Table 1. Arctan expressions versus octant location.	
Octant	Arctan approximation
first or eighth	$\theta' = \frac{IQ}{I^2 + 0.28125Q^2}$
second or third	$\theta' = \pi/2 - \frac{IQ}{Q^2 + 0.28125I^2}$
fourth or fifth	$\theta' = \pi + \frac{IQ}{I^2 + 0.28125Q^2}$
sixth or seventh	$\theta' = -\pi/2 - \frac{IQ}{Q^2 + 0.28125I^2}$

number residing in any octant. We do this by using the rotational symmetry properties of the arctangent

$$\tan^{-1}(-Q/I) = -\tan^{-1}(Q/I)$$
 (3)
 $\tan^{-1}(Q/I) = \pi/2 - \tan^{-1}(Q/I)$ (3')

Those properties allow us to create Table 1, listing the appropriate arctan approximation based on the octant location of complex x.

So we have to check the signs of Q and I, and see if |Q| > |I|, to determine the octant location and then use the appropriate approximation in Table 1. The maximum angle approximation error is 0.26° for all octants.

When θ is in the fifth octant, the above algorithm will yield a θ' that's more positive than $+\pi$ radians. If we need to keep the θ' estimate in the range of $-\pi$ to $+\pi$, we can rotate any θ residing in the fifth quadrant $+\pi/4$ rad (45°) by multiplying (I+jQ) by (1+j), placing it in the sixth octant. That multiplication yields new real and imaginary parts defined as

$$I' = (I - Q)$$
 and $Q' = j(I + Q)$. (4)

The fifth octant θ' is then estimated using I' and Q' with

$$\theta'_{5\text{th oct.}} = -3\pi/4$$

$$-\frac{I'Q'}{Q'^2 + 0.28125I'^2}.$$
(5

Concluding Remarks

This arctangent algorithm may be useful in a digital receiver application where I^2 and Q^2 have been previously computed in conjunction with an amplitude modulation demodulation process or envelope detection associated with automatic gain control.

Richard Lyons is a consulting systems engineer and lecturer with Besser Associates in Mt. View, California. He has been the lead hardware engineer for numerous multimillion dollar signal processing systems for both the National Security Agency and TRW Inc. and has taught at the University of California Santa Cruz Extension. An associate editor for IEEE Signal Processing Magazine, he is also the author of Understanding Digital Signal Processing (Prentice-Hall, 1997). He is a member of the IEEE and the Eta Kappa Nu honor society and rides a 1981 Harley Davidson.

An Update to the Sliding DFT

Eric Jacobsen and Richard Lyons

ecause of our continued investigation of the sliding DFT (SDFT), and the interest the March 2003 article [1] generated among our DSP brethren, we provide this update to our readers:

- \blacktriangle 1) Referring to [1], while the typical Goertzel algorithm description in the literature specifies the frequency resonance variable k in (2) and Figure 1 to be an integer (making the Goertzel filter's output equivalent to an N-point DFT bin output), k can in fact be any value between 0 and N-1 giving us full flexibility in specifying a Goertzel filter's resonance frequency.
- \blacktriangle 2) Since we wrote the article, we've been made aware of several other versions of the SDFT expression, $S_k(n)$ in (4). While (4) in [1] provides the correct DFT magnitude results for real-time spectrum analysis, its $S_k(n)$ phase contains a fixed offset requiring correction if DFT phase results are required. A better expression for the SDFT is

$$S_k(n) = e^{j2\pi k/N} [S_k(n-1) + x(n) - x(n-N)]. (1')$$

Equation (1'), implemented with a comb filter followed by a complex resonator, as shown in Figure 1, provides both correct DFT magnitude and phase results.

▲ 3) We've discovered a useful property of the SDFT that's not widely known but is important. If we change the SDFT's comb filter feedforward coefficient from −1 to +1, the

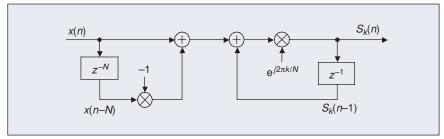
comb's zeros will be rotated counter-clockwise around the unit circle by an angle of π/N radians. Tans. This situation, for N=8, is shown on the right side of Figure 2(a). The zeros are located at angles of $2\pi(k+1/2)/N$ radians. The k=0 zeros are shown as solid dots. Figure 2(b) shows the zeros locations for an N=9 SDFT under the two conditions of the comb filter's feedforward coefficient being -1 and +1.

This alternate situation is useful, and we can now expand our set of spectrum analysis center frequencies to more than just N angular frequency points around the unit circle. The analysis frequencies can be $2\pi k/N$ or $2\pi (k+1/2)/N$, where integer k is in the range 0 < k <N-1. Thus we can build an SDFT analyzer that resonates at any one of 2N frequencies between 0 and f_s Hz. Of course, if the comb filter's feedfoward coefficient is set to +1, the resonator's feedforward coefficient must be $e^{j2\pi(k+1/2)/N}$ to achieve pole/zero cancellation.

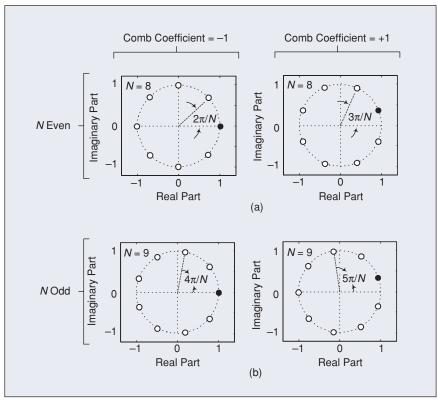
 \blacktriangle 4) To correct typographical errors in Table 1 of [1], the column headings should be a_1 , a_2 , and a_3 (not α_1 , α_2 , and α_3). For the Hanning window in Table 1, coefficient $a_1 = 0.5$ (not 0.25).

References

[1] E. Jacobsen and R. Lyons, "The sliding DFT," IEEE Signal Processing Mag., vol. 20, no. 2, pp. 74–80, Mar. 2003.



▲ 1. Improved SDFT structure.



▲ 2. Four possible orientations of comb filter zeros on the unit circle.