Green Time-Critical Fog Communication and Computing

Hanna Bogucka, Bartosz Kopras, Filip Idzikowski, Bartosz Bossy, and Paweł Kryszkiewicz

The authors examine the latency and energy consumption sources in fog networks and discuss models describing these costs for various technologies.

ABSTRACT

Fog computing allows computationally-heavy problems with tight time constraints to be solved even if end devices have limited computational resources and latency induced by cloud computing is too high. How can energy consumed by fog computing be saved while obeying latency constraints and considering not only computations but also transmission through wireless and wired links? This work examines the latency and energy consumption sources in fog networks and discusses models describing these costs for various technologies. Next, resource allocation strategies are discussed considering the various degrees of freedom available in such a complex system, and their influence on energy consumption and latency. Finally, a vision for a future distributed, Al-driven resources allocation strategy is presented and justified.

Introduction

Together with the rapid development of modern Information and Communication Technologies (ICT), the energy consumption of these technologies increases. Although the ICT sector's emissions are predicted to stabilize at 1.25 GtCO2e in 2030 [1], the energy cost of communication and computing services is continuously subject to minimization by the service providers and consumers. This is why energy efficiency is a key paradigm for modern contemporary and future networks, including the Fifth Generation (5G) and Sixth Generation (6G) systems. These networks and services involve both Communication and Computing (2C) of information across the network, and thus, 2C services should be handled (optimized) jointly.

The idea of fog or edge computing is proposed for 5G/6G communication systems and future ICT networks [2]. This technology is essentially a hierarchical, balanced network organization where communication and computing tasks can be performed flexibly using diverse resources available in a network. Fog is an architecture that distributes communication and computation services along the cloud-to-things continuum [2]. It includes information processing, storage, control, and networking to serve many growing applications. A representative instance of the fog network is shown in Fig. 1. Things, such as cars, cellphones, and other linked devices, are present in the things tier. Powerful data servers are deployed in the cloud layer. Connected computing devices (PCs, servers, computing clusters, etc.) that can process, communicate, and store data are located in the fog tier. Multiple hierarchical levels may exist in the fog tier. Collaboration including both vertical and horizontal communication is possible between them.

The execution of a task can be assigned to a (near or distant) fog node, the cloud, or carried out locally, depending on the Quality of Service (QoS) metrics that need to be guaranteed for that task. Information flow is depicted in Fig. 1 for a few examples of use cases, including vehicular communication, remote control in industrial or medical settings (usually Ultra-Reliable, Low-Latency Communication (URLLC)), task offloading from a device with low processing power and memory, content cashing (typically enhanced Mobile BroadBand communication (eMBB)), or telemetry data flow (usually massive Machine-Type Communication (mMTC)).

The objective of this work is to improve the energy efficiency of fog networks for mission-critical applications, that is, those constrained by the deadline of task execution. We:

- Jointly optimize resource allocation for communication and computing
- Consider various task allocation schemes
- Consider the adaptation of clock frequency and packet generation rate
- Discuss resource allocation with Artificial Intelligence (AI).

In the following section, we provide an overview of the causes (devices and processes) of energy consumption in wireless and wired parts of a network and computing machines. Following that, we present options for energy consumption minimization with latency and Age of Information (AoI) constraints as well as representative use cases and optimization results. Then we discuss Al-based practical methods for reducing the energy consumption of a fog network. We conclude our work in the final section.

KEY DEVICES AND PROCESSES AFFECTING ENERGY CONSUMPTION AND LATENCY IN FOG NETWORKS

The decision of where to process a computing task from the perspective of energy consumption and latency is affected by the performance of: the wireless part of the network, the wired part of the network, and the devices performing computations themselves.



The authors are with Poznan University of Technology, Poland.

WIRELESS ACCESS NETWORKS

Energy consumption depends on numerous factors, including the number of bits to be transmitted, required bitrate, transmission channel properties, for example, path loss, fading, and the utilized wireless transmission standard, for example, 5G or WiFi with its configuration. The most common approach to the modeling (limited in its application range) is to perform measurements of a wireless transceiver under various conditions, for example, payload and path loss, and extrapolate the values to cover other use cases as well. The main drawback of this approach is characterization limited to a single device. The other approach is to characterize every single element of a wireless transceiver in terms of its energy consumption, for example, Analog-Digital Converter (ADC) and coder. However, this results in a multi-parameter model which is difficult to be configured to resemble real products. While [3] can be used as a first reference point for WiFi devices, [4] shows energy consumption for a 4G/5G smartphone, and [5] for an LTE network. It is visible in Table 1 that the representative energy efficiency of a WiFi modem equals around 39-45 nJ/b at each side of a wireless link (assumed path loss of 83 dB). While the 5G transmission is about 10 times less efficient from a 5G terminal perspective, it still outperforms an LTE terminal. However, the energy efficiency of an LTE Base Station (BS) is significantly lower, resulting in 45 µJ/b on average [5]. As all these numbers were obtained in different environments, under different test conditions and methodologies. They cannot be used to compare the considered standards between each other. However, these numbers show us how far practical systems are from the theoretical limit derived using the Shannon formula for infinite bandwidth and path loss of 83 dB, that is, 0.55 pJ/b.

Similarly to energy consumption, the latency introduced by wireless links depends on multiple factors. The time of flight between the signal source and its destination is proportional to the distance and inversely proportional to the speed of light. It is negligible (below a few s) for a typical wireless link

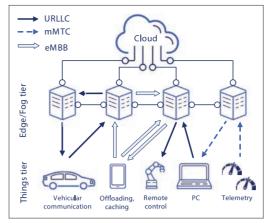


FIGURE 1. 2C fog network and its optimization platform.

The time of flight between the signal source and its destination is proportional to the distance and inversely proportional to the speed of light. It is negligible (below a few s) for a typical wireless link up to a few km.

up to a few km. Transmission time is more important. It is proportional to the payload (number of bits) and inversely proportional to the link throughput. However, there are other factors increasing latency, like the time needed by the Automatic Repeat reQuest (ARQ) procedure that is dependent on an internal characteristic of the utilized wireless standard. Next, the transmitted packet can be subject to a random delay caused by the utilized Medium Access Control (MAC) scheme, its configuration, and the number of users competing for a wireless medium at the same time. Finally, some random phenomena in the wireless channel, such as fast fading, can cause an outage of the link increasing the transmission latency. While all these factors are difficult to be accurately described by a single model, measurement-based models are of high potential. Measurements of a Round Trip Time between LTE/5G User Equipment (UE) and the BS from [4] are presented in Table 1 (mean values). This is a value for a short packet dominated by the MAC and ARQ procedures. Most importantly, the value is significantly below the limit of 4 ms specified for eMBB in 5G and above the limit of 0.5 ms for URLLC [4]. For WiFi networks, the dominating factor will be the MAC procedure requiring all trans-

Wireless Link	Bandwidth [MHz]	TX eff. [pJ/b]	RX eff. [pJ/b]	Latency [ms]
Shannon limit	∞	0.55	0	-
WiFi link [3]	20	4.5e4	3.9e4	1-1000
LTE UE DL [4]	20	_	~1.7e6	RTT: 2.6
5G UE DL [4]	100	_	~4e5	RTT: 2.2
LTE BS DL [5]	10	4.5e7	_	_
Wired Link	Capacity [Gb/s]	Active power [W]	Eff. [pJ/b]	Latency [ms]
1G EPON gate-way [11]	1	3.3	300	0.5e-5-0.5
10/10G GPON gateway [11]	10	5.5	200	as above
Juniper T1600 core router [7]	640	6572	1030	0.01-27
(Super) computer	Perf. [TFlop/s]	Cores	Power [kW]	Eff. [pJ/b]
Henri (#1 Green500) [8]	2038	5920	31	136-422
Frontier (#1 Top500) [8]	1102e3	8730112	21100	170-527
ASUS laptop Expertbook B9400CEA [9]	0.148	4	0.03347	2000-6199
Cumulus (#106 Green500) [8]	2271.38	50176	530	2069-6410

TABLE 1. Energy and latency consumption.

Performing computations in the cloud is more effective than performing them in the edge/ fog due to the parameters of computing devices (high computational power, effective cooling, etc.).

Scenario	Energy costs	Constraints	Variables
A. Optimization within fog and cloud tiers	Spent by fog and cloud nodes	Latency	Main: offloading decision (which node computes) Aux: CPU frequency, transmission rate
B. Optimization between wireless network, fog, and cloud tiers	Spent by end devices and fog and cloud nodes	Latency	Main: offloading decisions (which nodes to transmit, which node computes) Aux: CPU frequency, transmission rate
C. Optimization of requests generation rate considering the AoI for 2C	Spent by end devices and fog nodes	AoI	Main: operating frequency, transmission rate

TABLE 2. Summary of optimization scenarios.

mitting devices to compete for spectral resources. As shown in [6] the induced delay is quasi-exponentially distributed for a single packet with a mean delay ranging from a few to a few hundred ms.

WIRED PART OF THE NETWORK

Wired connections have always played a key role in the development of the Internet. They are essential in the modern Internet from its access (e.g., Passive Optical Networks (PONs)) to its core (e.g., Elastic Optical Networks (EONs)). Taking the perspective of 2C networks (Fig. 1), wired connections of end devices to the edge/ fog nodes (e.g., a laptop connected to a router using an Ethernet cable) are relatively rarely used nowadays due to their limited flexibility, even though their energy efficiency is higher than the efficiency of wireless links. Wired links are mainly used for interconnecting edge/fog nodes, as well as for connecting the edge/fog tier with the cloud. Gigabit Ethernet realized on copper cables is usually sufficient for interconnecting edge/fog nodes. However, Wavelength Division Multiplexing (WDM) links realized on optical cables are more suitable for these interconnections due to their higher bandwidth.

Performing computations in the cloud is more effective than performing them in the edge/fog due to the parameters of computing devices (high computational power, effective cooling, etc.). However, transporting computation tasks to the cloud as well as the computation outcomes back to the end-user can be time-consuming due to the physical distance between the fog and the cloud [6]. The few IP routers that the computation task needs to travel through may also influence experienced jitter. On the other hand, little additional energy is needed for the transportation of the tasks to the cloud due to the low dependence of power consumption of core IP routers and optical devices on load [7]. This is indicated in Table 1, where energy efficiency is based on the extra power needed for sending packets with respect to idle power. Induced latency is mainly determined by the propagation time of the optical signal reaching the highest values for submarine cables. Dense WDM and EONs are used in the core of the Internet to realize the connection between the cloud and the edge/fog nodes.

COMPUTING

The purpose of green computing is to increase energy efficiency over the course of a computing device's lifetime. Standard methods for achieving this energy efficiency are data-center design, software and deployment optimization, power management, optimized cloud computing, and edge/

fog computing. Algorithmic efficiency, optimized computing resource allocation, machine virtualization, Dynamic Voltage and Frequency Scaling (DVFS), sleeping modes, and the use of terminal servers are in place to optimize the software and deployment of the computing machines. These measures are taken to reduce the energy consumption resulting from the computers themselves and their air-conditioning and ventilation systems.

The performance-per-watt efficiency of the top 500 most energy-efficient supercomputers (Green500) [8] is continuously increasing with the top 2 supercomputers recently reaching values over 60 GFLOPS/W. However, as shown in [9], PCs are a plausible, energy-efficient option for the execution of non-complex tasks. Measurements of performance rates of tasks' execution and power efficiency (in GFLOPs/Watt) of five PCs are presented in [9]. In Table 1, key performance metrics of selected supercomputers and a PC are compared. Energy efficiency is provided in pJ/s for consistency reasons, assuming 71-220 Flop/B as a range of aggregate arithmetic intensities [10]. The Henri supercomputer (no. 1 on the Green500 list) has the best energy efficiency in Joules per bit, while the Frontier supercomputer (ranked no. 1 on the list of best performance supercomputers Top500) has worse energy efficiency but also lower power consumption and more than 500 times higher processing speed in Flop/s. Interestingly, an exemplary PC (Asus Expertbook, Core i7-1165G7 2.8 GHz [9]) has better energy efficiency than supercomputer Cumulus ranked 106 on Green500 (Table 1). Naturally, the processing speed is not as high for this PC as for supercomputers, but this example shows that when less computationally demanding tasks are to be executed, some less powerful but more energy-efficient machines are a viable option. Additionally, they are supposed to be localized closer to the end devices at the edge of a network.

OPTIMIZATION OF ENERGY CONSUMPTION IN 2C FOG NETWORKS

Both communication and computing introduce latency and energy costs in the network, as discussed above. On the one hand, an individual device from the things tier (e.g., a smartphone) is usually battery-powered and has limited resources compared to fog nodes and cloud nodes. Therefore, it can aim at the optimization of its energy consumption/utility, disregarding the costs in the higher tiers of the network treating it as a service provider. On the other hand, from the point of view of a network operator, optimizing the total

energy costs in the network (while maintaining the required OoS, for example, latency) could be the goal. In the first case, the decision boils down to whether the costs related to transmitting the task outweigh those caused by processing it locally by the device. In the second case, the fog network can distribute resources (networking and computing) choose which nodes should process the tasks offloaded by the users, and how it should be done, for example, using what CPU frequency. This optimization can be done after the tasks are sent by the users to their access points. This scenario (A) is examined in below. The optimization could also be carried out considering Radio Access Network (RAN). Then, the transmission from end devices to the fog is optimized jointly with the processing of tasks within fog and cloud nodes. This scenario (B) is shown in the following section.

Finally, the optimization can take into account that many fog applications are for periodic requests. In this case, it is both the timeliness and accuracy that specify if the QoS required by a given application is met. For this purpose, the AoI metric is currently used to optimize communications [12], though it can be easily extended to take 2C into account. AoI is defined as the time elapsed since the latest request (whose computation result reached the destination) has been generated. The request generation rate in the source influences the rate required in links, the number of computations to be carried in the fog, and the possible queuing of requests as such influencing the AoI. At the same time, energy utilization is impacted. Variable packet generation rate at source in order to minimize energy consumption while maintaining required AoI is considered later. Observe that while optimization of communications in the wired part of the network is performed in scenario A and scenario B extends it with RAN optimization, another degree of freedom is inserted in scenario C by considering the request source utilizing its periodic behavior. All considered optimization scenarios are compared in Table 2. All of them can be applied to various time-critical applications thanks to utilization of tight latency or AoI constraints.

These optimization problems can be sophisticated. Apart from the main decision variables which are binary (whether or not to process/offload a task) or integer (where to send/process it), there are other parameters such as clock frequency and transmit power (i.e., continuous variables) which make it nontrivial to find the optimum. In the following sections, illustrative results of simulations are shown and discussed.

SCENARIO A: OPTIMIZATION WITHIN THE FOG AND CLOUD TIERS

Let us assume the following scenario: there are 10 interconnected fog nodes with a connection to the cloud through the Internet. End devices wirelessly send computational requests to these nodes. The requests are characterized by size, arithmetic intensity (required number of operations relative to the size), and maximum tolerated delay. For such a network, the optimization problem can be defined as the minimization of energy consumption spent on computing and transmitting these requests while satisfying their delay constraints as in [6]. It is achieved by distributing

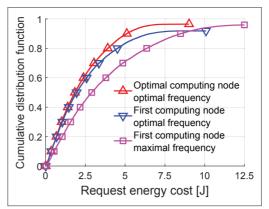


FIGURE 2. Distribution of energy costs spent on offloaded requests.

requests to nodes for computations and adjusting the CPU frequency of nodes through DVFS.

Figure 2 plots the cumulative distribution function of energy costs related to offloading requests considering 3 task allocation strategies. The results are achieved through computer simulations according to the model and optimization shown in [6]. The blue and magenta lines represent an approach in which arriving requests are computed in the same node to which they were transmitted by the end device, there is no inter-fog or fog-to-cloud transmission of requests. There is inter-fog and fog-to-cloud transmission for the red line (full optimization). Blue and red lines show results in which fog nodes are computing at optimal frequencies, while in the magenta solution computations are performed at the maximal available CPU frequency.

One can see that the red line (full optimization) is further left than the blue one (it achieves lower energy costs) and also further up (it is able to successfully process more requests). Computing at maximal frequencies (magenta line) induces significantly higher energy costs, while successfully processing a similar number of requests as the fully optimized solution (red). By comparing the median request energy, it is visible that around 30 percent of energy can be saved if instead of computing requests in the closest fog node with the highest CPU frequency (the magenta line), optimal allocation to computing nodes along with CPU frequency adjustment is carried out (the red line).

SCENARIO B: OPTIMIZATION BETWEEN WIRELESS NETWORK, FOG, AND CLOUD TIERS

In the previous section, the optimization began upon the appearance of requests in the fog nodes. Let us consider the same network and requests, but add a decision point "to which fog node should this end device wirelessly send this request." It also adds a new level of complexity to the existing optimization problem of choosing the optimal wireless transmission rate.

Figure 3 shows the results of optimization for this scenario. Here, the results are generated through simulation according to the model and optimization shown in [13]. Medians of energy costs spent on offloaded requests are plotted after a size parameter sweep. The red line shows the best results achieved by choosing the optimal computing node, optimal transmission path, and rate, as well as the optimal CPU frequency. The

One can see that the red line (full optimization) is further left than the blue one (it achieves lower energy costs) and also further up (it is able to successfully process more requests).

The request is sent to the base station over a single time slot with the transmission power minimizing energy consumption. Moreover, the CPU frequency in the fog node is optimized in order to minimize energy consumption.

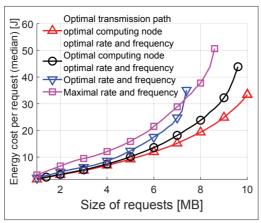


FIGURE 3. Median of energy costs spent on offloaded requests as a function of request size.

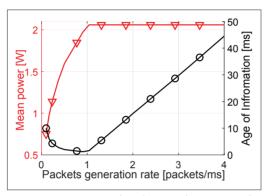


FIGURE 4. Mean power consumption and AoI versus the request generation rate.

blue line shows a scenario where all requests are processed in the fog nodes closest to the corresponding end devices. The magenta line shows the same scenario as the blue one, except fog nodes work at the maximal available CPU frequency. The black line corresponds to an optimization where each request is computed in the fog node collocated with the wireless access point to which the request has been originally transmitted.

Figure 3 shows that the optimal distribution of requests to nodes achieves the lowest energy consumption. The differences between plotted values increase as the sizes of requests increase. Baseline solutions shown in blue, black, and magenta "abruptly end" before reaching the right end of the plot. It corresponds to the fact that less than 50 percent of all requests were successfully processed within the tolerated delay. The difference between results obtained by different solutions varies with the size of the request. At 2 MB the optimal (red) solution saves 49.5 percent energy when compared with the solution shown in magenta, 23.5 percent when compared with blue, and 4.6 percent when compared with black. At 6 MB these savings change to 44.6 percent, 31.8 percent, and 12.2 percent respectively.

Scenario C: Optimization of Requests Generation Rate Con-Sidering the AoI for 2C

Let us consider an end device that generates a certain number of requests per unit of time. Each request must be transmitted to a proper fog node and processed therein to obtain useful information. If the resources at any stage (wireless network, wired network, computing nodes) are not available, the request is queued in a First-In-First-Out (FIFO) buffer. The request is sent to the base station over a single time slot with the transmission power minimizing energy consumption. Moreover, the CPU frequency in the fog node is optimized in order to minimize energy consumption. The mean consumed power, as well as the mean AoI versus request generation rate are plotted in Fig. 4. It can be observed that initially (up to 0.9 packets/ms) an increase in the requests generation rate results in a decrease in Aol. However, AoI starts to increase next as a result of computational or communications resources being exhausted, requiring requests to be queued. On the other hand, it is visible that an increase in the request generation rate results in a rise in power consumption. However, when the 2C resources become fully utilized, the mean required power reaches a defined plateau. It is reasonable as real world devices reach the maximum power consumption when fully utilized. Depending on the required AoI for a given application, an optimal request generation rate can be configured, such that the mean power consumption is minimized. This shows that source optimization should be considered together with wireless transmission, wired transmission, and fog nodes in order to maximize 2C efficiency while obeying the latency constraints.

AI FOR 2C ENERGY MANAGEMENT

The previous section has shown that increasing the number of degrees of freedom in optimization enables energy efficiency to increase without deterioration of the Quality of Service. However, global optimization considering numerous factors (e.g., fog nodes CPUs' frequency or the wireless access point to be used) can be problematic. First, it requires a global view of the considered system including all power consumption models and potential delays introduced by the considered allocation. Second, the optimization should be done without delays influencing internal networks of various service providers, for example, wireless radio access networks or cloud computing centers.

Artificial Intelligence (AI) and Machine Learning (ML) techniques can be employed. These can be used to learn the power consumption models or latency models while observing real-time network parameters and the induced energy consumption using, for example, some reinforced learning approach. While the latency can vary randomly as a result of, for example, random fading in the wireless channel, its distribution can be learned based on the available network parameters. Another perspective is to directly employ AI to select task allocation. This can use, for example, Deep Reinforcement Learning, as proposed in [14]. Previously tested allocation strategy will be assessed and after some operation time, it should converge to an optimal or close to the optimal solution. Additionally, utilization of such a scheme allows the allocation to adapt, for example, to changing conditions, traffic on each link, or changes of fog nodes.

Finally, ML can be used to design tasks allocation policies working independently, for example, in each fog node. In this case, it can be beneficial to utilize some clustering schemes. The incoming

computation requests can be clustered according to their properties, for example, number of calculations required, number of bits to be transmitted, or latency constraint, using the k-means algorithm [15]. Each cluster can be assigned a different strategy, for example, local computation or offloading to the cloud. The strategies for each node and cluster can be obtained using, for example, reinforced learning. It is also worth noting that the costs of training networks can be non-negligible. Ideally, costs spent on training and optimization should be included when examining the efficiency of ML-based and non-ML-based solutions. It is an interesting topic for future work.

CONCLUSIONS

Energy efficiency of fog computing becomes a major problem, especially for many time-critical applications. We have shown that it is possible to reduce energy consumption through proper coordination of communicating and computing resource allocation. The energy consumption can be further improved by proper source management depending on the current 2C network status. While centralized optimization is difficult to implement, we believe that distributed, Al-driven 2C management algorithms can achieve energy efficiency close to the global maximum.

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BIOGRAPHIES

HANNA BOGUCKA is a professor at the Institute of Radiocommunications (IR) at Poznan University of Technology (PUT). She is involved in research in wireless, cognitive, and green communications. She is a member of the Polish Academy of Sciences. She also serves as the Member-at-Large of IEEE Communications Society Board of Governors and Europe Regional Chair in IEEE ComSoc Fog/Edge Industry Community.

BARTOSZ KOPRAS received the B.Sc. degree and the M.SC. degree in telecommunications from PUT in 2019 and 2020, respectively. He is a Ph.D. student at the IR at PUT. His main field of interest is fog networks.

FILIP IDZIKOWSKI received the M.S. degree in tele-communication engineering from the PUT, Poland, and Dublin City University, Ireland, and the Ph.D. degree from the Technical University of Berlin, Germany. He is currently an Assistant Professor with PUT. He regularly serves as a member of various committees on several conferences, including IEEE ICC and IEEE Globecom.

BARTOSZ BOSSY received the M.Sc. degree and the Ph.D. degree in telecommunications from PUT in 2015 and 2022, respectively. He is a Research Assistant with the IR. He has been involved in a number of national and international projects. His research interests include green communications, energy-efficient resource allocation, fog networks, and optimization.

PAWEL KRYSZKIEWICZ is currently an Assistant Professor with the IR, PUT. He has been involved in a number of national and international research projects. His main fields of interest are multicarrier system design, green communications, Dynamic Spectrum Access, and Massive MIMO systems.