tem, is equal to zero. It is important that for the network $\bar{\pi}$ the equilibrium state defined above is identical with the state obtained in the *DC* analysis and it isn't valid for the Lagrangian networks.

REFERENCES

[1] L. O. Chua and J. D. Mc Pherson, "Explicit topological formulation of Lagrangian and Hamiltonian equations for nonlinear networks," *IEEE Trans. Circuits Syst.*, vol. CAS-21, pp. 277–286, Mar. 1974.

Correction to "Kronecker Products and Matrix Calculus in System Theory"

JOHN W. BREWER

In the above paper,[1] the Kronecker sum sign was misprinted as a Kronecker product sign in three instances in Table II. The correct versions are shown below.

T2.12 $\exp(N \oplus M) = \exp(N) \otimes \exp(M)$.

T2.14 $\beta_k \otimes \alpha_i$ is an eigenvector of $N \otimes M$ with eigenvalue $\lambda_i \mu_k$ and is also an eigenvector of $N \oplus M$ with eigenvalue $\lambda_i + \mu_k$.

T2.16 If N and M are symmetric and sign definite of the same sign then $N \oplus M$ is also sign definite of that sign.

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[1] J. W. Brewer, "Kronecker products and matrix calculus in system theory," *IEEE Trans. Circuits Syst.*, vol. CAS-25, pp. 772–781, Sept. 1978.

Correction to "An Algebra of Transfer Functions for Distributed Linear Time-Invariant Systems"

F. M. CALLIER AND C. A. DESOER

In the above paper,[1] the following errors occurred in the Proof of Theorem 2.2 (p. 659, first column). For convenience, we count lines downward starting from the subtitle Proof of Theorem 2.2.

Line 1: $e^{\sigma_0 t}$ should read $e^{-\sigma_0 t}$.
Line 3: $\hat{f}(\sigma + j\omega)$ should read $\hat{f}_p(\sigma + j\omega)$.
Line 3: $L_2(\boldsymbol{R}_+)$ should read $L_2(\boldsymbol{R})$.
Line 5: $e^{\sigma_0 t} f_p(t)$ should read $e^{-\sigma_0 t} f_p(t)$.
Line 5: g should read f (three times!).
Line 6: $g(p)$ should read $\hat{f}(p)$.
Line 8: the top "$t < 0$" should read "$t > 0$".
Line 10: delete "$k \in L_1(\boldsymbol{R}) \cap L_\infty(\boldsymbol{R})$ and," and replace by "since $\operatorname{Re} p > \sigma_0$".
Line 14: Replace "$e^{-\sigma_0 t}$," preceding the integral sign, by "$-$".
Line 14: Replace twice g by f.

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[1] F. M. Callier and C. A. Desoer, "An algebra of transfer functions for distributed linear time-invariant systems," *IEEE Trans. Circuits Syst.*, vol. CAS-25, pp. 651–662, Sept. 1978.

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