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Radio Modulation Classification Optimization Using Combinatorial Deep Learning Technique

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ABSTRACT We present an automatic signal modulation classification model using combinatorial deep learning technique. Our proposed deep learning model increase accuracy for low Signal-to-Noise Ratio (SNR) and maintain a high classification accuracy for high SNR signals. Using a hybrid deep learning model combining both ConvLSTM with Transformer-block neural networks, the proposed modulation classifier architecture can learn the signal for both low and high SNR and get better accuracy for signals with high noise. The proposed deep learning modulation classification technique achieves improved classification

accuracy of 66% for low SNR signals and 93.5% at high SNR showing that our model is robust under noisy signal modulation. Thus, getting better accuracy in lower SNR signals without sacrifice accuracy for higher SNR signals. An adaptive weighted focal loss function is proposed as an optimized loss function for efficient classification which can be used to control the outliers within a class imbalance and avoid underflow issues. Our deep learning radio modulation classification model works using raw signal without the need of denoising the noisy signal.

INDEX TERMS Automatic modulation classification, dynamic spectrum allocation, deep learning techniques, transformer-block ConvLSTM, feature-based extraction, AI-based wireless communications.

I. INTRODUCTION

Automatic signal modulation recognition in AI-based wireless communication can be done using combinatorial deep learning techniques to improve resource shortage and spectrum utilization efficiency for dynamic spectrum allocation [1]. A clean signal will have a high Signal-to-Noise Ratio (SNR). We should be able to classify signals in both low and high SNR. Our proposed deep learning model increase accuracy for low SNR and maintain a high classification accuracy for high SNR signals. Using a hybrid deep learning model by combining both ConvLSTM with Transformer-block

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neural networks shown in Fig. 1. The proposed deep learning modulation classification technique achieves improved classification accuracy of 66% for low SNR signals and 93.5% at high SNR. Thus, getting better accuracy in lower SNR signals without sacrifice accuracy for higher SNR signals. Simulation results show that our proposed deep learning model is robust under noisy signal modulation without the need of denoising the noisy signal.

By utilizing combinatorial technique in our proposed model that incorporates both ConvLSTM and transformerblock model. Our proposed model has advantage in using transformer-block network since it uses parallelization processing thus make use of parallel computation [2]. Also, the input size can be any size or vector length and simultaneously

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FIGURE 1. Automatic modulation classification model using combinatorial deep learning technique for both low and high SNR signal classification.

proceed by the transformer-block network instead of sequentially hence solving the vanishing gradient problem. By using transformer-block network in our proposed model, the context of data can be well captured because it uses the positional encoding and self-attention mechanism which are included in the network modules [2].

II. NEURAL-NETWORK MODULATION CLASSIFICATION

Automatic modulation classification (AMC) offers spectrum management and interference detection for software defined radio and cognitive radio networks [1].

As a practical solution to improve the effectiveness of automatic modulation classification, deep learning techniques have been widely used in wireless communication systems. Automatic modulation classification can be divided into likelihood-based and feature-based methods [1]. The likelihood-based method requires more computational complexity. Whereas feature-based method requires less computational complexity [3], [4], [5], [6].

The signal is not ideal and is usually combined with noise. A noisy signal will have a low SNR [3], [4], [5], [6]. It means that if the noise is higher, the model will likely to fail to do the modulation classification. We should be able to classify signals both in low SNR and high SNR.

The authors West and O'Shea [7] combined CNN and RNN neural networks to form a CLDNN model which improved the modulation recognition accuracy to 85% in high SNR only. The authors Chen et al. [8] combined CNN, RNN, and GAN neural networks to extract the signal spatial characteristics and classification is done with a fully connected layer achieving an accuracy of more than 90% in high SNR only. Jiang et al. [9] combined CLDNN with LSTM neural network achieving 90.8% accuracy at high SNR. Tang et al. [10] combined CNN with GAN achieving an accuracy of 100% at high SNR. Xu et al. [11] combined CNN with LSTM neural networks achieving an accuracy of 90% at high SNR. Jiang et al. [12] combined CNN with Bi-LSTM achieving an accuracy of 93.1%. Liang et al. [13] combined ResNeXt with Attention block achieving an accuracy of 90% in high SNR. Chang et al. [14] combined CNN with Bi-GRU achieving an accuracy of 84% in high SNR only.

Zhang et al. [15] combined GRU with CNN achieving an accuracy of 99.4%.. Zou et al. [16] combined CLDNN with Attention achieving an accuracy of 90% in high SNR. The

authors Bai et al. [17] combined ResNet with CNN achieving an accuracy of 91% in high SNR. Chen et al. [8] used a deep learning-based attention framework using CNN, RNN, and GAN neural networks. The CNN and RNN are used to extract the signal spatial characteristics. Zou et al. [16] used Attention along with CLDNN neural networks model achieving an accuracy of 90% in high SNR. Bai et al. [17] combined complex value network with ResNet model achieving an accuracy of 91% at high SNR. Chang et al. [14] combined CNN with Bi GRU networks achieving an accuracy of 84% at high SNR. Duan et al. [18] used combination of CNN with BiLSTM and Attention models achieving an accuracy of 93% at high SNR. Xu et al. [11] combined CNN and LSTM with FC models achieving an accuracy of 90% at high SNR.

Dampage et al. [19] used both LSTM and Bi LSTM models achieving an accuracy of 90% at high SNR. Liu et al. [20] combined DCN and BiLSTM models achieving an accuracy of 90% at high SNR. Yang et al. [21] used an IRS model combined with LSTM neural networks achieving an accuracy of 90% at high SNR. Kumaran et al. [22] combined GRU and BiLSTM neural networks achieving an accuracy of 92% at high SNR. Ze and Vikalo [23] used single neural network model LSTM achieving an accuracy of 90% at high SNR. Xie et al used DNN neural network model to extract sixth order cumulant feature of the signal achieving an accuracy of 92% at high SNR. Zhang et al. [24] used BP network model achieving an accuracy of 98% at high SNR. Our proposed deep learning model increase accuracy for low SNR and maintain a high classification accuracy for high SNR signals compared to previous published work. Using a hybrid deep learning model by combining both ConvL-STM with Transformer-block neural networks. Our proposed deep learning modulation classification technique achieves improved classification accuracy of 66% for low SNR signals and 93.5% at high SNR. Other published work such as Oikonomou [25] do not use deep learning models and hence do not have the capability of modulation recognition format prediction also they do not have the capability of loading automatic modulation recognition deep learning model on hardware accelerator chips to take processing load of the main hardware processor compared to our proposed deep learning model [25]. Our proposed automatic modulation recognition format prediction combined deep learning model can be loaded on a hardware accelerator chip thus take the processing load of the main hardware microprocessor.

Recent studies show that deep learning models such as neural networks can extract features effectively from various representation of wireless signals such as in-phase and quadrature (IQ) signal or spectrogram in order to achieve high modulation classification accuracy [3], [4], [5], [6].

The received signals is preprocessed from I/Q signals cartesian coordinates to polar coordinates to the corresponding amplitude and phase in order to extract more features. By learning more features from the polar domain makes the network more resilient to fading channels [3], [4], [5], [6] then are converted to Fig. 2 which describes the constellation



FIGURE 2. Various modulation constellation data signals are represented by two vectors one for quadrature and other for In-phase.

diagrams of common modulation modes after coordinate transformation.

Fig. 2 shows various modulation constellation data signals considered in this work that are represented by two vectors one for Quadrature and In-phase representation. Similar modulation constellation data signals are considered in previous publish work Bell [3] where they combined both ResNet and CNN achieving 86% accuracy in high SNR only unlike our proposed work where we achieve high accuracy in both high and low SNR. Also Huang [4] used similar modulation constellation data signals in their published work using compressive CNN achieving accuracy of 95% accuracy in high SNR only. Guo [5] also used similar modulation constellation data signals in their published work using Residual CNN achieving accuracy of 92% accuracy in high SNR only unlike our proposed work where we achieve high accuracy in both high and low SNR.

Zhang et al. [6] proposed a multiscale CNN for constellation-based modulation classification. The network structure was composed of multiple processing modules achieving a classification accuracy can reach 97.7% in high SNR only [6] [26]. Shi et al. [27] [26] proposed an automatic modulation recognition (AMR) method which includes a multi-scale convolution deep network for recognizing modulation types achieving an overall recognition accuracy of 98.7%.again only in high SNR unlike our proposed work where we achieve high accuracy in both high and low SNR [27] [26].

III. FEATURE EXTRACTION-BASED CLASSIFICATION

The proposed deep-learning-based model for automatic modulation classification (AMC) was trained using IQ

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component signals and image-based constellation diagrams [3], [4], [5], [6].

The feature-based method usually requires less computational complexity by extracting data representation features for classification [3], [4], [5], [6]. Key features can be categorized as time-domain features including instantaneous amplitude, phase and frequency and frequency-domain features such as wavelet transform of the signals, higher order moments (HOMs) and higher order cumulants (HOCs) that are described in (1) through (50) as follows [3], [4], [5], [6].

The BPSK transmitter emits a signal with voltage of "-a" volts when transmitting bits X=0 and the random variable X is mapped to voltage of "+a" volts when transmitting bits X=1. The communication channel adds the Gaussian noise to this transmitted signal. Therefore, the conditional distribution and variance of σ_n^2 with Gaussian distribution p(r) is the Gaussian distribution with mean "-a" volts variance of σ_n^2 given by and is represented as follows [28]

$$p(r) = \frac{1}{\sqrt{2\pi\sigma_n^2}} \exp\left(-\frac{1}{2}\left(\frac{r+a}{\sigma_n}\right)^2\right).$$
 (1)

The ratio when transmitter sends X=0 to X=1 is given by the following λ and is represented as follows [28]

$$\lambda = \frac{\frac{1}{\sqrt{2\pi\sigma_n^2}} \exp\left(-\frac{1}{2}\left(\frac{r-a}{\sigma_n}\right)^2\right)}{\frac{1}{\sqrt{2\pi\sigma_n^2}} \exp\left(-\frac{1}{2}\left(\frac{r+a}{\sigma_n}\right)^2\right)}.$$
 (2)

which simplifies to the following equation if $\lambda > 1$ the receiver estimates that X=1 is sent else X=0 [28]

$$\lambda = \exp\left(\frac{2ra}{\sigma_n^2}\right). \tag{3}$$

which is evaluated to

$$\log\left(\lambda\right) = \frac{2ra}{\sigma_n^2}.\tag{4}$$

The heterodyne Zero-IF receiver shown in Fig. 3 have a decision rule that can be written in a minimum distance which compares the squared Euclidean distances d_1^2 and d_0^2 and is represented as follows [28]

$$d_1^2 - d_0^2 = (r - a)^2 - (r + a)_{\cdot}^2$$
(5)

Various features extracted from IQ signal components, such as amplitude and phase, higher order statistics and higher order cumulants are utilized to provide sequence classification [3], [4], [5], [6].

A feature extraction-based classification method usually includes two stages data feature extraction and classifier decision making. The key features can be categorized as time domain features including amplitude, frequency, and transform domain features such as higher-order moments (HOMs) and higher-order cumulants (HOCs).

Coefficients series expansion are expected values of complex-valued polynomials H(z). They are computed using the input symbols cross-moments. These input symbols



FIGURE 3. Deep learning-based radio modulation recognition for heterodyne Zero-IF receiver with quadrature down conversion.

cross-moments used to determine the probability density function the symbols came from. The Gram-Charlier expansion series can be defined as follows [29]

$$f_{z}(z) = \sum_{p=0}^{\infty} \sum_{q=0}^{\infty} \frac{E\left[H_{p,q}(z)\right]^{*}}{\sqrt{p!q!}} \frac{H_{p,q}(z)}{\sqrt{p!q!}} \frac{1}{\pi} e^{-zz^{*}}$$
(6)

Some complex Hermite polynomials are given by the following coefficients [29]

$$H_{0,0}(z) = 1 \tag{7}$$

$$H_{1,0}(z) = z$$
 (8)

$$H_{1,1}(z) = |z|^2 - 1.$$
(9)

$$H_{2,1}(z) = z^2 z^* - 2z. \tag{10}$$

$$H_{2,2}(z) = |z|^4 - 4|z|^2 + 2.$$
(11)

The density functions can be determined by the infinite sequence of these coefficients and can be defined as follows [29].

$$h_{p,q}(f_z) = \frac{E\left[H_{p,q}(z)\right]^*}{\sqrt{p!q!}}.$$
(12)

The Euclidean distance between two density function or sequence coefficient is determined as follows [29]

$$d(f_1, f_2) = \sqrt{\sum_{p=0}^{\infty} \sum_{q=0}^{\infty} |h_{p,q}(f_1) - h_{p,q}(f_2)|^2}.$$
 (13)

This Euclidean metric on the set of Gram-Charlier coefficients enables use of metric space-based classifiers.

We can define the second-order moments of a stationary random process y(n) with the following coefficients. C_{40} , C_{41} , or C_{42} can be determined in terms of the fourth-and second order moments of y(n) as follows [30], [31]

$$C_{21} = \frac{1}{N} \sum_{n=1}^{N} |y(n)|^2.$$
 (14)

$$C_{20} = \frac{1}{N} \sum_{n=1}^{N} y^2(n).$$
 (15)

The higher order cumulants (HOCs) of fourth order are used for automatic modulation classification. The cumulants of the received symbol y are determined as follows [30], [31]

$$C_{40} = \frac{1}{N} \sum_{n=1}^{N} y^4(n) - 3C_{20}^2.$$
 (16)

$$C_{41} = \frac{1}{N} \sum_{n=1}^{N} y^3(n) y^*(n) - 3C_{20}C_{21}.$$
 (17)

We can estimate the normalized cumulants as such. By using the above (14) to (18), three HOC feature parameters (i.e., F1, F2, and F3) are extracted for classification and represented as follows [30], [31]

$$F_1 = \frac{|C_{40}|}{C_{42}} \tag{19}$$

$$F_2 = \frac{|C_{41}|}{C_{42}} \tag{20}$$

$$F_3 = \frac{|C_{63}|^2}{|C_{42}|^3} \tag{21}$$

 C_{40} is utilized to decide whether the constellation diagram is for the real valued rectangular QAM or circular PSK or BPSK or PAM. The amount of cumulative is used to determine the type of modulation. We choose the decision limits as illustrated as follows [30], [31]

$$C_{40} < 0.34$$
 implies PSK. (22)

$$0.34 < C_{40} < 1.02$$
 implies QAM. (23)

$$1.02 < C_{40} < 1.68$$
 implies PAM. (24)

$$1.68 < C_{40} < 1.68$$
 implies BPSK. (25)

Thus, the lowest value of distance between empirical cumulants and theoretical values $(L \rightarrow \infty)$ indicates the utilized modulation type.

The signal received by the receiver can be described as follows.

Under the assumption that the signal received by the receiver has undergone carrier synchronization, symbol timing, and matched filtering, and the channel noise is Gaussian white noise, the symbol synchronous sampling complex signal sequence obtained at the output is [32]

$$x(t) = s(t) + n(t)$$

= $\sqrt{A} \sum_{k}^{g} \mu_{k} \sqrt{E_{n}} \lambda (t - nT) \exp[j(2\pi f_{c} + O_{c}] + n(t)]$
(26)

x (t) is the signal received at the receiving end, and s (t) is the signal at the transmitting end, n (t) is the zero-mean complex Gaussian white noise, E_n is signal energy.

where k=1,2...g, and g is the length of the transmitted code element sequence. A is the unknown factor amplitude, λ (t) is transmitted waveform code element; μ_k is code sequence element, O_c is carrier phase, Ts is width of the code element, E_n is signal energy and f_c is carrier frequency [32].

For zero-mean stationary random process X(t), the p-order mixing moment and k-order HOC are defined as follows.

The characteristic parameters HOCs for various signals that can be designed in accordance is shown in Table 1. Utilizing the following equations three feature parameters

 TABLE 1. High-order cumulant HOC modulation signals.

Signal	C_{40}	C ₄₁	C ₄₂	C ₆₃
2ASK	$2E_n^2$	$2E_{n}^{2}$	$2E_n^2$	$16E_{n}^{3}$
4ASK	$1.36E_n^2$	$1.36E_n^2$	$1.36E_n^2$	$8.32E_{n}^{3}$
4PSK	E_n^2	0	E_n^2	$4E_n^2$
2FSK	Ô	0	Ő	$4E_{n}^{3}$
16QAM	$0.68E_{n}^{2}$	$0.68E_{n}^{2}$	$0.68E_{n}^{2}$	$2.08E_{n}^{3}$
64QAM	$0.62E_n^2$	$0.62E_n^2$	$0.62E_n^{2}$	$1.08E_n^{3}$



FIGURE 4. Classification loss function optimization.

(i.e., F1, F2, and F3) are extracted [31]

$$F_1 = \frac{|C_{40}|}{C_{42}} \tag{27}$$

$$F_2 = \frac{|C_{41}|}{C_{42}}$$
(28)
$$F_2 = \frac{|C_{63}|^2}{C_{63}}$$
(29)

$$F_3 = \frac{|C_{63}|}{|C_{42}|^3} \tag{29}$$

The three signal features extracted from HOC having strong low SNR robustness where E_n is signal energy [32].

The SNR estimated value can be defined as follows [32]

$$SNR = \frac{\sqrt{2M_2^2 - M_4}}{M_2 - \sqrt{2M_2^2 - M_4}}.$$
 (30)

The second-order moment M2 and fourth order moment M4 method are given by [32]

$$M_2 = \frac{1}{N} \sum_{n=0}^{N-1} |x(n)|^2.$$
 (31)

$$M_4 = \frac{1}{N} \sum_{n=0}^{N-1} |x(n)|^4.$$
 (32)

N is the signal length, and the received signal is x(n).

Then we perform normalization to the data by minimizing the penalty function is how Neural networks learn. And accordingly, they iteratively updates a series of weights and biases. Weights in loss function can be used to control the outliers for positive predictions to deal with a class imbalance as shown in Fig. 4.

The weighted cross-entropy loss function can be determined with the following equation. Where y_i is actual value of y and y'_i is predicted value of y, w is the weight associated with each sample, M is the total number of samples in the dataset,



FIGURE 5. Loss function optimization analysis.

N is the normalization factor for sample [2], [33], [34]

$$L(y'_{i}, y_{i}) = -\frac{\sum_{i=1}^{M} \omega_{i} \sum_{i=1}^{M} \frac{y_{i}}{N_{i}} \log y'_{i}}{\sum_{i=1}^{M} \omega_{i}}.$$
 (33)

A categorical cross-entropy loss function use softmax instead of using sigmoid as the last layer activation. The categorical cross-entropy loss function can be determined as follows where M is the total number of samples in the dataset [31], [33] [34]

$$L(y'_{i}, y_{i}) = -\sum_{i=1}^{M} y_{i} \log y'_{i}.$$
 (34)

In focal loss function has the same softmax of cross-entropy except it is an index of which category is true instead of the target being a probability distribution. The index of which category is the true value we just pass in as follows where M is the total number of samples in the dataset and Υ is the hyperparameter [31], [33] [34].

$$L(y'_{i}, y_{i}) = -\sum_{i=1}^{M} (1 - y'_{i})^{\Upsilon} y_{i} \log y'_{i}.$$
 (35)

To avoid underflow issues the Kullback Leibler loss function expects the argument input in the log-space and is computed as follows where M is the total number of samples in the dataset [31], [33] [34]

$$L(y'_{i}, y_{i}) = \sum_{i=1}^{M} y_{i}(\log y_{i} - \log y'_{i}).$$
(36)

An adaptive weighted focal loss is proposed as an optimized loss function for efficient classification which can be used to control the outliers with class imbalance and avoid underflow issues as shown in Fig. 5 and it can be determined as follows where Y_{pred} is the predicted probability representing the model's estimated probability that a sample belongs to the positive class [31], [33] [34]

$$L(y'_{i}, y_{i}) = -\frac{\sum_{i=1}^{M} \omega_{i} \sum_{i=1}^{M} \frac{(1-y'_{i})^{\lambda}}{N_{i}} (\log y_{i} - \log y'_{i})}{\sum_{i=1}^{M} \omega_{i}}.$$
 (37)



FIGURE 6. ConvLSTM memory cell structure.

IV. PROPOSED MODULATION CLASSIFICATION DEEP LEARNING MODEL

In this section, a hybrid combinatorial deep learning model combining both ConvLSTM with Transformer-block neural networks is proposed. Our proposed modulation classifier architecture can learn the signal for both low and high SNR and get better accuracy for signals with high noise. For learning persistent features from a time series data, Recurrent Neural Networks (RNN) are utilized. However, these models using RNNs suffer from much slower training time. LSTM efficient in learning long-term dependencies is a special type of RNN. ConvLSTM Convolutional Long Short-term is a special type of RNN which integrates both CNN with LSTM. ConvLSTM is a modification and extended version of LSTM as shown in Fig. 6.

The data transmission and processing in LSTM are realized by three key gate units: input gate, output gate, and forget gate, which are used for implementing information processing.

In LSTM, the input gate i_t , the output gate o_t , and forgotten gates f_t are defined as [19], [20], [35], and [36], respectively

The equations of LSTM cell are as follows. The input gate and memory status update information are [19], [20], [23] [35],

$$i_t = \sigma(W_{xi}X_t + W_{hi}H_{t-1} + W_{ci}C_{t-1} + b_i).$$
 (38)

$$f_t = \sigma(W_{xf}X_t + W_{hf}H_{t-1} + W_{cf}C_{t-1} + b_f).$$
(39)

$$p_t = \sigma(W_{xo}X_t + W_{ho}H_{t-1} + W_{co}C_t + b_o).$$
(40)

where σ is a sigmoid function and X_t is the input to the current gate structure, and H_{t-1} is the output of the previous gate memory cell structure. C_{t-1} represent the state of the last memory cell in LSTM. W_{xi} and b_i are the weight and bias of the input gate, W_{xf} and b_f are the weight and bias of the forget gate, and W_{xo} and b_o are the weight and bias of the output gate [19], [20], [23]. The input feature sequence X_t and the output sequence of the previous time H_{t-1} are input to the memory cell. The forgetting factor f_t is obtained via the forgetting gate. tanh is an activation function that generates candidate values \tilde{C}_t . In addition, \tilde{C}_t participates in the calculation to obtain the memory state C_t [19], [20], [23]

$$\tilde{C}_t = tanh(W_{xc}X_t + W_{hc}H_{t-1} + b_c).$$
(41)

$$c_t = f_t \cdot C_{t-1} + i_t \cdot C_t.$$
(42)

$$h_t = \sigma_t . \tanh(c_t). \tag{43}$$

The output gate control factor o_t determines whether to output information and is expressed as follows [35]

1

$$o_t = \sigma(W_{xo}X_t + W_{ho}H_{t-1} + W_{co}C_t + b_o).$$
 (44)

Compared with C_t , H_{t-1} contains more information about the current moment. Therefore, H_{t-1} represents short-term memory, while C_t represents long-term memory and the state-update is given by the following equations [19], [20], [23]

The Convolutional Long Short-term ConvLSTM shown in Fig. 6 calculation equations can be expressed as [37]

$$i_t = \sigma(W_{xi*}X_t + W_{hi*}H_{t-1} + W_{ci}OC_{t-1} + b_i).$$
 (45)

$$f_t = \sigma(W_{xf*}X_t + W_{hf*}H_{t-1} + W_{cf}OC_{t-1} + b_f).$$
(46)

$$o_t = \sigma(W_{xo*}X_t + W_{ho*}H_{t-1} + W_{co}OC_t + b_o).$$
 (47)

$$C_t = tanh(W_{xc*}X_t + W_{hc*}H_{t-1} + b_c).$$
 (48)

$$c_t = f_t \circ \mathcal{C}_{t-1} + i_t \circ \mathcal{C}_t. \tag{49}$$

$$H_t = \sigma_t \operatorname{otanh}(C_t). \tag{50}$$

where X_t denotes the input of the current cell, C_{t-1} and H_{t-1} are state and output of the last cell, respectively. The * operator means the convolution operation and the o denotes the Hadamard product. W denotes the convolution filter. W_{xi} and b_i are the weight and bias of the input gate, W_{xf} and b_f are the weight and bias of the forget gate, and W_{x0} and b_0 are the weight and bias of the output gate [37]. ConvLSTM Convolutional Long Short-term contains convolution operation inside it and is used extract spatial-spectral features [37]. It captures long-term and short-term dependencies by stacking multiple ConvLSTM layers [37]. We should be able to classify signals both in low SNR and high SNR. We proposed a combined deep learning architecture shown in the Fig. 7 that works to handle the noisy signal modulation low SNR signal modulation and maintain high accuracy for High SNR signals. Adding more ConvLSTM layers with MaxPooling layers can extract more features which is fed into classification layer to predict the probability distribution of each modulation class and is given by the following [37], [38], [39].

$$P(y = i | x, W, b) = \frac{e^{(\omega_{jx} + b_j)}}{\sum_{j=1}^{N} e^{(\omega_{jx} + b_j)}}.$$
 (51)

W is weight and b is the bias of the classification layer with a loss function determined as [37], [40]

$$L(y_i, y'_i) = -\sum_{i=1}^{M} (y_i \cdot \log y'_i).$$
 (52)

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FIGURE 7. Combinatorial deep learning neural networks model for both low SNR and high SNR modulation classification.

TABLE 2. ConvLSTM network model layers.

Layer type	OUTPUT SHAPE
Input	128x2
Conv1D	121x64
MaxPooling1D	60x64
ConvLSTM	60x64
Dropout	60x64
ConvLSTM	60x64
Dropout	64
GlobalAveragePooling1D	64
Dense	20
Dropout	20
Dense (Softmax)	11

Our proposed architecture uses two streams as shown in Fig. 7, first stream with ConvLSTM and second stream with transform-block network to extract features for high and low SNR signals. Our proposed model has advantage in using transformer-block network since it uses parallelization processing thus make use of parallel computation [2]. Also, the input size can be any size or vector length and simultaneously proceed by the transformer-block network instead of sequentially hence solving the vanishing gradient problem. By using transformer-block network in our proposed model, the context of data can be well captured because it uses the positional encoding and self-attention mechanism which are included in the network modules [2].

The layer type and output shape for ConvLSTM network structure specific to each layer that is implemented is shown in Table 2. As illustrated in Table 2 a Conv1D convolutional layer consisting of 64 filters is applied to the 128×2 IQ inputs with kernel size of 8.

For higher resolution we need a large filter. It maps the input IQ components onto feature channels. Then, based on the characteristics of IQ signal. Softmax is used as the activation function for multi-class classification and the optimizer

TABLE 3. ConvLSTM2D network model layers.

Layer type	OUTPUT SHAPE
Input	128x2
Conv2D	121x64
MaxPooling2D	60x64
ConvLSTM2D	60x64
Dropout	60x64
ConvLSTM2D	60x64
Dropout	64
GlobalAveragePooling2D	64
Dense	20
Dropout	20
Dense (Softmax)	11

used is Adam with loss function categorical cross entropy along with learning rate of 0.01.

After that a MaxPooling1D and then a ConvLSTM and dropout layer follows with the same parameters. After that second ConvLSTM and a dropout layer followed by a *GlobalAveragePooling1D* with the same parameters and a Dense and Dropout layer. At the end is a fully connected layer with an output size 11 with a Softmax activation function.

To increase the overall accuracy performance of our proposed model a ConvLSTM2D model is implemented. The layer type and output shape for ConvLSTM2D network structure specific to each layer that is implemented is shown in Table 3. The proposed architecture consists of an input layer of 128×2 IQ input, followed by a Conv2D layer with 64 filters and 8 kernels then a MaxPooling2D layer and then a ConvLSTM2D and a Dropout layer follows with the same parameters. After that second ConvLSTM2D and a Dropout layer followed by a *GlobalAveragePooling2D* with the same parameters and a Dense and Dropout layer. At the end is a fully connected layer with an output size 11. Softmax is used as the activation function for multi-class classification and the optimizer used is Adam with loss function categorical cross entropy along with learning rate of 0.01.

A Transformer-block is utilized as the second stream for larger training data set parallelization [41] [42]. Transformers use attention blocks resulting in faster training time and inference testing time. Our proposed model has advantage in using transformer-block network since it uses parallelization processing thus make use of parallel computation [2]. The final network design for our proposed classifier model combine Transformer-block with ConvLSTM2D as shown in Fig. 8 and Fig. 9 to achieve higher classification accuracy for both Low and High SNR signals. The proposed multi-stream network can extract various characteristics of signals as shown in Fig. 9.

To determine the transformer self-attention, we use the following [2], [43]

Attention(Q, K, V) = softmax
$$\left(\frac{QK^T}{\sqrt{d_k}}\right)$$
 V. (53)

where Q is the query sequence and K is the keys in the sequence and V is the sequence value. And the attention



FIGURE 8. Proposed automatic modulation classification model using combinatorial deep learning technique for both low and high SNR signal classification.



FIGURE 9. Proposed combinatorial deep learning classification model for both low SNR and high SNR modulation recognition.

weights are given by [2], [8], [43]

$$a = \operatorname{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right).$$
(54)

It uses different transformations activation functions to transform the input and eliminates the need for recurrent connections [2], [8], [13], [43].

Our proposed model has advantage in using transformerblock network since it uses parallelization processing thus make use of parallel computation. In turn faster training time and inference testing time in using parallelization. Moreover, the input size can be any vector length and simultaneously proceed by the transformer-block encoder-decoder attention instead of sequentially hence solving the vanishing gradient problem. Also, context of data is well captured positional encoding and self-attention mechanism.

To increase the overall accuracy performance and to capture more context of the input data, a transformer-block network is implemented as a second stream in our proposed architecture as shown in Fig. 9. The layer type and output

TABLE 4.	Transformer-block	network	model	layers.
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Layer type	OUTPUT SHAPE
Input	128x2
Conv1D	121x64
MaxPooling1D	60x64
ConvLSTM	60x64
Dropout	60x64
Transformer block	60x64
GlobalAveragePooling1D	64
Dropout	64
Dense	20
Dropout	20
Dense (Softmax)	11

shape for the transformer-block network structure specific to each layer that is implemented is shown in Table 4. The proposed architecture consists of an input layer of 128×2 IQ input, followed by a Conv1D layer with 64 filters and 8 kernels then a MaxPooling1D layer and then a ConvLSTM and a Dropout layer follows with the same parameters. After that a Transformer-block and a *GlobalAveragePooling1D* followed by Dropout layer with the same parameters and a Dense and Dropout layer. At the end is a fully connected layer with an output size 11. Softmax is used as the activation function for multi-class classification. The Transformer uses a stochastic gradient descent (SGD) optimizer and starts with a learning rate of 0.03, which can be lowered during the training.

V. RML2016.10a and RML2016.10b RADIO SIGNAL DATASET

DeepSig radio signal datasets RadioML2016.10a [44] [45] and RadioML2016.10b [21] are used for evaluating the modulation recognition of our proposed models.

TABLE 5. RadioML2016.10a DeepSig dataset parameters.

Parameter	VALUE
Modulations	11 Classes, 8 digital, 3 analog
	modulations
Length per sample	2x128
Signal format	In-phase & Quadrature IQ
Samples per	8
symbol	
Total number of	220,000
samples	
Sampling	1 MHz
frequency	
SNR Range	[-20:2:18]dB
Training Samples	176,000
Test Samples	44,000

TABLE 6. RadioML2016.10B DeepSig dataset parameters.

Parameter	VALUE	
Modulations	10 Classes, 8 digital, 2 analog	
Length per sample	2x128	
Signal format	In-phase & Quadrature IQ	
Signal dimension	2x128 per sample	
Total number of	1,200,000	
samples Duration per	128 µs	
sample SNR Range	[-20:2:18]dB	
Training Samples	960,000	
Test Samples	240,000	

The RML2016.10a dataset parameters [44] are shown in Table 5. It contains 220,000 samples, each represented using two vectors each of them has 128 elements Shape: (220,000, 2, 128) [46]. The IQ signal input component. A batch size of 128 is used on each training epoch [45].

The RML2016.10b dataset parameters [21] are shown in Table 6. It contains 1.2M samples, each represented using two vectors each of them has 128 elements Shape: (1200000, 2, 128) [46]. The IQ signal input component. A batch size of 128 is used on each training epoch.

The Nvidia Tesla A100 Tensor Core GPU is used to speed up the calculation. Models are implemented done using Keras framework with Nvidia A100 Tensor Core GPU.

The 128-sample baseband IQ time-domain signal data is used to identify the modulation type out of 11 modulations. based on power spectrum and time. The input data is fed in where the real and imaginary parts of samples are separated as shown in Fig. 10 and Fig. 11 [47].

Received r(t) signal is sampled into its discrete signal r[n], that is of the in-phase (I) components $r^{I}[n]$ and quadrature (Q) components $r^{Q}[n]$ are given as [36], [46], [48]

$$r[n] = r^{I}[n] + jr^{Q}[n].$$
(55)

In reality the signal is always not ideal and combined with unwanted signal that is considered as noise which can affect



FIGURE 10. IQ signal data samples constellation diagram where signals are represented by two vectors one for quadrature and other for In-phase representation.



FIGURE 11. IQ signal data samples power spectrum representation.

our ability to determine the signal. Their relationship with the transmitter side I[n] and Q[n] is given by [36], [49], [50]

$$r^{I}[n] = I[n] \cos (2\pi f n + \varphi)$$

- Q[n] sin (2\pi f n + \varphi) + n_{add}[n]. (56)
$$r^{Q}[n] = -I[n] \sin (2\pi f n + \varphi)$$

$$[n] = -I[n]\sin(2\pi fn + \varphi)$$
$$- O[n]\cos(2\pi fn + \varphi) + n_{add}[n]$$
(57)

extract the relation between
$$L$$
 and Q components, the

To construct the relation between I and Q components, the transformation function can be expressed as [36]

1

$$[n] = radius[n] = \sqrt{I[n]^2 - Q[n]^2}.$$
 (58)

$$\theta[n] = theta[n] = \arctan(\frac{I[n]}{Q[n]}).$$
(59)

We detect signals from their time representation showing value of each signal at a given time where each sample is represented by two vectors one for Quadrature and other for In-phase representation and the variance of data shown in

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FIGURE 12. Classifier accuracy performance versus SNR for high SNR modulation recognition increase model layer with batch size.



FIGURE 13. Varying learning rate and epoch with hyperparameter tunning.

Fig. 10 and Fig. 11. We should be able to classify signals both in low SNR and high SNR.

VI. CLASSIFICATION PERFORMANCE SIMULATION RESULTS

The simulation results show that our proposed deep learning model is robust under noisy signal modulation without the need of denoising the noisy signal. The simulation results show our technique outperforms existing feature-based extraction architectures in terms of modulation recognition performance getting better accuracy in lower SNR signals without sacrifice accuracy in higher SNR signals.

Our proposed deep learning modulation classification technique achieves improved classification accuracy of 66% for low SNR signals and 93.5% at high SNR. As shown in Fig. 12, Fig. 13 and Fig. 14 overall classification accuracy against SNR.

The overall classification performance of our proposed deep learning model for high SNR signals is shown in Fig. 13. Two ConvLSTM2D layers gives better accuracy than one ConvLSTM2D layer with batch size of 256 achieving accuracy of 93.5% for High SNR signals.

The overall classification performance of our proposed deep learning model for high SNR signals is shown in Fig. 13. Tuning the learning rate hyperparameter to 0.0001 with



FIGURE 14. Combined transformer-block with ConvLSTM neural network SNR classifier performance.



FIGURE 15. Confusion matrix of our proposed deep learning model for digital modulations at 0dB SNR with 50 epochs.

200 epochs gives higher classification accuracy achieving accuracy of 93.5% for High SNR signals.

As shown in Fig. 14 our proposed deep learning modulation classification technique achieves improved classification accuracy of 66% for low SNR signals and 93.5% at high SNR. Using our hybrid deep learning model by combining both ConvLSTM2D with Transformer-block neural networks, the proposed modulation classifier architecture can learn the signal for both low and high SNR and get better accuracy for signals with high noise. Showing that our model is robust under noisy signal modulation.

We analyze the classification accuracy of our proposed model for different modulation with DeepSig RadioML2016.10a dataset. The confusion matrix presents what modulation classes the model is confusing with other modulation classes. A dark blue along the diagonal represents a perfect classification.

The confusion matrix performance of the proposed deep learning model for digital modulation signals at 0dB SNR with 50 epochs is shown in Fig. 15. We analyze the classification accuracy of our proposed model for different modulation with DeepSig RadioML2016.10a dataset.







FIGURE 17. Confusion matrix of our proposed deep learning model for digital modulations at 2dB SNR with 50 epochs.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at 0dB SNR with 300 epochs is shown in Fig. 16. We analyze the classification accuracy of our proposed model for different modulation with DeepSig RadioML2016.10a dataset.

The confusion matrix performance of the proposed deep learning model for digital modulation signals at 2dB SNR with 50 epochs is shown in Fig. 17.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at 2dB SNR with 300 epochs is shown in Fig. 18.

The confusion matrix performance of the proposed deep learning model for digital modulation signals at -16dB SNR with 50 epochs is shown in Fig. 19.



FIGURE 18. Confusion matrix of our proposed deep learning model for both digital and analog modulations at 2dB SNR with 300 epochs.



FIGURE 19. Confusion matrix of our proposed deep learning model for digital modulations at -16dB SNR with 50 epochs.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at -14dB SNR with 300 epochs is shown in Fig. 20.

The confusion matrix performance of the proposed deep learning model for digital modulation signals at 4dB SNR with 50 epochs is shown in Fig. 21.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at 4dB SNR with 300 epochs is shown in Fig. 22.

The confusion matrix performance of the proposed deep learning model for digital modulation signals at 6dB SNR with 50 epochs is shown in Fig. 23.







FIGURE 21. Confusion matrix of our proposed deep learning model for digital modulations at 4dB SNR with 50 epochs.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at 6dB SNR with 300 epochs is shown in Fig. 24.

The confusion matrix performance of the proposed deep learning model for digital modulation signals at 8dB SNR with 50 epochs is shown in Fig. 25.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at 8dB SNR with 300 epochs is shown in Fig. 26.

The confusion matrix performance of the proposed deep learning model for digital modulation signals at 10dB SNR with 50 epochs is shown in Fig. 27.



FIGURE 22. Confusion matrix of our proposed deep learning model for both digital and analog modulations at 4dB SNR with 300 epochs.



FIGURE 23. Confusion matrix of our proposed deep learning model for digital modulations at 6dB SNR with 50 epochs.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at 10dB SNR with 300 epochs is shown in Fig. 28.

The confusion matrix performance of the proposed deep learning mode for digital modulation signals at 12dB SNR with 50 epochs is shown in Fig. 29.

The confusion matrix performance of the proposed deep learning mode for digital and analog modulation signals at 12dB SNR with 300 epochs is shown in Fig. 30.

The confusion matrix performance of the proposed deep learning mode for digital modulation signals at 14dB SNR with 50 epochs is shown in Fig. 31.



FIGURE 24. Confusion matrix of our proposed deep learning model for both digital and analog modulations at 6dB SNR with 300 epochs.



FIGURE 25. Confusion matrix of our proposed deep learning model for digital modulations at 8dB SNR with 50 epochs.

The confusion matrix performance of the proposed deep learning model for digital and analog modulation signals at 14dB SNR with 300 epochs is shown in Fig. 32.

The confusion matrix performance of the proposed deep learning mode for digital modulation signals at 16dB SNR with 50 epochs is shown in Fig. 33.

The confusion matrix performance of the proposed deep learning mode for digital and analog modulation signals at 16dB SNR with 300 epochs is shown in Fig. 34.

The confusion matrix performance of the proposed deep learning mode for signals at 18dB SNR with 50 epochs is shown in Fig. 35.



FIGURE 26. Confusion matrix of our proposed deep learning model for both digital and analog modulations at 8dB SNR with 300 epochs.



FIGURE 27. Confusion matrix of our proposed deep learning model for digital modulations at 10dB SNR with 50 epochs.

The confusion matrix performance of the proposed deep learning mode for digital and analog modulation signals at 18dB SNR with 300 epochs is shown in Fig. 36.

The results of the confusion matrix in Fig, 15 to Fig. 36 show that our proposed model performs well across most signal types as shown in the confusion matrix in Fig. 15 to Fig. 36. We analyze the classification accuracy of our proposed model for different modulation with DeepSig RadioML2016.10a dataset.

It is noted that QAM16 is often misrecognized as QAM64 and vice versa because the constellation points of QAM16 can be found in the constellation points of QAM64 so they can have constellation in common which causes short time observation to suffer. Moreover, features for a signal with







FIGURE 29. Confusion matrix of our proposed deep learning model for digital modulations at 12dB SNR with 50 epochs.

QAM64 modulation may not be captured by just 128 samples and so the deep network confuses it with QAM16 and therefore might benefit from a bigger dataset.

The accuracy performance of the proposed deep learning model per various modulation type versus SNR is shown in Fig. 37. A noisy signal will have a low SNR that means that if the noise is higher, the model will likely to less accuracy to do the modulation classification.

The overall classification performance of the proposed combined deep learning model is shown in Table 7.

The accuracy performance of the proposed deep learning model per various modulation type versus SNR from -20 dB to -2 dB is shown in Table 8.



FIGURE 30. Confusion matrix of our proposed deep learning model for both digital and analog modulations at 12dB SNR with 300 epochs.



FIGURE 31. Confusion matrix of our proposed deep learning model for digital modulations at 14dB SNR with 50 epochs.

TABLE 7. Overall classification performance.

SNR	MODEL	Accuracy
High SNR Signals	ConvLSTM	93.5% for High SNR Signals
Low SNR Signals	Transformer-block	62% for Low SNR Signals
Both High and Low SNR Signals	Transformer-block + ConvLSTM	62% for Low SNR and 93.5% for High SNR Signals

The accuracy performance of the proposed deep learning model per various modulation type versus SNR from 0 dB to 20 dB is shown in Table 9.







FIGURE 33. Confusion matrix of our proposed deep learning model for digital modulations at 16dB SNR with 50 epochs.

The overall training and prediction time performance of the proposed combined deep learning model compared to other models is shown in Table 10.

Other published work [25] that do not use deep learning models do not have the capability of applying automatic modulation recognition prediction. Other published work [44] that use deep learning models only achieve high accuracy in high SNR signals only unlike our proposed work where we achieve high accuracy in both high and low SNR signals. One of the main advantages of our proposed work is that our combined deep learning model provide the capability of loading automatic modulation recognition on hardware accelerator chips to take processing load of the main hardware processor. Also, another advantage of our proposed work is



FIGURE 34. Confusion matrix of our proposed deep learning model for digital and analog modulations at 16dB SNR with 300 epochs.



FIGURE 35. Confusion matrix of our proposed deep learning model for digital modulations at 18dB SNR with 50 epochs.

that by utilizing Transformer-block processing utilized for larger training data set parallelization in our combined model resulting in faster training time and inference testing as shown in Table 10. However, does not achieve the fastest prediction and training time compared combined models which is one of the shortcomings of our combined deep learning model.

As can be seen in Fig. 38, X. Hao [18] used CLDNN+ GRU model achieving accuracy of 90% at 0 dB SNR and less than 20% at -16 dB SNR. S. Huang [4] used Comprehensive CNN model achieving accuracy of 80% at 0 dB SNR and less than 20% at -16 dB SNR. X. Xie [35] used DenseNet and BLSTM model achieving accuracy of 84% at 0 dB SNR and less than 25% at -16 dB SNR. H. Yang [21] used IRLNet model achieving accuracy of 97% at 5 dB SNR and less





ACCURACY PER MODULATION TYPE VS SNR



FIGURE 37. Accuracy performance of the proposed deep learning model per various modulation type versus SNR.

 TABLE 8. Accuracy performance per various modulation type versus SNR.

Modulation Type	-20	-15	-12	-10	-8	-5	-2
16QAM	0.58	0.58	0.59	0.60	0.58	0.60	0.58
32QAM	0.40	0.41	0.39	0.40	0.39	0.41	0.48
64QAM	0.47	0.47	0.49	0.50	0.49	0.48	0.47
128QAM	0.41	0.40	0.40	0.41	0.38	0.41	0.45
256QAM	0.41	0.42	0.40	0.40	0.43	0.41	0.45
BPSK	0.63	0.65	0.63	0.62	0.63	0.62	0.62
QPSK	0.62	0.63	0.62	0.60	0.62	0.62	0.60
8PSK	0.47	0.48	0.47	0.48	0.46	0.47	0.46
4ASK	0.54	0.53	0.56	0.54	0.57	0.54	0.60
8ASK	0.54	0.54	0.56	0.56	0.54	0.55	0.56
PAM4	0.52	0.51	0.52	0.51	0.52	0.50	0.52
CPFSK	0.51	0.53	0.52	0.51	0.50	0.52	0.50
GFSK	0.51	0.53	0.52	0.51	0.50	0.51	0.52

than 50% at -16 dB SNR. F. Liu [32] used GRU model achieving accuracy of 86% at 0 dB SNR and less than 55%

TABLE 9. Accuracy per	formance per vario	us modulat	ion type	versus SNR
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Modulation Type	0	2	5	8	10	15	20
16QAM	0.63	0.76	0.80	0.82	0.66	0.82	0.83
32QAM	0.70	0.72	0.73	0.70	0.71	0.74	0.73
64QAM	0.50	0.65	0.65	0.65	0.66	0.68	0.66
128QAM	0.60	0.69	0.71	0.70	0.69	0.70	0.70
256QAM	0.74	0.75	0.73	0.74	0.75	0.78	0.76
BPSK	0.96	0.95	0.96	0.97	0.98	0.97	0.99
QPSK	0.94	0.95	0.96	0.98	0.95	0.94	0.97
8PSK	0.88	0.95	0.96	0.95	0.96	0.96	0.96
4ASK	0.88	0.87	0.89	0.88	0.89	0.89	0.88
8ASK	0.88	0.90	0.88	0.89	0.88	0.91	0.90
PAM4	0.95	0.96	0.95	0.97	0.98	0.96	0.98
CPFSK	0.97	0.98	0.97	0.98	0.96	0.97	0.96
GFSK	0.96	0.97	0.96	0.98	0.97	0.98	0.99

TABLE 10. Overall training & prediction time performance.

Model	TRAINING TIME PER EPOCH (S)	Prediction Time (µ/sample)	Training Time (s)
CNN [44]	30	1000	600
LSTM [44]	800	2000	44800
SCRNN [44	280	600	11480
L .	-		
ResNet [51]	341	183	1850
Resider [51]	541	105	1050
Transformer block + ConvLSTM (this work)	- 320	730	2250





FIGURE 38. Accuracy performance of the proposed deep learning model per various Models type versus SNR.

at -16 dB SNR. Our proposed model used ConvLSTM and Transformer-block model achieving accuracy of 93.5% at 0 dB SNR and 62% at -16 dB SNR.

As shown in Table 11, our proposed model used ConvL-STM and Transformer-block model achieving accuracy of 93.5% at 0 dB SNR and 62% at -16 dB SNR. Whereas F. Liu [32] used GRU model achieving accuracy of 86% at 0 dB SNR and less than 55% at -16 dB SNR. H. Yang [21] used IRLNet model achieving accuracy of 97% at 5 dB SNR and less than 50% at -16 dB SNR. X. Xie [35] used DenseNet and BLSTM model achieving accuracy of 84% at 0 dB SNR

TABLE 11.	Overall classification	modulation	recognition a	ccuracy
performan	ce comparison.			

Author	Input Signal	Model	Recognition Accuracy
K. Jiang [12]	IQ sequence	CNN + Bi LSTM	90% (0 dB) & < 10% (-16 dB)
B. Tang [10]	constellation map	CNN + GAN	100% (-2 dB) & < 10% (-16 dB)
J. Xu [11]	IQ sequence	CNN + LSTM + FC	90% (0 dB) & < 10% (-16 dB)
Z. Liang [13]	IQ sequence	ResNeXt + Attention	90% (0 dB) & < 10% (-16 dB)
W. Zhang[15]	Sampled signal	GRU + CNN	99.45% (0 dB) & < 10% (-16 dB)
S. Chang [14]	Sampled signal	CNN + Bi GRU + SAFN	84% (0 dB) & <10% (-16 dB)
B. Liu [20]	IQ sequence	DCN + Bi LSTM	90% (0 dB) & < 10% (-16 dB)
J. Bai [17]	IQ sequence	DMFF + CNN	90% (0 dB) & < 10% (-16 dB)
B. Udaya [19]	IQ sequence	LSTM + Bi LSTM	90% (0 dB) & < 10% (-16 dB)
B. Zou [16]	IQ sequence	Attention + CLDNN	90% (4 dB) & < 10% (-16 dB)
X. Hao [18]	IQ sequence	CLDNN+GRU	90% (0 dB) & <20% (-16 dB)
S. Huang [4]	IQ sequence	Compressive CNN	80% (0 dB) & <20% (-16 dB)
X. Xie [35]	IQ sequence	DenseNet-BLSTM	84% (0 dB) & <25% (-16 dB)
H. Yang [21]	IQ sequence	IRLNET	97% (5 dB) & <50% (-16 dB)
F. Liu [32]	IQ sequence	GRU	86% (0 dB) & <55% (-16 dB)
(This work)	IQ sequence	Transformer-block + ConvLSTM	93.5% (0 dB) & 62% (-16 dB)

and less than 25% at -16 dB SNR. And S. Huang [4] used Comprehensive CNN model achieving accuracy of 80% at 0 dB SNR and less than 20% at -16 dB SNR. And X. Hao [18] used CLDNN+GRU model achieving accuracy of 90% at 0 dB SNR and less than 20% at -16 dB SNR. All other published models in Table 11 achieve less than 10% at -16 dB SNR compared to our proposed model.

We compare our proposed models in terms of the number of trainable parameters, the number of floating point operations (FLOPs) and the memory cost as shown in Table 12. Smaller number of trainable parameters requires fewer FLOPs and the smaller memory space.

It can be seen in Table 12 that our proposed model needs to train 1702625 parameters with total number of

TABLE	12.	Model la	ver numl	per of	parameter.
		mouchia	y ci manni		parameter

Model Layer	Trainable Parameter	NUMBER OF Flops	Memory
CNN [23] LSTM [23]	5456219 199563	80548043 7696283	61.4MB 2.31MB
This work	1702625	60662829	19.7MB

60662829 floating point operations (FLOPs) at a 19.7MB memory cost. Whereas LTSM model in [1] needs to train 199563 parameters with total number of 7696283 floating point operations (FLOPs) at a 2.31MB memory cost. Also, CNN [1] needs to train 5456219 parameters with total number of 80548043 floating point operations (FLOPs) at a 61.4MB memory cost as shown in Table 12.

VII. CONCLUSION

An automatic signal modulation classification model using combinatorial deep learning technique was presented. Our proposed deep learning model increase accuracy for low signal to noise ratio SNR and maintain a high classification accuracy for high SNR signals. Using a hybrid deep learning model combining both ConvLSTM2D with Transformer-block neural networks, the proposed modulation classifier architecture can learn the signal for both low and high SNR and get better accuracy for signals with high noise. The proposed deep learning modulation classification technique achieves improved classification accuracy of 66% for low SNR signals and 93.5% at high SNR showing that our model is robust under noisy signal modulation. Our deep learning radio modulation classification model works using raw signal without the need of denoising the noisy signal. The simulation results show that the proposed technique outperforms existing feature-based extraction architectures in terms of modulation recognition performance getting better accuracy in lower SNR signals without sacrifice accuracy in higher SNR signals.

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