n this issue, "25 Years Ago" revisits the article "Bat-Like Sonar for Guiding Mobile Robots" by Roman Kuc and Billur Barshan in *IEEE Control Systems Magazine*, vol. 12, no. 4, pp. 4–12, 1992. Below is an excerpt from the article.

PREY-CAPTURE ABILITY OF BATS

ow do bats manage to catch insects? While the basic ideas have been known for some time [1], the availability of improved instrumentation has allowed this question

Digital Object Identifier 10.1109/MCS.2017.2697211 Date of publication: 18 July 2017

The prey capture ability of bats impacts directly on the problem of docking two robots.

to be reexamined by neuroscientists [2] and psychologists [3], [4], exploring the perception of the sonar signals and their mapping in the brain. From the engineering perspective, bat echolocation was analyzed by applying optimum correlation detection for binaural estimation of travel time and prey location [5]. Attempts are being made at applying some of these principles into hardware [6]. The same question is also relevant in the field of robotics. The prey capture ability of bats impacts directly on the problem of docking two robots, which is becoming important in multi-robot systems. This problem has been investigated by using infrared sensors [7] and by using camera vision [8]. We demonstrate that sonar can also accomplish docking. The main problem with current sonar systems, however, is that they do not work very reliably in unstructured environments. Problems arise

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