

# HEMT Average Temperature Determination Utilizing Low-Power Device Operation

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**Abstract**—The modified thermal device model was adapted to determine the channel temperature of the AlGaIn/GaN HEMT operating under pulsed and quasi-static conditions. The differential analysis of the isothermal and thermal part of the resulting current, as well as ambient temperature variation, is utilized to determine the average channel temperature. Ambient temperature increases in the device operating range is required under low-power operation only, while under high-power operation the thermal stress of the device is significantly reduced due to small ambient temperature variation. In addition, trapping phenomena incorporation is demonstrated to obtain more accurate results utilizing the HEMT threshold voltage shift and transconductance. For experimental verification of the thermal model, Al<sub>0.25</sub>Ga<sub>0.75</sub>N/GaN HEMT electrical properties are investigated. Experimentally verified results are in a good agreement with numerical simulations.

**Index Terms**—AlGaIn, average channel temperature, charge trapping, FET, GaN, HEMT.

## I. INTRODUCTION

THE high mobility combined with a high carrier density in two-dimensional electron gas (2DEG) in gallium nitride (GaN)-based wide bandgap structure gives an opportunity to fabricate the advanced electrical devices like high electron mobility transistors (HEMTs) exhibiting superior properties in the field of high-power, temperature, frequency, and microwave applications [1], [2], [3]. However, high operating voltage resulting in a high local electric field and dissipated power density bringing device self-heating have an impact on the device reliability although those negative phenomena

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are nowadays suppressed by advanced horizontal and vertical device design such as substrates with high thermal conductance utilization [4], [5], [6].

Besides plenty of experimental methods to estimate device operation temperature like Raman spectroscopy or interferometric mapping [7], [8] electrical measurements utilizing low-power operating regime including external heating [9], [10] were employed taking advantage from specific electro-thermal device properties if the active device itself is concerned as temperature sensor [11], [12].

Here isothermal and thermal processes are required to be sorted to obtain relevant results. Besides that, the device reliability plays a significant role during the measurements when ambient temperature variation along the operating temperature range is required. Moreover, pulse measurements suffer from finite applied voltage increase and real device electrical parasitic capacitance. Therefore, low-power measurements are utilized, the quasi-static and pulse measurements relation is highlighted, and isothermal current at the beginning of the pulse is estimated. The theoretical considerations are possible to be applied for ungated or gated field-effect transistor (FET) structure neglecting gate current. In this work, they are practically utilized to acquire AlGaIn/GaN HEMT channel average temperature based on hypothetical situation demonstrated by infinite channel thermal conductance in the active device area where power density inside plays no role to avoid thermal gradient calculations. The obtained experimental results under low-power and high-power operations are compared taking average temperature meaning into account and subsequently verified by temperature profile simulations.

## II. THEORY

The same temperature is supposed to be reached along the device active area corresponding to the average temperature  $T_A$  [13]. The resultant current  $I_{DS}$  change between two ohmic contacts of gated or ungated FET structure is described by thermal current change  $dI_T$ , assigned to  $dT_A$  including thermal thermal change of carrier concentration, velocity and mobility, and isothermal current change  $dI_E$  at defined time interval  $dt$ . Isothermal current change  $dI_E = dI_{VE} + dI_{TE}$  is related to  $dI_{VE}$  caused by immediate applied gate voltage  $V_{GS}$  or drain voltage  $V_{DS}$  change including parasitic electric capacitance charge. The term  $dI_{TE}$  corresponds to trapped charge isothermal variation [13]. Trapped charge variation under the

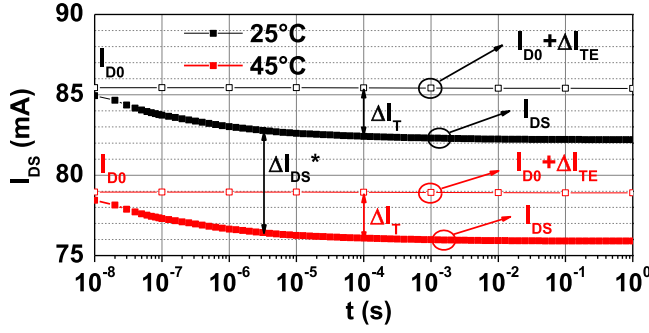


Fig. 1. Measured current  $I_{DS}$ , initial current  $I_{D0}$ , isothermal current  $I_{D0} + \Delta I_{TE}$  at  $V_{DS} = 2$  V.

gate is linearly assigned to threshold voltage  $V_{TH}$  shift of gated structure because of virtual gate superposition [14]. The correct  $dI_T$  and  $dI_E$  acquisition during time interval  $dt$  is requisite for proper  $dT_A$  determination.

Ambient temperature and zero dissipated power along the device active area are the initial conditions. After rectangular  $V_{GS}$  or  $V_{DS}$  pulse application at the zero time, the resultant current  $I_{D0} = I_{DS}(0)$  is reached supposing negligible rising time in comparison to thermal time constants.

### A. Low-Power Operation Condition

Coming out from  $T_A$  definition [13] for rectangular voltage pulse for small power dissipation  $P(t) = V_{DS}(t)I_{DS}(t)$  and inconsiderable  $P(t)$  variation the thermal resistance  $\Delta R_A(t, T_0) = T_A/P(t)$  is defined at time  $t$  and low-power ambient temperature  $T_{0L}$  utilizing  $\Delta T_A = T_A - T_{0L}$ . In the FET case, linear operating regime exhibits relatively low spatial deviation of the power dissipation and temperature distribution along the device active area.

The device investigated at two ambient temperatures  $T_{0L}$ ,  $T_{0L} + \Delta T_{0L}$  of relatively small difference  $\Delta T_{0L}$  exhibits the active area differential temperature  $\Delta T_A^*$  and differential current  $\Delta I_{DS}^* = k_T \Delta T_A^*$  resulting in  $\Delta T_A/\Delta T_A^* = \Delta I_T/\Delta I_{DS}^*$  utilizing  $\Delta T_A = T_A - T_{0L}$  and  $\Delta I_T \approx I_{DS}(t) - I_{D0} - \Delta I_{TE}(t)$  because of the same thermal coefficient  $k_T$  and relatively small  $P(t)$  variation during low-power operation [13], [14] as illustrated in Fig. 1. Isothermal trapping phenomena are covered by the term  $\Delta I_{TE}$ .

Therefore,  $R_A$  is possible to be calculated under low-power operation condition. The  $V_{GS}$  or  $V_{DS}$  step is required to be sufficiently high to acquire  $\Delta I_T$ . Dissipated power difference  $\Delta P^*(t) = V_{DS} \Delta I_{DS}^*(t)$  brings  $\Delta \Delta T_A^* = T_{0L} + R_A(t, T_{0L}) \Delta P^*(t)$ . Subsequently,  $R_A$  is yielded as

$$\Delta R_A(t, T_{0L}) = \frac{\Delta T_{0L} I_T}{V_{DS} \Delta I_{DS}^*(t)} [I_{D0} + \Delta I_{TE}(t)]^{-1}. \quad (1)$$

Dissipated power change  $|\Delta P^*(t)| \ll \Delta T_{0L}/R_A(t, T_{0L})$  caused by  $\Delta I_{DS}^*$  variation turns (1) into the simplified form possible to be utilized especially for low  $V_{DS}$  under low-power device operation

$$\Delta R_A(t, T_{0L}) = \frac{\Delta T_{0L} I_T}{V_{DS} \Delta I_{DS}^*(t) I_{DS}(t)}. \quad (2)$$

### B. Average Temperature Estimation Possibilities

The ambient temperature  $T_{0H}$  for high-power operation is required to be distinguished from low-power operation ambient temperature  $T_{0L}$  for  $T_A$  recurrent calculations purposes in the way  $T_{A,n} = T_{0H} + \sum_{k=1}^n \Delta T_{A,k}$  utilizing integer series coefficients  $k$  and  $n$ . The average temperature difference  $\Delta T_{A,k}$  is linearly dependent on dissipated power or time variation at  $T_{A,k} = T_{0L}$  utilizing  $R_A(t_k, T_{A,k}) = R_A(t, T_{0L})$  or normalized thermal resistance  $k_{R,k} = R_A(t_k, T_{A,k})/R_A(t_k, T_{0H})$  from low-power measurements.

Under the quasi-static state device operation,  $R_A(t \rightarrow \infty, T_{A,k}) = R_{A\infty}(T_{A,k})$  is utilizing [15] resulting in

$$\Delta T_{A\infty,n} = T_{0H} + \sum_{k=1}^n R_{A\infty}(T_{A,k}) P_k. \quad (3)$$

The  $T_A$  increase coming out from operation state time superposition results in  $dT_A(t)/dt \approx P(t)dR_A(t, T_A)/dt$ . This is applicable for rectangular pulse operation of small proportional  $P(t)$  variation under high-power and low-power operation and results in

$$\Delta T_{A,n} = T_{0H} + \sum_{k=1}^n [dR_A(t_k, T_{A,k})/dt] P(t_k) t_k. \quad (4)$$

Although FET operating in the saturation regime exhibits eligible temperature gradient and strongly uneven power dissipation along the active area in comparison to linear regime, the proper  $T_A$  interpretation provides this method applicable.

### C. Differential Average Temperature Calculation

To avoid  $T_A$  misinterpretation for the high-power  $V_{GS}$  or  $V_{DS}$  pulse response due to different high-power  $R_A(t, T_A)$  and low-power  $R_A(t, T_{0L})$  values at  $T_A = T_{0L}$  caused by partially various heat flux spatial distribution along the device active area, the low-power operation is utilized to obtain  $k_R(t, T_{0L}) = R_A(t, T_{0L})/R_A(t, T_{0H})$  only. The condition of similar normalized thermal resistance  $k_R$  for both cases is better fulfilled coming out from  $T_A$  definition [15].

The high-power  $I_{DS}$  time dependence is required to be obtained at two ambient temperatures of relatively small ambient temperature difference  $\Delta T_{0H}$  corresponding to active area temperature difference  $\Delta T_A^*$  and resultant current difference  $\Delta I_{DS}^*$ . Subsequently,  $dT_A = \Delta T_A^* dI_T/\Delta I_{DS}^*$  is calculated utilizing thermal current contribution  $dI_T = dI_{DS} - dI_{TE}$  during  $dt$  at  $t$  and  $T_A$  including isothermal trapping current contribution  $dI_{TE}$ .

The difference  $\Delta T_{0H}$  results in  $\Delta P^*(t) = V_{DSn} \Delta I_{DS}^*(t)$  and  $\Delta \Delta T_A^* = [R_A(t, T_A)/R_A(t, T_{0H})] T_{0H} + [R_A(t, T_A)] \Delta P^*(t)$  [15], [16]. For thermal resistance and capacitance defined at  $T_{0H}$  the average temperature contribution  $dT_{A0} = dT_A/k_R$ ,  $\Delta T_{A0}^* = \Delta T_A^*/k_R$  are possible to be defined utilizing  $\Delta T_{A0}^* = \Delta T_{0H} + R_A(t, T_{0H}) \Delta P^*(t)$ ,  $\Delta R_A(t, T_{0H}) = T_{A0}/P(t)$  coming out from linear  $\Delta T_{A0} = T_{A0} - T_{0H}$  dependence versus dissipated power. Therefore,  $T_{A0}$  and  $T_A$  increase result in

$$dT_{A0} = [\Delta T_{0H} + R_A(t, T_{0H}) \Delta P^*(t)] dI_T/\Delta I_{DS}^* \quad (5)$$

$$dT_A = k_R(t, T_A) dT_{A0}. \quad (6)$$

The term  $R_A(t, T_{0H})$  in (5) is estimated from the previous operating point. Recurrent calculations allow average

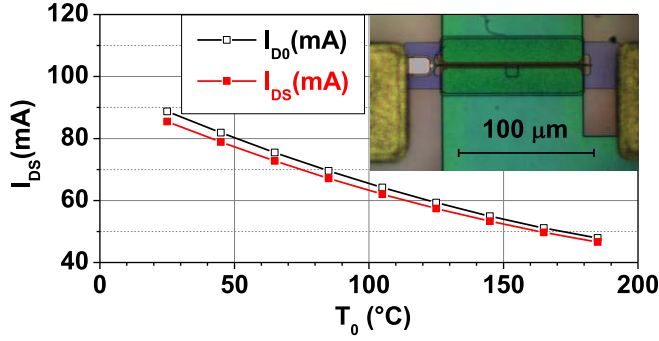


Fig. 2. Temperature dependence of measured current  $I_{DS}$  at  $t \approx 1$  s and initial current  $I_{DO}$  at  $V_{DS} = 2$  V. (Inset: top view microscope image of investigated HEMT.)

temperature time dependence acquisition  $T_{A0,n} = T_{0H} + \sum_{k=1}^n \Delta T_{A0,k}$  and  $T_{A,n} = T_{0H} + \sum_{k=1}^n \Delta T_{A,k}$  using (5) as  $\Delta T_{A0,k} = [\Delta T_{0H} + R_{A,k-1}(t, T_{0H}) \Delta P_k^*(t)] \Delta I_{T,k} / \Delta I_{DS,k}^*$  and (6) as  $\Delta T_{A,k} = k_{R,k} \Delta T_{A0,k}$  corresponding to  $\Delta t_k$ .

The condition  $R_A(t, T_{0H}) \Delta P^*(t) \ll \Delta T_{0H}$  and  $|dI_{TE}| \ll |dI_{DS}|$  turns (5) into  $dT_A = k_R \Delta T_{0H} dI_{DS} / \Delta I_{DS}^*$ . However, the term  $R_A(t, T_{0H}) \Delta P^*(t)$  for high  $V_{DS}$  plays significant role in (5).

The recursive way of recurrent calculations starting at the end of long  $V_{GS}$  or  $V_{DS}$  pulse equivalent to quasi-static state and initial conditions  $R_{A\infty}$  and  $T_{A\infty}$  gives opportunity to avoid  $I_{DO}$  and  $P(t)$  estimation at the beginning of the voltage pulse. On the other hand,  $dI_{TE}$  is possible to be neglected in (5) at the pulse beginning.

### III. EXPERIMENTAL

#### A. Structure Design and Experimental Setup

The 14 nm  $\text{Al}_{0.25}\text{Ga}_{0.75}\text{N}/1.5$  nm  $\text{AlN}/1700$  nm  $\text{GaN}/75$  nm TBR heterostructure was grown by MOVPE on 70- $\mu\text{m}$ -thick 4H-SiC substrate and top ohmic drain–source and gate contacts were formed by standard Au-based metallization to fabricate gated transmission line model (GTL)  $\text{Al}_{0.25}\text{Ga}_{0.75}\text{N}/\text{GaN}$  HEMT of width  $w \approx 100$   $\mu\text{m}$  with a gate of length  $d_G \approx 0.15$   $\mu\text{m}$ , the source to gate gap of length  $d_{GS} \approx 0.75$   $\mu\text{m}$  and the drain to gate gap of length  $d_{GS} \approx 1.5$   $\mu\text{m}$  [17] as shown in the inset of Fig. 2. The substrate backside Au contact soldered to 1-mm-thick CuMo leadframe makes possible to set investigated device in the open package placed on the Al thermal chuck preserved at a constant temperature.

Semiconductor parameter analyzer Agilent 4155C and controlled thermal chuck were utilized to acquire  $I_{DS}$  time response on  $V_{DS}$  pulse of amplitude 2 and 20 V keeping zero  $V_{GS}$ . The chuck temperature was set in the range 25 °C–185 °C to compare low-power and high-power methods based on ambient temperature and threshold voltage variation. Pulse measurements were done by utilizing pulse generator unit (PGU) as the 4155C extension unit. White LED illumination for one minute between measurements was utilized for the device recovery. The 3-D model incorporating device geometry, layout, and thickness of individual layers was employed in the 3-D thermal FEM simulations performed

TABLE I  
THERMAL COEFFICIENTS

| Material       | Thermal conductivity<br>( $\text{W}\cdot\text{m}^{-1}\text{K}^{-1}$ ) |
|----------------|---|
| Au             | 310   |
| AlGaN          | $40\cdot(T/298)^{1.37}$   |
| GaN (C doped)  | $190\cdot(T/298)^{1.37}$  |
| 4H-SiC xy-axis | $430\cdot(T/298)^{1.5}$   |
| z-axis         | $370\cdot(T/298)^{1.5}$   |
| AuSn           | 57  |
| CuMo           | 160   |

by Synopsys TCAD Sentaurus [18]. Material thermal conductivity and capacity values were obtained from the previous work and calibrated utilizing the measurements [19]. The constant ambient temperature boundary condition is set to the structure backside supposing ideal heat transfer between leadframe and heatsink. The structure self-heating is simulated by three thermal contacts placed along 2DEG between drain and source corresponding to the dissipated power source located: 1) along drain to source access region; 2) region under the gate electrode; and 3) pinch-off region located at the drain side gate edge [20]. The material thermal coefficients for the structure model and thermal boundary resistance (TBR) of the interfaces were taken from the literature and subsequently calibrated using infrared imaging measurement and micro-Raman thermometry [20].

The thermal coefficients for the FEM simulation are in Table I. The TBR is set to  $1 \times 10^4$   $\text{cm}^2\text{KW}^{-1}$  at the GaN/SiC interface. TBR value of 2  $\text{cm}^2\text{KW}^{-1}$  is set at the CuMo leadframe/cooler interface. The cooler temperature is set to a constant ambient temperature. It represents an ideal heatsink.

#### B. Trapping Phenomena Determination

The short-pulsed, long-pulsed, or quasi-static transfer  $I - V$  characteristics measured at the same  $T_{OL}$  and  $V_{DS}$  are assumed pointing on the same threshold voltage  $V_{TH}$  independent on  $V_{GS}$  for the trapping free device. Therefore,  $V_{TH}$  shift gives opportunity to incorporate time dependent isothermal trapping phenomena under the gate to determine  $T_A$  [13].

To acquire  $V_{TH}(t \rightarrow 0, T_{OL})$  and isothermal transconductance  $g_{M0}(T_{OL})$ , pulsed transfer  $I - V$  characteristics of pulse length  $\sim 100$  ns, constant amplitude  $V_{DS} = 2, 20$  V, sweeping amplitude  $V_{GS}$  in the range  $-4$  to  $0$  V, and  $T_{OL}$  range 25 °C–185 °C were measured.

The  $I_{DS}$  time response was acquired using a combined  $V_{DS}$  and  $V_{GS}$  pulse of length  $\sim 1$  s with a constant amplitude  $V_{DS} = 2, 20$  V, and a stepping amplitude  $V_{GS}$  in the range  $-4$  to  $-1$  V. This makes possible to approximate  $V_{TH}(t, T_{OL})$  for  $t$  step of one decade and  $T_{OL}$  step  $\sim 20$  °C. Thus, it is possible to obtain  $t$  and  $T_{OL}$  dependent trapped charge isothermal current variation  $\Delta I_{TE}(t, T_{OL}) = -g_{M0}(T_{OL})[V_{TH}(t, T_{OL}) - V_{TH}(t \rightarrow 0, T_{OL})]$ .

#### C. Thermal Resistance Determination

The  $I_{DS}$  time dependence for voltage pulse of amplitude  $V_{DS} \approx 2$  V,  $V_{GS} = 0$  V and length  $t_s \approx 1$  s was measured at

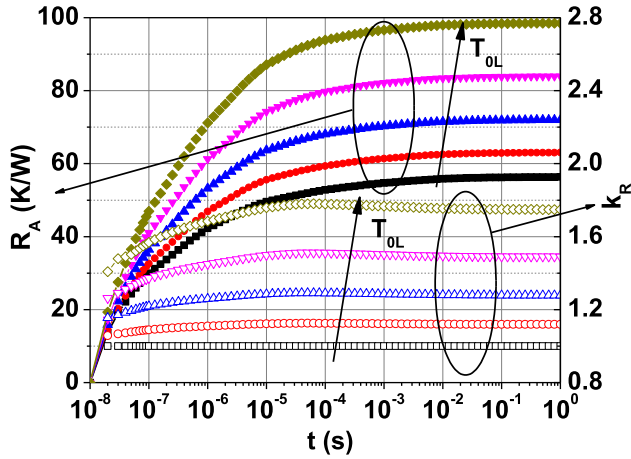


Fig. 3. Thermal impedance  $R_A$  and normalized thermal resistance  $k_R$  time dependence for  $T_{0L}$  in the range of 25 °C–185 °C (40 °C step).

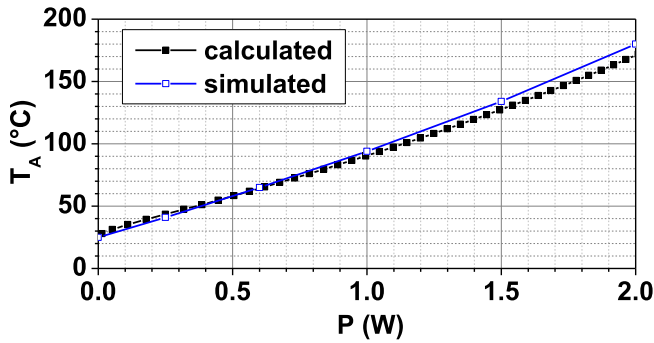


Fig. 4. Simulated and calculated average temperature  $T_A$  versus dissipated power in the quasi-static state.

varying ambient temperature  $T_{0L}$  in the range of 25 °C–185 °C with the step  $\sim 20$  °C as depicted in Fig. 1. Then  $I_{DS}$  approximation for  $20 \text{ ns} < t < 60 \text{ ns}$  by exponential function results in  $t_D \approx 5 \text{ ns}$  calculated by (A1) utilizing  $t_1 \approx 20 \text{ ns}$  and  $I_{D0}$  estimation by (A2) gives opportunity to plot  $I_{D0} + \Delta I_{TE}$  time dependence shown in Fig. 1.

The dependence of the measured current  $I_{DS}$  acquired at  $t \approx 1 \text{ s}$  equivalent to the quasi-static state on the ambient temperature and the estimated initial current  $I_{D0}$  at  $V_{DS} = 2 \text{ V}$  is shown in Fig. 2. The term  $\Delta I_{TE}$  exhibits  $\sim 2\%$ – $4\%$  of the term  $I_{DS} - I_{D0}$  under low-power operation.

Subsequently  $R_A(t, T_{0L})$  is calculated utilizing (1) and shifted by  $t_D \approx 5 \text{ ns}$  is shown in Fig. 3. For  $T_A$  determination under high-power operation at ambient temperature  $T_{0H} \approx 25$  °C,  $R_A(t, T_{0L})$  is normalized utilizing time-dependent  $k_R = R_A(t, T_{0L})/R_A(t, T_{0H})$  as depicted in Fig. 3.

#### D. Average Temperature Determination With Direct Use of Thermal Resistance

Utilizing  $R_{A\infty}(T_{A,k})$  obtained by (1) in recurrent calculations (3) results in average temperature determination in the quasi-static state as depicted in Fig. 4.

The dissipated power time dependence  $P(t)$  was calculated from  $I_{DS}$  and  $V_{DS}$  time response at  $T_{0H} \approx 25$  °C shown in Fig. 5. Employing  $t_1 \approx 70 \text{ ns}$  in (A1) results in  $t_D \approx 17 \text{ ns}$

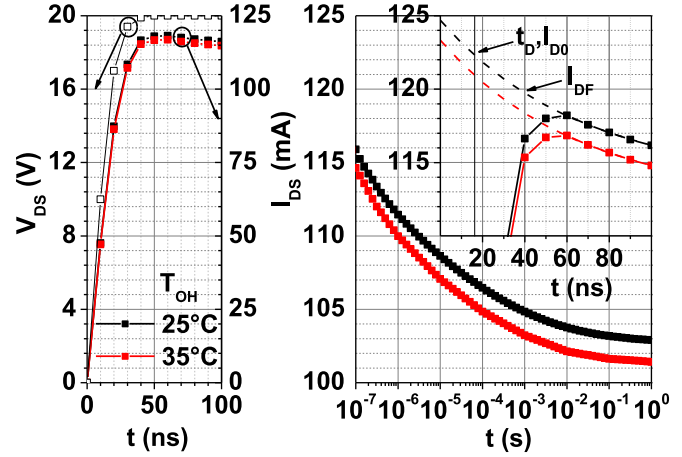


Fig. 5. Short-time  $V_{DS}$ ,  $I_{DS}$ , and logarithmic  $I_{DS}$  time dependence. (Inset: magnified  $I_{DS}$  at  $V_{DS} = 20 \text{ V}$ .)

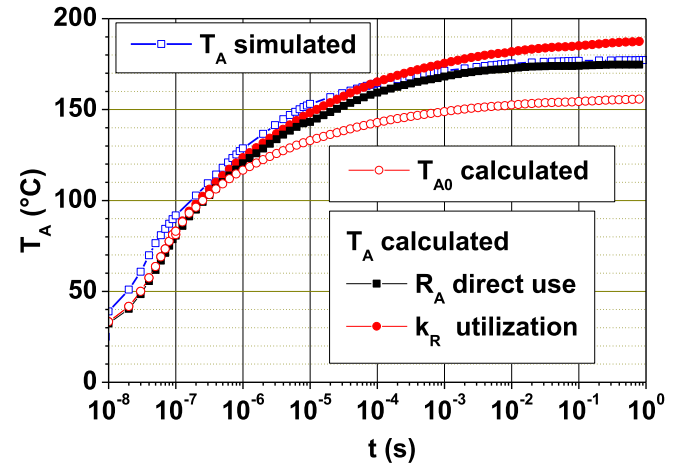


Fig. 6. Simulated and calculated average temperature  $T_A$  and  $T_{A0}$  versus time for pulsed operation.

and  $T_A(t_1)$  was estimated by (A4). Subsequently,  $T_A$  recurrent calculations (4) utilizing  $R_A(t_k, T_{A,k})$  obtained from Fig. 3 shifted by  $t_D \approx 17 \text{ ns}$  were applied to obtain  $T_A$  time dependence as shown in Fig. 6.

To compare calculated and simulated results, the source-to-gate serial resistance is supposed as the main thermal parameter for the HEMT [9]. The simulated average channel temperature of the source to the gate area is assumed as  $T_A$ . A good  $T_A$  correspondence with numerical simulations points on the small deviation between  $R_A(t, T_{0L})$  and  $R_A(t, T_A)$  utilized in the linear and saturation regime, respectively.

#### E. Average Temperature Determination Utilizing Normalized Thermal Resistance

The application of the method introduced in theoretical Section III-C is described below. The pulse  $V_{DS} \approx 20 \text{ V}$  of length  $t_S \sim 1 \text{ s}$  for gate–source voltage  $V_{GS} = 0 \text{ V}$  at ambient temperature  $T_{0H} \approx 25$  °C and  $T_{0H} + \Delta T_{0H} \approx 35$  °C was applied and  $I_{DS}$  time response was acquired as depicted in Fig. 5 giving opportunity to determine  $\Delta I_{DS}^*$ .



Fitting of  $I_{DS}$  by exponential function in the range  $70 \text{ ns} < t < 200 \text{ ns}$  results in  $t_D \approx 17 \text{ ns}$  and  $I_{D0}$  estimation utilizing (A1) and (A2), respectively, taking high-power operation  $V_{DS}$  and  $I_{DS}$  rising time emphasized in Fig. 5 into account. Subsequently,  $T_A$  at  $t_1 \approx 70 \text{ ns}$  was obtained utilizing (A3) as initial condition for recurrent calculations.

The acquired  $\Delta I_{TE}(t, T_{0L})$  dependence in experimental Section III-B allows to incorporate the isothermal trapping process under high-power operation at operating temperature  $T_A = T_{0L}$  by the term  $dI_{TE}(t, T_{0L}) \approx \Delta I_{TE}(t + dt, T_{0L}) - \Delta I_{TE}(t, T_{0L})$  incorporated in  $dI_T(t) = dI_{DS}(t) - dI_{TE}(t, T_A)$  in (5).

Recurrent calculations utilizing  $k_R$  depicted in Fig. 3 shifted by  $t_D \approx 17 \text{ ns}$  were applied to obtain  $T_A$  time dependence as shown in Fig. 6 exhibiting a good correspondence with results obtained by device thermal simulation for investigated  $\text{Al}_{0.25}\text{Ga}_{0.75}\text{N}/\text{GaN}$  HEMT. The value  $T_{A0}$  calculated by (5) is  $k_R$  independent and useful for  $R_A(t, T_{OH})$  comparison under low-power and high-power operation. Relative  $k_R$  time variation is lower than relative  $R_A$  variation, especially at the pulse beginning, hence incorrect  $t_D$  determination under low-power operation is less considerable compared to method employing low-power operation  $R_A$  directly. At the pulse beginning  $R_A$  is determined mainly by elementary thermal capacitance combination whereas at the end of the pulse by elementary thermal resistance combination.

#### IV. CONCLUSION

The average channel temperature of the  $\text{AlGaIn}/\text{GaIn}$  HEMT under high-performance operation was determined using a modified device thermal model in pulsed and quasi-static operating mode. This was achieved by a differential analysis employing the isothermal and thermal part of the resulting current. The key advantages of the proposed method are as follows: 1) isothermal trapping phenomena are incorporated utilizing threshold voltage shift and transconductance; 2) device thermal stress suppression by the ambient temperature increase under the low-power operation only; and 3) self-heating process at the beginning of the pulse during the rising edge obtained from the time dependence of voltage and current was discussed and analyzed in the appendix. Thermal resistance calculated from low-power operation was directly utilized in high-power average temperature recurrent calculations. The normalized thermal resistance obtained from low-power operation was utilized to calculate the HEMT average channel temperature under high-power operation. Both methods were compared and discussed exhibiting a good correspondence with numerical simulations. The average temperature  $\sim 175 \text{ }^\circ\text{C}$  was calculated at the end of dissipated power pulse  $\sim 2 \text{ W}$  when the device quasi-static state was reached. Significantly reduced thermal stress during measurements makes this method applicable for vulnerable devices.

#### APPENDIX

After rectangular  $V_{GS}$  or  $V_{DS}$  pulse is applied at the zero time and ambient temperature  $T_0 = T_{0L}$  or  $T_0 = T_{0H}$ , the time  $t_1$  is required for charging device parasitic electric capacitance and free carrier filling. This results in variable dissipated power

$P(t) = V_{DS}(t)I_{DS}(t)$  and eligible  $T_A$  increase [13]. However, in the short time interval  $t_1 < t < t_2$  in the same order as  $t_1$ , due to negligible charge trapping and small  $P(t)$  variation,  $I_{DS}$  is possible to be approximated by fitting function  $I_{DF}(t)$  linearly dependent on  $T_A$ . For  $t < t_2$ ,  $T_A$  is supposed to be increased by heat flux linearly dependent on  $P(t)$  due to thermal capacitance charging major role.

To reach the same  $T_A$  at  $t_1$  for real pulse including parasitic capacitance and increasing  $P(t)$  and ideal pulse containing zero  $V_{DS}$  and  $I_{DS}$  rising time and  $P(t) \approx P(t_1)$  for  $t_D < t < t_1$ , the ideal pulse is required to be delayed by  $t_D$  meeting the requirement  $\int_0^{t_1} P(t)dt = \int_{t_D}^{t_1} V_{DS}I_{DF}(t)dt$ . Negligible  $V_{DS}I_{DF}(t)$  variation in comparison to real  $P(t)$  for  $t < t_1$  results in

$$t_D = t_1 - P^{-1}(t_1) \int_0^{t_1} P(t)dt \quad (\text{A1})$$

$$I_{D0} = I_{DF}(t_D). \quad (\text{A2})$$

The device investigated at two ambient temperatures  $T_0$ ,  $T_0 + \Delta T_0$  of relatively small difference  $\Delta T_0$  gives opportunity to calculate  $\Delta T_A(t_1) = T_A(t_1) - T_0$  valid for low-power as well as high-power operation coming out from (1)

$$\Delta T_A(t_1) = \Delta T_0 I_{DS}(t_1) [I_{DS}(t_1) - I_{D0}] / [I_{D0} \Delta I_{DS}^*(t_1)]. \quad (\text{A3})$$

Already known  $R_A(t, T_0)$  for the ideal  $V_{DS}$  and  $I_{DS}$  pulse gives opportunity to calculate  $\Delta T_A(t_1)$  for real pulse

$$\Delta T_A(t_1) = P(t_1) [dR_A(t_1 - t_D, T_0) / dt] [t_1 - t_D]. \quad (\text{A4})$$

The value  $T_A(t_1)$  is advised to be utilized as the initial condition for recurrent calculations. Subsequently,  $R_A(t, T_{0L})$  and  $k_R(t, T_{0L})$  obtained from low-power operation measurements are required to be shifted by  $t_D$  to be employed in high-power operation calculations.

The  $I_{D0}$  and  $T_A(t_1)$  estimation brings more accurate results for widely utilized standard methods based on isothermal and real resultant current comparison.

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