

5G Uniform Linear Arrays With Beamforming and Spatial Multiplexing at 28, 37, 64, and 71 GHz for Outdoor Urban Communication: A Two-Level Approach

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Abstract—Multiple-input multiple-output (MIMO) spatial multiplexing and beamforming are regarded as key technology enablers for the fifth-generation (5G) millimeter wave (mmWave) mobile radio services. Spatial multiplexing requires sufficiently separated and incoherent antenna array elements, while in the case of beamforming, the antenna array elements need to be coherent and closely spaced. Extensive 28-, 60-, and 73-GHz ultra-wideband propagation measurements in cities of New York City and Austin have indicated formation of two or more spatial lobes for the angles-of-departure and angles-of-arrival even for line-of-sight (LOS) transmission, which is an advantageous feature of mmWave channels, indicating that the transmitting and receiving array antenna elements can be co-located, thus enabling a single architecture for both spatial multiplexing and beamforming. In this paper, a two-level beamforming architecture for uniform linear arrays is proposed that leverages the formation of these spatial lobes. The antenna array is composed of sub-arrays, and the impact of sub-array spacing on the spectral efficiency is investigated through simulations using a channel simulator named NYUSIM developed based on extensive measured data at mmWave frequencies. Simulation results indicate spectral efficiencies of 18.5–28.1 bits/s/Hz with a sub-array spacing of 16 wavelengths for an outdoor mmWave urban LOS channel. The spectral efficiencies obtained are for single-user (SU) MIMO transmission at the recently allocated 5G carrier frequencies in July 2016. The method and results in this paper are useful for designing antenna array architectures for 5G wireless systems.

Index Terms—5G, arrays, beamforming, mmWave, spatial multiplexing, SU-MIMO.

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I. INTRODUCTION

SPECTRUM allocation for fifth-generation (5G) cellular systems are classified by the 3rd Generation Partnership Project (3GPP) international cell phone standard body as being from 0.5 GHz up to 100 GHz [1]. The spectrum above 30 GHz is known as the millimetre wave (mmWave) band, with 28 GHz also being regarded as mmWave for its proximity to the 30 GHz spectrum. The vast spectrum at frequencies above 28 GHz offers wide channel bandwidths that will support high peak data rates of several Gigabits per second. Such throughput speeds will be required for high-definition (HD) video, low latency content, and high data rate transfer between data centers and virtual interaction between people and machines [2]. Video continues to be the major application generator for mobile data traffic growth accounting for 51 percent of global mobile data traffic in 2012, and it is predicted to account for 75 percent of global mobile data traffic by 2020 [3]. The 28 GHz band is attractive as it enables mobility on mmWave due to 850 MHz of contiguous bandwidth in the United States, and has been a frequency of major focus for academic research and prototyping efforts; whereas the 38 GHz band [4] is particularly suited for ultra-high data rates and has initial agreement from the International Telecommunications Union (ITU) World Administration Conference as a global spectrum allocation. The 64–71 GHz spectrum would enable development of new innovative unlicensed applications and promote next generation high-speed wireless links with wider connectivity and higher throughput [5]. The Federal Communications Commission (FCC) in July 2016 allocated the 28 GHz, 37/39 GHz and 64–71 GHz frequencies both as licensed and unlicensed bands for the 5G mobile radio services (MRS) [5].

Multiple-input multiple-output (MIMO) has already been used in 4G long term evolution (LTE) cellular networks, and is regarded as one of the technologies likely to be adopted in 5G to increase peak data rates along with beamforming for low signal-to-noise ratio (SNR) scenarios such as cell edge users [6]–[8]. Beamforming approaches that are suitable for mmWave frequencies can be broadly classified as analog, hybrid analog-digital, and low resolution digital, each having specific implications for deployment in mmWave MIMO chan-

nels. Analog beamforming requires analog phase shifters which are adaptively adjusted to vary the phases of antenna elements, thereby increasing the antenna gain to counter the path loss in line-of-sight (LOS) and non-line-of-sight (NLOS) mmWave propagation [9]. Phase shifters can be active elements, which suffer phase-shifter loss, noise and nonlinearity, or they can be passive, where passive phase shifters have the advantage of low power consumption and reduced nonlinearity, but incur more insertion loss and occupy more area [10]. Analog beamforming is employed with beam training algorithms and acquiring the channel state information (CSI). Hybrid (analog-digital) beamforming requires either precoding or combining techniques both in the baseband and radio-frequency (RF) level [11]–[14] and can be designed through different approaches using phase shifters [15], switches [16] and lenses [17]. Hybrid beamforming can be employed by having a group of elements connected to one RF chain or an array of sub-arrays, where each sub-array has several interconnected antenna elements but its own RF chain.

MmWave MIMO transmission requires multiple antenna elements to provide beamforming gain to compensate for higher path loss on account of mmWave incurring higher attenuation in the first meter of propagation due to Friis law [18]. Making a highly directive antenna with a small beamwidth, steerable over large angle ranges for the angle of arrival (AOA) at the receiver (Rx), would ensure a high gain. This adaptive beamforming requires multiple elements with high coherence to enable beamforming and with beam steering that requires co-polarized antenna elements closely spaced typically at $\frac{\lambda}{2}$, where λ is the carrier wavelength. MIMO transmission requires spatial multiplexing (SM) which is ensured by separate spatial paths of parallel transmissions, which mandates a contrary requirement of ensuring that there is no coherence between antenna elements transmitting parallel data streams simultaneously, i.e., antenna elements that are either cross-polarized, orthogonal in spatial beam patterns, and/or relatively spaced far apart [19]. This requires an antenna element spacing of greater than $\frac{\lambda}{2}$ which reduces coherence among antenna elements, but leads to formation of grating and quantization lobes which reduce the available angle range for beam steering. Continuous phase shifting requirements from 0° to 360° are expensive and typically not used in practice. Phase shifts are digitally controlled by realizing discrete phase shifts which causes quantization phase error leading to formation of quantization lobes, which occur at the grating lobe angles during beam steering. Meeting both MIMO and beam steering requirements simultaneously in a single architecture is challenging. In this paper these are explained followed by an architecture that addresses these challenges. Simulations are undertaken with a mmWave channel simulator developed by New York University (NYU) from extensive field data, NYUSIM v1.5, to characterize the MIMO channel conditions at the recently allocated FCC 5G frequencies of 28, 37/39, and 64–71 GHz. Section II details current limitations in single-user (SU)-MIMO with beam steering along with the proposed hybrid architecture. The mmWave MIMO channel model is described in Section III, based on a 3D statistical spatial channel model (SSCM) along with how the channel coefficients are obtained for the MIMO channel matrix \mathbf{H} . The section details degrees of freedom (DOFs) and channel condition number for \mathbf{H}

that quantify SM required for MIMO transmission. Section IV details the uniform linear array (ULA) element design and the array pattern, formation of the grating and quantization lobes. The channel condition number and spectral efficiency values obtained from simulations for various sub-array spacings are given in Section V, followed by conclusions in Section VI.

II. TWO-LEVEL HYBRID BEAMFORMING WITH SPATIAL MULTIPLEXING

A. Current Limitations in SU-MIMO

In the case of SU-MIMO, more than one spatial stream is exchanged between two arrays. Due to the multipath sparsity, the channel propagation matrix can be near-singular and conventional MIMO capacity will degrade significantly. The antenna spacing and array orientation can significantly affect the system performance [19], [20]. SU-MIMO capacity for a full digital mmWave array has been studied in [21] for LOS and in [20] for a two-path channel. When the LOS path is dominant, multiplexing gain is largely limited to the gain achievable by LOS-MIMO, which relies on careful placement of transmitter (Tx) and Rx antennas. For a full digital array, the LOS-MIMO capacity, which can be achieved at the Rayleigh distance, depends on the orientation of Tx and Rx arrays, their distance R , the element spacing and the number of antenna elements. The Rayleigh distance criterion leads to a full-rank and orthogonal MIMO channel matrix, but generally requires impractically large antenna space and array size. Nevertheless, results in [20]–[27] indicated that in principle it is possible to achieve the maximum multiplexing gain in mmWave MIMO channels with LOS transmissions by carefully designing the geometrical distribution of the antennas at both link ends. Using aligned ULAs at both ends showed that the channel vectors experienced by different Tx/Rx antennas can be mutually orthogonal if the antenna spacings and the end-to-end distance satisfy the Rayleigh distance criterion. This approach of Rayleigh distance criterion, however, relies on careful placement of Tx and Rx and is not practical for outdoor urban communication, which may require varying distances between Tx and Rx based on the different requirements of cell design and geometry. For a setup with a carrier frequency of 38 GHz, two parallel ULAs with 16 elements, and $R = 500$ meters, achieving system capacity requires an element spacing of about 0.5 m (~ 63 wavelengths). In [21], system throughput is examined for arrays with closer element space. It is shown that the maximum distance to support multiplexing communications over LOS-MIMO channels is mainly determined by the product of the aperture sizes of the Tx and Rx antenna arrays, instead of the numbers of antennas at both ends. For communication distance in the order of kilometers, the multiplexing gain is limited to 4, even for a large array size of 5 m.

Secondly, the array configurations based on the Rayleigh distance criterion for ensuring LOS SU-MIMO are highly constrained to a limited beam steering angle due to formation of grating lobes [23]–[27], thus the optimal spacing between the antenna elements for the Rayleigh distance criterion may not be optimal for beam steering. Therefore an antenna configuration based on the Rayleigh distance criterion would be severely constrained in terms of the beam steering angle.

In view of the challenging requirements for SU-MIMO, extensive investigation of the state-of-the-art hybrid precoding techniques is undertaken as reported in [28]–[43]. This indicates that most of the existing work details performance of architectures that are applicable to multiple-user MIMO (MU-MIMO). In these cases, Rx antenna arrays can be separated by considerable distances, as these are for multiple users which can ensure sufficient spatial separation that enables SM. Similar Rx antenna array separations are not feasible for SU-MIMO on a single mobile user equipment. Secondly, SM in mmWave propagation depends on both the channel and antenna properties. Antenna properties such as the radiation pattern, the sub-array spacing and orientation are intrinsic to implementing the ULA design which must be considered for obtaining the channel coefficients. These parameters are crucial to analysis of SM but also for the beamforming constraints such as formation of quantization and grating lobes in relation to the ULA architecture. Some analyses for SU-MIMO hybrid precoding are given in [28], [30], [36], [42], [43] but parameters assumed are for NLOS mmWave channels. Also, previous work did not systematically study the effects of sub-array spacing in mmWave for SU-MIMO, or formation of quantization and grating lobes which is an area of current research [19], [44]. Having multiple sub-arrays reduces hardware complexity at the expense of less overall array flexibility for beam scanning and MIMO which needs careful analysis. Overall, in the existing approaches, SU-MIMO is a less attractive option in mmWave cellular systems due to limited multiplexing gain and dependency on the distance relationship.

The main motivation for employing hybrid precoding in mmWave MIMO is for reducing the hardware resources. Employing a specific hybrid precoding technique or comparison of the existing hybrid precoding techniques such as for optimizing the hardware resources in mmWave MIMO is not the focus of this paper. Rather, our paper provides an alternative approach to the Rayleigh distance criterion that enables SM for SU-MIMO in LOS mmWave channels. Encouraging results for up to 500 m Tx-Rx separation distance are reported which are practical to implement for urban outdoor mmWave cell sizes. The proposed architecture is not constrained to any beam steering angle due to formation of grating lobes. As the proposed architecture is based on sub-arrays, a suitable hybrid precoder can be accordingly employed to offer reduction in hardware resources.

Furthermore, this novel approach leverages the unique characteristic of mmWave propagation which is formation of one or more spatial-lobes (SLs) even in LOS channels due to a rich scattering environment, which is not reported earlier in the context of enabling SM for SU-MIMO in LOS mmWave channels. The antenna elements can be co-located averting the limitation of space requirements as SM is ensured due to different angles of departure (AODs) and AOA of the SLs even in LOS propagation. The existing 3GPP channel models [1], [45] do not include the effects of directional local scattering at the Tx and Rx in an outdoor urban environment for mmWave propagation, yet real-world measurements in New York City show the existence of directional propagation in urban environments, leading to the formation of SLs [2], [46], [47]. SLs conveniently represent the mmWave radio channel because they implicitly account for directionality,

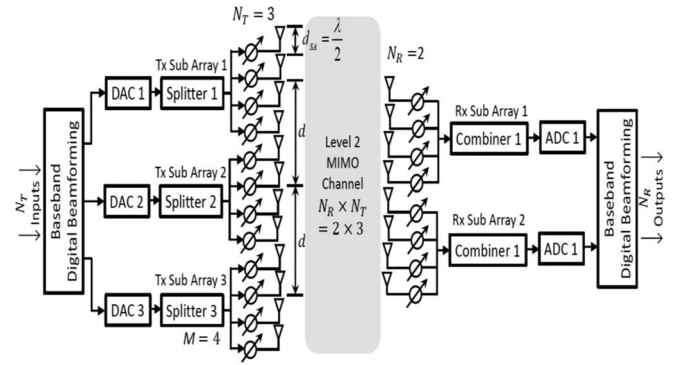


Fig. 1 MmWave MIMO hybrid beamforming.

a key differentiator of future wireless cellular and mobile systems operating in the mmWave spectrum compared with today's ultra-high frequency (UHF) and microwave systems.

B. System-Level Architecture

In order to meet the contradictory requirements of beamforming which requires co-polarized closely spaced antenna elements typically at $\frac{\lambda}{2}$ with high coherence, and SM which requires no coherence between antenna elements to ensure simultaneous separate parallel data streams [19], a two-level (2L) hybrid beamforming architecture is proposed as illustrated in Fig. 1. The architecture follows a 2L hierarchy wherein at level 1 (L1) each sub-array at the Tx and Rx is employed to adaptively form highly directive beams to provide beamforming gain. Each sub-array is an analog array consisting of antennas connected with adjustable phase shifters in the RF chain. Each sub-array is connected to a baseband processor via a digital-to-analog converter (DAC) in the Tx or an ADC in the Rx. Level 2 (L2) is the resulting MIMO system that enables SM of these beams to increase channel capacity by supporting simultaneous parallel data transfer based on the selected spatial directions of the sub-arrays formed from L1. A similar approach has been proposed in [26] for E-band (70–95 GHz) and employed for SM for a 60 GHz indoor link [27]. In [26], simulated values indicate higher spectral efficiency as the physical spacing of the sub-array antennas is increased, where sub-arrays with highly directive pencil beams are employed in telescopic dish configurations. However, these highly directional sub-array antennas are constrained for beam steering due to formation of grating lobes at 10° off boresight, since the increase in sub-array separation reduces the available angular sector for which grating lobes do not occur. One can increase the sub-array spacing to increase the number of SM paths but this leads to formation of the grating lobes, severely restricting the beam steering angle. In [27], analysis was restricted to only MIMO SM and no beamforming was employed in an indoor environment. The 2L approach presented in this paper can combine SM with beamforming for ULAs to enable prototype development of handsets and point-to-point Tx/Rxs in outdoor LOS or NLOS urban environments for SU-MIMO.

In Fig. 1 the number of MIMO transmitting elements at L2 is N_T , wherein each of the transmitting elements is actually a

TABLE I
 SUPER-ARRAY CONFIGURATIONS FOR FIG. 1 WITH LENGTHS IN CM

N_T	$C_{M4} (d = 2\lambda)$					$C_{M8} (d = 4\lambda)$					$C_{M16} (d = 8\lambda)$					$C_{M32} (d = 16\lambda)$				
	N	L_{28}	L_{37}	L_{64}	L_{71}	N	L_{28}	L_{37}	L_{64}	L_{71}	N	L_{28}	L_{37}	L_{64}	L_{71}	N	L_{28}	L_{37}	L_{64}	L_{71}
2	8	3.75	2.83	1.64	1.47	16	8.03	6.08	3.51	3.16	32	16.60	12.56	7.26	6.54	64	33.75	25.54	14.76	13.30
3	12	5.89	4.45	2.57	2.32	24	12.32	9.32	5.39	4.85	48	25.17	19.05	11.01	9.92	96	50.89	38.51	22.26	20.07
4	16	8.03	6.08	3.51	3.16	32	16.60	12.56	7.26	6.54	64	33.75	25.54	14.76	13.30	128	68.03	51.48	29.76	26.83
5	20	10.17	7.70	4.45	4.01	40	20.89	15.81	9.14	8.23	80	42.32	32.02	18.51	16.69	160	85.17	64.45	37.26	33.59
6	24	12.32	9.32	5.39	4.85	48	25.17	19.05	11.01	9.92	96	50.89	38.51	22.26	20.07	192	102.3	77.43	44.76	40.35
7	28	14.46	10.94	6.32	5.70	56	29.46	22.29	12.89	11.61	112	59.46	45.00	26.01	23.45	224	119.4	90.40	52.26	47.11
8	32	16.60	12.56	7.26	6.54	64	33.75	25.54	14.76	13.30	128	68.03	51.48	29.76	26.83	256	136.6	103.3	59.76	53.87

sub-array of many antenna elements. At L1 each sub-array has M elements. For mmWave propagation it is observed that two to five SLs occur and two to three is the number at which most if not all the energy will be received [46]. For example, in Fig. 1 the number of MIMO transmitting elements N_T is three, wherein each of the transmitting elements is a sub-array with M elements which in Fig. 1 is 4. Likewise, the number of MIMO Rx elements N_R is two. Accordingly, at L2 there is an $N_R \times N_T$ mmWave MIMO channel. Under low SNR conditions when employing beamforming, the same architecture can be configured with the sub-arrays resulting in formation of a larger array, which we call “super-array” in this paper. In Fig. 1, the Tx super-array consists of 12 elements (4 from each of the 3 sub-arrays) and the Rx super-array consists of 8 elements (4 from each of the 2 sub-arrays). The element spacing at L1, i.e., within each sub-array is given by d_{SA} , which remains $\frac{\lambda}{2}$, while the distance d is the separation of the sub-arrays, which are considered to be single elements for MIMO at L2.

The proposed architecture enables generating the channel coefficients based on the number of N_T , N_R and the half-power beamwidth (HPBW) for a single beam that is transmitted through the channel. At L2 accordingly the individual number of sub-array elements M are reflected through the HPBW for a single beam. It is worth noting that the HPBW is for the entire antenna array i.e., the super-array. In case of low SNR conditions the architecture enables beamforming via the antenna elements within each sub-array, such that one or more weights are generated to be applied to the individual ULA antenna element signals. During normal/high SNR conditions MIMO SM is carried out using sub-arrays, with each sub-array treated as a single radiating element in a MIMO super-array system that sends different data streams through each sub-array [19]. The antenna element spacing can be interleaved or localised among the sub-arrays, the later as in Fig. 1 offers smaller grating lobes, larger LOS-MIMO capacity of a given array size and is practical for hardware implementation as compared to the former [44]. In case of low SNR during beamforming all the elements in the entire super-array transmit the same symbol to compensate for the high path loss with the beamforming gain. While in case of normal or high SNR conditions for meeting the requirements of high data transfer with MIMO, the three transmitting sub-arrays in Fig. 1 would transmit two different symbols for SM. Since the antenna element spacing does not change during both

modes of transmission this circumvents formation of grating /quantization lobes during beamsteering

Various super-array configurations are possible for the ULA architecture in Fig. 1. Some of the configurations presented in this paper are detailed in Table I, where N is the total number of antenna elements at L1, C_{Mx} is the array configuration with x denoting the number of elements in each sub-array, and L_y the entire array length considering all sub-arrays in cm at y carrier frequency in GHz. If the lateral separation d between the sub-arrays is increased, with a view to reduce correlation between sub-arrays, the visible region for beam steering of the super-array (composed of sub-arrays) decreases, due to formation of grating and quantization lobes.

III. MMWAVE CHANNEL MODEL

A. 3D Statistical Spatial Channel Model

The MIMO channel model is based on a 3D SSCM for urban LOS and NLOS channels developed from extensive 28-, 60-, and 73-GHz ultra-wideband propagation measurements in cities of New York City and Austin [46], [47]. The model generates channel impulse responses (CIRs) that match measured field data at a wide range of distances and over local areas based on the time-cluster-spatial-lobe (TCSL) modeling framework. The approach extends the 3GPP model through directional root mean square (RMS) lobe angular spreads (ASs) and is consistent with the 3GPP modelling framework.

Based on the 3D statistical channel model in [46], [47], a MATLAB-based statistical simulator, NYUSIM v1.5, has been developed by NYU [48], [49] that can generate 3D AOD and AOA power spectra along with omnidirectional and directional power delay profiles (PDPs) that match measured field results. 3GPP has unrealistically large number of strong eigenvalues which are not found in measured mmWave channels. In order to realistically quantify performance, NYUSIM v1.5 is employed in this paper for simulating the MIMO channel as the simulator is built from field data which gives more realistic results [50].

B. Parameters and Antenna Properties

The simulator settings for the channel parameters and the antenna properties employed for simulations in this paper are listed in Table II. UMi, UMa and RMa denote urban microcell, urban

TABLE II
NYUSIM v1.5 SIMULATION SETTINGS USED IN THIS STUDY

Channel Parameters		
Frequency (0.1–100 GHz)	28, 37, 64, 71	As per frequencies allotted by the FCC on which this paper is based.
RF Bandwidth (0–800 MHz)	800	Typical bandwidth that is expected for mmWave 5G, and also the maximum bandwidth that NYUSIM supports.
Scenario (UMi/UMa/RMa)	UMi	Urban micro cell, as we are considering urban outdoor environment.
Environment (LOS/NLOS)	LOS	LOS is considered in this paper.
Tx Rx Sep. (10–500 m)	500	The maximum distance considering the worst case scenario. The cell size in mmWave 5G is unlikely to be greater than 500 m in view of high free space path loss. Accordingly, this is also the upper limit for NYUSIM v.1.5.
Tx Power (0–30 dBm)	30	A normal cellular base station has 30 dBm of power transmission.
Number of Rx Locations	100	Since the simulation output values are random, 100 values are considered for obtaining median values. Simulations show that any increase beyond 100 results is marginal dividend.
Barometric Pressure (mbar)	1013.25	Normal atmospheric conditions.
Humidity (0–100%)	50	Normal atmospheric conditions.
Temperature °C	20	Normal atmospheric conditions.
Rain Rate (0–150 mm/hr)	8	Normal atmospheric conditions.
Polarization (Co/Cross)	Co	Co polarization antennas are considered in this paper.
Foliage Loss	No	Nil foliage loss is considered.
Distance Within Foliage (m)	0	Nil distance within foliage.
Foliage Attenuation (dB/m)	0.4	Normal foliage attenuation.
Antenna Properties		
Tx Array Type (ULA/URA)	ULA	Horizontal ULAs are considered in this paper.
Rx Array Type (ULA/URA)	ULA	Horizontal ULAs are considered in this paper.
No. of Tx elements (sub-arrays)	N_T	Relevant Parameter.
No. of Rx elements (sub-arrays)	N_R	Relevant Parameter.
Tx Antenna (sub-array) Spacing (in λ , 0.1–100)	d	Relevant Parameter.
Rx Antenna (sub-array) Spacing (in λ , 0.1–100)	d	Relevant Parameter.
Tx Antenna (Super-Array) Azimuth HPBW (7° – 360°)	12.6, 7	In Section IV, the ULA antenna element has been designed with CST MICROWAVE STUDIO and array patterns developed using MATLAB R2016a generating HPBW input parameters for NYUSIM v1.5.
Tx Antenna (Super-Array) Elevation HPBW (7° – 45°)	45	Eqs. (5)–(9) in Section IV are used to plot array pattern in Fig. 6 from which the HPBW for azimuth and elevation values are extracted and detailed in Table II. This happens to be 12.6 degrees (azimuth) and 45 degrees (elevation) for the configuration with lowest number of array elements C_{M4} and are taken as such for simulation. For C_{M8} , the number of elements is doubled, accordingly the HPBW is half of 12.6 degrees which is 6.3 degrees (azimuth) and 45 degrees (elevation-does not change as the number of elements are changing in azimuth only). But NYUSIM v1.5 has a lower limit of HPBWs of 7 degrees for azimuth and elevation. Thus for simulations in this paper, an azimuth of 7 degrees is taken. SM gets worse as the HPBW increases, thus NYUSIM v1.5 gives a worst case scenario which can be accepted; as 6.3-degree azimuth HPBW is expected to achieve even higher spectral efficiencies. The narrower the azimuth beam, the higher the SM gain. Accordingly, C_{M16} azimuth HPBW is 3.13 degrees and for C_{M32} this decreases to 1.565 degrees. HPBW is taken as the lower bound in NYUSIM 1.5 which is 7 degrees. Accordingly, even better spectral efficiencies are expected for these configurations as we are assuming worse HPBW values than expected.
Rx Antenna Azimuth HPBW (7° – 360°)	12.6, 7	
Rx Antenna Elevation HPBW (7° – 45°)	45	

macrocell and rural macrocell settings, respectively. Co/Cross is the polarization between the Tx and Rx antenna arrays. Typical values for the barometric pressure, humidity, temperature, rain rate and foliage attenuation have been used with nil foliage loss. For the antenna properties, ULAs have been considered at the Tx and Rx with a variable antenna spacing d (i.e., the L2 sub-array spacing), the number of transmitting antenna elements (varying from 2 to 8, which is the number of sub-arrays at L2) is N_T , and the number of receiving sub-arrays is N_R . The Tx and Rx azimuth and elevation HPBWs are for the super-array at L2. In

Section IV, the ULA antenna element has been designed with CST MICROWAVE STUDIO and array patterns developed using MATLAB R2016a generating HPBW input parameters for NYUSIM v1.5. For various configurations in Table I, the maximum azimuth HPBW is $12.6^\circ (\pm 6.3^\circ)$ and elevation HPBW is $88^\circ (\pm 44^\circ)$. With an increase in the number of sub-array elements, the azimuth HPBW becomes less than $6.3^\circ (\pm 3.3^\circ)$ and is taken as 7° which is the lower limit in NYUSIM v1.5. The elevation HPBW remains constant and is taken as 45° , the upper limit in NYUSIM v1.5. A larger elevation HPBW would not

TABLE III
 NYUSIM v1.5 28 GHz CHANNEL SIMULATION OUTPUT VALUES

P	α (dBm)	τ (ns)	Phase ($^\circ$)	Azimuth AOD ($^\circ$)	Elevation AOD ($^\circ$)	Azimuth AOA ($^\circ$)	Elevation AOA ($^\circ$)
1	-73.5	333.3	2.3	131.3	-12.6	318.0	-7.7
2	-78.9	336.2	4.8	131.0	-16.0	338.1	-16.2
3	-84.5	339.8	4.5	220.1	-13.7	321.1	-8.0
4	-76.1	343.7	2.5	204.3	-10.7	330.8	-21.6
5	-95.7	347.8	2.8	124.8	-11.9	334.8	10.5
6	-93.7	352.1	4.4	203.1	-14.4	333.2	14.4
7	-93.1	356.5	0.6	346.1	-9.3	336.1	8.0
8	-92.3	463.7	3.3	89.4	1.7	322.3	-11.0

affect the SM since for horizontal ULAs the azimuth HPBW is more critical.

C. MIMO Channel Matrix Degrees of Freedom

Multi-carrier transmission is one of the technologies being considered for mmWave. Considering orthogonal frequency division multiplexing (OFDM) transmission, each resolvable multipath component contributes to the MIMO channel coefficients for an OFDM sub-carrier. Assuming ULAs at both the Tx and Rx, the channel coefficient is given by [51]:

$$h_{m,k}(f) = \sum_p \alpha_{m,k,p} e^{j\Phi_{m,k,p}} e^{-j2\pi f \tau_{m,k,p}} e^{-j2\pi d_T m \sin(\phi_{m,k,p})} e^{-j2\pi d_R k \sin(\varphi_{m,k,p})} \quad (1)$$

where $h_{m,k}(f)$ is the MIMO channel coefficient between the m th transmit antenna and the k th receive antenna for the sub-carrier f , p represents the p th resolvable multipath component, α is the amplitude of the channel gain, Φ denotes the phase of the multipath component, τ represents the time delay, d_T and d_R are the antenna element spacing at the Tx and Rx, respectively, while ϕ and φ denote the azimuth AOD and AOA, respectively. All of the above parameters are extracted from post simulations undertaken by NYUSIM v1.5 with settings in Table II, with a Tx height of 10 m and a Rx height of 1.5 m above the ground. Typical parameter values obtained for a single 28 GHz simulation that results in 8 resolvable multipath components are given in Table III.

The channel matrix \mathbf{H} is formed by the entries of channel coefficients generated in (1), assuming the frequency interval between adjacent sub-carriers is 10 MHz, which corresponds to 800 MHz/10 MHz + 1 = 81 sub-carriers, as 800 MHz is the RF bandwidth in the simulation settings in Table II. For the channel matrix \mathbf{H} , one can quantify the multiplexing capacity. With probability 1 the rank of the random matrix \mathbf{H} is given by [52]:

$$\text{rank}(\mathbf{H}) = \min \{ \text{no. of independent non-zero rows, no. of independent non-zero columns} \}. \quad (2)$$

This yields the DOFs available in the MIMO channel. The number of independent non-zero rows and columns depends on the amount of scattering, reflection and the length L_y of the Tx and Rx arrays. The more scatterers and reflectors there are, the

larger the number of non-zero entries in \mathbf{H} and the larger the DOF. Increasing L_y increases the array aperture allowing for higher resolution of more paths resulting in non-zero entries of \mathbf{H} . The AS for the AOD and AOA relate to the spatial selectivity of the channel, where it has been shown that directionality of the mmWave channel is noticeable and repeatable, and can be expressed in terms of spatial lobes that have a particular azimuth (AZ) and elevation (EL) angle spread [46]. The coherence distance across an antenna manifold provides a measure of maximum spatial separation over which multipath components of a transmitted signal have strong correlation and is inversely proportionate to the AS. MIMO channels even with co-located Tx and Rx antennas with reflectors and scatterers far away can also provide a DOF gain. For a channel where signals depart at the Tx array of length L_y and arrive at the Rx array with a length of L_y in distinct SLs as is the case for mmWave channels, with AS of the k th SL as Θ_{tk} and Θ_{rk} for the AOD and AOA respectively, the DOF is given by [53]:

$$\min \left\{ \sum_k [L_y [\theta_{tk}]], \sum_k [L_y [\theta_{rk}]] \right\}. \quad (3)$$

MmWave propagation due to comparatively smaller λ as compared to current MRS frequencies such as those used in LTE undergoes weaker diffraction due to reduced Fresnel zones, larger penetration loss and higher scattering. The diffused scattering leads the signal to arrive at the Rx in distinct SLs. Measurements undertaken for the 28 GHz NLOS channel in urban environments indicate a mean number of 1.6 SLs for both AOD and AOA. For the 73 GHz NLOS the mean values are 1.5 and 2.5 for the AOD and AOA respectively. More AOA SLs at 73 GHz arise from more prominent local scattering than at 28 GHz [46], likely due to the more thorough scanning in azimuth and elevation [47]. Measurements in [2], [46], [47] also indicate that for the LOS scenario, the mean number of AOD SLs was higher than the NLOS case at 28 and 73 GHz, suggesting that multipath signals can reach the Rx from more departing angles even in LOS cases; The mean number of AOA SLs for LOS and NLOS was found comparable indicating that both spatial environments appear similar to the Rx. SLs due to local scattering in mmWave account for directionality and are a key differentiator for mmWave MRS as compared to existing MRS such as LTE. The cumulative density function (CDF) plots for $\sum_k \Theta_{tk}$ and $\sum_k \Theta_{rk}$ in Fig. 2 obtained from 100 random channel realizations in the LOS scenario with NYUSIM v1.5 indicate higher values for the 28 GHz band as compared to an 800 MHz LTE channel implying a higher DOF for similar array lengths.

C. MIMO Channel Matrix Condition Number

A metric to characterize the quality of MIMO channels in the context of wireless communications is the condition number, defined as the ratio of the largest (λ_1) to smallest singular value (λ_2) in the singular value decomposition of a channel matrix \mathbf{H} [54]–[58]. The channel condition number and its statistical properties are important for characterization of the MIMO channel. It gives a measure of the relative conditioning (or rank-deficiency) of a matrix, indicating the independence or correlation between channel paths [59]–[62]. An indication of how much correlation

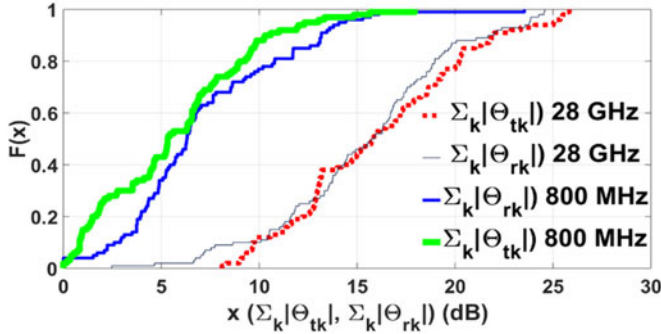


Fig. 2. CDF for AOD and AOA AS at 28 GHz and 800 MHz.

exists among the channel paths is important as it affects the Rx performance. Although the increase in the rank of channel matrix generally increases with the number of channel paths, the correlation between the channel paths increases if angular separation of the channel paths decreases. The channel condition number, a function of spatial separation of the signals arriving at the Rx, determines conditioning of the channel matrix \mathbf{H} . Signals that are misaligned or more spatially separated at the Rx lead to a well-conditioned \mathbf{H} . The channel condition number will be high (over 20 dB) if the minimum singular value is close to zero, and will be 0 dB if singular values are equal. Physically, a small channel condition number value of <20 dB indicates good orthogonality of different spatial sub-channels. The rank of a matrix is the dimension of the vector space generated by its columns or rows [56], and it determines how many data streams can be multiplexed over the channel in the context of MIMO communications [19], [55], [63]. A low channel condition number usually corresponds to a high rank and vice versa; the matrix has full rank (the highest rank) when the channel condition number is equal or close to 0 dB (the lowest theoretical condition number). The channel condition number is an important design parameter in MIMO systems as it has been shown to drastically affect the detection, error and performance of linear Rxs in MIMO systems. Performance of linear detectors such as zero-forcing (ZF), maximum-likelihood (ML) and minimum mean square error (MMSE) detectors has been investigated indicating strong dependence of the detector performance on the channel condition number [64]–[70]. The channel condition number is also adopted to formulate novel spectrum sensing algorithms in cognitive radio applications [71]–[73] for MIMO systems.

A MIMO system can provide both SM and diversity gain with adaptive switching. Such adaptive switching schemes can switch between SM and diversity for an optimal performance based on various parameters of the channel. The channel condition number is one such parameter that is employed as the switching criteria [64], [65], [74]. In [64] probability of SM versus diversity is given as a function of the number of antennas for a MIMO Rayleigh fading channel based on distribution of the channel condition number. The system proposed in [65] chooses either BLAST or STBC based on the instantaneous channel condition number. Furthermore, channel condition number is employed in the industry to analyze potential causes for throughput issues [75] and is an important design parameter used in 3GPP

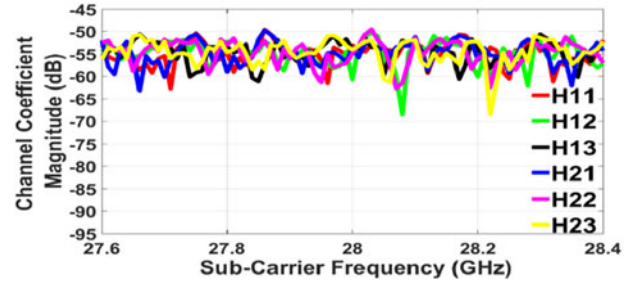


Fig. 3. MIMO channel matrix coefficient magnitudes for OFDM.

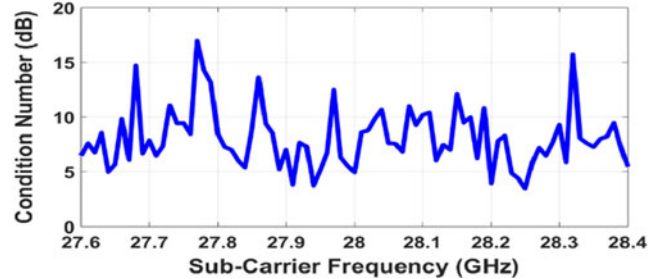


Fig. 4. Condition number of the channel matrix for OFDM sub-carriers with three transmit sub-arrays and two receive sub-arrays.

standards such as for the LTE [76]. For wireless system designers, this forms an important baseline reference for characterizing the MIMO channel for designing Rxs in 5G mmWave systems. Formation of higher number of SLs in mmWave even for LOS scenarios implicitly account for directionality which ensure that the channel matrix \mathbf{H} is well-conditioned when compared to existing sub mmWave mobile radio channels. Typical values of channel condition numbers for LTE range from 5–15 dB as measured by 3GPP in [76]; a similar method is employed in this paper for evaluating the channel condition numbers. The magnitudes of the six channel coefficients for the 2×3 L2 MIMO channel matrix \mathbf{H} in Fig. 1 are depicted in Fig. 3. ULAs are applied during the generation of \mathbf{H} , and the separation distance of sub-arrays is half-wavelength. Fig. 3 shows that the transmitted wideband signal undergoes frequency-selective fading, and the fading magnitude varies for different Tx-Rx antenna sub-array combinations. Although the multipaths are not rich in outdoor mmWave channels, the phases of the multipaths change over sub-carriers, which lead to different channel coefficients and hence different channel matrices over sub-carriers. Therefore, the channel condition numbers over different sub-carriers vary significantly. The corresponding channel condition number for each sub-carrier is plotted in Fig. 4, which clearly shows the fluctuation of the channel condition number over sub-carriers, where the discrepancy can exceed 12 dB.

IV. ULA ARRAY PATTERN

A. Sub-Array Antenna Element

The azimuth and elevation sub-array radiation pattern would depend on M in each sub-array and their individual element radiation pattern ($E(\theta)$). A typical sub-array element can be designed as a rectangular or circular patch antenna. Both

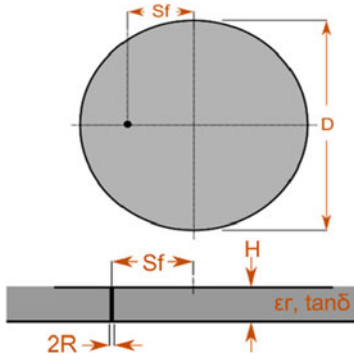


Fig. 5. Sub-array patch antenna element.

 TABLE IV
 SUB-ARRAY ELEMENT DESIGN PARAMETERS

Parameter	Value	
f_c (GHz)	28	37
D (mm)	4.265	3.277
S_f (μm)	477.1	361.0
R (μm)	28.39	21.48
H (μm)	227.1	171.9
ϵ_r	2	2

circular and rectangular patches have similar gain, beam position and efficiency. The circular patch however offers slightly narrower beamwidth and smaller physical area. Circular patches have increasingly become popular as they can offer increased levels of linear polarisation, frequency agility, viable mechanical properties and stability [77]–[79]. A circular pin-fed antenna patch is employed in this paper and its design parameters are given in Fig. 5 [80], where D , S_f , R , H , ϵ_r and $\tan\delta$ are the patch diameter, feed offset, feed pin radius, substrate height, relative permittivity and loss tangent due to the substrate medium respectively.

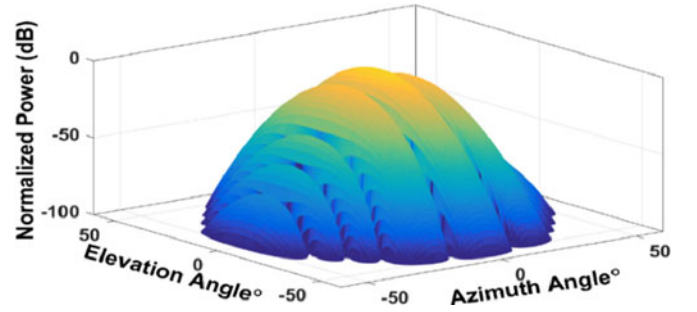
The patch antenna element was modelled using CST MICROWAVE STUDIO Antenna Magus for a frequency f_c as listed in Table IV.

$E(\theta)$ and impedance at 28 GHz and 37 GHz for the circular patch are obtained using parameters in Table IV. Achieving stable impedance values at RF frequencies is one of the main challenges to be addressed in the element design. The elements have similar characteristics such as a gain of 7.5 dBi and HPBWs of 87.2° and 79.1° for both E and H planes at 28 GHz and 37 GHz respectively. The dominant mode is TM_{11} and the radiation pattern is a single lobe with maximum in the direction normal to the plane of the antenna. Elements with similar characteristics can be designed at 64 GHz and 71 GHz.

B. Super-Array Element Spacing and Grating Lobes

The spatial response of a ULA with N array elements, with element amplitude and spacing of A_n and δ , and signal incident to the ULA at an angle θ is given by the array factor (AF):

$$AF = \sum_{n=1}^N A_n e^{j\frac{2\pi}{\lambda}\delta n \sin\theta}. \quad (4)$$


 Fig. 6. 28 GHz configuration C_{M4} super array pattern, two sub-arrays each with 4 patch antennas.

Assuming identical $E(\theta)$ for each element in ULA, the array pattern ($F(\theta)$) is then given by the pattern multiplication:

$$F(\theta) = E(\theta) \cdot AF \quad (5)$$

In the case that N elements are divided into N_T sub-arrays where elements per sub-array is $M = \frac{N}{N_T}$, then the sub-array pattern $F(\theta)_{SubA}$ is accordingly given by:

$$F(\theta)_{SubA} = E(\theta) \cdot \sum_{m=1}^M A_m e^{j\frac{2\pi}{\lambda}d_{SA} \sin\theta} = E(\theta) \cdot AF_{SubA}. \quad (6)$$

The array pattern of the ULA super array beamforming then can be obtained by summing over the total number of sub-arrays and is given by [81]:

$$F(\theta) = F(\theta)_{SubA} \cdot \sum_{n_t=1}^{N_T} B_{n_t} e^{j\frac{2\pi}{\lambda}d \sin\theta} \quad (7)$$

where $\sum_{n_t=1}^{N_T} B_{n_t} e^{j\frac{2\pi}{\lambda}d \sin\theta}$ is the array factor AF_{SA} for the super-array.

From (5) and (6):

$$F(\theta) = (E(\theta) \cdot AF_{SubA}) AF_{SA}. \quad (8)$$

The array pattern $F(\theta)$ of C_{M4} super-array with two sub-arrays and elements with radiation pattern $E(\theta)$ obtained is plotted in Fig. 6 with MATLAB R2016a where the sub-array separation is $d = 2\lambda$. This would be identical to a combined ULA with an element spacing of $\frac{\lambda}{2}$ for all the 8 elements. The azimuth HPBW is 12.6° ($\pm 6.3^\circ$) and elevation HPBW is 88° ($\pm 44^\circ$). For further increase in the number of sub-array elements i.e., $M \geq 8$ the azimuth HPBW $\leq 6.3^\circ$ ($\pm 3.3^\circ$) and is taken as 7° which is the lower limit in NYUSIM v1.5. The elevation HPBW remains constant and is taken as 45° that is the upper limit in NYUSIM v1.5. A smaller elevation HPBW would not affect the SM since the azimuth HPBW is more critical for horizontal ULAs.

In LOS, the L2 sub-arrays must maintain the lateral separation for favourable MIMO channel conditions. If we increase the number of sub-arrays to increase the channel capacity to realize the 3×3 and 4×4 MIMO, i.e., for the same configuration C_{M4} $d = 2\lambda$ between the sub-arrays, the channel condition number degrades as given in Fig. 7. Fig. 7 gives the CDF plot for 100 random channel realizations using NYUSIM v1.5 which indicate that the 50% median value for the channel condition

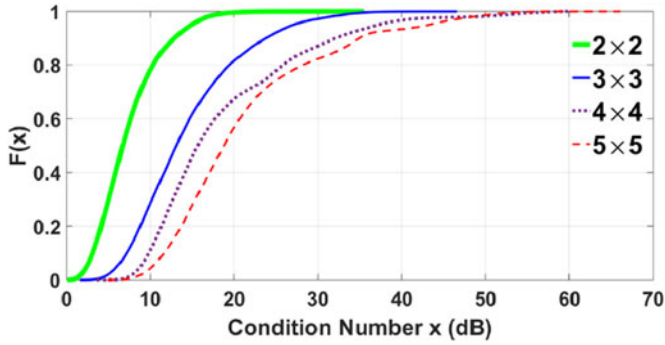


Fig. 7. 28 GHz MIMO channel condition number CDF plot for C_{M4} , $N_T = N_R = 2, 3, 4$ and 5 .

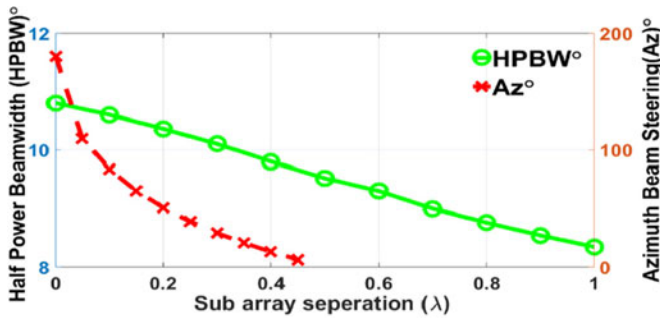


Fig. 8. Reduction in azimuth HPBW and beam steering angle at 28 GHz.

number increases from 6.7 dB to 13.1 dB and 16 dB for 2×2 , 3×3 and 4×4 MIMO channels respectively. As the number of MIMO channels increases for the same lateral separation of the sub-arrays, the channel condition number increases indicating unfavourable propagation conditions for MIMO SM. For the 5×5 MIMO, not only the median value increases to 18.9 dB, but also the steepness of the curve decreases indicating overall higher channel condition number values than the previous curves and hence unfavourable conditions for a MIMO channel.

As d increases the azimuth visible region reduces due to formation of the grating lobes which results in reducing the azimuth sector scan (the beam steering angle) of the super-array. The super-array at L2 consists of two sub-arrays each with an element spacing of $\frac{\lambda}{2}$ (which is fixed and does not change), however, the decrease in the beam steering angle is due to increment in d i.e., Δd in terms of λ which is given in Fig. 8. As d increases, the beam steering angle reduces from 180° ($\pm 90^\circ$) at $\Delta d = 0$ to 6° ($\pm 3^\circ$) at $\Delta d = 0.45\lambda$. As expected, the azimuth HPBW also reduces from 10.8° at $\Delta d = 0$ to 8.3° at $\Delta d = \lambda$.

C. Quantization Lobes

Consider the C_{M16} configuration as in Fig. 9(a) wherein phase shifters are applied only at the sub-array level for $N_T = 2$ with $d = 8\lambda$ satisfying the condition in (1) and Fig. 9(b) the phase shifters are applied at the element level. In both cases a single RF chain is used for a single sub-array.

As the sub-array spacing meets condition (1) and there is no beam steering i.e., steering angle $\alpha = 0$ there are no grating

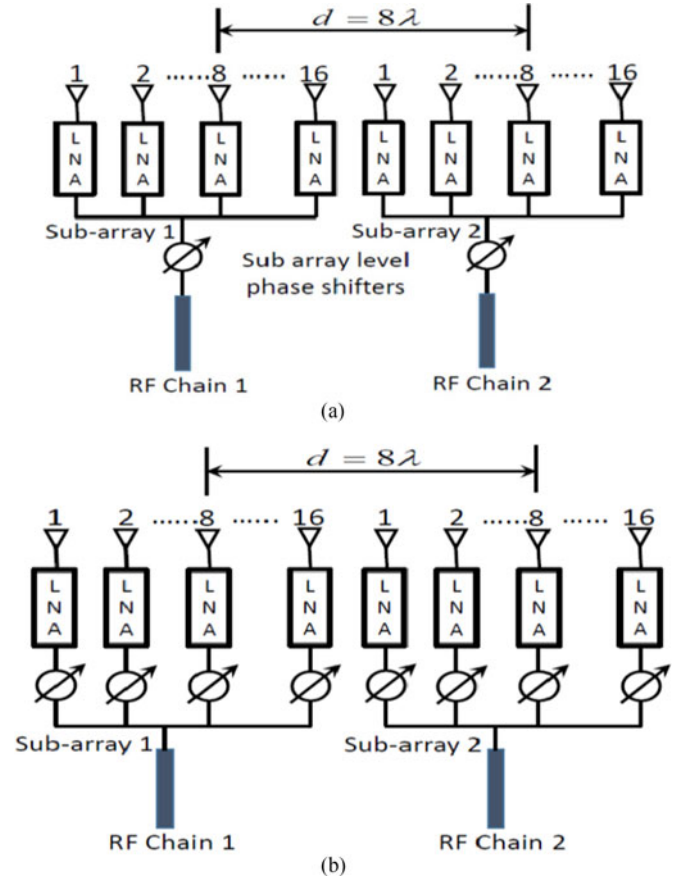


Fig. 9. (a) C_{M16} with sub-array level phase shifting. (b) C_{M16} with element level phase shifting.

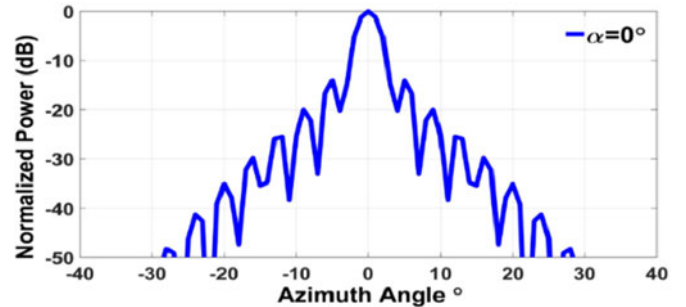
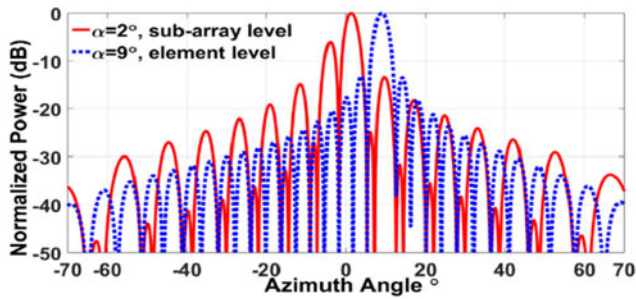
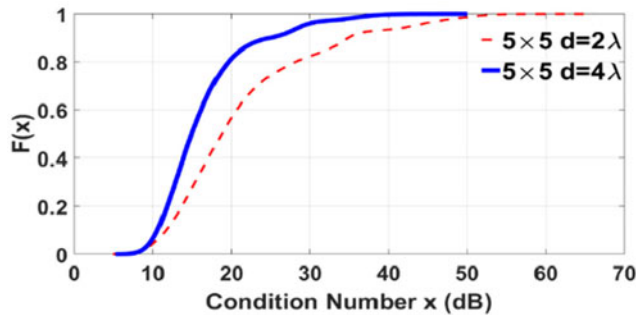


Fig. 10. 28 GHz configuration C_{M16} azimuth pattern with no beam steering.

lobes or quantization lobes observed in the azimuth pattern as given in Fig. 10.

When the beam is steered at α the quantization errors result in the formation of quantization lobes. The quantization lobes occur at the position of grating lobes. The quantization lobe amplitudes increase with increase in the beam steering angle. The effect of quantization lobes on the overall super array pattern is given in Fig. 11 as α increases from 2° to 9° . Even for a small steering angle of $\alpha = 2^\circ$ quantization lobes appear due to larger phase quantization steps as phase shifting is at the sub-array level as shown in Fig. 9(a). For element level phase shifters in Fig. 9(b) the levels of quantization lobes are marginal even for $\alpha = 9^\circ$. The sub-array elements have phase progression equal to the quantized phased phase shift $\Delta\phi_D$ spaced at $M \times d$.


 Fig. 11. 28 GHz configuration C_{M16} azimuth pattern with beam steering.

 Fig. 12. Channel condition number for 2×2 MIMO configuration C_{M4} .

Since $M \times d$ is likely to be several wavelengths long, the sub-arrays will generate a number of quantization lobes at θ_{QL} given by [82]:

$$\theta_{QL} = \sin^{-1} \left(\frac{\Delta\phi_D}{kMd} \right). \quad (9)$$

V. SIMULATION RESULTS

A. Channel Condition Number

With a view to improve the channel condition number for C_{M4} in Fig. 7, d is increased from 2λ to 4λ for the 5×5 MIMO 28 GHz channel. The channel condition numbers in Fig. 12 indicate an improvement of 4 dB from 18.9 dB to 14.9 dB for 50% median values, indicating improved channel performance with increase in lateral separation. However, the later configuration would be severely restricted in terms of adequate beam steering as indicated in Fig. 8.

In view of the limitations in the mentioned configuration, an alternative is to increase the number of sub-array elements. This will offer reduction in the HPBW in azimuth leading to increase in directivity. It also increases the lateral separation thereby increasing the possibility of improved channel condition number even for higher configurations such as for 3×3 and 4×4 MIMO. Consider C_{M8} with two sub-arrays each with $d = 4\lambda$ to ensure condition in (1) which now corresponds to a single ULA of 16 elements. The channel condition number is plotted in Fig. 13 indicating lower 50% median values of 6.5 dB, 10.6 dB and 14.2 dB for 2×2 , 3×3 and 4×4 MIMO as compared to the 4-element antenna sub-array configuration C_{M4} in Fig. 7.

The channel condition number decreases for super-array with a higher number of elements as this increases the sub-array spacing indicating favourable MIMO propagation even for further

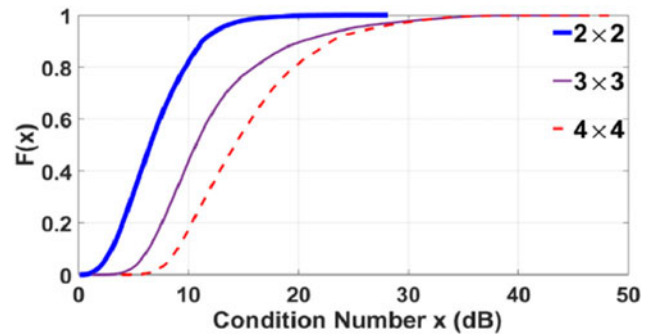
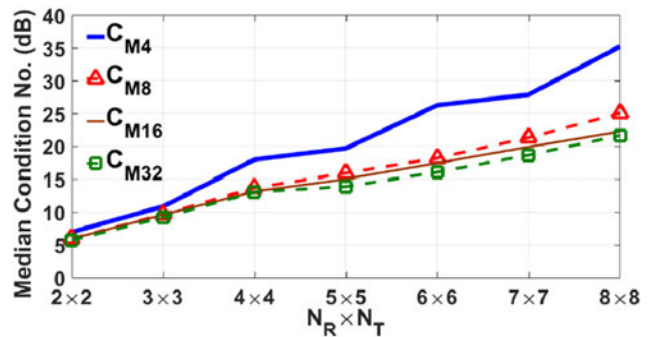

 Fig. 13. 28 GHz MIMO channel condition number CDF plot for C_{M8} .


Fig. 14. 28 GHz MIMO channels.

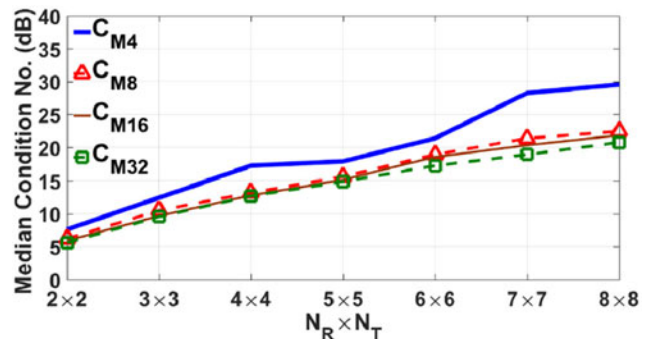


Fig. 15. 37 GHz MIMO channels.

increases in number of $N_R \times N_T$ elements at L2. This is evident from Fig. 14 where the median channel condition number for 28 GHz is plotted for C_{M4} , C_{M8} , C_{M16} and C_{M32} with increase in $N_R \times N_T$. As M increases, the sub-array distance d increases without violating the grating lobe condition in (1). The increase in M therefore supports higher number of MIMO channels. A C_{M4} can support up to 5×5 with channel condition number of 19.6 dB, while for C_{M8} , one can have favourable propagation conditions up to 6×6 while C_{M16} and C_{M32} can support up to 7×7 with maximum condition numbers ~ 20 dB. As M increases from 4 to 8, the decrease in the median channel condition number is higher than for further subsequent increases in M . Although there is a trade-off between M and the array size, increasing M will not only increase the number of MIMO channels for SM but have other known benefits such as higher directivity and narrower beamwidth.

Similar variations are observed for 37 GHz, 64 GHz and 71 GHz as in Figs. 15–17, respectively, which is conformity to

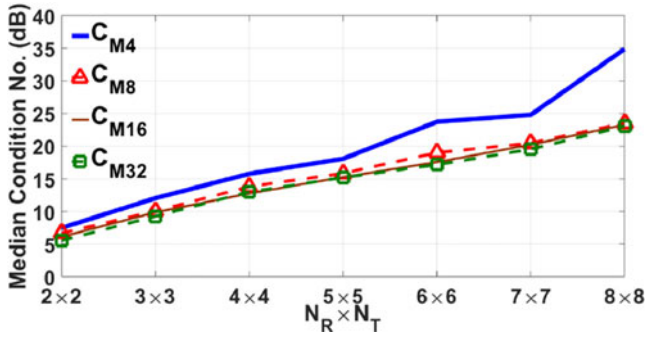


Fig. 16. 64 GHz MIMO channels.

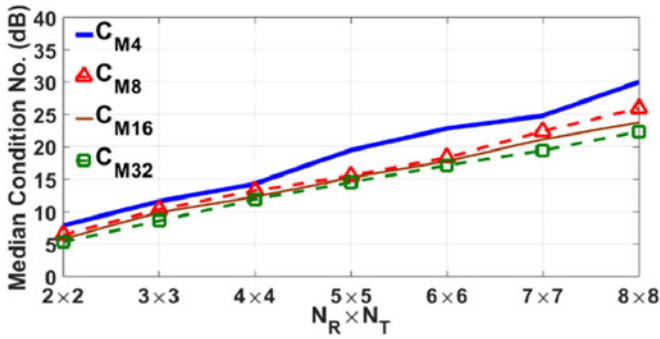


Fig. 17. 71 GHz MIMO channels.

the observation that mmWave MIMO channels behave almost identical for LOS channel conditions [45].

B. MIMO Spectral Efficiencies

The spectral efficiency of a MIMO-OFDM system, assuming equal power allocation to each Tx antenna sub-array, can be expressed as follows:

$$R = \frac{1}{\text{BW}} \int_{f_{min}}^{f_{max}} \log_2 \det \left(\mathbf{I} + \frac{\rho}{N_T} \mathbf{H}_f \mathbf{H}_f^H \right) df \quad (10)$$

where R denotes the spectral efficiency achievable using eigen beamforming, BW represents the RF bandwidth, f_{min} and f_{max} stand for the minimum and maximum sub-carrier frequency, respectively, ρ is the received SNR, N_T denotes the number of transmit antenna sub-arrays, and \mathbf{H}_f represents the MIMO channel matrix in the spatial domain (normalized by the corresponding path loss) for the sub-carrier frequency f . Fig. 18 shows the spectral efficiency as a function of received SNR for a MIMO-OFDM channel with three transmit antenna sub-arrays and two receive antenna sub-arrays for a variety of sub-array spacing at 28 GHz. It is evident from Fig. 18 that the spectral efficiency increases as the sub-array spacing grows from $1/2\lambda$ to 4λ for a fixed SNR. It is noteworthy that an increase of the sub-array spacing from 2λ to 4λ does not increase the spectral efficiency as substantially as from $1/2\lambda$ to λ and from λ to 2λ , which indicates that further increasing the sub-array spacing may not have a significant impact on spectral efficiency.

As the number of sub-array elements M increases the HPBW reduces leading to a more pencil beam which increases SM in LOS-MIMO. However the increase in dividend cannot be expected for ever increasing values of M . At 28 GHz frequency

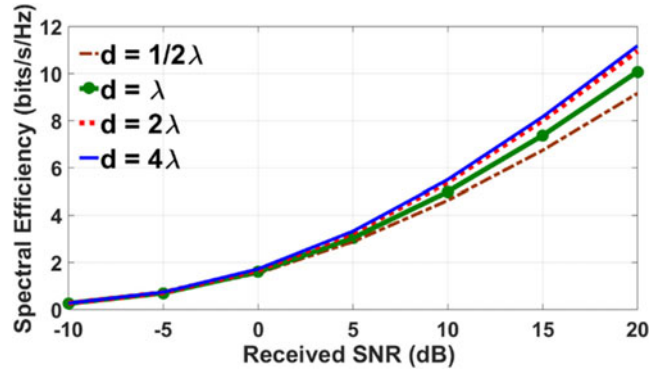


Fig. 18. Spectral efficiency for 28 GHz MIMO-OFDM channel with three transmit antenna sub-arrays and two receive antenna sub-arrays.

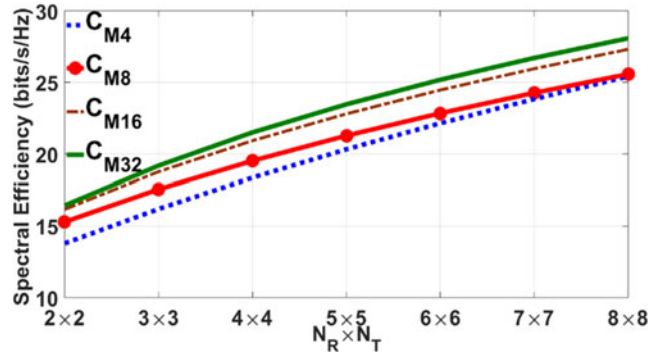


Fig. 19. Spectral efficiency 28 GHz MIMO-OFDM channels.

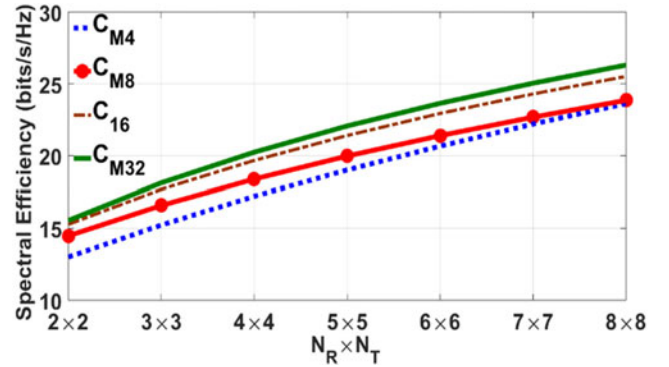


Fig. 20. Spectral efficiency 37 GHz MIMO OFDM channels.

this is evident from Fig. 19 in which the spectral efficiency increases, as the sub-array spacing d increases. The increase in d is due to increase in lateral separation of the sub-arrays as M increases. However the increase in spectral efficiency is most significant only when d grows from 4λ (C_{M8}), to 8λ (C_{M16}). Maximum dividend is accordingly obtained for a sixteen element sub-array. This is observed for a T-R separation distance of 500 m, and each spectral efficiency curve is averaged over 100 random channel realizations.

Figs. 20–22 illustrate achievable spectral efficiency of MIMO channels with ULA sub-array spacing of 2λ (C_{M4}), 4λ (C_{M8}), 8λ (C_{M16}), and 16λ (C_{M32}) at the Tx and Rx at 37, 64, and 71 GHz, respectively indicating similar behaviour in terms of increase in M and the corresponding spectral efficiencies that are achieved. Furthermore, for an identical sub-array spacing, the average SNRs and spectral efficiencies are the highest at 28 GHz,

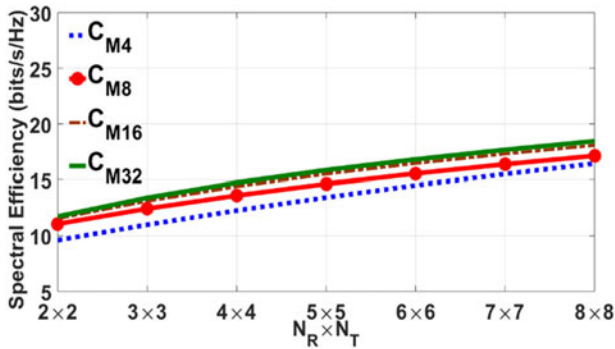


Fig. 21. Spectral efficiency 64 GHz MIMO-OFDM channels.

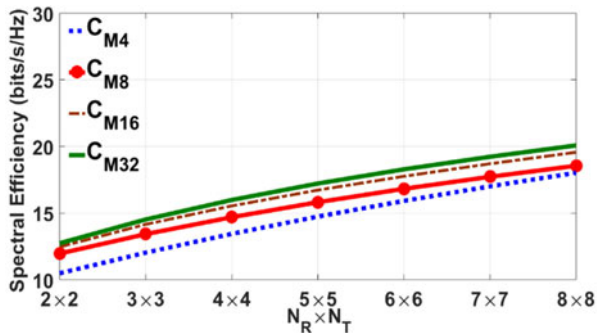


Fig. 22. Spectral efficiency 71 GHz MIMO-OFDM channels.

and are slightly lower at 37 GHz, while 64 GHz channel yield the lowest average SNR and spectral efficiency due to severe oxygen absorption and/or other types of attenuation.

Channel condition numbers and MIMO capacities indicate good correlation in terms of channel performance. Channel condition numbers indicate a value of 20 dB for 7×7 MIMO at all the frequencies except at 64 GHz which is 24 dB, and also has the lowest spectral efficiency. As increase in spectral efficiency is most at $8\lambda(C_{M16})$ it may not be necessary to employ arrays with a higher number of sub-array elements. From Table I the C_{M16} array size is in the range of 6.5–16.6 cm depending on the frequency for 2×2 MIMO and this range increases to 26.83–68 cm for a 7×7 MIMO channel.

VI. CONCLUSION

An architecture for ULAs based on beamforming with SM for mmWave 5G mobile services is proposed in this paper. The approach utilizes a single array that can employ single or multiple beams for beamforming at low SNR and cell edge scenarios. The array comprises of sub-arrays that configure as radiating elements for SM in high SNR LOS conditions for MIMO channels to increase the peak data rates, thereby giving the flexibility of employing a single ULA architecture in both low and high SNR MIMO conditions. The ULA element has been designed with CST MICROWAVE STUDIO and array patterns developed using MATLAB R2016a generating HPBW input parameters for the NYUSIM v1.5 simulator. Simulation results obtained from the NYUSIM v1.5 simulator indicate spectral efficiencies of 18.5–28.1 bits/s/Hz with a sub-array spacing of 16 wavelengths for outdoor mmWave urban LOS transmission at the recently allocated 5G carrier frequencies by the FCC in July 2016.

Formation of two or more spatial lobes for the AODs and AOA even for LOS scenarios in mmWave propagation is a characteristic that can be leveraged by beamforming and employed for SU-MIMO where the transmitting and receiving array elements can be co-located. The proposed architecture not only ensures adequate coherency between the array elements required for beamforming, but also results in adequate spatial separation during SM without violating the conditions for grating and quantization lobe formation that restricts the beam steering angle. The analysis will be extended to uniform rectangular arrays (URAs), the results of which may be reported in a future publication.

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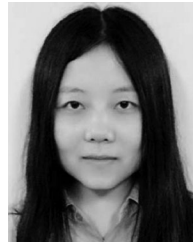
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