

# Guest Editorial

## Automation in Automotive Manufacturing

**A**UTOMOTIVE manufacturing is at a critical point. Not only does it have to fight against the impact of global recession, but also it needs to face the difficulty of adapting to dramatic change in the manufacturing sector, as well as emerging issues in product safety and quality. This provides both challenges and opportunities. Improving productivity, quality, and flexibility and reducing cost are the necessary steps in responding to these challenges and seizing these opportunities. Therefore, automation—a primary tool for making these improvements—is more relevant than ever in achieving these goals in all aspects of automotive manufacturing, from process and equipment control that reduces variations, ensures safety and increases productivity, to system and operation management that improves efficiency and quality, and application of new technologies, such as RFID.

Automation research in automotive manufacturing has attracted substantial effort from researchers in both academic and industrial communities for decades. Their goal has been to provide efficient scientific and engineering solutions for process and quality control, production planning and operation, and supply chain management. In recent years, significant advances in technology, the fast growing economy and rapidly changing markets have generated numerous opportunities for innovation in automation. At the same time, many new challenges have emerged in applying and implementing these innovations. Such advances have significantly expanded the scope of traditional automation research for automotive manufacturing.

The central theme of this Special Issue is *advances in automation science and engineering for automotive manufacturing*, with modeling, analysis, control and optimization as the focus areas. The purpose is to show the state-of-the-art research and applications in the general area of automation in automotive manufacturing, by bringing together researchers and practitioners from both academia and industry, to expose the significant advances, uncover and address the unsolved challenging problems, present the needs for integration of existing practice with new technologies, and provide visions for future research and development. We intend to provide original, significant and visionary automation research results describing scientific methods and technologies that improve efficiency, productivity, quality and flexibility in automotive manufacturing, with both solid theoretical development and practical importance.

The contributions in this Special Issue can be divided into four categories in automotive manufacturing: variation reduction on the process level; productivity or quality analysis and improvement on the system level; information and control problems in manufacturing environment, such as in painting, assembly and welding processes; and finally, RFID applications.

The first part of this Special Issue focuses on variation reduction in automotive manufacturing processes. Zhong *et al.* propose a feed-forward control strategy for a multistage assembly process to reduce dimensional variation by taking into account the uncertainties of the model coefficients explicitly. Such a system-level control strategy is able to minimize the end-of-line product variance, which is propagated from upstream manufacturing stages, even when significant changes of process parameters occur from their nominal values such that the designated model will be different from that of the actual process.

Huang and Kong carry out yield based sensitivity analysis for design evaluation of a multistage assembly process and present three analysis algorithms. The yield, i.e., conformity to product specifications, formulated as a high dimension probability integral over a specification region, is a transparent index for process capability evaluation. The sensitivity of such an index can provide valuable information on conformity to product specifications in the design stage.

Chase *et al.* analyze the variation of tooth engagement and loads in involute splines used in transmissions. A simple closed-form solution has been developed to allow designers to predict the load in spline teeth based upon the characteristics of the spline.

The second part of the Special Issue is devoted to analysis and improvement of manufacturing systems. Arinez *et al.* describe the design and implementation of a continuous improvement project at an automotive paint shop, where quality/quantity coupled operations exist in production systems. An integrated approach addressing such coupling is developed to evaluate system performance and identify both throughput and quality bottlenecks. Implementation of this project has resulted in substantial improvement on the factory floor.

Zhao *et al.* introduce an efficient simulation method for general assembly lines with material handling systems. Such a method is based on aggregated event-scheduling approach with a two-level framework, where the global event list is divided into small sizes in top-level simulation, and max-plus algebra is applied in bottom-level local simulation to further reduce local event lists. Such a method can mimic real production lines quickly and accurately within a reasonable computation effort.

Wang *et al.* study the impact of product sequencing on quality in flexible manufacturing systems with batch operations, such as vehicle sequencing in automotive paint shops where vehicles with same colors are grouped into batches to improve quality and reduce cost. A Markov chain model is presented to evaluate quality in such systems, and an analytical method is introduced to determine the appropriate sequencing and batch policies, and select the optimal sequence that leads to the highest quality.

Lennartson *et al.* introduce an integrated framework for product, process and automation design to obtain a unified information flow from early product design to final production.

The framework is based on the sequences of operations and includes a formal relation between product properties and process operations. A set of sequences of operations (SOP) is generated from this information and a formal graphical language for hierarchical operations and SOPs is then introduced and defined based on automata extended with variables. In this way, the inter-operability between different engineering disciplines is improved.

Control problems are addressed in the third part of this special issue. From and Gravdahl present a real-time algorithm to determine the optimal paint gun orientation in spray paint applications. Such a method can increase the speed at which a standard industrial manipulator can paint the surface so that a higher constant velocity throughout the trajectory can be maintained and uniform paint coating can be guaranteed.

Lee *et al.* develop a safety measurement to help ensure smooth control mode switching of an intelligent assist device (IAD), that is, Skill-Assist, a force-control-based robotic device that enables a human operator to handle heavy modules. Applying the proposed safety measurement enables the Skill-Assist to recognize the reaching gesture of an operator when the control mode is switched, so that control mode switching without abrupt deceleration can be achieved, and collision and serious injuries to a human operator can be avoided.

Li and Zhang introduce the interval model control of a new welding process, the Consumable Double-Electrode Gas Metal Arc Welding, which can double the travel speed for automobile welding. Interval models are developed and a prediction-based interval model control algorithm is implemented to control the resultant models.

The last section of this Special Issue addresses the application of RFID in manufacturing. Lin and Lin propose an efficient estimation and collision-group based anticollision algorithms for dynamic frame-slotted ALOHA in RFID networks. Such an anticollision algorithm can identify all tags within a small number of time slots to improve efficiency.

The Guest Editors would like to thank all the authors and the anonymous reviewers for their outstanding work. We would also like to thank Editor-in-Chief Emeritus Peter Luh, Editor-in-Chief N. Viswanadham, Editor Mengchu Zhou, Editor Y. Narahari, Editorial Assistant Amit Chakravarty, and many others for their efforts devoted to this Special Issue.

JINGSHAN LI, *Lead Guest Editor*  
University of Kentucky  
Department of Electrical and Computer Engineering  
Lexington, Kentucky 40506 USA  
jingshan@enr.uky.edu

MASARU NAKANO, *Guest Editor*  
Keio University  
Graduate School of System Design and Management  
Kanagawa, 223-8526 Japan  
m.nakano@sdm.keio.ac.jp

WAYNE CAI, *Guest Editor*  
General Motors Global R&D Center  
Manufacturing Systems Research Laboratory  
Warren, MI 48090 USA

KAI FURMANS, *Guest Editor*  
Karlsruhe Institute of Technology  
Department of Mechanical Engineering  
Karlsruhe, D-76131 Germany  
Kai.Furmans@ifl.uni-karlsruhe.de

ALAIN PATCHONG, *Guest Editor*  
Goodyear Dunlop Tires Operations S.A.  
Regional Industrial Engineering  
L-7750 Colmar-Berg, Luxembourg  
alain\_patchong@goodyear.com



**Jingshan Li** (S'97–M'00–SM'06) received the B.S. degree from the Department of Automation, Tsinghua University, Beijing, China, the M.S. degree from the Institute of Automation, Chinese Academy of Sciences, Beijing, and the Ph.D. degree in electrical engineering systems from the University of Michigan, Ann Arbor, in 1989, 1992, and 2000, respectively.

From 2000 to 2006, he was a Staff Research Engineer at the Manufacturing Systems Research Laboratory, General Motors Research and Development Center, Warren, MI. He joined the University of Kentucky as an Assistant Professor in the Department of Electrical and Computer Engineering and the Center for Manufacturing in 2006. To date he has published about 90 refereed journal and conference papers. His primary research interests are in modeling, analysis and control of manufacturing, service, and health care systems.

Prof. Li received the 2010 NSF Career Award, the 2009 IIE Transactions Best Application Paper Award, the IEEE Transactions on Automation Science and Engineering Best Paper Award for 2005, the 2006 IEEE Early Industry/Government Career Award in Robotics and Automation, and was

also a finalist of the Best Paper Awards of the 2009 IEEE Conference on Automation Science and Engineering and the 2005 IEEE International Conference on Robotics and Automation. He was an Associate Editor of the IEEE TRANSACTIONS ON AUTOMATION SCIENCE AND ENGINEERING, and of *Mathematical Problems in Engineering*.



**Masaru Nakano** received the B.S. and M.S. degrees in applied mathematics and physics from Kyoto University, Kyoto, Japan, and the Ph.D. degree in industrial engineering from Nagoya Institute of Technology, Aichi, Japan.

He is a Professor at the Graduate School of System Design and Management, Keio University, Kanagawa, Japan. From 1980 to 2008, he was a Principal Researcher at Toyota Central R&D Laboratories, Inc. His research interests are in system design for environment, enterprise integration and supply network, enterprise risk management, marketing and value chain analysis, management of technology development, business process reengineering, and new mobility system for aging people.



**Wayne Cai** received the B.S. degree from the University of Science and Technology of China, Hefei, the M.S. degree from the University of Iowa, Ames, and the Ph.D. from the University of Michigan, Ann Arbor, all in Mechanical Engineering.

He is a Staff Researcher at the Manufacturing Systems Research Laboratory, General Motors Global R&D Center, Warren, MI. He has 15 archived journal publications, and 17 U.S. or international patents or patents pending. His area of expertise is joining, assembly, forming and manufacturing process simulation, particularly in automotive engineering.



**Kai Furmans** received the Diploma degree in wirtschaftsingenieurwesen (similar to industrial engineering), the Ph.D. degree in mechanical engineering, and the Habilitation degree in 2000, all from Karlsruhe University, Karlsruhe, Germany.

He is a Full Professor of Mechanical Engineering at the Karlsruhe Institute of Technology (formerly University of Karlsruhe) and the Head of the Institute for Material Handling and Logistics Systems. As Postdoc, he worked with the IBM Thomas J. Watson Research Lab in 1994. From 1996 to 2003, he worked for Robert Bosch in several fields, being responsible for logistics for the Thermotechnology division before joining the Department of Mechanical Engineering, Karlsruhe University, in 2003, as a Professor. Since 2008, he is also the Academic Director of the Hector-School. His research interest is the modeling and optimization of facility logistics and supply chains, as well as the flexible automation of material handling systems.



**Alain Patchong** received the Ph.D. degree from Université de Valenciennes, Valenciennes, France.

He is managing the Regional Industrial Engineering for Europe, the Middle East, and Africa, and is Manager at Goodyear in Luxembourg. Before joining Goodyear in 2007, he worked with PSA Peugeot Citroën for 12 years, where he developed and implemented the methods for manufacturing system engineering and production line improvement. He also led lean implementation within PSA weld factories. He teaches at Ecole Centrale Paris and Ecole Supérieure d'Electricité (two French Grandes Ecoles). He was a finalist of the INFORMS' Edelman Competition in 2002 and a Visiting Scholar at MIT in 2004.