

Errata

Erratum to “A Bayesian Formulation of Coherent Point Drift”

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REFERENCE

[1] O. Hirose, “A Bayesian formulation of coherent point drift,” *IEEE Trans. Pattern Anal. Mach. Intell.*, vol. 43, no. 7, pp. 2269–2286, Jul. 2021.

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IN the above article [1], the IEEE published Fig. 15 incorrectly. The correct figure is below:

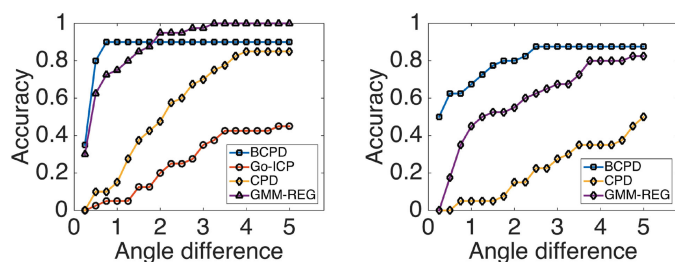


Fig. 15. Comparisons of rigid registrations using the ASL data (left) and the UWA data (right). The y-axis represents the rate of correct registrations using 40 pairs of point sets. A trial is defined as being a success if the angular difference from the ground truth is less than a value specified by the x-axis. For the UWA dataset, the ground truth was defined based on the results of Go-ICP, owing to its almost perfect performance finding partial overlaps in the dataset.

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