Corrections

Corrections to "An Approach to Subjective Computing: A Robot That Learns From Interaction With Humans"

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In the article above [1], the sentence reading "As outlined above, reciprocity holds between $\delta(\hat{r})$ and $\alpha(V \rightarrow \hat{R})$" should read "As outlined above, reciprocity holds between $\delta(\hat{r})$ and $\alpha(C \rightarrow \hat{R})$."

Also, there was mistake in Table I, the corrected table is as follows.

TABLE I
RELATIONAL CONSTRUCTION OF THE COACHED RL AGENT

Observable \ Domain	D_0 : *algorithmic*	D_1: *functional*	D_2: *mental*
Interface	$\hat{r}$	AF	$\delta(AF)$
Interpretation	C	ER	$\alpha(ER)$
Learning	$\hat{R}$	IP	$\alpha(IP)$
Relational arrangement	$\delta(\hat{r}) \rightleftarrows \alpha(C \rightarrow \hat{R})$	$\delta(AF) \rightleftarrows \alpha(ER \rightarrow IP)$	

The notations are defined as follows:

D_0: $\hat{r}$ reward value; C contingency and causality detection; $\hat{R}$ updated reward function.

D_1: AF allocation of feedback; ER estimation of relevance; IP improvement of performance.

Relational arrangement: $\alpha(x)$ means x is self-referentially arranged;

$\delta(x)$ means that the agent is directly coupled to x; $\delta(x) \rightleftarrows \alpha(y)$ means x and y are reciprocal.

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[1] P. Grüneberg and K. Suzuki, "An approach to subjective computing: A robot that learns from interaction with humans," *IEEE Trans. Automon. Mental Develop.*, vol. 6, no. 2, pp. 5–18, Mar. 2014.