


Retrieval of Surface Temperature and Emissivity From Ground-Based Time-Series Thermal Infrared Data

Yonggang Qian , Ning Wang, Kun Li, Hua Wu , Sibao Duan, Yaokai Liu, Lingling Ma , Caixia Gao, Shi Qiu, Lingli Tang, and Chuanrong Li

I. INTRODUCTION

Abstract—This article addressed the simultaneous retrieval of land surface temperature (LST) and emissivity (LST&E) from the time-series thermal infrared data. On the basis of the assumption that the time-series LSTs can be described by a piecewise linear function, a new method has been proposed to simultaneously retrieve LST&E from atmospherically corrected time-series thermal infrared data using LST linear constraint. A detailed analysis has been performed against various errors, including error introduced by the method assumption, instrument noise, initial emissivity, atmospheric downwelling radiance error, etc. The proposed method from the simulated data is more immune to noise than the existing methods. Even with a noise equivalent delta temperature of 0.5 K, the root-mean-square error of LST is observed to be only 0.13 K, and that of the land surface emissivity (LSE) is 1.8E-3. In addition, our proposed method is simple and efficient and does not encounter the problem of singular values unlike the existing methods. To validate the proposed method, a field experiment from June to September 2017 was conducted for sand target in Baotou site, China. The results show that the samples have an accuracy of LST within 0.87 K and that the mean values of LSE are accurate to 0.01.

Index Terms—Land surface temperature (LST), emissivity, time series, thermal infrared data.

LAND surface temperature (LST) is one of the key parameters in the physics of land surface processes, combining the surface–atmosphere interactions and the energy fluxes between the atmosphere and the ground [1]. LST is required for a wide variety of scientific studies—from climatology to hydrology to ecology and biogeology, such as the energy budget modeling and evapotranspiration modeling, estimating soil moisture, frost detection and forecasting, monitoring the state of the crops [2], studying land and sea breezes, and nocturnal cooling. LST is also a good indicator of the greenhouse effect, and the radiative transfer simulations based on the observed surface temperature data show a positive correlation between the normalized greenhouse effect and the surface temperature [3]. Accurate LSTs would not only help to estimate surface energy and water balances, thermal inertia, and soil moisture [4], [5], it would also enable an analysis of the global surface temperature and its variability within a long period of time.

One key parameter to derive LST is land surface emissivity (LSE). LSE is the ratio of the radiance emitted by an actual land surface at some temperature to the theoretical radiance emitted by a blackbody at the same temperature. It is a measure of a material's ability to absorb and radiate energy. LSE is an intrinsic property of the surface and is almost independent of the temperature under natural conditions [6], e.g., the channel-averaged emissivity in AVHRR channel 3 for coarse sand changes only 0.004 over the temperature range of 240–320 K [7]. LSE can also support more accurate retrievals of atmospheric properties, such as temperature and moisture profiles from multispectral satellite radiance measurements.

Many land surface temperature and emissivity (LST&E) retrieval methods from the remotely sensed multiple thermal infrared data have been proposed [8], [9]. The temperature-emissivity separation methods include the classification-based emissivity retrieval method [10], the reference channel method [11], the emissivity normalization method [12], the spectral ratio method [13], the alpha emissivity method [14] and the physics-based emissivity-temperature decoupling method based on the temperature-independent spectral indices concept [6], the iterative spectrally smooth temperature and emissivity separation (ISSTES) method [15], [16], and the stepwise refining algorithm of temperature and emissivity separation method [17].

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LST retrieval algorithms are based on the radiative transfer theory.

In this article, an LST&E retrieval method has been proposed from the ground-based time-series single-band TIR data. This article is organized as follows. Section II describes the theoretical method, including the basic theory and the separation of LST&E. Section III introduces the time-series data measured by thermometers. In Section IV, the sensitivity analysis of the new method with respect to measurement noise and uncertainty of LSE and atmospheric downwelling radiance. The new method is applied to the soil and vegetation areas in Section V, and finally, the conclusion is given.

II. METHOD

A. Thermal Radiative Transfer Equation

According to the radiative transfer theory, for a cloud-free atmosphere under local thermodynamic equilibrium, the TIR channel radiance L received by the sensor can approximately be written as [18]

$$L(T) = \tau \varepsilon B(T_s) + \tau(1 - \varepsilon)L_{\text{atm}\downarrow} + L_{\text{atm}\uparrow} \quad (1)$$

where T is the at-sensor brightness temperature, ε is the LSE, τ is the channel atmospheric transmittance, $B(T_s)$ is Planck's function at T_s , $L_{\text{atm}\uparrow}$ is the upwelling atmospheric channel radiance, and $L_{\text{atm}\downarrow}$ is the channel downward atmospheric radiance, defined as $1/\pi$ times the total downward atmospheric radiance.

It is obvious that the retrieval of LST&E from (1), the atmospheric parameters including τ , $L_{\text{atm}\downarrow}$, and $L_{\text{atm}\uparrow}$ should be removed first. The equation can be written as follows after atmospheric correction:

$$L_g(T_g) = \varepsilon B(T_s) + (1 - \varepsilon)L_{\text{atm}\downarrow}. \quad (2)$$

$L_g(T_g)$ is the at-ground channel radiance. T_g is the brightness temperature at the ground level. In this article, to validate the feasibility of the proposed method, the ground-based measurement data are used for analysis in following section.

B. Retrieval of LST and Emissivity From Time-Series Data

For a sensor with N infrared spectral channels, there are N measurements but $N + 1$ unknown (N channel emissivities plus one surface temperature). For resolving this ill-posed problem, additional assumptions are necessary to constrain the extra degree of freedom, which has led to different temperature-emissivity separation methods [19], [20]. There are generally two ways to solve this ill-posed problem [21]. In this article, the ill-posed problem is that for a sensor with one infrared channel and N time-series measurement data, there are N measurements but $N + 1$ unknown (one channel emissivity plus N time-series temperatures). To solve the ill-posed problem, one could fit the time-series LSTs with a polynomial curve to reduce the number of unknowns. Thus, we assumed that the relationship between the time-series temperature and time can be expressed as a piecewise linear function.

By assuming that there are N time-series TIR data, accordingly, there are N LSTs. As shown in Fig. 1, by dividing the

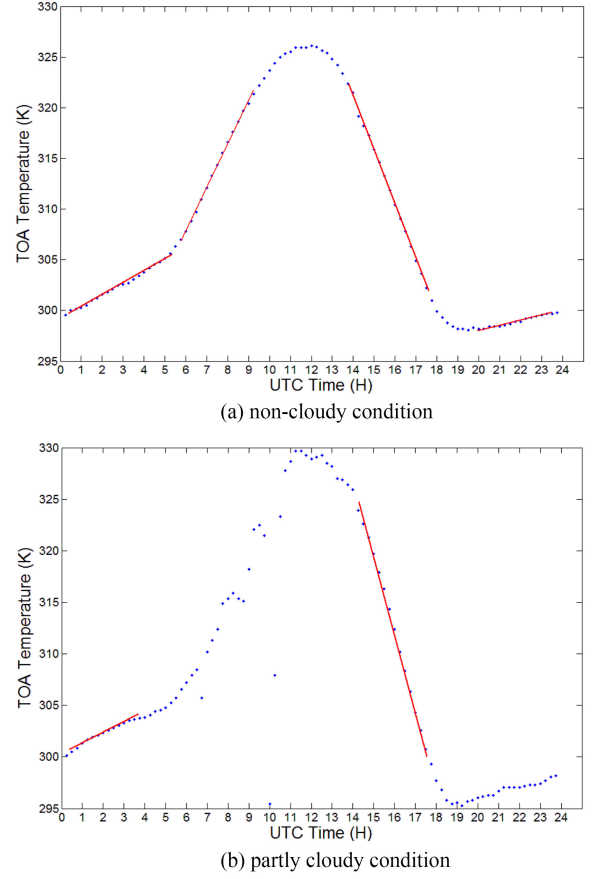


Fig. 1. Sketch map of the piecewise linear time-series temperatures for noncloudy condition. (a) Partly cloudy condition. (b). Blue dot is the actual time-series LST and the red lines are the fitting lines.

time-series LSTs into M sections, with each section containing C_i LSTs, the whole time-series can be fitted by M lines, such as the red lines shown in Fig. 1. Thus, the time-series LSTs can be expressed by a group of linear equations as

$$T_{i,j} = T_{0,j} + k_j \cdot (t_{i,j} - t_{0,j}) \quad (3)$$

where $T_{0,j}$ and k_j are the intercept and slope in j section. $t_{0,j}$ is the beginning time in j section and $t_{i,j}$ is the time at i o'clock in j section. $j = 1, 2, \dots, M$, $i \in [\Sigma C_i, \Sigma C_{i+1}]$.

Assumed that the atmospheric correction has been performed well. The LST&E retrieval method proposed using the single TIR band with the time-series measurement data can be expressed as the following:

$$\begin{cases} L_g^{t_1}(T^{t_1}) = \varepsilon B(T_s^{t_1}) + (1 - \varepsilon)L_{\text{atm}\downarrow}^{t_1} \\ L_g^{t_2}(T^{t_2}) = \varepsilon B(T_s^{t_2}) + (1 - \varepsilon)L_{\text{atm}\downarrow}^{t_2} \\ L_g^{t_3}(T^{t_3}) = \varepsilon B(T_s^{t_3}) + (1 - \varepsilon)L_{\text{atm}\downarrow}^{t_3} \\ \dots \\ L_g^{t_n}(T^{t_n}) = \varepsilon B(T_s^{t_n}) + (1 - \varepsilon)L_{\text{atm}\downarrow}^{t_n} \\ T_{i,j} = T_{0,j} + k_j \cdot (t_{i,j} - t_{0,j}) \end{cases} \quad (4)$$

where t_1, t_2, \dots, t_n is the observation time.

The number of each group time-series LSTs should be larger than or at least equal to three because a linear function fitted with only two times cannot provide additional useful information to meet the aim of reducing the number of unknowns [21].

Obviously, the introduction of the piecewise linear fitting function makes the ill-posed problem to have a deterministic solution because, now, there are N equations to solve $2M + 1$ unknowns (M intercepts, M slopes, and one emissivity). The criterion (cost function) is defined as the sum of the square of the residual errors of the at-ground radiance between the calculated and the actual ones, i.e.

$$f = \sum_i^M \sum_j^{C_i} [\langle L_g(T_{i,j}) \rangle - L_g(T_{i,j})]^2. \quad (5)$$

Next, the least square technique is employed to find the best-fitting temperature and emissivity. To avoid the unordinary cases, a series of error terms, including the least square error of the difference between measured and calculated at-sensor radiances across the spectral range, limit temperature range to a range of temperature to avoid retrieval of high temperatures and low emissivities, “penalty” function, etc., are given in the ARTEMISS algorithm. The error function helps to avoid solutions where the retrieved emissivities are close to zero and have very large temperatures.

III. DATA

A. Time-Series Data Simulated From MODTRAN

A simulation dataset is used with different atmospheres and land surface conditions from MODTRAN 5.0. Six MODTRAN standard atmospheric profiles of temperature, moisture, and ozone have been used, covering a wide range of bottom atmospheric temperature and total precipitable water. Meanwhile, 150 atmospheric profiles with the bottom atmospheric temperature varying between 220 and 320 K and total precipitable water (TPW) with relative humidity at any layer smaller than 90% (see Fig. 2) were extracted from TIGR atmospheric profiles [22]. Emissivity spectra of several representative surface materials, including soil, vegetation, water, and ice, were chosen from the ASTER spectral library [23]. Five subranges of the atmosphere water vapor content (WVC): [0–1.25], [1.25–2.25], [2.25–3.25], [3.25–4.25], and [4.25–5.5] g/cm² are used.

B. Time-Series Data Measured From Soil Area

To evaluate the performance of the method, a comprehensive field campaign was carried out at the Baotou site in September, 2017. The Baotou site (see Fig. 3) is located in Urad Qianqi, Inner Mongolia, in northern China at a latitude of 40.85°N and a longitude of 109.6°E. The land covers in Baotou site included cropland, herbaceous land, shrubland, grassland, sparse vegetation, urban areas, sand, and water body. In this article, its temperature measured for sands was used to validate the retrieval results by using our proposed method. The SI-111 thermometers were distributed within the sand area covered about 1 km² and deployed at nadir to capture the natural variability of the ground radiometric temperature, and the temporal sampling interval is

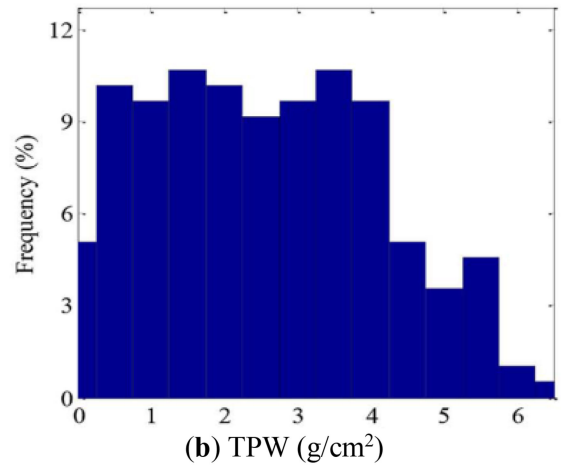
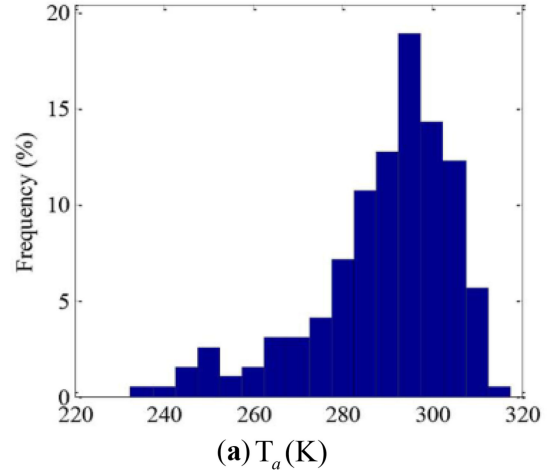


Fig. 2. Histogram of selected atmospheric quantities. (a) Bottom atmospheric temperature. (b) TPW of profiles.

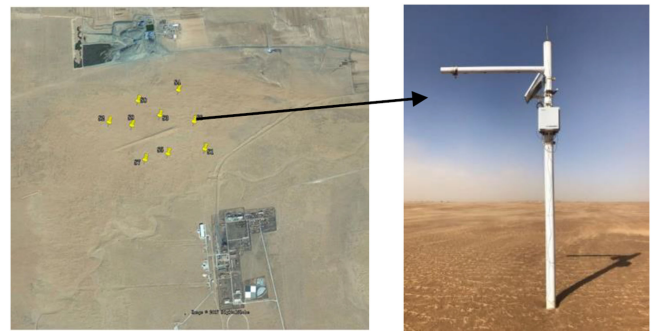


Fig. 3. SI-111 thermometers in the Baotou site.

per minute. Then the continuous LST measurements are used to retrieve the LST&E. The SI-111 thermometer is the spectral range of 8–12 μm and field-of-view (FOV) of 44°.

The radiometric temperatures were measured by the SI-111 thermometers from June to September, 2017. These data will be used for validation of the proposed method. To obtain the actual sand temperature from the field-measured time series data, the environmental downwelling radiance is necessary.

The Baotou site includes the SI-111 radiometers that one vertically measured the surface properties from a 4 m height and the other measured the atmospheric downwelling radiance at an approximately 55° zenith angle [23], [27]. The sampling frequency of the radiometers and the SI-111 radiometers is 1 min. For the SI-111 radiometer measurements, the LST was calculated using the following equation [24], [25]

$$T_s = B^{-1} \left(\frac{L(T) - (1 - \varepsilon) \cdot L_\downarrow}{\varepsilon} \right) \quad (6)$$

where B is the Planck function, T_s is the surface temperature, ε is the surface emissivity, and L_\downarrow is the atmospheric downwelling radiance.

Emissivity measurements were performed using the 102 F Fourier transform infrared spectroradiometer with the spectrum covered from 2 to 16 μm , the spectral resolution of 4 cm^{-1} , and FOV of 4.8° . Then, the spectral emissivity was retrieved using the ISSTES algorithm. Finally, an emissivity value of the SI-111 channel was obtained using the spectral response function [26].

The accuracy of the method is characterized by the root-mean-square errors (RMSEs) of the temperature and the rms of the relative emissivity errors

$$\text{RMSE}_{\text{LST}} = \sqrt{\frac{\sum_{i=1}^M (\text{LST}_{\text{ret}} - \text{LST}_{\text{true}})^2}{M - 1}} \quad (7a)$$

$$\text{RMSE}_{\text{LSE}} = \sqrt{\frac{\sum_{i=1}^M (\text{LSE}_{\text{ret}} - \text{LSE}_{\text{true}})^2}{M - 1}} \quad (7b)$$

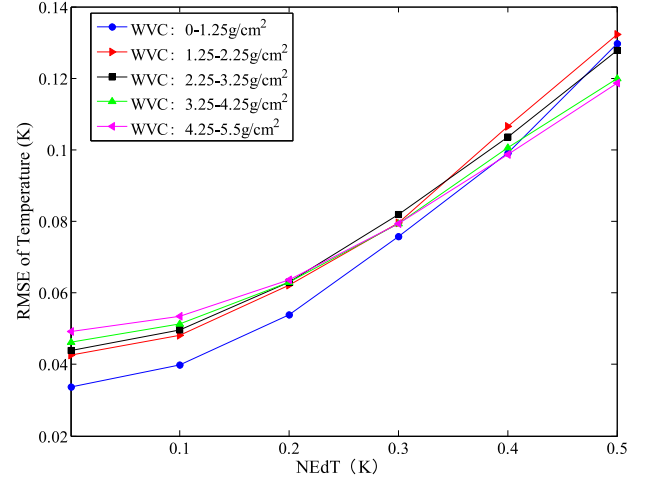
where LST_{ret} and LST_{true} are the retrieved and true temperatures, respectively. LSE_{ret} and LSE_{true} are the retrieved and true emissivities, respectively. M is the total number of measurements. Therefore, the following results will exhibit the performance of the proposed method.

IV. RESULTS AND ANALYSIS

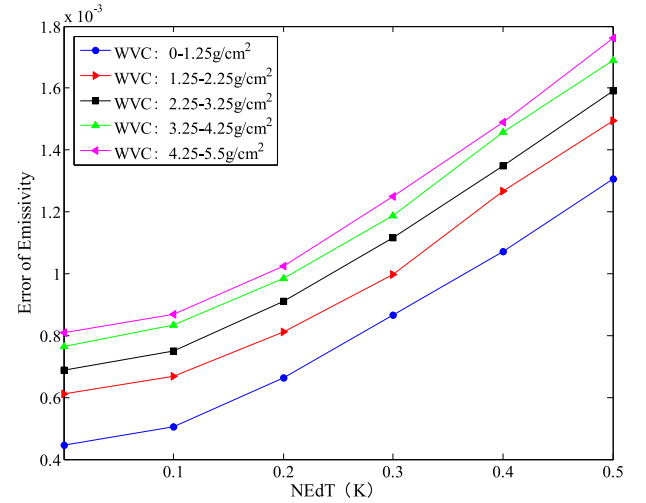
A. Sensitivity Analysis

The accuracy of this method is also influenced by the uncertainty of instrument noise, the uncertainty of initial emissivity, and the error of the atmospheric downwelling radiance. A sensitive analysis of the proposed method was, thus, performed with respect to the uncertainty of these parameters using the simulated data from MODTRAN 5.0.

1) *Effect of Instrument Noise:* The noise equivalent delta temperature (NE Δ T) of the TIR sensor with different levels of instrument noise is used to analyze. To analyze the effect of the instrument noise on LST&E retrieval, a Gaussian-distribution noise with a mean of 0 K and a standard deviation of NE Δ T = 0.1, 0.2, 0.3, 0.4, and 0.5 K was added to the at-ground brightness temperatures. LST&E with the noised at-ground brightness temperatures was estimated, and the RMSEs of LST&E are calculated. The relative error is shown in Fig. 4 between the LSTs retrieved from the non-noise/noise added brightness temperatures.



(a)



(b)

Fig. 4. RMSEs of LST&E caused by instrument noises. (a) LSE of temperature. (b) RMSE of emissivity.

The RMSEs of LST&E are increasing with the increasing NE Δ T; meanwhile the RMSEs of LST&E are also increasing with the increasing WVC. It can be seen that the error is relatively small. Even if the NE Δ T is up to 0.5 K, the largest RMSEs of LST&E are 0.13 K and 1.8×10^{-3} . It is obvious that the errors of the LST&E caused by the NE Δ T are very slight.

2) *Effect of Initial Emissivity:* Initial emissivity is closely related to the LST&E retrieval. To investigate the method's sensitivity to initial emissivity, 0.005, 0.01, 0.015, and 0.02 uncertainties of the initial emissivity of the TIR channel were added in the retrieval of LST using the new method, respectively. In addition, the 0.2 K random noises are added to the at-ground brightness temperatures. The LST&E were retrieved under the five subranges of atmospheric WVCs (see Fig. 5).

The RMSEs of the retrieved LST&E are generally better than 0.6 K and 0.01 under the condition of the 0.01 uncertainty of LSE, respectively. Meanwhile, the RMSEs of the retrieved

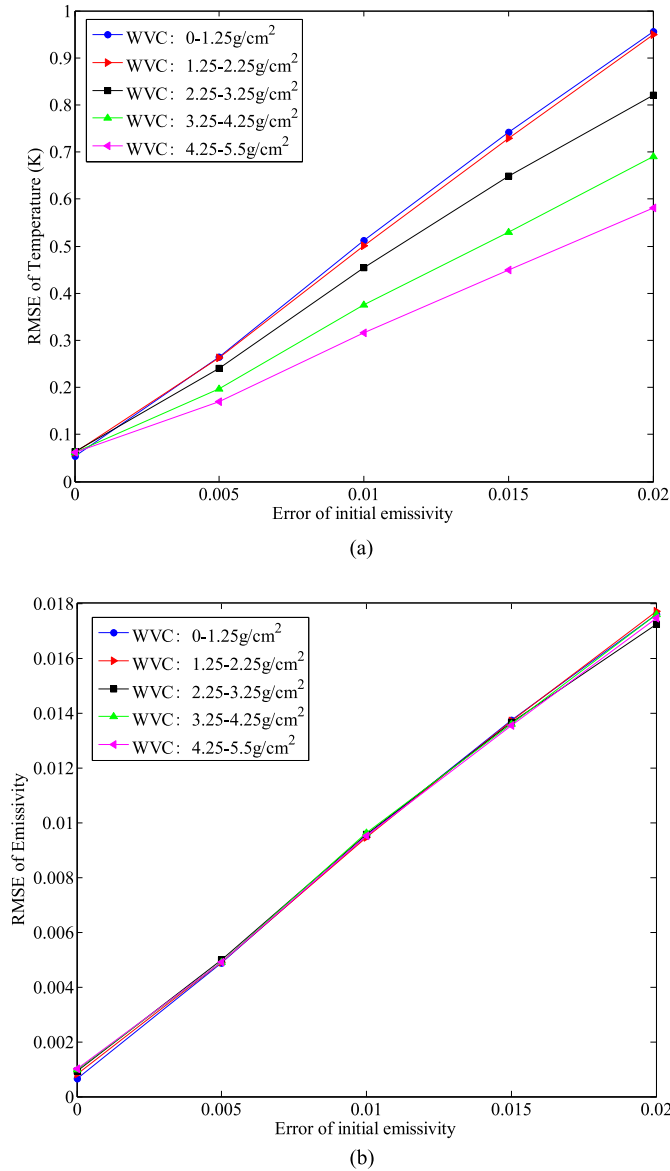


Fig. 5. RMSEs of LST&E caused by emissivity uncertainty. (a) RMSE of temperature. (b) RMSE of emissivity.

LST&E are better than 1.0 K and 0.018 for all the WVC subranges, when the initial emissivity error is 0.02. It should be noted that the RMSE of LST will be increasing with the decreasing of WVC, while there are no significant influences for emissivity for each WVC subranges.

3) *Effect of Initial Atmospheric Downwelling Radiance:* The accuracy of LST&E retrieval is influenced significantly by the error of the atmospheric parameters. As well known, the error of the initial atmospheric downwelling radiance will lead to the inaccuracy of at-surface radiance. Consequently, the inaccuracy will affect the retrieval accuracy of LST&E. Thus, to investigate the effects of uncertainties, 5%, 10%, 15%, and 20% uncertainties of atmospheric downwelling radiance are considered, respectively. In addition, the 0.2 K random noises are added to the at-ground brightness temperatures. Then, the

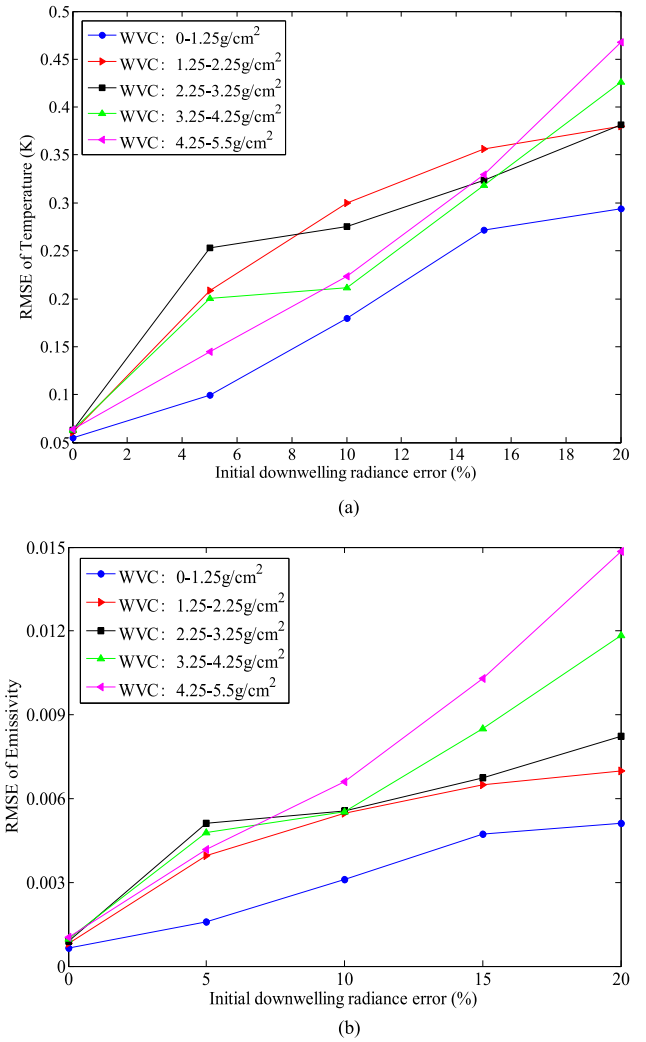


Fig. 6. RMSEs of LST&E caused by initial atmospheric downwelling radiance. (a) RMSE of temperature. (b) RMSE of emissivity.

error-effected at-ground brightness temperatures are used to estimate the LST&E.

The RMSEs of the retrieved LST&E will be increasing with the increase of the initial error of atmospheric downwelling radiance and WVC (see Fig. 6). The RMSEs of the LST&E retrieval results are better than 0.45 K and 0.015 for all WVC subranges under the condition of the 20% uncertainty of initial atmospheric downwelling radiance, respectively. Meanwhile, when the uncertainty of initial atmospheric downwelling radiance is 10%, the RMSEs of the retrieved LST&E are better than 0.3 K and 0.007 for all WVC subranges, respectively. It is obvious that the effect of initial atmospheric downwelling radiance is slight on the errors of the retrieved LST&E.

B. Application to Ground Measured Time-Series Thermal Infrared Data

To evaluate the performance of the proposed method, the time-series thermal infrared data measured by the SI-111 thermometer in Baotou site in 2017 are used. The time range is from

TABLE I
TEMPERATURE AND EMISSIVITY INVERSION RESULTS FROM JUNE TO
SEPTEMBER 2017

Month	Item	Bias	RMSE
June	Temperature	-0.09 K	0.76 K
	Emissivity	0.004	0.014
July	Temperature	-0.12 K	0.58 K
	Emissivity	0.007	0.0135
August	Temperature	-0.033K	0.594K
	Emissivity	0.0037	0.0119
September	Temperature	-0.01 K	0.472K
	Emissivity	0.0015	0.0076

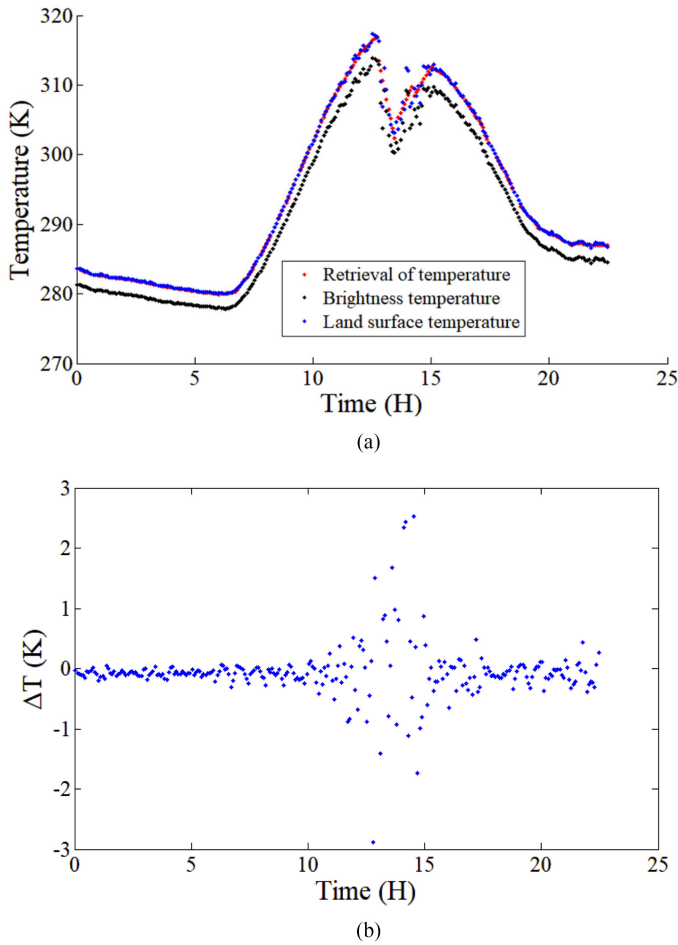


Fig. 7. Results estimated by the proposed method on 6 September, 2017. (a) The temperature inversion result. (b) The error of temperature.

1 June to 30 September, 2017. The temperature and emissivity are estimated by the proposed method. The bias and RMSE of temperature and emissivity are calculated.

Table I gives the monthly statistics of temperature and emissivity inversion results for June, July, August, and September, 2017. It can be seen that the bias of temperature is about -0.1 K and the bias of emissivity is less than 0.007 for every month.

Figs. 7–9 are the detail results for a single day. The results show that the RMSE of temperature inversion is less than 0.5 K.

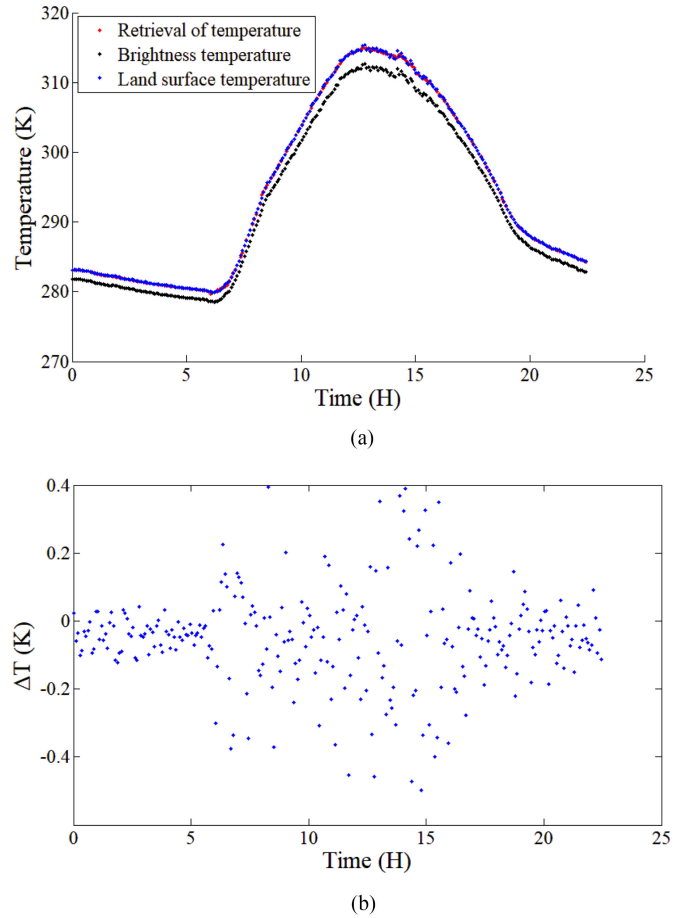


Fig. 8. Results estimated by the proposed method on 8 September, 2017. (a) The temperature inversion result. (b) The error of temperature.

In addition, it can be seen from the graphs that although the cloud exists in some time periods, it does not affect the overall temperature inversion results. From the error graphs, it can be seen that the temperature inversion error in the cloudy time period is much higher, even to the error of 3 K. The time of high error of temperature inversion almost occurs at noon.

Furthermore, to obtain the more detailed LST inversion results, three time segments, i.e., the morning (local time 0:00–12:00), the noon (local time 12:00–15:00), and the afternoon (local time 15:00–24:00), are used for the analysis separately. Table II is temperature inversion results in different time segment from June to September, 2017. The biases and RMSEs are -0.075 K and 0.753 K, respectively, for all days. The biases of the retrieved LST are underestimated for three time segments. The error of the retrieved LST in the morning and afternoon is close for every month. For the results in the noon, the biases of the LST were also larger than those of the LST in the morning and the afternoon, with bias of -0.1 K for noon, 0.049 K for the morning, and 0.074 K for the afternoon; and the RMSEs are 1.14 K for the noon, 0.53 K for the morning, and 0.59 K for the afternoon. The reason for the largest error in noon is that there are more clouds at noon. In addition, the applicability of the method at noon also needs to be further improved. Because the

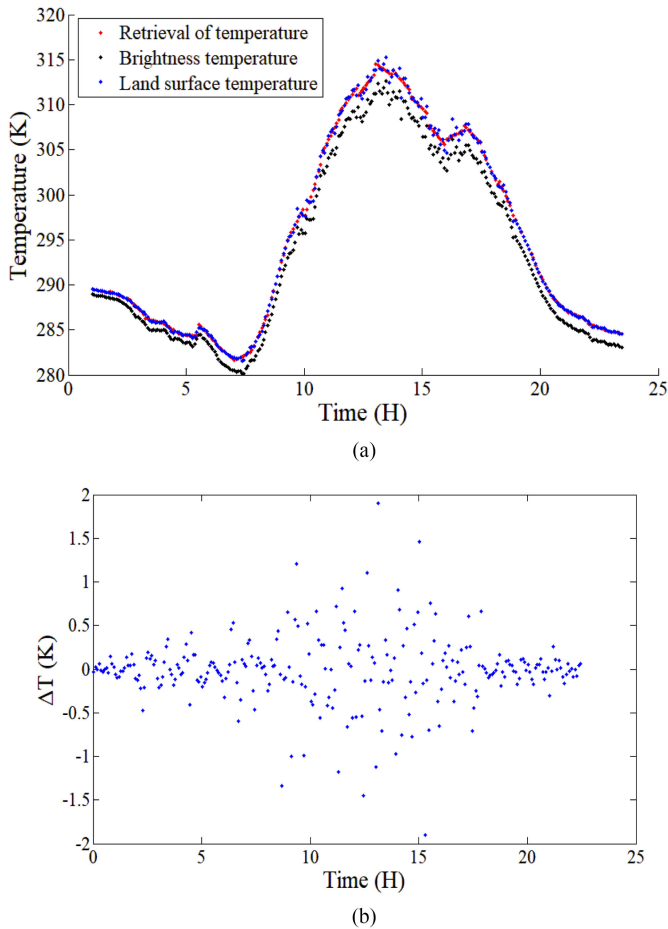


Fig. 9. Results estimated by the proposed method on 9 September, 2017. (a) The temperature inversion result. (b) The error of temperature.

TABLE II
TEMPERATURE INVERSION RESULTS IN DIFFERENT TIME SEGMENT FROM
JUNE TO SEPTEMBER 2017

Month	Time	Bias	RMSE
June	0:00-12:00	-0.0817	0.6744
	12:00-15:00	-0.1212	1.3747
	15:00-24:00	-0.0975	0.7505
July	0:00-12:00	-0.098	0.5043
	12:00-15:00	-0.2055	1.1007
	15:00-24:00	-0.1278	0.5690
October	0:00-12:00	-0.018	0.533
	12:00-15:00	-0.059	1.16
	15:00-24:00	-0.047	0.6584
September	0:00-12:00	-1.6e-4	0.41
	12:00-15:00	-0.023	0.921
	15:00-24:00	-0.024	0.384

temperature variation in the daytime shows the cosine function, especially at noon, however, the piecewise linear assumption to fit the time series temperature in the method. It should be noted that the largest error occurred in June because there are more rainfall and dust in this season and the measured data are affected by these factors.

V. CONCLUSION

In this article, a new method for LST and emissivity retrieval from the thermal infrared time series data is proposed. In this method, we assumed that the time series temperature can be depicted by some piecewise linear functions. In this article, the single-band TIR data are used for retrieval. However, the proposed method can be fit for single-band data or multiband data. The time series temperatures of sand are used to analyze the accuracy of the method.

A detailed analysis has been performed against various errors, including error introduced by the method assumption, instrument noise, initial emissivity, atmospheric downwelling radiance error, etc. As for the impact of the atmosphere, the results show that our proposed method performs well with the uncertainty of the atmospheric downwelling radiance but suffers from the inaccuracy of the atmospheric upwelling radiance, which implies that an accurate atmospheric correction is still needed to convert the radiance measured at the satellite level to the at-ground radiance. The proposed method from the simulated data is more noise immune than the existing methods. Even with a $NE\Delta T$ of 0.5 K, the RMSE of LST is observed to be only 0.13 K and that of LSE is $1.8E-3$. In addition, our proposed method is simple and efficient and does not encounter the problem of singular values unlike the existing methods.

The result shows that the LST&Es estimated by this method with the RMSEs are approximately 0.87 K and 0.0097 using the time-series thermal infrared data measured by SI-111 in Baotou site, China. Furthermore, the detailed LST inversion results according to the three time-segments, i.e., the morning, the noon, and the afternoon, are used for analysis separately. The largest error in the noon with LST RMSE of 1.14 K is shown, and the results in the morning and afternoon with LST RMSE 0.53 K and 0.59 K of are similar. Meanwhile, the LST error in June is largest because there are more rainfall and dust in this season and the measured data are affected by many factors. From this study, although the method has already been proposed, it can also be seen that it is necessary to do more work to accurately acquire LST/LSE from remotely sensed thermal infrared time series data.

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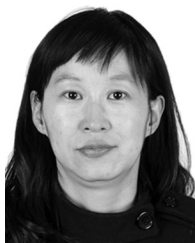
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