

## RESEARCH ARTICLE

# MBAHIL: Design of a Multimodal Hybrid Bioinspired Model for Augmentation of Hyperspectral Imagery via Iterative Learning for Continuous Efficiency Enhancements

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**ABSTRACT** The augmentation of hyperspectral images requires the design of high-density feature analysis & band-fusion models that can generate multimodal imagery from limited information sets. The feature analysis models use deep learning operations to maximize inter-class variance while minimizing inter-class variance levels for efficient classification operations. When combined with intelligent band-fusion methods, such models allow the augmentation model to enhance its classification efficiency under different use cases. Existing band-fusion-based augmentation models for hyperspectral images do not incorporate continuous efficiency enhancements and showcase higher complexity levels. Furthermore, these models can't be scaled for more varied use cases because their use is restricted to specific image types. To overcome these issues, we designed a novel multimodal hybrid bioinspired model for the augmentation of hyperspectral imagery via iterative learning for continuous efficiency enhancements. The proposed model initially represents input images into Fourier, Laplacian, Cosine, multimodal Wavelet, Mellin, and Z-Transform domains, which will assist in describing the images in multimodal domains. These transformed image sets are passed through a convolutional filter to extract windowed feature sets. A Grey Wolf Optimizer (GWO) is used to identify high inter-class variance features from the extracted image sets, which assists in selecting transformed images that can help improve hyperspectral classification performance. The selected hyperspectral images are fused via a Bacterial Foraging Optimization (BFO) model, which assists in reducing intra-class variance levels. The final set of selected images is intelligently augmented via Particle Swarm Optimization (PSO), which performs rotation, zooming, shifting, and brightness variation operations selectively. These augmented images are classified via a customized VGGNet-19-based Convolutional Neural Network (CNN) classifier that assists in continuously estimating accuracy levels for different application scenarios. Based on these accuracy levels, the model is reconfigured via hyperparameter tuning of GWO and PSO optimizers. Due to combining these models and incremental accuracy optimizations, the proposed model has improved its hyperspectral classification accuracy by 10.6% and precision by 10.4%, as compared to standard deep learning-based augmentation techniques.

**INDEX TERMS** Bacterial foraging optimization, grey wolf optimizer, hyperspectral images, particle swarm optimization, VGGNet-19.

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## I. INTRODUCTION

The hyperspectral images (HSIs) that are acquired via the use of remote sensing are made up of hundreds of continuous

spectral bands that are very thin, and each pixel (vector) in the image offers a distinct description of the objects that are being investigated [46]. HSIs have a wide variety of applications, some of which include object identification, segmentation, and classification [47]. Support vector machines (SVMs), extreme learning machines (ELMs), and single-hidden layer feedforward networks are a few examples of machine learning approaches that have been used to extract information from high-dimensional hidden-state images (SHLFNs) [48]. Recent advancements in Earth observation missions have made it possible to capture HSI images of more excellent quality, including the addition of spectral bands and a higher resolution in space and spectral dimensions [49]. These improvements have been made possible due to recent advancements in imaging technology. Because of this, there has been a demand for an increase in both the storage capacity and the runtime via Adversarial Encoding Network (AEN) [4]. In this context, CNN models effortlessly combine spectral characteristics with spatial-contextual information from HSI data more effectively than prior DNN models; they have gained increasing traction as a powerful method for making sense of HSI data [5], [6]. As a result, deep learning methods based on CNNs have become the current gold standard for classifying HSI data [3]. Most of CNN's attempts to recognize HSI data include the problem of overfitting, which may be problematic. This difficulty adds to the challenge of learning already provided by the significant spectrum fluctuation characteristic of HSIs. According to various authors' understanding, the majority of the currently available strategies for reducing the impact of the overfitting problem [7] and enhancing CNN's capacity for generalization focus on amassing more training data during the phase of the process where it is being learned by including large geographical areas, sometimes with the help of geometric alterations [6]. Regularization methods are used in a variety of tactics. Techniques like dropout and Max Pooling were used in [5] work as a regularization. By giving an abstract representation of the convolved features, the max pooling layer aids in reducing both their spatial size and overfitting. A regularization method called dropout is used to minimize overfitting in neural networks. Deep learning models often employ dropout on the fully connected layers; however, it is also feasible to use dropout following the max-pooling layers, which augments image noise.

Recent attempts have also been made to improve the model architecture by increasing residual designs AEN [4] to offer each layer more data or expanding the connections between levels [8]. Both of these improvements were made very recently. There are just two examples included in this list. These strategies have been improved upon using a variety of methods, some of which include fully linked architectures [12], active learning [11], and pixel-pairs features (PPFs) [10]. These methods place a significant amount of emphasis on the performance of the output (Soft Max) layer to achieve their goals, contributing to the computation's complexity. The principal component analysis is a technique

that is used by several scholars, including Chen et al. [12], to augment this level of analysis (PCA).

In comparison, the research in [11] enhances the model's generality by integrating data with greater levels of uncertainty. PPFs are used in the data pertinent to pixel neighborhoods in work presented in [10], which is an attempt very similar to those done to solve the problem of inconsistencies in the data. Data occlusion, also known as the inability of a remote sensor to view a portion of the Earth's surface due to factors such as the presence of an obstacle between the sensor and the two-dimensional target surface or adjacent three-dimensional objects, is a significant challenge that arises in the field of remote sensing. This may take place if, for instance, a three-dimensional object is positioned between the sensor and the two-dimensional surface that is being scanned. Since they cause a reduction in the amount of information in an image, blocking elements such as clouds, shadows, and others are to blame for this problem. The removal of data occlusions may be accomplished by many different strategies that have been established. These techniques were conceptualized after observing the human brain, which can operate most effectively in a three-dimensional environment [13], [14]. This concept may enhance the process of instructing machine learning strategies. From this brief review and the comprehensive review in the next section, it can also be observed that existing band-fusion-based augmentation models for hyperspectral images do not incorporate continuous efficiency enhancements and showcase higher complexity levels.

Moreover, the application of these models is limited to certain image types and thus cannot be scaled for broader use cases. To overcome these issues, section 3 of this text proposes designing a novel multimodal hybrid bioinspired model for the augmentation of hyperspectral imagery via iterative learning for continuous efficiency enhancements. The model was validated on multiple datasets, and its performance was compared for different datasets in section 4 of this text. Finally, this text is concluded with some context-specific observations about the proposed model and recommends various methods to further improve its performance levels.

The following is a summary of the study's key contributions:

- Proposed a novel bio-inspired augmentation methodology based on Fourier, Laplacian, Cosine, multimodal Wavelet, Mellin, and Z-Transform domains.
- PSO is used to optimize the geometric transformation parameters.
- It is possible to create a larger volume of images in less time that may be utilized as a remote sensing training data set for scene classification.
- The Python source code used in the experiments described in this article is made available to the public without charge (available at <https://github.com/dipen0401/augmentation>).

## II. BRIEF REVIEW OF IMAGE AUGMENTATION MODELS

Data augmentation broadens the pool of information used to train a model. The key benefit is that the model becomes more stable and resistant to overfitting [57], [58]. The authors in [59] used flip, translation, and rotation in remote sensing scene classification. For instance, works in [15], [16], [17], and [18] propose the use of a Generative Adversarial Network (GAN), YOLOv5s, a multi-semantic global channel, and spatial joint attention module (MsGCS) for the estimation of augmented image sets for different application scenarios. These scenarios are extended in [19], [20], which discuss using Soft Augmentation-Based Siamese CNN (SAB SCNN) and different GANs for hyperspectral image sets. These models are highly scalable but showcase higher complexity, which limits their speed performance levels. To overcome this issue, works in [21], [22], [23], [24], and [25] propose using Hapke equations, Local Bias CNN, Hierarchical Amortized GAN, Cycle GAN, and Attention Networks for the estimation of augmented image sets. These sets are obtained via simplified augmentation operations and can be applied to multimodal application scenarios. Similarly, work in [26], [27], [28], [29], and [30] proposes the use of a Convolutional Network with Twofold Feature Augmentations, Proto-MaxUp (PM), Conditional GAN, Hierarchical CNN with Soft Augmentation (HCNN SA), and Mask Region CNN, for estimation of high-density image sets under different application scenarios. These models can improve classification efficiency under multimodal scenarios.

Models that propose the use of Low-Pass Activation Function with DCT Augmentation [31], Spatial Feature Enhanced Unets [32], Localization-Aware Adaptive Pairwise Margin Loss [33], Bitplane Information Recombination [34], improved YoLo [35], auto-updating multitemporal matrix factorization with spatio-spectral channel augmentation (AMMF SSCA) [36], Spectral Index Generative Adversarial Network (SIGAN) [37], and pixel-level augmentations [38], that assist in improving classification performance for various application sets. These models aim to optimize the augmentations via pre-emptive analysis, enabling high accuracy and low complexity classification operations. Models discussed in [39], [40], [41], and [42] further extend these methods via integrating multimodal GAN, small target GAN, Siamese CNN, and Global Spatial with Local Spectral Similarity levels for satellite image sets. These models showcase higher complexity but enable high-accuracy augmentations for larger image sets. Similar models are proposed in [43], [44], and [45] that use deformable convolutional networks (DCNs), Generative Motion Models, and fully convolutional neural networks (FCN) for simplified classification with moderate accuracy levels. But these models do not incorporate continuous efficiency enhancements and showcase higher complexity levels.

Moreover, the application of these models is limited to certain image types and thus cannot be scaled for broader use cases. To overcome these issues, the next section of this text proposes a design of a novel multimodal hybrid bioinspired

model for the augmentation of hyperspectral imagery via iterative learning for continuous efficiency enhancements. The proposed model was validated under different application sets, and their performance was evaluated under large-scale scenarios.

## III. DESIGN OF THE PROPOSED MODEL

Based on the review of existing hyperspectral image augmentation models, these models use high-complexity feature analysis to improve classification performance under different use cases. When combined with intelligent band-fusion methods, such models allow the augmentation model to enhance its classification efficiency under other use cases. Existing band-fusion-based augmentation models for hyperspectral images do not incorporate continuous efficiency enhancements and showcase higher complexity levels. Moreover, the application of these models is limited to certain image types and thus cannot be scaled for broader use cases. To overcome these issues, this section discusses the design of a novel multimodal hybrid bioinspired model for augmentation hyperspectral imagery via iterative learning for continuous efficiency enhancements. The flow of the model is depicted in Fig. 1. It can be observed that the proposed model initially represents input images into Fourier, Laplacian, Cosine, multimodal Wavelet, Mellin, and Z-Transform domains, which will assist in representing the images in multimodal domains. These transformed image sets are passed through a convolutional filter to extract windowed feature sets. A Grey Wolf Optimizer (GWO) [62] is used to identify high inter-class variance features from the extracted image sets, which assists in selecting transformed images that can improve hyperspectral classification performance. The selected hyperspectral images are fused via a Bacterial Foraging Optimization (BFO) model [50], which assists in reducing intra-class variance levels. The final set of selected images is intelligently augmented via Particle Swarm Optimization (PSO) [51], which performs rotation, zooming, shifting, and brightness variation operations selectively. These augmented images are classified via a customized VGGNet-19-based Convolutional Neural Network (CNN) classifier [59], [61] that assists in continuously estimating accuracy levels for different application scenarios.

Thus, all the collected satellite images are initially passed through a transformation process. This process uses the following transforms,

- Fourier transformation is evaluated via (1) and used to represent input pixels as frequency components, thus assisting in identifying any frequent patterns in the image sets. [53]

$$F(r, c, b) = \frac{1}{R * C * B} \sum_{i=1}^R \sum_{j=1}^C \sum_{l=1}^B I(r, c, b) * \exp\left(\frac{2 * \sqrt{-1} * \Pi * i * j * l}{R * C * B}\right) \quad (1)$$

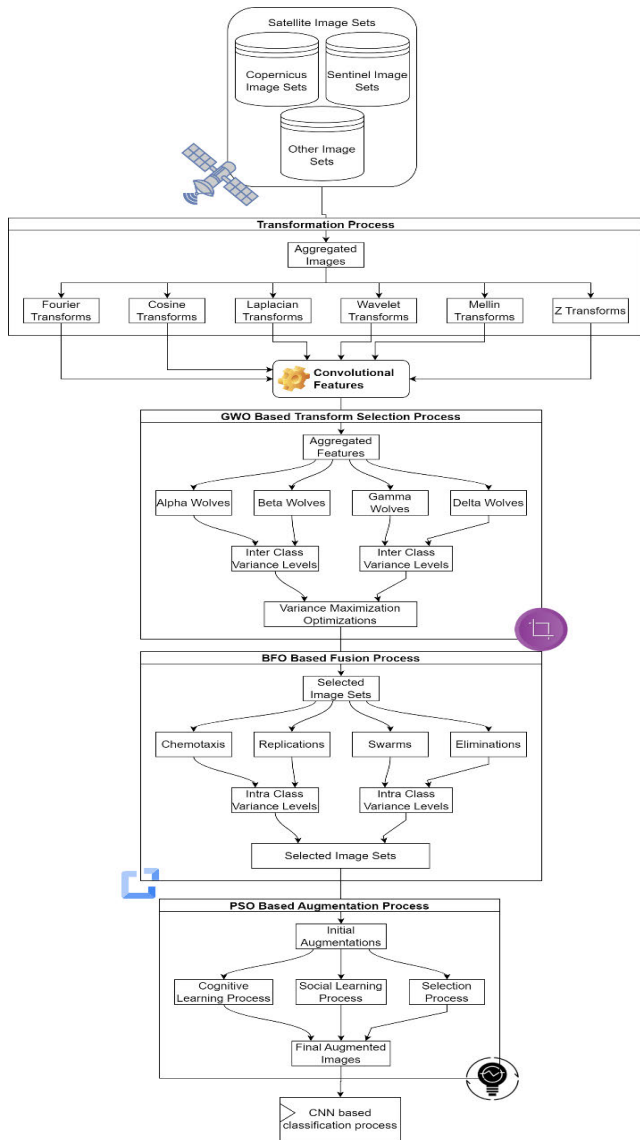


FIGURE 1. The flow of the proposed augmentation process.

- Laplacian transformation is evaluated via equation 2 and used to represent input pixels as equational entities, thus assisting in evaluating temporal feature sets [56].

$$L(r, c, b) = \frac{b}{\Pi} \sum_{i=1}^R \sum_{j=1}^C \frac{I(r, c, b)}{(r-i)^2 + (c-j)^2 + (b)^2} \quad (2)$$

- Cosine transformation is evaluated via (3) and used to represent input pixels as entropy levels, thus assisting in identifying maximal energy patterns in the image sets [55].

$$DCT(r, c, b) = \frac{1}{2\sqrt{RCB}} \sum_{i=1}^R \sum_{j=1}^C \sum_{l=1}^B I(r, c, b)$$

$$\begin{aligned} & * \cos\left(\frac{(2i+1)\Pi\sqrt{-1}}{2R}\right) * \cos\left(\frac{(2j+1)\Pi\sqrt{-1}}{2C}\right) \\ & * \cos\left(\frac{(2l+1)\Pi\sqrt{-1}}{2B}\right) \end{aligned} \quad (3)$$

- Multimodal Wavelet transformation is evaluated via (4), (5), (6), & (7) and used to represent input pixels as approximate, diagonal, vertical, and detail components, thus assisting in the identification of directional patterns in the image sets [54].

$$Wa(r, c, b) = \frac{I(r, c, b) + I(r, c + 1, b) + I(r + 1, c, b) + I(r + 1, c + 1, b)}{4} \quad (4)$$

$$Wh(r, c, b) = \frac{I(r, c, b) - I(r, c + 1, b) + I(r + 1, c, b) + I(r + 1, c + 1, b)}{4} \quad (5)$$

$$Wv(r, c, b) = \frac{I(r, c, b) + I(r, c + 1, b) - I(r + 1, c, b) + I(r + 1, c + 1, b)}{4} \quad (6)$$

$$Wd(r, c, b) = \frac{I(r, c, b) - I(r, c + 1, b) + I(r + 1, c, b) - I(r + 1, c + 1, b)}{4} \quad (7)$$

where,  $Wa$ ,  $Wh$ ,  $Wv$ , &  $Wd$  represent approximate, horizontal, vertical, and diagonal wavelet components respectively.

- Mellin transformation is evaluated via (8) and used to represent input pixels as variance-independent sets, thus assisting in identifying variance levels in the image sets.

$$M(r, c, b) = \frac{1}{2\Pi\sqrt{-1} * R * C * B} \sum_{i=1}^R \sum_{j=1}^C \times \sum_{l=1}^B I(r, c, b)^{-(ijl)} \quad (8)$$

- Z-Transform transformation is evaluated via (9) and used to represent input pixels as frequency components and assists in the identification of stability levels of pixel sets [53].

$$Z(r, c, b) = \frac{\sum_{i=1}^R \sum_{j=1}^C \sum_{l=1}^B I(r, c, b) * z^{-rcb}}{RCB} \quad (9)$$

Based on these transforms, each band of the input image is represented in multiple domains. These domain sets are represented into convolutional feature sets via (10),

$$Conv_{out_{i,j}}(band) = \sum_{a=-\frac{m}{2}}^{\frac{m}{2}} \sum_{b=-\frac{n}{2}}^{\frac{n}{2}} I \times (i-a, j-b, band) * ReLU\left(\frac{m}{2} + a, \frac{n}{2} + b\right) \quad (10)$$

where  $m$ ,  $n$  represents window sizes,  $a$ ,  $b$  represents stride sizes, and ReLU represents a rectilinear unit which is used to activate the feature sets via (11),

$$\begin{aligned} \text{ReLU}(x, y) &= \text{Max}(x, y) \\ &\text{when } x > 0 \quad \& \quad y > 0, \text{ else } x \\ &\text{when } x > 0, \quad \text{else } y \\ &\text{when } y > 0, \quad \text{else } 0 \text{ for other cases} \end{aligned} \quad (11)$$

These feature sets are processed via a Grey Wolf Optimizer [62] that works via the following process,

- To initialize the GWO-based feature selection process, setup the following constants,
  - Total GWO iterations =  $N_i$
  - Total GWO Wolves =  $N_w$
  - Rate of cognitive learning between Wolves =  $L_w$

To set up initial Wolf configurations, generate  $N_w$  Wolves as per the following process, Stochastically select  $N$  features via (12),

$$N = \text{STOCH}(L_w * N_f, N_f) \quad (12)$$

*STOCH* represents a stochastic Markovian process used to generate number sets, while  $N_f$  represents some extracted feature sets.

For the selected feature sets, identify their inter-class variance levels for each class via (13),

$$icv(m) = \sqrt{\frac{\sum_{a=1}^m \left( x_a - \frac{\sum_{i=1}^m \sqrt{\frac{\sum_{j=1}^n (x_j - \frac{\sum_{k=1}^n x_k)^2}{n}}}{n-1}}{m} \right)^2}{m-1}} \quad (13)$$

where  $m$  represents total features in the current class,  $icv$  represents their interclass variance levels,  $x$  represents the extracted features, and  $n$  represents features in other classes.

- This variance is estimated for all classes, and then Wolf fitness is calculated via (14),

$$f = \frac{1}{c} \sum_{i=1}^c icv(m)_i \quad (14)$$

where  $c$  represents the total number of classes present in the image sets.

- This fitness is estimated for all Wolves, and then a Wolf fitness threshold is calculated via (15),

$$f_{th} = \frac{1}{N_w} \sum_{i=1}^{N_w} f_i * L_w \quad (15)$$

- Based on this evaluation, Wolves are reconfigured as per the following conditions,
  - Mark the current Wolf as ‘Alpha,’ if  $f > 2 * f_{th}$
  - Else, mark the current Wolf as ‘Beta,’ if  $f > f_{th}$
  - Else, mark the current Wolf as ‘Gamma,’ if  $f > f_{th} * L_r$

- Else, mark the Wolf as ‘Delta’ and use it for optimization processes

- Regenerate all Wolves that are marked as ‘Delta’ as per (12), (13), and (14)
- Reconfigure all ‘Gamma’ & ‘Beta’ Wolves by replacing their features from ‘Beta’ & ‘Alpha’ Wolves respectively, where variance levels are higher, as per (16)

$$f(\text{New}) = f(\text{Old}) |_{f > f_{th}} \quad (16)$$

where  $f(\text{New})$  represents new features for ‘Gamma’ and ‘Beta’ Wolves, while  $f(\text{Old})$  represents highly variant features from respective ‘Beta’ and ‘Alpha’ Wolf configurations [62].

- This process is repeated for  $N_i$  iterations. At the end of the final iteration, select unique features from all ‘Alpha’ Wolves, and use their respective transform images for further augmentation. The chosen transform images from different bands are fused via a BFO-based optimization model that works as per the following process [50],
- To initialize the fusion optimization process, setup the following constants,
  - Total number of bacteria in the swarms (NB)
  - Total iterations used for optimization (NI)
  - Elimination constant ( $C_e$ )
  - Regeneration constant ( $C_r$ )

- Loop through NI iterations and perform the following process,
  - Generate NB bacteria chemotaxis as per the following process,
    - Select  $N$  transformed images for fusion as per (17),

$$N = \text{STOCH}(C_r * NI, NI) \quad (17)$$

where  $NI$  represents the total number of highly variant images identified from the GWO process.

- Fuse these images as per Brovey fusion via (18),

$$F_{out} = \frac{F_{in}}{\sum_{i=1}^B I_i} * P \quad (18)$$

where,  $F_{in}$  &  $P$  represents input multispectral & panchromatic image bands, while  $B$  represents total bands in the multispectral images.

- For each of these images, convolutional features are extracted via (10), and then their intra-class variance is estimated via (19),

$$iccv(m) = \sqrt{\frac{\sum_{i=1}^m \sqrt{\frac{\sum_{j=1}^n (x_j - \frac{\sum_{k=1}^m x_k)^2}{m}}}{m-1}}{m}} \quad (19)$$

where  $m$  represents total images in the current class,  $iccv$  represents their intra-class variance levels.

- Based on these values, bacteria fitness is estimated via (20),

$$f_b = \left(C_e + \frac{1}{C_r}\right) * \sum_{i=1}^c \frac{iccv(m)_i}{c} \quad (20)$$

- This fitness is estimated for each bacterium, and then their configuration is updated via (21),

$$\begin{aligned} f(New) &= \sum_{i=1}^{NB} -f_b * \exp(-C_e) * \left(C_e + \frac{1}{C_r}\right) \\ &+ \sum_{i=1}^{NB} -iccv(m)_i \\ &* \exp(-C_e) * \left(C_e + \frac{1}{C_r}\right) \end{aligned} \quad (21)$$

- A Bacterium with  $f_b > f(New)$  is passed to the next iteration, while others are reconfigured as per the BFO process [50],
- After repeating this process for NI iterations, select bacteria configurations with maximum fitness levels. The selected bacterium represents fused images that can be used for efficient augmentation operations. These operations are controlled via a Particle Swarm Optimization (PSO) Model that selectively performs different augmentations. This PSO Model works via the following process [51],
- Initially set up following PSO constants for efficient augmentations,
  - Total optimization iterations ( $N_i$ )
  - Total optimization particles ( $N_p$ )
  - The cognitive learning rate for these particles ( $L_c$ )
  - The social learning rate for these particles ( $L_s$ )
- To start the PSO optimization process, generate  $N_p$  particles as follows,
  - Select N augmentation operations as per (22),

$$N = STOCH(L_c * NA, NA) \quad (22)$$

where NA represents the total number of operations available to perform augmentations, and NA ∈ (Shift, Scale, Rotate, Zoom, Brightness) [52]

- Based on this value of N, perform the augmentation and estimate the accuracy of augmentation via the CNN-based classification model [59], which is depicted in Fig. 2 as follows:
- The CNN model [59] extracts convolutional features from the input images and then uses a series of Max Pooling and Dropout operations.
- These operations use a Max Pooling threshold which is estimated as per (23),

$$f_{th} = \left(\frac{1}{X_k} * \sum_{x \in X_k} x^{pk}\right)^{1/pk} \quad (23)$$

where X represents the extracted convolutional features and p represents dropout probability levels.

TABLE 1. Parameters used in the training model.

Sr. No	Parameters	Value
1	Total layers	16
2	Window size	8, 16, 32, 64, 128, 256
3	Kernel size	3, 5, 7, 9, 11, 13, 15
4	Activation function	Softmax

- The selected features are classified via a fully connected neural network (FCNN) based classification layer that uses Soft Max activations as per (24),

$$c_{out} = SoftMax\left(\sum_{i=1}^{N_f} f_i * w_i + b\right) \quad (24)$$

where  $w$  &  $b$  represent weights and biases of the convolutional layers.

- Based on these operations, particle fitness levels are estimated as per (25),

$$f_p = \sum_{i=1}^N \frac{C_i}{T_i} \quad (25)$$

where  $C$  &  $T$  represent correctly classified and total images used for the classification process, respectively.

- This fitness is estimated for all particles.
- Current fitness is marked as ‘Particle Best,’ while the highest fitness is marked as ‘Global Best’ levels.
- Now, loop through  $N_i$  iterations, and perform the following tasks,
  - Update the number of augmentation operations in each particle [51] via (26),

$$\begin{aligned} A(New) &= A(Old) + L_c * s_1 * |A(Old) - PBest| \\ &+ L_s * s_2 * |A(Old) - GBest| \end{aligned} \quad (26)$$

where, A (Old) & A(New) represents old and new augmentation operations, while  $s_1$  &  $s_2$  represents two stochastic number sets.

- At the end of the final iteration, identify the particle with the highest fitness levels and use its augmentation operations to optimize classification performance for satellite image sets.

Based on these optimization processes, the model can identify efficient augmentation operations that can effectively classify different satellite images. This performance is estimated in terms of classification accuracy, precision, recall, and computational delay in the next section of this manuscript.

The parameters used in the training models have been listed in Table 1.

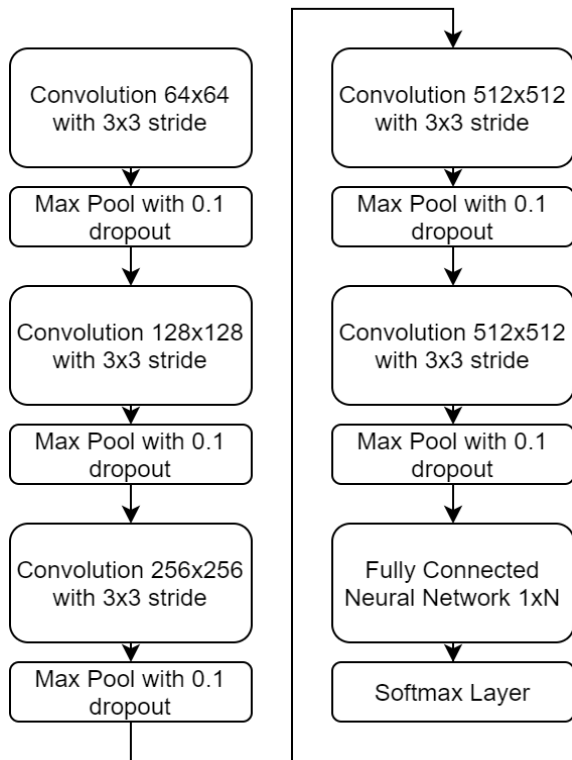


FIGURE 2. Design of the CNN model for classification operations.

**IV. THE RESULT ANALYSIS & COMPARISON WITH STANDARD AUGMENTATION TECHNIQUES**

The proposed model initially uses a multimodal image representation framework capable of extracting Wavelet components, Fourier Components, Cosine Components, Laplacian Components, Mellin Transformations, and Z Transformations. These image sets are processed via a GWO-based image selection framework that uses convolutional feature sets for efficient inter-class image representations. These selected image sets are further optimized via a BFO-based intra-class feature variance optimization process. Due to the use of GWO and BFO, the image-chosen are observed to have higher variance levels, which assists in optimizing classification performance. These selected images are augmented via a PSO-based optimization process, which helps choose efficient augmentation operations validated by a CNN-based classifier to maximize accuracy levels. To evaluate the performance of this model, it was validated on the following datasets,

Sentinel image sets obtained from Google Earth Engine

- Copernicus image sets obtained from Kaggle
- IEEE data port sets for different areas

These sets were aggregated to form 300k images, of which 70% were used to train the model, while 15% each was used for validation & testing purposes. Based on this evaluation, the accuracy of the classification [60] ( $A_c$ ) was estimated

TABLE 2. Classification accuracy for different satellite image sets.

VTI	$A_c$ AEN [4]	$A_c$ SAB SCNN [19]	$A_c$ SI GAN [37]	$A_c$ MBA HIL
1k	88.10	88.34	85.81	95.00
2k	88.25	88.68	86.05	95.26
3k	88.40	89.00	86.29	95.53
5k	88.55	89.34	86.53	95.79
10k	88.71	89.68	86.76	96.05
25k	88.86	90.00	87.00	96.31
50k	88.99	90.34	87.24	96.57
75k	89.14	90.68	87.47	96.83
100k	89.29	91.02	87.71	97.09
125k	89.44	91.35	87.95	97.35
150k	89.60	91.68	88.19	97.61
200k	89.74	92.02	88.43	97.88
250k	89.90	92.35	88.66	98.14
300k	90.04	92.69	88.91	98.40

via (27),

$$A_c = \frac{S_c}{S_T} \tag{27}$$

where  $S_C$  &  $S_T$  are the total number of correctly classified satellite image sets and used image sets, respectively. Results of these augmentations can be observed in Fig. 3(a), Fig. 3(b), and Fig. 3(c), wherein different satellite images were used for the scene classification process.

Based on similar image sets, these accuracy levels were estimated for all validation & test images (VTI) and were compared with AEN [4], SAB SCNN [19], and SI GAN [37] in Table 2 as follows:

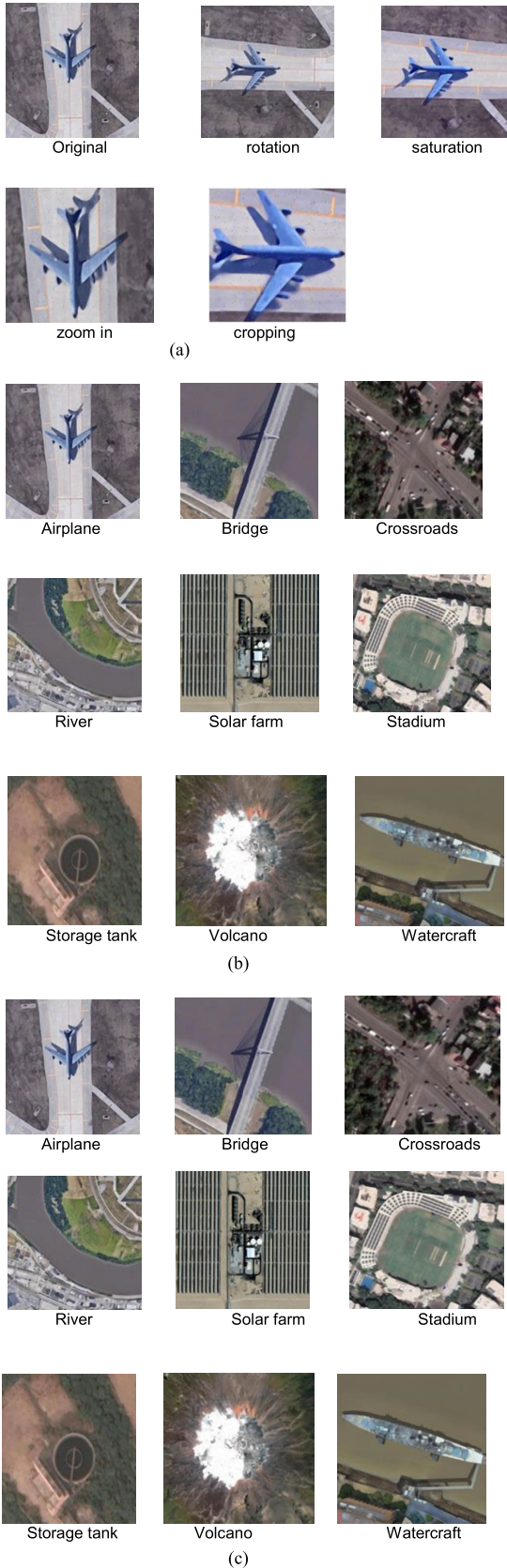
As per this analysis and Fig. 4, it can be observed that the proposed model is capable of improving the accuracy of classification by 9.2% when compared with AEN [4], 6.1% when compared with SAB SCNN [19], and 10.6% when compared with SI GAN [37] under different image sets. This is possible due to the incorporation of accuracy during the selection of PSO-based augmentation operations. Due to this, the model can showcase superior accuracy performance under large image sets. Similarly, the precision of classification [60] was evaluated via (28),

$$P_c = \frac{S_{CI}}{S_T} \tag{28}$$

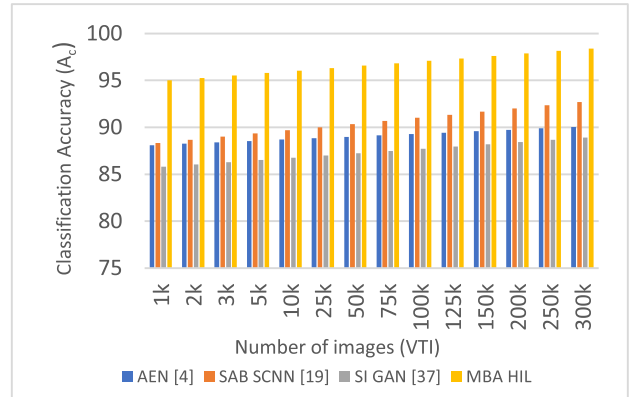
where  $S_{CI}$  and  $S_T$  represents the total number of correctly identified images in the incorrect category and the total number of images used for the classification process. This precision can be observed in Table 3 as follows:

As per this analysis and Fig. 5, it can be observed that the proposed model is capable of improving the precision of classification by 10.4% when compared with AEN [4], 3.9% when compared with SAB SCNN [19], and 7.3% when compared with SI GAN [37] under different image sets.

This is possible due to the incorporation of inter-class variance levels during the selection of fusion operations and



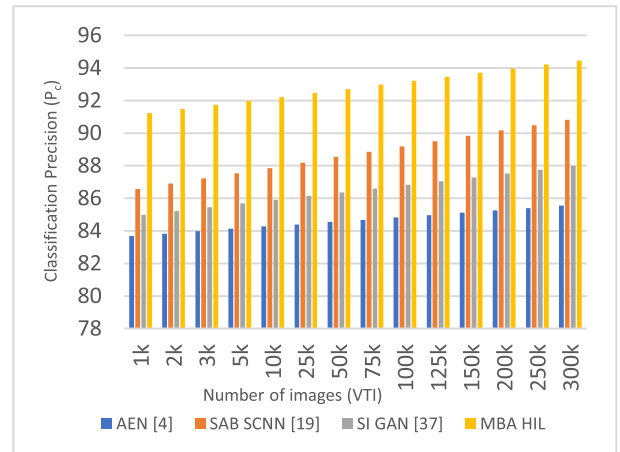
**FIGURE 3.** (a) Use of basic transformation techniques for augmentation. (b) Some scene classifications of the augmented image sets. (c) Use of the augmentation for different application sets.



**FIGURE 4.** Classification accuracy for different satellite image sets.

**TABLE 3.** Classification precision for different satellite image sets.

VTI	Pc			
	AEN [4]	SAB SCNN [19]	SI GAN [37]	MBA HIL
1k	83.68	86.58	84.98	91.24
2k	83.83	86.90	85.21	91.48
3k	83.98	87.22	85.45	91.74
5k	84.13	87.54	85.69	91.98
10k	84.27	87.86	85.91	92.22
25k	84.40	88.19	86.14	92.47
50k	84.54	88.53	86.36	92.71
75k	84.67	88.86	86.60	92.97
100k	84.82	89.19	86.83	93.21
125k	84.96	89.51	87.05	93.46
150k	85.11	89.84	87.29	93.71
200k	85.26	90.17	87.52	93.96
250k	85.40	90.49	87.76	94.21
300k	85.55	90.82	87.99	94.45



**FIGURE 5.** Classification precision for different satellite image sets.

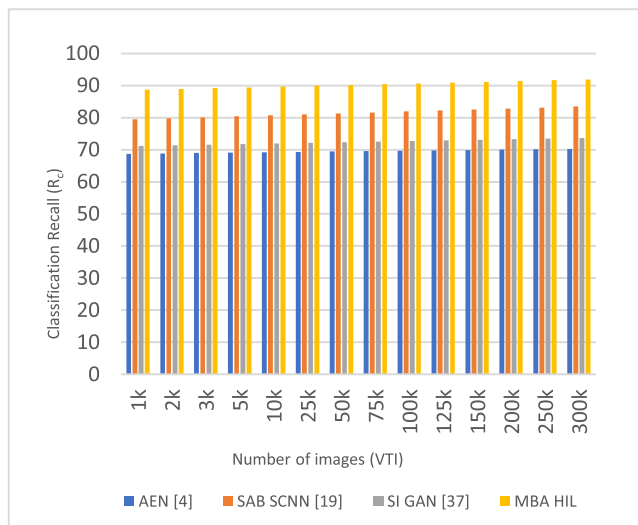
the use of accuracy during the selection of PSO-based augmentation operations. Due to these integrations, the model can showcase superior precision performance under large image sets. Similarly, the recall [60] was evaluated via (29),

$$R_c = \frac{S_{CC}}{S_T} \quad (29)$$



**TABLE 4.** Classification recall for different satellite image sets.

VTI	Rc			
	AEN [4]	SAB SCNN [19]	SI GAN [37]	MBA HIL
1k	68.71	79.47	71.17	88.67
2k	68.84	79.78	71.38	88.93
3k	68.97	80.08	71.57	89.19
5k	69.09	80.39	71.76	89.43
10k	69.21	80.69	71.95	89.67
25k	69.33	81.00	72.14	89.91
50k	69.43	81.31	72.33	90.16
75k	69.53	81.61	72.52	90.40
100k	69.65	81.92	72.72	90.64
125k	69.76	82.22	72.93	90.89
150k	69.88	82.53	73.13	91.13
200k	70.01	82.83	73.32	91.38
250k	70.13	83.14	73.52	91.63
300k	70.26	83.44	73.71	91.87

**FIGURE 6.** Classification recall for different satellite image sets.

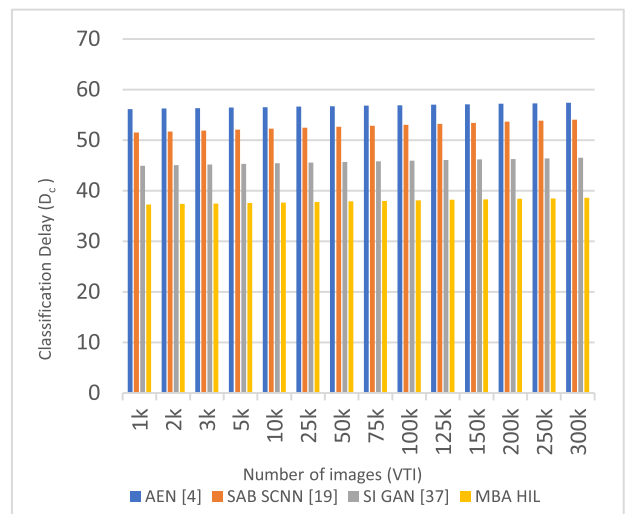
where  $S_{CC}$  represents the total number of satellite images correctly identified into correct categories. The recall levels can be observed in Table 4 as follows:

As per this analysis and Fig. 6, it can be observed that the proposed model is capable of improving recall of classification by 30.7% when compared with AEN [4], 10.1% when compared with SAB SCNN [19], and 24.6% when compared with SI GAN [37] under different image sets. This is possible due to the use of intra-class & inter-class variance levels during the identification of multimodal sets and the selection of fusion operations, with the help of accuracy during the selection of PSO-based augmentation operations. Due to these integrations, the model can showcase superior recall performance under large image sets. Similarly, the classification delay can be observed from Table 5 as follows:

As per this analysis and Fig. 7, it can be observed that the proposed model is capable of decreasing the classification delay by 32.7% when compared with AEN [4], 28.5% when compared with SAB SCNN [19], and 17.04% when compared with SI GAN [37] under different image sets.

**TABLE 5.** Classification delay for different satellite image sets.

VTI	Dc			
	AEN [4]	SAB SCNN [19]	SI GAN [37]	MBA HIL
1k	56.11	51.49	44.92	37.25
2k	56.21	51.69	45.05	37.36
3k	56.31	51.88	45.18	37.46
5k	56.41	52.07	45.30	37.56
10k	56.51	52.26	45.42	37.66
25k	56.61	52.45	45.54	37.76
50k	56.70	52.64	45.66	37.87
75k	56.79	52.83	45.78	37.97
100k	56.89	53.03	45.90	38.07
125k	56.99	53.23	46.02	38.18
150k	57.08	53.42	46.15	38.28
200k	57.18	53.62	46.27	38.38
250k	57.28	53.81	46.39	38.48
300k	57.38	54.01	46.52	38.59

**FIGURE 7.** Classification delay for different satellite image sets.

This is possible due to the identify optimum image sets for classification under various satellite image types. Due to these integrations, the model can showcase high-speed performance under large image sets. This makes the model highly useful for a wide variety of classification scenarios.

## V. CONCLUSION

Our research has observed that data augmentation is a significant way to keep a model from becoming too good at what it does and to lower the cost of labeling and cleaning the raw dataset. This study proposed a new bio-inspired model for improving the augmentation of hyperspectral imagery that uses the domains of Fourier, Laplacian, Cosine, multi-modal Wavelet, Mellin, and Z-Transform. In our findings, we observed that Particle Swarm Optimization helps to find the best values for the parameters of geometric transformations, such as rotation, shifting, etc. When we compared our proposed model with existing models like AEN, SAB SCNN, and SI GAN, we learned that it improved the classification

accuracy by 9.2%, 6.1%, and 10.6%, respectively. With the incorporation of inter-class variance levels during the selection of fusion operations and the use of accuracy during the selection of PSO-based augmentation operations, we noticed that the proposed model has improved classification precision by 10.4%, 3.9%, and 7.3% as compared to AEN, SAB SCNN, and SI GAN, respectively, for different image sets. Furthermore, we observed that the proposed model could improve recall of classification by 30.75% compared with AEN, 10.1% with SAB SCNN, and 24.6% with SI GAN due to the use of intra-class & inter-class variance levels during the identification of multimodal sets, and selection of fusion operations, with use of accuracy during the selection of PSO based augmentation operations.

The model can be further improved by combining low-complexity and high-density feature extraction techniques as a future enhancement. We can improve classification performance using hybrid bioinspired models, autoencoders, gated recurrent units (GRUs), or other deep-learning methods.

#### AUTHOR CONTRIBUTIONS

All authors have contributed equally to this work.

#### CONFLICTS OF INTEREST

The authors declare no conflict of interest.

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