

Received 1 February 2024, accepted 15 March 2024, date of publication 25 March 2024, date of current version 4 April 2024. *Digital Object Identifier 10.1109/ACCESS.2024.3381621*

RESEARCH ARTICLE

Real Time Intelligent Detection of PQ Disturbances With Variational Mode Energy Features and Hybrid Optimized Light GBM Classifier

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The work of Mohammed S. Al-Numay and Pierluigi Siano was supported by the Researchers Supporting Project, King Saud University, Riyadh, Saudi Arabia, under Grant RSP2023R150.

ABSTRACT The modern era power system is constantly undergoing constructive changes and implementations both in source and load side. Certainly, the distributed generators, unconventional/nonlinear loads, charging stations etc are mostly integrated through power electronics interfaces. As a result, frequent power quality disturbances appear in the system that is to be mitigated at the earliest. Since detection is the prerequisite for mitigation, therefore the article presents a novel intelligent power quality detection scheme to detect and classify the PQ Events. At first, the energy feature of the 5 band limited modes are calculated from variational mode decomposed voltage signals. Then the mode energy features are utilized to train a novel Hybrid Arithmetic Whale Optimized light gradient boosting machine classifier. A total of 15 different PQ events have been investigated and exceptional classification results have obtained with optimum computational complexity, both under noiseless and noisy conditions. Moreover, the accuracy of the proposed PQ classification schemes found to be towering against other related pre-published works. Finally, the ability of the proposed detection scheme is validated in real time though OPAL-RT 4510 and grid simulator hardware in loop setup.

INDEX TERMS Power quality, variational mode decomposition, whale optimization, arithmetic optimization, light gradient boosting machine.

I. INTRODUCTION

The idiom Power Quality simply means the power signal should preserve its sinusoidal characteristics at rated amplitude and frequency [\[1\]](#page-15-0) and any deviation from these will be treated as Power Quality Disturbance (PQD). The evergrowing energy demand and awareness of green energy have shifted the focus towards distributed generation (DG). These

The associate editor coordinating the review of this manuscript and approving it for publication was Arturo Cond[e](https://orcid.org/0000-0002-5941-3323)

DGs are basically renewable energy source (RES) oriented generation systems. But the power electronics interfacing and the intermittent nature of the RES such as solar, wind have certainly increased the rate of recurrence of PQDs to a higher extend [\[2\]. Al](#page-15-1)ong with that, the usability of power electronics in several network equipment's at the grid side as well as in different devices at the industries and end user increased drastically [\[3\]. A](#page-15-2)s a result, numerous types of PQDs are frequently occurring in the power networks such as sag, swell, interruption, flicker, notches transients etc and even a mix of

few of these. Since, the primary goal of the electricity market participants such as producer, trader and distributer are to deliver power of highest quality. Therefore, it is necessary to continuously monitor the power system and identify the PQDs to take necessary measures at the earliest.

The field of PQD identification have started from the thresholding-based techniques and eventually grown up to intelligent detection techniques (IDTs) [\[4\]. B](#page-15-3)asically, these IDTs involve two fundamental steps, data processing and development of machine learning (ML) model. In the data processing phase, the hidden features of the power signal are retrieved through some signal processing tool then fed to the second phase to build the ML model. Several signal processing techniques have proposed in literature to address the voltage and current signals having their own uniqueness and limitations [\[5\]. S](#page-15-4)ince PQ signals possess lot of irregularity in terms of amplitude and frequency and often noise contaminated, it is necessary to implement such a signal processor that can act on non-stationary, non-linear and noise prone signals. In this context, mode decomposition techniques like, empirical made decomposition (EMD) [\[6\],](#page-15-5) ensemble EMD (EEMD) [\[7\], do](#page-15-6)wn-sampling EMD (DEMD) [\[8\]](#page-15-7) are much more useful. But these methods are suffering two major drawbacks such as mode mixing and end effect when the signal nature is very complex. To eradicate the effect of these two limitations Variational mode decomposition (VMD) was introduced $[9]$ [wh](#page-15-8)ich also facilitate low computational complexity while ensuring non-ambiguous outcome of decomposition. In addition to that, VMD has already proven its effectiveness in several PQ studies [\[10\],](#page-15-9) [\[11\],](#page-15-10) [\[12\],](#page-15-11) [\[13\],](#page-15-12) hence elected as the signal processing tool in this study.

Now, to perform the second step of IDT, it is required to select a ML classifier (MLC) that can well identify the PQ disturbances with utmost accuracy. There are a number of studies reported in literature for detecting PQD through MLCs such as artificial neural network (ANN), decision tree (DT), support vector machine (SVM), extreme learning machine (ELM), kth-Nearest neighbour (KNN) and several variants of these [\[4\],](#page-15-3) [\[5\]. H](#page-15-4)owever, these standalone MLCs are generally search through a number of possible hypotheses to find out the best approximation to the targets. Therefore, they suffer from three major problems those are statistical, computational and representational problems. Since, PQD identification is such a sensitive matter that may lead to catastrophic cascading effect and eventually might end up scenarios like blackout, it should be sincerely addressed with optimum possibility of detection failure. In this regard ensemble MLCs can bring more generalization with uplifted predictability as it combines the prediction of a number of learners [\[14\]. B](#page-15-13)oosting and bagging are two popular ensemble learning methods. Bagging specifically minimize the variance in the dataset by bootstrapping. A number of bagging techniques have already used for PQD assessment random forest [\[15\],](#page-15-14) subspace KNN [\[16\]](#page-15-15) voting-staking based classifier [\[17\]](#page-15-16) etc. But the key advantage of boosting algorithms over bagging is their ability to produce models

with higher accuracy [\[18\]. M](#page-15-17)oreover, boosting is designed to iteratively improve model performance by focusing on samples that were previously misclassified. This allows boosting to correct errors introduced by previous weak models and ultimately lead to a more accurate final model. A number of boosting methods are found in literature for PQD determination such as adaboost [\[19\],](#page-15-18) gradient boost $[20]$, XGBoost $[21]$, but it is still in its initial stage of implementation. Another advantage of boosting is its ability to handle imbalanced datasets better than bagging. But the limitation boosting-techniques possess are comparatively slower training process, sensitivity to outliers and difficult to implement in large sized dataset due to sequential building of model. To retain the benefits of boosting and eliminate its drawbacks Light Gradient Boosting Machine (LGBM) has introduced [\[22\],](#page-15-21) [\[23\]. L](#page-15-22)GBM is memory efficient, facilitates parallel training, provides speed & accuracy and capable of acting on large dataset. Hence, in this work LGBM is chosen as the MLC. However, LGBM has a number of parameters that can be tuned to enhance its classification ability. Therefore, the study has proposed a novel optimization algorithm hybridizing whale optimization [\[24\]](#page-15-23) and arithmetic optimization [\[25\]](#page-15-24) to tune the parameters of LGBM.

Taking into account the unmatched advantages of VMD and LGBM, this paper proposes an intelligent PQD detection scheme having utmost accuracy and minimal computational burden. The contributions of the manuscript are highlighted as follows,

- ✓ Fourteen different Types of Power Quality Disturbance signal assessment is performed in MATLAB Simulink environment. The energy of all the Band Limited Modes (BLMs) obtained from VMD are considered as features for LGBM classifier and thus completely irradicate the worry of selecting most informative BLM as well as identifying different statistical features.
- ✓ Maidan application of proposed Hybrid Arithmetic Whale Optimization Algorithm (AWOA) to optimize the hyper parameters of LGBM so as to bolster its prediction efficiency.
- ✓ The proposed VMD & Hybrid Optimized Light GBM (HOLGBM) based Power Quality Detection Model is validated with different noise contaminated signal to test its effectiveness in real grid conditions and also analysis of comparison is made with related prepublished articles.
- ✓ Real-Time Validation of the HOLGBM PQD detection scheme with OPAL-RT 4510 and grid simulator hardware in loop (HIL) setup is carried out to obtain the detection time which itself a novel attempt in power quality monitoring study.

Further, the paper organization is as follows. The current section covers brief introduction of the research work. Section[-II](#page-2-0) describes the Theoretical aspects of the study. The Section[-III](#page-2-1) is all about the PO disturbances is to be detected with their mathematical modelling. In section[-IV](#page-2-2) the step wise mythology is discussed along with the proposed

detection scheme. The section[-V](#page-8-0) covers the analysis and discussion part of the obtained result. The research work is concluded in the last section.

II. POWER QUALITY EVENTS

In this study a total of 15 different types of PQ events including a healthy signal are taken in to account for analysis. There are 8 single, 4 double and 2 triple PQ disturbances as presented in Table[-1.](#page-3-0) The single events are healthy sinusoidal signal, sag, swell, interruption, flicker, harmonics, notches, oscillatory and impulse transient. The double PQ signals includes independent association of harmonics and oscillatory transient signals along with sag and swell signals receptivity. Further, the triple PQ signals includes the association of both harmonics and oscillatory transient signals independently with sag and swell signals receptivity. The study assumes the reference voltage to be 1p.u. and frequency to be 50 Hz. Therefore, it is required to convert the disturbance signals to per unit before proceeding for any analysis. All the signals are sampled at 10kHz. An integer PQ Index (PQI) of the signals are also mentioned along with their names, which will be useful during real time detection study. Since the work makes use of variational mode decomposition of the signals, Table[-1](#page-3-0) displays the mathematical modelling along with VMD of all the respective signals. It can be seen that each signal is decomposed to 5 different modes and each mode is placed on the z-axis and the respective mode number is also mentioned.

III. LIGHT GRADIENT BOOSTING MACHINE

Gradient Boosting Machine is an ensemble iterative machine learning algorithm that makes the prediction by aggregating the prediction of a group of weak learners. These learners, often called estimators are generally decision trees. The prime concept of the algorithm is the sequential building of learners, where the current learner is attempting to reduce the error of the previous one. The objective is to optimizing the loss function using gradient descent. GBM can act as both regressor and classifier with different kind of loss function. Generally, the mean square error for regression and loglikelihood for classification in adapted as loss function. Since the concept of the manuscript is demanding classification task, hence here the focus is only limited to classification problem. GBM tries to optimize the loss function $L(t_k, p)$ by finding a prediction value $'p'$ such that the loss function will be minimum. It can be denoted as,

$$
f_L = \underbrace{argmin}_p \sum_{k=1}^O L(t_k, p) \tag{1}
$$

The loss function for classification can de defines as,

$$
L(t_k, p) = -\left[\sum_{k=1}^{O} t_k \log (p) + (1-p)\log(1-p)\right] (2)
$$

where, t_k is the Target value kth observation of the Training Dataset, *k*= 1, 2, 3*O*

Next the pseudo residual is evaluated, and the 1st tree is built while taking the residues as the targets. Then the output from the 1st tree is calculated, based on which the next trees are constructed sequentially.

Despite the performance excellence, the efficacy of GBM is affected under big data and high dimensionality of feature set $[26]$. It is because, the various data points should be scanned to determine an estimate of all feasible tree splits which is time intensive in nature. Therefore, GBM is not scalable for large feature set. To deal with this particular issue Light GBM is introduced. The term ''light'' signifies the reduction of data and feature dimensionality. First of all, LGBM excludes a considerable part of data with small gradient and keep remaining to evaluate information gain. This is called Gradient based One Sided Sampling (GOSS). Secondly, it only keeps the mutually exclusive features and discard others in a way that is not going to affect the overall accuracy of the predictor. This is called Exclusive Feature Bundle (EFB). These two implementations speed up the training process up to 20 times.

IV. METHODOLOGY

The prime goal of the study is the intelligent identification of PQDs with minimum time and maximum accuracy. In order to achieve this, a three-stage process is followed in this work as shown in Fig[.1.](#page-7-0) These stages are discussed in the succeeding subsections.

A. DATA COLLECTION

Since the work is focusing on data driven solution, a proper data collection process is essential at first. It involves three steps as follows,

1) DATA ACQUISITION

In this stage the voltage signal is sensed from the grid continuously with a sampling frequency of 10 kHz (200 samples/cycle). Since the voltage signals have a periodic characterizes, a 5-cycle snapshot is kept on taking from the continues live data and stacked to data buffer for further data processing. The buffer is having an overlap of 4 cycles, which means every new set of data is collected after a shift of 200 samples from the previous set. It can be clearly seen in the Stage-1 of Fig[.1.](#page-7-0)

2) DATA PROCESSING

The 5-cycle data is further fed to a signal processing stage, to bring edge to the detection process. The signal processing tool (SPT) split the base signal to number of sub signals thereby exposing the disturbance event to be prominent enough. Here the SPT is chosen as VMD due to its advantage of reducing end effect and mode mixing. Most of the studies in this regard trying to select a the most informative sub signal called BLM for feature extraction. But selecting the proper BLM can be another overhead to be solved [\[27\],](#page-15-26) [\[28\].](#page-15-27) Hence in this proposed work the feature extraction is done in a completely different way as discussed in next subsection.

TABLE 1. PQDs with mathematical modelling and variational mode decomposition.

TABLE 1. (Continued.) PQDs with mathematical modelling and variational mode decomposition.

$\left[1 + \rho * \begin{pmatrix} u(t - t_1) \\ -u(t - t_2) \end{pmatrix}\right] * [h_1 * sin(\omega t) + h_3 *$ VMD-SWELL+HARMONICS+OT $sin(3\omega t) + h_5 * sin(5\omega t) + h_7 * sin(7\omega t)$ + Swell+ $\beta * sin(\omega_n t) * e^{\frac{-t}{ty}} * \left(\frac{u(t-t_3)}{u(t-t_4)}\right)$ where, 0.1 \leq Harmonics+ Oscillatory $\rho~\leq 0.8$ **Transient** $0.05 \le h_{3,5,7} \le 0.15$, $\sum (h_i)^2 = 1$
 $0.8 \le \beta \le 1, 2\pi 300 \le \omega_n \le 2\pi 500$, (14) 0.05 0.1 0.15 0.2 0.25 0.3

TABLE 1. (Continued.) PQDs with mathematical modelling and variational mode decomposition.

3) DATA PREPARATION

The data preparation stage facilitates the extraction of inherent features. These features will be going to act as predictor variables for the machine learning classifier. But it is highly important to make sure the machine learning model should be ready before passing new feature data for prediction. In order to achieve this, a sum total of 30000 synthetic signal data (rows) each of 5 cycles at a sampling frequency of 10khz i.e., 1000 datapoints (columns) are stored to the database initially (30000∗1000 data table dimension). That means 2000 signals from each class considering both noise free and noisy signals are stored in the disturbance database initially. Then the pre stored disturbance data will go through the data processing stage to obtain the BLMs. Next the energy magnitude of all 5 BLMs are considered as features for the MLC. Further the collected feature set is divided in to two parts as Training Data and Testing Data, where 70% is dedicated to training and rest 30% is dedicated to testing.

B. OPTIMIZATION

LGBM is consisting of decision trees, where each tree takes in different subset of features to provide best split. Undoubtedly LGBM has some inherent advantages like parallel learning, speeded up training, least memory utilization and compatibility to handle both small $\&$ large dataset [\[22\]. B](#page-15-21)ut its performance can be further improvised by optimizing its hyper parameters. There are a number of hyper parameters of LGBM, but the major parameters are being optimized to reach best possible accuracy. Those parameters are estimator count (EC), learning rate (LR), bagging fraction (BAGF), maximum tree depth (MTD), number of leaves (NL) and lambda (L). The NL param is crucial to control the complexity of the model and LR help in weight management in boosting step. The TD and L parameters are optimized to avoid overfitting.

The objective is to identify the optimum set of hyperparameters $HP_{opt} = \{EC^*, LR^*, BAGF^*, MTD^*, NL^*, L^*\}$ such that the cost function is minimized. For that it is required to define the necessary prerequisites.

First, the dataset with 'n' feature-target set is defined as,

$$
DS = [(F_1, T_1); (F_2, T_2); --- ; (F_n, T_n)] \tag{3}
$$

where $F_i = \{e_i^{IMF1}, e_i^{IMF2}, e_i^{IMF3}, e_i^{IMF4}, e_i^{IMF5}\}$ is the energy feature vector of all 5 IMFs and T_i is the Target PQD class Index $\in (0, 8)$.

Here the energy feature of an IMF can be calculated by,

$$
e^{IMF} = \sum_{m=1}^{d} (s_m)^2
$$
 (4)

where s_m is the mth sample of the IMF having length d .

Second, the population (POP) with p candidates is defined as,

$$
POP = [HP_1; HP_2; ---; HP_p] \tag{5}
$$

where $HP_i = \{EC^i, LR^i, BAGF^i, MTD^i, NL^i, L^i\}$ is a set of hyper parameters bearing values in their respective lower and upper range as shown in Table[-2.](#page-6-0)

Third, the cost function of the optimization problem is as follows,

$$
HP_{opt} = argmin_{HP \in POP} \left\langle \sum_{i=1}^{n} \varphi \left(\check{T}_i, T_i \right) \right\rangle \tag{6}
$$

where $\check{T}_i = LGBM(HP_i, F_j)$ is the predicted PQD class index and φ denotes the loss function considered as the objective of the optimization problem.

Fourth is the proposed optimization itself, that combines two different meta-heuristic algorithms. These are Arithmetic Optimization Algorithm (AOA) and Whale Optimization Algorithm (WOA). AOA is a non-gradient based algorithm. It has four main steps: initialization, arithmetic operation, update, and termination. In each iteration, AOA randomly selects two agents and performs one of the four arithmetic operations on them to generate a new agent. Then, the new agent is compared with the worst agent in the population and replaces it if it is better. In contrast, WOA is gradient based. It has three main steps: initialization, encircling prey, and bubble-net attacking.

In each iteration, WOA updates the position of each agent according to a mathematical model that simulates the movement of whales towards the best agent (the prey).

The study proposes a Hybrid Optimization approach where AOA will perform exploration task due to its highly scattering dynamic movement through multiplication and division operation. On the other hand, WOA will involve in exploitation due to its shrinking encircling mechanism to escape from local optima.

The proposed hybrid arithmetic whale optimization algorithm (AWOA) is as follows,

Initialize, POP, **UB**, **LB**, **ITR**_{*max}*,*MOA*_{*max}*,*MOA*_{*min*}, *b*, $\mu = 0.5$, $\alpha = 5$, $\varepsilon = 0.000001$ </sub></sub> **Evaluation of fitness of the candidates Identify the best Search Agent***HPbest* $for1$ $C_{ITR} = 1$: ITR_{max} *for2* **each** *HP* **as** *k* **in POP** $\text{Evaluate, } MOA \text{ } (\text{C}_{ITR}) = MOA_{max} + \text{C}_{ITR} * \frac{MOA_{max} - MOA_{min}}{ITR_{max}}$ *Take,* $r_1 = rand(0, 1)$ *If1* r_1 > *MOA* (*C_{ITR}*) *Take,* $r_2 = rand(0, 1)$ *for3* **each variable** *j* **in** *HP* $p_{k,j} =$ $\sqrt{ }$ $\Big\}$ $\overline{\mathcal{L}}$ HP_{best}^j \div (MOP + ϵ) \times $\left[\left(UB_j{-}LB_j\right) \times \mu$ $+LB_j\right]$, r_2 < 0.5 $HP_{best}^j \times \left(\textit{MOP} \right) \times \left[\left(\textit{UB}_j{-} \textit{LB}_j \right) \times \mu + \textit{LB}_j \right], otherwise$ $where \; MOP = 1 - \left(\frac{C_{ITR}}{ITR_{max}}\right)^{1/2}$ *endfor3 else1 Take,* $r_3 = rand(0, 1)$ *for3* **each variable** *j* **in** *HP If2 r***3**< **0**.**5** *Take,* $r_{j1} = rand(0, 1), r_{j2} = rand(0, 1)$ **Evaluate,** $A_j = 2.a. r_{j1} - a$ and $C_j = 2.r_{j2}$ **where** *a* **linearly decreased from 1 to 0** Evaluate, $M_j = |C_j * HP_{best} - p|$ $p_{k,j} = p - A_j * M_j$ *else2* $Take, r_4 = rand(-1, 1)$ $\text{Evaluate, } M_j = \left| HP^j_{best} - p \right|$
 $p_{k,j} = HP^j_{best} + M_j * e^{br_4} * \cos(2\pi r_4)$ *endif2 endfor3 endif1 endfor2* **Check if any candidate exceeds the search space, then bound it Revaluate of fitness of the candidates Update** *HPbest* **if better solution found** *endfor1*

TABLE 2. PQDs with mathematical modelling and variational mode decomposition.

C. CLASSIFICATION

In stage-3, initially the training procedure is carried out with the optimized hyper parameters of LGBM obtained in stage-2. Here the required training data (feature-target data matrix) is retrieved from stage-1. The training process is performed with a 10-fold cross validation and as a result, the proposed HOLGBM based Power Quality Detection Model (PQDM) is obtained. The very first time the trained model will undergo testing process where the 30% feature data reserved for testing is getting utilized to test its detection accuracy. Then after the proposed PQDM can be utilized for real time detection of power quality events. The real time detection part is marked as GREEN arrow in work flow diagram Fig[.1.](#page-7-0) The steps for real time detection are as follows,

- \checkmark The live voltage signal is being constantly sensed and buffered in a batch of 1000 data samples at a sampling frequency of 10khz.
- ✓ Subsequent VMD implementation is made on the collected data samples to obtain 5 BLIMFs.
- \checkmark The Energy of all BLIMFs are computed to form the feature vector of 1×5 .

	NO NOISE	40dB	30dB	20dB
Interruption (PQI0)				
Sag (PQI1)				MMMMMM
Healthy (PQI2)				www.
Swell (PQI3)				<i>MMMM</i>
Flicker (PQI4)				ww
Harmonics (PQI5)	UUUUUUUUUUUUUUU		<i>AAAAAAAAAA</i>	VVVVVVVVVVVVV
Notches (PQI6)				
Oscillatory Transient (PQI7)				VVV
Impulse Transient (PQI8)	MMMMMMMMM	VAAAAAAAAA		wwwwww
Sag+ Harmonics (PQI9)	Maammunnin	Mannovanna	Maaanninnin	munnmm
Swell+ Harmonics (PQI10)	maaannmmm			Mmmm M
Sag+ Oscillatory Transient (PQI11)				WWWWWW
Swell + Oscillatory Transient (PQI12)			MMMMM	mmmmmm
Sag+ Harmonics+ Oscillatory Transient (PQI13)		Maarannnnn	Maarannnnn	Maanmmm
Swell+ Harmonics+ Oscillatory Transient (PQI14)	mannamm	maannnnnnn	MAAAMMMM	manann

FIGURE 2. Chosen Power Quality Indices (PQIs) and their corresponding wave shapes of all PQ events.

- \checkmark The feature vectors are sequentially presented to the proposed VMD and HOLGBM based PQDM for event classification.
- If disturbance is detected the necessary action is to be taken by the protection system else the loop keeps on continuing.

V. RESULT ANALYSIS & PERFORMANCE EVALUATION

To assess the efficacy of the proposed approach, 14 variations of PQ disturbance signals along with a healthy signal is examined. To create a comprehensive evaluation, 4 different variant datasets are generated namely DS1, DS2, DS3 and DS4 where DS1&2 for single PQ events (PQI0 to PQI8) and DS3&4 for all PQ events (PQI0 to PQI14). DS1 and DS3 is having 500 synthetic samples for each disturbance category with dimension 4500×5 and 7500×5 respectively. While DS2 and DS4 contain 3 subsets of samples possessing signalto-noise ratios (SNRs) of 20dB, 30dB and 40dB respectively with each dB level having 500 feature sets. That means DS2 and DS4 having dimension 13500×5 and 22500×5 respectivly. A glimpse of all events will every noise level can be seen in Fig[.2.](#page-8-1) It is to be noted that, PQI denotes the respective Power Quality Index as per Table[-1.](#page-3-0) These samples were randomly generated and shuffled. For performance evaluation out of the whole data 70% allocated for training purposes and the remainder for testing with class wise random selection. The modelling stage is executed using MATLAB 18a on a desktop computer equipped with an Intel 2.30 GHz i5-8300 CPU and 8GB RAM.

A. NOISE-FREE PERFORMANCE

Here the DS1 and DS3 datasets are taken into account with 350 samples from each class is dedicated to training and 150 is for testing. Since the performance of a classifier can be well defined through a confusion matrix, therefore

the training and testing confusion matrices of the proposed classifier is presented in Fig[.3\(a\)](#page-9-0) to (d) . It is seen that all events are completely detected from the training set with 100% accuracy for both datasets. On the other hand, from the testing set one each from swell, flicker and harmonics are misclassified as interruption, harmonics and flicker respectively in DS1. That means 1347 PQDs truly detected out of 1350 testing event with an accuracy of 99.77%. Similar outcomes can be observed with DS3 test-sets with minimal misclassification and accuracy of 99.56%. It is seen that; few misclassifications are observed between sag + harmonics $\&$ $sag + harmonics + oscillatory transients as well as swell$ + harmonics & swell + harmonics + oscillatory transients successively.

B. NOISE-IN PERFORMANCE

Since the power lines in real world often experience electromagnetic interference with communication lines, the measured parameters like voltage or current are usually contaminated with noise. That means it is really necessary to demonstration the performance of the detection scheme under noisy circumstances. In this regard, the DS2 and DS4 datasets are utilized to verify the same where the random sampling of all the three SNR levels are carried out to simulate a varying noise condition then divided in to training and testing in 70:30 ratio. It seems that, accuracy of 98.29% and 96.44% are observed with training and testing for DS2 with only one type of PQ disturbances. The respective confusion matrices are shown in Fig.4(a) $\&(b)$. While dealing with complex PQ disturbance dataset, similarities can be observed between many events. Certainly, the training confusion matrix shown in Fig[.4\(c\)](#page-10-0) is showing accuracy of 98.44% whereas the testing confusion matrix Fig. $4(d)$ is displaying accuracy of 96.77%. This indicates, the performance of the proposed VMD and

PREDICTED CLASS (d) Testing DS3

CLASS

TRUE

FIGURE 4. Confusion matrix of noise contained dataset DS2 and DS4.

FIGURE 5. Individual accuracy bar diagram of all disturbance events with 3 SNR levels.

HOLGBM classifier is neither compromised while detecting complex PQ disturbances nor in case of noise.

Further, the individual accuracy of each PQD class with 3 different noise levels are presented in the bar chart as shown in Fig[.4.](#page-10-0) It is to be noted that this accuracy is calculated on overall data of individual class and not on separately for training and testing data. It is observed that, the maximum accuracy is found to be of impulse transient (PQI8) under 40dB noise whereas minimum accuracy is of 94.26% is found for interruption event (PQI0) at 20dB noise level.

C. REAL TIME VALIDATION

The study carried out a real-time Hardware in Loop simulation to address two crucial aspects. The first one is the performance of the proposed PQDM trained with synthetic $+$ noise contained dataset, against unseen disturbance retrieved from a system that replicating the behaviour of actual grid. The second one is the determination of an average detection time of the classifier. To achieve the same the proposed PQDM is validated through OPAL RT simulator by intentionally creating few of the disturbances in Grid Simulator (GS). Here GS will resemble as a practical grid system, therefore is utilized to apprehend few of the disturbances such as sag, swell and interruption. Moreover, the GS is internally consisting of a front-end converter (FEC) and a load side converter (LSC), where the PWM signal of the LSC is modified to generate the specific disturbances. This PWM is generated at a switching frequency of 5kHz in the host computer and fed to the GS through digital out (D-OUT) of OP5410 by running the real time simulation. Then the measurement points of GS are connected to OP8662 VI sensor and the measurements are fed back to OP4510 through its analog in (A-IN). Finally, the outputs are being displayed by connecting the analog out (A-OUT) of OP4510 to YOKOGAWA Multi Signal Oscilloscope (MSO). The overall validation setup and its flow can be seen in Fig[.6.](#page-12-0)

The MSO is set to display two signals, where the first one is real time PQD signal from GS. The other one is the PQD index which presents the current state of the real time PQD signal detected by the proposed HOLGBM PQ Detection Model. The list of Indices for the PQDs are already given in Table[-1.](#page-3-0) It can be observed from Fig[.7](#page-12-1) that, a sequence of intentional disturbances are generated from GS for a duration of 15 AC cycles (50Hz) to validate the detection capability of the proposed classifier. In the bottom half figure the index "2" is indicating to PQ label "PQI2" which designates the system is in ''Healthy'' state. But after the occurrence of SAG event the indicator drops from 2 to 1 indicating to PQ label ''PQI1'' which designates the system is under ''SAG'' state. Next the system again gets back to ''Healthy'' state and indicator changed from 1 to 2 and further steps to 3 indicating to PQ label ''PQI3'' which designates the system is under "SWELL" state and so on. It is to be noted that the live voltage signal is initially converted to per unit then only further processing is carried out, since the classifier is trained with the per unit signals.

Further the detection time of the proposed classifier is calculated from the real time results. In Fig[.8](#page-13-0) a sag event is zoomed at 10ms/div to indicate the detection time. It can be clearly seen that the PQ Index changed from 2(healthy) to 1(sag) after certain amount of time delay. This delay is actually the detection time which has two parts as follows,

DetectionTime (*DT*) $=$ *AcquisionDelay* (*AD*) + *ProcessDelay* (*PD*) (7)

The acquisition delay is because of the way the real time data is collected in the buffer before processing. Since the data collection is made for 5 cycle-window with a 1 cycle gap as shown in data acquisition part of Fig[.1,](#page-7-0) the acquisition delay is fix to 20ms or 200 samples. Further, to calculate the process delay, the PQD Signal and Index samples are saved to the host PC for more than 3000 cycles. From this data, 100 number of PQD observations are taken where the sample difference between the instance of occurrence to the instant of detection are evaluated. It has been observed that the sample difference varies from 341 to 373 as show in Fig[.9.](#page-13-1) That means the process delay varies in between 141 to 173 samples. Therefore, the detection time is evaluated by taking the average of 100 observation which comes to be 358.8 samples (≈35.88ms). Moreover, a confusion matrix is given in Fig[.10](#page-13-2) of these 100 observations to validate the detection accuracy of the proposed classifier with real time data. It has been observed that, the classifier successfully detected all events without any misclassification i.e., the detection accuracy is found to be 100%.

D. COMPARATIVE STUDY

In this subsection, first the training-testing time and the respective accuracy of the proposed method is compared

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FIGURE 6. Real time setup to validate the proposed PQ detection scheme.

FIGURE 7. Real time voltage and PQD index from MSO.

FIGURE 9. Differential sample count between disturbance occurrence and detection instant of 100 real time observations.

TABLE 3. Comparison of GBM and LGBM with proposed HOLGBM along with VMD.

Boosting	Processing Time (msec)		Detection	
Techniques	Training	Testing	Accuracy (In %)	
VMD+GBM	142.67	11.34	93.2	
VMD+LGBM	63.6	11.17	95.1	
Proposed	20.9	10.98	97.21	
VMD+HOLGBM				

with plain vanilla Gradient Boosting Machine (GBM) and LGBM. It is to be noted that the dataset taken here is the mix all datasets with dimensions 30000×5 . Here once again

FIGURE 10. Confusion matrix of 100 real time observations.

random sampling in 70:30 ratio is maintained for training and testing respectively. The observation shown in Table[-3](#page-13-3) revels a significant improvement in training time in the proposed method whereas the testing times are nearly equal to each other. Moreover, the detection accuracy is hitting 97.21% which is also found to be superior among the three.

Further, the proposed PQD detection method is being compared with the similar pre-published methods to study its effectiveness in terms of detection time and accuracy. The outcomes are presented in Table[-4](#page-14-0) along with the number of test events and sampling frequency. Since, a limited number of research works have been published especially for PQ detection with ensemble tree classifiers, the comparative study is further extended to tally different ensemble tree

TABLE 4. Performance comparison with similar priorly published studies.

SL.	Pre-proposed	Event Count	Sampling frequency (In kHz)	Accuracy (In $\%$)			
	Works			Ideal	20dB	30dB	40dB
1	$[29]$, 2016	9	5	99.38	97.77		
$\mathbf{2}$	$[30], \overline{2017}$	10	3.2	99.2	98.5	\blacksquare	
3	$[31]$, 2019	$\overline{7}$	$\overline{2}$	98.61	\blacksquare	\blacksquare	\blacksquare
$\overline{\mathbf{4}}$	$[32]$, 2019	11	10	99.92	\blacksquare		\blacksquare
5	$[33]$, 2020	9	3.2	99.78			
6	$[34]$, 2020	9	3.2	99.68	\blacksquare		\blacksquare
7	$[35]$, 2020	16	15.36	99.47	\blacksquare	97.45	98.37
8	$[36]$, 2022	8	\sim	\blacksquare	97.57	98.25	\blacksquare
9	$[37]$, 2023	8	12.5	99.5	\blacksquare	\blacksquare	\blacksquare
		9		99.77	95.72	97.07	98.4
10	Proposed	15	10	99.56	95.69	97.00	98.39

TABLE 5. Comparison of conceptualization with similar priorly published Studies.

techniques (bagging & boosting) for PQ detection in Table[-5.](#page-14-1) A total of 5 conceptual factors namely, feature selection, dataset type, proposed optimizer, real time validation and detection time are considered. It is found that, most of the studies neither gone for feature selection [\[15\],](#page-15-14) [\[19\],](#page-15-18) [\[38\],](#page-16-0) [\[39\],](#page-16-1) [\[40\]](#page-16-2) nor gone for a computation of detection time. As feature selection is a crucial step for classifier performance, it is needed to be taken care of. Unlike other classifiers LGBM [\[41\],](#page-16-3) [\[42\],](#page-16-4) [\[43\]](#page-16-5) automatically take care of feature selection applying its internal GOSS and EFB mechanism, therefore used as base classifier of the proposed study.

Similarly, detection time is also a much crucial performance parameter especially when real-time monitoring is performed and thus calculated in the proposed work. In addition to that, [\[7\]](#page-15-6) (Memetic Fire Fly Algorithm-MFFA), [\[41\]](#page-16-3) (Improved Gray Wolf Optimization-IGWO) studies undergone the optimization of classifier parameters but suggested classifier is not validated in real time. Similarly, [\[39\]](#page-16-1) has tested its PQ detection technique with data extracted from PQSCADA system but no in real-time mode. References [\[19\]](#page-15-18) and [\[42\]](#page-16-4) have done real-time simulation through Real Time Digital simulator (RTDS) & OPAL-RT setups respectively whereas [\[15\]](#page-15-14) proposed Digital Signal Processing (DSP) board-based monitoring system. On the other hand, the proposed study has gone through all the aforementioned conceptual parameters and therefore can be well generalized for real grid applications. Hence, from the overall study and experimentation, it is evident that, the proposed VMD based HOLGBM classifier can well perform the classification task even with practical scenario data.

VI. CONCLUSION

The research work is focusing upon fast and accurate power quality disturbance identification combining the likes of VMD and LGBM. Since most informative signal recognition is a major concern in signal separation techniques like VMD, in this approach all five BLMs are considered to overcome this challenge. Moreover, feature selection is one more key concern in MLC based technique like LGBM, the process is completely simplified by taking the energies of all five BLMs as features. Following the aforesaid information, a feature dataset of 15 PQDs are prepared with dimension of 30000×5 combining both ideal and noisy signals where

each PQD has 2000 data instances. The dataset is further used to train and test the LGBM where the training time and detection accuracy are found to be 63.6 msec and 95.1% respectively. To improve the performance of the concerned classifier the hyper parameters of LGBM are optimized through a proposed Hybrid Arithmetic Whale Optimization Algorithm. The imposed modification significantly reduced the training time to almost one third i.e. 20.9msec along with elevated the over accuracy to 97.21% with ideal accuracy of 99.56%. Furthermore, the proposed technique is also validated in real time through OPAL-RT and Grid Simulator Hardware in Loop (HIL) setup and three PQ events such as sag, swell and interruption are investigated. A total of 100 real-time signals generated in grid simulator are successfully detected by the proposed VMD & HOLGBM based PQDM with an average detection time of 35.88msec. This setup ensured the integrity and reliability of our experimentation and analysis.

ACKNOWLEDGMENT

Sairam Mishra, Ranjan Kumar Mallick, Debadatta Amaresh Gadanayak, Pravati Nayak, Renu Sharma, and Gayadhar Panda express their gratitude to the Microgrid Research Laboratory, ITER, Siksha 'O' Anusandhan (Deemed to be University), Bhubaneswar, for their invaluable support and resources during the course of this research.

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