VRCT: A Viewport Reconstruction-Based 360◦ Video Caching Solution for Tile-Adaptive Streaming

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*Abstract***—360◦ video streaming demands higher bandwidth and lower latency than conventional videos. Some solutions employ tile-adaptive 360◦ video streaming and edge caching mechanisms to improve the quality of their content delivery. However, it is hard to cache large amounts of popular content with limited cache capacity. Reconstruction technologies, which have been widely adopted for images and conventional videos, can potentially reconstruct complete tile-based viewports from partial observation for 360◦ videos, thus further relieving the pressure on the caching. However, it is challenging to design a flexible and efficient caching solution that supports viewport reconstruction for 360◦ videos. In this paper, we propose a Viewport Reconstructionbased 360◦ video Caching solution for Tile-adaptive streaming (VRCT). To enhance viewers' quality of experience (QoE), a QoE-driven reconstruction trigger scheme is designed to determine whether to perform reconstruction or not based on current cache information and network conditions. To make efficient use of the cache space and facilitate the viewport reconstruction, a heuristic-based solution, named aggregation-based cache replacement scheme, is proposed to improve the probability of viewport reconstruction by carefully selecting which tiles to be stored in the given limited space. Through comprehensive experiments with a**

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real head movement dataset, we show that the proposed VRCT increases the cache hit ratio by up to 29%, reduces the backhaul usage by up to 44% and improves user QoE by up to 32% compared with other existing methods. In addition, experimental results show that our proposed cache replacement scheme facilitates viewport reconstruction and supports different video types.

*Index Terms***—Adaptive 360◦ video streaming, caching strategy, viewport reconstruction, tile-based transmission, edge computing.**

I. INTRODUCTION

T HE RECENT evolution of virtual reality (VR), VR devices and network communication technologies have significantly stimulated the production and consumption of 360◦ videos (a.k.a. panoramic videos) [\[1\]](#page-10-0). Many leading content providers, such as Facebook and YouTube, have deployed support for 360[°] videos and are increasingly promoting immersive user experiences in a wide range of areas, including education, sports and entertainment [\[2\]](#page-10-1). According to a recent market report [\[3\]](#page-10-2), this trend will continue and a whopping number of 112.62 million smartphone-based VR devices and Head-Mounted Displays (HMDs) is expected by 2026. Unfortunately, due to the ultra-high resolution (up to 8K) and bitrate (up to 200 Mbps) of 360◦ videos, the bandwidth to deliver such multimedia content is 4-5 times larger than that required to deliver conventional videos [\[4\]](#page-10-3). Besides, the delivery latency of the immersive videos must be kept small (e.g., less than 20 ms) to guarantee users' quality of experience (QoE) [\[5\]](#page-10-4). In spite of the effective increase in the available network bandwidth and reduced network latency enabled by the 5G communication technology, it is still a challenge to stream 360◦ videos from remote content servers to multiple users.

To alleviate bandwidth consumption and transmission latency, some solutions $[6]$, $[7]$, $[8]$ propose adaptive 360[°] video streaming by leveraging information about users' field of view (FoV). FoV is a portion of the 360◦ video around the user's line of sight. It can be spatially partitioned into non-overlapped rectangular regions called tiles. In tile-based techniques, each tile is transcoded into multiple representations with different bitrates. Both bandwidth consumption and latency can be significantly decreased by delivering only the tiles within the user's FoV at high resolution, while the other tiles are served at low resolution or not delivered at all.

To avoid the transmission redundancy associated with repeated requests and reduce the traffic load on the backhaul

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path, some works [\[9\]](#page-10-8), [\[10\]](#page-10-9), [\[11\]](#page-10-10) bring popular content closer to users by deploying transcoding-enabled cache servers at the edge of the Content Delivery Network (CDN). The application of cache servers effectively reduces the load on the content servers and improves users' QoE on the client side. However, with the volume of the 360◦ videos exploding, it has become increasingly more challenging to store massive popular content in the cache server. Exploiting the multi-access edge computing (MEC) paradigm, [\[12\]](#page-10-11), [\[13\]](#page-10-12), [\[14\]](#page-10-13) propose more advanced caching systems to optimize the edge computing capacity. However, these solutions require that all tiles requested to participate in edge computing be cached before the optimization methods are executed, which is unpractical given the limited cache capacity.

Reconstruction technologies are widely used in images [\[15\]](#page-10-14), [\[16\]](#page-10-15), [\[17\]](#page-10-16) and conventional videos [\[18\]](#page-10-17), [\[19\]](#page-10-18), [\[20\]](#page-11-0) because they can infer missing regions from partial observation, which is helpful to reduce additional requests for uncached content. However, unlike traditional videos, where the entire frames can be reconstructed, it is difficult and also unnecessary to reconstruct the entire frames of 360° videos due to two reasons. First, the volume of 360◦ videos is usually much larger than that of conventional videos. It will waste excessive amount of bandwidth to transmit the whole frames. Second, as will be shown in Section [II-C,](#page-2-0) only the users' viewports, rather than the entire frames, need to be reconstructed in 360[°] videos. As such, it is necessary to design a flexible cache system that can facilitate viewport reconstruction, to store appropriate tiles given the limited cache space. To the best of our knowledge, no work has yet incorporated reconstruction techniques into tile-based 360◦ video streaming.

In this paper, we propose a Viewport Reconstructionbased 360◦ video Caching solution for Tile-adaptive streaming (VRCT). The proposed VRCT addresses the following two key challenges: (i) how to decide whether to perform the viewport reconstruction task, and (ii) how to choose which tiles to evict in the cache server when the cache capacity is exceeded.

To solve the first problem, a QoE-driven Reconstruction Trigger Scheme (QRTS) is proposed to determine whether to perform the viewport reconstruction or not based on current cache information and network conditions. VRCT first estimates the viewport quality and associated delay by introducing a fitting function and employing queuing theory. Then it calculates user QoE with/without viewport reconstruction based on the estimations, and finally makes a decision to enhance user QoE. Related to the second problem, we propose a heuristic-based solution, named Aggregation-based Cache Replacement Scheme (ACRS), to select specific cached tiles to be removed, aiming to increase the viewport hit ratio of requests and improve the probability of viewport reconstruction. It can efficiently improve the spatial aggregation of the cached tiles and the temporal uniformity of the cache proportion. In other words, tiles of the same segment are stored centrally in the spatial dimension, while the number of cached tiles in any segment remains within a desirable range.

To assess the performance of VRCT, we compare it with several existing caching policies through comprehensive experiments, using a head-tracking dataset consisting of real traces. Experimental results show that: (i) VRCT outperforms other schemes, increasing up to 29% cache hit ratio and 32% user QoE, and effectively reducing the load on the backhaul path by up to 44%; (ii) The proposed cache replacement algorithm, ACRS, makes it easier to reconstruct viewports by improving the spatial aggregation of the cached tiles and the temporal uniformity of the cache proportion; (iii) The introduction of ACRS improves the probability of viewport reconstruction in different video types by 2% to 7%, which shows great robustness, and an average of 10% more users can benefit from the reconstruction mechanism.

The contributions of this paper are as follows:

- We propose VRCT, a 360[°] video caching solution based on viewport reconstruction for tile-adaptive streaming;
- • We design a system model to estimate user QoE and develop a QoE-driven reconstruction trigger scheme for the viewport reconstruction task;
- We propose an aggregation-based cache replacement scheme to change the cache features of the cached content and improve the probability of viewport reconstruction;
- We conduct comprehensive experiments in a real-world testbed with a head movement dataset to demonstrate the superior performance of VRCT.

The rest of the paper is organized as follows. In Section II , we briefly introduce related works and discuss our motivation. In Section [III,](#page-3-0) we present the system model and detailed definitions. Section [IV](#page-4-0) details the design of the proposed VRCT solution. Section [V](#page-7-0) describes the experimental testing setup, and Section [VI](#page-8-0) discusses the testing results. Section [VII](#page-9-0) summarizes the advantages and limitations of VRCT. Finally, Section [VIII](#page-10-19) concludes the paper.

II. RELATED WORKS AND MOTIVATION

A. Adaptive 360◦ *Video Streaming*

Over the years, 360◦ video streaming solutions have progressed from viewport-independent schemes and viewportdependent schemes to tile-based schemes. The viewportindependent schemes [\[21\]](#page-11-1) treat 360◦ videos similarly as traditional ones and stream the whole video frame area at the same quality level, without considering the user's FoV. In viewport-dependent schemes [\[22\]](#page-11-2), not only the bitrate level, but also the transmission area of the frame can be dynamically selected, so the streaming is adaptive. Compared with the first two approaches, tile-based schemes are more flexible. In tilebased schemes, the 360◦ videos are spatially partitioned into a number of non-overlapping rectangular regions, called tiles, which are further split temporally into many fixed-duration segments according to the dynamic adaptive streaming over HTTP (DASH) standard [\[23\]](#page-11-3). The employment of the DASHbased approach makes it easier to choose the appropriate quality of requested videos for users according to different network situations.

Many efforts are put to reduce bandwidth consumption and enhance viewport quality in tile-based 360◦ video streaming. Wang et al. [\[24\]](#page-11-4) design a saliency-driven mobile 360◦ video streaming system which takes full advantage of gaze information to improve the QoE under insufficient wireless network bandwidth. Zheng et al. [\[25\]](#page-11-5) present a novel ShiftTile-Tracking (STC) streaming system, which crops and transmits video by tracking the FoV movement of users. Wu et al. [\[26\]](#page-11-6) propose a dual-queue streaming framework to enable the Deep Reinforcement Learning (DRL) agent to determine and change the tile download order without incurring overhead. Madarasingha and Thilakarathna [\[27\]](#page-11-7) present a computational geometric approach-based adaptive tiling mechanism, which can take visual attention information as the input and provide a suitable non-overlapping variable size tile cover on the frame. Yaqoob and Muntean [\[28\]](#page-11-8) introduce CFOV, a combined FoV tile-based adaptive streaming solution, which introduces a practical-oriented tile selection method and actively allocates the video bitrate budget to different video frame areas to enhance the VR perception quality. The same authors have gone a step further and have proposed DVS, a prioritised bitrate adaptation approach based on dynamic viewport adjustment [\[29\]](#page-11-9). Additionally, Madarasingha et al. [\[30\]](#page-11-10) also propose an Inductive Logic Programming (ILP)-based mechanism to devise optimal cache tile configuration at MEC server which reduces the data fetched from the content server.

Although adaptive streaming technologies can reduce bandwidth consumption, traditional network architectures based on centralized storage and computing no longer meet the requirements of high-bitrate content request and delivery. Since popular content is often requested repeatedly, this approach drives up the load on the content server and wastes a lot of bandwidth on the backbone network.

B. Edge Caching and Edge Computing

To reduce duplicate content delivery and alleviate the load on the backbone network, alternative solutions based on edge caching and edge computing should be introduced in the 360◦ video streaming process.

He et al. $[31]$ present an edge caching scheme for 360° video streaming at the video and tile levels to reduce traffic load and improve user QoE. He et al. [\[31\]](#page-11-11) model the process of collaborative transcoding and caching as a Markov decision process, and use a model-free DRL approach to obtain an efficient caching replacement and computing power allocation strategy. Furthermore, Fu et al. [\[32\]](#page-11-12) propose a sequential reinforced 360-degree video streaming scheme, which boosts the performance of long-term viewpoint prediction with cross-user attentive network. Dai et al. [\[13\]](#page-10-12) design a view synthesisbased VR caching system that can synthesize the user's current desired FoV by cached nearby FoVs. Dasari et al. [\[14\]](#page-10-13) combine traditional video encoding with super-resolution techniques by training small micro-models, significantly increasing video quality while reducing bandwidth requirements.

However, the above solutions require all the requested tiles to be cached before their optimization methods can be executed. As such, they always have to fetch extra uncached tiles from the remote content servers, causing escalated backhaul traffic. Fortunately, reconstruction technology can alleviate this problem, among which the masked autoencoders (MAE) approach [\[17\]](#page-10-16) is the most advanced. MAE is an encoderdecoder architecture. The encoder maps the partial observed

Fig. 1. Some examples of heatmaps for 360° videos.

Fig. 2. Hit ratio vs. Cached ratio of users' watching traces.

signal to a latent representation, from which the decoder can reconstruct the original signal. Finally, the masked image can be reconstructed from partial observations. Intuitively, by reconstructing complete tile-based viewports from the cached tiles already available in the MEC-Cache server, the reconstruction technology can reduce additional requests for uncached tiles.

C. Motivation

To verify the above-mentioned ideas, we analyze a headtracking dataset with real traces [\[33\]](#page-11-13), and compute the heatmap with three different types of 360° videos. As depicted in Figure [1,](#page-2-1) the salient regions that attract users' attention always appear in the same tiles, and these areas are defined as regions of interest (ROI). Additionally, we further investigate the similarity of 50 users' head movement traces, and Figure [2](#page-2-2) shows the experimental result in detail. An important conclusion is that a 60% hit ratio can be achieved when only 20% of the watching traces are stored, indicating users share similar behavioral patterns when watching 360◦ videos. These two phenomena reveal that users' demands for tiles are highly correlated in the spatial dimension, which means that only a small number of viewports need to be reconstructed to meet the viewing needs of most users. Besides, highly overlapping cached tiles can also improve the viewport hit ratio and guarantee the quality of reconstructed viewports.

However, due to the limited computational resources and storage space available at the edge, the introduction of reconstruction technology brings new challenges to the design of tile-based caching and streaming systems. These challenges include 1) determination of the appropriate timing for viewport reconstruction instead of executing it whenever cache misses are encountered; 2) specially designed cache replacement strategy to facilitate the reconstruction technology. In

Fig. 3. The system overview of VRCT.

this context, we propose VRCT, a viewport reconstructionbased 360◦ video caching solution for tile-adaptive streaming, to reduce the number of requests for uncached tiles.

III. SYSTEM OVERVIEW

A. System Model

Figure [3](#page-3-1) illustrates the system overview of VRCT. Our proposed VRCT framework considers a wireless network scenario involving multiple mobile terminals, and there is a MEC-Cache server between the remote content server and these clients. On the server side, the created 360° videos undergo preprocessing such as projection, transcoding and partitioning before streaming. On the edge side, the MEC-Cache server is able to store a portion of 360° videos, as well as reconstruct viewports as needed to enhance the 360◦ video streaming quality.

To address two aforementioned challenges in Section [I,](#page-0-0) we first develop a QoE-driven reconstruction trigger scheme, which allows the flexibility to choose whether to reconstruct the incomplete viewports or fetch the uncached tiles from the remote content server. Then, we design an aggregation-based cache replacement scheme to facilitate viewport reconstruction by storing appropriate tiles in the given limited space. Combining both, the viewport reconstruction-based tile adaptive streaming can be achieved.

B. 360-Degree Video Model

Assume that there are *V* 360◦ videos stored on a remote content server, indexed by $V = \{1, \ldots, v, \ldots, V\}$, which can be transmitted and cached in edge servers. Each video is spatially partitioned into $M \times N$ non-overlapped tiles and a tile is indexed by *m* and *n*, where $m \in \mathcal{M}, \mathcal{M} = \{1, \ldots, m, \ldots, M\},\$ is the column index and $n \in \mathcal{N}$, $\mathcal{N} = \{1, \ldots, n, \ldots, N\}$ is the row index. Then, each tile is further split temporally into *S* consecutive segments, indexed by $S = \{1, \ldots, s, \ldots, S\}.$ To facilitate adaptive 360◦ video streaming, each 360◦ video is transcoded into *K* different representations indexed by $K = \{1, \ldots, k, \ldots, K\}$. And there are *U* users in the network,

indexed by $\mathcal{U} = \{1, \ldots, u, \ldots, U\}$. Therefore, $v_{s,m,n}^k$ denotes the tile at the *m*-*th* column and *n*-*th* row in the *s*-*th* segment of the *v*-*th* video, transcoded at the *k*-*th* bitrate level.

In addition, we use D to indicate the set of tiles within the requested viewport, and $\mathcal{D}(v_s)$ means the set of tiles within the specific viewport in the *s*-*th* segment of the *v*-*th* video. For tile $v_{s,m,n}^k$, $x_{u,t}^{v_{s,m,n}^k} = 1$ indicates that $v_{s,m,n}^k$ is located in the FoV of user *u* at time slot *t*, and $x_{u,t}^{v_{s,m,n}^k} = 0$ otherwise.

C. Adaptive Bitrate Algorithm

On the client side of the 360◦ video streaming network, a hybrid adaptive bitrate (ABR) algorithm, which takes both throughput and buffer size into account, is adopted to decide for users which representations of 360◦ videos to request based on historical network conditions.

First, the network throughput $B(t)$ at time slot *t* is estimated based on the historic downloading capacity as follows:

$$
B(t) = \frac{\sum_{v_{s,m,n}^k \in \mathcal{D}} size(v_{s,m,n}^k)}{\sum_{v_{s,m,n}^k \in \mathcal{D}} DT(v_{s,m,n}^k)},
$$
(1)

where $size(\cdot)$ and $DT(\cdot)$ represent the file size and download time of the input tile, respectively. Then, the estimation of the throughput at time slot $t + 1$ is defined as the harmonic mean of the downloading throughput for the last *I* segments:

$$
B(t+1) = \frac{I}{\sum_{i=0}^{I-1} 1/B(t-i)},
$$
\n(2)

where the input length I is set to 5 segments to cope with frequent fluctuations in network bandwidth [\[34\]](#page-11-14).

When the current buffer size *BS* is within the preset range [BS_{min} , BS_{max}], the user will request the next viewport based on the estimated throughput $B(t + 1)$, that is, we first select a subset of K in which the bitrates of all files are less than $B(t+1)$, and then choose the representation with the highest bitrate in the subset as the request quality. Otherwise, if *BS* is less than the preset minimum *BSmin*, the client will fetch the tiles at the lowest quality to fill the buffer as soon as

possible. And if *BS* exceeds the preset maximum *BSmax*, the requests will be suspended and the buffer will be consumed continuously.

D. Quality of Experience Model

To evaluate the user's viewing experience, inspired by [\[35\]](#page-11-15), [\[36\]](#page-11-16), [\[37\]](#page-11-17), we build an objective QoE evaluation model by jointly considering the following metrics.

1) *Perceived Quality:* In 360° videos, only the tiles in the user's FoV can affect the perceived quality. Therefore, the average perceived quality of the requested tile set $\mathcal{D}(v_s)$ is defined as:

$$
Q_p(\mathcal{D}(v_s)) = \frac{1}{N(\mathcal{D}(v_s))} \sum_{v_{s,m,n}^k \in \mathcal{D}(v_s)} q\left(v_{s,m,n}^k\right),\tag{3}
$$

where $N(\mathcal{D}(v_s))$ represents the number of tiles in $\mathcal{D}(v_s)$, and $q(\cdot)$ calculates the perceived quality of the input tile based on its bitrate. Note that a user can only request one representation of the tile in a fixed position, as such, the following constraint is satisfied:

$$
\sum_{k \in \mathcal{K}} x_{u,t}^{\nu_{s,m,n}^k} = 1. \tag{4}
$$

2) *Rebuffering*: When a user starts to request a video, the initial buffer is empty. During video playback, the buffer may also run out due to network fluctuations. In both cases, the client player needs to stop playing until the requested viewport is prepared. So we define the rebuffering duration as the time spent waiting:

$$
Q_r(\mathcal{D}(v_s)) = [PT(\mathcal{D}(v_s)) - BS]^+, \tag{5}
$$

where $PT(\cdot)$ calculates the preparation time required to acquire the requested viewport consisting of the input tile set, which will be discussed in Section [IV-A2.](#page-4-1)

3) *Switching Quality:* When the network bandwidth fluctuates greatly, the selected quality version will also fluctuate accordingly, resulting in frequent switching of video quality across segments. Therefore, the smoothness of video quality across the segments is defined as

$$
Q_s(\mathcal{D}(v_s)) = |Q_p(\mathcal{D}(v_s)) - Q_p(\mathcal{D}(v_{s-1}))|.
$$
 (6)

Finally, we define the QoE objective by a weighted summation formulation:

$$
QoE(\mathcal{D}(v_s)) = \alpha_1 \cdot Q_q(\mathcal{D}(v_s)) - \alpha_2 \cdot Q_r(\mathcal{D}(v_s)) - \alpha_3 \cdot Q_s(\mathcal{D}(v_s)), \tag{7}
$$

$$
QoE = \frac{1}{\bar{s} - \underline{s} + 1} \sum_{s = s}^{\bar{s}} QoE(\mathcal{D}(v_s)),
$$
 (8)

where α_1 , α_2 and α_3 are weighting factors. Due to the introduction of reconstruction technology, we are most concerned with the perceived quality of the viewports. Therefore, the weighting factors $(\alpha_1, \alpha_2, \alpha_3)$ are set to $(1, 0.25, 0.25)$, which is the setting also used in [\[35\]](#page-11-15) and [\[36\]](#page-11-16). Besides, *s* and *s* denote the start and end segments of user requests, respectively. As can be seen, QoE is enhanced by higher video quality, shorter rebuffering duration and fewer bitrate switches.

Fig. 4. The Impact of viewport hit ratio on reconstruction tasks: (a) The PSNR of the viewport after reconstruction (V-N-A) and before reconstruction (V-N-B) (b) The bitrate of the viewport after reconstruction (V-N-A) and

IV. VRCT FRAMEWORK DESIGN

A. QoE-Driven Reconstruction Trigger Scheme

before reconstruction (V-N-B).

In this subsection, we first introduce two key metrics for evaluating the impacts of reconstruction, i.e., the quality of the reconstructed viewport and the time consumed by the process. Then, the QoE-driven reconstruction trigger scheme is detailed.

1) Quality of the Reconstructed Viewport: As for the improvement in viewport quality, we run a series of tests with multiple 360◦ videos. In the experiments, we randomly mask a certain proportion of tiles as black areas and then reconstruct the viewport. Figure [4](#page-4-2) demonstrates how the viewport hit ratio affects the peak signal-noise ratio (PSNR) and bitrate of the reconstructed viewport, where the viewport hit ratio refers to the percentage of unmasked tiles in all requested tiles. As illustrated in Figure [4\(](#page-4-2)a), the PSNR of the viewport after/before reconstruction increases with the viewport hit ratio, and the reconstruction mechanism can effectively improve the viewport quality. From Figure [4\(](#page-4-2)b) we can observe that a higher viewport hit ratio brings a higher bitrate of the reconstructed viewport and finally benefits the quality.

In the experiments, we find that the bitrate of the reconstructed viewport can be roughly approximated by linear regression. We use $f(\cdot)$ to represent the fitting function. The output of $f(\cdot)$ is the bitrate of the reconstructed viewport, which is decided by two inputs, i.e., the viewport hit ratio and the perceived quality of the cached tiles that are used to reconstruct the viewport.

2) Time to Prepare the Viewport: The time to prepare the viewport consists of the computation delay for reconstructing viewports and the transmission delay for streaming viewports.

$$
t_{cd} = \frac{1}{\mu - p \cdot \lambda} + \frac{1}{\mu} = \frac{1}{\mu - \frac{N_{vr}}{N_{req}} \cdot \lambda} + \frac{1}{\mu},\tag{9}
$$

where μ is the number of viewports that the cache server can reconstruct per second, λ is the average rate at which requests are arriving, and *p* is the proportion of the reconstruction tasks. We use *Nreq* and *Nvr* to represent the number of requests and viewport reconstruction tasks, respectively. In order to obtain more accurate delay estimates, we update *p* in real-time by counting N_{req} and N_{vr} within sliding time windows which are set to 5 minutes. In equation [\(9\),](#page-4-3) $1/(\mu - p \cdot \lambda)$ is the average queuing delay of each task with $\mu - p \cdot \lambda > 0$, and $1/\mu$ is the average execution delay.

In fact, μ , *p* and λ are time-varying parameters, so we divide the time series into successive time windows (usually set to 1 minutes empirically), and update these parameters in realtime to obtain more accurate delay estimates.

The transmission delay in reconstruction tasks is given by:

$$
t_{rv} = \frac{\text{size}\left(\hat{\mathcal{D}}\right)}{B_{eu}},\tag{10}
$$

where $\hat{\mathcal{D}}$ represents the reconstructed viewport, while B_{eu} and *Boe* are the estimated throughputs of the fronthaul and backhaul links based on equations (1) – (2) , respectively. If the viewport can not be reconstructed, the uncached tiles should be fetched from the origin server, and then all requested tiles will be sent to users. In this case, we use t_{oe} and t_{eu} to indicate the transmission delays from the origin server to the edge server and from the edge server to users, respectively. Their formulas are given in equation [\(11\):](#page-5-0)

$$
t_{oe} = \frac{\sum_{v_{s,m,n}^k \in \mathcal{D}_{miss}} size(v_{s,m,n}^k)}{B_{oe}},
$$

$$
t_{eu} = \frac{\sum_{v_{s,m,n}^k \in \mathcal{D}} size(v_{s,m,n}^k)}{B_{eu}},
$$
(11)

where *Dmiss* indicates the subset of the uncached tiles in *D*. Similarly, we use D_{hit} to represent the subset of the cached tiles in *D*, which will be used later.

Finally, the total delay for reconstructing and delivering the viewport in viewport reconstruction tasks is defined as *tvr*:

$$
t_{vr} = t_{cd} + t_{rv},\tag{12}
$$

while the total delay for fetching the uncached tiles and sending them to users along with the cached ones is *tfetch*:

$$
t_{\text{fetch}} = t_{oe} + t_{eu}.\tag{13}
$$

They can be used to represent the viewport preparation time $PT(\cdot)$ in equation [\(5\)](#page-4-4) when calculating the corresponding user QoE, namely *QoEvr* and *QoEfetch*.

3) QoE-Driven Reconstruction Trigger Scheme (QRTS): Algorithm [1](#page-5-1) summarizes the decision-making process for viewport reconstruction. The algorithm describes the actions that the MEC-Cache server takes whenever it receives a user request. We use *C* to indicate the set of all cached content in the MEC-Cache server, and $C(v_s^k)$ indicates the set of cached tiles in the *s*-*th* segment of the *v*-*th* video at the *k*-*th* level.

First, QRTS performs adaptive representation selection based on the ABR algorithm mentioned in Section [III-C,](#page-3-4) and use the obtained representation level *k* to retrieve the subset of the cached tiles in $\mathcal{D}(v_s^k)$, called $\mathcal{D}_{hit}(v_s^k)$. Then, it counts the number of tiles in $\mathcal{D}(v_s^k)$ and $\mathcal{D}_{hit}(v_s^k)$, respectively defined as $N(\mathcal{D}(v_s^k))$ and $N(\mathcal{D}_{hit}(v_s^k))$, and calculates the viewport hit ratio δ. After that, it estimates the bitrate of the reconstructed viewport based on the fitting function $f(\cdot)$, and computes t_{vr} and t_{fetch} by equations (9) [-\(13\).](#page-5-2) In order to maximize QoE, we calculate $QoE_{vr}(\mathcal{D}(v_s))$ and $QoE_{fetch}(\mathcal{D}(v_s))$ for two different scenarios, and choose the one that achieves the higher QoE as our action.

Algorithm 1: QoE-Driven Reconstruction Trigger Scheme **Input:** Requested tile set *D*; Cached content *C*; Historical network conditions *H*; Current buffer size *BS* and its preset range [*BSmin*, *BSmax*]. **Output:** Whether to reconstruct the viewport or not. **¹ Function** *QRTS*()**: ²** Adaptive representation selection: $k \leftarrow ABR(\mathcal{H}, BS, BS_{min}, BS_{max});$ **3** Retrieve the hit requested file: $\mathcal{D}_{hit}(v_s^k) = \mathcal{D}(v_s^k) \cap \mathcal{C}(v_s^k);$ **⁴** Calculate the viewport hit ratio: $\delta = N(\mathcal{D}_{hit}(v_s^k))/N(\mathcal{D}(v_s^k));$ **⁵** Calculate the quality of the reconstructed viewport: $Q_p(\mathcal{D}(v_s)) \leftarrow f(\delta, Q_p(\mathcal{D}_{hit}(v_s^k)))$; **6** Calculate the delays used to prepare the viewport: t_{cd} , t_{rv} , *toe*, *teu*, *tvr* and *tfetch*; **⁷** Calculate the user QoE in two different scenarios: $QoE_{vr}(\mathcal{D}(v_s))$ and $QoE_{fetch}(\mathcal{D}(v_s))$;

$$
\text{If } \mathcal{Q}oE_{vr}(\mathcal{D}(v_s)) > \mathcal{Q}oE_{fetch}(\mathcal{D}(v_s)) \text{ then}
$$

9 | N_{vr} += 1; **¹⁰ return** True;

¹¹ else

¹² return False;

$$
13 \quad \boxed{N_{req} + = 1};
$$

B. Aggregation-Based Cache Replacement Scheme

In this subsection, we first analyze the cache features of panoramic videos. Then, we propose an aggregation-based cache replacement scheme that selects appropriate tiles to store in the limited space and improves the probability of viewport reconstruction.

1) Cache Feature Analysis: In order to improve the viewport hit ratio and enhance the quality of the reconstructed viewport, it is necessary to increase the aggregation degree of cached tiles in the spatial dimension. It means that the tiles of a segment should be cached centrally rather than distributively.

To characterize the aggregation degree of cached content, we first define $\xi(v_{s,m,n}^k)$ as the aggregation degree of the cached tile $v_{s,m,n}^k$ by

$$
\xi\left(v_{s,m,n}^k\right) = \frac{N_c\left(v_{s,m,n}^k\right)}{N_{view}},\tag{14}
$$

where $N_c(v_{s,m,n}^k)$ represents the number of cached tiles that current viewport contains when $v_{s,m,n}^k$ is located in the center of user's FoV, and *Nview* represents the total number of tiles in the viewport.

As illustrated in Figure [5,](#page-6-0) there are two different scenarios when calculating the aggregation degree. In general, the viewport is located within the frame, i.e., $\xi(v_{s,m,n}^k) = 7/9 = 0.78$ in Figure [5\(](#page-6-0)a). Otherwise, we need to stitch together the boundary of the frame before calculation, i.e., $\xi(v_{s,m,n}^k) = 5/9$ = 0.56 in Figure [5\(](#page-6-0)b). The aggregation degree of segment v_s^k is defined as the average aggregation degree of the cached tiles in $\mathcal{C}(v_s^k)$:

$$
\xi\left(v_s^k\right) = mean\left\{\xi\left(v_{s,m,n}^k\right)|v_{s,m,n}^k \in \mathcal{C}\left(v_s^k\right)\right\}.\tag{15}
$$

However, if all tiles of a segment are cached, the aggregation degree of this segment will reach the maximum value of 1. Unfortunately, this is not what we expect, since we only want

Fig. 5. Two scenarios for calculating the aggregation degree.

to store the frequently requested tiles in the given limited space rather than caching all of them. Therefore, in addition to the aggregation degree in the spatial dimension, the uniformity degree of cached content in the temporal dimension also needs to be considered. We define the cache proportion of segment v_s^k , denoted by $\psi(v_s^k)$, as the ratio of the cached tiles to all tiles in the segment:

$$
\psi\left(v_s^k\right) = \frac{N(C(v_s^k))}{M \cdot N},\tag{16}
$$

where $N(C(v_s^k))$ represents the number of cached tiles in v_s^k .

2) Problem Formulation: The results of many experiments perform that the ROI size in a segment only accounts for 20%∼30% area [\[38\]](#page-11-18) (approximately equal to the size of one viewport), which is also intuitive in Figure [1.](#page-2-1) Therefore, we assume that only viewport-sized tiles are stored for each segment. Then, we define $\vartheta(v_s^k)$ as the composite indicator of segment v_s^k :

$$
\vartheta\left(v_s^k\right) = \xi\left(v_s^k\right) - \beta \left[\frac{N(C(v_s^k)) - N_{view}}{M \cdot N}\right]^+
$$

$$
= \xi\left(v_s^k\right) - \beta \left[\psi\left(v_s^k\right) - \psi_{view}\right]^+, \tag{17}
$$

where β is the penalty for the tiles that exceed the preset storage range, and ψ_{view} represents the cache proportion of a viewport. Further, $\vartheta(v)$ is defined as the average of $\vartheta(v_s^k)$ for the *v*-*th* video overall segments and quality versions:

$$
\vartheta(v) = \frac{\sum_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \vartheta(v_s^k)}{K \cdot S}.
$$
 (18)

The goal of our cache policy is to maximize the composite indicator of the cached content, which can be achieved by selecting appropriate tiles to be stored in the limited cache capacity. The optimization problem can be formulated as

$$
\max \ \vartheta(C) = \sum_{v \in \mathcal{V}} w_v \cdot \vartheta(v) \tag{19a}
$$
\n
$$
\text{s.t.} \ \sum_{v \in \mathcal{V}} \sum_{s \in S} \sum_{m \in \mathcal{M}} \sum_{n \in \mathcal{N}} \sum_{k \in \mathcal{K}} \text{size} \left(v_{s,m,n}^k \right) \cdot y \left(v_{s,m,n}^k \right) \leq C_B,
$$
\n
$$
(19b)
$$

$$
\sum_{v \in \mathcal{V}} w_v = 1,\tag{19c}
$$

where w_v is the request probability of the *v*-*th* video.

Constraint [\(19b\)](#page-6-1) ensures that the size of cached data does not exceed the cache capacity C_B , where $y(v_{s,m,n}^k) = 1$ if

Algorithm 2: Aggregation-Based Cache Replacement Scheme

	Input: Tile to be cached $v_{s,m,n}^k$; Cached content C; Cache					
	capacity C_B . 1 $C(v_s^k)$.append $(v_{s,m,n}^k)$ (store $v_{s,m,n}^k$ on the cache); 2 while cache.size() > C_B do					
	if $\psi(v_s^k) > \psi_{view}$ then					
	$\begin{array}{c} 3 \\ 4 \end{array}$ for $v_{s,x,y}^k \in \mathcal{C}(v_s^k)$ do					
$\overline{}$	Assume that $v_{s,x,y}^k$ is removed from $C(v_s^k)$;					
6	Compute $\xi(v_s^k)$ of the rest tiles in $\mathcal{C}(v_s^k)$;					
7	Remove the tile with the largest $\xi(v_s^k)$;					
8	else					
9	Remove the tile with the smallest $\gamma(v_{s,m,n}^k)$;					

 $v_{s,m,n}^k$ is stored in the cache server. Otherwise, $y(v_{s,m,n}^k) = 0$. Constraint [\(19c\)](#page-6-2) normalizes the popularity of videos.

Problem [\(19\)](#page-6-3) is an Integer Linear Programming (ILP) problem. As the problem is NP-hard, it is extremely challenging to solve the problem optimally within polynomial time. Therefore, we propose a heuristic-based solution in Algorithm [2](#page-6-4) for cache replacement, named the aggregationbased cache replacement scheme.

3) Aggregation-Based Cache Replacement Scheme (ACRS): Algorithm [2](#page-6-4) shows the process of ACRS, in which a cache replacement metric, $\gamma(v_{s,m,n}^k)$, that takes both age and frequency into consideration is utilized:

$$
\gamma\left(v_{s,m,n}^k\right) = \sum_{t=0}^T \Big[R_t\Big(v_{s,m,n}^k\Big)\cdot\phi(T-t)\Big],\tag{20}
$$

$$
R_t\left(v_{s,m,n}^k\right) = \sum_{u \in \mathcal{U}} x_{u,t}^{v_{s,m,n}^k}, \quad \phi(T-t) = e^{-\sigma(T-t)}, \quad (21)
$$

where $R_t(v_{s,m,n}^k)$ refers to the number of requests to tile $v_{s,m,n}^k$ made by all users at time slot *t*, *T* represents the current time slot, and $\phi(T-t)$ is a kernel function that decreases the weights of old tiles. Meanwhile, we use σ to represent a non-negative empirical constant in the kernel function.

When the MEC-Cache server decides to remove some cached tiles to make room for a new one, the new tile $v_{s,m,n}^k$ will be stored on the cache first, and then one of the following two cases happens.

If the condition $\psi(v_s^k) > \psi_{view}$ is satisfied, the MEC-Cache server will remove tiles in $C(v_s^k)$ to ensure that the cache proportion does not increase anymore, which avoids the occurrence of excessive caching. In this situation, we calculate the aggregation degree $\xi(v_s^k)$ of the remaining cached tiles by assuming each tile in $\mathcal{C}(v_s^k)$ is removed. Finally, the tile with the largest remaining $\xi(v_s^k)$ will be actually removed because its removal has minimal effect on the aggregation degree. Consider an example in Figure [5\(](#page-6-0)a), assuming that tile $v_{s,1,1}^k$ is removed, the aggregation degree of the remaining cached tiles in $C(v_s^k)$ is $\xi(v_s^k) = 0.59$, while this value would be $\xi(v_s^k) = 0.65$ if tile $v_{s,4,2}^k$ were to be removed. Similarly, we can get the results assuming any one of the tiles is removed and find the maximum $\xi(v_s^k)$ among them is 0.65, which happens when tile $v_{s,4,2}^k$ is removed. As a result, tile $v_{s,4,2}^k$ is

Algorithm 3: Reconstruction-Based Tile Adaptive Streaming

			Input: Requested tile set D; Subsets \mathcal{D}_{hit} and \mathcal{D}_{miss} ; Cached			
			content C; Cache capacity C_R .			
$\mathbf{1}$			while receive a request for D do			
$\overline{2}$			if $D \in \mathcal{C}$ (all requested tiles are hit) then			
3			Send D to the user;			
4	else					
5	if $ORTS()$ then					
6			Reconstruct the viewport and send it back;			
7		else				
8			for $v_{s,m,n}^k \in \mathcal{D}$ do $\begin{cases} \text{if } v_{s,m,n}^k \in \mathcal{D}_{hit} \text{ then} \end{cases}$			
9						
10			Send $v_{s,m,n}^k$ to the user;			
11			else			
12			Fetch $v_{s,m,n}^k$ from the origin server;			
13			Send $v_{s,m,n}^k$ to the user;			
14			if cache.size() < C_B then			
15			Store $v_{s,m,n}^k$ on the cache;			
16			else			
17			Cache replacement using ACRS;			

actually removed. Otherwise, if the condition is not satisfied, the same process will be performed by removing the tile with the smallest $\gamma(v_{s,m,n}^k)$, which only considers the popularity of tiles. These operations are repeated until the cache capacity is sufficient to store the new tile.

C. Reconstruction-Based Tile Adaptive Streaming

Algorithm [3](#page-7-1) shows the overview of the reconstruction-based tile adaptive streaming in the MEC-Cache server. If all the tiles within the requested viewport are hit, the requested content will be sent to the user. Otherwise, the MEC-Cache server will determine whether to reconstruct the viewport or not by using the QRTS in Algorithm [1.](#page-5-1) When the outcome of the algorithm is true, the complete viewport will be reconstructed and sent back. Otherwise, the cache server will be ordered to fetch the uncached tiles one by one from the remote content server, and the ACRS in Algorithm [2](#page-6-4) will be executed when the cache capacity is insufficient to accommodate more content.

D. Time Complexity Analysis

Let $\mathcal{D}(v_s^k)$ and *r* represent the requested tile set and the number of user requests, respectively. The computational complexity of QRTS is $O(N(\mathcal{D}(v_s^k)))$, while that of ACRS is $O(N(\mathcal{C}(v_s^k))^2)$. Consequently, the overall time complexity of the proposed reconstruction-based tile adaptive streaming algorithm is $O(r \cdot N(\mathcal{D}(v_s^k)) \cdot N(\mathcal{C}(v_s^k))^2)$.

V. EXPERIMENTAL SETUP

A. Experimental Settings

The performance evaluation is based on head movement data traces of 50 users watching ten 360◦ videos [\[33\]](#page-11-13), including fast-paced and slow-paced videos. The details of the 360◦

TABLE I SPECIFICATIONS OF VIDEO DATASET

ID	Video Name	Category	Used Segment
	Hog Rider	NI, slow-paced	$0:00 - 1:00$
2	Kangaroo Island	NI, slow-paced	$0:01 - 1:01$
3	SFR Sport	NI, slow-paced	$0:16 - 1:16$
$\overline{4}$	Shark Shipwreck	NI, slow-paced	$0:30 - 1:30$
5	Roller Coaster	NI, fast-paced	$0:20 - 1:20$
6	Mega Coaster	NI, fast-paced	$1:30 - 2:30$
	Driving with	NI, fast-paced	$0:48 - 1:48$
8	Perils Panel	NI, slow-paced	$0:10 - 1:10$
9	Pac-Man	CG, fast-paced	$0:10 - 1:10$
10	Chariot Race	CG, fast-paced	$0:02 - 1:02$

¹ CG: Computer-Generated; NI: Natural Image; Video Dataset [33].

videos used in our experiments are presented in Table [I.](#page-7-2) In addition, the head-tracking dataset contains the information of users' FoVs and requested tiles for every frame.

On the server side, each 360◦ video is cut to a fixed duration of 1 minute, encoded and projected by equirectangular projection with 4K resolution (3840×1920) and 30 frames per second. In order to acquire multiple quality versions, we use the HEVC encoder kvazaar [\[39\]](#page-11-19) to transcode 360° videos into 5 different representations at 2 Mbps, 3 Mbps, 5 Mbps, 7 Mbps and 10 Mbps. Then, we spatially partition the 360◦ videos into 4×8 tiles (expressed by rows \times columns). Finally, GPAC MP4Box [\[40\]](#page-11-20) is used to package the encoded videos in MP4 containers and generate Media Presentation Description (MPD) files which split each video temporally into 2-second long segments.

On the client side, We conduct a total of ten rounds of experiments and in each round, a total of 5000 requests for 360[°] videos from 50 simulated users were sent to the edge server, following a Poisson distribution [\[41\]](#page-11-21) with rate $\lambda_r = 20$ [requests/min]. We assume that the video popularity is decided by using a Zipf distribution [\[42\]](#page-11-22) with shape parameter $\eta_v = 1.2$. Hence, the probability of the *v*-*th* popular 360° video to be selected is given by $p_v = \frac{1/v^{\eta_v}}{\sum_{v \in \mathcal{V}} 1/v^{\eta_v}}$.

The experiments are conducted in a real-world testbed with a prototype especially built to perform the delivery of 360◦ videos with the support of three x86 servers. We utilize one server as the source server, one server as the edge server, and one client-server acting as multiple clients. We implement Nginx [\[43\]](#page-11-23) to all servers to enable the DASH-based video delivery and use Django [\[44\]](#page-11-24) with uWSGI to implement VRCT at the edge server. In addition, we use the Linux Traffic Control tool (i.e., tc) [\[45\]](#page-11-25) to simulate the dynamic bandwidth, which is generated based on a 4G/LTE dataset [\[46\]](#page-11-26) with varying throughput patterns. To support the playback of 360◦ videos, we linearly scale the network throughput, and the throughput values fall between 2.7 Mbps and 13.1 Mbps, with an average of 5.4 Mbps. The average number of viewports that the cache server can reconstruct per second is $\mu = 1.8$ [requests/s].

For viewport reconstruction, we choose the MAE architecture [\[17\]](#page-10-16), which is a well-known encoder-decoder architecture implemented by Vision Transformers (ViT) [\[47\]](#page-11-27), to reconstruct the viewport frames. To achieve a better reconstruction effect, ViT-Huge [\[47\]](#page-11-27) is employed as our pre-training model.

Fig. 6. Evaluation of 360 \degree video streaming performance with respect to change in cache capacity.

B. Baseline Algorithms

The performance of the proposed VRCT for tile-adaptive 360◦ video streaming is evaluated by choosing among the following existing caching algorithms.

1) *Random:* Random caching policy randomly selects tiles to remove whenever the cache capacity is exceeded.

2) *LRU (Least Recently Used):* In LRU scheme, whenever the cache capacity is exceeded, the tile with the longest idle time has the highest rank for being removed.

3) *LFU (Least Frequently Used):* In LFU scheme, whenever the cache capacity is exceeded, the tile that is least frequently accessed has the highest rank for being removed.

(4) *VR-noACRS:* VR-noACRS is a caching policy that utilizes viewport reconstruction and always removes the tile with the smallest metric in equation [\(20\),](#page-6-5) instead of using ACRS as the cache replacement algorithm. It is designed for ablation experiments.

5) *Ptiling:* Ptiling [\[35\]](#page-11-15) is a popularity-aware 360° video streaming algorithm, which encodes the popularly viewed areas as macrotiles to save bandwidth and enhance the QoE.

6) *Optimal:* For the optimal solution, we assume that the prior knowledge about the user requests and the video popularity is known in advance, and the tiles with the highest requested probability are cached in the MEC-Cache server.

C. Performance Metrics

In terms of metrics, we use the following metrics to verify the performance of different schemes.

1) *Cache Hit Ratio:* The fraction of the requested tiles that are stored in the cache server and obtained by the viewport reconstruction technology. A higher cache hit ratio indicates less need to retrieve new data from the remote content server.

2) *User QoE:* User QoE is first calculated by equation [\(3\)](#page-4-5)[-\(8\),](#page-4-6) and then the QoE metrics of different schemes are limited to the range [0, 1] through numerical normalization, where the largest QoE value under all parameters is set to 1.

3) *Backhaul Traffic Load:* The bandwidth consumed for streaming 360° videos from the content server to the MEC-Cache server, which reflects the load of the backhaul path.

4) *Reconstruction Ratio:* The proportion of reconstructed viewports in all viewports delivered to users.

VI. PERFORMANCE EVALUATION

A. Effect of Cache Capacity

We first study the impact of cache capacity on 360° video streaming. To this end, we set $\eta_v = 1.2$ and vary the cache capacity in the range [2, 20]% of the video library size to evaluate the aforementioned performance metrics, and the results are shown in Figure [6.](#page-8-1)

As we can see from Figure $6(a)$ $6(a)$, the cache hit ratio increases with the cache capacity for all schemes. Due to the introduction of the reconstruction mechanism, VRCT and VR-noACRS can further improve the hit ratio. Meanwhile, VRCT outperforms other schemes (except the optimal one) in all ranges of cache size. Specifically, for large cache capacities, i.e., 20%, VRCT improves the cache hit ratio by 5%, 11%, 18%, 19% and 29% compared with VR-noACRS, Ptiling, LFU, LRU and Random, respectively.

As illustrated in Figure [6\(](#page-8-1)b), the QoE performance of VRCT is lower than Ptiling but still higher than the others when the cache size is small. This is because there are not enough cached tiles that can be used to reconstruct the complete viewport, and the missing tiles need to be fetched from the remote content server. However, as the cache capacity increases, the QoE of VRCT increases significantly and outperforms all baselines when the cache capacity is 8% and above. Specifically, the proposed VRCT improves QoE by at least 17% when the cache capacity is 20% of the video library.

The results in Figure $6(c)$ $6(c)$ and Figure $6(d)$ depict that VRCT can significantly reduce backhaul traffic load by reconstructing part of the requested viewports regardless of the size of the cache capacity. For example, it can reduce the backhaul usage by 12%∼44% compared with other schemes when the cache capacity is 20% of the video library. Furthermore, we can note that VRCT outperforms VR-noACRS, because the introduction of ACRS optimizes the cache features of the cached content, which will be discussed in Section [VI-D,](#page-9-1) and makes it easier to reconstruct viewports, thus reducing bandwidth consumption for uncached content.

B. Effect of Video Popularity Distribution

To observe the effect of the video popularity distribution on different schemes, we set the cache capacity to 10% of the video library and vary the Zipf shape parameter η_v in the range [0, 2] for different popularity distributions.

The results in Figure $7(a)$ $7(a)$ show that VRCT outperforms all baselines (except the optimal one) under all settings. Moreover, an increase in η_v leads to a smaller performance gap between the optimal scheme and VRCT, and the gap reduces to less than 10% when $\eta_v = 2$. This is because a larger η_v makes the video popularity distribution get steeper, which is beneficial to the viewport hit ratio of the reconstruction tasks.

Fig. 7. Evaluation of 360° video streaming performance with respect to change in Zipf shape parameter.

Fig. 8. Ratio of reconstruction tasks, users who benefit from reconstruction, and three feedback types with respect to change in video type.

As shown in Figure [7\(](#page-9-2)b), the QoE of VRCT increases sharply as η_v increases. VRCT provides over 10% improvement compared with other schemes when η_v is 2. Moreover, Figure [7\(](#page-9-2)c) and Figure [7\(](#page-9-2)d) show that skewed user request behavior will increase the reconstruction ratio, thus alleviating backhaul traffic load.

C. Effect of Video Types

In this experiment, we analyze the effect of the proposed ACRS with different categories of $360°$ videos. Figure $8(a)$ $8(a)$ shows the reconstruction ratios in ten different 360[°] videos. The results demonstrate that no matter what kind of video is requested, the reconstruction ratio of VRCT is higher than that of VR-noACRS. This is because the introduction of ACRS optimizes the cache features, improving the probability of viewport reconstruction. Figure [8\(](#page-9-3)b) shows the percentage of users who benefit from reconstruction. Compared with VR-noACRS, VRCT brings improvements in terms of the benefited user ratio for most videos due to the use of ACRS, which is very important, especially in the context of a network with multiple users who have different video preferences.

In order to assess Algorithm [3,](#page-7-1) in terms of viewport hits, reconstruction of the viewport and fetching the missing content, we explicitly plot the ratio of the three types in VRCT in Figure $8(c)$ $8(c)$. It can be noted how, VRCT achieves a reconstruction ratio of around 15% for all types of videos, which indicates the robustness of the proposed algorithm across multiple video categories.

D. Effect of Cache Features

In this experiment, we count the distributions of two cache features obtained from VRCT and baselines, namely

Fig. 9. CDFs of two different cache features.

cache proportion and aggregation degree. Their Cumulative Distribution Functions (CDFs) are illustrated in Figure [9.](#page-9-4)

As shown in Figure $9(a)$ $9(a)$, all baseline algorithms result in near uniform distribution. On the other hand, the cache proportion of VRCT is mainly distributed in the interval of 20%∼40%, which is a more desirable distribution than the uniform distribution. This is because an overly large cache proportion can lead to a waste of cache capacity, and an overly small cache proportion can make it difficult to trigger the reconstruction mechanism, resulting in an increase in the backhaul traffic load. Thanks to the cache replacement scheme ACRS, VRCT can maintain an appropriate cache proportion and increase the number of different segments stored in the cache by an average of 10%, so that the limited cache capacity can be effectively utilized. Figure [9\(](#page-9-4)b) shows that VRCT significantly increases the aggregation degree of the cached content compared with other schemes, which is important to improve the viewport hit ratio of the reconstruction tasks.

VII. DISCUSSIONS

The framework design and experimental evaluations presented in this paper demonstrate that VRCT can intelligently realize viewport reconstruction-based 360◦ video adaptive streaming by integrating network conditions, client status and cache information. The proposed VRCT flexibly selects between three different approaches to provide viewing tiles to 360◦ video consumers. It effectively alleviates the transmission pressure of the backhaul path, significantly enhances the user QoE, and exhibits great robustness in complex multi-user caching scenarios. However, there are still some limitations of the proposed solution.

First, VRCT may degrade the viewing experience of users in non-mainstream viewing modes. To improve the probability of viewport reconstruction, the proposed ACRS aims to increase the aggregation degree of cached tiles during the cache replacement process. In other words, ACRS deliberately removes some cached tiles outside of the ROI to make room for new tiles located inside it. This means that VRCT sacrifices the viewing experience of a few users with non-mainstream watching traces to improve the QoE of the majority of users.

Secondly, the adaptive bitrate streaming of VRCT can be further enhanced in the tile-based mechanism. Since each tile in the requested viewport is transmitted independently, delivering different quality versions of tiles in the same viewport is feasible. However, it is difficult to reconstruct the viewport by using tiles with different quality versions, and the decrease in perceived quality caused by the quality variation among different tiles in the same viewport also needs to be considered in QoE modeling.

Thirdly, the proposed system model is scalable to multiedge assisted content delivery scenarios. In the experiments, we only use one edge server to cache tiles and reconstruct viewports, but in reality, a large number of edges are expected to be available in 5G network environments. In the multi-edge assisted network, introducing collaborative caching strategies helps to adaptively aggregate video content. For instance, by redirecting user requests and communicating between edge nodes, contents can be congregated automatically in different edges by video type. In this way, each edge can provide better caching and reconstruction services for specific 360◦ videos.

Addressing these challenges involves complex client behavior analysis, adaptive mechanism optimization and cooperative scheduling models, which is not trivial. Future work will try to improve the proposed method by focusing on some of these limitations.

VIII. CONCLUSION

In this paper, we propose VRCT, a viewport reconstructionbased 360◦ video caching solution for tile-adaptive streaming, which consists of a QoE-driven reconstruction trigger scheme and an aggregation-based cache replacement scheme that can support viewport reconstruction. The employment of the reconstruction mechanism reduces the need for retrieving new data, decreasing backhaul traffic load. In order to enhance the user QoE, we design a decision-making process for viewport reconstruction, and choose the action that leads to a higher QoE by building models to predict viewport bitrate and consumed delay. To increase the probability of viewport reconstruction, we propose an innovative cache replacement

algorithm, which can improve the spatial aggregation of the cached tiles and store more different segments. Extensive testing results demonstrate that VRCT outperforms other schemes, as it improves the cache hit ratio by up to 29%, reduces the backhaul usage by up to 44% and significantly enhances user QoE. Moreover, VRCT optimizes the cache features to facilitate viewport reconstruction and supports different video types in 360◦ video streaming.

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