-device (D2D) links, Wi-Fi access points, and cognitive radio (CR) [2], [5]–[7], [18]. As a result, the traditional approach of using Gaussian signaling schemes for system analysis and design no longer holds. It should be noted that non-Gaussian interference is also observed in speech and audio signals [19], as well as in imaging science [20], [21]. For instance, in image processing, corruption of images due to impulsive interference is a significant hurdle. This interference is caused by a noisy sensor or sensor heat. It may also occur during image acquisition, recording, or transmission [20], [21].

Over the years, several interesting results on informationtheoretical aspects of non-Gaussian channels have been obtained for single-user point-to-point channels [22]–[28]. For example, in [29], the characteristics of a capacityachieving input were studied for channels under generalized Gaussian noise, and the discreteness of a capacity-achieving input was shown for some special cases of generalized Gaussian noise. However, a generalized Gaussian distribution is not general enough to represent any arbitrary distribution. In [22] and [23], predefined conditions on noise distributions have been examined to guarantee the discreteness of the optimal input under the input average power constraint. Unfortunately, for many non-Gaussian models, the noise distributions do not satisfy those pre-defined conditions. If a more practical limitation of the input peak constraint is imposed, the capacity-achieving input signal is shown to be finite and discrete [24]-[26]. Recently, [30] has considered a general class of non-Gaussian channels under the assumption of two conditions imposed on the noise distribution. These two conditions rely on a lower bound and an upper bound on the noise distribution. While these conditions are satisfied by several well-known distributions, they do not hold in more general cases. Thus, the characterizations of capacityachieving inputs for more general non-Gaussian point-topoint channels remain to be elucidated. It is worth mentioning that the discreteness of the optimal input amplitude has also been observed in Gaussian channels under the average power constraint together with other constraints, such as peak constraint [31], [32], non-coherent conditions [33]-[36], rapid phase variations [37], or duty cycle [38]. Due to the difficulty in studying the detailed properties of the optimal input and in establishing the capacity in closed-form for a non-Gaussian channel, a novel approach was proposed in [39] to study the sensitivity of the capacity, i.e., how the capacity changes when the channel parameters vary.

While information-theoretical results for point-to-point links are certainly useful, it is also important to extend the analysis and design to multi-user networks. One of the most fundamental network scenarios is the multiple access channel (MAC) for the uplink, and this scenario has been well-investigated for Gaussian channels under average power constraints with many breakthroughs. Under this line of work, Gaussian signals are usually assumed to be optimal for the design and analysis. In a recent work in [40], a two-user Gaussian MAC under peak power constraints is investigated. It has been shown in [40] that both users can use finite and discrete signaling schemes to achieve any point on the boundary of the capacity region. The proof in [40] is relied on the key result that for a point-to-point link that is affected by a Gaussian noise and an interference having a finite support, the capacityachieving input is discrete under the peak power constraint. To our knowledge, network information-theoretical results for non-Gaussian noise and interference are lacking. Therefore, considering non-Gaussian interference plus noise in multi-user networks presents new challenges.

In this work, we attempt to generalize and prove the discrete and finite nature of the capacity-achieving signaling schemes for general classes of non-Gaussian point-to-point and multiple-access channels under peak power constraints. Specifically, we first investigate the detailed characteristics of capacity-achieving inputs for a single-user channel that is impaired by two types of noise: a Gaussian mixture (GM) noise Z consisting of Gaussian elements with arbitrary means, and the interference U with an arbitrary distribution. Different from [40] that assumed a finitely supported U, the only very mild condition we impose on U is that its second moment is finite. Note that when U is either Gaussian or GM, the total noise W = U + Z is a GM. We then extend the results to a general *M*-user Gaussian mixture MAC. Different from the previous literature that only investigated GM noise with zero-mean components (please see [27], [41], and references therein), our considered GM noise with arbitrary-mean Gaussian components can be used to approximate any distribution of engineering interest to arbitrary accuracy [42]-[45]. The significance of our results is two-fold as follows:

- Since the considered GM is general enough to represent all PDFs of engineering interest, the proof of the discreteness and finiteness of the capacity-achieving input partially addresses the conjecture in [24] that the capacity-achieving input for any peak power constrained channel is discrete with finite number of mass points. The results in this work can be used in system analysis for various channels impaired by different sources of interference, such as cognitive radio with imperfect spectrum sensing and 5G and beyond heterogeneous cellular networks [2], [3], [5]–[7], [18], [46].
- The obtained results also shed important light on the characteristics of capacity-achieving signaling schemes for a multiple-access non-Gaussian channel, which has not been explored in the literature so far.

In this paper, we follow a standard procedure to prove the optimality of discrete input by first showing the existence of the optimal solution before eliminating the possibility of having an optimal continuous input. However, the novelty in technical derivations and analysis makes our work stand out from the current state-of-the-art. Specifically, for the pointto-point channel, by using lower and upper bounds on the probability density functions (PDFs) of the total noise W and the output, we first show that the mutual information (MI) is continuous and concave. Therefore, the capacity-achieving input exists. We then establish a necessary and sufficient Kuhn-Tucker condition (KTC) on an optimal input, and show that the KTC function is analytic on the complex plane. While this analyticity is obvious for Gaussian channels, the consideration of the general noise model W = U + Z is much more challenging, and it requires new techniques. In particular, our proof relies on Fubini-Tonelli's and Morera's theorems, which is very different from the standard approach employed in [31]. Then using the Bolzano-Weierstrass and Identity Theorems, we show that a capacity-achieving input is continuous if only if the KTC is zero on the entire real line. However, by establishing and examining an upper bound on the tail of the output PDF, the KTC is proved to be bounded away from zero. As such, any capacity-achieving input must be discrete

with a finite number of mass points. Note that the traditional approach of using the Fourier transform of the noise distribution as in [31] cannot be used, since there exist zeros in the transformation. Finally, building upon the results of the point-to-point channel, we characterize the sum-capacity achieving signaling schemes of a multiple access channel under GM noise. Specifically, we exploit the arbitrary nature of U to show that the optimal input distributions that achieve the sum-capacity of an M-user MAC under GM noise are discrete and finite. In addition, we prove that there exist at least two different points that achieve the sum capacity on the rate region.

The results and tools developed in this work will be important to major communication systems, such as power line communications, digital subscriber lines, urban indoor and outdoor wireless communications, cognitive radio, and underwater acoustic communications. More importantly, insights from the developed information-theoretic results can be exploited to develop powerful and efficient signaling and coding techniques for practical purposes. In addition, other disciplines such as imaging science can also benefit from the proposed results and methodologies to advance the current state-of-the-art.

The rest of this paper is organized as follows. Sec. II introduces the considered single-user and multiple-access non-Gaussian channels. Detailed characteristics of a capacity-achieving input for the single-user channel are studied in Sec. III. Numerical examples are also provided in this section to confirm the analysis. In Sec. IV, we address the characterization of optimal inputs for a multiple-access channel. Finally, conclusions are drawn in Sec. V.

II. POINT-TO-POINT AND MULTI-USER NON-GAUSSIAN CHANNELS: CHANNEL MODELS

A. SINGLE-USER CHANNEL

We consider a non-Gaussian point-to-point channel with the following input-output model

$$V = X + U + Z,\tag{1}$$

where X and V are the channel input and output, respectively. Here, it is assumed that the input is subject to a peak power constraint $|X| \leq A$, which is a practical constraint for any communication system. In (1), U and Z are two sources of additive noise/interference. We assume that U follows a fixed yet arbitrary distribution with only a mild condition that its second moment is finite. This assumption in fact holds true for almost all practical interference sources. In addition, $Z \in \mathbb{R}$ is a Gaussian Mixture (GM) with its PDF being a weighted sum of N Gaussian component densities with arbitrary means. The PDF of Z can be expressed as

$$f_Z(z) = \sum_{n=1}^N \varepsilon_n \mathcal{N}(z, a_n, \sigma_n^2), \qquad (2)$$

where $\mathcal{N}(z, \mu, \sigma^2)$ denotes a real Gaussian distribution with mean μ and variance σ^2 , and $\varepsilon_n > 0$ is the mixing probability

For a given input cumulative distribution function (CDF) $F_X(x)$, the mutual information between the input and output of the channel can be calculated as

$$I(X; V) = h(V; F_X(x)) - h(V \mid X) \stackrel{\Delta}{=} I(F_X(x)), \quad (3)$$

where $h(V; F_X(x))$ is the output entropy given as

$$h(V; F_X(x)) = -\int_{\mathbb{R}} f_V(v; F_X(x)) \ln f_V(v; F_X(x)) \, dv.$$
(4)

Note that $f_V(v; F_X(x))$ is the PDF of the output V for a given input $F_X(x)$. In addition, h(V | X) = h(W) is the total noise entropy. Under the peak input power constraint $|X| \le A$, the Shannon capacity of the channel is the supremum of I(X; V) over the feasible set of $F_X(x)$, which is expressed as

$$C = \sup_{F_X(x)\in\mathcal{F}} I(F_X(x)),\tag{5}$$

where \mathcal{F} is the set of all CDFs having all mass points in the interval [-A, A], i.e., $\mathcal{F} = \left\{F : \int_{-A}^{A} dF(x) = 1\right\}$. The optimal input distribution, which is denoted as $F_X^*(x)$, is referred to as the capacity-achieving input. Since h(W) is independent of $F_X(x)$, the capacity-achieving input maximizes the output entropy. For convenience, hereafter, the use of $F_X(x)$ and F_X to indicate the distribution of the input is interchangeable.



FIGURE 1. An M-user multiple-access channel (MAC) under GM noise Z.

B. MULTIPLE-ACCESS CHANNEL (MAC) UNDER GM NOISE In this paper, we are also interested in a MAC under a GM noise Z in (2) in which M users communicate with a common receiver as shown in Fig. 1. Let's assume that X_i is the signal of user $i, i = 1 \cdots M$, and it is imposed by the peak constraint $|X_i| \le A_i$. The received signal Y is then written as:

$$Y = \sum_{i=1}^{M} X_i + Z.$$
 (6)

Note that with a suitable choice of $\{N, \varepsilon_n, a_n, \sigma_n\}$, a GM Z can be used to represent any PDF of engineering interest [42]–[45]. Furthermore, with arbitrary mean Gaussian components, the GM model considered in this work is more

general than other GM channels studied earlier using all zeromean Gaussian elements.

For the considered MAC, the sum-capacity is the supremum of the joint MI between the inputs and output over the feasible set of the inputs, and it is given as:

$$C_{\text{sum}} = \sup_{\substack{F_{X_i} \in \mathcal{F}_{i,i=1} \cdots M}} I(X_1, X_2, \dots, X_M; Y)$$

$$\stackrel{\Delta}{=} \sup_{\substack{F_{X_i} \in \mathcal{F}_{i,i=1} \cdots M}} I\left(\{F_{X_i}\}_{i=1}^M\right). \tag{7}$$

In (7), each set \mathcal{F}_i , $1 \leq i \leq M$, consists of all CDFs having mass points in the interval $[-A_i, A_i]$. A given set of the input distributions $\{F_{X_i}^{\star}\}$ that achieves C_{sum} is called the optimal set.

III. DETAILED CHARACTERISTICS OF OPTIMAL F_X^{\star} IN **POINT-TO-POINT CHANNELS**

In this section, the focus is on the point-to-point channel in (1). In the following, we will first show the existence of an optimal input distribution F_X^{\star} before investigating its detailed characteristics.

A. EXISTENCE OF F_X^*

It has been well-known that the set \mathcal{F} of all distributions F_X satisfying the peak power constraint is convex and weakly compact with respect to weak* topology [47]. In addition, the output entropy and the mutual information are concave with respect to F_X . As such, to prove the existence of the optimal F_X^{\star} , we only need to show the weak continuity of the output entropy on the feasible set of input distributions. Therefore, the key steps are to show the weak continuity of $f_V(v; F_X)$ on F_X and obtain an integrable upper bound on $|f_V(v; F_X) \ln f_V(v; F_X)|$. Toward this end, we first have the following proposition regarding the continuity of the PDF $f_W(\cdot)$.

Proposition 1: The function $f_W(w)$: $\mathbb{R} \rightarrow \mathbb{R}$ is continuous.

Proof: We first have:

$$f_W(w) = \int_{-\infty}^{\infty} f_Z(w-u) dF_U(u).$$
(8)

Now, let $\{w_n\} \in \mathbb{R}$ be a sequence such that $\lim_{n \to \infty} w_n = w_0$ for some $w_0 \in \mathbb{R}$. Since the GM PDF $f_Z(z)$ is continuous, we have

$$\lim_{n\to\infty} f_Z(w_n-u) = f_Z(w_0-u), \quad \forall u \in \mathbb{R}.$$

Without loss of generality, it is assumed that $\sigma_1 \ge \cdots \ge \sigma_N$. Therefore, $f_Z(z) \le \frac{1}{\sqrt{2\pi\sigma_N^2}}$. It then follows that

$$0 \le f_Z \left(w_n - u \right) \le \frac{1}{\sqrt{2\pi\sigma_N^2}}.$$
(9)

Then by applying Dominated Convergence Theorem [48], we can conclude that

$$\lim_{n\to\infty}f_W(w_n)=f_W(w_0),$$

which implies the continuity of $f_W(w)$.

Note that in a similar manner, we can show the continuity of $f_V(v; F_X)$ in v for a given F_X . The next proposition states the weak continuity of $f_V(v; F_X)$ with respect to the input distribution.

Proposition 2: $f_V(v; F_X)$ is weakly continuous in F_X .

Proof: Assume we have a sequence $\{F_X^{(n)}\}$ that weakly converges to some specific $F_X^{(0)}$, i.e., $\{F_X^{(n)}\} \xrightarrow{\text{w}} F_X^{(0)}$. Besides its continuity, $f_W(\cdot)$ is also upper bounded by the constant $d = \sum_{n=1}^N \frac{\varepsilon_n}{\sqrt{2\pi\sigma_n^2}}$ as shown in Appendix A. In addition, we have $f_V(v; F) = \int_{-\infty}^{\infty} f_W(v - x) dF(x)$. Therefore,

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$$\lim_{n \to \infty} f_V(v; F_X^{(n)}) = \lim_{n \to \infty} \int_{-\infty}^{\infty} f_W(v - x) dF_X^{(n)}(x)$$
$$= \int_{-\infty}^{\infty} f_W(v - x) dF_X^{(0)}(x)$$
(10)

$$= f_V(v; F_X^{(0)}) \tag{11}$$

It should be noted that (10) comes from Helly-Bray theorem [49].

We then have the following theorem regarding the weak continuity of the output entropy $h(V; F_X(x))$.

Theorem 1: The entropy $h(V; F_X)$ is weakly continuous in F_X .

Proof: First, assume that $F_X^{(n)} \xrightarrow{w*} F_X^{(0)}$. From Proposition 2, we have $\lim_{n \to \infty} f_V(v; F_X^{(n)}) = f_V(v; F_X^{(0)})$ for all $v \in \mathbb{R}$. Moreover, since $f(\xi) = \xi \ln \xi$ is continuous for $\xi > 0$, we obtain

$$\lim_{n \to \infty} f_V(v; F_X^{(n)}) \ln f_V(v; F_X^{(n)}) = f_V(v; F_X^{(0)}) \ln f_V(v; F_X^{(0)}).$$

Therefore, by Lebesgue Dominated Convergence Theorem, to prove the weak continuity of output entropy, it is enough to show that $|f_V(v; F_X^{(n)}) \ln f_V(v; F_X^{(n)})|$ is upper bounded by an integrable function of v uniformly in n. First, as shown in Appendix A, there always exist positive k_0 and k_1 such that

$$f_W(w) \le k_1 w^{-2}$$
 when $|w| > k_0$. (12)

Therefore, for all $|v| > A + k_0$ we have:

$$f_{V}\left(v; F_{X}^{(n)}\right) = \int_{-A}^{A} f_{W}(v-x) dF_{X}^{(n)}(x)$$

$$\leq \int_{-A}^{A} k_{1} (v-x)^{-2} dF_{X}^{(n)}(x)$$

$$\leq k_{1} (|v|-A)^{-2}.$$
(13)

In addition, as we demonstrate in Appendix B, $f_V(v; F_X^{(n)})$ is always upper bounded by the constant *d*. Therefore, we have

$$f_V\left(v; F_X^{(n)}\right) \le \begin{cases} k_1 \left(|v| - A\right)^{-2}, & |v| > A + k_0\\ d, & |v| \le A + k_0. \end{cases}$$
(14)

It is well known that $\ln x^{\gamma-1} \le x^{\gamma-1}$ for $0 < x, \gamma < 1$, and $\ln x \le \frac{x^{\gamma}}{\gamma}$ for any positive x and γ . As such, for any $0 < \gamma < \gamma$ 1, we have $|x \ln x| \le \max\{\frac{1}{1-\gamma}, \frac{\beta}{\gamma}\}x^{\gamma}$ when $0 < x < \beta$ for any positive β . By combining this with (14), we have

$$|f_V(v; F_X^{(n)}) \ln f_V(v; F_X^{(n)})| \le g(v), \tag{15}$$

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where g(v) is given as:

$$g(\nu) = \begin{cases} \max\{\frac{1}{1-\gamma}, \frac{d}{\gamma}\} \left(k_1 \left(|\nu| - A\right)^{-2}\right)^{\gamma}, & |\nu| > A + k_0 \\ \max\{\frac{1}{1-\gamma}, \frac{d}{\gamma}\} d^{\gamma}, & |\nu| \le A + k_0. \end{cases}$$
(16)

It can be verified that g(v) is an integrable function for $\frac{1}{2}$ < $\gamma < 1$. Therefore, $h(V; F_X)$ is weakly continuous.

Given the result in Theorem 1, it can be concluded that the output entropy, and as a consequence, the mutual information is weakly continuous and concave. Therefore, the optimal input distribution exists on \mathcal{F} .

B. DISCRETENESS OF F_x^*

Given the existence of F_X^{\star} , this subsection focuses on the characterization of F_X^{\star} . In particular, we prove that the optimal input support set E^* of any optimal F_X^* has a finite number of mass points. To this end, we first establish the Kuhn-Tucker condition (KTC), which is a necessary and sufficient condition for an input to be optimal, and show that the KTC is analytic on the complex plane. By exploiting this analyticity of the KTC, we then demonstrate that it is not possible to have a continuous F_X^{\star} .

1) THE KTC AND ITS ANALYTICITY

For convenience, some preliminaries regarding the concepts of directional derivative and optimization theory are given in Appendix D. We then have the following theorem regarding the KTC:

Theorem 2 (KTC): F_X^* is an optimal input distribution if and only if

- i) $\Phi(x) = \int_{-\infty}^{\infty} f_W(v x) \ln f_V(v; F_X^{\star}) dv + H^{\star} \ge 0, \quad \forall x \in [-A, A]$ where $H^{\star} = C + h(W)$.
- *ii)* The equality is achieved when $x \in E^*$, with E^* being the set of points of increase for F_X^{\star} defined as

$$E^{\star} = \left\{ z \in \mathbb{R} : F_X^{\star} \left(z + r \right) > F_X^{\star} \left(z - r \right), \quad \forall r > 0 \right\}.$$

$$\tag{17}$$

The proof of this theorem is similar to the arguments in [31]. It is because $I(F_X)$ is concave and continuous, and we have the existence and finiteness of the directional derivative for $I(F_X)$ (See Lemma 7 in Appendix D).

In the following, we will show that the KTC function $\Phi(x)$ is analytic on the complex plane. To this end, we have the following lemmas regarding the analyticity of $f_W (v - s)$ and $\rho(s) = \int_{-\infty}^{\infty} f_W(v-s) \ln f_V(v; F_X) dv$ as functions of s.

Lemma 1: For any $v \in \mathbb{R}$, the function $f_W(v-s) : \mathbb{C} \to \mathbb{C}$ \mathbb{C} is analytic.

Proof: We will first demonstrate that $f_W(v-s)$ is continuous. Specifically, let $\{s_n\}_{n \in \mathbb{N}}$, be a sequence in \mathbb{C} such that $\lim_{n\to\infty} s_n = s_*$ for $s_* \in \mathbb{C}$. From (8), and the fact that $f_{Z}(.)$ is continuous and analytic over \mathbb{C} , which results in $\lim_{n\to\infty} f_Z(v - s_n - u) = f_Z(v - s_* - u)$ for all $u, v \in \mathbb{R}$, the continuity of $f_W(v-s)$ is reduced to finding an integrable

upper bound for $f_Z(v-s_n-u)$. Since s_n converges, there exists b > 0 such that $|s_n| \le b$ for any $n \in \mathbb{N}$. We then have:

$$\begin{aligned} |f_Z(v - s_n - u)| \\ &\leq \sum_{n=1}^N \frac{\varepsilon_n}{\sqrt{2\pi\sigma_n^2}} \left| \exp\left(-\frac{(v - s_n - u - a_n)^2}{2\sigma_n^2}\right) \right| \\ &= \sum_{n=1}^N \frac{\varepsilon_n \exp\left(\frac{[(\Im(s_n)]^2}{2\sigma_n^2}\right)}{\sqrt{2\pi\sigma_n^2}} \exp\left(-\frac{(v - \Re(s_n) - u - a_n)^2}{2\sigma_n^2}\right) \\ &\leq e^{\frac{b^2}{2\sigma_N^2}} f_Z(v - \Re(s_n) - u) \end{aligned}$$
(18)

$$\leq e^{2\sigma_N} f_Z(v - \Re(s_n) - u) \tag{18}$$

$$1 \quad \frac{b^2}{2c^2}$$

$$\leq \frac{1}{\sqrt{2\pi\sigma_N^2}} e^{2\sigma_N^2},\tag{19}$$

where \Re and \Im denote the real and imaginary parts, respectively. Note that the inequality in (18) is obtained by using $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_N$ and the fact that $|s_n| \leq b$. Then by using the Dominated Convergence Theorem, we have $\lim_{n\to\infty} f_W(v - s_n) = f_W(v - s_*)$. Equivalently, $s \to \infty$ $f_W(v-s)$ is continuous in \mathbb{C} . Now, let \triangle be an arbitrary triangular path in \mathbb{C} . Then,

$$\left|\oint_{\Delta} f_{W}(v-s)\,ds\right| \le len(\Delta) \max_{s\in\Delta} |f_{W}(v-s)| < \infty, \quad (20)$$

where $len(\Delta)$ denotes the length of the path Δ and we have used the fact that $\max_{s \in \Delta} |f_W(v - s)|$ exists and is finite due to continuity of $f_W(v-s)$ on the compact set \triangle . As a result, we can use Fubini-Tonelli theorem [50] and exchange the integrals \oint_{Δ} and $\int_{-\infty}^{\infty}$ to obtain the following:

$$\oint_{\Delta} f_W(v-s) \, ds = \int_{-\infty}^{\infty} \oint_{\Delta} f_Z(v-s-u) ds dF_U(u).$$
(21)

As $f_Z(\cdot)$ is analytic everywhere, we have $\oint_{\Delta} f_Z(v-s-u)ds = 0$ from Cauchy's Integral theorem [51]. It then follows that $\oint_{\Delta} f_W(v-s) ds = 0$ for any triangular path \triangle . Then by Morera's Theorem [51], we can conclude that $f_W(v - s)$ is analytic everywhere.

Lemma 2: The function $\rho(s) : \mathbb{C} \to \mathbb{C}$ is analytic for any $F_X \in \mathcal{F}.$

Proof: We will first show that $\rho(s)$ is continuous. As before, let $\{s_n\}_{n\in\mathbb{N}}$, be a sequence in \mathbb{C} such that $\lim_{n\to\infty} s_n = s_*$ for $s_* \in \mathbb{C}$. As we know that $f_W(v-s)$ is continuous, then by Generalized Lebesgue Dominated Convergence Theorem, it is enough to show that $\exists \{g_n(v)\}, g(v)$ such that

- i) $|f_W(v s_n) \ln f_V(v; F_X)| \le g_n(v).$
- ii) $g_n(v) \to g(v)$ almost everywhere. iii) $\lim_{n \to \infty} \int_{-\infty}^{\infty} g_n(v) dv = \int_{-\infty}^{\infty} g(v) dv < \infty$.

It is clear that for a function $g(\alpha)$ such that $0 < g(\alpha) \le \beta < \beta$ ∞ for all $\alpha \in \mathbb{R}$ and some $\beta > 0$, we have $|\ln g(\alpha)| \le -\ln g(\alpha) + 2 |\ln \beta|$. As $f_V(v; F_X^{(n)})$ is upper bounded by d, we have:

$$|\ln f_V(v; F_X^{(n)})| \le -\ln f_V(v; F_X^{(n)}) + 2|\ln d|.$$
 (22)

Then using the upper bound on $-\ln f_V(v; F_X^{(n)})$ given in Appendix B, we end up with the following inequality:

$$|\ln f_V(v; F_X^{(n)})| \le av^2 - 2b_2v + c_2 + 2|\ln d|.$$
(23)

As a result, using (18) and (23), we obtain the following bound:

$$\begin{aligned} |f_W(v - s_n) \ln f_V(v, F_X)| \\ &\leq e^{\frac{b^2}{2\sigma_N^2}} f_W(v - \Re(s_n)) \left(av^2 - 2b_2v + c_2 + 2|\ln d| \right) \\ &= g_n(v). \end{aligned}$$
(24)

Furthermore, we have:

$$\int_{\mathbb{R}} g_{n}(v) dv$$

$$= e^{\frac{b^{2}}{2a_{N}^{2}}} \int_{\mathbb{R}} f_{W}(v - \Re(s_{n})) \left(av^{2} - 2b_{2}v + c_{2} + 2|\ln d|\right) dv$$

$$= e^{\frac{b^{2}}{2a_{N}^{2}}} \left[a \int_{\mathbb{R}} v^{2} f_{W}(v - \Re(s_{n})) dv - 2b_{2} \int_{\mathbb{R}} v f_{W}(v - \Re(s_{n})) dv + c_{2} + 2|\ln d|\right]. \quad (25)$$

Now by changing the variables as $t = v - \Re(s_n)$ we have

$$\int_{\mathbb{R}} g_{n}(v) dv$$

$$= e^{\frac{b^{2}}{2\sigma_{N}^{2}}} \left[a \int_{\mathbb{R}} t^{2} f_{W}(t) dt + 2a \Re(s_{n}) \int_{\mathbb{R}} t f_{W}(t) dt + a \left(\Re(s_{n})\right)^{2} - 2b_{2} \int_{\mathbb{R}} t f_{W}(t) dt - 2b_{2} \Re(s_{n}) + c_{2} + 2 \left|\ln d\right| \right]$$

$$= e^{\frac{b^{2}}{2\sigma_{N}^{2}}} \left[aE \left[W^{2} \right] + (2a \Re(s_{n}) - 2b_{2}) E \left[W \right] + a \left(\Re(s_{n})\right)^{2} - 2b_{2} \Re(s_{n}) + c_{2} + 2 \left|\ln d\right| \right].$$
(26)

Since $E[W^2]$ and E[W] are finite, and the fact that $|\Re(s_n)| \leq b$, we have $\int_{\mathbb{R}} g_n(v) dv < \infty$. Moreover, as $\Re(s_n) \to \Re(s_*)$, it is straightforward to verify that $\lim_{n\to\infty} \int_{-\infty}^{\infty} g_n(v) dv = \int_{-\infty}^{\infty} g(v) dv$ based on equation (26), where g(v) is defined as $g_n(v)$ with s_* replacing s_n . Then using the Generalized Dominated Convergence Theorem, we can conclude that $\rho(s)$ is continuous. Considering the analyticity of $f_W(v-s)$ and following a similar procedure as in the proof of Lemma 1 using Fubini-Tonelli, Cauchy's Integral, and Morera's theorems, it can be shown that $\rho(s)$ is analytic.

Combining Lemmas 1 and 2, it can be concluded that the KTC function $\Phi(s)$: $\mathbb{C} \to \mathbb{C}$ is analytic everywhere.

2) DISCRETENESS OF OPTIMAL INPUT

Given the analyticity of the KTC function $\Phi(s) : \mathbb{C} \to \mathbb{C}$, we then now shed light on the characterization of an optimal input F_X^* . To this end, assume that the set E^* of F_X^* includes an infinite number of mass points on a bounded interval. This includes a continuous F_X^{\star} as a special case. From Bolzano-Weierstrass Theorem [50], this set of mass points admits a limit point. Furthermore, following the Identity Theorem [52], we know that if two analytic functions are identical on an infinite set of points in a region along with their limit points, these two functions must be identical in the entire region. As a result, we obtain the extended KTC as follows:

$$\Phi(x) = \int_{-\infty}^{\infty} f_W(v-x) \ln f_V\left(v; F_X^\star\right) dv + H^\star = 0 \quad \forall x \in \mathbb{R}.$$
(27)

In the following, we will show that it is not possible to have (27). Consider the two constants k_0 and k_1 defined in the proof of Theorem 1. We can then select a constant *m* such that $m > A + k_0 + E[|W|]$ and $\ln\left(\frac{e^{H^*}k_1}{(m-A)^2}\right) < 0$. It then follows that for all |v| > m

$$\ln\left(e^{H^*}f_V\left(\nu;F_X^*\right)\right) \le \ln\left(\frac{e^{H^*}k_1}{(|\nu|-A)^2}\right)$$
$$\le \ln\left(\frac{e^{H^*}k_1}{(m-A)^2}\right) < 0, \quad (28)$$

where the first inequality is obtained from (13). Now, we rewrite the KTC in (27) as

$$\int_{\Omega^{+}} f_{W}(v-x) \ln\left(e^{H^{*}}f_{V}\left(v;F_{X}^{\star}\right)\right) dv$$
$$= -\int_{\Omega^{-}} f_{W}(v-x) \ln\left(e^{H^{*}}f_{V}\left(v;F_{X}^{\star}\right)\right) dv, \qquad (29)$$

where

$$\Omega^{+} = \left\{ v \in \mathbb{R} : \ln\left(e^{H^{*}}f_{V}\left(v; F_{X}^{\star}\right)\right) \ge 0 \right\}, \qquad (30)$$

$$\Omega^{-} = \left\{ v \in \mathbb{R} : \ln\left(e^{H^{*}}f_{V}\left(v; F_{X}^{\star}\right)\right) \leq 0 \right\}.$$
(31)

Now, let first examine the left-hand side of (29). From (28), we have $\Omega^+ \subset [-m, m]$. Thus,

$$0 \leq \int_{\Omega^{+}} f_{W}(v-x) \ln\left(e^{H^{*}}f_{V}\left(v;F_{X}^{\star}\right)\right) dv$$
$$\leq \left[\max_{v\in\Omega^{+}} \ln\left(e^{H^{*}}f_{V}\left(v;F_{X}^{\star}\right)\right)\right] \int_{-m}^{m} f_{W}(v-x) dv. \quad (32)$$

Because of the continuity of $\ln \left(e^{H^*}f_V\left(v; F_X^*\right)\right)$, $\zeta = \max_{v \in \Omega^+} \ln \left(e^{H^*}f_V\left(v; F_X^*\right)\right)$ exists and is finite. Hence, for $x > m + k_0$, we have

$$0 \leq \int_{\Omega^{+}} f_{W}(v-x) \ln \left(e^{H^{*}} f_{V}\left(v; F_{X}^{\star}\right) \right) dv$$

$$\leq \zeta \int_{-m}^{m} f_{W}(v-x) dv$$

$$\leq 2m\zeta k_{1} \left(x-m\right)^{-2}, \qquad (33)$$

where the last inequality follows from (12). Therefore, as $x \to \infty$, the left hand side of (29) goes to zero.

For the right-hand side of (29), we have

$$-\int_{\Omega^{-}} f_{W}(v-x) \ln\left(e^{H^{*}}f_{V}\left(v;F_{X}^{\star}\right)\right) dv$$

$$\geq -\int_{m}^{\infty} f_{W}(v-x) \ln\left(e^{H^{*}}f_{V}\left(v;F_{X}^{\star}\right)\right) dv$$

$$\geq -\ln\left(\frac{e^{H^{*}}k_{1}}{(m-A)^{2}}\right) \int_{m}^{\infty} f_{W}(v-x) dv$$

$$= -\ln\left(\frac{e^{H^{*}}k_{1}}{(m-A)^{2}}\right) \Pr\left(W > m-x\right). \quad (34)$$

Moreover, for all x > 2m, by using Markov's inequality, we have

$$\Pr(W > m - x) \ge 1 - \Pr(|W| > m) \ge 1 - \frac{E[|W|]}{m} > 0.$$
(35)

By combining (35) and (34) we then have

$$-\int_{\Omega^{-}} f_{W}(v-x) \ln\left(e^{H^{*}}f_{V}\left(v;F_{X}^{\star}\right)\right) dv > l, \quad \forall x > 2m,$$
(36)

where $l = -\ln\left(\frac{e^{H^*}k_1}{(m-A)^2}\right)\left(1 - \frac{E[|W|]}{m}\right) > 0$. The inequalities in (33) and (36) therefore result in a contradiction. As a consequence, E^* consists of only a finite number of elements and, hence, any optimal F_X^* is discrete with a finite number of mass points.

C. NUMERICAL EXAMPLES

In this section, several numerical examples are provided to confirm the discreteness of the capacity-achieving input for the considered non-Gaussian channels. To find the optimal input numerically, we apply the well-known gradient descentbased method [31], [33]. In particular, starting with a single mass point distribution, we will identify the number of mass points, the locations of the mass points and their corresponding probabilities in an iterative manner. To guarantee the global optimality of the solution, the obtained distribution is verified with the necessary and sufficient condition given in Theorem 2.

We first consider a non-Gaussian channel impaired by a two-term GM noise Z with $f_Z(z) = 0.2\mathcal{N}(z, -4, 10) + 0.8\mathcal{N}(z, 1, 1)$ and a BPSK-like interference U with $f_U(u) = \frac{1}{2}\delta(u-2) + \frac{1}{2}\delta(u+2)$. It is not hard to verify that the total interference W is a four-term GM, and its PDF is shown in Fig. 2. The optimal input distributions at different signalto-noise ratios (SNRs), (with SNR defined as SNR $= \frac{A^2}{E[W^2]}$), are plotted in Fig. 3. Observe from Fig. 3 that at sufficiently low SNRs, the optimal input has only two mass points. As the SNR increases, the number of mass points also increases. To verify the optimality of the solutions, we have also plotted the left hand side of KTC function at SNR = 1dB in Fig. 4. Clearly, the KTC is equal to zero at three mass points. It is also interesting to note that in this case, we always have



FIGURE 2. The probability distribution function of a four-term GM W.



FIGURE 3. The location of mass points of the optimal input distribution and the corresponding probabilities with $f_Z(z) = 0.2\mathcal{N}(z, -4, 10) + 0.8\mathcal{N}(z, 1, 1)$ and $f_U(u) = \frac{1}{2}\delta(u-2) + \frac{1}{2}\delta(u+2)$.



FIGURE 4. The KTC values for the input distribution $f_X(x) = 0.4362 \delta$ $(x + 1.8775) + 0.2043 \delta (x - 0.004) + 0.3595 \delta (x - 1.8775)$ at SNR=1dB.

transmission at the peak power level, i.e., there are two mass points at A and -A.

In the second example, we consider another non-Gaussian channel impaired by a GM noise Z with $f_Z(z) = 0.1\mathcal{N}(z, 0, 2) + 0.9\mathcal{N}(z, 3, 1)$, and an interference U that follows a Laplace distribution with $f_U(u) = \frac{1}{2} \exp(-|u|)$.



FIGURE 5. The probability distribution function of *W* resulting from Laplace distributed *U*.



FIGURE 6. The location of mass points of the optimal input distribution and the corresponding probabilities with $f_Z(z) = 0.1\mathcal{N}(z, 0, 2) + 0.9\mathcal{N}(z, 3, 1)$ and $f_U(u) = \frac{1}{2} \exp(-|u|)$.

In this case, W is no longer a GM, and its PDF is given in Fig. 5. The optimal inputs for this channel are shown in Fig. 6 at different SNRs. We also plot the corresponding KTC at SNR = 1dB. As similar to the previous example, at a given SNR, it is clear that the optimal input is discrete.

IV. EXTENSION TO MULTI-USER CHANNELS UNDER GM NOISE

In this section, we address the detailed characterization of optimal inputs for an M-user MAC with GM noise under the peak-power constraints in (6). While we follow closely the arguments in [40] for a Gaussian MAC, the results in this section mainly rely on the arbitrary property of U and the results established in Section III. Specifically, we first show that the sum-capacity of the channels can only be achieved if each user uses a discrete distribution with a finite number of mass points. An interesting important property of the rate region is also given.

Now, for the considered MAC, by following a similar analysis as in Section III, it can be shown that a set of optimal input distributions $\{F_{X_i}^{\star}\}$ that achieves C_{sum} always exists.



FIGURE 7. The KTC value for the input distribution $f_X(x) = 0.5139 \delta(x + 1.9755) + 0.4861 \delta(x - 1.9755)$ at SNR=1dB.

However, such a set is not necessarily unique. For a given optimal set $\{F_{X_i}^{\star}\}$, it is clear that:

$$\{F_{X_i}^{\star}\} = \arg \sup_{F_{X_i} \in \mathcal{F}_i, i=1\cdots M} h\left(\sum_{i=1}^M X_i + Z\right).$$
(37)

To shed light on the characteristics of $\{F_{X_i}^*\}$, $1 \le i \le M$, consider a point-to-point link with an input X_i subject to the peak constraint in the feasible set \mathcal{F}_i and the output V impaired by two types of noise, the GM noise Z and the interference $U = \sum_{j=1, j \ne i}^{M} X_j^*$. Here, each $X_j^*, j \in \{1, \ldots, M\} \setminus \{i\}$, follows the distribution $F_{X_j}^*$, which is unknown yet fixed. Let F_{X_i}' be an optimal input distribution of this point-to-point channel, i.e.,

$$F'_{X_i} = \arg \sup_{F_{X_i} \in \mathcal{F}_i} I\left(F_{X_i}\right) = \arg \sup_{F_{X_i} \in \mathcal{F}_i} I\left(X_i; X_i + U + Z\right).$$
(38)

We then have the following lemma regarding the characteristics of F'_{X_i} .

Lemma 3: F'_{X_i} exists, and it is discrete and unique.

Proof: Since each $F_{X_i}^{\star}$, $1 \le i \le M$, is peak constrained, the distribution of U is fixed but unknown with a finite second-order moment. Therefore, it follows from the results for the point-to-point channel that F'_{X_i} exists, and it is discrete.

Next, it can be verified that the moment-generating function (MGF) of $U = \sum_{j=1, j\neq i}^{M} X_j^*$ exists on an interval around 0. As a result, the MGF of W = U + Z denoted as $M_W(t)$ exists in the range $|t| < t_0$ for a positive constant t_0 . As we show in Appendix C, when extended to the complex plane, the function $M_W(s) : \mathcal{D} \to \mathbb{C}$ is analytic on \mathcal{D} , where $\mathcal{D} = \{s \in \mathbb{C} : |\Re(s)| < t_0\}$. As a result, $M_W(s)$ has isolated zeros on \mathcal{D} . Since the characteristic function (CF) $\phi_W(t)$ of W is its MGF evaluated along the imaginary axis, i.e., $\phi_W(t) = M_W(jt), \phi_W(t)$ is analytic on the real line and has isolated zeros. Now, besides F'_{X_i} , assume that F''_{X_i} is another optimal distribution. It means both F'_{X_i} and F''_{X_i} maximize the output entropy $h(V; \cdot)$. Since the output entropy $h(\cdot)$ is strictly concave in $f_V(\cdot)$, we then have $f_V\left(v, F'_{X_i}\right) = f_V\left(v, F''_{X_i}\right)$. Therefore,

$$\phi_W(t)\left(\phi'_{X_i}(t) - \phi''_{X_i}(t)\right) = 0, \quad \forall t \in \mathbb{R},$$
(39)

where ϕ (.) denotes the CFs of the corresponding random variables. Because zeros of ϕ_W (.) are isolated, and a CF is uniformly continuous on the entire real line [53], it is clear that $\phi'_{X_i}(t) - \phi''_{X_i}(t) = 0, \forall t \in \mathbb{R}$. Therefore, $F'_{X_i} = F''_{X_i}$. Given the result in Lemma 3, a similar argument as in [40] can be used to addresses the characteristics of the optimal input distributions $\{F^*_{X_i}\}$. The result is stated in the following proposition.

Proposition 3: For any set of optimal distributions $\{F_{X_i}^{\star}\}$ in (37), $F_{X_i}^{\star} = F'_{X_i}$ where F'_{X_i} , $1 \le i \le M$, is the optimal input defined in (38). As a result, each $F_{X_i}^{\star}$ is discrete with a finite number of mass points.

Proof: The proof follows the method used in [40]. In particular, from Lemma 3, we know that F'_{X_i} is unique and discrete, having a finite number of mass points. Furthermore, it is clear from (38) that $F'_{X_i} = \arg \sup_{F_{X_i} \in \mathcal{F}_i} h(X_i + Z)$ U + Z). It then follows that $h\left(X'_i + \sum_{j=1, j \neq i}^M X_j^* + Z\right) \ge$ $h\left(\sum_{j=1}^M X_j^* + Z\right)$, where X'_i follows the distribution F'_{X_i} . On the other hand, since the set $\{F^*_{X_i}\}$ achieves the sumrate, we have from (37) that $h\left(X'_i + \sum_{j=1, j \neq i}^M X_j^* + Z\right) \le$ $h\left(\sum_{j=1}^M X_j^* + Z\right)$. Thus, $h\left(X'_i + \sum_{j=1, j \neq i}^M X_j^* + Z\right) =$ $h\left(\sum_{j=1}^M X_j^* + Z\right)$. Equivalently, $F^*_{X_i}$ is also optimal for the point-to-point channel. Therefore, $F^*_{X_i} = F'_{X_i}$, and each $F^*_{X_i}$ is discrete with a finite support set.

While the sum-capacity is one of the most important benchmarks, it is also of interest to understand the characteristics of the rate region of the considered MAC. By following a similar analysis as in [40], we can also show that for the considered MAC, there exist at least two distinct points achieving the sum capacity on the rate region. For completeness, the proof of this result is given in Appendix E. Finally, it is worth mentioning that we can use time-sharing arguments to show that there exists a linear segment between these two points in which any point belonging to the segment is also sum-capacity achieving. As a result, there exists an infinite number of sum-capacity achieving points.

Before closing this section, we should emphasize that it is certainly of great interest to obtain some numerical results to confirm the finiteness and discreteness of the optimal inputs for the case of multiple-access channels. Towards this end, an effective numerical method to accurately calculate the optimal mass points and their corresponding probabilities is required. The development of such a method is, however, non-trivial. It is because for the considered multiple-access channel, we need to deal with the optimization of multiple input distributions simultaneously. It should be noted that even for the single-user cases, there exist several drawbacks of the well-known gradient decent-based method we adopted earlier to find the optimal input [33], [36]. It is due to the relatively small sensitivity of the MI to the number of mass points as well as their locations and probabilities used in each iteration. As a consequence, it is difficult to find the optimal input consisting of more mass points, some of which having low probabilities, with high accuracy. Dealing with multiple inputs, and at the same time, paying attention to the convergence behavior of the solution are therefore more challenging. Given that, we believe the investigation on such new numerical methods is beyond the scope of the current work, and the topic deserves further studies.

V. CONCLUSION

This paper has proved the existence and discreteness of the capacity-achieving input signals for general class of pointto-point and multiple access channels with additive non-Gaussian noise under peak-power constraints. In particular, the considered non-Gaussian link consists of a Gaussian mixture noise having Gaussian elements with arbitrary means, and an arbitrary interference U having finite second order moment. The novelty of the work lies in the establishment of the necessary and sufficient condition for an input signal to be optimal and the use of Fubini-Tonelli's and Morera's theorems to show the analyticity of this condition. The continuity of the optimal input is then ruled out by proving that the optimal support set admits no limit point. Taking these into account, it is concluded that the capacity-achieving input is discrete with a finite number of mass points. We also exploited the arbitrary property of U to show that the optimal input distributions that achieve the sum-capacity of an *M*-user multiple access channel under GM noise are discrete. In addition, there exist at least two distinct points that achieve the sum capacity on the rate region. The point-to-point and multiple-user channels considered in this paper are general enough to represent all non-Gaussian additive channels of engineering interest.

APPENDIX A

TWO UPPER BOUNDS AND A LOWER BOUND ON $f_w(\cdot)$

In this section, upper and lower bounds on the distributions $f_W(\cdot)$, which are useful for the developments in Sections III-A and III-B, are derived. The bounds are given in the following two lemmas.

Lemma 4: The distribution $f_W(\cdot)$ can be upper-bounded by a constant d as $f_W(w) \le d$. Furthermore, there exist two positive constants k_0 and k_1 such that $f_W(w) \le k_1 w^{-2}$ when $|w| > k_0$.

Proof: Since
$$W = U + Z$$
, we have

$$f_W(w) = \int_{-\infty}^{\infty} f_Z(w - u) dF_U(u)$$

= $\sum_{n=1}^{N} \frac{\varepsilon_n}{\sqrt{2\pi\sigma_n^2}} \int_{-\infty}^{\infty} \exp\left(-\frac{(w - a_n - u)^2}{2\sigma_n^2}\right) dF_U(u)$
 $\leq \sum_{n=1}^{N} \frac{\varepsilon_n}{\sqrt{2\pi\sigma_n^2}} = d$ (40)

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Furthermore, as *Z* is a GM, it can be verified that there are positive constants α_0 , α_1 and α_2 such that $f_Z(z) \le \alpha_1 e^{-\alpha_2 |z|}$ for all $|z| > \alpha_0$. As a consequence, there exist finite constants $\alpha_3 > 0$ and $\alpha_4 \ge \alpha_0$ such that $f_Z(z) \le \frac{\alpha_3}{z^2}$ for all $|z| > \alpha_4$. Then when $w > 2\alpha_4$ we have:

$$f_{W}(w) = \int_{-\infty}^{w/2} f_{Z}(w-u) dF_{U}(u) + \int_{w/2}^{\infty} f_{Z}(w-u) dF_{U}(u)$$

$$\leq \int_{-\infty}^{w/2} \frac{\alpha_{3}}{(w-u)^{2}} dF_{U}(u) + c \Pr(U \ge w/2) \quad (41)$$

$$\leq \frac{\alpha_3}{(w-w/2)^2} + \frac{4cE\left[U^2\right]}{w^2}$$
 (42)

$$=\frac{4\left(\alpha_{3}+cE\left[U^{2}\right]\right)}{w^{2}}=T_{u}(w).$$
(43)

where (41) comes from the fact that the PDF of any GM random variable is upper bounded by any constant *c* that is great than *d*, and (42) follows from Markov's inequality. By using the same procedure, we can also obtain the same upper bound when $w < -2\alpha_4$. Therefore, by choosing $k_0 = 2\alpha_4$ and $k_1 = 4(\alpha_3 + cE[U^2])$, the lemma is proved.

Now, a lower bound on $f_W(\cdot)$ is stated in the following.

Lemma 5: The distribution $f_W(\cdot)$ can be lower bounded as

$$T_l(w) = \frac{e^{-c_1}}{e^{(aw^2 - 2b_1w)}} \le f_W(w)$$
(44)

for finite constants a, b_1, c_1 .

Proof: We know that the function $-\ln(x)$ is convex for $x \in (0, \infty)$. It then follows that:

$$-\ln (f_{W}(w))$$

$$= -\ln \left[\sum_{n=1}^{N} \varepsilon_{n} \int_{-\infty}^{\infty} \frac{\exp\left(-\frac{(w-a_{n}-u)^{2}}{2\sigma_{n}^{2}}\right)}{\sqrt{2\pi\sigma_{n}^{2}}} dF_{U}(u)\right]$$

$$\leq \sum_{n=1}^{N} \varepsilon_{n} \left(-\ln \left[\int_{-\infty}^{\infty} \frac{\exp\left(-\frac{(w-a_{n}-u)^{2}}{2\sigma_{n}^{2}}\right)}{\sqrt{2\pi\sigma_{n}^{2}}} dF_{U}(u)\right]\right) (45)$$

$$\leq \sum_{n=1}^{N} \varepsilon_{n} \int_{-\infty}^{\infty} -\ln \left[\frac{\exp\left(-\frac{(w-a_{n}-u)^{2}}{2\sigma_{n}^{2}}\right)}{\sqrt{2\pi\sigma_{n}^{2}}}\right] dF_{U}(u) \quad (46)$$

$$= \sum_{n=1}^{N} \frac{\varepsilon_{n}}{2\sigma_{n}^{2}} \int_{-\infty}^{\infty} \left[w^{2} - 2w(u+a_{n}) + (u+a_{n})^{2}\right] dF_{U}(u)$$

$$+\sum_{n=1}^{N}\varepsilon_{n}\ln\left(\sqrt{2\pi\sigma_{n}^{2}}\right)$$
(47)

$$\leq \sum_{n=1}^{N} \frac{\varepsilon_n}{2\sigma_n^2} \int_{-\infty}^{\infty} \left[w^2 - 2w \left(u + a_n \right) + 2 \left(u^2 + a_n^2 \right) \right] dF_U(u) + \sum_{n=1}^{N} \varepsilon_n \ln \left(\sqrt{2\pi \sigma_n^2} \right)$$
(48)

$$= aw^2 - 2b_1w + c_1$$
(49)

where

$$a = \sum_{n=1}^{N} \frac{\varepsilon_n}{2\sigma_n^2},\tag{50}$$

$$b_{1} = \sum_{n=1}^{N} \frac{\varepsilon_{n}}{2\sigma_{n}^{2}} (a_{n} + E[U]),$$
(51)

$$c_1 = \sum_{n=1}^{N} \varepsilon_n \ln\left(\sqrt{2\pi\sigma_n^2}\right) + \sum_{n=1}^{N} \frac{\varepsilon_n}{\sigma_n^2} \left(a_n^2 + E\left[U^2\right]\right).$$
(52)

Note that the inequality in (45) follows from the convexity of $-\ln(x)$, while we obtain (46) using Jensen inequality and (48) using the fact that $(\alpha + \beta)^2 \leq 2(\alpha^2 + \beta^2)$. It is clear to see that the above upper bound for $-\ln(f_W(w))$ is equivalent to the lower bound $f_W(w) \geq \frac{e^{-c_1}}{e^{(\alpha w^2 - 2b_1w)}}$.

It is worth mentioning that the two bounds in (43) and (44) do not satisfy the two conditions used in [30]. It is because $L(w) = \ln \left[\frac{1}{T_l(w)}\right]$ is not non-increasing for w < 0, and we also have $\int_{-\infty}^{\infty} T_u(w) \ln [T_l(w)] dw = -\infty$.

APPENDIX B BOUNDS ON $f_V(\cdot)$

Lemma 6: *The distribution* $f_V(\cdot)$ *for a given input distribution* F_X *can be bounded as*

$$\frac{e^{-c_2}}{e^{(av^2 - 2b_2v)}} \le f_V(v; F_X) \le d$$
(53)

for finite constants a, b_2, c_2 and d.

Proof: The upper bound on $f_V(\cdot)$ comes directly from that of $f_W(\cdot)$, which is:

$$f_V(v; F_X) = \int_{-\infty}^{\infty} f_W(v - x) dF_X(x)$$

$$\leq \sum_{n=1}^N \frac{\varepsilon_n}{\sqrt{2\pi\sigma_n^2}} = d$$
(54)

For the lower bound, we have:

$$-\ln (f_V(v; F_X))$$

$$= -\ln \left[\int_{-\infty}^{\infty} f_W(v - x) dF_X(x) \right]$$

$$\leq \int_{-\infty}^{\infty} -\ln [f_W(v - x)] dF_X(x)$$
(55)
$$\leq \int_{-\infty}^{\infty} \left[a (v - x)^2 - 2b_1 (v - x) + c_1 \right] dF_X(x)$$
(56)

$$\leq \int_{-\infty} \left[a \left(v - x \right)^2 - 2b_1 \left(v - x \right) + c_1 \right] dF_X(x)$$
(56)
= $av^2 - 2b_2v + c_2$, (57)

where

$$b_2 = b_1 + aE[X], (58)$$

$$c_2 = c_1 + aE\left[X^2\right] + 2b_1E[X].$$
 (59)

Note that for the above, we apply Jensen inequality in (55). In addition, (56) comes from the upper bound on

 $-\ln (f_W(w))$. The lower bound on $f_V(v; F_X)$ therefore follows directly from the upper bound on $-\ln (f_V(v; F_X))$ in (57).

APPENDIX C

ANALYTICITY OF $M_W(s)$

Because $M_W(t)$ is finite for all $|t| < t_0$, we have

$$|M_W(s)| \le \int_{-\infty}^{\infty} |e^{sw}| dF_W(w) = \int_{-\infty}^{\infty} e^{\Re(s)w} dF_W(w)$$

< ∞ , (60)

for any $s \in \mathcal{D}$. Therefore, $M_W(s)$ exists on \mathcal{D} . Let $\{s_n\}_{n\in\mathbb{N}}$, be a sequence in \mathcal{D} such that $\lim_{n\to\infty} s_n = s_*$ for $s_* \in \mathcal{D}$. Then there exists a constant b > 0 such that $|\Re(s_n)| \le b < t_0$ for any $n \in \mathbb{N}$. As such, for any $w \in \mathbb{R}$, we have $|e^{s_n w}| = e^{\Re(s_n)w} \le e^{bw}$. Moreover, $\int_{\mathbb{R}} e^{bw} dF_W(w) < \infty$ since $b < t_0$ and $\int_{\mathbb{R}} e^{tw} dF_W(w) < \infty$ for all $|t| < t_0$. So by applying Dominated Convergence Theorem, we have $\lim_{n\to\infty} M_W(s_n) = M_W(s_*)$. Equivalently, $M_W(s)$ is continuous on \mathcal{D} . Furthermore, because of the analyticity of e^{sw} , we can apply the same procedure as in the proof of Lemma 1 using Fubini-Tonelli, Cauchy's Integral, and Morera's theorems to show the analyticity of $M_W(s)$.

APPENDIX D

DIRECTIONAL DERIVATIVE AND LAGRANGIAN THEOREM

This appendix provides some well-known concepts, which are helpful for the establishment of the KTC.

Definition 1: Let $f : \mathcal{V} \to \mathbb{R}$ be a function on a normed linear space \mathcal{V} . The directional derivative of f at $a \in \mathcal{V}$ along a direction $d \in \mathcal{V}$ is defied by

$$D_a(f; d) = \lim_{t \to 0} \frac{1}{t} (f(a + td) - f(a)),$$

if this limit exists.

Lemma 7: Let $f : \mathcal{A} \to \mathbb{R}$ be a concave function where \mathcal{A} is a convex set. For any $a \in int(\mathcal{A})$ and for any $a' \in \mathcal{A}$, the directional derivative of f along a' - a

$$D_a(f; a' - a) = \lim_{t \to 0} \frac{1}{t} (f((1 - t)a + ta') - f(a))$$

exists and is finite. Moreover, a is a point of global maximum for f if and only if $D_a(f; a' - a) \leq 0$ for any $a' \in A$.

Proof: The proof is given in [54].

Theorem 3 (Optimization Theorem): Let Ω be a compact and convex metric space, and f a continuous, weakly differentiable and convex-cap functionals on Ω to \mathbb{R} . Define:

$$C = \sup_{x \in \Omega} f(x).$$

Then

- 1) $C = \max_{x \in \Omega} f(x)$; i.e., f(x) achieves its maximum on Ω .
- 2) The necessary and sufficient condition for $f(x_0) = C$ is $D_{x_0}(f; x x_0) \le 0$ for all $x \in \Omega$.
- 3) If f is strictly convex-cap, C is achieved by a unique x_0 in Ω .

Proof: See [47], [55].

APPENDIX E THE PROOF OF TWO DISTINCT POINTS ACHIEVING THE SUM CAPACITY

Let $\{F_{X_i}^{\star}\}$ be a given set of sum-capacity-achieving distributions. If there exists only a single point S in the rate region that achieves the sum capacity, it is clear that

$$C_{\rm sum} = \sum_{i=1}^{M} I\left(F_{X_i}^{\star} \mid \left\{X_j^{\star}\right\}_{j=1, j \neq i}^{M}\right).$$
(61)

On the other hand, based on the chain rule of MI, we have

$$C_{\text{sum}} = I\left(\{F_{X_j}^{\star}\}_{j=1}^{M}\right) = \sum_{i=1}^{M} I\left(F_{X_i}^{\star} \mid \left\{X_j^{\star}\right\}_{j=1}^{i-1}\right).$$
 (62)

Let Q and Q' denote the sets $\{X_j^{\star}\}_{j=i+1}^M$ and $\{X_j^{\star}\}_{j=1}^{i-1}$, respectively and \mathcal{X} represent the support set of Q. Since $\{F_{X_i}^{\star}\}$ are finite and discrete, \mathcal{X} has finite number of elements. It then follows that:

$$I\left(F_{X_{i}}^{\star} \mid \left\{X_{j}^{\star}\right\}_{j=1, j\neq i}^{M}\right)$$

$$= \sum_{q \in \mathcal{X}} \Pr\left(\mathcal{Q} = q\right) I\left(F_{X_{i}}^{\star} \mid \mathcal{Q} = q, \mathcal{Q}'\right)$$

$$= \sum_{q \in \mathcal{X}} \Pr\left(\mathcal{Q} = q\right)$$

$$\times D\left(f_{X_{i}^{\star}, Y^{\star} \mid \mathcal{Q}, \mathcal{Q}'}\left(., . \mid q, .\right) \parallel f_{X_{i}^{\star}}\left(.\right) f_{Y^{\star} \mid \mathcal{Q}, \mathcal{Q}'}\left(. \mid q, .\right)\right)$$

$$\geq D\left(\sum_{q \in \mathcal{X}} \Pr\left(\mathcal{Q} = q\right) f_{X_{i}^{\star}, Y^{\star} \mid \mathcal{Q}, \mathcal{Q}'}\left(., . \mid q, .\right)$$

$$\parallel \sum_{q \in \mathcal{X}} \Pr\left(\mathcal{Q} = q\right) f_{X_{i}^{\star}}\left(.\right) f_{Y^{\star} \mid \mathcal{Q}, \mathcal{Q}'}\left(. \mid q, .\right)$$

$$\parallel \sum_{q \in \mathcal{X}} \Pr\left(\mathcal{Q} = q\right) f_{X_{i}^{\star}}\left(.\right) f_{Y^{\star} \mid \mathcal{Q}, \mathcal{Q}'}\left(. \mid q, .\right)$$

$$= I\left(F_{X_{i}}^{\star} \mid \mathcal{Q}'\right) = I\left(F_{X_{i}}^{\star} \mid \left\{X_{j}^{\star}\right\}_{j=1}^{i-1}\right).$$
(63)

where D(.) is the relative entropy between two distributions, $Y^{\star} = \sum_{i=1}^{M} X_i^{\star} + Z$ and the inequality comes from the log-sum inequality. It can be verified that the equality in (63) can only be achieved if and only if $f_{Y^{\star}|X_i^{\star}, Q, Q'}(. | ., ., .) = f_{Y^{\star}|Q, Q'}(. | ., .)$, which is equivalent to $E[Y^{\star} | X_i^{\star} = x, Q, Q'] = E[Y^{\star} | Q, Q']$ for any mass point *x* in the support set of X_i^{\star} . Therefore, the equality in (63) only happens if $E[X_i^{\star}] = x$ for any mass point *x* in the support set of X_i^{\star} , or equivalently, X_i^{\star} has only a single mass point, which is not possible. As a result, $I(\{F_{X_i}^{\star}\}_{j=1}^M) <$ $\sum_{i=1}^{M} I(F_{X_i}^{\star} | \{X_j^{\star}\}_{j=1, j \neq i}^M)$, which contradicts with (61).

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